### <u>Abstract</u>

#### **Connecting Ground Validation and Algorithms**

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The Ground Validation (GV) component of the Global Precipitation Measurement (GPM) mission involved several field campaigns, involving aircraft, ground radars, and other instrument networks designed to measure various aspects of precipitation. In many cases, these instruments are still in operation at ongoing data collection sites at Wallops Flight Facility, VA and Marquette, MI. The data collected has been used for algorithm formulation and validation, but in many cases has been under-utilized. This presentation describes aspects of GPM algorithms that could benefit from GV data that has been collected and announces a workshop to be held for that purpose in March 2020.

# Connecting Ground Validation and Algorithms





NAS

# Summary of Field Campaigns

Field Campaign	Aircraft Obs	Dedicated Ground Radar	Ground Instruments
MC3E Apr-May 2011	ER-2 (73 hours) UND Citation (42.6 hours)	NPOL D3R X-SAPR, C-SAPR KAZR, SACR	PARSIVEL (17) Gauge pairs (16) 2DVD (7)
GCPEX Jan-Feb 2012	DC-8 (14 flights) UND Citation (11 flights) NRC Convair-580 (5 flights)	D3R MRR2 W-/X-band profiling	PARSIVEL (10) 2DVD (5) PIP (3) POSS (5) Pluvio (9)
IFLOODS Mar-Apr 2013		MRR NPOL D3R XPOL	PARSIVEL (14) Gauge Pairs (18) 2DVD (6)
IPHEX May-Jun 2014	ER-2 (18 flights) UND Citation (20 flights)	NPOL D3R NOXP	PARSIVEL (24) Gauges (108) 2DVD (5)
OLYMPEX Nov-Dec 2015	ER-2 (11 flights) DC-8 (17 flights) UND Citation (15 flights)	NPOL D3R EC X-band DOW MRR (4)	PARSIVEL (15) Gauge Pairs (25) 2DVD (3) PIP





### What do algorithms need from GV?

### **Direct validation**

- Compares algorithm output to a comparable ground-based measurement
- Metrics upon which mission success is measured
- Example: use ground-based radar to evaluate attenuation-corrected Z, R, D<sub>m</sub>

### **Physical Constraints**

- GV data can, and should, be used to inform algorithm assumptions, but with caveats:
  - Algorithms contain many wrong but useful models
  - Acceptable performance is often achieved by balancing incorrect assumptions (local minimum)
- Examples: Default R-D<sub>m</sub> relationship, N<sub>w</sub> pdf











## Algorithm Physical Assumptions: What could be improved?

2ADPR, 2AKu, 2AKa, are low by a factor of 7-10

2ADPR:

Made from 21 orbitals\*,  $T_{surf} < 5^{\circ}$ C,  $T_{gate} \le 0$ \*Orbitals are not collocated to GV

NASA GV: Made from APR-Nevzorov colocations in OLYMPEX/GCPEX Courtesy of Randy Chase





# Algorithm Physical Assumptions: Ice scattering tables

Dual-frequency measurements alone are insufficient to characterize particle size in ice phase (even after converting to melted equivalent diameter). Particle density and geometry assumptions are important. Ability to identify rimed particles by other means (profile shape, BB characteristics) may reduce ambiguities.

Source: OpenSSP and ARTS single scattering databases.





6. Better informed extrapolation of profiles below clutter – particularly when there is a phase change (MRR)



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