# Simulating the binary variates for the components of a socioeconomical system 

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#### Abstract

Often in practice the components $W j$ of a sociological or an economical system $\underline{W}$ take discrete $0-1$ values. We talk about how to generate arbitrary observations from a binary $0-1$ system $\underline{B}$ when is known the multidimensional distribution of the discrete random vector $\underline{B}$. We also simulated a simplified structure of $B$ given by the marginal distributions together with the matrix of the correlation coefficients. Different properties of the systems $\underline{W}$ are presented too.


Keywords: binary system, marginal distribution, Monte Carlo simulation, random variates, correlation coefficient.

## 1. Introduction

A general system $\underline{W}$ with $k$ components $W_{1}, W_{2}, W_{3}, \ldots, W_{k}$ is characterized by the features $\lambda_{j}$ of every variable $W_{j}$ and the intensity $c_{i j}$ of the relation between any two components $W_{i}$ and $W_{j}, 1 \leq i, j \leq k$. Frequently in practice the relation among the elements of the subsystem $\left\{W_{i}, W_{j}\right\}$ is a symmetric one, that is $c_{i j}=c_{j i}$.

The characteristic $\lambda_{j}$ of the component $W_{j}$ could be just the parameters which define the marginal distribution of the random variable $W_{j}$. In the following we will choose the Pearson correlation coefficient $\operatorname{Cor}\left(W_{i}, W_{j}\right)$ to measure the intensity $c_{i j}$ of the relation which is present between the components $W_{i}$ and $W_{j}$ of the system $\underline{W}$. We mention here that in the literature there are known many other indicators to measure the ratio among the elements $W_{i}$ and $W_{j}$ from $\underline{W}$ ([1], [2], [6] ).

Figure 1 presents some kinds of systems $\underline{W}$.
Many times in practice the system $\underline{W}$ has components $W_{j}$ with a normal distribution. Such a system will be designated in the subsequent by $\underline{X}$. For this particular case the system components $X_{j}, 1 \leq j \leq k$, are dependent normal random variables characterized by their means $\mu_{j}$ and their dispersions $\sigma_{j}^{2}$. So we will take $\lambda_{j}=\left(\mu_{j}, \sigma_{j}\right)$ and $c_{i j}=\operatorname{Cor}\left(X_{i}, X_{j}\right), 1 \leq i, j \leq k$.

Another class from the systems $\underline{W}$ are binary $0-1$ systems designated by $\underline{B}$. The elements $B_{1}, B_{2}, B_{3}, \ldots, B_{k}$ of the system $\underline{B}$ are binary dependent variables which take only the values 0 and 1 . To make a distinction between the systems $\underline{B}$ and $\underline{X}$ we will use the notation $r_{i j}=\operatorname{Cor}\left(B_{i}, B_{j}\right)$ in the discrete case and $c_{i j}=\operatorname{Cor}\left(X_{i}, X_{j}\right)$ for the continuous normal marginals variant.

We mention here that the normal type system $\underline{X}$ is completely characterized by the set of the parameters $\mu_{i}, \sigma_{i}, c_{i j}, 1 \leq i<j \leq k$, that is $k(k+3) / 2$ values ([3]).

[^0]But the multidimensional distribution of an arbitrary binary system $\underline{B}$ has more parameters. For this reason, in opposition with the normal distributions case, we can not define a general binary $0-1$ system $\underline{B}$ by knowing only the values $\mu_{i}, \sigma_{i}, r_{i j}, 1 \leq i<j \leq k$. More, in the discrete case of $\underline{B}$, the variance $\sigma_{j}^{2}=\operatorname{Var}\left(B_{j}\right)$ depends on the mean $\mu_{j}=\operatorname{Mean}\left(B_{j}\right)$. So, knowing only the marginals and the correlation matrix of $\underline{B}$ we lose a lot of information which define the real multivariate discrete distribution of the system $\underline{B}$. Some details concerning the behavior of a binary system $\underline{B}$ will be given in the next section.


Fig. 1. A system $\underline{W}$ with $k$ components
We reveal a new other aspect which is present for sociological and economical systems too. So, the individuals of a given population estimate the behaviour of each component $W_{j}$ from a continuous system $\underline{W}$ by putting subjective marks.

In this approach a binary system $\underline{B}$ results from $\underline{W}$ when the marks take only 0 and 1 values. Hence, in practice, we often approximate a continuous system $\underline{W}$ by a binary one, like $\underline{B}$. In this case we must evaluate the discretization error.

## 2. The binary $\mathbf{0 - 1}$ systems

The binary random vector $\underline{B}=\left(B_{1}, B_{2}, B_{3}, \ldots, B_{k}\right)$ which takes only 0 and 1 values is completely characterized by the probabilities $p_{i_{1}, i_{2}, i_{3}, \ldots, i_{k}}, i_{j} \in\{0,1\}, 1 \leq j \leq k$, where

$$
p_{i_{1}, i_{2}, i_{3}, \ldots, i_{k}}=\operatorname{Pr}\left(B_{1}=i_{1}, B_{2}=i_{2}, B_{3}=i_{3}, \ldots, B_{k}=i_{k}\right)
$$

Obviously, $p_{i_{1}, i_{2}, i_{3}, \ldots, i_{k}} \geq 0$ for all indices $i_{j} \in\{0,1\}$ and in addition

$$
\begin{equation*}
\sum_{i_{1}=0}^{i_{1}=1} \sum_{i_{2}=0}^{i_{2}=1} \sum_{i_{3}=0}^{i_{3}=1} \ldots \sum_{i_{k}=0}^{i_{k}=1} p_{i_{1}, i_{2}, i_{3}, \ldots, i_{k}}=1 \tag{1}
\end{equation*}
$$

To simplify our expose, for any $i_{j} \in\{0,1\}$, we will use the notation

```
\(p_{i_{1}, \ldots, i_{j-1},+, i_{j+1}, \ldots, i_{k}}=p_{i_{1}, \ldots, i_{j-1}, 0, i_{j+1}, \ldots, i_{k}}+p_{i_{1}, \ldots, i_{j-1}, 1, i_{j+1}, \ldots, i_{k}}\)
```

So, the equality (1) could be also written in a shorter form as $p_{+,+,+, \ldots,+}=1$.
The marginal distributions of the random vector $\underline{B}$ are defined only by the probabilities $q_{j}=\operatorname{Pr}\left(B_{j}=1\right)$, $1 \leq j \leq k$.

Choosing, for example, the component $B_{1}$ we deduce

$$
\operatorname{Pr}\left(B_{1}=0\right)=p_{0,+,+, \ldots,+}=1-p_{1,+,+, \ldots,+}=1-\operatorname{Pr}\left(B_{1}=1\right)=1-q_{1}
$$

Remark 1. Since the distribution of the system $\underline{B}=\left(B_{1}, B_{2}, B_{3}, \ldots, B_{k}\right)$ is determined by the probabilities $p_{i_{1}, i_{2}, i_{3}, \ldots, i_{k}}$ with the restriction (1) we conclude that a general binary $0-1$ system $\underline{B}$ with $k$ components is defined by $2^{k}-1$ parameters.

Now we will enumerate some properties of a binary $\underline{B}=\left(B_{1}, B_{2}\right)$ system which has only two components.
We remind that the distribution of an arbitrary 0-1 binary vector $\underline{B}=\left(B_{1}, B_{2}\right)$ is given by the probabilities $p_{i, j}=\operatorname{Pr}\left(B_{1}=i, B_{2}=j\right)$ where $i, j \in\{0,1\}$ and $p_{+,+}=1$

In this case $q_{1}=p_{1,+}=\operatorname{Pr}\left(B_{1}=1\right), q_{2}=p_{+, 1}=\operatorname{Pr}\left(B_{2}=1\right), 0 \leq q_{1}, q_{2} \leq 1$ and therefore

$$
p_{1,0}=q_{1}-p_{1,1}, \quad p_{0,1}=q_{2}-p_{1,1}, \quad p_{0,0}=1+p_{1,1}-q_{1}-q_{2}
$$

Hence we have the inequalities
P2.1. $\max \left\{0, q_{1}+q_{2}-1\right\} \leq \min \left\{q_{1}, q_{2}\right\}$
After a straightforward calculus we obtain the relations
P2.2. $\operatorname{Mean}\left(B_{j}\right)=\operatorname{Mean}\left(B_{j}^{2}\right)=q_{j}, \operatorname{Var}\left(B_{j}\right)=q_{j}\left(1-q_{j}\right), j \in\{0,1\}$

$$
r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)=\frac{p_{1,1}-q_{1} q_{2}}{\sqrt{q_{1}\left(1-q_{1}\right)} \sqrt{q_{2}\left(1-q_{2}\right)}}, 0<q_{1}, q_{2}<1
$$

Remark 2. This expression of the correlation coefficient $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)$ does not depend on the concrete values of the binary random variables $B_{1}$ and $B_{2}$. For example, considering $B_{1} \in\left\{a_{1}, b_{1}\right\} \neq\{0,1\}$, $B_{2} \in\left\{a_{2}, b_{2}\right\} \neq\{0,1\}$ we obtain the same value for the indicator $r_{12}$.

Since $q_{1}=p_{1,0}+p_{1,1}$ and $q_{2}=p_{0,1}+p_{1,1}$ we prove easily
P2.3. If $p_{1,1}=q_{1} q_{2}$ then we have also the following equalities
$p_{0,1}=\left(1-q_{1}\right) q_{2}, p_{1,0}=q_{1}\left(1-q_{2}\right), \quad p_{0,0}=\left(1-q_{1}\right)\left(1-q_{2}\right)$
From P2.2 and P2.3 it results
P2.4. The binary 0-1 random variables $B_{1}, B_{2}$ are independent if and only if $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)=0$.
Remark 3. The property P2.4 is not always true for an arbitrary continuous two component system $\underline{W}=\left(W_{1}, W_{2}\right)$.

Applying the propositions P2.1 and P2.2 we deduce the inequalities
P2.5. $\operatorname{Cor}\left(B_{1}, B_{2}\right) \geq \frac{\max \left\{0, q_{1}+q_{2}-1\right\}-q_{1} q_{2}}{\sqrt{q_{1}\left(1-q_{1}\right)} \sqrt{q_{2}\left(1-q_{2}\right)}}, 0<q_{1}, q_{2}<1$
$\operatorname{Cor}\left(B_{1}, B_{2}\right) \leq \frac{\min \left\{q_{1}, q_{2}\right\}-q_{1} q_{2}}{\sqrt{q_{1}\left(1-q_{1}\right)} \sqrt{q_{2}\left(1-q_{2}\right)}}, 0<q_{1}, q_{2}<1$
The following properties are particular cases of the proposition P2.5.
P2.6. If $q_{1}=q_{2}$ then $\operatorname{Cor}\left(B_{1}, B_{2}\right) \leq 1$

$$
\text { If } q_{1}=1-q_{2} \text { then } \operatorname{Cor}\left(B_{1}, B_{2}\right) \geq-1
$$

Using the formulas

$$
\operatorname{Cov}\left(1-B_{1}, B_{2}\right)=-\operatorname{Cov}\left(B_{1}, B_{2}\right), \operatorname{Var}\left(1-B_{1}, B_{2}\right)=\operatorname{Var}\left(B_{1}, B_{2}\right)
$$

we can prove directly the equalities
P2.7. $\operatorname{Cor}\left(1-B_{1}, B_{2}\right)=\operatorname{Cor}\left(B_{1}, 1-B_{2}\right)=-\operatorname{Cor}\left(B_{1}, B_{2}\right)$
Graphic 1 presents us a suggestive image of the variation for the lower and upper bounds of $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)$ index depending on the marginal distributions indicators $0<q_{1}, q_{2}<1$.

Remark 4. From the propositions P2.1-P2.7 we conclude that the discrete distribution of the system $\underline{B}=\left(B_{1}, B_{2}\right)$ is completely determined by the indices $0<q_{1}, q_{2}<1$ which characterize the marginal distributions of $\underline{B}$ together with the correlation coefficient $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right),-1 \leq r_{12} \leq 1$. But the parameters $q_{1}, q_{2}, r_{12}$ are mutually dependent (see the properties P2.1 and P2.5 or Graphic 1 ).


Graphic 1. The lower and upper bounds of $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)$

## 3. Generate random observations from a binary system

Leisch, Weingessel and Hornik suggested in [5] the application of the general inverse method for discrete random vectors ([3], [4] ) to generate arbitrary observations ( $b_{1}, b_{2}, b_{3}, \ldots, b_{k}$ ), $b_{j} \in\{0,1\}$, for the system $\underline{B}=\left(B_{1}, B_{2}, B_{3}, \ldots, B_{k}\right)$.

The following algorithm $G D R V$ produces ( $b_{1}, b_{2}, b_{3}, \ldots, b_{k}$ ) vectors, $b_{j} \in\{0,1\}$, such that
$\operatorname{Pr}\left(B_{1}=b_{1}, B_{2}=b_{2}, B_{3}=b_{3}, \ldots, B_{k}=b_{k}\right)=p_{b_{1}, b_{2}, b_{3}, \ldots, b_{k}}$
where the probabilities $p_{i_{1}, i_{2}, i_{3}}, \ldots, i_{k}, i_{j} \in\{0,1\}, 1 \leq j \leq k$, define the binary $0-1$ system $\underline{B}$.

Algorithm GDRV ( Generating Discrete Random Vectors ).
Step 0. Input : the probabilities $p_{i_{1}, i_{2}, i_{3}, \ldots, i_{k}}, i_{j} \in\{0,1\}, 1 \leq j \leq k$, with $p_{+,+,+, \ldots,+}=1$.
Step 1. Establish a one to function $h:\left\{1,2,3, \ldots, 2^{k}\right\} \rightarrow\{0,1\}^{k}$
Step 2. Compute recurrently the sums
$s_{0}=0$
$s_{t}=s_{t-1}+p_{h(t)}, \quad 1 \leq t \leq 2^{k}$
Step 3. Generate a random variate $u$ uniformly distributed on the interval $(0,1]$
Step 4. Find the index $1 \leq t \leq 2^{k}$ such that $u \in\left(s_{t-1}, s_{t}\right]$
Step 5. $b=h(t)$
Step 6. Output : $b$

Details regarding the theoretical justification of the generating procedure $G D R V$ can be found in the books [3] and [4].

Remark 5. Applying algorithm $G D R V$ we generated $n=10^{6}$ random variates ( $b_{1}, b_{2}, b_{3}$ ) from the binary system $\underline{B}=\left(B_{1}, B_{2}, B_{3}\right)$ defined by Table 1 . For this case the frequences of the categories ( $i_{1}, i_{2}, i_{3}$ ), $i_{j} \in\{0,1\}$, $1 \leq j \leq 3$, are given in Table 2. The validity of the algorithm $G D R V$ is proved in part since the theoretical values and the empirical estimations of the probabilities $p_{i_{1}, i_{2}, i_{3}}$ are very closed (compare the results from Tables 1-2).

Table 1. The theoretical distribution of the binary 0-1 system $\underline{B}=\left(B_{1}, B_{2}, B_{3}\right)$

| $p_{0,0,0}$ | $p_{0,0,1}$ | $p_{0,1,0}$ | $p_{0,1,1}$ | $p_{1,0,0}$ | $p_{1,0,1}$ | $p_{1,1,0}$ | $p_{1.1 .1}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.050 | 0.200 | 0.100 | 0.150 | 0.100 | 0.050 | 0.050 | 0.300 |

Table 2. The frequences for the variates $\left(b_{1}, b_{2}, b_{3}\right)$ obtained after $10^{6}$ simulations with algorithm GDRV

| $(0,0,0)$ | $(0,0,1)$ | $(0,1,0)$ | $(0,1,1)$ | $(1,0,0)$ | $(1,0,1)$ | $(1,1,0)$ | $(1,1,1)$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 49763 | 200067 | 99951 | 149842 | 99672 | 49832 | 50332 | 300541 |

## 4. Systems with normal distributed components

Now we will discuss the case of a system $\underline{X}=\left(X_{1}, X_{2}, X_{3}, \ldots, X_{k}\right)$ where its components $X_{j}, 1 \leq j \leq k$, are random variables with normal distributions.

By $X \sim \operatorname{Norm}\left(\mu, \sigma^{2}\right)$ with $\mu \in R, \sigma>0$, we understand that the random variable $X$ is normal distributed where $\operatorname{Mean}(X)=\mu$ and $\operatorname{Var}(X)=\sigma^{2}$. We denote by $\Phi(x)$ the Laplace function, that is the cumulative distribution function for the random variable $Z \sim \operatorname{Norm}(0,1)$.

Remind some properties which will be applied in the subsequent.
P4.1. If $Z \sim \operatorname{Norm}(0,1)$ and ${ }^{X=\mu+\sigma Z}$ with $\mu \in R, \sigma>0$ then we have $X \sim \operatorname{Norm}\left(\mu, \sigma^{2}\right)$.
P4.2 ( Inverse method, [3], [4] ). If the random variable $U$ is uniformly distributed on the interval [0,1] and $Z=\Phi^{-1}(U)$ then $Z \sim \operatorname{Norm}(0,1)$.

P4.3. For any $\mu_{i} \in R, \sigma_{i}>0$, if $X_{i} \sim \operatorname{Norm}\left(\mu_{i}, \sigma_{i}^{2}\right)$ and $Y=X_{1}+X_{2}$ then $Y \sim \operatorname{Norm}\left(\mu_{1}+\mu_{2}, \sigma_{1}^{2}+\sigma_{2}^{2}\right)$.
Discretization procedure DP. For any $a \in R, \mu \in R, \sigma>0$ and $X \sim \operatorname{Norm}\left(\mu, \sigma^{2}\right)$ we designate by $B_{X, a}$ the following binary 0-1 random variable

$$
B_{X, a}= \begin{cases}0, & \text { when } X<a \\ 1, & \text { when } X \geq a\end{cases}
$$

Using the procedure $D P$ we deduce by a direct calculus
P4.4. For any $X \sim \operatorname{Norm}\left(\mu, \sigma^{2}\right)$ we have $\operatorname{Pr}\left(B_{X . a}=1\right)=1-\Phi((a-\mu) / \sigma)$
P4.5. For any $-1 \leq c \leq 1, Z_{i} \sim \operatorname{Norm}(0,1)$, the standard normal random variables $Z_{1}, Z_{2}$ being independent, if

$$
\begin{aligned}
& X=Z_{1} \\
& Y=c Z_{1}+\sqrt{1-c^{2}} Z_{2} \\
& \text { then } X \sim \operatorname{Norm}(0,1), Y \sim \operatorname{Norm}(0,1) \text { and more } \operatorname{Cor}(X, Y)=c .
\end{aligned}
$$

Remark 6. By using a normal random variable $X \sim \operatorname{Norm}\left(\mu, \sigma^{2}\right)$ and a given bound $a \in R$ we build a binary 0-1 random variable $B_{X, a}$ such that

$$
q=\operatorname{Pr}\left(B_{X . a}=1\right)=1-\Phi((a-\mu) / \sigma)
$$

( see the discretization procedure DP and Proposition P4.4). When $\mu=0$ and $\sigma=1$, the threshold $a \in R$ determine effectively the distribution of the discrete 0-1 random variable $B_{X, a}$.

## 5. A discretization process

Having a continuous normal distributed system $\underline{X}=\left(X_{1}, X_{2}, X_{3}, \ldots, X_{k}\right)$ and fixing some arbitrary thresholds $a_{1}, a_{2}, a_{3}, \ldots, a_{k} \in R$ we can obtain a binary $0-1$ system $\underline{B}=\left(B_{1}, B_{2}, B_{3}, \ldots, B_{k}\right)$ with $B_{j}=B_{X_{j}}, a_{j}$, $1 \leq j \leq k$ (apply the procedure $D P$ ).

More, when $X_{j} \sim \operatorname{Norm}(0,1), 1 \leq j \leq k$, then $q_{j}=\operatorname{Pr}\left(B_{j}=1\right)=1-\Phi\left(a_{j}\right)$.

Obviously, in this last case, the correlation indicators $r_{i j}=\operatorname{Cor}\left(B_{i}, B_{j}\right)$ and $c_{i j}=\operatorname{Cor}\left(X_{i}, X_{j}\right), 1 \leq i, j \leq k$, have not equal values. More precisely, a correlation coefficient $r_{i j}$ depends on the quantities $c_{i j}, q_{i}, q_{j}$. The effective relation between $r_{i j}$ and $c_{i j}$ indices will be established in the subsequent by applying a stochastic Monte Carlo simulation.

Remark 7. For an arbitrary $-1 \leq c \leq 1$, propositions $P 4.2$ and $P 4.5$ permit us to generate two dependent standard normal random variables $X, Y$ having just the Pearson correlation coefficient $\operatorname{Cor}(X, Y)=c$. We can apply Proposition P4.2 ( the inverse method, [3], [4] ) to generate independent $Z_{i} \sim \operatorname{Norm}(0,1)$ random variables which are used by Proposition P4.5.

Now, keeping all the previous notations, we will suggest a Monte Carlo procedure MCRCC to establish the real ratios between he correlation coefficients $c_{i j}=\operatorname{Cor}\left(X_{i}, X_{j}\right)$ and $r_{i j}=\operatorname{Cor}\left(B_{i}, B_{j}\right)$.

Procedure MCRCC.
Step 1. We generate random variates of volume $n$ for a bidimensional random vector ( $X_{1}, X_{2}$ ) with standard normal dependent marginals and $c_{12}=\operatorname{Cor}\left(X_{1}, X_{2}\right),-1 \leq c_{12} \leq 1$ ( more details in Remark 7 ).

Step 2. Knowing the marginal probabilities $-1 \leq q_{1}, q_{2} \leq 1$, we specify the discretization thresholds, that is $a_{1}=\Phi^{-1}\left(1-q_{1}\right), a_{2}=\Phi^{-1}\left(1-q_{2}\right)$.

Step 3. We obtain $0-1$ binary samples $\left(b_{1}, b_{2}\right)$ from the random vector $\underline{B}=\left(B_{i}, B_{j}\right)$ considering the discretization procedure $B_{1}=B_{X_{1}, a_{1}}, B_{2}=B_{X_{2}, a_{2}}$ ( algorithm $\left.D P\right)$.

Step 4. Using the samples resulted for $\underline{B}=\left(B_{i}, B_{j}\right)$ we estimate the correlation coefficient $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)$.

The correlation values $r_{12}$ from Tables 3-5 were deduced by running the Monte Carlo algorithm MCRCC for samples having the volume $n=10^{7}$.

Table 3. $q_{1}=q_{2}=0.5, n=10^{7}$ Monte Carlo simulations with MCRCC

| $c_{12}$ | -0.999 | -0.9 | -0.8 | -0.7 | -0.6 | -0.5 | -0.4 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $r_{12}$ | -0.9714 | -0.7129 | -0.5906 | -0.4938 | -0.4099 | -0.3335 | -0.2621 |
| $c_{12}$ | -0.3 | -0.2 | -0.1 | 0 | 0.1 | 0.2 | 0.3 |
| $r_{12}$ | -0.1940 | -0.1282 | -0.0637 | 0.0001 | 0.0638 | 0.1284 | 0.1943 |
| $c_{12}$ | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 | 0.9 | 0.999 |
| $r_{12}$ | 0.2622 | 0.3333 | 0.4096 | 0.4937 | 0.5904 | 0.7129 | 0.9714 |

Table 4. $q_{1}=0.4, q_{2}=0.6, n=10^{7}$ simulations with MCRCC

| $c_{12}$ | -0.999 | -0.9 | -0.8 | -0.7 | -0.6 | -0.5 | -0.4 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $r_{12}$ | -0.9713 | -0.7106 | -0.5872 | -0.4902 | -0.4060 | -0.3298 | -0.2588 |
| $c_{12}$ | -0.3 | -0.2 | -0.1 | 0 | 0.1 | 0.2 | 0.3 |
| $r_{12}$ | -0.1912 | -0.1261 | -0.0628 | -0.0004 | 0.0616 | 0.1240 | 0.1869 |
| $c_{12}$ | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 | 0.9 | 0.999 |
| $r_{12}$ | 0.2512 | 0.3173 | 0.3861 | 0.4589 | 0.5364 | 0.6181 | 0.6667 |

Table 5. $q_{1}=0.5, q_{2}=0.7, n=10^{7}$ simulations with MCRCC

| $c_{12}$ | -0.999 | -0.9 | -0.8 | -0.7 | -0.6 | -0.5 | -0.4 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $r_{12}$ | -0.6546 | -0.6091 | -0.5293 | -0.4529 | -0.3809 | -0.3125 | -0.2472 |
| $c_{12}$ | -0.3 | -0.2 | -0.1 | 0 | 0.1 | 0.2 | 0.3 |
| $r_{12}$ | -0.1838 | -0.1219 | -0.0608 | -0.0002 | 0.0605 | 0.1214 | 0.1834 |
| $c_{12}$ | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 | 0.9 | 0.999 |
| $r_{12}$ | 0.2469 | 0.3124 | 0.3808 | 0.4530 | 0.5297 | 0.6091 | 0.6546 |

Remark 8. The differences between the correlation values $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)$ and $c_{12}=\operatorname{Cor}\left(X_{1}, X_{2}\right)$ are sometimes considerable. Graphic 2 gives us a suggestive illustration of this aspect ( compare the differences between the continuous and dotted curves ).


Graphic 2. The ratio between the correlation indices $r_{12}$ and $c_{12}$
Remark 9. We can use successively Proposition P4.5 and the discretization procedure $D P$ to simulate directly samples from a tree type binary systems. See, for example, the one level tree system depicted in Figure 1, case 1.3.

## 6. Concluding remarks

We discussed two algorithms to generate random variates for a binary system $\underline{B}=\left(B_{1}, B_{2}, B_{3}, \ldots, B_{k}\right)$ with $k$ components.

The algorithm GDRV uses as inputs all the probabilities $p_{i_{1}, i_{2}, i_{3}, \ldots, i_{k}}, i_{j} \in\{0,1\}, 1 \leq j \leq k$, which characterize the binary system $\underline{B}$. It is not so easy to apply practically the procedure $G D R V$ for systems $\underline{B}$ which have a lot of components. In this case the quantity $2^{k}-1$ of the input data for $G D R V$ algorithm becomes extremely large.

For this reason is suggested a new other algorithm based on the discretization procedure $D P$ to obtain arbitrary observations from $\underline{B}$. This procedure simulate better the real aspects. The correlation structure of a continuous system $\underline{X}$ is inherited by the binary system $\underline{B}$ resulted after a discretization process. The relation between the correlation coefficients $c_{12}=\operatorname{Cor}\left(X_{1}, X_{2}\right)$ and $r_{12}=\operatorname{Cor}\left(B_{1}, B_{2}\right)$ can be determined by applying MCRCC algorithm ( see also Graphic 2 ).

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