# ON NONLOCAL PROBLEMS FOR FRACTIONAL DIFFERENTIAL EQUATIONS IN BANACH SPACES 

XiWang Dong, JinRong Wang, Yong Zhou


#### Abstract

In this paper, we study the existence and uniqueness of solutions to the nonlocal problems for the fractional differential equation in Banach spaces. New sufficient conditions for the existence and uniqueness of solutions are established by means of fractional calculus and fixed point method under some suitable conditions. Two examples are given to illustrate the results.


Keywords: nonlocal problems, fractional differential equations, existence, generalized singular Gronwall inequality, fixed point method.

Mathematics Subject Classification: 26A33, 34K12, 34A40.

## 1. INTRODUCTION

During the past two decades, fractional differential equations have been proved to be valuable tools in the modelling of many phenomena in various fields of engineering, physics and economics. For more details, one can see the monographs of Kilbas et al. [6], Lakshmikantham et al. [7], Miller and Ross [8], Podlubny [12]. Very recently, fractional differential equations and optimal controls in Banach spaces are studied by Balachandran et al. [3, 4], N'Guérékata [9, 10], Mophou and N'Guérékata [11], Wang et al. [13-20], Zhou et al. [22-24] and etc.

Throughout this paper, $(X,\|\cdot\|)$ will be a Banach spaces, and $J=[0, T], T>0$. Let $C(J, X)$ be the Banach space of all continuous functions from $J$ into $X$ with the norm $\|u\|_{C}:=\sup \{\|u(t)\|: t \in J\}$ for $u \in C(J, X)$.

We consider the following nonlocal problems of fractional differential equation

$$
\left\{\begin{array}{l}
{ }^{c} D^{q} u(t)=f(t, u(t)), t \in J  \tag{1.1}\\
u(0)+g(u)=u_{0}
\end{array}\right.
$$

where ${ }^{c} D^{q}$ is the Caputo fractional derivative of order $q \in(0,1), f: J \times X \rightarrow X$ is strongly measurable with respect to $t$ and is continuous with respect to $u$. The nonlocal term $g: C(J, X) \rightarrow X$ is a given function satisfying some assumptions that will be specified later. The nonlocal condition can be applied in physics with better effect than the classical initial value problem. Nonlocal conditions were initiated by Byszewski [1] when he proved the existence and uniqueness of mild and classical solutions of nonlocal Cauchy problems. As remarked by Byszewski [2] and Deng [5], the nonlocal condition can be more useful than the standard initial condition to describe some physical phenomena.

A pioneering work on the existence results of solutions for system (1.1) has been reported by N'Guérékata [9]. Also, N'Guérékata [10] reported that the results in [9] hold only in finite dimensional spaces. In the present paper, we revisit this interesting problem and establish some new existence principles of solutions to the system (1.1) by virtue of fractional calculus and fixed point theorems under some suitable conditions, which extend the results in [9] to infinite dimensional spaces.

The rest of this paper is organized as follows. In Section 2, we give some notations and recall some concepts and preparation results. In Section 3, we give an important priori estimation of solutions and obtain two main results (Theorems 3.4-3.5), the first result based on Banach contraction principle, the second result based on Krasnoselskii's fixed point theorem. At last, two examples are given to demonstrate the application of our main results.

## 2. PRELIMINARIES

In this section, we introduce notations, definitions, and preliminary facts which are used throughout this paper.

Let us recall the following known definitions. For more details see [6].
Definition 2.1. The fractional integral of order $\gamma$ with the lower limit zero for a function $f$ is defined as

$$
I^{\gamma} f(t)=\frac{1}{\Gamma(\gamma)} \int_{0}^{t} \frac{f(s)}{(t-s)^{1-\gamma}} d s, t>0, \gamma>0
$$

provided the right side is point-wise defined on $[0, \infty)$, where $\Gamma(\cdot)$ is the gamma function.

Definition 2.2. The Riemann-Liouville derivative of order $\gamma$ with the lower limit zero for a function $f:[0, \infty) \rightarrow R$ can be written as

$$
{ }^{L} D^{\gamma} f(t)=\frac{1}{\Gamma(n-\gamma)} \frac{d^{n}}{d t^{n}} \int_{0}^{t} \frac{f(s)}{(t-s)^{\gamma+1-n}} d s, t>0, n-1<\gamma<n
$$

Definition 2.3. The Caputo derivative of order $\gamma$ for a function $f:[0, \infty) \rightarrow R$ can be written as

$$
{ }^{c} D^{\gamma} f(t)={ }^{L} D^{\gamma}\left[f(t)-\sum_{k=0}^{n-1} \frac{t^{k}}{k!} f^{(k)}(0)\right], t>0, n-1<\gamma<n .
$$

Remark 2.4. (i) If $f(t) \in C^{n}[0, \infty)$, then

$$
{ }^{c} D^{\gamma} f(t)=\frac{1}{\Gamma(n-\gamma)} \int_{0}^{t} \frac{f^{(n)}(s)}{(t-s)^{\gamma+1-n}} d s=I^{n-\gamma} f^{(n)}(t), t>0, n-1<\gamma<n
$$

(ii) The Caputo derivative of a constant is equal to zero.
(iii) If $f$ is an abstract function with values in $X$, then integrals which appear in Definitions 2.1 and 2.2 are taken in Bochner's sense.
Lemma 2.5 (Bochner theorem). A measurable function $f: J \rightarrow X$ is Bochner integral if $\|f\|$ is Lebesbuge integrable.
Lemma 2.6 (Mazur lemma). If $\mathcal{K}$ is a compact subset of $X$, then its convex closure $\overline{\text { conv }} \mathcal{K}$ is compact.

Lemma 2.7 (Ascoli-Arzela theorem). Let $\mathcal{S}=\{s(t)\}$ is a function family of continuous mappings $s: J \rightarrow X$. If $\mathcal{S}$ is uniformly bounded and equicontinuous, and for any $t^{*} \in J$, the set $\left\{s\left(t^{*}\right)\right\}$ is relatively compact, then there exists a uniformly convergent function sequence $\left\{s_{n}(t)\right\}(n=1,2, \cdots, t \in J)$ in $\mathcal{S}$.
Theorem 2.8 (Krasnoselskii). Let $\mathfrak{B}$ be a closed convex and nonempty subsets of $X$. Suppose that $\mathcal{L}$ and $\mathcal{N}$ are in general nonlinear operators which map $\mathfrak{B}$ into $X$ such that:
(1) $\mathcal{L} x+\mathcal{N} y \in \mathfrak{B}$ whenever $x, y \in \mathfrak{B}$;
(2) $\mathcal{L}$ is a contraction mapping;
(3) $\mathcal{N}$ is compact and continuous.

Then there exists $z \in \mathfrak{B}$ such that $z=\mathcal{L} z+\mathcal{N} z$.
To end this section, we collect an important singular type Gronwall inequality which is introduce by Ye et al. [21] and can be used in fractional differential equations.
Theorem 2.9 ([21, Theorem 1]). Suppose $\beta>0, \widetilde{a}(t)$ is a nonnegative function locally integrable on $J$ and $\widetilde{g}(t)$ is a nonnegative, nondecreasing continuous function defined on $\widetilde{g}(t) \leq M, t \in J$, and suppose $u(t)$ is nonnegative and locally integrable on $J$ with

$$
u(t) \leq \widetilde{a}(t)+\widetilde{g}(t) \int_{0}^{t}(t-s)^{\beta-1} u(s) d s, t \in J
$$

Then

$$
u(t) \leq \widetilde{a}(t)+\int_{0}^{t}\left[\sum_{n=1}^{\infty} \frac{(\widetilde{g}(t) \Gamma(\beta))^{n}}{\Gamma(n \beta)}(t-s)^{n \beta-1} \widetilde{a}(s)\right] d s, t \in J
$$

Remark 2.10. Under the hypothesis of Theorem 2.9, let $\widetilde{a}(t)$ be a nondecreasing function on $J$. Then we have

$$
u(t) \leq \widetilde{a}(t) E_{\beta}\left(\widetilde{g}(t) \Gamma(\beta) t^{\beta}\right)
$$

where $E_{\beta}$ is the Mittag-Leffler function defined by

$$
E_{\beta}(z)=\sum_{k=0}^{\infty} \frac{z^{k}}{\Gamma(k \beta+1)} .
$$

## 3. MAIN RESULTS

We make some following assumptions.
[H1] For any $u \in X, f(t, u)$ is strongly measurable with respect to $t$ on $J$.
[H2] For any $t \in J, f(t, u)$ is continuous with respect to $u$ on $X$.
[H3] For arbitrary $u \in X$, there exists a $a_{f}>0$, such that

$$
\|f(t, u)\| \leq a_{f}(1+\|u\|)
$$

and for arbitrary $u \in C(J, X)$, there exists a $a_{g} \in(0,1)$ such that

$$
\|g(u)\| \leq a_{g}\left(1+\|u\|_{C}\right)
$$

[H4] For arbitrary $u, v \in X$ satisfying $\|u\|,\|v\| \leq \rho$, there exists a constant $L_{f}(\rho)>0$, such that

$$
\|f(t, u)-f(t, v)\| \leq L_{f}(\rho)\|u-v\|
$$

and for arbitrary $u, v \in C(J, X)$ there exists a constant $L_{g} \in(0,1)$, such that

$$
\|g(u)-g(v)\| \leq L_{g}\|u-v\|_{C}
$$

Now, let us recall the definition of a solution of the system (1.1).
Definition 3.1. A function $u \in C^{1}(J, X)$ is said to be a solution of the system (1.1) if $u$ satisfies the equation ${ }^{c} D^{q} u(t)=f(t, u(t))$ a.e. on $J$, and the condition $u(0)+g(u)=u_{0}$.

By Definition 2.1-2.3, one can obtain the following lemma.
Lemma 3.2. If the hypothesis [H1]-[H3] hold. A function $u \in C(J, X)$ is a solution of the fractional integral equation

$$
\begin{equation*}
u(t)=u_{0}-g(u)+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} f(s, u(s)) d s \tag{3.1}
\end{equation*}
$$

if and only if $u$ is a solution of the system (1.1).

Proof. For any $r>0$ and $u \in B_{r}=\left\{u \in C(J, X):\|u\|_{C} \leq r\right\}$, according to [H1]-[H2], $f(t, u(t))$ is measurable function on $J$. For $t \in J$, we obtain that

$$
\begin{aligned}
\int_{0}^{t}(t-s)^{q-1}\|f(s, u(s))\| d s & \leq \int_{0}^{t}(t-s)^{q-1} a_{f}(1+\|u(s)\|) d s \leq \\
& \leq a_{f} \int_{0}^{t}(t-s)^{q-1} d s+a_{f} \int_{0}^{t}(t-s)^{q-1} r d s \leq \\
& \leq \frac{(1+r) a_{f} T^{q}}{q}
\end{aligned}
$$

Thus $\left\|(t-s)^{q-1} f(s, u(s))\right\|$ is Lebesgue integrable with respect to $s \in[0, t]$ for all $t \in J$ and $u \in B_{r}$. Then from Bochner's theorem (Lemma 2.5) it follows that $(t-s)^{q-1} f(s, u(s))$ is Bochner integrable with respect to $s \in[0, t]$ for all $t \in J$.

Let $G(\tau, s)=(t-\tau)^{-q}|\tau-s|^{q-1}$. Since $G(\tau, s)$ is a nonnegative, measurable function on $D=[0, t] \times[0, t]$ for $t \in J$, we have

$$
\int_{0}^{t} \int_{0}^{t} G(\tau, s) d s d \tau=\int_{D} G(\tau, s) d s d \tau=\int_{0}^{t} \int_{0}^{t} G(\tau, s) d \tau d s
$$

and

$$
\begin{aligned}
\int_{D} G(\tau, s) d s d \tau= & \int_{0}^{t} \int_{0}^{t} G(\tau, s) d s d \tau= \\
= & \int_{0}^{t}(t-\tau)^{-q} \int_{0}^{t}|\tau-s|^{q-1} d s d \tau= \\
= & \int_{0}^{t}(t-\tau)^{-q}\left(\int_{0}^{\tau}(\tau-s)^{q-1} d s\right) d \tau+ \\
& +\int_{0}^{t}(t-\tau)^{-q}\left(\int_{\tau}^{t}(s-\tau)^{q-1} d s\right) d \tau \leq \\
\leq & \frac{2 T}{q(1-q)}
\end{aligned}
$$

Let $G_{1}(\tau, s)=(t-\tau)^{-q}(\tau-s)^{q-1}$. Note that $\|f(s, u(s))\| \leq a_{f}(1+r)$, therefore, $G_{1}(\tau, s) f(s, u(s))$ is a Lebesbuge integrable function on $D$, then we have

$$
\int_{0}^{t} \int_{0}^{\tau} G_{1}(\tau, s) f(s, u(s)) d s d \tau=\int_{0}^{t} \int_{s}^{t} G_{1}(\tau, s) f(s, u(s)) d \tau d s
$$

We now prove that

$$
{ }^{L} D^{q}\left(I^{q} f(t, u(t))\right)=f(t, u(t)), \text { for } t \in(0, T] .
$$

Indeed, we have

$$
\begin{aligned}
{ }^{L} D^{q}\left(I^{q} f(t, u(t))\right) & =\frac{1}{\Gamma(1-q) \Gamma(q)} \frac{d}{d t} \int_{0}^{t}(t-\tau)^{-q} \int_{0}^{\tau}(\tau-s)^{q-1} f(s, u(s)) d s d \tau= \\
& =\frac{1}{\Gamma(1-q) \Gamma(q)} \frac{d}{d t} \int_{0}^{t} \int_{0}^{\tau} G_{1}(\tau, s) f(s, u(s)) d s d \tau= \\
& =\frac{1}{\Gamma(1-q) \Gamma(q)} \frac{d}{d t} \int_{0}^{t} \int_{s}^{t} G_{1}(\tau, s) f(s, u(s)) d \tau d s= \\
& =\frac{1}{\Gamma(1-q) \Gamma(q)} \frac{d}{d t} \int_{0}^{t} f(s, u(s)) d s \int_{s}^{t} G_{1}(\tau, s) d \tau= \\
& =\frac{d}{d t} \int_{0}^{t} f(s, u(s)) d s= \\
& =f(t, u(t)) .
\end{aligned}
$$

We claim that $u(t)$ is absolutely continuous on $J$. For that, for any disjoint family of open intervals $\left\{\left(a_{i}, b_{i}\right)\right\}_{i=1}^{n}$ on $J$ with $\sum_{i=1}^{n}\left(b_{i}-a_{i}\right) \rightarrow 0$, we have

$$
\begin{aligned}
& \sum_{i=1}^{n} \frac{1}{\Gamma(q)}\left\|\int_{0}^{b_{i}}\left(b_{i}-s\right)^{q-1} f(s, u(s)) d s-\int_{0}^{a_{i}}\left(a_{i}-s\right)^{q-1} f(s, u(s)) d s\right\| \leq \\
& \leq \sum_{i=1}^{n} \frac{1}{\Gamma(q)}\left\|\int_{a_{i}}^{b_{i}}\left(b_{i}-s\right)^{q-1} f(s, u(s)) d s\right\|+ \\
& \quad+\sum_{i=1}^{n} \frac{1}{\Gamma(q)}\left\|\int_{0}^{a_{i}}\left(\left(b_{i}-s\right)^{q-1}-\left(a_{i}-s\right)^{q-1}\right) f(s, u(s)) d s\right\| \leq \\
& \leq \\
& \quad+\frac{a_{f}(1+r)}{\Gamma(q)} \sum_{i=1}^{n} \int_{a_{i}}^{b_{i}}\left(b_{i}-s\right)^{q-1} d s+ \\
& \leq \frac{a_{f}(1+r)}{\Gamma(q)} \sum_{i=1}^{n} \int_{0}^{a_{i}}\left(\left(a_{i}-s\right)^{q-1}-\left(b_{i}-s\right)^{q-1}\right) d s \leq \\
& \quad+\frac{a_{f}(1+q)}{\Gamma(1+q)} \sum_{i=1}^{n}\left(b_{i}-a_{i}\right)^{q}+ \\
& \leq \frac{2 a_{f}(1+r)}{\Gamma(1+q)} \sum_{i=1}^{n}\left(\left(a_{i}\right)^{q}+\left(b_{i}-a_{i}\right)^{q-1}-\left(b_{i}\right)^{q}\right) \leq
\end{aligned}
$$

Thus, $u(t)$ is differentiable for almost all $t \in J$. According to the Remark 2.4, we have

$$
\begin{aligned}
{ }^{c} D^{q} u(t) & ={ }^{c} D^{q}\left[u_{0}-g(u)+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} f(s, u(s)) d s\right]= \\
& ={ }^{c} D^{q}\left[\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} f(s, u(s)) d s\right]= \\
& ={ }^{c} D^{q}\left(I^{q} f(t, u(t))\right)= \\
& ={ }^{L} D^{q}\left(I^{q} f(t, u(t))\right)-\left[I^{q} f(t, u(t))\right]_{t=0} \frac{t^{-q}}{\Gamma(1-q)} .
\end{aligned}
$$

Since $(t-s)^{q-1} f(s, u(s))$ is Lebesgue integrable with respect to $s \in[0, t]$ for all $t \in J$, we known that $\left[I^{q} f(t, u(t))\right]_{t=0}=0$ which implies that

$$
{ }^{c} D^{q} u(t)=f(t, u(t)), \text { a.e. } t \in J
$$

Moreover, $u(0)+g(u)=u_{0}$. Thus, $u \in C(J, X)$ is a solution of system (1.1). On the other hand, if $u \in C(J, X)$ is a solution of system (1.1), then $u$ satisfies the integral equation (3.1).

In order to derive the existence results, we need important a priori estimation.
Lemma 3.3. Suppose system (1.1) has a solution $u$ on the time interval J. If the hypothesis $[\mathrm{H} 3]$ holds, then there exists a constant $\rho>0$ such that

$$
\|u(t)\| \leq \rho \text { for all } t \in J
$$

Proof. By Lemma 3.2, the solution of system (1.1) is equivalent to the solution of integral equation

$$
u(t)=u_{0}-g(u)+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} f(s, u(s)) d s
$$

According to the hypothesis [H3],

$$
\begin{aligned}
\|u(t)\| & \leq\left\|u_{0}-g(u)\right\|+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\|f(s, u(s))\| d s \leq \\
& \leq\left\|u_{0}-g(u)\right\|+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} a_{f}(1+\|u(s)\|) d s \leq \\
& \leq\left\|u_{0}\right\|+a_{g}+a_{g}\|u\|_{C}+\frac{a_{f}}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} d s+\frac{a_{f}}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\|u(s)\| d s
\end{aligned}
$$

which implies that

$$
\left(1-a_{g}\right)\|u\|_{C} \leq\left\|u_{0}\right\|+a_{g}+\frac{a_{f}}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} d s+\frac{a_{f}}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\|u(s)\| d s
$$

Thus,

$$
\|u(t)\| \leq \frac{\Gamma(q+1)\left(\left\|u_{0}\right\|+a_{g}\right)+a_{f} T^{q}}{\left(1-a_{g}\right) \Gamma(q+1)}+\frac{a_{f}}{\left(1-a_{g}\right) \Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\|u(s)\| d s
$$

Applying the singular type Gronwall inequality (Lemma 2.9),

$$
\|u(t)\| \leq \frac{\Gamma(q+1)\left(\left\|u_{0}\right\|+a_{g}\right)+a_{f} T^{q}}{\left(1-a_{g}\right) \Gamma(q+1)} \sum_{n=0}^{\infty} \frac{\left(a_{f} T^{q}\right)^{n}}{\Gamma(n q+1)\left(1-a_{g}\right)^{n}}
$$

where $\sum_{n=0}^{\infty} \frac{\left(a_{f} T^{q}\right)^{n}}{\Gamma(n q+1)\left(1-a_{g}\right)^{n}}$ is just the well known Mittag-Leffler function. Thus, there exists a constant $\rho>0$ such that

$$
\|u(t)\| \leq \rho, \text { for } t \in J
$$

Our first result is based on Banach contraction principle.

Theorem 3.4. Assume that $[\mathrm{H} 1]-[\mathrm{H} 4]$ hold. If the following two conditions:

$$
\begin{equation*}
a_{g}+\frac{a_{f} T^{q}}{\Gamma(q+1)}<1 \tag{3.2}
\end{equation*}
$$

and

$$
\begin{equation*}
\Upsilon_{T, q, \rho}=L_{g}+\frac{L_{f}(\rho) T^{q}}{\Gamma(q+1)}<1 \tag{3.3}
\end{equation*}
$$

hold, then system (1.1) has an unique solution.

Proof. Let

$$
\rho \geq \frac{\left\|u_{0}\right\|+a_{g}+\frac{a_{f} T^{q}}{\Gamma(q+1)}}{1-a_{g}-\frac{a_{f} T^{q}}{\Gamma(q+1)}}
$$

and define

$$
\begin{equation*}
C_{\rho}=\{x \in C(J, X):\|u(t)\| \leq \rho, t \in J\} . \tag{3.4}
\end{equation*}
$$

Define a operator $F: C_{\rho} \rightarrow C_{\rho}$ as follows

$$
\begin{equation*}
(F u)(t)=u_{0}-g(u)+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} f(s, u(s)) d s \tag{3.5}
\end{equation*}
$$

By Lemma 3.2, it is obvious that $F$ is well defined on $C_{\rho}$ in the sense of Bochner integrable.

We divide our proof into two steps.

Step 1. $F u \in C_{\rho}$ for every $u \in C_{\rho}$.
For every $u \in C_{\rho}$,

$$
\begin{aligned}
\|(F u)(t+\delta)-(F u)(t)\| \leq & \frac{1}{\Gamma(q)} \int_{0}^{t}\left((t-s)^{q-1}-(t+\delta-s)^{q-1}\right)\|f(s, u(s))\| d s+ \\
& +\frac{1}{\Gamma(q)} \int_{t}^{t+\delta}(t+\delta-s)^{q-1}\|f(s, u(s))\| d s \leq \\
\leq & \frac{a_{f}}{\Gamma(q)} \int_{0}^{t}\left((t-s)^{q-1}-(t+\delta-s)^{q-1}\right)(1+\|u(s)\|) d s+ \\
& +\frac{a_{f}}{\Gamma(q)} \int_{t}^{t+\delta}(t+\delta-s)^{q-1}(1+\|u(s)\|) d s \leq \\
\leq & \frac{a_{f}(1+\rho)}{\Gamma(q)}\left(\frac{t^{q}}{q}-\frac{(t+\delta)^{q}}{q}+\frac{\delta^{q}}{q}\right)+\frac{a_{f}(1+\rho)}{\Gamma(q)} \frac{\delta^{q}}{q} \leq \\
\leq & \frac{2 a_{f}(1+\rho)}{\Gamma(q+1)} \delta^{q} .
\end{aligned}
$$

It is easy to see that the right-hand side of the above inequality tends to zero as $\delta \rightarrow 0$. Therefore $F u \in C(J, X)$.

Moreover, for all $t \in J, u \in C_{\rho}$, due to the condition (3.2),

$$
\begin{aligned}
\|F u(t)\| & \leq\left\|u_{0}\right\|+\|g(u)\|+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\|f(s, u(s))\| d s \leq \\
& \leq\left\|u_{0}\right\|+a_{g}\left(1+\|u\|_{C}\right)+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} a_{f}(1+\|u(s)\|) d s \leq \\
& \leq\left\|u_{0}\right\|+a_{g}(1+\rho)+\frac{a_{f}(1+\rho)}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} d s \leq \\
& \leq\left\|u_{0}\right\|+a_{g}(1+\rho)+\frac{a_{f}(1+\rho) T^{q}}{\Gamma(q+1)} \leq \rho,
\end{aligned}
$$

which implies that $F u \in C_{\rho}$.

Step 2. $F$ is a contraction mapping on $C_{\rho}$. In fact, for any $u, v \in C_{\rho}$, we get

$$
\begin{aligned}
\|(F u)(t)-(F v)(t)\| & \leq\|g(u)-g(v)\|+\int_{0}^{t}(t-s)^{q-1}\|f(s, u(s))-f(s, v(s))\| d s \leq \\
& \leq L_{g}\|u-v\|_{C}+\frac{L_{f}(\rho)}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\|u(s)-v(s)\| d s \leq \\
& \leq\left[L_{g}+\frac{L_{f}(\rho) T^{q}}{\Gamma(q+1)}\right]\|u-v\|_{C}
\end{aligned}
$$

which implies that

$$
\|F u-F v\|_{C} \leq \Upsilon_{T, q, \rho}\|u-v\|_{C}
$$

Thus, $F$ is a contraction mapping on $C_{\rho}$ due to our condition (3.3). By applying Banach's contraction mapping principle we know that the operator $F$ has a unique fixed point on $C_{\rho}$. Therefore, system (1.1) has an unique solution.

Our second result uses the well known Krasnoselskii's fixed point theorem. For that, we make the following assumption.
[H5]: For every $t \in J$, the set $K=\left\{(t-s)^{q-1} f(s, u(s)): u \in C(J, X), s \in[0, t]\right\}$ is relatively compact.

Theorem 3.5. Assume that $[\mathrm{H} 1]-[\mathrm{H} 3]$ and $[\mathrm{H} 5]$ hold. If the condition (3.2) holds, then system (1.1) has at least one solution.

Proof. We subdivide the operator $F$ defined by (3.5) into two operators $P$ and $Q$ on $C_{\rho}$ as follows

$$
\begin{aligned}
& (P u)(t)=\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} f(s, u(s)) d s, t \in J, \\
& (Q v)(t)=u_{0}-g(v), t \in J
\end{aligned}
$$

where $C_{\rho}$ is given by (3.4).
Therefore, the existence of a solution of system (1.1) is equivalent to that the operator $P+Q$ has a fixed point on $C_{\rho}$.

The proof is divided into several steps.
Step 1. $P u+Q v \in C_{\rho}$ for every pair $u, v \in C_{\rho}$.
In fact, for every pair $u, v \in C_{\rho}$,

$$
\begin{aligned}
\|(P u)(t)+(Q v)(t)\| & \leq\left\|u_{0}\right\|+\|g(v)\|+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\|f(s, u(s))\| d s \leq \\
& \leq\left\|u_{0}\right\|+a_{g}\left(1+\|v\|_{C}\right)+\frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} a_{f}(1+\|u(s)\|) d s \leq \\
& \leq\left\|u_{0}\right\|+a_{g}(1+\rho)+\frac{a_{f}(1+\rho)}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} d s \leq \\
& \leq\left\|u_{0}\right\|+a_{g}(1+\rho)+\frac{a_{f}(1+\rho) T^{q}}{\Gamma(q+1)} \leq \rho
\end{aligned}
$$

which implies that $P u+Q v \in C_{\rho}$.
Step 2. $Q$ is a contraction mapping on $C_{\rho}$.
In fact, for every $v_{1}, v_{2} \in C_{\rho}$,

$$
\left\|Q v_{1}-Q v_{2}\right\|_{C}=\left\|g\left(v_{1}\right)-g\left(v_{2}\right)\right\| \leq L_{g}\left\|v_{1}-v_{2}\right\|_{C}
$$

Thus $Q$ is a contraction mapping due to $L_{g} \in(0,1)$.
Step 3. $P$ is a continuous operator.
For that, let $\left\{u_{n}\right\}$ be a sequence of $C_{\rho}$ such that $u_{n} \rightarrow u$ in $C_{\rho}$. Then, $f\left(s, u_{n}(s)\right) \rightarrow$ $f(s, u(s))$ as $n \rightarrow \infty$ due to the hypotheses [H2].

Now, for all $t \in J$, we have

$$
\left\|\left(P u_{n}\right)(t)-(P u)(t)\right\| \leq \frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\left\|f\left(s, u_{n}(s)\right)-f(s, u(s))\right\| d s
$$

On the one other hand using [H3], we get for each $t \in J$,

$$
\left\|f\left(s, u_{n}(s)\right)-f(s, u(s))\right\| \leq L_{f}(\rho)\left\|u_{n}(s)-u(s)\right\| \leq 2 \rho L_{f}(\rho)
$$

On the other hand, using the fact that the functions $s \rightarrow 2 \rho L_{f}(\rho)(t-s)^{q-1}$ is integrable on $J$, by means of the Lebesgue Dominated Convergence Theorem yields

$$
\int_{0}^{t}(t-s)^{q-1}\left\|f\left(s, u_{n}(s)\right)-f(s, u(s))\right\| d s \rightarrow 0
$$

Thus, $P u_{n} \rightarrow P u$ as $n \rightarrow \infty$ which implies that $P$ is continuous.

Step 4. $P$ is a compact operator.
Let $\left\{u_{n}\right\}$ be a sequence on $C_{\rho}$, then

$$
\begin{aligned}
\left\|\left(P u_{n}\right)(t)\right\| & \leq \frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1}\left\|f\left(s, u_{n}(s)\right)\right\| d s \leq \\
& \leq \frac{1}{\Gamma(q)} \int_{0}^{t}(t-s)^{q-1} a_{f}\left(1+\left\|u_{n}(s)\right\|\right) d s \leq \frac{(1+\rho) T^{q} a_{f}}{\Gamma(q+1)}
\end{aligned}
$$

Thus, $\left\{u_{n}\right\}$ is uniform boundedness.
Now we prove that $\left\{P u_{n}\right\}$ is is equicontinuous. For $0 \leq t_{1}<t_{2} \leq T$, we get

$$
\begin{aligned}
\left\|\left(P u_{n}\right)\left(t_{1}\right)-\left(P u_{n}\right)\left(t_{2}\right)\right\| \leq & \frac{1}{\Gamma(q)} \int_{0}^{t_{1}}\left(\left(t_{1}-s\right)^{q-1}-\left(t_{2}-s\right)^{q-1}\right)\left\|f\left(s, u_{n}(s)\right)\right\| d s+ \\
& +\frac{1}{\Gamma(q)} \int_{t_{1}}^{t_{2}}\left(t_{2}-s\right)^{q-1}\left\|f\left(s, u_{n}(s)\right)\right\| d s \leq \\
\leq & \frac{a_{f}}{\Gamma(q)} \int_{0}^{t_{1}}\left(\left(t_{1}-s\right)^{q-1}-\left(t_{2}-s\right)^{q-1}\right)\left(1+\left\|u_{n}(s)\right\|\right) d s+ \\
& +\frac{a_{f}}{\Gamma(q)} \int_{t_{1}}^{t_{2}}\left(t_{2}-s\right)^{q-1}\left(1+\left\|u_{n}(s)\right\|\right) d s \leq \\
\leq & \frac{a_{f}(1+\rho)}{\Gamma(q)}\left(\frac{t_{1}^{q}}{q}-\frac{t_{2}^{q}}{q}+\frac{\left(t_{2}-t_{1}\right)^{q}}{q}\right)+ \\
& +\frac{a_{f}(1+\rho)}{\Gamma(q)} \frac{\left(t_{2}-t_{1}\right)^{q}}{q} \leq \\
\leq & \frac{2 a_{f}(1+\rho)}{\Gamma(q+1)}\left(t_{2}-t_{1}\right)^{q} .
\end{aligned}
$$

As $t_{2} \rightarrow t_{1}$, the right-hand side of the above inequality tends to zero. Therefore $\left\{P u_{n}\right\}$ is equicontinuous.

In view of the condition [H5] and the Lemma 2.6, we know that $\overline{\operatorname{conv}} K$ is compact.
For any $t^{*} \in J$,

$$
\begin{aligned}
\left(P u_{n}\right)\left(t^{*}\right) & =\frac{1}{\Gamma(q)} \int_{0}^{t^{*}}\left(t^{*}-s\right)^{q-1} f\left(s, u_{n}(s)\right) d s= \\
& =\frac{1}{\Gamma(q)} \lim _{k \rightarrow \infty} \sum_{i=1}^{k} \frac{t^{*}}{k}\left(t^{*}-\frac{i t^{*}}{k}\right)^{q-1} f\left(\frac{i t^{*}}{k}, u_{n}\left(\frac{i t^{*}}{k}\right)\right)= \\
& =\frac{t^{*}}{\Gamma(q)} \zeta_{n}
\end{aligned}
$$

where

$$
\zeta_{n}=\lim _{k \rightarrow \infty} \sum_{i=1}^{k} \frac{1}{k}\left(t^{*}-\frac{i t^{*}}{k}\right)^{q-1} f\left(\frac{i t^{*}}{k}, u_{n}\left(\frac{i t^{*}}{k}\right)\right) .
$$

Since $\overline{\operatorname{conv}} K$ is convex and compact, we know that $\zeta_{n} \in \overline{\operatorname{conv}} K$. Hence, for any $t^{*} \in J$, the set $\left\{P u_{n}\right\}(n=1,2, \cdots)$ is relatively compact. From Ascoli-Arzela theorem every $\left\{P u_{n}(t)\right\}$ contains a uniformly convergent subsequence $\left\{P u_{n_{k}}(t)\right\}(k=1,2, \cdots)$ on $J$. Thus, the set $\left\{P u: u \in C_{\rho}\right\}$ is relatively compact.

Therefore, the continuity of $P$ and relatively compactness of the set $\left\{P u: u \in C_{\rho}\right\}$ imply that $P$ is a completely continuous operator. By Krasnoselskii's fixed point theorem, we get that $P+Q$ has a fixed point on $C_{\rho}$. Hence system (1.1) has a solution, and this completes the proof.

## 4. EXAMPLES

In this section we give two examples to illustrate the usefulness of our main results.
Example 4.1. Let us consider the following nonlocal problem of fractional differential equation

$$
\left\{\begin{array}{l}
{ }^{c} D^{q} u(t)=\frac{e^{-t} \rho|u(t)|}{\left(1+L e^{t}\right)(1+|u(t)| \mid}, q \in(0,1), t \in J=[0, T],  \tag{4.1}\\
u(0)+\sum_{j=1}^{m} \lambda_{j} u\left(t_{j}\right)=0,0<t_{1}<t_{2}<\cdots<t_{m}<T,
\end{array}\right.
$$

where $\rho, L, \lambda_{j}>0, j=1,2, \cdots, m$.
Set

$$
f(t, u)=\frac{e^{-t} \rho u}{\left(1+L e^{t}\right)(1+u)}, \quad(t, u) \in J \times[0, \rho],
$$

and

$$
g(u)=\sum_{j=1}^{m} \lambda_{j} u\left(t_{j}\right)
$$

Let $u_{1}, u_{2} \in X$ and $t \in J$. Then we have

$$
\begin{aligned}
\left|f\left(t, u_{1}\right)-f\left(t, u_{2}\right)\right| & \leq \frac{e^{-t} \rho}{1+L e^{t}}\left|u_{1}-u_{2}\right| \leq \\
& \leq \frac{\rho}{1+L}\left|u_{1}-u_{2}\right|
\end{aligned}
$$

and

$$
\begin{aligned}
\left|g\left(u_{1}\right)-g\left(u_{2}\right)\right| & \leq \sum_{j=1}^{m} \lambda_{j}\left|u_{1}\left(t_{j}\right)-u_{2}\left(t_{j}\right)\right| \leq \\
& \leq \sum_{j=1}^{m} \lambda_{j} \max _{t_{j} \in J}\left\{\left|u_{1}\left(t_{j}\right)-u_{2}\left(t_{j}\right)\right|\right\} .
\end{aligned}
$$

Obviously, for all $u \in X$ and each $t \in J$,

$$
|f(t, u)| \leq \frac{\rho}{1+L}\|u\|,
$$

and

$$
\begin{aligned}
|g(u)| & \leq \sum_{j=1}^{m} \lambda_{j}\left|u\left(t_{j}\right)\right| \leq \\
& \leq \sum_{j=1}^{m} \lambda_{j} \max _{t_{j} \in J}\left\{\left|u\left(t_{j}\right)\right|\right\} .
\end{aligned}
$$

It is obviously that our assumptions in Theorem 3.4 can be satisfied by choosing a sufficient large $L>0$ and small enough $T$ and $\lambda_{j}$ such that $\sum_{j=1}^{m} \lambda_{j}+\frac{\rho T^{q}}{(1+L) \Gamma(q+1)}<1$ for some $q \in(0,1)$. Therefore, the problem (4.1) has an unique solution.

Example 4.2. Let us consider another nonlocal problem of fractional differential equation

$$
\left\{\begin{array}{l}
{ }^{c} D^{q} u(t)=\frac{e^{-v t}|u(t)|}{\left(1+9 e^{t}\right)(1+|u(t)| \mid}, v>0, q \in(0,1), t \in J=[0, T],  \tag{4.2}\\
u(0)+\sum_{j=1}^{m} \lambda_{j} u\left(t_{j}\right)=0,0<t_{1}<t_{2}<\cdots<t_{m}<T .
\end{array}\right.
$$

Set

$$
f_{1}(t, u)=\frac{e^{-v t} u}{\left(1+9 e^{t}\right)(1+u)},(t, u) \in J \times[0,+\infty),
$$

and

$$
g(u)=\sum_{j=1}^{m} \lambda_{j} u\left(t_{j}\right), \text { where } \sum_{j=1}^{m} \lambda_{j}<1 .
$$

Let $v=\frac{1}{t^{2}}, t \in(0, T]$, it is obvious that $\lim _{t \rightarrow 0^{+}} \frac{t^{q-1}}{e^{\frac{1}{t}}}=0$. As a result, the set $K_{1}=\left\{(t-s)^{q-1} \frac{e^{-v s}|u(s)|}{\left(1+9 e^{s}\right)(1+|u(s)|)}: u \in C(J), s \in[0, t]\right\}$ is bounded and closed which implies that $K_{1}$ is compact. Thus, all the assumptions in Theorem 3.5 are satisfied by choosing a small enough $T$ and $\lambda_{j}$ such that $1-\sum_{j=1}^{m} \lambda_{j}-\frac{T^{q}}{10 \Gamma(q+1)}>0$, our results can be applied to the problem (4.2).

## Acknowledgments

We would like to thank the referees for their careful reading of the manuscript and their valuable comments.
This work was supported by Tianyuan Special Funds of the National Natural Science Foundation of China (No. 11026102), National Natural Science Foundation of Guizhou Province (2010, No. 2142). This work was also partially supported by National Natural Science Foundation of China (No. 10971173).

## REFERENCES

[1] L. Byszewski, Theorems about existence and uniqueness of solutions of a semilinear evolution nonlocal Cauchy problem, J. Math. Anal. Appl. 162 (1991), 494-505.
[2] L. Byszewski, V. Lakshmikantham, Theorem about the existence and uniqueness of a solution of a nonlocal abstract Cauchy problem in a Banach space, Appl. Anal. 40 (1991), 11-19.
[3] K. Balachandran, J.Y. Park, Nonlocal Cauchy problem for abstract fractional semilinear evolution equations, Nonlinear Anal. 71 (2009), 4471-4475.
[4] K. Balachandran, S. Kiruthika, J.J. Trujillo, Existence results for fractional impulsive integrodifferential equations in Banach spaces, Commun. Nonlinear Sci. Numer. Simulat. 16 (2011), 1970-1977.
[5] K. Deng, Exponential decay of solutions of semilinear parabolic equations with nonlocal initial conditions, J. Math. Anal. Appl. 179 (1993), 630-637.
[6] A.A. Kilbas, H.M. Srivastava, J.J. Trujillo, Theory and applications of fractional differential equations, [in:] North-Holland Mathematics Studies, vol. 204, Elsevier Science B.V., Amsterdam, 2006.
[7] V. Lakshmikantham, S. Leela, J.V. Devi, Theory of fractional dynamic systems, Cambridge Scientific Publishers, 2009.
[8] K.S. Miller, B. Ross, An introduction to the fractional calculus and differential equations, John Wiley, New York, 1993.
[9] G.M. N'Guérékata, A Cauchy problem for some fractional differential abstract differential equation with nonlocal conditions, Nonlinear Anal. 70 (2009), 1873-1876.
[10] G.M. N'Guérékata, Corrigendum: A Cauchy problem for some fractional differential equations, Commun. Math. Anal. 7 (2009), 11-11.
[11] G.M. Mophou, G.M. N'Guérékata, Existence of mild solutions of some semilinear neutral fractional functional evolution equations with infinite delay, Appl. Math. Comput. 216 (2010), 61-69.
[12] I. Podlubny, Fractional differential equations, Academic Press, San Diego, 1999.
[13] JinRong Wang, W. Wei, Y. Yang, Fractional nonlocal integrodifferential equations of mixed type with time-varying generating operators and optimal control, Opuscula Math. 30 (2010), 217-234.
[14] JinRong Wang, Y. Yang, W. Wei, Nonlocal impulsive problems for fractional differential equations with time-varying generating operators in Banach spaces, Opuscula Math. 30 (2010), 361-381.
[15] JinRong Wang, W. Wei, Y. Yang, On some impulsive fractional differential equations in Banach spaces, Opuscula Math. 30 (2010), 507-525.
[16] JinRong Wang, W. Wei, Y. Yang, Fractional nonlocal integrodifferential equations and its optimal control in Banach spaces, J. KSIAM 14 (2010), 79-91.
[17] JinRong Wang, Yong Zhou, Time optimal control problem of a class of fractional distributed systems, Int. J. Dyn. Diff. Eq. 3 (2011), in press.
[18] JinRong Wang, Yong Zhou, A class of fractional evolution equations and optimal controls, Nonlinear Anal. 12 (2011), 262-272.
[19] JinRong Wang, X. Yan, X.-H. Zhang, T.-M. Wang, X.-Z. Li, A class of nonlocal integrodifferential equations via fractional derivative and its mild solutions, Opuscula Math. 31 (2011), 119-135.
[20] JinRong Wang, W. Wei, Yong Zhou, Fractional finite time delay evolution systems and optimal controls in infinite dimensional spaces, J. Dyn. Contr. Syst. 17 (2011), in press.
[21] H. Ye, J. Gao, Y. Ding, A generalized Gronwall inequality and its application to a fractional differential equation, J. Math. Anal. Appl. 328 (2007), 1075-1081.
[22] Yong Zhou, Existence and uniqueness of fractional functional differential equations with unbounded delay, Int. J. Dyn. Diff. Eq. 1 (2008), 239-244.
[23] Yong Zhou, Feng Jiao, Existence of mild solutions for fractional neutral evolution equations, Comp. Math. Appl. 59 (2010), 1063-1077.
[24] Yong Zhou, Feng Jiao, Nonlocal Cauchy problem for fractional evolution equations Nonlinear Anal. 11 (2010), 4465-4475.

XiWang Dong
jzdxw@yahoo.com.cn
Guizhou University
Department of Mathematics
Guiyang, Guizhou 550025, P.R. China

JinRong Wang
wjr9668@126.com
Guizhou University
Department of Mathematics
Guiyang, Guizhou 550025, P.R. China
Yong Zhou
yzhou@xtu.edu.cn
Xiangtan University
Department of Mathematics
Xiangtan, Hunan 411105, P.R. China
Received: November 20, 2010.
Revised: December 9, 2010.
Accepted: December 10, 2010.

