

**POSITIVE SOLUTIONS  
OF ARBITRARY ORDER  
NONLINEAR FRACTIONAL DIFFERENTIAL  
EQUATIONS  
WITH ADVANCED ARGUMENTS**

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**Abstract.** In this paper, we investigate the existence and uniqueness of positive solutions to arbitrary order nonlinear fractional differential equations with advanced arguments. By applying some known fixed point theorems, sufficient conditions for the existence and uniqueness of positive solutions are established.

**Keywords:** positive solution, advanced arguments, fractional differential equations, super-linear (sublinear) condition, uniqueness.

**Mathematics Subject Classification:** 34A08, 34B18, 34K37.

## 1. INTRODUCTION

Fractional differential equations arise in many engineering and scientific disciplines as the mathematical modeling of systems and processes in the fields of physics, chemistry, aerodynamics, electrodynamics of complex medium, polymer rheology, etc. involves derivatives of fractional order ([20, 21, 26, 27]). The interest in the study of fractional-order differential equations lies in the fact that fractional-order models are more accurate than integer-order models, that is, there are more degrees of freedom in the fractional-order models. Fractional-order differential equations are also better for the description of hereditary properties of various materials and processes than integer-order differential equations. As a consequence, the subject of fractional differential equations is gaining much importance and attention. For details, see ([1, 8, 10, 11, 13–15, 22, 23, 25, 32]) and the references therein. Some recent work on fractional differential equations can be seen in ([2–6, 9, 12, 24, 28]).

The theory of differential equations with deviated arguments is an important and significant branch of nonlinear analysis. It is worthwhile mentioning that differential

equations with deviated arguments appear often in investigations connected with mathematical physics, mechanics, engineering, economics and so on (see [4, 12]). One of the basic problems considered in the theory of differential equations with deviated arguments is to establish convenient conditions guaranteeing the existence of solutions of those equations. For the general theory and applications of differential equations with deviated arguments, we refer the reader to the references ([5, 17, 18, 28–31]). However, fractional differential equations with deviated arguments have not been much studied and many aspects of these equations are yet to be explored. For some recent work on equations of fractional order with deviated arguments, see [7], and the references therein.

Motivated by some recent work on advanced arguments and boundary value problems of fractional order, in this paper, we investigate the following nonlinear fractional-order differential equation with advanced arguments

$$\begin{cases} D_0^\alpha u(t) + a(t)f(u(\theta(t))) = 0, & 0 < t < 1, \quad n-1 < \alpha \leq n, \\ u^{(i)}(0) = 0, & i = 0, 1, 2, \dots, n-2, \\ [D_0^\beta u(t)]_{t=1} = 0, & 1 \leq \beta \leq n-2, \end{cases} \quad (1.1)$$

where  $n > 3$  ( $n \in \mathbb{N}$ ),  $D_0^\alpha$  is the standard Riemann-Liouville fractional derivative of order  $\alpha$ ,  $f : [0, \infty) \rightarrow [0, \infty)$ ,  $a : [0, 1] \rightarrow (0, \infty)$  and  $\theta : (0, 1) \rightarrow (0, 1]$  are continuous functions.

By a positive solution of (1.1), one means a function  $u(t)$  that is positive on  $0 < t < 1$  and satisfies (1.1).

Our purpose here is to give existence and uniqueness results of positive solution to problem (1.1). We apply the Banach contraction principle and the well-known Guo-Krasnoselskii fixed point theorem:

**Theorem 1.1** ([16]). *Let  $E$  be a Banach space, and let  $P \subset E$  be a cone. Assume that  $\Omega_1, \Omega_2$  are open subsets of  $E$  with  $0 \in \Omega_1$ ,  $\bar{\Omega}_1 \subset \Omega_2$ , and let  $T : P \cap (\bar{\Omega}_2 \setminus \Omega_1) \rightarrow P$  be a completely continuous operator such that:*

- (i)  $\|Tu\| \geq \|u\|$ ,  $u \in P \cap \partial\Omega_1$ , and  $\|Tu\| \leq \|u\|$ ,  $u \in P \cap \partial\Omega_2$ ; or
- (ii)  $\|Tu\| \leq \|u\|$ ,  $u \in P \cap \partial\Omega_1$ , and  $\|Tu\| \geq \|u\|$ ,  $u \in P \cap \partial\Omega_2$ .

*Then  $T$  has a fixed point in  $P \cap (\bar{\Omega}_2 \setminus \Omega_1)$ .*

## 2. PRELIMINARIES

For the reader's convenience, we present some necessary definitions from fractional calculus theory and some known lemmas.

**Definition 2.1.** The Riemann-Liouville fractional integral of order  $q$  is defined as

$$I^q y(t) = \frac{1}{\Gamma(q)} \int_0^t (t-s)^{q-1} y(s) ds, \quad q > 0,$$

provided that the right side is pointwise defined on  $(0, \infty)$ .

**Definition 2.2.** The Riemann-Liouville fractional derivative of order  $q$  for a function  $y$  is defined by

$$D^q y(t) = \frac{1}{\Gamma(n-q)} \left( \frac{d}{dt} \right)^n \int_0^t (t-s)^{n-q-1} y(s) ds, \quad n = [q] + 1,$$

provided the right hand side is pointwise defined on  $(0, \infty)$ .

**Lemma 2.3** ([15]). Assume that  $y(t) \in C[0, 1]$ . Then the following problem

$$\begin{cases} D_0^\alpha u(t) + y(t) = 0, & 0 < t < 1, \quad n-1 < \alpha \leq n, \\ u^{(i)}(0) = 0, & i = 0, 1, 2, \dots, n-2, \\ [D_0^\beta u(t)]_{t=1} = 0, & 1 \leq \beta \leq n-2, \end{cases} \quad (2.1)$$

has the unique solution

$$u(t) = \int_0^1 G(t, s) y(s) ds,$$

where

$$G(t, s) = \begin{cases} \frac{t^{\alpha-1}(1-s)^{\alpha-\beta-1} - (t-s)^{\alpha-1}}{\Gamma(\alpha)}, & 0 \leq s \leq t \leq 1, \\ \frac{t^{\alpha-1}(1-s)^{\alpha-\beta-1}}{\Gamma(\alpha)}, & 0 \leq t \leq s \leq 1. \end{cases} \quad (2.2)$$

In the paper we will use the following lemma contained in [15].

**Lemma 2.4.** There exists a constant  $\gamma \in (0, 1)$  such that

$$\min_{t \in [\frac{1}{2}, 1]} G(t, s) \geq \gamma \max_{t \in [0, 1]} G(t, s) = \gamma G(1, s),$$

where  $G(t, s)$  is given by (2.2).

**Remark 2.5.** In [15] it was proved that  $\gamma$  has the expression

$$\gamma = \min \left\{ \frac{\left(\frac{1}{2}\right)^{\alpha-\beta-1}}{2^\beta - 1}, \left(\frac{1}{2}\right)^{\alpha-1} \right\}. \quad (2.3)$$

## 3. MAIN RESULTS

Let  $E = C[0, 1]$  be the Banach space of all continuous real-valued functions on  $[0, 1]$  endowed with the usual sup-norm  $\|\cdot\|$ . Let us introduce the cone

$$P = \{u | u \in C[0, 1], u \geq 0, \inf_{t \in [\frac{1}{2}, 1]} u(\theta(t)) \geq \gamma \|u\|\},$$

where  $\gamma \in (0, 1)$  is given by (2.3), and define the operator  $T : C[0, 1] \rightarrow C[0, 1]$  as follows:

$$Tu(t) = \int_0^1 G(t, s) a(s) f(u(\theta(s))) ds. \quad (3.1)$$

Using Lemma 2.3 with  $y(t) = a(t)f(u(\theta(t)))$ , the problem (1.1) reduces to a fixed point problem  $u = Tu$ , where  $T$  is given by (3.1). Thus the problem (1.1) has a solution if and only if the operator  $T$  has a fixed point.

By using the Ascoli-Arzelà theorem, it is easy to prove that  $T$  is completely continuous. Since  $t \leq \theta(t) \leq 1$ ,  $t \in (0, 1)$ , we have

$$\inf_{t \in [\frac{1}{2}, 1]} u(\theta(t)) \geq \inf_{t \in [\frac{1}{2}, 1]} u(t) \geq \gamma \|u\|. \quad (3.2)$$

Thus Lemma 2.4 and (3.2) show that  $TP \subset P$ , i.e.  $T : P \rightarrow P$ .

Set

$$f_0 = \lim_{u \rightarrow 0} \frac{f(u)}{u}, \quad f_\infty = \lim_{u \rightarrow \infty} \frac{f(u)}{u}.$$

Now we give our results.

**Theorem 3.1.** *Assume that:*

- (H<sub>1</sub>)  $a \in C([0, 1], [0, \infty))$  and  $a$  does not vanish identically on any subinterval.  
 (H<sub>2</sub>) The advanced arguments  $\theta$  satisfy  $t \leq \theta(t) \leq 1$ , for all  $t \in (0, 1)$ .

Then the problem (1.1) has at least one positive solution if:

- (i)  $f_0 = \infty$  and  $f_\infty = 0$  (sublinear)

or

- (ii)  $f_0 = 0$  and  $f_\infty = \infty$  (superlinear).

*Proof.* (i) *Sublinear case* ( $f_0 = \infty$  and  $f_\infty = 0$ ).

Since  $f_0 = \infty$ , then there exists a constant  $\rho_1 > 0$  such that  $f(u) \geq \delta_1 u$  for  $0 < u < \rho_1$ , where  $\delta_1 > 0$  satisfies

$$\delta_1 \gamma \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s) ds \geq 1. \quad (3.3)$$

Take  $u \in P$  such that  $\|u\| = \rho_1$ . Then, we have:

$$\begin{aligned} \|Tu\| &\geq Tu\left(\frac{1}{2}\right) = \int_0^1 G\left(\frac{1}{2}, s\right) a(s) f(u(\theta(s))) ds = \\ &= \int_0^{\frac{1}{2}} G\left(\frac{1}{2}, s\right) a(s) f(u(\theta(s))) ds + \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s) f(u(\theta(s))) ds \geq \\ &\geq \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s) f(u(\theta(s))) ds \geq \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s) \delta_1 u(\theta(s)) ds \geq \\ &\geq \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s) \delta_1 \gamma \|u\| ds = \delta_1 \gamma \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s) ds \|u\| \geq \|u\|. \end{aligned}$$

Let  $\Omega_{\rho_1} = \{u \in C[0, 1] \mid \|u\| < \rho_1\}$ . Thus, (3.4) shows that  $\|Tu\| \geq \|u\|, u \in P \cap \partial\Omega_{\rho_1}$ . Next, since  $f_\infty = 0$ , then there exists a constant  $R > \rho_1$  such that  $f(u) \leq \delta_2 u$  for  $u \geq R$ , where  $\delta_2 > 0$  satisfies

$$\delta_2 \int_0^1 G(1, s) a(s) ds \leq 1. \tag{3.4}$$

We consider the following two cases.

*Case 1.  $f$  is bounded.* Then there exists a constant  $R_1 > 0$  such that  $f(u) \leq R_1$  for  $u \in [0, \infty)$ . Now, we may choose  $u \in P$  such that  $\|u\| = \rho_2$ , where  $\rho_2 \geq \max\{\mu, R\}$ . Then,

$$Tu(t) = \int_0^1 G(t, s) a(s) f(u(\theta(s))) ds \leq R_1 \int_0^1 G(1, s) a(s) ds \triangleq \mu \leq \rho_2 = \|u\|. \tag{3.5}$$

*Case 2.  $f$  is unbounded.* Then there exists a constant  $\rho_2 > \frac{R}{\gamma} > R$  such that  $f(u) \leq f(\rho_2)$  for  $0 < u \leq \rho_2$ . (Note that  $f \in C([0, \infty), [0, \infty))$ ). Let  $u \in P$  such that  $\|u\| = \rho_2$ . We have

$$\begin{aligned} Tu(t) &= \int_0^1 G(t, s) a(s) f(u(\theta(s))) ds \leq \int_0^1 G(1, s) a(s) f(\rho_2) ds \leq \\ &\leq \delta_2 \rho_2 \int_0^1 G(1, s) a(s) ds = \delta_2 \int_0^1 G(1, s) a(s) ds \|u\| \leq \|u\|. \end{aligned} \tag{3.6}$$

Hence, in either case, we may always let  $\Omega_{\rho_2} = \{u \in C[0, 1] \mid \|u\| < \rho_2\}$  such that  $\|Tu\| \leq \|u\|$  for  $u \in P \cap \partial\Omega_{\rho_2}$ . Thus, by the first part of the Guo-Krasnoselskii fixed point theorem, we can conclude that (1.1) has at least one positive solution.

(ii) *Superlinear case* ( $f_0 = 0$  and  $f_\infty = \infty$ ).

Now, in view of  $f_0 = 0$ , there exists a constant  $r_1 > 0$  such that  $f(u) \leq \tau_1 u$  for  $0 < u < r_1$ , where  $\tau_1 > 0$  satisfies

$$\tau_1 \int_0^1 G(1, s)a(s)ds \leq 1. \quad (3.7)$$

Take  $u \in P$  such that  $\|u\| = r_1$ . Then we have

$$\begin{aligned} Tu(t) &= \int_0^1 G(t, s)a(s)f(u(\theta(s)))ds \leq \int_0^1 G(1, s)a(s)f(u(\theta(s)))ds \leq \\ &\leq \int_0^1 G(1, s)a(s)\tau_1 u(\theta(s))ds \leq \tau_1 \int_0^1 G(1, s)a(s)ds \|u\| \leq \|u\|. \end{aligned} \quad (3.8)$$

Let  $\Omega_{r_1} = \{u \in C[0, 1] \mid \|u\| < r_1\}$ . Thus, (3.8) shows  $\|Tu\| \leq \|u\|$ ,  $u \in P \cap \partial\Omega_{r_1}$ . Next, in view of  $f_\infty = \infty$ , there exists a constant  $r > r_1$  such that  $f(u) \geq \tau_2 u$  for  $u \geq r$ , where  $\tau_2 > 0$  satisfies

$$\tau_2 \gamma \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s)ds \geq 1. \quad (3.9)$$

Let  $\Omega_{r_2} = \{u \in C[0, 1] \mid \|u\| < r_2\}$ , where  $r_2 > \frac{r}{\gamma} > r$ . Then  $u \in P$  and  $\|u\| = r_2$  implies

$$\inf_{t \in [\frac{1}{2}, 1]} u(\theta(t)) \geq \gamma \|u\| > r,$$

and so

$$\begin{aligned} \|Tu\| &\geq Tu\left(\frac{1}{2}\right) = \int_0^1 G\left(\frac{1}{2}, s\right) a(s)f(u(\theta(s)))ds \geq \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s)\tau_2 u(\theta(s))ds \geq \\ &\geq \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s)\tau_2 \gamma \|u\| ds = \tau_2 \gamma \int_{\frac{1}{2}}^1 G\left(\frac{1}{2}, s\right) a(s)ds \|u\| \geq \|u\|. \end{aligned} \quad (3.10)$$

This shows that  $\|Tu\| \geq \|u\|$  for  $u \in P \cap \partial\Omega_{r_2}$ . Therefore, by the second part of the Guo-Krasnoselskii fixed point theorem, we can conclude that (1.1) has at least one positive solution  $u \in P \cap (\overline{\Omega_{r_2}} \setminus \Omega_{r_1})$ .  $\square$

**Theorem 3.2.** Assume that  $(H_1)$  holds. In addition we suppose that the following condition:

$(H_3)$  There exists a non-negative bounded integrable function  $M(t)$  such that

$$|f(u) - f(v)| \leq M(t)|u - v|, \quad t \in (0, 1), \quad u, v \in C[0, 1],$$

is satisfied. Then the problem (1.1) has a unique solution provided

$$L = \frac{1}{\Gamma(\alpha)} \int_0^1 (1-s)^{\alpha-\beta-1} a(s)M(s)ds \leq 1.$$

*Proof.* Let  $u, v \in C[0, 1]$ . Then we can get

$$\begin{aligned} |(Tu)(t) - (Tv)(t)| &\leq \int_0^1 G(t, s)a(s)|f(u(\theta(s))) - f(v(\theta(s)))|ds \leq \\ &\leq \int_0^1 G(t, s)a(s)M(s)|u(\theta(s)) - v(\theta(s))|ds \leq \\ &\leq \int_0^1 G(1, s)a(s)M(s)ds\|u - v\| = \\ &= \int_0^1 \frac{(1-s)^{\alpha-\beta-1}}{\Gamma(\alpha)} a(s)M(s)ds\|u - v\|. \end{aligned}$$

Thus,  $\|Tu - Tv\| \leq L\|u - v\|$ . As  $L < 1$ ,  $T$  is a contraction. Therefore, the conclusion of the theorem follows by the contraction mapping principle.  $\square$

#### 4. EXAMPLE

**Example 4.1.** Consider the fractional differential equation with advanced arguments

$$\begin{cases} D_0^{8.6}u(t) + e^{-t^2}f(u(\theta(t))) = 0, & 0 < t < 1, \\ u^{(i)}(0) = 0, & i = 0, 1, 2, \dots, 7, \\ [D_0^{6.8}u(t)]_{t=1} = 0, \end{cases} \quad (4.1)$$

where  $\alpha = 8.6, \beta = 6.8, \theta(t) = t^\nu, 0 < \nu < 1$  and

$$f(u) = \begin{cases} \frac{e^u}{\sin^2 u}, & 0 \leq u \leq \frac{\pi}{2}, \\ e^{\frac{\pi}{2}} + \frac{\sin u + 2}{u}, & u > \frac{\pi}{2}. \end{cases}$$

Obviously, conditions  $(H_1)$  and  $(H_2)$  of Theorem 3.1 hold. Through a simple calculation we can get  $f_0 = \infty$  and  $f_\infty = 0$ . Thus, by the first part of Theorem 3.1, we get that the problem (4.1) has at least one positive solution.

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*Received: August 8, 2010.*

*Revised: November 12, 2010.*

*Accepted: November 16, 2010.*