

ULF magnetic emissions connected with under sea bottom earthquakes

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Abstract. Measurements of ULF electromagnetic disturbances were carried out in Japan before and during a seismic active period (1 February 2000 to 26 July 2000). A network consists of two groups of magnetic stations spaced apart at a distance of ≈ 140 km. Every group consists of three, 3-component high sensitive magnetic stations arranged in a triangle and spaced apart at a distance of 4–7 km. The results of the ULF magnetic field variation analysis in a frequency range of $F = 0.002$ – 0.5 Hz in connection with nearby earthquakes are presented. Traditional Z/G ratios (Z is the vertical component, G is the total horizontal component), magnetic gradient vectors and phase velocities of ULF waves propagating along the Earth's surface were constructed in several frequency bands. It was shown that variations of the $R(F) = Z/G$ parameter have a different character in three frequency ranges: $F_1 = 0.1 \pm 0.005$, $F_2 = 0.01 \pm 0.005$ and $F_3 = 0.005 \pm 0.003$ Hz. Ratio $R(F_3)/R(F_1)$ sharply increases 1–3 days before strong seismic shocks. Defined in a frequency range of $F_2 = 0.01 \pm 0.005$ Hz during nighttime intervals (00:00–06:00 LT), the amplitudes of Z and G component variations and the Z/G ratio started to increase ≈ 1.5 months before the period of the seismic activity. The ULF emissions of higher frequency ranges sharply increased just after the seismic activity start. The magnetic gradient vectors ($\nabla \mathbf{B} \approx 1 - 5$ pT/km), determined using horizontal component data ($G \approx 0.03 - 0.06$ nT) of the magnetic stations of every group in the frequency range $F = 0.05 \pm 0.005$ Hz, started to point to the future center of the seismic activity just before the seismoactive period; furthermore they continued following space displacements of the seismic activity center. The phase velocity vectors ($\mathbf{V} \approx 20$ km/s for $F = 0.0067$ Hz), determined using horizontal component data, were directed from the seismic activity center. Gradient vectors of the vertical component pointed to the closest seashore (known as the “sea shore” effect). The location of the seismic activity centers by two gradient vectors, con-

structed at every group of magnetic stations, gives an ≈ 10 km error in this experiment.

1 Introduction

On the basis of modern knowledge, one can conclude that the main processes in the Earth's crust, connected with the earthquake preparation and reflected in ULF electromagnetic fields in a frequency range of $f = 0.011$ Hz, are the following: direct ULF radiation from the EQ origin zone (Kopytenko et al., 1990, 1993; Fraser-Smith et al., 1990; Bernardy et al., 1991; Molchanov et al., 1992); and the changing of a geoelectric conductivity inside and nearby the EQ hearth zone leads to the changing of amplitudes of reflected electromagnetic waves generated by outer sources (Mogi, 1985; Rokijtanskij, 1975; Kovtun, 1980; Gasanenko, 1963).

Spatial/temporal ULF characteristics observed on the Earth's surface are fragmental. This is caused by infrequent ULF magnetic measurements in seismic active zones during the earthquakes. Construction of magnetic variation polarization (the ratio of the vertical component of the magnetic field variations to the horizontal one), calculated from magnetic data measured on the Earth's surface by 3-component magnetometers, is traditional when investigating ULF magnetic emissions in the seismic active zones. It was shown (Hayakawa et al., 1996a; Hayakawa et al., 1996b; Kopytenko et al., 1999) that there is an increasing of the Z/H ratio before a strong earthquake takes place, and after the earthquake the ratio decreases. We continue to use this method. Time evolutions of the ULF magnetic variation amplitudes before and during seismic active periods were investigated in this work too.

A phase-gradient method (Kopytenko et al., 2000) using three-point measurements of magnetic field variations is applied. A vector of the phase velocity of waves propagating from a source is always directed from the source. A vector of the gradient of the wave intensities is always directed to the source. The method gives an opportunity to construct the

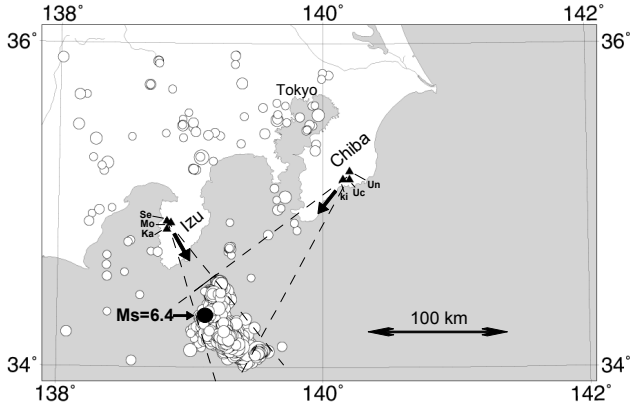


Fig. 1. Location of magnetic stations (black triangles) and seismic shock epicenters (circles). Black circle is the epicenter of the earthquake; black arrows represent the direction of the magnetic gradient vectors defined in the frequency range of $f = 0.05 \pm 0.005$ Hz during the period of 00:00–06:00 LT, 1 July 2000. Dashed lines are gradient cones of the ULF electromagnetic source location. Symbols *Se*, *Mo*, *Ka*, *Un*, *Uc* and *Ki* represent the first two letters of the names of the magnetic stations.

phase velocity and the gradient vectors along the Earth’s surface using three-points measurements. It provides the possibility of finding a direction to the ULF source and of determining the position of seismic activity centers, if the ULF disturbances are accompanied by these centers.

2 Experiment

Electromagnetic measurements were performed in a seismically active zone of Japan by two special sets of ground-based gradient installation, spaced about 140 km apart. The special array consists of three MVC-2DS high sensitive torsion magnetometers (50 Hz sampling rate, GPS system for data synchronization), arranged in a triangle and spaced ≈ 4 –7 km apart. One set of the magnetometers was installed at the Izu peninsula (Seikoshi, Mochikoshi and Kamo) another one at the Chiba peninsula (Unobe, Kiyosumi and Uchiura). The seismic active period began on 27 June 2000 and lasted more than 2 months. The positions of the magnetic stations and epicenters of the seismic shocks with magnitude $M \geq 2$ are shown in the Fig. 1. The size of the circles in Fig. 1 corresponds to the magnitude of the seismic shocks. The seismic shocks with the magnitude $M \geq 2$ were taken into consideration in this work since the shocks with smaller magnitudes were not observed at the recordings of the closest magnetic station (Kamo). The strongest shock (EQ) had the magnitude $M = 6.4$. The epicenter of this EQ was situated at a depth of ≈ 15 km under the sea surface at a distance of ≈ 80 km to the southeast from the magnetic stations located at the Izu peninsula and ≈ 140 km to the southwest from the magnetic stations located at the Chiba peninsula.

3 Data processing and results

Magnetic data from the Mochikoshi station were used for the construction of Fig. 2. This figure presents a connection of the magnetic field component ratios with the seismic activity. The number of seismic shocks during 6-hour intervals of every day (00:00–06:00 LT) during the period from 1 April to 27 July 2000 are shown as columns with a light color in the top panel (a) of Fig. 2. Columns with a dark color in the same panel correspond to the energy of the shocks with $M > 2$ summarized in every time interval. The energy of EQ was calculated according with the formula

$$\log(E) = \alpha + \beta M \quad (1)$$

where E is EQ energy, and M is a magnitude of the EQ. Coefficients $\alpha = 12.32$ and $\beta = 1.42$ were proposed in Mogi (1985) and King et al. (1969). Most of the EQ energy was selected on 1 July 2000 and is connected to the strongest EQ.

The seismic shocks with $M \geq 2$ are plotted in panel (b). Only shocks with epicenters situated closer than 120 km from the Mochikoshi station were taken into account. Strong seismic activity began on 27 June 2000 at $\approx 15:00$ LT and lasted more than 3 months. The strongest EQ ($M = 6.4$) took place on 1 July 2000 at 16:01:56 LT.

The lowest panel (e) in Fig. 2 presents K indexes calculated at the Kakioka observatory and summarized during the same time intervals (00:00–06:00 LT). The nighttime intervals were chosen due to the lower level of the industrial noise. Strong magnetic storms occurred on 6 April, 5 May, 23 May, 9 June, 12 June, 15 June and 15 July.

The magnetic component ratios $R = Z/G$ are marked in panel (d) of Fig. 2 as F_1 and F_2 . Symbol Z means the vertical component and G represents the total horizontal component. The lower curve in panel (d) presents the Z/G ratio in the frequency range of $F_1 = 0.0950$ – 1.05 Hz and the upper curve is the same ratio but for the lower frequency range of $F_2 = 0.0020$ – 0.08 Hz. These ratios and power spectra densities in frequency range $F = 0.002$ – 0.2 Hz were obtained using the maximum entropy spectral method. It is clearly seen that F_1 curve values sharply decrease just before the beginning of the seismic activity. F_2 curve values have no strong variation associated with the seismic activity, but the variations have a good correlation with the magnetic activity plotted in the lowest panel. The parameter $R(F_2)$ decreases when the magnetic activity increases.

The histogram in panel (c) is a ratio of the values of $R(F_2)$ and $R(F_1)$ plotted in panel (d). This parameter was constructed to emphasize the difference in time behaviour of these curves. As seen from this panel, the length of the histogram columns decrease when the magnetic activity increases.

Time evolutions of the emissions of the total horizontal magnetic field component G and Z/G ratios before and during the seismic active period (1 February to 26 July 2000) in 4 narrow-band ranges (from 0.002 to 0.2 Hz) are plotted

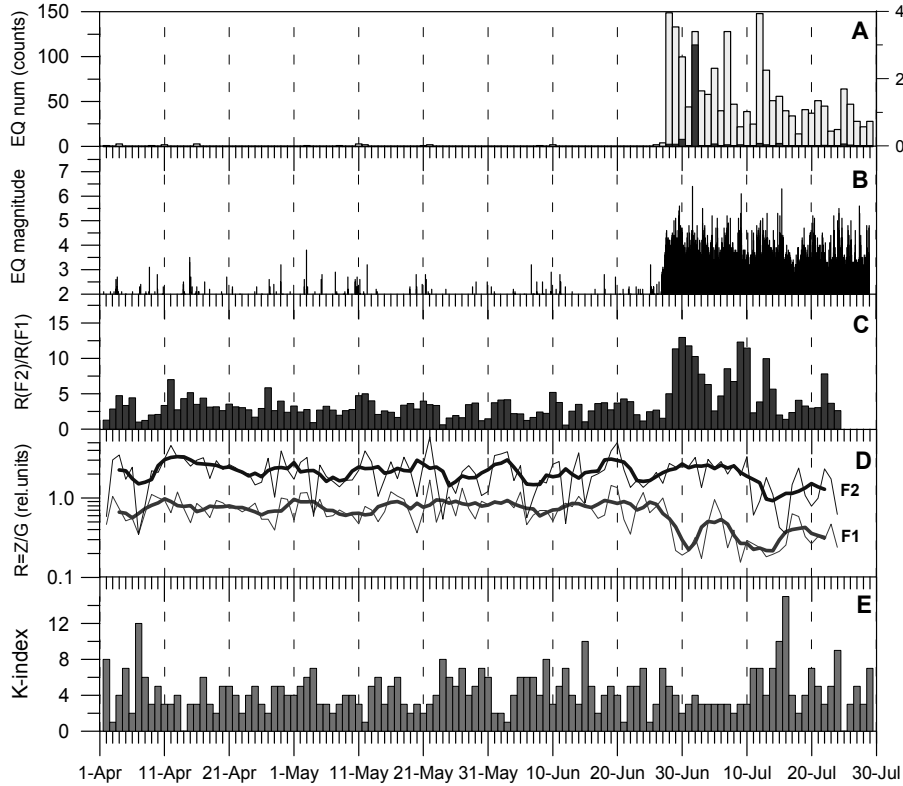


Fig. 2. Comparison of magnetic field component ratios Z/G with seismic activity in two frequency ranges of $F_1 = 0.1 \pm 0.005$ and $F_2 = 0.005 \pm 0.003$ Hz (Mochikoshi st., Japan, 2000). (A) The number of EQ during 6-hour intervals (00:00–06:00 LT) for every day (light color) and summary of the energy of earthquakes in these time intervals (dark color); (B) The magnitudes of the earthquakes with $M > 2$; (C) The ratio of the two curves from panel (D) with $R(F_2)/R(F_1)$; (D) The magnetic field component ratios ($R = Z/G$) in two frequency ranges of F_1 and F_2 , where bold curves are 5-day running means; (E) The K -indexes of the Kakioka magnetic station (sums in intervals 00:00–06:00 LT).

in the upper part of Fig. 3. The time evolutions for the frequency $f = 0.33 \pm 0.03$ Hz are presented in the lower part of the figure for a shorter time interval (20 June to 27 July 2000). The numbers in the lower part represent the seismic shock magnitudes (left side) and the seismic shock depths (right side). EQ with $M = 6.3$ produces a maximal magnetic effect in the higher frequency range, probably due to the smallest depth (5.4 km). The effect of a strong magnetic storm is clearly seen in the lower frequency ranges just after this EQ. The curves in Fig. 3 were constructed using the spectral maximum entropy method. The increasing of the G component amplitude and the Z/G ratio decreasing are seen just before the start of the seismic activity in the higher frequency ranges of 0.1, 0.2 and 0.33 Hz. The lower frequencies have none of the same sharp features connected with the seismic activity beginning, but the amplitude of the G component and the Z/G ratio both have noticeable 20-day variations before the seismic activity start. Two to three days before the strongest seismic shocks ($M > 6.0$), we observe a considerable increase in the emission intensities in the higher frequencies. These amplitude intensifications can possibly be the short-term precursors of strong earthquakes.

Time evolutions of the magnetic field amplitudes, gradients and Z/G ratios are presented in Fig. 4. The data of the magnetic field variations from three stations (Seikoshi, Mochikoshi and Kamo) were used. The data were preliminary filtered by a pass-band digital filter in a frequency range of $F = 0.005 \pm 0.003$ Hz. Each panel in the figure contains 3 curves marked by the symbols S , M , K , which represent the first letter of the magnetic station name. The three upper panels of Fig. 4 present the time evolution of the RMS values of the vertical (Z), and the total horizontal (G) components of the magnetic field variations and the Z/G ratio. The RMS values were calculated for 6-hour nighttime intervals (00:00–06:00 LT,) using the whole period under investigation.

As seen from Fig. 4, the amplitudes of the magnetic field variations have a tendency to increase with time. The increasing had started ≈ 1.5 – 2.0 months before the seismic active period and changed from ≈ 0.15 up to ≈ 0.2 nT in the Z component and from ≈ 0.07 to ≈ 0.08 nT in the G component. The increasing in the vertical component is more pronounced than in the total horizontal component. This fact is reflected in the Z/G ratio (upper most panel). One can see an increase in this ratio before the seismic active period.

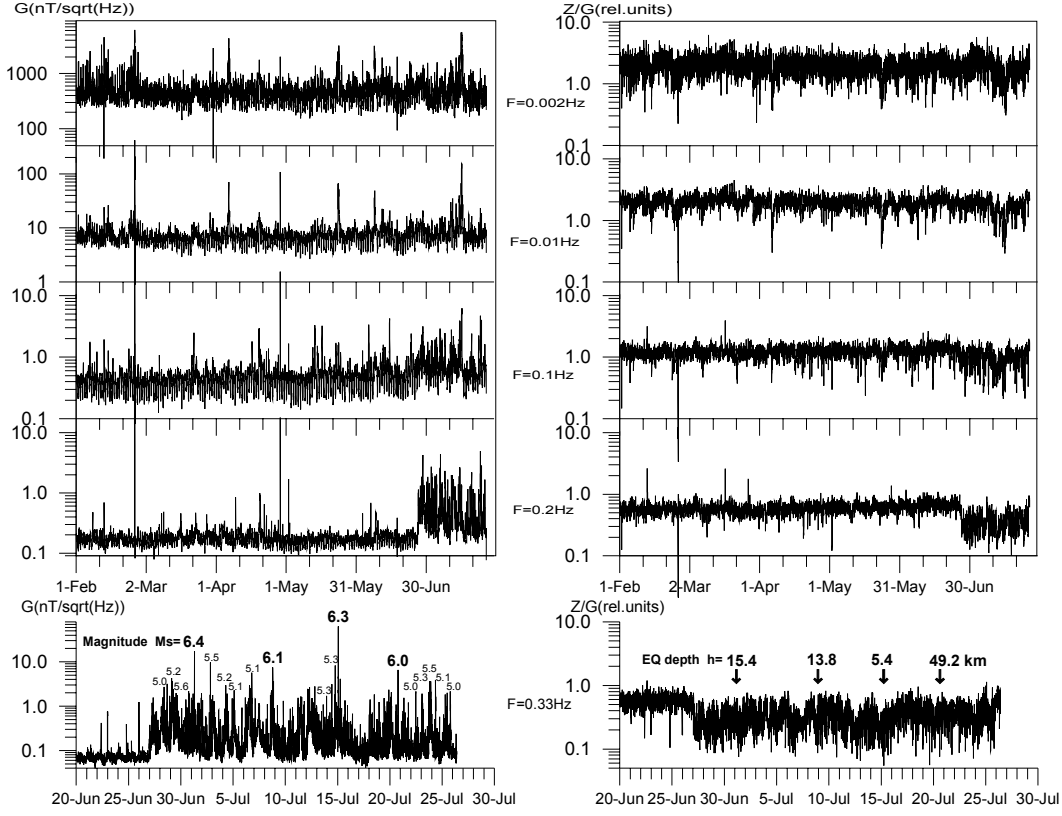


Fig. 3. Time evolutions of the total horizontal magnetic field component G and the Z/G ratios before and during the seismic active period of 1 February to 26 July 2000 in 4 narrow-band frequency ranges (upper part). Time evolution of the total horizontal magnetic field component G and the Z/G ratios for frequency $F = 0.33 \pm 0.03$ Hz during the period of 20 June to 27 July 2000 (lower part). Japan, st. Mochikoshi.

The two lowest panels in Fig. 4 present the time behaviour of the gradients of the G component of the magnetic field variations in the directions of Kamo-Seikoshi, Mochikoshi-Seikoshi, Kamo-Mochikoshi for the same nighttime intervals. The gradients were calculated using the spectral method. The square roots of the Z and G components power spectral density, calculated for the same 6-hour nighttime intervals, were integrated in the frequency band of $F = 0.01 \pm 0.005$ Hz after those differences were calculated for the pairs of magnetic stations: Kamo-Mochikoshi, Kamo-Seikoshi, Mochikoshi-Seikoshi. The vectors of the gradients were approximately pointed to the north at the beginning of May 2000 (two months before the seismic activity start) and to the southeast at the beginning of June 2000 (three weeks before the seismic activity start). The southeast direction is the direction of the future seismic activity region. To delete the occasional jumps in the results plotted in Fig. 4, three-point median filtering was used. All curves in Fig. 4 are 20-day running means.

4 Phase-gradient method of data processing

Three, 3-component magnetic stations arranged in a triangle and spaced about 4–7 km apart provide an opportunity to construct vectors of phase velocities of the ULF magnetic

waves propagating from a source and the magnetic field gradients along the Earth's surface. Any two pairs of magnetic stations can be used for the vector calculations.

Suppose we choose the following coordinate system: X axis is directed from magnetic station 1 to station 2, Y axis is orthogonal to the X axis and directed along the Earth's surface toward station 3, Z axis is a vertical one and directed downward. Let us choose the following two pairs of stations: 1–2 and 1–3. In this case, for the phase velocity vector, we have:

$$\alpha = \pm \arccos \left[\frac{V_{31} \cos(\beta)}{\sqrt{V_{21}^2 + V_{31}^2 - 2V_{21}V_{31} \sin(\beta)}} \right]$$

$$|V| = V_{21} \cos(\alpha) = V_{31} \sin(\alpha + \beta) \quad (2)$$

For the gradient vector:

$$\alpha = \pm \arccos \left[\frac{G_{21} \cos(\beta)}{\sqrt{G_{21}^2 + G_{31}^2 - 2G_{21}G_{31} \sin(\beta)}} \right]$$

$$|G| = G_{21} \cos(\alpha) = G_{31} \sin(\alpha + \beta) \quad (3)$$

The angle α in Eqs. (2) and (3) is the angle between the X axis and the directions of the vectors. The angle β is the angle between the Y axis and a line connecting stations 1 and 3. In Eqs. (2) and (3), V_{21} , V_{31} values (phase velocities in

the direction from station 2 to the station 1 and from station 3 to station 1) and G_{21} , G_{31} values (gradients in the directions from station 2 to station 1 and from the station 3 to station 1 can be defined in the following way:

$$\begin{aligned} V_{21} &= d_{21}/T_{21}, & V_{31} &= d_{31}/T_{31}, \\ G_{21} &= \Delta B_{21}/d_{21}, & G_{31} &= \Delta B_{31}/d_{31} \end{aligned} \quad (4)$$

where d_{21} , d_{31} represent the distances between the magnetic stations situated at points 2 and 1, 3 and 1, respectively; T_{21} , T_{31} are the time (phase) shifts of the ULF geomagnetic pulsations between the magnetic stations 2 and 1, 3 and 1, respectively; ΔB_{21} , ΔB_{31} represent the values of the differences (taking into account the phase shifts) between stations 2 and 1, 3 and 1 in any magnetic field component, respectively. For the geomagnetic coordinate system, similar formulas were reported in Kopytenko et al. (2000).

The phase shift distributions are plotted in Fig. 5. Initial data were preliminary filtered by pass-band filters with central frequencies shown in the figure and a half-width of 0.005 Hz. The phase shifts of magnetic field variations between pairs of magnetic stations were defined for the nighttime intervals 00:00–06:00 LT. The length of the data window for the determination of the time shifts and gradients was $T = 5/f_c$ (f_c is the central frequency of the pass-band filter). The data window moved along the 6-hour data realization with a step equal to half of the window.

Maximums of the time shift distributions (most probable values) have a negative sign for the horizontal component of the magnetic field variations and a positive sign for the vertical component, as can be seen from Fig. 5. This means that the horizontal component waves of the ULF magnetic field variations propagate primarily in the direction from Mochikoshi to Seikoshi (from southeast to northwest), but the waves in the Z component propagate in the opposite direction. Thin curves present the phase distributions in the time interval 00:00–06:00 LT 26 June 2000 (just before the beginning of the seismic active period), and bold curves were plotted for the time interval 00:00–06:00 LT, 1 July 2000 (during the seismic active period). The influence of the seismic activity itself is seen in the broadening of the distributions. It can be connected to the increase in the seismic active region size and to the probable increase in the ULF source size. There are no seismic shacking effects in the investigated frequency range, since we do not observe an additional maximum at the ≈ -0.5 s shift. The shift has to arise at the phase distributions as a time interval of the seismic wave propagation between the two magnetic stations.

The horizontal component curves in Fig. 5 have the distributions with a larger half-width during the seismic active period. The influence of the seismic activity in the vertical component phase shift distributions is very small. The time shifts depend on the frequencies: the longer the period is of the magnetic field variations, the higher the absolute value of the time shift. The dependence between the time shifts and the frequencies is approximately the following $-\Delta t \approx F^{-1/2}$. Hence, the phase velocity values of the electromagnetic waves along the Earth's surface have the inverse

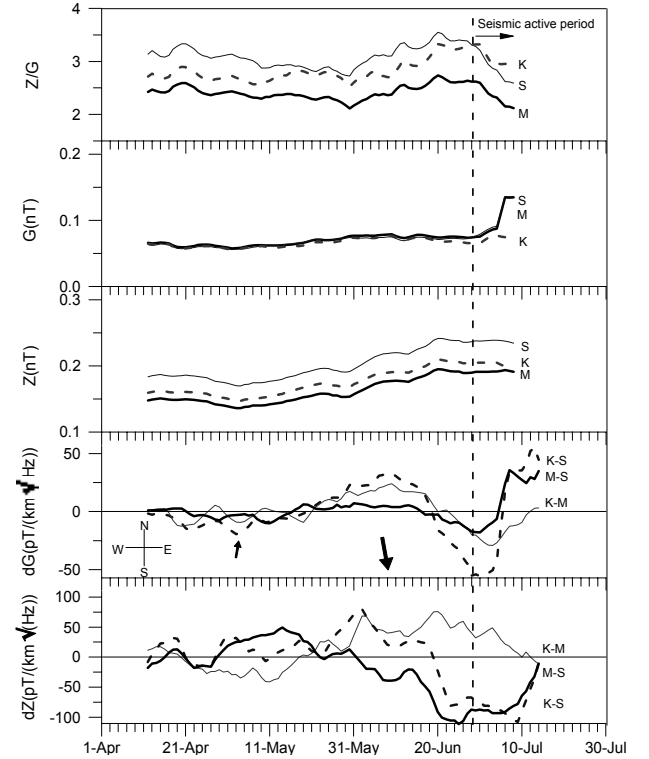


Fig. 4. Time evolutions of the magnetic field variation amplitudes and the Z/G ratios before and during the seismic active period at 3 magnetic stations (Mochikoshi, Seikoshi and Kamo, 1 April to 27 July 2000). The frequency range is $F = 0.005 \pm 0.003$ Hz. Symbols K , M , S represent the results of the data processing using Kamo, Mochikoshi, Seikoshi data. Vertical dashed line represents the moment when the seismic activity starts. Arrows at the second from the bottom panel show the directions of the total horizontal component gradients. All curves are 20-day running means.

dependence. It corresponds to the well-known expression (Kovtun, 1980) for the phase velocity of the electromagnetic plane waves: $V = 10^3(10\rho F)^{1/2}$ (F is a frequency and ρ is an apparent resistivity).

An example of the amplitude and magnetic gradient statistical distributions is presented in Fig. 6. Maximums of the distributions are the most probable values of the amplitudes and gradients. The histograms were constructed for the time interval of 00:00–06:00 LT, 26 June 2000. The raw data were preliminary filtered by the pass-band filter ($F = 0.05 \pm 0.005$ Hz). The amplitude (peak-to-peak values) distributions of the total horizontal component ($G = H \sin \alpha + D \cos \alpha$, $\alpha = \arctan(H/D)$) at the Izu and Chiba peninsulas are plotted in the left part of the figure. The most probable amplitude values are ≈ 0.035 nT (Chiba) and ≈ 0.065 nT (Izu). The gradient distributions are plotted in the right side of Fig. 6. The negative sign of the gradient values means that the gradient vector is directed from Seikoshi to Mochikoshi (Izu), and from Unobe to Kiyosumi (Chiba). As seen from Fig. 6, the gradient vectors of the total horizontal component are directed to the southeast from Izu and to the

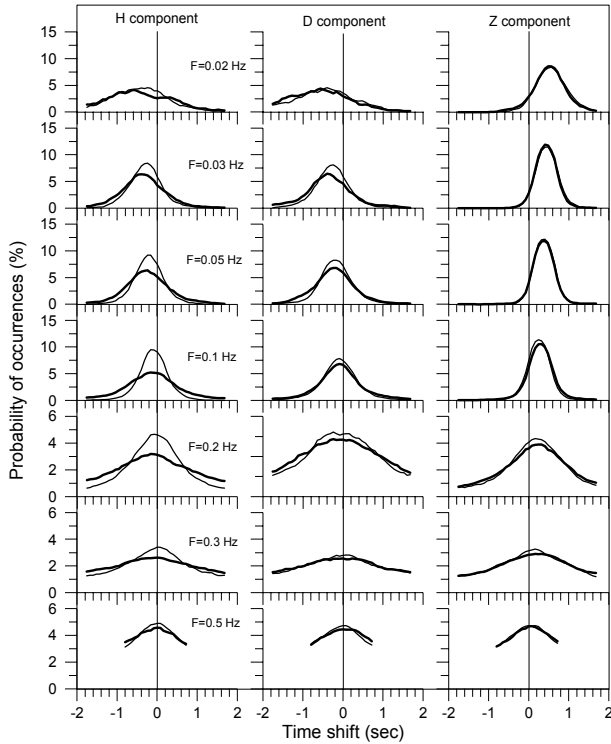


Fig. 5. Phase shift distributions of the ULF variations in the direction from st. Seikoshi to st. Mochikoshi for 3 magnetic field components in 7 frequency ranges. Thin curves are plotted for period of 00:00–06:00 LT, 26 June 2000 (before the start of the seismic active period), bold curves represent the period of 00:00–06:00 LT, 1 July 2000 (during the seismic active period). All curves are 7-point running means.

southwest from Chiba (to the side of the seismic activity zone in both cases), but the gradient vectors of the vertical component are directed to the northwest from Izu group of the stations (to the closest seashore). Z gradients at Chiba had values close to zero in the direction from Unobe to Kiyosumi. A line connecting Unobe and Kiyosumi stations is approximately parallel to the closest seashore; hence, the “seashore” effect does not produce outstanding gradients in this direction.

Figures 5 and 6 were constructed using one pair of the magnetic stations from two groups at Izu and Chiba: Seikoshi-Mochikoshi or Unobe-Kiyosumi. Using three-point measurements at any group of magnetic stations, we can calculate the total horizontal (along the Earth’s surface) vectors of the phase velocities and gradients of the magnetic variations in accordance with the Eqs. (2–4). These vectors for the ULF emissions with a period of $T = 15$ s for the time interval 00:00–06:00 LT, 27 June and 1 July 2000 are plotted in Fig. 7 using the data from the Izu group of stations. Seismic activity centers were defined using epicenters of the seismic shocks with $M > 3$. Black points mark the epicenters. Grey circles mark the activity centers. These centers shifted at a distance of ≈ 15 km during 5 days, as can be seen from

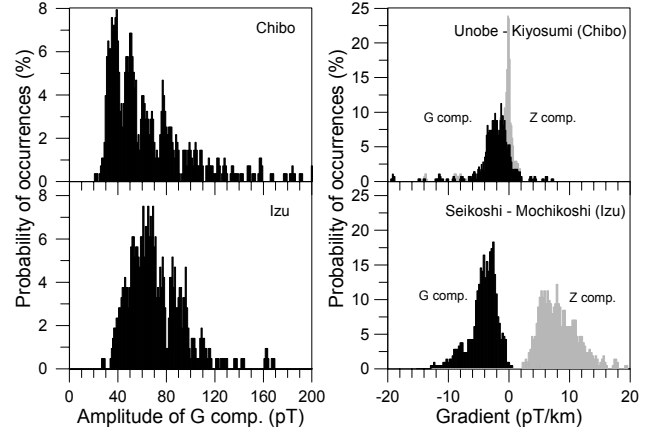


Fig. 6. Distributions of the total horizontal component amplitudes (left) and the magnetic field gradients (right) at the Izu and Chiba peninsulas for the geomagnetic variations ($F = 0.05 \pm 0.005$ Hz) during the period of 00:00–06:00 LT, 26 June 2000. The black color represents the total horizontal component, the grey color represents the vertical component.

Fig. 7. On the 27 June 2000, the gradients and phase velocity vectors at Izu rotated 01.07 relatively counterclockwise at an ≈ 100 angle accordingly to the seismic activity centers displacement. We can see that the horizontal component gradient vectors are directed to the source of the ULF emissions. The phase velocity vectors of the ULF waves point in the direction from the source. The vertical component vectors point to the closest seashore situated at ≈ 5 km from the Seikoshi magnetic station despite a good correlation between the ULF variations in the Z and G magnetic components.

5 Discussion

The results of the investigation of the ULF magnetic disturbances are presented in Figs. 2 to 4. It is clearly seen that the disturbances with periods close to $T = 100$ s have the usual “precursor” behaviour where the Z/G ratio started to increase ≈ 1 month before the seismic activity and the ratio then decreased during the seismic activity (Hayakawa et al., 1996a, 1996b; Kopytenko et al., 1999). The emission amplitudes in the total horizontal and vertical components have a clear increase during ≈ 1.5 months before the seismic shocks begin (Fig. 4). The disturbances of the longer period ($T = 200$ s) have not the same peculiarity during this event.

The ULF emissions with a shorter period ($T = 10$ s) have a different time evolution that was not observed earlier. We can see from Fig. 2 (curve F_1) that just before the seismic active period, the Z/G ratio of these emissions (parameter $R(F_1)$) decreases, while the parameter $R(F_2)$ has very small variations. The ratio $R(F_2)/R(F_1)$ has sharp variations after the beginning of the seismic active period (the middle panel in Fig. 2). Strongest seismic shocks are followed by the maximal values of this ratio except EQ with $M = 6.0$ (probably due to big EQ depth of 49.2 km). Therefore, the variations

in the $R(F) = Z/G$ parameter have a different character in three frequency ranges: $F_1 = 0.02 - 0.5$, $F_2 = 0.01 \pm 0.005$ and $F_3 = 0.005 \pm 0.003$ Hz. The ratio $R(F_3)/R(F_1)$ sharply increases after the beginning of strong seismic activity. This phenomenon is probably caused by the intensive ULF electromagnetic radiation from the seismic source. As seen in Fig. 2, the strong magnetic storm influence leads to a decreasing of the Z/G ratios in the longest period range.

The essence of this effect has become clear after an investigation of the results presented in Figs. 5 to 7. As it was reported in the previous sections, the phase-gradient method provides the opportunity to find the vectors of the phase velocities of ULF waves propagating along the Earth's surface and their magnetic gradients by using the special magnetometer array (three, 3-component magnetic stations situated at the top of the triangle and spaced a small distance apart). To find the most probable values, the statistical distributions of the phase and magnetic gradients were constructed similarly to the distributions presented in Figs. 5 and 6. Using the horizontal component vectors, we can find the direction of the ULF source from the Izu and Chiba peninsulas. This procedure can be called "magnetic location" of the ULF electromagnetic sources. The black arrows in Fig. 1 show magnetic gradient directions from Izu and Chiba. The dashed lines in Fig. 1 present the gradient cones used for the magnetic location in the frequency range of $F = 0.067 \pm 0.005$ Hz. The most probable values of the gradients were found from the statistical gradient value distribution constructed for period of 00:00–06:00 LT, 1 July 2000. The cone borders were determined using half of the distribution heights. It is clearly seen that the location area covers the region of the seismic shock epicenters. The location area center is a 5–10 km distance from the strongest earthquake with magnitude $M = 6.4$. Therefore, we can propose that the seismic hearth is the source of the ULF electromagnetic disturbances in a wide frequency range.

The magnetic gradient of the ULF disturbances in the vertical component is directed to the closest seashore (Fig. 7); we probably observe a so-called "seashore" effect. The phase velocity vector in the Z component is directed from the shore. The directions of the phase velocity and gradient vectors do not coincide with the Z and G components, but the magnetic variations (the wave forms) in all the components are well correlated. This means that they have a common primary source. We suppose that the vertical magnetic component variations were caused by induction currents in sea water (sea depth is more than 1 km to the west of the Izu peninsula). The currents are induced by the horizontal component variations (orthogonal to the seashore) propagating from the seismic source region and they produce magnetic field variations just in the Z component.

As seen from Fig. 6, the most probable amplitudes (peak-to-peak values) of the ULF signal are ≈ 0.035 nT at Chiba (distance from the center of the seismic activity ≈ 135 km) and ≈ 0.060 nT at Izu (distance from the seismic activity center ≈ 85 km). If we neglect a damping in the Earth's crust, we can assume that the amplitude of the ULF emissions changes

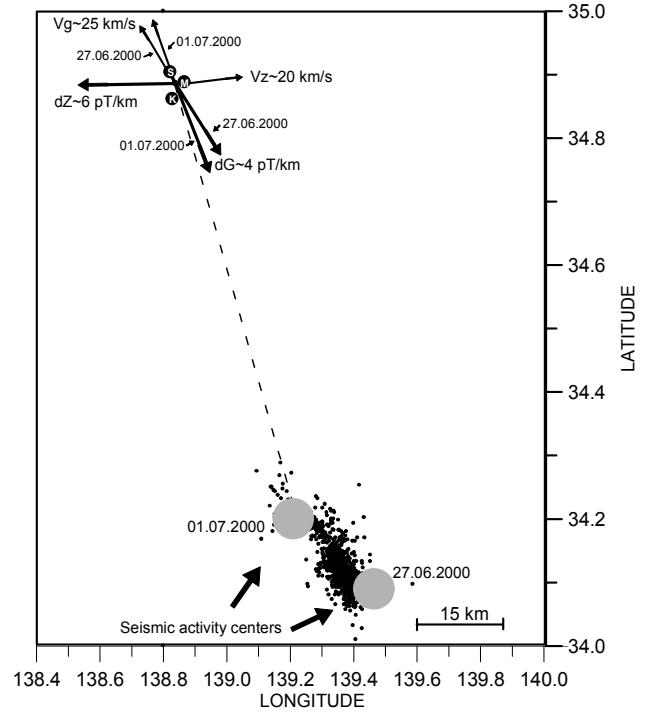


Fig. 7. Vectors of gradients and phase velocities of ULF magnetic emissions ($F = 0.067$ Hz). Black circles (with the letters S , M , K inside) represent the magnetic stations Seikoshi, Mochikoshi and Kamo. Black points represent the epicenters of seismic shocks with magnitudes $M > 3$ for the time period 27 June to 2 July 2000. The letters V_g (for the total horizontal component) and V_z (for the vertical component) mark the vectors of the phase velocities along the Earth's surface. The vectors of the gradients are marked by the letters dG and dZ . The grey circles represent the seismic activity centers on 27 June and 2 July 2000. The dashed line connects the magnetic stations and the epicenter of the strongest EQ with $M = 6.4$.

with the distance from the source as $\approx 1/R$. A simple dependence can be proposed:

$$\mathbf{B}(\mathbf{R}) = A_0 \exp(-f\beta R)/R \quad (5)$$

where \mathbf{B} is the ULF emission amplitude; \mathbf{R} is the distance from the source center; A_0 and β are the parameters depending on the intensity of the source and damping in the Earth's crust; f is the frequency of the electromagnetic wave. By using Eq. (5) and the amplitude values from Fig. 6, we can find that for the frequency of $F = 0.05$ Hz, the amplitude value equals ≈ 1.2 nT at the 5 km distance from the center of the ULF source (approximately at the border of the seismic activity region) and ≈ 0.6 nT at the distance 10 km. Similar values were observed near the Loma-Prieta EQ epicenter (Fraser-Smith et al., 1990; Bernardy et al., 1991).

A ULF generation mechanism can be connected with a region where the intense production of microcracks in the seismic activity hearth takes place (Molchanov and Hayakawa, 1994a, 1994b, 1998). Observed from a large distance, the magnetic field component of the ULF emissions has to depend on the orientation of the microcracks (Molchanov and

Hayakawa, 1998). In the investigated event, we primarily observed the horizontal component. This means that the microcracks have primarily opened in the vertical direction. Any local closed configuration of currents inside a seismic active region cannot produce the magnetic field emissions depending on the distance as $1/R$. The production of such a dependence can be received if the electric charge acceleration is the mechanism of the electromagnetic emissions. Movement of the walls accelerates the electric charges in the microcrack walls during the microcrack's opening process and transverse electromagnetic fields are then radiated. These fields will change with a distance as $1/R$. The model of the electric dipole oscillations was reported by Warwick et al. (1982) and Gershenson et al. (1989).

Unfortunately, the frequencies ($f > 1$ MHz) in this generation mechanism are too high, as discussed by Molchanov and Hayakawa (1998). The frequencies of the electromagnetic waves can be much lower if we assume that the electromagnetic fields are produced by the acceleration of charged water dust and small particles that arise from inside the microcracks during the opening process. The charged particles will be accelerated during the time when the electric charge exists inside the microcrack walls, or during the time when the conductive currents exist, which destroy the microcrack walls charge. As reported in Molchanov and Hayakawa (1998), this time is $> 10^{-3}$ s (the time depends on a size of the microcracks and a conductivity of a media around the microcracks); hence, it leads to lower frequencies than those in the models of Warwick et al. (1982); and Gershenson et al. (1989). In the proposed generation mechanism, the vertical direction of the microcrack's opening is also necessary to receive at a large distance the horizontal magnetic field component of the emissions.

A mechanism of the ULF electromagnetic field generation, associated with the deformation of a solid, was proposed in Vallianatos and Tzanis (1998, 1999a, 1999b) and Tzanis et al. (2000). The solid deformation generates electric currents. Therefore, we can observe ULF electromagnetic waves outside the deformation zone. But in this case, the ULF emission amplitudes will change with a distance from the source close to the $1/R$ law, only if the size of the current system will be much more than a distance from the current system to the observational points.

6 Summary

The next properties of the ULF emissions can be defined:

- The emissions arise just before and during the seismic activity period;
- The waveform of the emissions looks like a wide-band electromagnetic noise;
- The horizontal magnetic component of the emissions was primarily observed at the Izu and Chiba peninsulas during the investigated event;

- The ULF variations in the vertical magnetic component were caused by induction currents in sea water (the sea depth is more than 1 km near the Izu peninsula);
- The emission amplitudes increase with frequency increasing;
- The emission amplitudes have a distance dependence of $\approx 1/R$.

Long-period variations in the amplitudes of the ULF disturbances in the Z and G magnetic field components and the increasing of the Z/G ratio before the seismic active period can serve as middle-term predictors of a strong EQ. The amplitude intensifications of the ULF emissions in frequencies of 0.5–0.05 Hz can be the short-term precursors of strong earthquakes.

As it was shown in this work, the direction of the gradient and the phase velocity vectors of the ULF magnetic disturbances, calculated in the way described above, points to the region of the EQ preparation. Two groups of magnetic stations spaced at a distance of 50–150 km provide the opportunity to locate this region at distances of ≤ 100 km from the magnetic stations. Using the observations of the ULF electromagnetic disturbances and the suggested method of the magnetic location of the ULF electromagnetic sources are very important for EQ predictions since many strong EQs have no foreshocks (Mogi, 1985).

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