## **2-LP-SIMA-S07:**

# Modelling an HTS dynamo using a segregated finite-element model

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**Experimental HTS** 

#### Segregated finite-element model geometry: permanent magnet model, time-independent (left),

### **Modelling Framework**

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Permanent magnet movement past the HTS wire is simulated using time-dependent boundary conditions &a translation operator for the magnet's static magnetic field



#### dynamo schematic

#### **Electromagnetic model:**

2D (infinitely long) *H*-formulation COMSOL Multiphysics 5.3a

$$\nabla \times \boldsymbol{E} + \left(\frac{d\boldsymbol{B}}{dt}\right) = \nabla \times \boldsymbol{E} + \frac{d(\mu_0 \mu_r \boldsymbol{H})}{dt} = 0$$
$$\nabla \times \boldsymbol{H} = \boldsymbol{J}$$
$$\boldsymbol{E} = \begin{bmatrix} E_0 & J & J \end{bmatrix} = \begin{bmatrix} n-1 & J & J \end{bmatrix}$$

$$E = \frac{1}{J_{c}(B, \theta)} \left| \frac{1}{J_{c}(B, \theta)} \right|$$
$$E_{0} = 10^{-4} \text{ V/m}$$

Current constraint (open-circuit):

$$I_{sc} = \int_{\Omega_{sc}} \boldsymbol{J} \cdot d\boldsymbol{s} = 0$$

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Cumulative,

#### **Permanent magnet properties:**

 $B_{\rm r} = 0.5 {\rm T}$ Width  $(w_m) = \text{length} (L) = \text{depth} = 10 \text{ mm}$ Gap between wire & PM: 3 mm Voltage scaled by active magnet length, L  $\boldsymbol{E} \cdot d\boldsymbol{s}$ 

HTS wire, time-dependent (right)

#### **Assumed wire properties:**

SCS4050-AP, width 4 mm, extrapolated to 12 mm for the model  $I_c \approx 320 \,\mathrm{A} \,\mathrm{(self-field)}$ 1  $\mu$ m HTS layer, artificially expanded to 5  $\mu$ m to improve computational speed

' H<sub>ext</sub>

· H<sub>self</sub>

50  $\mu$ m substrate (Hastelloy), 266 n $\Omega$ ·m 25  $\mu$ m top/bottom copper stabiliser, 3 n $\Omega$ ·m



Measured  $J_c(B,\vartheta)$  characteristics (left) &  $n(B,\vartheta)$  (right) for the SuperPower SCS4050-AP HTS wire

#### **Electromagnetic boundary conditions:**

On outer boundary:  $H = H_{ext} + H_{self}$ where  $H_{ext}(x,y,t) = T_t H_{PM}(x,y) = H_{PM}(x+x_M(t),y+y_M(t))$ 

 $(x_{\rm M}, y_{\rm M})$  is the time-dependent position of the HTS assembly relative to O

 $H_{self}$  is obtained by the 2D integration of the Biot-Savart law:

$$H_{self,x}(x, y, t) = \frac{1}{2\pi} \iint_{\Omega_{sc}} \frac{-J_z(x', y', t) \cdot (y - y')}{(x - x')^2 + (y - y')^2} dx' dy'$$
$$H_{self,y}(x, y, t) = \frac{1}{2\pi} \iint_{\Omega_{sc}} \frac{J_z(x', y', t) \cdot (x - x')}{(x - x')^2 + (y - y')^2} dx' dy'$$

**Thermal model (when included):** 

$$\rho \cdot C \frac{dT}{dt} = \nabla \cdot (\kappa \nabla T) + Q$$
  
Heat source,  $Q = E \cdot J$ 

Assumed thermal properties for YBCO, copper & Hastelloy substrate from reference data published in Zhang *et al.* J. Appl. Phys. **112**, 043912 (2012)









for magnet frequencies, f = 10 - 500 Hz











For the HTS wire only, the output increases linearly. The inclusion of generated heat reduces the output, this effect increasing with frequency.

Including the whole wire architecture produces results observed in experiments: a linear output for low-f, a plateau & then reducing output for high-f.

For high-f, current sharing between the layers in the HTS wire architecture become important; in particular, current flow into the Cu stabiliser due to excessive overcritical currents developing in the HTS layer. The numerical models give an important insight into what is occurring inside the HTS wire in the HTS dynamo.