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# A systems analysis and design for the digital representation of circuit information

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### ABSTRACT

#### DIRECTION

#### A SYSTEMS ANALYSIS AND DESIGN

#### FOR THE DIGITAL REPRESENTATION

### OF CIRCUIT INFORMATION

Many companies in the electrical equipment industry continue to prepare circuit schematic drawings in a conventional pictorial format for many and varied reasons. Valid as these reasons might be, the advantages of converting the circuit information to a digital representation of the substantial.

From an engineering viewpoint, there are advantages to be gained in the ease of retrieval when information is stored in a machine processable form. The circuit information can be presented to the engineer in a variety of formats, each one suitable for a particular

engineering function. Along with proper presentation of output, a number of routine design checks can be performed by the computer in a more efficient manner than a human. This ease of verification allows substantially more checking than would be possible with manual methods. From a manufacturing viewpoint, the format of a pictorial circuit schematic is not suitable. Wire color, gauge and method, order of multing, which involves specifying the specific order in which electrically common points are connected together, and dotailed wire run information are not indicated. It is a normal engineering function to prepare this manufacturing information. This thesis proposes that

maintenance of circuit information in a digital format would allow preparation of manufacturing information using automatic data processing equipment.

In order to realize the advantages both to engineering and manufacturing, that are indicated above, the author of this thesis has proposed a systems design which will allow conversion of both existing and new pictorial circuit schematics to a digital representation. These schematics could then be maintained on magnetic tape or in random access computer memory. Incorporated into this system are schemes for highly flexible additions, modifications and deletions of the master files and preparation of informative reports on a selective basis.

Implementation of this proposed system has been accomplished using a COEOL (Common Business Oriented Language) type processor on a General Electric Company, GE 225, computer. The system of programs ,

required utilized approximately 45,000 words of storage and included over 3400 source statements.

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Use of the system titled DIRECTION, for <u>Digital Representation</u> of <u>Circuit Information</u>, would in the author's opinion, result in considerable savings in time and manpower in implementation of new circuit designs and incorporation of changes to existing clos. Additional advantages would be gained by better verification of design accuracy and by lower design cost. The latter stems from the ability of the system to assist the designer in maintaining higher performance, thereby eliminating the need for accuracy verification at each stage of the design activity. One of the greatest advantages would come

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from the ability of the manufacturing organization to operate under shortened schedules.

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The thesis concludes with an assessment of the additional work which must be accomplished before a completely integrated system can<sup>\*</sup>. be developed which will take design information as input and produce an output consisting of complete manufacturing information for wiring, assembly and testing of electromechanical and electronic equipment. Included in this output would be a media for controlling automatic wiring and testing machines.

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### DIRECTION

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A SYSTEMS ANALYSIS AND DESIGN FOR THE DIGITAL REPRESENTATION OF CIRCUIT INFORMATION

by

Robert Jay Edelman

A THESIS Presented to the Graduate Faculty Of Lehigh University In Candidacy for the Degree of

Master of Science

# Lehigh University

1964

This thesis is accepted and approved in partial fulfillment of the requirement for the degree of Master of Science.

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**ii** 

23 march 1964

(Date)

William a Amich G.

William A. Smith, Jr. Professor in Charge

Arthur F. Gould Head of the Department

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Mr. E. W. Aeschlimann of the Western Electric Company,

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DIRECTION A SYSTEMS ANALYSIS AND DESIGN FOR THE DIGITAL REPRESENTATION

ABSTRACT

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OF CIRCUIT INFORMATION

Many companies in the electrical equipment industry continue to prepare circuit schematic drawings in a conventional pictorial format for many and varied reasons. Valid as these reasons might be, the advantages of converting the circuit information to a digital representation are quite substantial.

From an engineering viewpoint, there are advantages to be gained in the ease of retrieval when information is stored in a machine processable form. The circuit information can be presented to the engi-

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From a manufacturing viewpoint, the format of a pictorial circuit schematic is not suitable. Wire color, gauge and method, order of multing, which involves specifying the specific order in which electrically common points are connected together, and detailed wire run information are not indicated. It is a normal engineering function to prepare this manufacturing information. This thesis proposes that

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maintenance of circuit information in a digital format would allow preparation of manufacturing information using automatic data processing equipment.

In order to realize the advantages both to engineering and manufacturing, that are indicated above, the author of this thesis has proposed a systems design which will allow conversion of both existing and new pictorial circuit schematics to a digital representation. These schematics could then be maintained on magnetic tape or in random access computer memory. Incorporated into this system are schemes for highly flexible additions, modifications and deletions of the master files and preparation of informative reports on a selective basis.

Implementation of this proposed system has been accomplished using a COBOL (Common Business Oriented Language) type processor on a General Electric Company, GE 225, computer. The system of programs required utilized approximately 45,000 words of storage and included over 3400 source statements.

Use of the system titled DIRECTION, for <u>Digital Representation</u> of <u>Circuit Information</u>, would in the author's opinion, result in considerable savings in time and manpower in implementation of new circuit designs and incorporation of changes to existing ones. Additional advantages would be gained by better verification of design accuracy and by lower design cost. The latter stems from the ability of the system to assist the designer in maintaining higher performance, thereby eliminating the need for accuracy verification at each stage of the design activity. One of the greatest advantages would come

from the ability of the manufacturing organization to operate under shortened schedules.

The thesis concludes with an assessment of the additional work which must be accomplished before a completely integrated system can be developed which will take design information as input and produce an output consisting of complete manufacturing information for wiring, assembly and testing of electromechanical and electronic equipment. Included in this output would be a media for controlling automatic wiring and testing machines.

### 1. Introduction

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The engineering activities that precede the introduction of every new product can be broken into a number of steps: Research and Design, Development, and Preparation for Manufacturing. In actual practice these steps are not discrete but tend to diffuse into each other. A later period during which actual manufacturing takes place will be omitted from this discussion for the present time.

Research and Design, the first stage in the development of a new product, in comparison to the later stages, requires the least expenditure of man hours of effort. It is during this period that ideas are formalized and goals are delineated. Preliminary circuits are designed and in most all cases, models are constructed to test the feasibility of the prospective system.

If a critical evaluation of the results of the research and design activity is favorable, effort on the project proceeds into the development stage. By no means does research and design activity cease at this point. Circuit improvements and the incorporation of additional features continue at an ever increasing pace. What has actually happened is that the project has grown to the point that practical implementation is receiving its share of the total effort.

The second stage, development activity, concerns itself with the design of circuit elements, equipment layouts and most

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1. See Figure 1.

important, the application of sound engineering principles to the more theoretical results of the research. It is particularly important to note that the manpower requirements of the project have grown to meet the increasing scope of the activity at hand. Before the development activity on a new product is concluded, work begins on the third stage, implementation for manufacturing. This area encompasses the preparation of manufacturing layouts, preparation of wiring and testing information and of course acquisition of tools and facilities for the actual manufacturing operation.

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> As a result of increased competition and shorter schedules there is invariably considerable overlapping of all of the above functions. The significant point to recognize is that any project that has as its ultimate goal the manufacture of a new product,

starts with a relatively small expenditure of man hours of effort during the research stage, but with each successive step on the road to actual manufacturing, requires the expenditure of a larger amount of effort. In a similar manner the volume of data that is generated increases progressively with advancement from research, to development, to manufacturing planning.<sup>2</sup> The output of the research group may be a relatively small number of sheets containing the basic circuit design and a description of its operation. The development engineers will increase this volume several times with the inclusion of apparatus information and specifications. The

2. Hoberecht, V. L. "Design Information Systems" Unpublished Paper, IBM Corporation, 1962.

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manufacturing engineers, finally, will create a veritable flood of information on wiring, tooling, testing, etc. <sup>3</sup> Corresponding to this increase in man hours expended and volume of information produced, there is a decline in the creativity level of the activity on the project. The very nature of much of the work in planning for manufacturing is routine. Preparation of wiring and testing information, in particular, is essentially a restatement of information shown in a different form on the original circuit design.

It has been estimated that the expenditures for fundamental and applied research and development from all sources in the United States for 1961-1962 was approximately 14.7 billion dollars. If the relationships between research and development and preparation for manufacturing that have been presented are true, then the total annual expenditures for the latter must be staggering. The combina-

tion of the large expenditure in man hours, increase in volume of information, and decline in creativity required for the preparation of manufacturing information, coupled with the very detailed nature of manufacturing information, makes this area very attractive for the application of machine aided methods.

One particular area of manufacturing information, more than any other, is especially susceptible to these automatic techniques.

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- 3. See Figure 2.
- 4. Hoberecht. op. cit.
- 5. See Figure 3.
- 6. <u>Statistical Abstract of the United States</u>, U. S. Dept. of Commerce, 1963, P. 543.

K.,

This is the area of wiring and testing information. The circuitry for any electronic or electro-mechanical system is first produced by the research and development organizations. This information can generally take one of two broad forms. If the development of the logic for the circuit has been done by computer aided methods, then it is likely that the completed circuit design, or as it is commonly titled, circuit schematic, is in a format which reflects the methods used in its preparation namely, tabular format. Since a computer has been used in the development of this electrical circuit, preparation of wiring and continuity testing information may very possibly be merely an extension of the technique used in developing the logic of the circuit.

The second form of circuit information, namely the conventional pictorial schematic drawing, arises as a result of strictly manual

design techniques or because the needs of the business require a pictorial type representation of the circuit.<sup>7</sup> This thesis will be concerned with this second form of schematic drawing and the resultant methods which can be used to translate pictorial information into a digital form so that the many advantages of machine processing can come into play.

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7. See Figure 4.

## 2. <u>History of the Application of Machine Aided Methods in the</u> <u>Preparation of Wiring and Testing Information</u>

It might be useful in a study of applying machine methods to the representation of circuit information and the preparation of manufacturing information to review some of the techniques and methods that have already been developed.

The first real theoretical breakthrough in the processing of information came from the work of Weiner and Shannon during the 8 9 Second World War and documented by them in 1948 and 1949 respectively. It is as a result of this work that a really scientific approach to the problem of information and information transmission is possible. According to Shannon, "The fundamental problem of communication is that of reproducing at one point exactly or approximately a message selected at another point." Shannon stated,

the semantic aspects of the communication problem are irrelevant,

and accordingly he concerned himself with the technical aspects

only. However, Weaver in a generalization of Shannon's work,

restates the communication problem in three levels:

- 1. How accurately can the symbols be transmitted (the technical problem).
- 2. How precisely is the meaning conveyed (the semantic problem).
- 3. How effectively does the received meaning affect conduct (the effectiveness problem).
- 8. Weiner, N. Cybernetics. New York: The Technology Press & John Wiley and Sons, 1948.
- 9. Shannon, C. E. and Weaver, W. <u>The Mathematical</u> <u>Theory of Communications</u>. Champaign, Illinois: <u>University of Illinois Press</u>, 1949. P. 3.
  10. ibid., P. 96.

<sup>10</sup> 

It is this generalization, in particular the latter two levels, that is especially related to the problem of circuit and manufacturing information. Information Theory postulates the idea that any part of the communication that is predicatable is redundant. As a result it has been estimated that as much as 99% 11 of the information in a TV picture is unnecessary. It seems that Shannon and Wiener have discredited the old adage that a

picture is worth a thousand words.

These particular ideas are germaine to the problem of preparation of wiring and testing information from pictorial schematics in that they show the considerable advantage that is to be gained in utilizing machine methods. Pictorial schematics and their resultant pictorial wiring diagrams do not offer the best method of solving the communication problem in the levels of semantics

and effectiveness, and as a result of redundancy, do not convey as much information as may appear. These schematics, being designed and drawn by humans, are not especially adaptable to modern methods of data processing and information retrieval. <sup>12</sup> They are bulky and difficult to change. A method must be developed to adapt this technique of presenting schematic information to the more modern methods of processing information.

11. Editors of Fortune. The Mighty Force of Research. New York: McGraw-Hill, 1956. P. 285.

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12. Martin, R. B. "Wiring Run Lists: Preparation By Electronic Accounting Machine Methods." Unpublished Paper, Bell Telephone Laboratories Memorandum,

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**1961.** 

Utilizing the theoretical knowledge gained from Shannon and Wiener, methods for thinking through and recording the logic of complex information systems have been developed. One of particular 13 Developed by the General Electric Company, note is TABSOL. TABSOL has as its essential element, Decision Structure Tables. Similar to the truth tables utilized in Boolean Algebra, Decision Structure Tables provide a standard method of describing complex, multi-variate, multi-result decision systems. The table consists of rectangular arrays of blocks, the left side containing the decision logic, the right side the results or functions. By making the appropriate logical decisions, the table will provide a path to the correct result or function. TABSOL makes it possible to state complex information systems in a logical nature that allows selection of the proper path through the system to a logical

Techniques have been developed which were specifically designed

as an application of automatic data processing methods to the manu-

facturing information problem. Among these are "Design Mechanization"

- 13. Kavanagh, T. F. "TABSOL The Language of Decision Making," <u>Computers and Automation</u>, Vol. 10, No. 9 (Sept. 1961), PP. 15-22.
- 14. Evans, O. Y. "Decision Tables." Unpublished Paper, IBM Corporation, 1961.
- 15. The General Electric Company has developed a compiler titled GECOM which allows source programming in TABSOL with direct translation into machine language instructions. This technique was used in implementing part of DIRECTION.

programs developed by IBM Corporation which produce back panel wiring lists and other related information in accordance with certain design requirements including least total wire length and isolation of wire runs from each other to minimize electrical interference. The input to this system of programs is a digital description of the electrically common points in the <u>regular</u>

matrix of terminals on the back panel. A modification of the 17 procedure developed by Loberman and Weinberger for connecting terminals with a minimum quantity of wire is used in this system.

Minneapolis-Honeywell Regulator Company has also been active 18 in this area with a system of computer programs called GDWRAP. The IBM and M-H systems are very similar, both reaching the ultimate in automation in that the programs, in addition to preparing information on wiring, also provide punched card input to Gardner-

Denver Automatic Wiring Machines.

The Gardner-Denver wire wrapping machine is a numerically controlled machine that, upon receiving instructions from a punched card, proceeds to wire wrap one end of a continuous strand of

- 16. Altman, G. W., Decampo, L. A. and Warburton, C. R. "Automation of Computer Panel Wiring," <u>AIEE Communi-</u> cations and Electronics, No. 48 (May, 1960), PP. 118-125.
- 17. Loberman, H. and Weinberger, A. "Formal Procedures of Connecting Terminals With A Minimum Total Wire Length," Journal of the Association for Computing Machinery, Vol. 4, No. 4, (Oct. 1957), PP. 428-437.
- Brown, R. R. and Putnam, G. R. "The Automation of Topological Layout," <u>AIEE Communications and Elec-</u> tronics, No. 60 (May 1962), PP. 136-139.

insulated wire on one terminal in an array of terminals, run the wire over a predetermined path under control of information on the punched card, to another terminal where the wire is cut and the loose end wrapped on the terminal. This machine runs one wire 19,20for each card in the input deck. Use of this technique reduces errors and results in a time saving factor over manual methods of 21approximately 36:1.

Another group active in this area has been the Aerospace 22Division of Martin Marietta Corporation. Martin's approach has been principally to produce "drawings" in a tabular format on  $8\frac{1}{2}$  x 11 inch sheets for test stand cabling on the Titan Project.

Some of the most significant work that has been done in the area of utilization of computer methods in schematic representation

and preparation of manufacturing information has been at the Bell Telephone Laboratories. Systems for not only preparing manufacturing information but also tabular format schematic circuit drawings have been developed. Some of these are BLADES (Bell

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- 19. Grimm, R. J. and Brouwer, D. P. "Wiring Terminal Panels by Machine", <u>Control Engineering</u>, Vol. 8 No. 8 (Aug. 1961) PP. 77-81.
- 20. "Automatic Computer Directed Wiring Machines for Making Computers," <u>Computers and Automation</u>, Vol. 10 No. 9 (Sept. 1961), P. 12B.

21. Brown and Putnam. op. cit.

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22. Lanfond, C. D. "Lineless Drawings Aid Titan Work", <u>Missiles and Rockets</u>, Vol. 11, No. 11 (Sept. 10, 1962), PP. 30,35,40.

Laboratories Automatic Design System), 23, 24, 25 MAPID (Machine Aides in the Preparation of Instruction Data), 26, 27 UNICOM (Universal Integrated Communications Equipment), 29, 30, 31 and other

systems without specific names including one that produces wiring

- 23. Morzenti, O. J. "Implications of Machine Aids To Design," AIEE Paper, No. 61-104.
- 24. Herbst, R. T., Leagus, D. G. and Sellers, G. A. "Machine Processing of Manufacturing Information For Digital Systems." Unpublished Paper, Bell Telephone Laboratories Memorandum, \_\_\_\_\_, 1962.
- 25. Winans, R. C. "The Use of The BLADES Automatic Design System Computer Program for the Mechanical Design and Preparation of Manufacturing Drawings for Nike-Zeus "C" Planes." Unpublished Paper, Bell Telephone Laboratories Memorandum, 1960.
  - 26. Kalish, H. M. "The Automatic Print Out of a Sample Functional Schematic for MAPID." Un-Published Paper, Bell Telephone Laboratories

Memorandum, \_\_\_\_\_, 1961.

- 27. Kalish, H. M. "A Study of the Feasibility of Using Machine Aids in the Preparation of Instruction Data." Unpublished Paper, Bell Telephone Laboratories Memorandum, \_\_\_\_\_\_, 1961.
- 28. Switak, F. E. "Unicom Computer Aided Wiring Program." Unpublished Paper, Bell Telephone Laboratories, 1962.
- 29. Rosenthal, C. W. "Computing Machine Aids to a Development Project," <u>IRE Transactions on</u> <u>Electronic Computers</u>, Vol. EC-10, No. 3 (Sept. 1961), PP. 400-406.
- 30. Kirby, D. B. and Rosenthal, C. W. "Computer Program for Preparing Wiring Diagrams," <u>AIEE</u> Paper, No. 60-1007.
- 31. Kirby, D. B. and Rosenthal, C. W. "A Computer Program for Preparing Wiring Diagrams." Unpublished Paper, Bell Telephone Laboratories Memorandum, 1960.

information for conventional telephone circuits using machine aided methods. 32A brief description of these systems might be useful at this point.

The DIPS programs provide the user with a vocabulary of two dozen words which enable him to verify design data, locate electronic logic packages, route interconnecting wires and prepare documents to support the above. Input to this system is a running list or interconnection list that is prepared from the <u>logic diagram</u> by the design engineer.

MAPID is a system which proposes to produce instruction data automatically. Included in this classification are pictorial functional schematics, functional theory, turn on/shut off procedures, check and adjustment procedures and maintenance procedures. The preparation of pictorial functional schematics using MAPID is

particularly interesting in that it is proposed that this is accomplished utilizing an IBM 7090 Computer and a Stromberg Carlson 4020 Printer. The S-C 4020 is a CRT/microfilm-printer which, when directed by a program prepared on the IBM 7090, photographically produces high quality pictorial schematics.

The BLADES System is the most advanced development of all those produced by Bell Telephone Laboratories. BLADES starts with a

32. Hornung, G. T. and Weber, L. J. P., Jr., "A Method of Producing Wiring Information for Conventional Type Telephone Circuits Using Machine Aided Methods." Unpublished Paper Bell Telephone Laboratories Memorandum, 1960.

logic diagram of the circuit to be represented which is then translated into a set of TOPO-LOGIC equations. The term TOPO-LOGIC is used, because in addition to the logic of the circuit, the equation also includes topographical information such as terminal numbers, etc. The BLADES system is a large group of IRM 704 programs which, utilizing the TOPO-LOGIC equations, assigns logic functions to specific printed wiring board packages, places these packages to satisfy wire-run restrictions, generates the necessary wire runs, selects certain component values, and assigns power supplies. The total system of programs utilizes approximately 37,000 instructions for the IBM 704. At the conclusion of the wire placement, most of the required manufacturing information is present but not in proper form. Output routines present an electrical parts list, assembly information, and wiring information in an acceptable

format. All information is stored on magnetic tape so that the full power of electronic data processing can be brought to bear on the information maintenance problem. The magnetic tape becomes the official record. The BLADES program also provides input to a Gardner-Denver automatic wire wrapping machine.

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The UNICOM System is really only an application of a small part of BLADES, namely that part which produces the wire running information. The particular advantages gained in using UNICOM were in a reduction in the number of errors made in the preparation of the wire running lists.

BLADES, MAPID, UNICOM and DIPS have several very important

things in common. They are all based on working from logic diagrams that were formulated particularly for the processing system involved. In most cases, this involved skipping entirely the development of a conventional pictorial schematic drawing. In addition, the layout of the apparatus involved was very regular. This means that the terminals to which the wiring was connected were arranged in a completely symetrical matrix.

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One processing system, however, has been developed to operate on apparatus which has its terminals arranged in an irregular manner.<sup>33</sup> This is the system previously mentioned that has been developed by the Bell Telephone Laboratories in their Columbus, Ohio Laboratories. The original system utilized IBM Unit Record equipment to produce wiring information for changes that were to

be made on existing crossbar type telephone equipment. Later plans include the use of an IBM 1401 with large random access storage to replace the Unit Record equipment. This system has attempted to solve the many problems that arise when the apparatus is not regular in arrangement. Since the principal purpose of this system is to provide information for wiring changes on laboratory apparatus, it does not satisfy all of the necessary requirements that would be present in a regular manufacturing situation. The necessity of keeping permanent records that are easily updated to reflect the) latest changes, while at the same time keeping a record

33. Hornung & Weber. op. cit.

of the old wiring, is one of the requirements of a regular manufacturing situation.

3. Objectives

The objectives of this study are to evaluate the feasibility of designing a computer oriented system for quantifying pictorial type schematic drawings so that they can be represented in a digital manner suitable for storage on magnetic media. The system must have the capability of easy updating and rapid information retrieval with selective production of informative engineering reports, and also should have the capacity to conduct routine design verification procedures. Design verification, in this application, should consist of automatically checking the accuracy of a number of the more routine design functions, for example, the assignment of apparatus identification codes to circuit elements.

Preparation of detailed manufacturing information is not an objective of this study, it is, instead, a logical extension of this system.

In order to justify these objectives it might be worthwhile to summarize the previous historical discussion.

It has been shown that the greatest engineering effort, from a man-hour consideration, is centered in the area of preparation of manufacturing information and that certain parts of this information, by its very nature, is especially adaptable to machine aided methods. This fact is especially pointed out by the significant amount of effort that has been expended by industrial organizations in the direction of automating the preparation of wiring

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information. Interestingly enough though, almost all of this effort has been accomplished as a part of an overall development program to utilize input information restricted to a format particularly suited to the later stages of processing and to equipment design that is easily adapted to this type of processing. In these cases the layout of apparatus has been completely regular and even within a particular type of apparatus, the terminals have been arranged on a symetrical matrix. In addition, the effort has been in the direction of military type equipment that does not require extensive historical record keeping procedures. These records are necessary in the telephone industry for example because of the necessity of making all vintages of equipment compatible within one large system.

The intention, therefore, is to direct attention to the large

segment of industry that finds itself unable to utilize the very considerable gains that have already been made in applying machine aids to the preparation of highly structured manufacturing information. Many research organizations are organized in such a way that the result of their activities is a pictorial type schematic 34circuit drawing. While it is immediately recognized that this procedure may not be the most efficient from the view of later processing of information or even from the aspects of design activity itself, the needs of the business or of the ultimate

34. See Figure 4.

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customer seemingly may require this procedure. The apparatus involved, while including circuit packs or printed wiring boards as they are more commonly known, which have terminals arranged in a symetrical matrix, also includes wire spring relays and other types of conventional electro-mechanical devices which are very irregular in layout.

The situation, therefore, is one in which the input to the processing system is a pictorial schematic drawing that has been developed by mostly manual methods and utilizes apparatus which is partially regular and partially irregular in arrangement.

What is needed is a method of keeping a master record of the circuit schematic and equipment arrangement in digital language that is easily updated or corrected and that also lends itself to further data processing methods for the production of manufacturing

information. The vehicle that will best accomplish this objective is either:

- A random access memory device such as IBM's RAMAC or NCR's CRAM (Card Random Access Memory) or,
- 2. Magnetic tape.

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The appropriate vehicle for containing the master record of the circuit schematic must be coupled with a method of easily updating this record. The input information normally does not arrive in a complete package. More likely, as a result of short schedules and last minute design changes, the schematic is produced in a piecemeal fashion. The processing procedure must be capable of

merging additional information with that already available and to allow insertions, deletions, and modifications. The ideal situation of course is to have all data inserted at the beginning and then to allow the computer to run free of human interference to the very end of the process.<sup>35</sup> The approach taken to this problem of flexibility is similar to that used in DIPS in that a vocabulary of order words<sup>36</sup> will call on a library of subroutines that will enable an un-experienced person to utilize the computer to manipulate the information which is contained in the master record. Using this procedure, circuit options which are required by price changes or circuit improvements, for ease of manufacturing or, simply, for record keeping purposes can be handled.

Once the information on the circuit schematic is translated

into a digital language that is easily updated, problems of information retrieval must be solved. The information in the circuit schematic must be presented to the engineer in a logical manner for his corrections and modifications. It may be desirable to do this in several different formats: for example, a format that shows the electrically functional relationships or one that is arranged to conform to the physical relationship of the apparatus involved. Of course, the computer will be used to make extensive checks on the accuracy of the design data. Such things as multiple use of relay contacts, stray leads that are never terminated, interconnection

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35. Weiner, op. cit. P. 139.36. Rosenthal. op. cit.

with other circuits and physical interference between apparatus can be easily identified. The problem becomes, largely, one of file organization.

The total problem of converting conventional pictorial circuit schematic information into a digital form and producing manufacturing information from that media, is a very large one. Previous activities in this area have been accompanied by an expenditure measured in terms of tens of man-years of effort. Accordingly, this thesis shall be concerned only with the first part of the problem: representing circuit schematic information in a digital format.

During the systems design consideration will be given to the following stage, preparation of manufacturing information. Hopefully, sufficient flexibility will be built into the first phase

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so as to make implementation of the second as easy as possible.



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### 4. DIRECTION

### 4.1 Introduction

DIRECTION is an acronym for DIgital REpresentation of Circuit InformaTION. It consists of a number of computer programs designed to accomplish the objectives listed in the previous section, principally the representation of pictorial circuit schematics in a digital format. Any system of this sort can be divided into two major categories: coding methods for quantifying the pictorial input information and information retrieval methods for the production of informative, useful output reports. Efficient organization of the required files is the single most important requirement common to both of these categories. The file organization must be so structured as to allow a meaningful conversion of the input pictorial information; it must have sufficient flexibility to allow the inclusion of certain classes of exception items; it must include provisions for the extension of the system design to future requirements; it must be organized in a manner best suited to easy updating; and finally it should be sequenced in a manner that will allow the production of reports of the highest entropy coincident with their intended use. At the start of a system design such as this one, these ideas are relatively meaningless platitudes. As work progresses, the real importance of file organization takes on its true significance in that the peak effort required in this design is reached not at the middle or end of the design but rather near the beginning when the basic groundwork is laid. In fact, some of the seemingly

more difficult aspects of the objectives, namely the design verification, proved to be relatively easy as a result of the file organization which was in existence at the time this phase of the system design was under active development.

DIRECTION itself consists of three types of basic files. The first, called the APPARATUS MASTER FILE contains information for the many items of standard apparatus or building blocks that can be combined within a circuit to construct a useful functional piece of equipment. Included in this category are relays, transistors, keys, lamps, capacitors, etc. This file is not in any way oriented toward the particular circuit that is being processed by the system but is simply a dictionary containing a vocabulary of all the available standard components which might be used in that circuit.

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The remaining two types of files differ from the first in that

they are unique to the particular circuit being considered. The first of these is the UNIT FILE. This file, utilizes standard apparatus in the APPARATUS MASTER FILE and any necessary special items such as brackets or other special hardware to create a stocklist for the circuit involved and information to show the physical arrangement of the apparatus according to some coordinate system. The third type of file, also unique to a particular circuit and most important of the system, is the WIRE FILE. It is here that information concerning the wiring of the circuit is contained in a carefully stratified organization oriented toward later processing requirements. In the discussion to follow the organization

of each of these files will be covered in more detail including a description of the implementation of the system in terms of specific computer programs and a specific circuit vehicle. Perhaps at this time it might be worth while to include an introduction to both the circuit schematic and the computer used.

### 4.11 Choice of Sample Circuit

In selecting a pictorial circuit schematic to serve as the vehicle for the first implementation of DIRECTION it was desired to utilize apparatus of many types. Electronic as well as electromechanical apparatus are common in the electrical equipment industry and any system which could process circuits containing only one of these types would be severely limited in applicability. Accordingly the circuit selected is the Trunk Switching Circuit, a component of the Electronic Telephone Switching System currently being introduced into the telephone network of the Bell Telephone System. The design of this circuit is new. It contains however, along with the latest electronic devices, many electromechanical components such as wire spring relays which have been in common use for a number of years.

The second requirement of the circuit selected is that it be of the proper size. The Trunk Switch Frame, one of a number of different apparatus configurations used in an Electronic Telephone Central Office is composed almost entirely of the Trunk Switching Circuit. This complex of equipment is mounted on a framework four

feet wide and nine feet high. It contains over 10,000 terminals and includes a variety of different wiring methods. The size of this frame was considered optimal for a first implementation in that it was not so large as to obscure the objectives in its implementation (the largest circuit contains over 90,000 terminals) nor was it so small as to be considered a trivial application (the smaller units are of the order of ten inches by ten inches and contain about a hundred terminals).

### 4.12 Computer Restrictions

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From the relative size of the circuits involved it is apparent that in order to process this volume of information a computer of the upper medium or large class is required. Such a computer, as will be shown later, must have high speed input-output devices

and a relatively large core capacity. The computing facilities available for this study did not, in general, meet these qualifications. The Computing Laboratory at Lehigh University included an LGP 30 computer, a small machine, and a General Electric Company GE 225, a medium sized machine. The GE 225 at Lehigh University included a 900 line per minute printer, a 400 card per minute reader, a card punch, four 15K tape units and 8K positions of magnetic core storage. While the GE 225 is basically of the proper size, the

37. Figure 5 shows a framework similar to the Trunk Switch Frame.
particular configuration at Lehigh University was severely limited in the number and speed of the tape units and in the available core storage. As a result of these hardware constraints certain limitations were necessary in the system design. These limitations are not fundamental and where a compromise has been made an indication of the improved design is included.

Available for use on the GE 225 is a general purpose compiler titled GECOM. GECOM is essentially COBOL, the common business oriented language. Included however, are certain elements of ALGOL, an algebraic language and TABSOL, a tabular solution language. This compiler, while more rigid in form then COBOL-61, fulfills the requirement for a more or less universally interchangeable language. The first hardware limitation comes into play with the use of GECOM. In order to compile a GECOM program and

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assign the object program to magnetic tape, a minimum of five tape units are required. Since only four were available, object programs were placed on punched cards. While most programs were written so as to require the use of a call or parameter word to start processing, the usefulness of this procedure was severely limited by the assignment of object programs to punched cards. A better design would be to have all programs in a single magnetic tape library. An executive routine utilizing the call-words could call up the required program at each stage of the processing. This change in operating procedure does not reflect any fundamental system variation.

In this discussion mention is made of the GECOM programs that have been written to implement this system. The detailed coding for these programs is contained in a separate appendix to this thesis.

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# 4.2 APPARATUS MASTER FILE

The APPARATUS MASTER FILE is a magnetic tape file containing information concerning the various items of standard apparatus that can be utilized in an electrical circuit. Included in this category are relays, electron tubes, capacitors, transistors, tube sockets, resistors, circuit packs, etc. Since producing the circuit design is not one of the objectives of DIRECTION, apparatus design parameters need not be included within this file. Information is necessary that will be useful to uniquely identify the particular piece of apparatus involved and to identify each terminating point for a wire on that apparatus. Hopefully, this information should be contained in a reasonable sized record. The file organization of the APPARATUS MASTER FILE was designed with these objectives in mind.

In establishing the organization of this file, every piece of apparatus containing more than one terminal must have a unique system of terminal identification if the function of the terminals, in terms of the apparatus, is different. In order to clarify this statement, consider the following examples:

 Relay - every terminal on a relay has a unique function in terms of the relay contacts. Each terminal must be identified. Any identification scheme used is satisfactory provided it is used consistently in all files in the system.

Resistor - most pigtail resistors do not require 2. differentiation between terminals in terms of the resistance itself. Normally, a resistor cannot be connected backwards in the circuit. The pigtail leads need not, therefore, be uniquely identified and they can simply both be labeled PT. At first examination it seemed necessary that each of these terminals be uniquely identified. Later developments indicated that the two PT leads of a resistor will appear to be uniquely identified in the wiring information with each terminal in the proper wire run. Terminal Strip - each terminal in a terminal strip is

electrically separate from every other. A unique identification scheme must be consistently used so as to avoid

any confusion in identification.

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Having established a method of uniquely or non-uniquely identifying apparatus terminals, it immediately becomes obvious that there is a wide variance in the possible number of terminals on an apparatus unit. The pigtail resistor for example has only two leads which are both normally called PT. A large terminal strip on the other hand may have hundreds of terminals each uniquely identified. The problem that must be addressed is the selection of a fixed or variable record length. With a fixed length record

system, each record must be equal in size to that for the apparatus with the most terminals. Most of the apparatus included in the file have less than 36 terminals while a very few may have as many as 300 terminals. Fixed length records would, therefore, be a great waste of the medium used to store this type of information. Variable length records on the other hand, while tailormade to each piece of apparatus, would be sufficiently random in size so as to prevent the blocking of records. With an expected large sized APPARATUS MASTER FILE, the apparatus file utilized by the Bell Telephone System alone contains in excess of 30,000 items, and the use of this file in DIRECTION being somewhat limited, it was decided to utilize variable length records with a control-key to identify the record length.

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Control-keys are a feature common to the entire DIRECTION

system. They are used to indicate the type and size of the input record being processed. Two alphabetic characters which occupy ? the first two positions within the record comprise the control-keys in DIRECTION. Using alphabetics allows the largest number of control-keys in the smallest number of character positions. In the APPARATUS MASTER FILE control-keys are used as follows:

CONTROL-KEY	NO. OF TERMINALS
JA	16
JB	42
JD	68
JF	94
JH	120

The remaining item of information which must be included in this file concerns the unique identification of the apparatus itself. Various coding schemes consisting of letters and numbers, with sophisticated check bit systems, have previously been developed. Each of these methods, while minimizing the number of digits used, require the translation of the code to a meaningful English identification before the information can be used by humans. This type of translation was avoided in every stage of DIRECTION. Instead, information was stored in a useful English language format. Each item of apparatus is therefore identified by its generic name or type, and the code number within that type. For example, a 481 Relay is a REL 481. A 185C Network is a NET 185C. Ten alphabetic digits are sufficient to identify the type

The APPARATUS MASTER FILE, therefore, contains variable length records on magnetic tape, one for each piece of standard apparatus available. An individual record consists of, in addition to the control-key which indicates the length and type of the record, information about the apparatus type, code number within the type and an identification for each terminal.<sup>38</sup> For the particular application of DIRECTION included in this study a master file of only that apparatus required for the Trunk Switching Circuit was

while twenty alphanumerics comprise the code number.

38. For the detailed structure of the APPARATUS MASTER FILE and examples of input records see Figures 24 and 25 respectively.

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created. This file consists of sixty-eight records of various lengths.

In order to create this file and produce a printed report containing information on the file contents, two programs have been written. They are respectively APMSTRIN<sup>39</sup> and APMSTROUT.<sup>40</sup>

#### 4.21 APMSTRIN

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APMSTRIN is a program which provides for the creation of a magnetic tape file from a punched card input. In order to provide for a variable length input record which involves a variable number of punched cards, control-keys are used. The control-key, occupying the first two columns of each punched card being used as input, not only indicates the contents of the remainder of that card but also identifies the number of additional cards which together contain all the information about a single item of appa-

ratus. Use of control-keys in this instance becomes a very useful but complicated procedure. During processing, the program detects the improper use of control-keys, printing a suitable message on the high speed printer which will enable identification of the incorrect record. Completion of processing is also indicated on the printer.

39. See FIGURE 6.

40. See FIGURE 7.

41. Figure 26, in TABSOL format shows the use of control-keys in APMSTRIN.

#### 4.22 APMSTROUT

APMSTROUT produces a printed report titled MASTER APPARATUS 42 LIST which contains the information in the APPARATUS MASTER FILE. 42 A single parameter card is required which is identified by a control-key and contains the current date. The report utilizes this date on its cover sheet. Additional pages of the report include information on every record in the file. The apparatus type, code and identification for each terminal is shown. When all information in the file has been printed, the end of file is indicated. The pages of the report are numbered, continuations are shown and in general every effort is made to produce a meaningful, easily read and understood document. For the Trunk Switching Circuit the MASTER APPARATUS LIST contained nineteen pages of computer

output.

No provision has been made for updating the APPARATUS MASTER

FILE. The feasibility of the system design did not hinge on this flexibility and the application involved did not require it. Accordingly, any file updating requires the creation of an entirely new file. It is expected that an extension of the present design would include provision for updating this file in a manner similar to that included in another part of the system.

4.3 UNIT FILE

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The UNIT FILE is a magnetic tape file which contains information concerning the physical arrangement of a particular

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42. FIGURE 14 contains a sample MASTER APPARATUS LIST report.

equipment unit. It is different in concept from the APPARATUS MASTER FILE in that while the APPARATUS MASTER FILE is a file of apparatus useful in many circuits, the UNIT FILE, being applicable to a particular physical arrangement, applies only to the circuits for that arrangement. This file includes a variety of information including a stocklist, functional designations of apparatus, quantities and physical location.

The file is organized around the identifying code for a unit or frame of equipment. This frame or major assembly usually will consist of a number of subassemblies each with their own code identification which, in some way, is related to the code for the entire assembly. The subassemblics in turn can be broken into individual items of apparatus, piece parts, hardware, etc. The Trunk Switch Frame is stratified in exactly this manner, the

entire frame being identified as J1A030A-1. This major assembly consists of subassemblies coded J1A030AX-Y and EDZZZZZ-YY, where the Z represents an alphanumeric character, the X an alphabetic and the Y a numeric digit. The ED classification generally represents an unwired hardware subassembly while the J indicates a wired one. Each of the J and ED subassemblies are in turn composed of other J or ED subassemblies of piece parts, of apparatus items or of hardware. In order to make this coding system more general, the J and ED units are further broken into lists or groups. Each list or group symbolizes a particular application or function of

the assembly and may be selected for inclusion if desired in a particular unit being manufactured. Generally, the first list or group is always required with additional ones providing optional extra features. .

Up to this point, the description of the UNIT FILE has consisted of that information which would normally be considered as a stock list. The UNIT FILE contains much more than this. Individual pieces of apparatus are assigned functional designations within the circuit to indicate their function. For example, a 34A Transistor (designated as TRSTR 34A in the APPARATUS MASTER FILE and the UNIT FILE)might also be known as the SCR.O Transistor in the circuit. The functional designation, SCR.O, indicating that this transistor is in the zero circuit and has a screening function. These functional designations are included in the UNIT FILE for

each piece of apparatus.

Some place within DIRECTION, information should be provided concerning the physical relationship of each piece of apparatus with each other piece. This information is included in the UNIT FILE. A system of coordinates must be established for each physical complex of apparatus. It is not within the scope of this study to consider all the ramifications of the establishment of such a coordinate system. Let it suffice to say that this phase of the system organization is one of the most important with implications reaching into the earliest stages of the circuit design. It is

not at all difficult to design a circuit, in particular the equipment arrangement, that makes impossible the assignment of any reasonable, workable, coordinate system. The key is consistency. When the equipment layout is first undertaken certain rules must be established and consistently followed. For the Trunk Switch Frame a vertical coordinate system of two inch inrements and a horizontal one of one-eighth or one-tenth inch increments, depending on the type of apparatus involved, was established. If automatic machine wiring is contemplated, an accurate system must be used. For this frame, due to the lack of consistency in terminal configuration, such a wiring method is unfeasible and the coordinate scheme used, while inexact, is sufficient.

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The UNIT FILE in order to contain the various items of information discussed above for the various assemblies, subassemblies, piece parts, apparatus, hardware and purchased materials, consists of three types of records each identified by its own unique two digit control-key. The order of records in the file is significant in that it indicates the hierachy of assemblies, subassemblies, etc. within the file.

The first type of record is used to provide information about apparatus items which are contained in the APPARATUS MASTER FILE. The usual information consisting of apparatus type, code and functional designation along with the physical location and quantity required are included in this record. The second type,

for subassemblies of the J and ED classification includes information to identify the required sub-unit, its lists or groups (up to ten per sub-unit) and the necessary quantity of each. The third record type was created to provide for all the other items of hardware which might be included in the UNIT FILE. Part numbers, descriptions and quantities make up the various items in this record type. In addition to the contents indicated above, all of the record types contain information which allows them to be related to the main unit code and sub unit code of which they are a part.

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In order to create the UNIT FILE and produce a report of its contents two programs UNITMSTR  $^{44}$  and UNITRPT  $^{45}$  have been written. Input to these programs is a deck of punched cards with a magnetic tapo file and a printed magnetic sector.

tape file and a printed report respectively as the outputs. Extensive provision for easy updating of this file is provided due to the anticipated information changes concerning the physical arrangement of the unit during all phases of development. Shortened schedules and design reappraisals will make this necessary. The UNIT FILE is capable of fast, simple reaction to these changes. The following description of UNITMSTR will indicate how this updating is accomplished.

43. FIGURES 27 and 28 contain information which shows the detailed structure of the three record types and some input examples.

44. See Figure 8 for a flow chart of UNITMSTR.

45. Figure 9 consists of a flow chart of UNITRPT.

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# 4.31 UNITMSTR

UNITMSTR converts an input deck of punched cards into an output file on magnetic tape. In accomplishing this objective, extensive error detection routines are included to detect improper use of control-keys and call-cards. Illogical situations in file updating, mainly end of file signals, are detected and printouts of error messages on the high speed printer are used to inform the operator of these situations. As much as possible, processing is designed to continue without operator intervention. A vocabulary of four words is used to control the operation of the program. These words are:

START

#### MODIFY

#### DELETE

#### ADDITION

In creating a new file, a single card with a control-key indicating that it contains one of the four vocabulary words, and the word START will signal the start of a new file. The following cards in the input deck will then be transcribed to a newly created magnetic tape file.

If updating of an already created file is required, the call words MODIFY, DELETE and ADDITION, are used. A call card consisting of the word ADDITION signals that an addition is to be made to an already existing file. Since it is necessary that the addition be made in exactly the proper place in the existing file, a method

must be provided to search that file in a sequential manner. This is accomplished by using so called qualifier input cards. The qualifier is identified by the use of an appropriate controlkey. The function of the qualifier is to provide a means of searching the UNIT FILE. The search is successful when a match is made between the UNIT FILE and the qualifier. Any number of qualifiers may be used, the sequential search being concluded when the UNIT FILE is positioned so that its last read record matches the last qualifier. The next input dard, not being a qualifier, is inserted into the UNIT FILE as the next record. If no qualifiers are present in the input data, the input records are added to the UNIT FILE as the first ones in that file. Examination of the program flow charts will show exactly how this operation is performed. The call words MODIFY and DELETE operate in a similar

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manner except that the qualifiers are used for a first level search with the first following card used for a second level search. In the DELETE operation, when the second level scarch is concluded, the record in the output file which matches the next input record is deleted. In the MODIFICATION operation, conclusion of the second level search causes the computer to insert the next input card in place of the second level matching record. Any number of qualifiers can be used, any number of additions, modifications or deletions can be made in one run and in fact the three types of operations can be mixed provided the input data is in the same sequence as the UNIT FILE. This system allows extensive updating in one easy

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run. If the input deck should be incorrectly structured, error messages on the printer will provide information for correcting the error.

4.32 UNITRPT

The UNIT FILE has been created and kept up to date using the program UNITMSTR outlined in the previous section. In order to have a record of the contents of that file, which among other reasons is necessary for updating, the program UNITRPT has been written. UNITRPT requires as input the UNIT FILE created on tape as a result of UNITMSTR and a single parameter card containing the control-key PA and the current date. The program then produces a report titled UNIT LIST. <sup>46</sup> The cover sheet of this report in addition to the title and date includes the main unit code, in the case of the Trunk Switch Frame, J1A030. The body of the report is

presented not in the information sequence used in the UNIT FILE, but reorganized to convey the greatest amount of useful information to the persons desiring the report. For the Trunk Switching Frame the UNIT FILE consisted of 609 records and the UNIT LIST contained 34 pages of computer output. Examination of this report will show that it contains a complete picture of the equipment stratification including quantities, physical arrangement and functional designations for the Trunk Switch Frame. Blank fields are present because at the time of implementation complete information was not available for this frame.

46. FIGURE 15 contains a sample UNIT LIST report.

# 4.4 WIRE FILE

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The WIRE FILE is the most important single file in DIRECTION. Its purpose is to systematically provide a structured system of recording the information necessary to define the point to point wire runs in a particular circuit schematic. Since this is also one of the primary objectives of DIRECTION, the two previously described files, APPARATUS MASTER FILE and UNIT FILE, are in a large sense supporting information for the WIRE FILE. In addition to wire run information the WIRE FILE also contains provisions for later additions of information pertaining to the preparation of manufacturing data necessary for the wiring operation. Since the detailed wiring runs shown on the circuit schematic are subject to a great probability of change, the WIRE FILE must be resilient enough to respond to these changes in a simple manner. Another

characteristic of the wiring information is the great variety of special situations that are included. The file organization must be flexible enough to allow the inclusion of information for most all of these special situations.

The basic coding system used in the organization of the WIRE FILE is that known as the nodal or equipotential system. In this method, which has been used in a number of other systems, all those wire terminations, or terminals, which are electrically common are assigned a single unique coded identification number. This identification is never repeated for another group of electrically common terminals within an entire circuit. There may be any quantity of

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wire ends or terminals within any single node, however, no wire run can originate in one node and terminate in another. The node system does not indicate in what order terminals are to be connected together, merely that they are electrically common.

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The following example may help clarify the use of the nodal identification system. That part of the circuit drawn with solid lines comprises a single node. The terminals in that single node are listed.





	Functional	Apparatus
Terminal	Designation	Туре
<b>7</b> F	PA	RELAY
12	2613	CIRCUIT PACK
11	2412	CIRCUIT PACK
<b>2U</b>	PB	RELAY
11 <b>F</b>	PA	RELAY

The most important contribution of this system is that it allows the reduction of a single, large, complicated circuit into a large number of small, simple circuits. Each of these small circuits or nodes can be studied individually. This system is well suited to computer technology which provides for extremely high speed solution of a large number of individually simple problems.

In DIRECTION, the coding system used to identify each node has a meaning in terms of the pictorial schematic drawing for the In order to provide some useful subdivision of the wiring circuit. information contained in the circuit schematic, the design engineer usually breaks the circuit into a number of modules each of which perform a different function. The quantity of these subdivisions may vary from one to a hundred and usually a one or two digit number is sufficient to identify these functional subdivisions or functional schematics. This functional schematic number is used as the first two digits of the seven digit node identification numbering system used in DIRECTION. The next three digits of the node number is the number of the circuit schematic page on which either all or part of the node appears. The last two digits are merely an arbitrarily assigned number starting from 01 for a particular page of the circuit schematic. A typical node identification number might be:



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The WIRE FILE consists of a large quantity of records, sequenced on node numbers. Each record represents information for a single terminal or connection to an external circuit. Since a node has been defined to include all wire terminations or terminals that are electrically connected together; within apparatus a path is not considered to be continuous; it is possible and in fact necessary that a node number be common to more than one record in the file. While the node numbers are in themselves unique, they are not unique between records. With records sequenced on node numbers, one record for each terminal or external circuit connection, the final organization of the file places information concerning all terminals or external connections in a single node contiguous within the file.

In addition to records containing information on wire terminations and external connections other record types are necessary for the

inclusion of the circuit title, issue, circuit notes and a cross reference of apparatus functional designations and type and code numbers. This latter category, apparatus information, is a duplication of some of the information contained in the UNIT FILE but because of the order in which the circuit is designed and the timing of the availability of documents it must be included in the WIRE FILE. When the circuit is being designed the primary consideration is to connect circuit elements, relays transistors, etc., together in a manner that will accomplish the desired objective. The circuit elements are identified by a functional designation which indicates

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the use of the apparatus and does not provide a clue to its specific physical identification. Knowing the purpose of each circuit element and the necessary design parameters, an apparatus specialist can, at a later time, select the specific codes to be used from a master file. The fragmentation of design effort results in wiring information containing only functional designations for apparatus and a separate cross reference of functional designation and type and code number. The circuit schematic that is finally issued by the design group consists of several sections including all of this information. and a second

The various record types that make up the WIRE FILE are identified by the use of control-keys. The record containing the circuit number, issue and title is always the first type in the file. It serves as a file label. The next record type contains circuit

notes and is sequenced on the note number. The third type of record found in the file provides the cross reference between the apparatus functional designation and the apparatus type. This information is grouped in Apparatus Figures which define, to some degree, the functional unit subdivisions of the equipment configuration (J Units). Some apparatus items have dual functional designations hence, the field for upper half functional designation. Sequencing of this record type is by Apparatus Figure number. The remainder of the WIRE FILE consists of apparatus terminal information and information concerning connections to external circuits. These two types of records, about 90% of the total, are intermingled and

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sequenced on the node identification. An explanation of the pur-47 pose of some of the fields might be useful. The field titled option is used to designate wiring which has been included in the circuit to provide optional features or to reflect changes mostly caused by improvements in the circuit. Methods of historical record keeping are predicated on this type of designation. Wire gauge, type and color information is usually not available on the circuit schematic although it is sometimes provided in circuit notes. The main purpose of including these fields at the present time is to provide flexibility for the extension of DIRECTION to the preparation of manufacturing information. It is expected that information for these fields will be provided automatically by another system. The Wiring Method, Strap and Loop fields are also provided for future flexibility. The field titled Pair-Triple-Quad

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is required to indicate the pairing, tripling and quading of wires in the circuit. This information is included, by the designer, in the circuit schematic. A P, T or Q is inserted for each end of the runs if any of the three conditions exist. The field titled Miscellaneous is used to interrelate the necessary nodes involved in the pairing, tripling or quading. In addition to this use for the Miscellaneous field, it serves as a catch-all for many other types of information. For example, a lead to an external circuit will frequently have a functional name assigned to it. This

47. FIGURES 29 and 30 contain detailed information on the structure of the WIRE FILE and present some examples of the input data.

information could be indicated under Miscellaneous.

# 4.41 WIREMSTR

Creation and maintenance of the WIRE FILE requires the use of  $\frac{48}{1000}$  the program titled WIREMSTR. This program is similar to UNITMSTR

in that it utilizes the four call words

START

MODIFY

# DELETE

#### ADDITION

to create and update the file. The updating process in both UNITMSTR and WIREMSTR causes the creation of a new master file from the old one with incorporation of the necessary changes. Qualifiers are used in updating WIREMSTR just as in UNITMSTR with suitable control-keys identifying the qualifying records. It is possible that the fields containing miscellaneous and note information might not be sufficiently large to contain all the necessary information. The program allows the use of input cards in addition to the first which contain only a continuation of the miscellaneous or note information along with the node identification if applicable. This extra material is stored as a separate record immediately after its related one in the output WIRE FILE. Extensive error detection routines are included in this program as well as in all others in DIRECTION.

48. A flow chart of WIREMSTR is shown in FIGURE 10.

# 4.42 WIRERPTS - APPLIST

Once the magnetic tape file, WIRE FILE, has been created by the use of WIREMSTR, retrieval of information is accomplished by 50 **49** Two programs are the programs titled WIRERPTS and APPLIST. required for this purpose only because of the physical limitations of the computer configuration involved. A single program required approximately 10,000 core positions, more than was available. The WIRE FILE created for the Trunk Switching Circuit consists of 9,971 records. This is considered an average size file for this type of circuitry. With such a large number of records, it is important that a great deal of care be exercised in producing reports that will be useful. A complete listing of all the information in this particular WIRE FILE is a large cumbersome document. It is so large that its only usefulness might be for possible documentation purposes. The principal objective of WIRERPTS and APPLIST is, therefore, to provide reports of such flexibility that they can be almost tailor made to their intended use. This flexibility of output is attained by the extensive use of call-cards. The engineer, or any other user, has been provided with a vocabulary which enables him to command the computer to produce any one of several documents from the WIRE FILE. The vocabulary consists of

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49. See FIGURE 11 for the WIRERPTS flow chart. 50. FIGURE 12 contains a flow chart of APPLIST.

the following seven words:

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ALL LIST
 NOTE LIST
 FS LIST
 PAGE LIST
 PAGE LIST
 NODE LIST
 APP FIG LIST
 APP LIST

The use of each of these call-words results in the production of a different type of report. The first card in the input deck to either program, provided only once per run, is a card containing the current date. The date is used on the cover sheet of each report as a chronological index. The following paragraphs contain

detailed information on each of the reports which can be produced. The first report to be considered is titled ALL LIST.<sup>51</sup> This report, which has been previously alluded to, is a complete listing of the contents of the WIRE FILE, presented in a suitable format consistent with the size of the file. Wiring information in this report is sequenced in node identification numbers and includes circuit notes and apparatus cross references. Production of this report is accomplished by use of a single call-card, in addition to the date card, containing the appropriate control-key followed by the words ALL LIST. For the Trunk Switching Circuit, this report

51. Some sample pages from an ALL LIST report are shown in FIGURE 17.

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consisted of 376 pages. An engineer could hardly be expected to assimilate this volume of information, hence its use, as indicated, is primarily for documentation.

A report titled NOTE LIST is also available. Again, just a single call-card is required containing the words NOTE LIST. The ease in controlling DIRECTION should be apparent. NOTE LIST is merely a listing of the circuit notes contained in the WIRE FILE, presented in a meaningful format with suitable page and section headings.

#### 53

FS LIST is a report containing information on from one to ten functional schematic subdivisions of the circuit schematic. Two call-cards must be utilized. The first contains FS LIST, the second has provision for from one to ten functional schematic identification numbers. Each of these numbers is represented by a two

digit numeric field. The desired FS numbers must be listed in the order they appear in the WIRE FILE. The report generated by this routine will include all the wiring information for the functional schematics listed on the call-card.

PAGE LIST<sup>54</sup> is a listing of wiring information contained on a single page of the pictorial circuit schematic from which the WIRE FILE was created. Two call-cards, the first with the words PAGE LIST and the second with from one to ten page numbers, in the order

52. See FIGURE 18 for an example of a NOTE LIST.
53. See FIGURE 22 for an example of an FS LIST.
54. See FIGURE 20 for an example of a PAGE LIST.

<sup>52</sup> 

listed in the wire file, each expressed in three numeric digits, are required for this routine. The report printed on the high speed printer contains wiring information for the desired pages of the pictorial circuit schematic.

NODE LIST is a report which contains information concerning certain specified wiring nodes in the WIRE FILE. As many as ten individual nodes may be included in this report but all the nodes must be from one page of the pictorial circuit schematic and must be listed in ascending order. Two call-cards are required for this segment of WIRERPTS. The first, as usual, contains the call words NODE LIST. The second, in three numeric digits, contains a pictorial circuit schematic page number followed by as many as ten arbitrary node numbers, each represented by two numeric digits. These two items, page number and node number, along with the functional

schematic number, make up the complete node identification. This output report presents, to the user, wiring information for a carefully defined area of the source document. The area covered, being so defined, presents a large amount of information in a very simple, short report.

APP FIG LIST<sup>56</sup> the last type of report produced by WIRERPTS contains information for as many as ten apparatus figures. As previously defined, an apparatus figure represents the apparatus which comprises a physical unit. The information contained in this

55. See FIGURE 21 for a sample NODE LIST.
56. FIGURE 19 contains a sample APP FIG LIST.

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classification is a cross reference between apparatus codes and functional designations. The usual two card calling format is used. The first contains the words APP FIG LIST, the second card providing from one to ten apparatus figure numbers each in four alphanumeric digits. The output report is a simple printed cross reference table of the desired apparatus figures.

The program titled APPLIST produces a single report called APP LIST. <sup>57</sup> A two card control format is used including the title of the report and up to four repeats of apparatus functional designations and generic names such as P38 REL. The output report, using this input information, produces, from the WIRE FILE, the associated apparatus codes and apparatus figure numbers. In addition, a complete list of all information concerning the wiring of each of these pieces of apparatus is included. This report in one op-

eration produces complete information about any piece of apparatus in the circuit with knowledge only of its functional designation and generic name. By relating information from various parts of the file together and then presenting that material in a logical structure APP LIST may well be the most useful report of all those generated by both WIRERPTS and APPLIST.

The WIRE FILE part of DIRECTION, containing both input routimes to create a tape file and output procedures for the production of a variety of useful reports from that file, has been designed to be flexible enough to provide a base for the extension of

57. See FIGURE 16 for sample of APP LIST.

DIRECTION to the area of preparation of manufacturing information. In addition, by the use of a calling vocabulary, the selective production of reports covering almost every possible format, is possible. These reports can be generated on the basis of one report per program run or, by stacking the input call cards, an unlimited number can be printed in a single pass. From a design or engineering viewpoint, this flexibility of file establishment and information retrieval is very useful. The ease of retrieval is particularly dependent on the file organization that has been established.

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#### 4.5 DESIGN VERIFICATION

One of the principal objectives of DIRECTION is to provide a simple automatic method of conducting certain checks on the accuracy of the design information contained in the pictorial circuit

schematic. These checks might range from the simplest test for duplication to the most elaborate analysis of the circuit logic. In order to reduce the complexity of such a procedure to that which could reasonably be considered at this time, it was decided to eliminate checks on circuit logic from the system. Instead, an area of design verification that would be most useful and at the same time lend itself to concentrated study was selected. DESIGN VERIFICATION, therefore, was defined to consist of five parts:

- 1. Multiple use of terminals.
- 2. Duplication of functional designations.

3. Presence of a functional designation in an apparatus figure but not in a functional schematic and vice versa.
4. Use of illegal terminals.

5. List of used and unused terminals.

It was expected that the DESIGN VERIFICATION portion of DIRECTION would be the most difficult to accomplish. At this point, the true value of efficient file organization was made evident. As a result of the structuring of the three files, the accomplishment of this portion of DIRECTION proved to be mostly a matter of resorting the files in a different manner so as to allow a comparison of various records.

Frequently, in a large circuit, terminals on a particular piece of apparatus are inadvertently used more than once. This type of an error is difficult to locate until the item is actually

wired. That late in the procedure, the detection of the error creates a great deal of difficulty. What is desired is a method for checking every wire termination in the WIRE FILE against every other termination to see if there exists a terminal duplication. The solution is simple. The magnetic tape WIRE FILE is resorted on three keys. The high order key is terminal number, the middle order is the functional designation of the apparatus on which the terminal appears, and the low order key is apparatus type. This resorting program can be a standard sort-merge routine produced by a sort generator. The resultant reordered file will contain all of the, say terminal number eights, together. Furthermore, the secondary keys of functional designation and apparatus type will

cause the multiple use of a particular terminal to appear in adjacent records. A procedure for comparing adjacent records with a branch-on-equal to a print routine would conclude the check. The determination of the duplicate use of functional designations is equally simple. If the portion of the WIRE FILE containing the apparatus type and functional designation cross reference was to be resorted on a primary key of functional designation and a secondary key of apparatus type, any multiple use of functional designations would appear in adjacent records. A comparison like that indicated above would produce a list of the duplications.

In order to determine the presence of a functional designation in an apparatus figure which is not used any place in the functional schematics, several sorting procedures must be used. The cross reference tables in the WIRE FILE must be resorted on a primary key of functional designation and a secondary key of apparatus type. This order is exactly that used in the check for duplicate functional designations. In addition, a sort must be conducted on the wiring type records in the WIRE FILE. These records, containing information on wire terminations on apparatus terminals, are sequenced in exactly the same manner as the apparatus cross reference type records. Once these two new files have been properly established, a record comparison will reveal whether a functional designation shown in an apparatus figure is present in a functional schematic or vice versa.

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A check for the use of non-existent or illegal terminals is most important. The variety of terminal configurations on different types of apparatus makes this test necessary. Three sorting procedures, a merge and a comparison, are necessary to accomplish this objective. First the wiring type records in the WIRE FILE are sorted on three keys. The primary one is functional designation, the secondary is apparatus type and the low order key is terminal. The apparatus cross reference type records in the WIRE FILE must also be sorted on three keys. The keys are, in order, functional designation, apparatus type and apparatus code. These two files are then merged to produce a new file containing four fields; functional designation, apparatus type, apparatus code and terminal. The merged file is sorted again, this time on apparatus type, apparatus code, terminal and functional designation. This file is now exactly in sequence with the APPARATUS MASTER FILE which contains information on the terminal configuration of all apparatus. A comparison of the two files will produce a list of illegal or non-existent terminals which are indicated as used in the WIRE FILE. Once the procedures for determination of the use of illegal terminals has been completed, the same two files, one the merged and resorted WIRE FILE, the other the APPARATUS MASTER FILE, can be used to determine used and unused terminals. Each record in the new modified WIRE FILE represents a used terminal. A comparison of these records with the APPARATUS MASTER FILE will indicate legal but unused terminals. This type of information is of value to the designer trying to make additions to the circuit and faced with the problem

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of locating vacant terminals.

# 4.51 DUPLICATEFD

Determination of duplicate use of functional designations is the one portion of DESIGN VERIFICATION which has been implemented. Due to the size of the appropriate portion of the WIRE FILE for the Trunk Switching Circuit, sorting was accomplished within core instead of on tape. The program developed for this check is titled DUPLICATEFD.<sup>58</sup> The output is a list containing only the duplicated functional designations.<sup>59</sup> Since the core sort used in DUPLICATEFD is limited to seven hundred functional designations, extensions to DIRECTION should include a conversion of this program to a tape oriented sort.

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58. See FIGURE 13 for the flow chart of DUPLICATEFD.
59. FIGURE 23 contains sample output of DUPLICATEFD.

# 5. Conclusion

The objective of this study was to design and evaluate a system to represent electrical circuit schematic information in a manner suitable for storage on a magnetic media with:

1. Provision for easy updating.

2. The capacity to rapidly produce selective engineering reports.

3. The ability to conduct routine design checks.

Each part of this objective has been accomplished.

Conversion of a pictorial circuit schematic drawing to a digital format was accomplished by the use of the nodal or equipotential method of reducing a large complex circuit into a number of simple circuits each with a unique seven digit identification number. A magnetic tape file has been designed, called the WIRE

FILE, which contains information about each of these small circuits or nodes. Other information such as circuit notes and apparatus cross reference tables are also included in the WIRE FILE. With the WIRE FILE containing mostly wiring or electrical information, another file titled UNIT FILE has been designed to include information about the physical components which comprise a unit of electrical equipment. Part numbers, quantities, descriptions and stock list information was included in the records of this file. A third file was necessary to provide information about the many standard items of apparatus which may be used in the design of a circuit. This file has been titled AP MSTR FILE. Within these

three files:

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1. WIRE FILE

2. UNIT FILE

3. AP MSTR FILE

can be contained all of the information necessary to completely describe an electrical circuit.

The next objective was to provide a means for the rapid updating of the three files. This was made necessary by the transitory condition of the design information. Shortened schedules require the release of design information before it is either complete or thoroughly tested. As a result it can be expected that many changes will be required right up to the time for manufacturing to start. This updating problem has been solved by the use of a vocabulary of four call-words:

- 1. START
- 2. ADDITION
- 3. MODIFY
- 4. DELETE

A person, not highly trained in computer technology, through the use of these four call-words and the associated computer programs which have been prepared, can easily maintain the magnetic tape files for any circuit.

The ability to rapidly produce selective engineering reports was a key one in this system design. Using the present method of representing the circuit information in a pictorial format the user is presented with a number of large documents from which he must

cull the information he desires to use. This technique violates the most elementary principles of information presentation.<sup>60</sup> If the value of a report is to be measured by its usefulness to the user, some technique should be used to present only the information which the user desires. DIRECTION does this by providing him with a vocabulary of seven words with which he can direct the computer to produce the report he desires. These words are:

- 1. ALL LIST
- 2. NOTE LIST
- 3. FS LIST
- 4. PAGE LIST
- 5. NODE LIST
- 6. APP FIG LIST
- 7. APP LIST

The resulting seven types of output are each designed to provide a different type of information, each in a different form.

The ability of the system to conduct certain routine design checks was a key objective. Consider the design problem. In order to do what is considered a good job there should be few errors in the circuit drawing. Errors in this document can originate either with the designer or with the draftsman. In order to eliminate the errors an elaborate system of manually checking the circuit at each stage in its preparation is presently followed. Use of DIRECTION

60. Gregory, R. H. and Van Horn, R. L. <u>Automatic Data</u> <u>Processing Systems: Principles and Procedures</u>. <u>Belmont, Colifornia: Wadsworth, 1963, P. 3</u>.

AND PR.

makes possible the elimination of some of this tedious nonproductive effort. While checking for errors in logic is not included, the detection of other types of errors is so simple and rapid that finding them by any other method is without merit. In the implementation of DIRECTION used in this study, keypunched data was machine verified. Further consideration in this area indicates that even this effort might not be necessary. The system itself should and can be used to check its own input. The few errors it detects can then be corrected manually.

Some of the savings which are made possible by the use of **DIRECTION** are worthy of consideration. Some of these savings might result from:

1. Reduction in required manpower.

2. Improvement in communication.

The press of competition and expanding technology has resulted in an ever increasing, more rapid, flow of manufacturing information from designer to factory. It has been estimated that 40% to 80% of this information concerns itself with wiring.<sup>61</sup> In addition to the great increase in volume of wiring information and the press toward a shorter engineering interval, an even greater problem in available engineering manpower is looming over the horizon. Estimates have been made that by the mid 1970's it will be

61. Bedell, E. H., "New Techniques in Preparation and Use of Manufacturing Information". Speech given before Bell System Executives, Cherry Hill, New Jersey, June 20, 1963.
impossible to recruit sufficient engineering talent to process design information into manufacturing information by manual 62 A parallel is drawn that if the automatic dial telemethods. phone system had not been perfected, approximately one fourth of the total female working population would presently be required 63 The use of DIRECTION will help to solve as telephone operators. this problem by allowing the computer to accomplish much of the work presently being done by engineers and draftsman. For example, in translating the Trunk Switching Circuit onto punched cards approximately four man weeks were required for both analysis and keypunching effort. With the exception of manual intervention in special situations, this represents the total manual effort required on this circuit. All additional processing, including all of the drafting effort, toward the production of manufacturing in-

formation will be done by the computer. Using more conventional techniques the engineering and drafting effort on a medium sized circuit might amount to as much as one and a half man years. The indicated saving in man effort, therefore, is of the order of 20 to 1.

The communications problem that exists in transmitting circuit and wiring information between manufacturing or engineering locations is another area of savings. Elaborate data transmission systems

62. "Regional Computer Utilization: Costs and Savings". Unpublished Paper, Western Electric Company - Systems Equipment Engineering, 1963.

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63. ibid.

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which are capable of high speeds are in existence. They depend, however, on a magnetic input media. DIRECTION allows the utilization of this transmission network while more conventional methods of circuit representation are dependent on slower communication

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#### 6. Future Considerations

DIRECTION must be considered as merely the first step in the process of completely automatic preparation of manufacturing in-The area in which the expenditure of additional effort formation. will result in the greatest gain will therefore be in the extension of DIRECTION to the actual preparation of local cable design, surface wiring lists and other detailed wiring information. Techniques exist, as outlined in Section 3. of this thesis, which should make possible the accomplishment of these goals. Before this ominously large undertaking is started, a number of limitations which have been included in DIRECTION should be removed. These limitations, including the absence of an overall executive routine to interconnect each of the eight programs comprising DIRECTION and the incomplete detailed programming of the design verification

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phase, are largely caused by the shortcomings of the computer hardware configuration used. A larger machine must be utilized. With the present programming in COBOL, conversion to almost any other machine should be easily facilitated.

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FIGURE I.

64. SELLERS, G. A. JR. PERSONAL INTERVIEW, BELL TELEPHONE LABORATORIES, APRIL 1963.

# EXPLOSION OF INFORMATION 65

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66. HOBERECHT, V. L. op. cit.

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FIGURE 4

Pictorial Circuit Schematic Drawing

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FIGURE 5

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Flow Chart - APMSTRIN

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Flow Chart - APMSTROUT

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Flow Chart - UNITMSTR

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Flow Chart - UNITRPT

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URI OPEN ALL 1 FILES READ DATE-FILE WRITE UNITRPT COVER READ UNIT-MSTR UNIT-MSTR CONTROL-KEY EQUAL NB NA UR4 URS MOVE MOVE UNIT-MSTR RECORD TO WORKING STORAGE

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FIGURE 10

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Flow Chart - WIREMSTR

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START WML OPEN

WIRE-DATA, NEW-WIRE-MST. ERROR-FILE ÷.

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WRITE-DEA SECTION

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OGP-CA TO OUTPUT

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MOVE DGP-EA TO OUTPUT WRITE NEW-WIRE-END

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COMPARE-AA SECTION

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OLD-WIRE-MST WIRE-DATA GP-AA

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FIGURE 11

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Flow Chart - WIRERPTS

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WRITE-HEADS SECTION

BEGIN

ADVANCE RPT-FILE TO TOP OF PAGE

ADD I TO PAGE NUMBER

WRITE HEAD5

END

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FIGURE 12

Flow Chart - APPLIST

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0.0.1	FLAG EQ	FS-NOO(0) EQ	PAGE-NOO(O) EQ	NODF-NOO(U) EQ	<u>CO TO</u>
	BA CA	F5-N0 F5-N0	PAGE-NO PAGE-NO	NODE-NO NODE-NO	TABLE SEARCHO TABLE SEARCHO

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FLAG EQ	FS-NON(N) EQ	PAGE-NON(N) EQ	NODE - NON(N) EQ	SPACES	WRITE	CO TO
BA	FS-NO	PACE-NO	NODE-NO	EQ APP-TYPE	REC-JDBA	WR 77
BA	/ FS-NO	PAGE-NO	NODE-NO	NEQ APP-TYPE	PEC-5C	-
BA	FS-NO	PAGE-NO	NODE-NO	NEQ MISC	REC-JDBA	WR77
BA	FS-NO	PAGE-NO	NODE-NO	EQ MISC	-	WR77
CA	FS-NO	PAGE-NO	NODE-NO	EQ TERMINAL	REC-3DCA	WR77
CA	FS-NO	PAGE-NO	NODE-NO	NEQ TERMINAL	REC-6D	•
CA	FS-NO	PAGE-NO	NODE-NO	NEQ MISC	REC-JDCA	WR.77
CA	F5-NO	PACE-NO	NODE-NO	EQ MISC		WR77





FROM PAGE 110



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		TABLE SEAR	СНМ			
FLAG EQ	F5-NOM(M) EQ	PACE-NOM(M) EQ	NODE-NOM(M) EQ	SPACES	WRITE	CO <b>TO</b>
ВА ВА ВА СА СА СА СА	F5 - NO F5 - NO	PAGE - NO PAGE - NO PAGE - NO PAGE - NO PAGE - NO PAGE - NO PAGE - NO	NODE - NO NODE - NO NODE - NO NODE - NO NODE - NO NODE - NO NODE - NO	EQ APP-TYPE NEQ APP-TYPE NFQ MISC EQ TERMINAL NEQ TERMINAL NEQ MISC EQ MISC	REC-3DDA REC-6C REC-3DDA REC-3DCA REC-5D REC-5DCA	WR 79 WR 79 WR 79 WR 79 WR 79 WR 79



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1	TABLE SEARCHMM						
FLAG EQ	FS-NOM(M) EQ	PAGE-NOM(M) EQ	NODE-NOM(M) EQ	CO TO			
BA CA	FS-NO FS-NO	PAGE-NO PAGE-NO	NODE-NO NODE-NO	TABLE SEARCHM TABLE SEARCHM			

<b></b>			TABLE SEARCHI				
	FLAG EO	FS-NOL(L) EQ	PAGE-NOL(L) EQ	NODE-NOL(L) EQ	SPACES	WRITE	CO TO
	BA	F5 - NO	PACE - NO	NODE - NO	EQ APP-TYPE	REC-JDBA	WR 81
	BA	FS - NO	PAGE-NO	NODE-NO	NEQ APP-TYPE	REC-6C	-
	BA	ES - NO	PACE-NO	NODE - NO	NEQ MISC	REC-JDBA	WRAI



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FIGURE 13

Flow Chart - DUPLICATEFD

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READ CONTROL-FILE

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STOP RUN

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Output - MASTER APPARATUS LIST

## FIGURE 14

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PAGE

APPARATUS Type	APPARATUS CODE	CONTACTS OR TERMINALS
BIAS CORE	26048	1
		2
		3
		• 4
	·	5
		6
		7
<b>0</b> • •		8
UAP	437A	Δ
CAP	- 4 7	B
CAP	5130	1
CAR		2
	535EA 535CA	ΡΤ
	505GA	PT
	6U1A	PT
	601E	PT
	K514056,L6-220	PT
	K319000,L10056	PT
UP	A 4	0
		1
		2
		3
		4
		5

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APPARATUS CODE	CONTACTS UR TERMINALS
A35	17 (CONT)
	18
	19
	20
	21
	22
	23
	24
	25
	26
	2/
426AC	1
4 D 7 7 4	2
103/4	1
K610007 10	∠
KOTASSOLS	78
	20
	40 1 T
	21
	31
	4 T
	5T
<b>A</b> 3	1
	2
185A	PT
185C	PT
	APPARATUS CODE A35 426AC 1037A KS19223.L2 A3 185A 185A 185C

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185C PT ...

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APPARATUS Type	APPARATUS CODE	CONTACTS OR TERMINALS
NET REL	186D 303A	PT 1 3 5 6 8
REL	<b>303G</b>	1 3 4 5 6 7 8
	<b>A J 5</b>	18 28 38 48 58 68 78 88 98 108 118 128 1F 2F 3F

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### PAGE 10

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4	APPARATUS Type	APPARATUS CODE	CONTACTS OR TERMINALS
	REL	<b>AK6</b>	10M (CONT) 11M 12M 1U 2U 1L
	RES	1 8 R	1
	NE O		2
	RES	18CJ	1
	RES	18FC	2 1 2
	RES	19EY	1 2
			3
	RES	K\$8512,L11-10	PI
	RES	KS13492, L2-2200	PI
	RES	KS14603,L1A-316	PI
	RES	KS14603,L1A-619	PI
	RES	KS14603,L1D-562	
	RES	KS146U3,L38-3U1	
	RES	KS19150,L2-1000	
	RES	K319150,L2-1000	
	RES	KS1919U0L2-02UU	
	RES	KOTAIDAPESIAAA	
	RES	K519150,L2-0.1MEG	
	RES	K217121, L2-00U	<b>F</b> 1

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#### PAGE 16

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APPARATUS TYRE	APPARATUS Code	CONT Term	ACTS OR Inals
SW	2424	38R	[CONT]
TRNSF	2074A	39K 1	
,		2 3 4	<b>`</b>
		5	
TRSTR	34A	B C	
END MASTER	APPARATUS LIST	E	

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PAGE :4 . 

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#### FIGURE 15

#### Output - UNIT LIST

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UNIT LIST

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## DEC 6, 1963

J1A030

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1.

		APPARATUS CODE, Group or list,	APPARATUS Type, sub Unit or
UNIT	QTY	OR PART NO.	DESC.
J1A030A-1	1	1	J1A030AA-1
A-1	1	1	J1A030AB-1
 A-1	1	1	J1A030AD-1
A-1	1	1	J1A030AE-1
A-1	1	1	J1A030AR-1
A-1	1	1	J1A030AG-1
A-1	1	1	J1A030AH-1
	1	SA	
A-1	1	1	J1A030AH-1
	1	SB	
A-1	1	1	J1A030AH-1
	1	SC	
A-1	1	1	J1A030AH-1
	1	SD	
A-1	1	1	J1A030AM-1
A-1	1	1	J1A030AN-1
A-1	1	1	J1A053A-1
A-1	` <b>1</b>	1	J1A0538-1
A-1	1	2	ED1A151-70
	1	C	
A-1	2	4	ED1A157-70
A-1	1	P-45G418	VERT GRD BU
A-1	6	P-45G785	GROMMET
A-1	3	P-45G781	CAPS
A-1	6	P-45G032	CABLE ASSY
A-1	2	P-45G032	STA-KON TER
A - 1.	7	P-45G414	CABLE RING
A-1	2	P-45G415	CABLE BKT

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FUNCT DESIG POSITION L'A S RMS T-B CAT NO C126

J1A030



PAGE 2

	UNIT	QTY	APPARATUS CODE, GROUP OR LIST, or part no.	APPARATUS Type, Sub Unit or f Desc. 1
	J1A030A-1	2	P-45G416	CABLE BKT
	A-1	4	P-45G439	CABLE SUPPOR
	A-1	5	P-423662	· CLIP
	A-1	2	~	SNAP BUSHING
	A-1	3	P-43A298	RHST SUR .164
	A-1	18	P-41C930	PHSI SUR .130
	A-1	2	P-353449	RHM SCR .216
	A-1	11	P-174399	PHST SCR .210
	AA-1	2	P-45G8U4	MIG BAR
	AA-1	1	286A	MIG MLAIC
12	AA-1	2	2598M	TPASE
Ő	AA-1	L	2590M	TONCE
	AA-1	1	25908	TRNDE
	AA-1	1	2598 <b>K</b>	TS
	AA-1	1	236M	TS
•	AA-1	1	280M	TS
	AA-1	1		DEC
	AA-1	1	$K_{510047}$ , $L_{2}^{-100}$	
	AA-1	1	KS16645 L2-100	RES
	AA-1	4	KS16645, L2-100	RES
		4	2860	MTG PLATE
		1	2000 46A	APP MTG
		. 1	364	APP MTG
		1	9n5A	CONN
	- AA_4	1	905A	CONN
		1	905A	CONN
		-	905A	CONN
		-		

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FUNCT DESIG POSITION

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HEYMAN MFG CO KENILWORTH NJ CAT NO SB100-12 4-32 × 11/16 8-32 × 1/2 -24 × 3/4 6-24 × 1 0AD 89

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88 728 1AD 24B OAD 888 408 1AD 0 C 568 1048 MISC 10 24R TR40.0 24R 88R 88R TR41.0 TR40.1 TR41.1 ۰. 1 2 3 5

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				APPARATUS
			APPARATUS CODE,	TYPE, SUB
		_	GROUP OR LIST,	UNIT OR
	UNIT	QTY	OR PART NO.	DESC.
			· ·	
	J1A030AM-1	8	724	FUSE DUMMY
	÷ AM-1	13	KS14174,L1	DESTG PIN
	AM-1	2	KS14174,L2	DESIG PIN
	AM-1	2	KS14174,L2	DESIG PIN
	AM-1	1	KS8512, L4A-178	RES
	AM-1	1	KS8512, L4A-178	RES
	AM-1	1	KS8512, LQA-178	RES
•	AM-1	1	KS8512,L4A-178	RES
	AM-1	1	KS8512, L4A-825	RES
	• AM-1	1	KS8512 - 4A-825	RES
	AM-1	12	P-374596	WASHER, CUP S
	AM-1	12	P-95836	WASHER, MICA
	AM-1	2	P-338014	ALARM TERM P
	AM-1	6	KS15977,L13	CONN
	AM-1	12	P-181358	BHM SCR 138
	AM-1	12	P-183146	LOCK WASHED
	AM-1	24	P-386216	HEX NUT 130
	AM-1	6		TERMINAL STA.
	AM-1	6		HEAT SHRINKAN
	AM-1	6	P-181470	RHM SCR . 164
	AM-1	4	P-182142	BHM SCR . 216.
	AM-1	1	P-174399	PHST SCP 240
	AM-1	2	P-148634	RHM SCR 216
	AM-1	1	P-388493	PHST SCR 21
	AN-1	2	P-45G801	MTG RAR
	AN-1	1	285A [1H21]	MTG PLATE
	AN-1	1	AK6	REI
	AN-1	1	19EY	RES

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J1A030

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FUNCT DESIG POSITION SWA1 SWB1 36R 42R . 62R 68R 10R 16R 4 PRING US BAR -32 X 3/8 .022-.320 -KON T-B CAT NO C126U BLE INS. T-B CAT NO N375-2 -32 X 1 1/4 5-24 X 1/4 16-24 X 1 5-24 X 1/4 16-24 X 5/8

	UNIT	QTY	APPARATUS CODE, Group or list, or part no.	APPARATUS Type, sub Unit or Desc.	F
	J1A030AN-1	1	19EY	RES	
	AN-1	1	AJ5	REL	
	AN-1	1	AJ5	REL	
	AN-1	1	AF11	REL	
	AN-1	2	1850	NET	
	AN-1	1	185C	NET	
	AN-1	1	1850	NET	
	AN-1	1	185A	NET	N
	AN-1	1	186A	NET	F
	AN-1	1	KS19150, <b>L2-560</b>	RES	S
2	AN-1	1	KS19150,L2-3900	RÉS	S
00	AN-1	1	210A	TERM	
	- AN-1	1	P-174399	PHST SCR .2	16
	AN-1	2	P-148634	RHM SCR .21	6 -
	AN-1	1	P-388493	PHST SCR .2	16
	AP-1	1	P-456534	MTG PANEL	
	AP-1	1	P-45G789	BKT	
	AP-1	1	P-45G500	HOUSING ASS	Y
	AP-1	4	KS14523,L1	CONN	
	AP-1	1	KS19150,L <b>2-12000</b>	RES	H
	AP-1	1	1224	DES STRIP	
	AP-1	3	306A	TS	
	AP-1	1	P-45G526	PANEL ASSY	
•	AP-1	1	P-45G505	JK MTG	
	AP-1	2	223A	JK	T
~	AP-1	1	238A	JK	S
()*	AP-1	4	KS14523,L1	CONN	
	AP-1	4	P-45G539	MTG BKT	

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J1A030

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		APPARATUS
	APPARATUS CODE,	TYPE, SUB
	GROUP OR LIST,	UNIT OR
QTY	OR PART NO.	DESC.
1	KS14056,L6-220	CAP
1	KS14056,L6-220	CAP
1	535GA	CAP
1	535GA	CAP
2		LUG ZIERICK
4	P-388493	PHST SCR .2
8	P-353501	RHM SCR .21
4	P-180781	RHM SCR .09
4	P-384948	HEX NUT .09
24	P-210800	RHM SCR .11
24	P-210828	HEX NUT .11
4	P-205654	FHM SCR .16
4	P-206519	RHM SCR .10
4	P-125949	RHM SCR .13
4	P-125952	HEX NUT .13
8	P-206518	HEX NUT .16
PORT		
	QTY 1 1 1 2 4 8 4 24 24 24 24 24 24 24 24 24 24 24 24 2	APPARATUS CODE, GROUP OR LIST, QTY OR PART NO. 1 KS14056,L6-220 1 KS14056,L6-220 1 535GA 2 4 P-388493 8 P-353501 4 P-180781 4 P-180781 4 P-210800 24 P-210828 4 P-205654 4 P-205654 4 P-205654 5 P-206519 4 P-125952 8 P-206518 PORT

J1A030

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PAGE 34

FUNCT POSITION DESIG C116.0 C116.1 C117.0 C117.1 K MFG CO NEW ROCHELLE, NY. CAT NO 7 216-24 X 5/8 16-24 X 5/16 99-48 X 5/16 99-48 12-40 X 1/4 12-40 64-32 X 3/8 64-32 X 3/8 38-32 X 1/2 38-32 64-32

FIGURE 16

Output - APP LIST

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SD-1A107-01 ISSUE 1

APP LIST

DEC 6, 1963

ELECTRONIC SWITCHING SYSTEMS NO 1 TRUNK SWITCHING CIRCUIT

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TYPE

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APP	ARATUS	FUN	CT	APP	CODE		
TTP	E	DE 2	16	r I G	CODE	ι.	
REL		P13		0003	AJ703		
				FUN	ст	APPARATUS	
FS	PAGE	NODE	CONTACT	DES	IG	TYPE	0P1
1	11	76	25	320	4	CP	
1	11	76	10	P13		REL	
1	11	76	PT	P13	A	NET	
1	14	58	25	322	0	CP	
1	14	58	20	P13	•	REL	
1	14	58	PT	P13	B	NET	
2	17	10	8	261	.1	CP	
2	17	10	1L	P10		REL	
2	17	10	PT	P10	Α	NET	
2	17	10	1L	P11		REL	
2	17	10	PT	P11	. 🔺	NET	
2	17	10	1L	P12	2	REL	
2	17	10	PT	P12	? A	NET	
2	17	10	1L	P13	5	REL	
2	17	10	PT	P13	5 A	NET	
2	17	10	<b>1</b> L	P14	ŀ	REL	
2	17	10	PT	P14		NET	
2	17	10	1L	P15	5	REL	
2	17	10	PT	P15	5 A	NET	
2	17	10	1L	P16	5	REL	
2	17	10	PT	P16	5 A	NET	
2	17	10	1L	P17	7	KEL	
2	17	10	PT	P17	7 A	NET	
2	18	16	8	242	27	CP	

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APP LIST

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#### WIRING METHOD

COLOR

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		56	BACE	NODE	CONTACT	FUNCT	APPARATUS					WIRING	
		rJ	FAUL	NUDE	CUNTACT	DESIG	IYPE	OPT	<b>GA</b>	TYPE	COLOR	METHOD	
		2	18	16	2L	P10	REL						
		2	18	16	PT	P10B	NET						•• •
je -		. 2	18	16	2L	P11	REL					::	
	-	2	18	16	PT	P118	NET						
		2	18	16	2L	P12	REL						
1 de	-	2	18	16	PT	P128	NET					ж.	
-		2	18	16	2L	P13	REL						
		2	18	16	PT	P13B	NET						
	,	2	18	16	2L	P14	REL						
		2	18	16	PT	P14B	NET				·		
		2	18	16	2L	P15	REL					•	
		2	18	16	PT	P158	NET						
i	щ	Ž	18	16	2L	P16	REL					°.	
А.	ι ε	Ž	18	10	PT	P168	NET					<del></del>	·
	~~	Ž	18	16	2L	P17	REL						L
		Ž	18	16	PT	P178	NET						
		0	24	06	PT	R7	RES				2		· ·
ł		6	24	06	24F	P10	REL				<b>₽</b> 1		•
Ĺ		0	24		24F	P11	REL					:+	
1	,	6	24	06	24F	P12	REL						
1		0	24	06	24F	P13	REL				Ý		ingen er
ł		0	24	06	24F	P14	REL						
l		6	24	06	24F	P15	REL						
		6	24	06	24F	P16	REL						
		6	24	06	24F	P17	REL			a 🛋 î			
l		0	24	12	9F	TO	REL			₩,			<b>-</b> .
		0	24	12	24M	P10	REL			2			
		0	24	12	24M	P11	REL			·.			·
		6	24	12	24M	P12	REL					*	
		Ð	24	12	24M	P13	REL					2	
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#### SD-1A107-01 ISS 1 APP LIST PAGE

WIRING TYPE COLOR GA METHOD
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- 41 F

APP	ARATUS	FUNCT DESIG		APP FIG	APP Code		
SW		003	۲	0006	2424		
FS	PAGE	NODE	CONTACI	FUN Des	CTIG	APPARATUS Type	0P
9	28	01	09R	003		SW	
Ó	28	01	1 0 R	003	)	SW	
9	28	06	4F	P10		REL	
ó	28	06	00R	003	5	SW	
ġ	28	07	4F	P11		REL	
ó	28	07	01R	003	5	SW	
ó	28	08	4F	P12	2	REL	
ó	28	08	02R	003	5	SW	
ó	28	09	4F	P13	3	REL	
ģ	28	09	03R	003	5	SW	
9	28	10	4F	P14	ł	REL	
9	28	10	04R	003	5	SW	
9	28	11	4F	P15	5	REL	
9	28	11	05R	003	3	SW	
<b>Q</b>	28	12	4F	P10	5	REL	
9	28	12	06R	003	3	SW	
9	28	13	<b>4</b> F	P11	7	REL	
9	28	13	07R	003	3	SW	
9	28	14	19R	003	3	SW	
9	28	14	8F	P3	3	REL	
9	28	15	18R	0 0	3	SW	
9	28	15	7 M	P3	3	REL	
Ŷ	28	16	17R	00	3	SW	
9	28	16	6F	P3	3	REL	

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7-01	ISS	1	APP LIST	۲. ۲	PAGE	11
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PT GA TYPE COLOR METHOD

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24	BU		1		
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24	8 <b>u</b>				
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24	BU				
24	BU				
24	BU				
24	BU			::	
24	RU				
24	211				
24	RU				

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APPARATUS FUNCT COLOR TYPE GA OPT TYPE DESIG CONTACT NODE PAGE FS BU 24 SW 003 16R 17 28 9 BU 24 REL P33 5M 28 17 9 BU 24 SW 003 18 15R 28 9 BU 24 REL P33 4F 18 28 9 24 BU SW 003 14R 19 28 9 24 BU REL P33 3M 19 9 28 BU 24 SW 003 13R 20 28 9 24 BU REL P33 20 2F 9 28 24 BU SW 003 9 9 12R 21 28 BU 24 REL P33 21 1M 28 SW 003 11 11 00F 01 44 TO TRK DIST CKT 01 44 LEAD T30 SW 003 01F 02 11 44 TO TRK DIST CKT 02 11 44 LEAD R30 SW 003 02F 03 44 11 TO TRK DIST CKT 03 11 44 LEAD T31 SW 003 038 04 11 44 TO TRK DIST CKT 04 11 44 LEAD R31 SW 04F 003 05 11 44 TO TRK DIST CKT 05 11 44 LEAD T32 SW 05F 003 06 11 44 TO TRK DIST CKT 06 44 11 LEAD R32 SW 06F 003 07 11 44 TO TRK DIST CKT 07 11 44 LEAD T33

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-01	ISS 1	APP LIST	PAGE	12

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APPARATUS Type		PPARATUS FUNCT YPE DESIG		APP APP FIG CODE			
CP		260	3	0002	A 6		
FS	PAGE	NODE	CONTACT	FUN	CT 1G	APPARATUS	OPT
Ϋ́́́	r AUL	NODE	CONTACT	DEG	10		UPT
2	17	21	15	240	2	CP	
2	17	21	24	260	5	CP	
2	17	21	19	260	5	CP	
2	17	21	10	260	3	CP	
2	17	21	6	260	3	CP	
2	17	21	7	240	5	CP	
2	17	21	9	260	9	CP	
2	17	21	20	260	9	CP	
2	17	21	8	260	9	CP	
4	21	07	8	260	5	CP	
4	21	07	2	260	4	CP	
4	21	07	8	260	4	CP	
4	21	07	21	260	3	CP	
4	21	07	11	240	5	CP	
4	21	11	1	260	3	CP	
4	21	11	COMM BL	JS CKT	•		
			LEAD OF	D36			
4	21	12	5	260	3	CP	
4	21	12	COMM BL	JS CKT			
			LEAD 1A	D36			
4	21	16	3	260	4	CP	
4	21	16	1	260	4	CP	
4	21	16	0	240	5	CP	
- 4	21	16	10	240	6	CP	

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### SD-1A107-01 ISS 1 APP LIST

## GA TYPE COLOR

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## PAGE 15

## WIRING METHOD

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					S	D-1A107	-01	ISS 1	APP	LIST PAGE	16
FS (	PAGE	NODE	CONTACT	FUNCT DESIG	APPARATUS Type	OPT	GA	TYPE	COLOR	WIRING Method	
4	21	16	0	2404	CP						· · · · · · · · · · · · · · · · · · ·
4	21	16	8	2603	CP						
4	21	18	10	2604	CP				1		
4	21	18	9	2604	CP				u.		
4	21	13 11	2	2405	CP				,		
4	21	181	12	2603	CP					:	
4	21	18	8	2406	CP					· · · · · ·	· · ·
4	21	18	3	2414	CP					, .r	
4	21	20	0	2603	CP						
4	21	20	4	2405	CP						
4	21	20	9	2603	CP						
4	21	21	3	2603	CP						
4	21	21	5	2405	CP						
4	21	21	11	2603	CP						,
4	21	26	20	2603	CP					• •	
4	21	26	25	2404	CP				ŕ		· •
4	21	26	12	2405	CP						•,:
4	21	26	24	2603	CP						
4	21	30	23	2402	CP				¢.		· · · · · · · · · · · · · · · · · · ·
4	21	30	10	2402	CP					ļ	
4	21	30	23	2603	CP				,		
4	21	55	13	2603	CP				R.	् इ <sup>1</sup> इ. हे	
4	21	55	GRD						DN DN		
4	21	58	14	2603	CP					2 2 2 2	
4	21	58	+24 A2 B	ATT	•••					י ג אי	[.
END L	IST		_			ν.			RED		
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FIGURE 17

Output - ALL LIST

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SD-1A107-01

ISSUE 1

ALL LIST

DEC 6, 1963

# NO 1 TRUNK SWITCHING CIRCUIT

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ELECTRONIC SWITCHING SYSTEMS

PAGE 1

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ALL LIST PAGE SD-1A107-01 ISS 1 2

### CIRCUIT NOTES.

103 NETWORK NO 1 CODE 185C 560 OHMS 0.25MF NETWORK NO 2 CODE 186D 270 OHMS 0.5MF

EQUIPMENT NOTES.

AND THIS MOUNTING SHALL BE ADJUSTED AS FOLLOWS TIGHTEN MOUNTING SCREWS TIGHT AGAINST PLATE AND BACK OFF FOUR #CLICKS#. UNLESS OTHERWISE SPECIFIED ALL LEADS ARE IN #OPEN TROUGH#. 202

INFORMATION NOTES.

301 UNLESS OTHERWISE SPECIFIED RESISTANCE VALUES ARE IN OHMS. CAPACITANCE VALUES ARE IN MICROFARADS. 302 THE CIRCUIT DESIGN INFORMATION AVAILABLE FOR ISSUE 1 DOES NOT INCLUDE

CROSS CONNECTING INFORMATION AND NOTES.

402 THE INTERCONNECTING INFORMATION TO THE JUNCTOR SWITCHING CIRCUIT (B-LINK WIRING! IS NOT AVAILABLE FOR ISSUE 1. THIS INFORMATION WILL BE AVAILABLE AS A J-SPECIFICATION.

140

NOTES

201 ALL (GR), (PS), AND (P) RELAYS SHALL BE MOUNTED WITH LP19A890 FLEXIBLE MOUNT

THE CIRCUIT DESCRIPTION(CD), EQUIPMENT MANUFACTURING TESTING REQUIREMENTS [X-SPECIFICATION ; SEQUENCE CHARTS AND CIRCUIT REQUIREMENTS TABLE (CRT).

•:

APP	APPARATUS	APPARATUS	FUNCT
FIG	TYPE	CODE	DESIG
	<b>a</b> 0		
0001		A32	2810
0001	CP	A32	2812
0001	CP	A32	2814
0001	CP	A32	2826
0001	CP	A32	2828
0001	CP	A32	2830
0001	CP	A32	3010
0001	CP	A32	3012
0001	CP	A32	3014
0001	CP	A32 °	3026
0001	CP	A32	3028
0001	CP	A32	3030
0001	CP	A32	3210
0001	CP	A32	3212
0001	CP	A32	3214
0001	CP	A32	3226
0001	CP	A32	3228
0001	CP	A32	3230
0001	CP	A29	2802
0001	CP	A29	2804
0001	CP	A29	2806
0001	CP	A29	2808
0001	CP	A29	2818
0001	CP	A29	2820
0001	CP	A29	2822
0001	CP	A29	2824
0001	CP	A29	3002
0001	CP	A29	3004
0001	CP	A29	3006
0001	CP	A29	3008

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### SD-1A107-01 ISS 1 ALL LIST

# UPPER HALF FUNCT Desig

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PAGE 3

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APP	APPARATUS	APPARATUS		FUNCT
FIG	TYPE	CODE		DESIG
0007	RES	KS19150,L1-1000		R65
0007	RES	KS19150,L1-1000		R66
0007	RES	KS19150,L2-1800		R67
0007	RES	KS19150,L2-1800		R68
0907	RES	KS19150,L2-1800		R69
0007	RES	KS19150,L2-1800		R70
0007	RES	18R		R83
0007	RES	18R		R84
0007	RES	18R		R85
0007	RES	18R		R86
0007	RES /	18R		R87
0007	RES	18R		R88
0007	RES	18R		R89
0007	RES	18R		R90
0008	REL	AK6		P1
0008	REL	AJ5		PWO
0008	REL	AJ5		PW1
0008	NET	185C		P 0
0008	NET	185C		P1
0008	NET	185C		PWO
0008	NET	1850		PW1
0008	RES	19EY		R81
0008	RES	19EY		R82
0008	KEY	KS19223,L2	$\sim$	NOR
0008	KEY	KS19223,L2		0FF-0
0008	KEY	KS19223,L2		0FF-1
0008	LP	A 3		OFFNOR
0008	LP	A 3		<b>0S-</b> 0
0008	LP	A 3		05-1
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## UPPER HALF FUNCT DESIG

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PAGE 24

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					FUNCT	APPARATUS				-
	FS	PAGE	NODE	CONTACT	DESIG	TYPE	OPT	GA	TYPE	CO
	_ 1	11	01	12	3012	CP				
	1	11	01	27	2404	CP				
	1	11	01	12	3014	CP				
	1	11	01	12	3010	CP				
	1	11	01	12	3214	CP				
5	1	11	01	12	3212	CP				
	1	11	01	12	3210	CP				
	1	11	01	12	2814	CP				
	1	11	01	12	2812	CP				
	1	11	01	12	2810	CP				
	1	11	02	4	2404	CP				
	1	11	02	5	3214	CP				
	1	11	02	5	3212	CP				
14	1	11	02	5	3210	CP				
ω	1	11	02	5	3014	CP				
	1	11	02	5	3012	CP				
	1	11	02	5	3010	CP				
	1	11	02	5	2814	CP '				
Ø	1	11	02	5	2812	CP				
-	1	11	02	5	2810	CP				
	1	11	03	5	2404	CP				
	1	11	03	8	3214	CP				
	1	11	03	8	3212	CP				
	1	11	03	8	3210	CP				
	1	11	03	8	3014	CP			κ.	
	1	11	03	8	3012	CP				
	1	11	03	8	3010	CP				
	1	- 11	03	8	2814	CP				
	1	11	03	8	2812	CP				
	1	11	03	8	2810	CP				
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				FUNCT	APPARATUS	
FS	PAGÉ	NODE	CONTAC	T DESIG	TYPE	OPT
1	12	77	4 1 1	DAA	<b>D</b> C 1	
1	12	77	DT		NET	
1	12	78	07	791A 7000		
4	10	70	20	3002		
4	12	70 79	10	P42	KEL	
4	40	70		P42A	NEI	
1	12	/ 9	25	3002	CP	
1	12	/9	10	P43	REL	
1	12	/9	PT	P43A	NET	
1	12	80	20	3002	CP	
1	12	80	10	P44	REL	
1	12	8U P4	Pľ	P44A	NET	
I	12	01	22	3002	CP	
1	12	81	10	P45	REL	
1	12	81	PT	P45A	NET	
- 1	12	82	24	3002	CP	
1	12	82	10	P46	REL	
1	12	82	PT	P46A	NET	
1	12	83	26	3002	CP	
1	12	83	10	P47	REL	
1	12	83	PT	P47A	NET	
1	12	84	13	3014	CP	
1	12	84	GRD			
1	12	85	13	3012	CP	
1	12	85	GRD			
1	12	86	13	3010	CP	
- 1	12	86	GRD			
1	12	87	14	3014	СР	
1	12	87	+24 A0	BATT		
1	12	88	14	3012	СР	
1	12	88	+24 A0	BATT		

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GA TYPE COLOR WIRTNG METHOD

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ini Sector						FUNCT	APPARATUS	
		FS	PAGE	NODE	CONTACT	DESIG	TYPE	OPT
		2	17	34	5 M	CPO	REL	
•		2	17	34	A	C1.0	CAP	
		2	17	35	8	C1.0	CAP	
i		2	17	35	GRD	<i>.</i>		
1 1 1 1		2	17	36	19	2613		
		2	17	36	19	2611		
]		2	17	36	19	2413		
		2	17	36	19	2411		
1 		2	17	36	5	2409		
1		2	17	36	12	2408		
		2	17	37	22	2613		
		2	17	37	22	2611		
		2	17	37	22	2413		
	سو	2	17	37	22	2411		
	45	2	17	37	2	2409		
		2	17	37	11	2408		
-		2	17	38	10	2413	CP	
		2	17	38	10	2411	CP	
		2	17	38	-48 AO E	BATT		
		2	17	39	0	2409	CP	
		2	17	39	4	2408	CP	
		2	17	39	8	2409	CP	
		2	17	40	6	2409	CP	
		2	17	40	6	2408	CP	
		2	17	40 4	23	2609	CP	
1	•	2	17	41	16	2609	CP	
		2	17	41	18	2609	CP	
		2	17	41	1	2408	CP	
		2	17	41	20	2409	CP	
		2	17	41	PT	R1	RES	
		<del>-</del> -						

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			FUNCT	APPARATUS	
FS	PAGE	NODE	CONTACT DESIG	TYPE	OPT
-2	18	55	+24 B2 BATT		
2	18	56	14 2427	CP	
2	18	56	+24 B2 BATT		
2	18	<b>5</b> 7	13 2625	CP	
2	18	57	GRD		
2	18	58	14 2625	CP	
2	18	58	+24 B2 BATT		
2	18	59	13 2425	CP N	24
2	18	59	GRD		
2	18	60	14 2425	CP	
, 2	18	60	+24 B2 BATT		
- 3	20	01	1L PS00	REL	
3	20	01	PT PS00A	NET	
3	20	01	1L PS01	REL	
3	20	01	PT PS01A	NET	
3	20	01	-48 AO BATT		
3	20	02	1L PS10	REL	
3	20	02	PT PS10A	NET	
3	20	02	1L PS11	REL	
3	20	02	PT PS11A	NET	
3	20	02	-48 BO BATT		
4	21	01	1M CPO	REL	
			PR WITH 0402102		
4	21	01	11 2406	CP	
4	21	01	7 2406	CP	
4	21	01	27 2405	CP	
4	21	01	27 2604	CP	
4	21	02	1F CPO	REL	
·			PR WITH 0402101		
4	21	02	GRD		

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FS   PAGE   NODE   CONTACT   DESIG   TYPE     4   21   38   4   2406   CP     4   21   38   PT   R6.0   RES     4   21   38   PT   R6.0   RES     4   21   39   +24   A2   BATT     9   +24   A2   BATT   PR   WITH   0402138     4   21   39   PT   F0   NET     4   21   39   8   F0   REL     4   21   39   8   F0   REL     4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4   21   38   4   2406   CP     4   21   38   PT   R6.0   RES     9   21   39   +24   A2   BATT     9   +21   39   +24   A2   BATT     9   PR   WITH   0402139      4   21   39   PT   FO   NET     4   21   39   PT   FO   REL     4   21   39   8   FO   REL     4   21   40   6   FO   REL     4   21   40   7   FO   REL     4   21   41   PT   FO   NET	0P
4   21   38   PT   R6.0   RES     9   PR   WITH   0402139   9     4   21   39   +24   A2   BATT     9   PR   WITH   0402138   9     4   21   39   PT   F0   NET     4   21   39   8   F0   REL     4   21   39   8   F0   REL     4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4   21   39   +24   A2   BATT     PR   WITH   0402138     4   21   39   PT   F0   NET     4   21   39   8   F0   REL     4   21   39   8   F0   REL     4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4   21   39   +24   A2   BATT     PR   WITH   0402138     4   21   39   PT   F0   NET     4   21   39   8   F0   REL     4   21   39   8   F0   REL     4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4   21   39   PT   F0   NET     4   21   39   8   F0   REL     4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4   21   39   PT   F0   NET     4   21   39   8   F0   REL     4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4   21   39   8   F0   REL     4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4   21   40   6   F0   REL     4   21   40   7   F0   REL     4   21   41   PT   F0   NET	
4 21 40 7 F0 REL   4 21 41 PT F0 NET	
4 21 41 PT FO NET	
4 21 41 PT PK 0 PCO	
4 21 41 4 FO PE	
4 21 42 17 2605 CD	
4 21 42 10 2605 CP	
4 21 42 16 2005 CP	
<b>4 21 43 2 2405 CP</b>	
<b>4</b> 21 43 26 2605 CP	
4 21 43 17 2005 CP	
4 21 43 1 2405 CP	
4 21 43 PT D400 0 D50	
VIA LO AND DO TZ	
4 21 44 0 0404 00	
4 21 44 PT 2400 UP	
4 21 45 7 R11 RES	
4 21 45 PT 2400 CP	
4 21 46 6 RIU RES	• .:.
4 21 46 5 2406 CP	•
4 21 47 0 2402 CP	
4 21 47 0 2406 CP	
4. 21 48 CA 2402 CP	
- 2406 CP	

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				FUNCT		APPARATU	IS
FS	PAGE	NODE	CONTACT	DESIG		TYPE	0
6	24	13	8F	T <b>P</b> 0		REL	
6	24	13	24M	<b>P5</b> 0		REL	
6	24	13	24M	P51		REL	
6	24	14	PT	R9		RES	
6	24	14	6F	TPO		REL	
6	24	15	PT	R1		RES	
6	24	15	3F	TPO		REL	
6	24	16	PT	R2		RES	
6	24	16	1F	TPO		REL	
6	24	17	1 M	TO		REL	
6	24	17	1 M	T1		REL	
2			PR WITH	0602426			
6	24	17	TO PREC	OR SUCC	FR	OR MS	
-	_		LEAD OG				
6	24	18	3 M	TO		REL	
6	24	18	3 M	T1		REL	
•.			PR WITH	0602427			
6	24	18	TO PREC	OR SUCC	FR	OR MS	
			LEAD G4				
6	24	19	5M	TO		REL	
6	24	19	5 M	T1		REL	
,			PR WITH	0602428			
6	24	19	TO PREC	OR SUCC	FR	OR MS	
			LEAD G3				
6	24	20	7 M	TO		REL	
. 6	24	20	7 M	T1		REL	
			PR WITH	0602429			
6	24	20	TO PREC	OR SUCC	FR	OR MS	
			LEAD G2				
-6	24	21	9 M	TO		REL	

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	";					S	D-1A107-	01	155 1	ALL LIST	PAGE 199	
	FS	PAGE	NODE	CONTACT	FUNCT DESIG	APPARATUS Type	OPT	G A	TYPE	COLOR	WIRTNG Method	
	10	36	32	3F	P22	REL		24	BU			
	10	36	32	02R	012	SW		24	BU			
	10	36	33	3F	P23	REL		24	RU			
	10	36	33	03R	012	SW		24	BU	۵.		
	10	36	34	3F	P24	REL		24	BU			1
	10	36	34	04R	012	SW		24	RU			
	10	36	35	3F	P25	REL	4.	24	BU	-		1
	10	36	35	05R	012	SW		24	BU			Â.
	10	36	36	3°F	P26	REL		24	BU		5. <b>.</b>	: بند
	10	36	36	06R	012	SW		24	BU			5 17
	10	36	37	3F	P27	REL		24	BU			in an
	10	36	37	07R	012	SW		24	BU			±. .≛.
	10	36	<b>38</b> (	3 M	P20	REL						
14	10	36	38	3 M	P21	REL						
9	10	36	-38	3 M	P22	REL						
	10	36	38	3 M	P23	REL						
	10	36	38	3 M	P24	REL						
	10	36	38	3 M	P25	REL						/
	10	36	38	3 M	P26	REL						
	10	36	38	3 M	P27	REL						
	10	36	38	17M	P42	REL						
	10	36	39	2M	P37	REL		24	BU			
	10	36	39	19R	011	SW *		24	BU			
	10	36	40	2M	P36	REL		24	BU			
	10	36	40	18R	011	SW		24	BU			
	10	36	41	2M	P35	REL		24	BU			
-	10	36	41	17R	011	SW		24	BU			
	10	36	42	2M	P34	REL		24	BU			
	10	36	42	16R	011	SW		24	BU	•:		٠.
	10	36	43	2M	P33	REL		24	BU			

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				FUNCT	APPARATUS	
FS	PAGE	NODE	CONTACT	DESIG	TYPE	OPT
11	60	14	TO TRK D Lead R16	IST CKT		
11	60	15	14F	201	SW	
11	60	15	TO TRK D	IST CKT		
11	60	16	15F	201	SW	
11	60	16	TO TRK D	IST CKT		
**	00	10	LEAD R17			
11	60	17	34R	201	SW	
11	60	17	22R	217	SW	
11	60	18	35R	201	SW	
11	60	18	23R	217	SW	
11	60	19	32R	201	SW	
11	60	19	22R	216	SW	
11	60	20	33R	201	SW	
11	60	20	23R	216	SW	
11	60	21	308	201	SW	
11	60	21	22R	215	SW	
11	60	22	31R	201	SW .	
11	60	22	23R	215	SW	
11	60	23	28R	201	SW	
41	60	23	228	214	SW	
4 1	60	24	208	201	SW	
4 4	60	24	23R	214	SW	
41	60	25	268	201	SW	
4 1	6 <b>0</b>	25	228	213	SW	
44	60 60	26	270	201	SH	
4 4	0 U ∡ ∩	26	2 / N 9 7 P	247	5 H 5 H	
<b>T T</b>		20		201		
11	00	C/ 07	248	201	SW SM	
11	<b>6</b> 0.	21	22K	212	JW	

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FS	PAGE	NODE	CONTACT	FUNCT DESIG	APPARATUS	0P
21	3	33	3F	PW1	REL	
20	ני ז	34	2 M	PW1	REL	
20	2	34	3M	PW1	REL	
~ 2U	3 7	34	-48 B1 E	BATT		
20	2	35	TO MISC	CKT		
20	7	75	-48 B2 E	BATT		
20	3 7	3 <i>3</i> 76	TO MISC	CKT		
20	37	J O T A	125	PW1	REL	
20	3	30	121	PW1	REL	
20	: <b>.</b>	37				
20	3	<b>))</b> /		CKT		
20	3	30	10 MISC		REL	
20	3	30	100		REI	
20	3	38	111			
20	3	39	+24 81	BAII	REI	
20	3	39	10M	PW1		
20	3	39	11M	PW1	NEL	
20	3	40	TO MISC	CKT	PCI	
20	3	40	<b>9</b> F	PW1	REL	
20	3	41	9 M	PW1	REL	
20	3	41	+24 B2	BATT		
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FIGURE 18

Output - NOTE LIST

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SD-1A107-01 ISSUE 1 NOTE LIST DEC 6, 1963

ELECTRONIC SWITCHING SYSTEMS NO 1 TRUNK SWITCHING CIRCUIT

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### NOTES

CIRCUIT NOTES.

103 NETWORK NO 1 CODE 185C 560 OHMS 0.25MF NETWORK NO 2 CODE 186D 270 OHMS 0.5MF

EQUIPMENT NOTES.

AND THIS MOUNTING SHALL BE ADJUSTED AS FOLLOWS TIGHTEN MOUNTING SCREWS TIGHT AGAINST PLATE AND BACK OFF FOUR #CLICKS#. 202 UNLESS OTHERWISE SPECIFIED ALL LEADS ARE IN #OPEN TROUGH#.

INFORMATION NOTES.

- 301 UNLESS OTHERWISE SPECIFIED RESISTANCE VALUES ARE IN OHMS. CAPACITANCE VALUES ARE IN MICROFARADS.
- 302 THE CIRCUIT DESIGN INFORMATION AVAILABLE FOR ISSUE 1 DOES NOT INCLUDE THE CIRCUIT DESCRIPTION(CD), EQUIPMENT MANUFACTURING TESTING REQUIREMENTS X-SPECIFICATION), SEQUENCE CHARTS AND CIRCUIT REQUIREMENTS TABLE (CRT).

CROSS CONNECTING INFORMATION AND NOTES.

402 WIRING! IS NOT AVAILABLE FOR ISSUE 1. THIS INFORMATION WILL BE AVAILABLE AS A J-SPECIFICATION.

END LIST

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NOTE LIST SD-1A107-01 ISS 1

PAGE 2

201 ALL (GR), (PS), AND (P) RELAYS SHALL BE MOUNTED WITH LP19A890 FLEXIBLE MOUNT

THE INTERCONNECTING INFORMATION TO THE JUNCTOR SWITCHING CIRCUIT (B-LINK

Output - APP FIG LIST

## FIGURE 19

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APP FIG LIST

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ELECTRONIC SWITCHING SYSTEMS NO 1 TRUNK SWITCHING CIRCUIT

PAGE

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ADD	APPARATUS	APPARATUS	FUNCT
EIG	TYPE	CODE	DESIG
riu		• •	
0001	CP	A32	2810
0001	CP	A32	2812
0001	CP	A32	2814
0001		A 3 2	2826
0001	CP	A32	2828
0001	CP	A32	2830
0001	CP	A32	3010
0001	CP	A32	3012
0001	CP	A32	3014
0001	CP	A32	3026
0001	CP	A32	3028
0001	CP	A32	3030
0001	CP	A32	3210
0001	CP	A32	3212
0001	CP	A32	3214
0001	CP	A32	3226
0001	CP	A32	3228
0001	CP	A32	3230
0001	CP	A29	2802
0001	CP	A29	2804
0001	CP	A29	2806
0001	CP	A29	2808
0001	CP	A29	2818
0001	CP	A29	2820
0001	CP	A29	2822
0001	CP	A29	2824
0001	CP	A29	3002
0001	CP	A29	3004
0001	CP	A29	3006
0001	CP	A29	3008

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APP FIG'LIST 2 PAGE SD-1A107-01 ISS 1

UPPER HALF FUNCT Desig

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APP	APPARATU	S APPARATUS	FUNCT
FIG	TYPE	CODE	DESIG
	,,, _		
0001	NET	186D	Z16.1
0001	NET	186D	Z17.1
0001	NET	186D	Z18.1
0001	NET	186D	Z19.1
0001	NET	186D	Z20.1
0001	NET	186D	Z21.1
0001	NET	186D	Z22.1
0001	NET	186D	Z23.1
0001	NET	186D	Z24.1
0001	NET	186D	Z25.1
0001	NET	186D	Z26.1
0001	NET	186D	Z27.1
0001	NET	186D	Z28.1
0001	NET	186D	Z29.1
0001	NET	186D	Z30.1
0001	NET	186D	Z31.1
0005	REL	303A	PC1.0
0005	REL	303A	PC1.1
0005	·REL	303G	ET0.0
0005	REL	303G	E10.1
0005	REL	303G	PC2.0
0005	REL	303G	PC2.1
0005	REL	303G	50.0
0005	REL	303G	50.1
0005	BIAS CO	RE 2604B	
0005	BIAS CO	RE 2604B	2103.1
0005	CAP	513C	
0005	CAP	5130	
0005	CAP	5130	
0005	CAP	513C	

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### APP FIG LIST PAGE SD-1A107-01 ISS 1



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APP	APPARATUS	APPARATUS	FUNCT	
FIG	TYPE	CODE	DESIG	
0005	RES	KS14603,L1A-316	R105.0	
0005	RES	KS14603,L1A-316	R105.1	
0005	RES	KS19152,L2-470	R106.0	
0005	RES	KS19152,L2-470	R106.1	
0005	RES	KS14603,L1D-562	R107.0	
0005	DES	KS14603,L1D-562	R107.1	
0005	DEC	KS14603,L38-301	R108.0	
0005	DEC	KS14603,L38-301	R108.1	
0002	DEC	KS19150.12-1000	R109.0	
	RES DEC	KS10150.12-1000	R109.1	
	RES	74A	SCR.0	
0005			SCR.1	
0005	THSIN	94A 70744		
0005	TRNSF	20/44		
0005	TRNSF	2074A	1100.1	
END L	IST			

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### PAGE APP FIG LIST 8 SD-1A107-01 ISS 1

# UPPER HALF FUNCT Desig

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# FIGURE 20

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ELECTRONIC SWITCHING SYSTEMS NO 1 TRUNK SWITCHING CIRCUIT

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				FUNCT	APPARATUS	
PAGE	FS	NODE	CONTACT	DESIG	TYPE	OPT
28	9	<b>N</b> 1	n9R	003	SW	
28	á	01	108	003	SW	
20	á	02	ngR	002	SW	
20	9	02	108	002	SW	
20	,	07		001	SW	
20	7	03	108	001	SW	
20	2	00	nop	000	SW	
20	7	04			SW	
20	<b>y</b>	05		<b>P</b> 50	REI	
28	<b>9</b>	05	4 1 <sup>-1</sup>	P10	REL	
20	9	05	••• 1*1 		REI	
28	9	07	4 M	FII P40	REI	
28	9	05	4 M	P12	REI	
28	9	リラ	4 M	P13		
28	9	05	4 M	P14 D15		\$
28	9	05	4 M	P15	NEL DEI	
28	9	05	4 M	P10		
28	9	05	4 M	P17	REL	
28	9	06	4F	P10	REL	
28	9	06	0 0 R	003	SW	
28	9	07	<b>4</b> F	P11	REL	
28	9	07	01R	003	SW	
28	9	80	<b>4</b> F	P12	REL	
28	9	08	02R	003	SW	
28	9	09	4F	P13	REL	
28	9	09	03R	003	SW	
28	ġ	10	4F	P14	REL	•
28	9	10	04R	003	SW	••
28	ģ	11	<b>4</b> F	P15	REL	
20	Ó	11	<b>15R</b>	003	SW	
20	7	++ 12	AF	P16	REL	
20	7	<b>+ C</b>		• • •		

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### PAGE PAGE LIST 2 ISS 1

WIRING Method \* GA TYPE COLOR

BN BN 24 24 24 24 24 24 BU BU BU 24 BU BU 24

BU 24 BU 24 BU 24 BU 24

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				FUNCT	APPARATUS	
PAGE	FS	NODE	CONTACT	DESIG	TYPE	0P'
28	9	62	1M	P15	REL	
28	9	62	05R	000	SW	
28	9	63	1 M	P16	REL	
28	9	63	06R	000	SW	
28	9	64	1M	P17	REL	
28	9	64	07R	000	SW	
28	9	65	8F	P30	REL	
28	9	65	19R	000	SW	
28	9	66	7 M	P30	REL	
28	9	66	18R	000	SW	
28	9	67	6F	P30	REL	
28	9	67	17R	000	SW	
28	9	68	5 M	P30	REL	
28	9	68	16R	000	SW	
28	9	69	4F	P30	REL	
28	9	69	15R	000	SW	
28	9	70	3 M	P30	REL	
28	9	70	14R	000	SW	
28	9	71	2F	P30	REL	
28	9	71	13R	000	SW	
28	9	72	1 M	P30	REL	
28	9	72	12R	000	SW	
37	10	01	09R	117	SW	
37	10	01	10R	117	SW	
37	10	02	09R	116	SW	
37	10	02	10R	116	SW	
37	10	03	09R	115	SW	
37	10	03	10 <b>R</b>	115	SW	
37	10	04	09R	114	SW	
37	10	04	10R	114	SW	

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GA	TYPE	COLOR	WIRING Method	d	::	
24	BU		-		**	
24 24	BN BN					
24	BU		A3	Ť I	ı	
24 24	BU				. *	
24	BU					
24	BU		X.			
24	8U	•:				
24	BU					1997) 1997)
24 24	8U 8U					
24	BU		<i>x</i> *			
24	BU					
24	8U					.**
24	BU					4.
24	80 80					
24	BU					э <b>х</b>
24	BU					

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			FUNCT	APPARATUS				
FS	NODE	CONTACT	DESIG	TYPE	OPT	GA	TYPE	COLOR
10	69	<b>5</b> F	P45	REL		24	BU	
10	69	05R	114	SW		24	BU	
10	70	5F	P46	REL		24	BU	э.
10	70	<b>N6</b> R	114	SW		24	BU	
10	71	5F	P47	REL		24	BU	
10	71	07R	114	SW		24	BU	۲.
10	72	5M	P40	REL				
10	72	5M	P41	REL				
10	72	5M	P42	REL				
10	72	- 5M	P43	REL				
10	72	5M	P44	REL				×
10	72	5M	P45	REL				
10	72	5M	P46	REL				
10	72	5 M	P47	REL		ý		
10	72	17M	P24	REL "				
	FS 10 10 10 10 10 10 10 10 10 10	FSNODE1069106910701070107110711072	FS   NODE   CONTACT     10   69   5F     10   69   05R     10   70   5F     10   70   06R     10   70   06R     10   71   5F     10   71   07R     10   72   5M     10   72   17M	FS   NODE   CONTACT   PUNCT     10   69   5F   P45     10   69   05R   114     10   70   5F   P46     10   70   06R   114     10   70   06R   114     10   71   5F   P47     10   71   07R   114     10   71   07R   114     10   72   5M   P40     10   72   5M   P41     10   72   5M   P43     10   72   5M   P444     10   72   5M   P45     10   72   5M   P45     10   72   5M   P46     10   72   5M   P46     10   72   5M   P47     10   72   5M   P47     10   72   5M   P47     10   72   5M   P47     10   72   5M   P47 <	FS   NODE   CONTACT   DESIG   APPARATOS     10   69   5F   P45   REL     10   69   05R   114   SW     10   70   5F   P46   REL     10   70   06R   114   SW     10   70   06R   114   SW     10   71   5F   P47   REL     10   71   07R   114   SW     10   71   07R   144   SW     10   72   5M   P40   REL     10   72   5M   P41   REL     10   72   5M   P43   REL     10   72   5M   P444   REL     10   72   5M   P45   REL     10   72   5M   P45   REL     10   72   5M   P46   REL     10   72   5M   P47   REL     10   72   5M   P47   REL     1	FS   NODE   CONTACT   DESIG   TYPE   OPT     10   69   5F   P45   REL   0   0     10   69   05R   114   SW   0   10     10   70   5F   P46   REL   0   10   70   06R   114   SW     10   70   06R   114   SW   10   71   5F   P47   REL     10   71   07R   114   SW   10   72   5M   P47   REL   10   72   5M   P40   REL   10   72   5M   P41   REL   10   72   5M   P43   REL   10   72   5M   P443   REL   10   72   5M   P444   REL   10   72   5M   P45   REL   10   72   5M   P45   REL   10   72   5M   P46   REL   10   72   5M   P46   REL   10   72   5M   P47   REL   10   72   5M   P	FS   NODE   CONTACT   DESIG   TYPE   OPT   GA     10   69   5F   P45   REL   24     10   69   05R   114   SW   24     10   70   5F   P46   REL   24     10   70   06R   114   SW   24     10   70   06R   114   SW   24     10   71   5F   P47   REL   24     10   71   07R   114   SW   24     10   71   07R   114   SW   24     10   72   5M   P47   REL   24     10   72   5M   P40   REL   10     10   72   5M   P443   REL   10     10   72   5M   P45   REL   10     10   72   5M   P46   REL   10     10   72   5M   P46   REL   10     10   72   5M	FS   NODE   CONTACT   DESIG   TYPE   OPT   GA   TYPE     10   69   5F   P45   REL   24   BU     10   69   05R   114   SW   24   BU     10   70   5F   P46   REL   24   BU     10   70   5F   P46   REL   24   BU     10   70   06R   114   SW   24   BU     10   70   06R   114   SW   24   BU     10   71   5F   P46   REL   24   BU     10   71   07R   114   SW   24   BU     10   71   07R   114   SW   24   BU     10   72   5M   P40   REL   10   24   BU     10   72   5M   P41   REL   10   10   10   10   10   10   10   10   10   10   10   10   10   10   10

END LIST

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WIRING	
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PAGE 13

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FIGURE 21

Output - NODE LIST

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ELECTRONIC SWITCHING SYSTEMS NO 1 TRUNK SWITCHING CIRCUIT

PAGE 1

# SD-1A107-01 ISSUE 1 NODE LIST

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				FUNCT	APPARATUS	
PAGE	NODE	FS	CONTACT	DESIG	TYPE	OPT
18	41	2	16	2625	CP	
18	41	2	18	2625	CP	
18	41	2	n	2424	CP	
18	41	2	20	2425	СР	
18	41	2	PT	R41	RES	
4 9	42	2	21	2625	CP	
10	42	2	27	2625	CP	
4 G T O	42	2	4	2424	CP	
10	42	2	⊥ 17	2625	CP	
10	47	2	10	2625	CP	
10	47	2	2	2424	CP	
4 Q	47	2	47	2425	CP	
10	47	2	<u>т</u>	RAD	RES	
	49	2	26	2625	CP	
10	40	2	20	2022	CP	
18	40	2	2	2029	CP	
18	40	۲	3	6464		
END	LISI					

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WIRTNG Method GA TYPE COLOR

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FIGURE 22

Output - FS LIST

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FS LIST

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ELECTRONIC SWITCHING SYSTEMS NO 1 TRUNK SWITCHING CIRCUIT

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PAGE

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		•		FUNCT	APPARATUS	
FS	PAGE	NODE	CONTACT	DESIG	TYPE	OP
4	21	01	1M	CPO	REL	
			PR WITH	0402102		
4	21	01	11	2406	CP	
4	21	01	7	2406	CP	
4	21	01	27	2405	CP	e
4	21	01	27	2604	CP	
4	21	02	1F	CPO	REL	
•			PR WITH	0402101		
4	21	02	GRD			
4	21	03	+24 A2 E	BATT		
·			PR WITH	0402104		
4	21	03	8	VCTO	REL	
4	21	03	PT	C2.0	CAP	
4	21	04	1	2605	CP	
4	21	04	3	2605	CP	
4	21	04	18	2405	CP	
•			PR WITH	0402103		
4	21	04	PT	R5.0	RES	
4	21	05	PT	R5.0	RES	
4	21	05	PT	C2.0	CAP	
4	21	05	4	VCTO	REL	
4	21	06	6	VCTO	REL	÷
4	21	06	7	VCTO	REL	
4	21	07	8	2605	CP	
4	21	07	2	2604	CP	
4	21	07	8	2604	CP	
4	21	07	21	2603	CP	
4	21	07	11	2405	CP	
4	21	08	4	2605	CP	
	24	08	24	2604	CP	
	C I					

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FS LIST PAGE SD-1A107-01 ISS 1 2

#### GA TYPE COLOR. PT

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				FUNCT		APPARATUS	
FS	PAGE	NODE	CONTACT	DESIG		TYPE	OPT
4	21	34	1	FO		REL	
4	21	35	3	FO		REL	
4	21	35	2	R9.0		RES	
4	21	36	2	R8.0		RES	
4	21	36	- 1	R9.0		RES	
4	21	37	1	R8.0		RES	
4	21	37	+24 A1 8	TAT			
4	21	38	21	2605		CP	
4	21	38	27	2605		CP	
4	21	38	20	2405		CP	
4	21	38	4	2406		CP	
4	21	38	PT	R6.0		RES	
	_		PR WITH	0402139			
4	21	39	+24 A2 E	BATT			
·			PR WITH	0402138			
4	21	39	PT	FO		NET	
4	21	39	8	FO		REL	
4	21	40	6	FO		REL	
4	21	40	7	FO		REL	
4	21	41	PT	FO		NET	
4	21	.41	PT	R6.0		RES	
4	21	41	4	FO		REL	
4	21	42	17	2605		CP	
4	21	42	10	2605		СР	
4	21	42	16	2405		CP	
4	21	43	2	2605		CP	
4	21	43	26	2605	•	CP	
4	21	43	17	2405		CP	
4	21	43	1	2406		CP	
4	21	43	PT	R109.0		RES	
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FS LIST PAGE SD-1A107-01 ISS 1 **ب** WIRING Method TYPE COLOR GA RED Red P . P P . N-., •:: - . •

					S	D-1A107	-01	ISS 1	FS LIS	T PAGE	15	т. Т.
FS	PAGE	NODE	CONTACT	FUNCT DESIG	APPARATUS Type	OPT	G▲	TYPE	COLOR	WIRING Method		
4	22	58	+24 82	BATT								≂ s Ę
4	22	59	14	2425	CP				RED			-
4	22	59	+24 82	BATT					RED			-
4	22	60	13	2422	CP			·	BK			10 - 10 - 10 - 10 - 10 - 10 - 10 - 10 -
4	22	60	GRD						BK			
4	22	61	14	2422	CP				RED			
4	22	61	+24 82 1	BATT					RED	ier:		
4	22	62	13	2420	CP				BK			
4	22	62	GRD						BK			
4	22	63	14	2420	CP	:			RED			
4	22	63	+24 82 8	BATT					RED	· · · ·		S.
4	22	64	13	2418	CP				BK			
4	22	64	GRD						BK			
4	22	07	14	2418	CP				RED			
4	22	07	+24 82 8	BATT	0.5				RED			
4	22	00 66	1	2418	CP CD							
	22	67		2020								<u>,</u> ,, Х
	22	67	14 14						RED			
20	22 7	01		5411				·	RED	1:		
20	3	01	4F	Pun					BK	er F		
20	3	02	6 M		NEL Rei				RK	•.	14	×
20	3	02	10	PO	REI				•			·
20	3	02	PT	PO	NET							
20	3	03	20	PO	REI					:		
20	3	03	PT	PO	NET							
20	3	03	1	R81	REL							8
20	3	04	2	R81	REL				RED			,
20	3	04	-48 A2 E	BATT					RED			ŕ
20	3	05	GRD						BK			<i>ж</i>
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				FUNCT	APPARATUS	
FS	PAGE	NODE	CONTACT	DESIG	TYPE	OPT
20	3	39	+24 B1 B	ATT		
20	3	39	10M	PW1	REL	
20	3	39	11M	PW1	REL	
20	3	40	TO MISC	CKT		
20	3	40	9F	PW1	REL	
20	3	41	9 M	PW1	REL	
20	3	41	+24 B2 B	ATT		
FND	IST					

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7-01	ISS 1	FS LIST	PAGE	19

GA TYPE COLOR METHOD

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FIGURE 23

Output - DUPLICATE FD

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THE FOLLOWING FUNCTIONAL DESIGNATIONS ARE DUPLICATED

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3212	CP
Z01.0	NET
CT0.1	REL
R1.1	RES
P32	REL
C104.1	CAP
017	SW
END LIST	

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# DUPLICATE FD

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PAGE

# DEC 6, 1963 SD-1A107-01 ISS 1

THE FOLLOWING FUNCTIONAL DESIGNATIONS ARE DUPLICATED NO DUPLICATES END LIST

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#### DUPLICATE FD " PAGE

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FIGURE 24

Structure of APPARATUS MASTER FILE

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In indicating the structure of a file it is necessary to define a hierarchy of information. This can be done as follows:

1. File - A major body of related data.

- Record Subdivision of file; contains data common to a subject or key.
- 3. Group Subdivision of record.

4. Field - Specific items of data within a group of records.

The file is the highest level of information. In showing the

structure of the file, the levels of information within the file
will be shown by using a system of indentation; the first indentation
indicating the record level, the second the group level, etc.

In addition to indicating the hierarchy of information, it is important to show the form that the input data is to assume. For

this reason, the data image for each field is also shown. The symbol x is used to indicate an alphanumeric field, A and 9 represent alphabétic and numeric fields respectively. The quantity of characters in the field is shown either by repeating the symbol or by suffixing it with the quantity in parenthesis. For example, xxx is equivalent to x(3) which is a representation of a three digit alphanumeric field.

The structure of the APP MSTR FILE follows:

# Name

APP MSTR FILE

# Record 1

Control-KeyA(2)Apparatus TypeA(10)Apparatus Code NumberX(20)Terminal (Repeated 16 times)X(3)

Data

Image

# Record 2

Control-Key A(2)

Terminal (Repeated 26 times) X(3)



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# 179

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## FIGURE 25

Sample Input - APPARATUS MASTER FILE

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	Number of Terminals On Apparatus <	Number of Input Data Cards EQ	Control-Key On First Card EQ	Control-Key On Second Card EQ	Control-Key On Third Card EQ	Control-Key On Fourth Card EQ	Control-Key On Fifth Card EQ	Control-Key On Output Record EQ
-	16	1	JA	-	-	_		JA
-	42	2	JB	JC	-	_	-	JB
	68	3	JD	JC	JE	-	-	JD
	94	4	JF	JC	JE	JG	-	JE
181	120	5	JH	JC	JE	JG	JI	JH

FIGURE 26

Use of Control-keys in APPARATUS MASTER FILE

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FIGURE 27

Structure of UNIT FILE

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# 67 <u>Name</u>

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UNIT FILE

Record NA

Control-Key

Specification Number

Unit Number

Apparatus Type

Apparatus Code

Functional Designation

Position

Quantity

Record NB Control-Key

.

Y(6)

Data

Image

"NA" 68

X(6)

X(4)

A(10)

X(20)

X(9)

X(5)

**9**9

**ن**و :

••

20

Specification Number	X(0)
Unit Number	X(4)
Sub Unit	X(10)
List OR Group (Repeated 10 Times)	
Quantity	99
List OR Group	X(3)

67. FIGURE 24 contains information concerning the indentation system and the data image symbols used.

68. When used as qualifiers Control-keys NA, NB and NC become ND, NE and NF respectively.





68. When used as qualifiers Control-keys NA, NB and NC become ND, NE and NF respectively.



FIGURE 28

Sample Input - UNIT FILE

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# 127 III

# FIGURE 29

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Structure of WIRE FILE

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69 Name

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WIRE FILE

Record AA

Control-Key SD Number Issue Title

Record EA Control-Key

Note Number

Note

Record DA

Control-Key

X(4) X(32)

1

Data

Image

"AA"<sup>70</sup>

T

X(9)

. 1

"EA",70 "EA",70 9(3) X(75)

"DA"<sup>70</sup>

"BA"<sup>70</sup>

Apparatus Figure	X(4)
Apparatus Type	A(10)
Apparatus Code Number	<b>X(</b> 20)
Functional Designation	X(9)
Upper Half Functional Designation	X(9)

Record BA

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Control-Key

69. FIGURE 24 contains information concerning the indentation system and the data image symbols used.

70. When used as qualifiers control-keys AA, BA, DA and EA become AQ, BQ, DQ and EQ respectively.

# Name

# Node Identification

5

	Functional Schematic Number			9(2)
	Page Number			9(3)
	Node Number	÷	₹ ₹	9(2)
Те	rminal			
	Number			X(6)
	Functional Designation			X(9)
	Apparatus Type			A(10)
Wi	ring		,	
	Option			X(4)
	Gauge			9(2)

Туре

X(3)

X(12)

Data

Image

Color	
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Wiring Condition

MethodX(4)StrapXLoopXPair-Triple-QuadX

Miscellaneous

# Miscellaneous

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X(18)

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	3		
		en e	
	Name (Cont'd.	Data Image	
•	Record CA		
	Control-Key	"CA" <sup>71</sup>	
4. -	Node Identification	1	
•	Functional Schematic Number	9(2)	٢
	Page Number	9(3)	
•	Node Number	9(2)	
	External Circuit		
	Ckt. Name	X (25)	
	Wiring		
	Option	X(4)	
	Gauge	9(2)	
	Туре	X(3)	

- 1

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Color X(12) Wiring Condition Method X(4) Strap X Loop X Pair-Triple-Quad X Miscellaneous Miscellaneous X(18)  $\overline{\mathbf{v}}$ 71. When used as a qualifier control-key CA becomes CQ. J 189



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