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A Central Limit Theorem for Products of Random Matrices and GOE Statistics for the Anderson Model on Long Boxes

Christian Sadel^{1,2}, Bálint Virág³

¹ Department of Mathematics, University of British Columbia, Vancouver, BC V6T 1Z2, Canada

² Institute of Science and Technology, 3400 Klosterneuburg, Austria.

E-mail: chrsadel@gmail.com

³ Department of Mathematics, University of Toronto, Toronto, ON M5S 2E4, Canada

Received: 5 November 2014 / Accepted: 13 January 2016 Published online: 6 April 2016 – © The Author(s) 2016. This article is published with open access at Springerlink.com

Abstract: We consider products of random matrices that are small, independent identically distributed perturbations of a fixed matrix \mathcal{T}_0 . Focusing on the eigenvalues of \mathcal{T}_0 of a particular size we obtain a limit to a SDE in a critical scaling. Previous results required \mathcal{T}_0 to be a (conjugated) unitary matrix so it could not have eigenvalues of different modulus. From the result we can also obtain a limit SDE for the Markov process given by the action of the random products on the flag manifold. Applying the result to random Schrödinger operators we can improve some results by Valko and Virag showing GOE statistics for the rescaled eigenvalue process of a sequence of Anderson models on long boxes. In particular, we solve a problem posed in their work.

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The work of C. Sadel was supported by NSERC Discovery Grant 92997-2010 RGPIN and by the People Programme (Marie Curie Actions) of the EU 7th Framework Programme FP7/2007-2013, REA Grant 291734.

1. Introduction and Results

The goal of this paper is to study scaling limits of random matrix products

$$T_{\lambda,n}T_{\lambda,n-1}\cdots T_{\lambda,1}$$

with $\lambda \to 0$ where the $\mathcal{T}_{\lambda,n}$ are perturbations of a fixed $d \times d$ matrix of the form

$$\mathcal{T}_{\lambda,n} = \mathcal{T}_0 + \lambda \mathcal{V}_{\lambda,n} + \lambda^2 \mathcal{W}_{\lambda}. \tag{1.1}$$

Here, for every λ , $V_{\lambda,n}$ is a family of independent, identically distributed random matrices with $\mathbb{E}(V_{\lambda,n}) = \mathbf{0}$ and W_{λ} is a deterministic matrix, both of order one. In the simplest case, d = 1, $\mathcal{T}_0 = 1$, $W_{\lambda} = 0$, and $V_{\lambda,n} = V_n$ are independent centered random variables with variance one. Then, the classical Donsker's central limit theorem applied to the logarithm of (1) shows that the product (for here denoted $\mathcal{X}_{\lambda,n} = \mathcal{T}_{\lambda,n}\mathcal{T}_{\lambda,n-1}\cdots\mathcal{T}_{\lambda,1}$) satisfies

$$(\mathcal{X}_{\lambda;t/\lambda^2}, t \ge 0) \implies (e^{B(t)-t/2}, t \ge 0)$$

as $\lambda \to 0$, where B(t) is a standard Brownian motion. Compared to the simplest case, the general case has extra interesting features.

- The matrix T_0 can have eigenvalues of different absolute values, so the product can grow exponentially at different rates in different directions.
- The matrix T_0 can have complex eigenvalues of the same absolute value that act as rotations; this can produce an averaging effect for the added drift and noise terms.

The main question that we resolve in this paper is the following.

Question. If the matrix T_0 has an eigenvalue of large absolute value, can one still understand the fine evolution of the product in the directions belonging to smaller eigenvalues?

Matrix products of this kind are used in the study of quasi-1-dimensional random Schrödinger operators, and the large eigenvalues are related to so-called hyperbolic channels. Indeed, the main motivating example is this case, which we will introduce in Sect. 1.2. When \mathcal{T}_0 is (the multiple of) a unitary matrix this type of result has been established in that context, [BBR, SS2, VV1, VV2] and the limiting process is described by a stochastic differential equation (SDE). In [KVV, VV1] the SDE limit was used to study the limiting eigenvalue statistics of such random Schrödinger operators in a critical scaling $\lambda^2 n = t$ (at band edges one has a different scaling as mentioned in Appendix A). We can extend this result and obtain a limit for the rescaled eigenvalue process in the presence of hyperbolic channels as well (cf. Theorem 5.4). In particular, we solve Problem 3 raised in [VV1] and obtain limiting GOE statistics for the Anderson model on sequences of long boxes (cf. Theorem 1.2) with appropriate scalings. We essentially reduce the proof to a situation where it is left to analyze the same family of SDEs as in [VV1]. Deriving the GOE statistics then relies on the work of Erdös, Schlein, Yau and Yin [ESYY, EYY], but we do not repeat these steps that are done in [VV1]. The main result is stated in Sect. 1.2, further details are given in Sect. 5.

In the considered scaling limit $\lambda^2 n = t$ in Theorem 5.4 localization effects and Poisson statistics are not seen and the description through an SDE arises. We obtain that the hyperbolic channels only shift the eigenvalues but do not affect the local statistics. In fact, fixing the width and base energy, the local eigenvalue statistics only depends on the number of so called elliptic channels. This can be seen as some universality statement. Increasing the number of elliptic channels and choosing appropriate sequences of models, the GOE statistics arises.

As a byproduct of this work we solve some conjecture from [Sa1] showing that there is an SDE limit for the reduced transfer matrices in the presence of hyperbolic channels (cf. Remark 5.1).

Random matrix ensembles such as the Gaussian Orthogonal Ensemble (GOE) were introduced by Wigner [Wi] to model the observed repulsion between eigenvalues in large nuclei. The local statistics is given by the Sine₁ kernel, see e.g. [Me]. This type of repulsion statistics is expected for many randomly disordered systems of the same symmetry class (time reversal symmetry) that have delocalized eigenfunctions. This is referred to as *universality*. Most models with rigorously proved universal bulk behavior are themselves ensembles of random matrices, e.g. [DG,ESY,Joh,TV]. Recently, Shcherbina proved universal GUE statistics (Gaussian Unitary Ensemble) for random block band matrix ensembles that in some sense interpolate between the classical matrix ensembles and Anderson models [Shc].

The Anderson model was introduced by P. W. Anderson to describe disordered media like randomly doped semi-conductors [And]. It is given by the Laplacian and a random independent identically distributed potential and has significantly less randomness than the matrix ensemble models. For large disorder and at the edge of the spectrum, the Anderson model in \mathbb{Z}^d or \mathbb{R}^d localizes [FS, DLS, SW, CKM, AM, Aiz, Klo] and has Poisson statistics [Mi, Wa, GK]. For small disorder in the bulk of the spectrum, localization and Poisson statistics appear in one and quasi-one dimensional systems [GMP, KuS, CKM, Lac, KLS] (except if prevented by a symmetry [SS3]) and is expected (but not proved) in 2 dimensions. Delocalization for the Anderson model was first rigorously proved on regular trees (Bethe lattices) [K] and had been extended to several infinite-dimensional treelike graphs [KI,ASW,FHS,AW,KLW,FHH,KS,Sa2,Sa3,Sha]. Recently it was shown that there is a transition from localization to delocalization on normalized antitrees at exactly 2-dimensional growth rate [Sa4]. For 3 and higher dimensions one expects delocalized eigenfunctions (absolutely continuous spectrum) for small disorder and the eigenvalue statistics of large boxes should approximate GOE by universality. However, proving any of these statements in \mathbb{Z}^d or \mathbb{R}^d for d > 3 remains a great mathematical challenge.

The papers [BBR, VV1, VV2] are restricted to the subset of the important cases where all eigenvalues of T_0 had the same absolute value (and no Jordan blocks). The novelty of this work is to handle eigenvalues of different absolute value for T_0 ; the application to Schrödinger operators comes from applying Theorem 1.1 to the transfer matrices.

Let us briefly explain why this is not a trivial extension. If \mathcal{T}_0 (or $A\mathcal{T}_0A^{-1}$ for some matrix A) is unitary one simply has to remove the free evolution from the random products. To illustrate this, let for now $\mathcal{X}_{\lambda,n} = \mathcal{T}_{\lambda,n}\mathcal{T}_{\lambda,n-1}\cdots\mathcal{T}_{\lambda,1}$. Then, $\mathcal{T}_0^{-n}\mathcal{X}_{\lambda,n} = (\mathbf{1}+\lambda\mathcal{T}_0^{-n}\mathcal{V}_{\lambda,n}\mathcal{T}_0^{(n-1)}+\lambda^2\mathcal{T}_0^{-n}\mathcal{W}_{\lambda}\mathcal{T}_0^{(n-1)})(\mathcal{T}_0^{-(n-1)}\mathcal{X}_{\lambda,n-1})$. The conjugations like \mathcal{T}_0^{-n} $(\mathcal{V}_{\lambda,n}\mathcal{T}_0^{-1})\mathcal{T}_0^n$ simply lead to an averaging effect over the compact group generated by the unitary \mathcal{T}_0 in the limit for the drift and diffusion terms. Adopting techniques by Strook and Varadhan [SV] and Ethier and Kurtz [EK] to this situation (cf. Proposition 23 in [VV2]) one directly obtains an SDE limit for $\mathcal{T}_0^{-n}\mathcal{X}_{\lambda,n}$ in the scaling $\lambda^2 n = t$. If \mathcal{T}_0 has eigenvalues of different sizes then generically some entries of $\mathcal{T}_0^{-n}\mathcal{W}_{\lambda}\mathcal{T}_0^{n-1}$ and the variance of some entries of $\mathcal{T}_0^n\mathcal{V}_{\lambda,n}\mathcal{T}_0^{n-1}$ will grow exponentially in *n*. This destroys any hope of a limiting process. Instead one may then consider a process $U^{-n}\mathcal{X}_{\lambda,n}$ where *U* is a unitary just counteracting the fast rotations. But then one still has different directions growing at different exponential rates even for the free evolution, and simply projecting to some subspace, $PU^{-n}\mathcal{T}_0^{-n}\mathcal{X}_{\lambda,n}$, does not work either!

The trick lies in finding a projection that cuts off the exponential growth of the free evolution **and** does not screw up the convergence of the random evolution to some drift and diffusion terms. The correct way to handle the exponential growing directions is choosing a Schur complement. The exponentially decreasing directions will tend to zero and not matter, and the directions of size 1 will lead to a limit. The exponential growing directions have some non-trivial effect and lead to an additional drift term. As the Schur complement itself is not a Markov process, it will be better to consider it as part of a quotient of $\mathcal{X}_{\lambda,n}$ modulo a certain subgroup of $GL(d, \mathbb{C})$. Then one still needs several estimates to handle the appearing inverses in the Schur complement and the error terms before one can apply Proposition 2.1 which is some modification of Proposition 23 in [VV2].

In the Appendix we will state some further general corollaries or applications of Theorem 1.1. Although we cannot take an SDE limit of the entire matrix as indicated above, it will be possible to describe the limit of its action on Grassmannians and flag manifolds (cf. Appendix A). For this limit the correlations for SDE limits corresponding to different sizes of eigenvalues of \mathcal{T}_0 are important. The limit processes live in certain submanifolds that are stable under the free, non-random dynamics of \mathcal{T}_0 . This result is related to the numerical calculations in [RS], where the authors considered the action of the transfer matrices on the so called Lagrangian Planes, or Lagrangian Grassmannians (which is some invariant subspace of a Grassmannian). The limiting submanifold corresponds to the 'freezing' of some phases related to the hyperbolic channels. In the scaling limit, only a motion of the part corresponding to the so called elliptic channels can be seen and it is described by a SDE.

In Appendix B we also study the case of non-diagonalizable Jordan blocks. These can be dealt with by a λ -dependent basis change, which leads to a different critical scaling. In the Schrödinger case, such Jordan blocks appear at band-edges and we give an example for a Jordan block of size 2*d* for general *d*.

1.1. General SDE limits. Without loss of generality we focus on the eigenvalues with absolute value 1 and assume that T_0 has no Jordan blocks for eigenvalues of size 1. Next, we conjugate the matrices $T_{\lambda,n}$ to get T_0 in Jordan form. We may write it as a block diagonal matrix of dimension $d_0 + d_1 + d_2$ of the form

$$\mathcal{T}_0 = \begin{pmatrix} \Gamma_0 & & \\ & U & \\ & & \Gamma_2^{-1} \end{pmatrix}$$
(1.2)

where U is a unitary, and Γ_0 and Γ_2 have spectral radius smaller than 1. The block Γ_0 corresponds to the exponential decaying directions and the block Γ_2^{-1} to the exponential growing directions of \mathcal{T}_0 .

The only way the matrix product $\mathcal{T}_{\lambda,n} \cdots \mathcal{T}_{\lambda,1}$ can have a continuous limiting evolution is if we compensate for the macroscopic rotations given by U (as in [BBR, VV1, VV2]). Hence define

$$\mathcal{X}_{\lambda,n} := \mathcal{R}^{-n} \mathcal{T}_{\lambda,n} \mathcal{T}_{\lambda,n-1} \cdots \mathcal{T}_{\lambda,1} \mathcal{X}_0 \quad \text{where} \quad \mathcal{R} = \begin{pmatrix} \mathbf{1}_{d_0} \\ U \\ \mathbf{1}_{d_2} \end{pmatrix}$$
(1.3)

where \mathcal{X}_0 is some initial condition and $\mathbf{1}_d$ is the identity matrix of dimension d.

In most of the following calculations we will use a subdivision in blocks of size $d_0 + d_1$ and d_2 . Let us define the Schur complement $X_{\lambda,n}$ of size $(d_0 + d_1) \times (d_0 + d_1)$ by

$$X_{\lambda,n} = A_{\lambda,n} - B_{\lambda,n} D_{\lambda,n}^{-1} C_{\lambda,n}, \quad \text{where} \quad \mathcal{X}_{\lambda,n} = \begin{pmatrix} A_{\lambda,n} & B_{\lambda,n} \\ C_{\lambda,n} & D_{\lambda,n} \end{pmatrix}.$$
(1.4)

If $\mathcal{X}_{\lambda,n}$ and $D_{\lambda,n}$ are both invertible, then

$$X_{\lambda,n} = (\mathcal{P}^* \mathcal{X}_{\lambda,n}^{-1} \mathcal{P})^{-1}$$
(1.5)

where \mathcal{P} is the projection to the first $d_0 + d_1$ coordinates. Note that invertibility of $D_{\lambda,n}$ is required to define $X_{\lambda,n}$. Therefore, we demand the starting value D_0 to be invertible, where

$$\mathcal{X}_0 = \begin{pmatrix} A_0 & B_0 \\ C_0 & D_0 \end{pmatrix}$$
, and we define $X_0 = A_0 - B_0 D_0^{-1} C_0$.

The first important observation, explained in Sect. 3, is that the pair

$$(X_{\lambda,n}, Z_{\lambda,n})$$
 where $Z_{\lambda,n} = B_{\lambda,n} D_{\lambda,n}^{-1}$ (1.6)

is a Markov process. Therefore, it will be more convenient to study this pair.

We need the following assumptions.

Assumption. We assume that for some constants $\epsilon > 0$, $\lambda_0 > 0$ one has

$$\sup_{0<\lambda<\lambda_0} \mathbb{E}(\|\mathcal{V}_{\lambda,n}\|^{6+\epsilon}) < \infty.$$
(1.7)

Furthermore we assume that the limits of first and second moments

$$\lim_{\lambda \to 0} \mathcal{W}_{\lambda}, \quad \lim_{\lambda \to 0} \mathbb{E}((\mathcal{V}_{\lambda,n})_{i,j}(\mathcal{V}_{\lambda,n})_{k,l}), \quad \lim_{\lambda \to 0} \mathbb{E}((\mathcal{V}^*_{\lambda,n})_{i,j}(\mathcal{V}_{\lambda,n})_{l,k}) \quad \text{exist.}$$
(1.8)

In order to state the main theorem, we need to subdivide $\mathcal{V}_{\lambda,n}$, \mathcal{W}_{λ} in blocks of sizes d_0 , d_1 , d_2 . We denote the $d_j \times d_k$ blocks by

$$V_{\lambda,jk}$$
, and $W_{\lambda,jk}$ respectively. (1.9)

The covariances of the $d_1 \times d_1$ block $V_{\lambda,11}$ will be important. A useful way to encode covariances of centered matrix-valued random variables A and B is to consider the matrix-valued linear functions $M \mapsto \mathbb{E}(A^{\top}MB)$ and $M \mapsto \mathbb{E}(A^*MB)$. Choosing matrices M with one entry 1 and all other entries zero one can read off $\mathbb{E}(A_{ij}B_{kl})$ and $\mathbb{E}(\overline{A}_{ij}B_{kl})$ directly. Let us therefore define

$$h(M) := \lim_{\lambda \to 0} \mathbb{E}(V_{\lambda,11}^{\top} M V_{\lambda,11}), \quad \widehat{h}(M) := \lim_{\lambda \to 0} \mathbb{E}(V_{\lambda,11}^* M V_{\lambda,11}).$$
(1.10)

Furthermore the lowest order drift term of the limit will come from the lowest order Schur-complement and hence contain some influence from the exponentially growing directions. Therefore, let

$$W := \lim_{\lambda \to 0} W_{\lambda,11} - \mathbb{E}(V_{\lambda,12}\Gamma_2 V_{\lambda,21}).$$
(1.11)

By the assumption (1.8) above these limits exist.

Theorem 1.1. Let the assumptions (1.7) and (1.8) stand. Then, for t > 0 we have convergence in law, $Z_{\frac{1}{\sqrt{n}},\lfloor tn \rfloor} \implies 0$ and

$$X_{\frac{1}{\sqrt{n}},\lfloor tn \rfloor} \implies X_t = \begin{pmatrix} \mathbf{0}_{d_0} & \\ & \Lambda_t \end{pmatrix} X_0 \quad for \quad n \to \infty.$$

 Λ_t is a $d_1 \times d_1$ matrix valued process and the solution of

$$d\Lambda_t = V\Lambda_t \, dt + d\mathcal{B}_t \, \Lambda_t \,, \quad \Lambda_0 = \mathbf{1}.$$

 \mathcal{B}_t is a complex matrix Brownian motion (i.e. \mathcal{B}_t is Gaussian) with covariances

$$\mathbb{E}(\mathcal{B}_t^\top M \mathcal{B}_t) = g(M)t, \quad \mathbb{E}(\mathcal{B}_t^* M \mathcal{B}_t) = \widehat{g}(M)t$$
(1.12)

where

$$V = \int_{\langle U \rangle} u W U^* u^* \, du \tag{1.13}$$

$$g(M) = \int_{\langle U \rangle} \overline{u} \,\overline{U} \,h(u^{\top} M u) \,U^* u^* \,du \tag{1.14}$$

$$\widehat{g}(M) = \int_{\langle U \rangle} u U \,\widehat{h}(u^* M u) \, U^* u^* \, du. \tag{1.15}$$

Here, $\langle U \rangle$ denotes the compact Abelian group generated by the unitary U, i.e. the closure of the set of all powers of U, and du denotes the Haar measure on $\langle U \rangle$.

- *Remark.* (i) The analogous theorem in the situation $d_2 = 0$ (no exponential growing directions) holds. In this case the matrices $B_{\lambda,n}$, $C_{\lambda,n}$ and $D_{\lambda,n}$ do not exist and one simply has $X_{\lambda,n} = A_{\lambda,n} = \mathcal{X}_{\lambda,n}$. For this case one can actually simplify some of the estimates done for the proof, as one does not need to work with the process $B_{\lambda,n}D_{\lambda,n}^{-1}$ and no inverse is required.
- (ii) In the case where $d_0 = 0$, i.e. no exponential decaying directions, the Theorem also works fine. In this case one simply has $X_t = \Lambda_t X_{11}$.
- (iii) The Theorem does not hold for t = 0 and indeed it looks contradictory for small t. However, the exponentially decaying directions go to zero exponentially fast so that one obtains

$$X_{\frac{1}{\sqrt{n}},\lfloor n^{\alpha}\rfloor} \Longrightarrow \begin{pmatrix} \mathbf{0} \\ \mathbf{1}_{d_1} \end{pmatrix} X_0$$

for sufficiently small α which gives the initial conditions for the limiting process.

(iv) When defining the process $\mathcal{X}_{\lambda,n}$ one may want to subtract some of the oscillating terms in the growing and decaying directions as well, i.e. one may want to replace \mathcal{R} in (1.3) by a unitary of the form $\hat{\mathcal{R}} = \begin{pmatrix} U_0 \\ U_2 \end{pmatrix}$ written in blocks of sizes d_0, d_1, d_2 , respectively. Then let

$$\hat{\mathcal{X}}_{\lambda,n} = \hat{\mathcal{R}}^{-n} \mathcal{R}^n \mathcal{X}_{\lambda,n} = \begin{pmatrix} \hat{A}_{\lambda,n} & \hat{B}_{\lambda,n} \\ \hat{C}_{\lambda,n} & \hat{D}_{\lambda,n} \end{pmatrix}$$

and define the corresponding Schur complement $\hat{X}_{\lambda,n} = \hat{A}_{\lambda,n} - \hat{B}_{\lambda,n} \hat{D}_{\lambda,n}^{-1} \hat{C}_{\lambda,n}$ as well has $\hat{Z}_{\lambda,n} = \hat{B}_{\lambda,n} \hat{D}_{\lambda,n}^{-1}$. Simple algebra shows that

$$\hat{X}_{\lambda,n} = \begin{pmatrix} U_0^{-n} \\ \mathbf{1} \end{pmatrix} X_{\lambda,n}, \quad \hat{Z}_{\lambda,n} = \begin{pmatrix} U_0^{-n} \\ \mathbf{1} \end{pmatrix} Z_{\lambda,n} U_2^n.$$

Hence, it is easy to see that for $n \to \infty$,

$$\hat{Z}_{\frac{1}{\sqrt{n}},\lfloor nt \rfloor} \Rightarrow 0, \quad \hat{X}_{\frac{1}{\sqrt{n}},\lfloor nt \rfloor} \Rightarrow X_t$$

where X_t is the exact same process as in Theorem 1.1.

- (v) When T₀ has eigenvalues of absolute value *c* different from 1, and T₀ is diagonalized (or in Jordan form) so that the corresponding eigenspace are also the span of coordinate vectors and have no Jordan blocks, then we can apply Theorem 1.1 to the products of T_{λ,n}/*c*. Moreover, considering products of direct sums T_{λ,n}/*c*⊕T_{λ,n}/*c*' the application of Theorem 1.1 gives correlations of these SDEs, cf. Theorem A.1.
- (vi) The stated SDE limit can be seen as limiting processes of equivalence classes of $\mathcal{R}^{-n} \mathcal{X}_{\lambda,n}$ modulo a certain group \mathbb{G} . This means the following: For a specific subgroup $\mathbb{G} \subset \operatorname{GL}(d, \mathbb{C})$ we define two matrices to be equivalent, $M \sim M'$, if and only if M = M'G for some $G \in \mathbb{G}$. This equivalence relation defines the quotient $\operatorname{Mat}(d, \mathbb{C})/\mathbb{G}$. One may ask for which subgroups \mathbb{G} of $\operatorname{GL}(d, \mathbb{C})$ one has some normalization $\widetilde{\mathcal{R}}$ such that the process $\widetilde{\mathcal{R}}^{-n} \mathcal{T}_{1/\sqrt{n},n} \cdots \mathcal{T}_{1/\sqrt{n},1} \mathcal{X}_0 / \mathbb{G}$ has a distributional limit. As we will show in Appendix A, for invertible and diagonalizable \mathcal{T}_0 we get such a limit on the so-called flag manifold (cf. Theorem A.2) and whenever \mathbb{G} is algebraic and cocompact (cf. Corollary A.3).
- (vii) Finally, one might pose the question whether one can also obtain some similar result in the presence of Jordan blocks. In fact, combining this work with the techniques of [SS1], one can obtain a limit for a process obtained with a λ -dependent basis change. In terms of Schrödinger operators these situations occur on band-edges, cf. Appendix B.

The proof is structured in the following way. Section 2 states an abstract theorem for convergence of Markov processes to SDE limits that we will use. In Sect. 3 we will develop the evolution equations for the process $(X_{\lambda,n}, Z_{\lambda,n})$, together with some crucial estimates. In Sect. 4 we will then obtain the limiting stochastic differential equations as in Theorem 1.1. The reader interested in the proofs can continue with Sect. 2.

Applications to random Schrödinger operators are given in the following subsection and in Sect. 5, which also contains the proofs.

1.2. The GOE limit for random Schrödinger operators. Let $\mathbb{Z}_{n,d}$ be the adjacency matrix of the $n \times d$ grid (embedded in \mathbb{Z}^2), and let *V* be a diagonal matrix with i.i.d. random entries of the same dimension. A fundamental question in the theory of random Schrödinger operators is how the eigenvalues of

$$\mathbb{Z}_{n,d} + \lambda V \tag{1.16}$$

are distributed. Predictions from the physics literature suggest that in certain scaling regimes that correspond to the delocalized regime, random matrix behavior should appear. More precisely, the random set of eigenvalues in a window centered at some energy

E and scaled properly should converge to the Sine₁ point process. The latter process is the large-*n* limit of the random set of eigenvalues of the $n \times n$ Gaussian orthogonal ensemble near 0.

A version of such predictions was proved rigorously [VV1] for subsequences of $n_i \gg d_i \rightarrow \infty$, $\lambda_i^2 n_i \rightarrow 0$ but only near energies E_i tending to zero. In a modified model where the edges in the *d* direction get weight r < 1 the proof of [VV1] works for almost all energies in the range (-2 + 2r, 2 - 2r). Proving such claims for almost all energies of the original model (1.16) presented a challenge, the main motivation for the present paper. For a better comparison with [VV1] let us re-introduce the weight *r*. It is natural to think of operators like (1.16) as acting on a sequence $\psi = (\psi_1, \ldots, \psi_n)$ of *d*-vectors. So given the weight *r*, let us define the $nd \times nd$ matrix $H_{\lambda,n,d}$ by

$$(H_{\lambda,n,d}\psi)_k = \psi_{k+1} + \psi_{k-1} + (r\mathbb{Z}_d + \lambda V_k)\psi_k$$
(1.17)

with the notational convention that $\psi_0 = \psi_{n+1} = 0$. Here, \mathbb{Z}_d is the adjacency matrix of the connected graph of a path with *d* vertices and the V_k are i.i.d. real diagonal matrices, i.e.,

$$\mathbb{Z}_d = \begin{pmatrix} \mathbf{0} & \mathbf{1} & & \\ \mathbf{1} & \ddots & \ddots & \\ & \ddots & \ddots & \mathbf{1} \\ & & \mathbf{1} & \mathbf{0} \end{pmatrix}, \quad V_1 = \begin{pmatrix} v_1 & & \\ & \ddots & \\ & & v_d \end{pmatrix}$$
(1.18)

with

$$\mathbb{E}(v_j) = 0, \quad \mathbb{E}(|v_j|^{6+\varepsilon}) < \infty, \quad \mathbb{E}(v_i v_j) = \delta_{ij}.$$
(1.19)

Then we obtain the following:

Theorem 1.2. For any fixed r > 0 and almost every energy $E \in (-2 - 2r, 2 + 2r)$ there exist sequences $n_k \gg d_k \rightarrow \infty$, $\sigma_k^2 := \lambda_k^2 n_k \rightarrow 0$, and normalizing factors $\nu_k \sim d_k n_k / \sigma_k$ such that the process of eigenvalues of

$$\nu_k \left(H_{\lambda_k, n_k, d_k} - E \right)$$

converges to the Sine₁ process. In particular the level statistics corresponds to GOE statistics in this limit.

Theorem 1.2 resolves Problem 3 posed in [VV1]. There one has r < 1 and $E \in (-2 + 2r, 2 - 2r)$ or r = 1 and a sequence of energies converging to 0. (Note that this interval is smaller than the one in Theorem 1.2 and in fact empty for $r \ge 1$). Theorem 1.2 applies to the exact Anderson model r = 1 with any fixed energy in the interior (-4, 4) of the spectrum of the discrete two-dimensional Laplacian. It also applies in the case r > 1. This is because hyperbolic channels can now be handled for the SDE limit. The exact definition of 'elliptic' and 'hyperbolic' channels will be given in Sect. 5. Overcoming this difficulty was the main motivation for this work.

Essentially, only the elliptic channels play a role in the eigenvalue process limit. It is thus important to have a sequence with a growing number of elliptic channels going to infinity. Indeed, one can obtain GOE statistics even for a sequence of energies E_k approaching the edge of the spectrum |E| = 2+2r. For this, one needs that the sequence d_k grows fast enough, such that the number of elliptic channels at energy E_k grows.

Further details will be given in Sect. 5 where we will also consider an SDE description for the eigenvalue processes of operators on strips with a fixed width in the critical scaling. The operators considered are slightly more general than (1.17). In fact, many techniques

can be applied to $n \times d_1 \times \cdots \times d_m$ grids embedded in \mathbb{Z}^{m+1} . However, for the last step to obtain the GOE limit, it is so far crucial that the operators $H_{\lambda,n,d}$ are random operators on a grid embedded in \mathbb{Z}^2 , see also Remark 5.6.

2. A Limit Theorem for Markov Processes

The key idea is to use a variation of Proposition 23 in [VV2] to obtain the convergence to the limiting process.

Proposition 2.1. *Fix* T > 0, *and for each* $m \ge 1$ *consider a Markov chain*

$$(X_n^m \in \mathbb{R}^d, n = 1 \dots \lfloor mT \rfloor).$$

as well as a sequence of "good" subsets G_m of \mathbb{R}^d . Let $Y_n^m(x)$ be distributed as the increment $X_{\ell+1}^m - x$ given $X_n^m = x \in G_m$. We define

$$b^{m}(t,x) = m\mathbb{E}[Y^{m}_{\lfloor mt \rfloor}(x)], \quad a^{m}(t,x) = m\mathbb{E}[Y^{m}_{\lfloor mt \rfloor}(x)Y^{m}_{\lfloor mt \rfloor}(x)^{\mathrm{T}}].$$

Let $d' \leq d$, and let \tilde{x} denote the first d' coordinates of x. These are the coordinates that will be relevant in the limit. Also let \tilde{b}^m denote the first d' coordinates of b^m and \tilde{a}^m be the upper left $d' \times d'$ sub-matrix of a^m .

Furthermore, let f be a function $f : \mathbb{Z}_+ \to \mathbb{Z}_+$ with f(m) = o(m), i.e $\lim_{m\to\infty} f(m)/m = 0$. Suppose that as $m \to \infty$ for $x, y \in G_n$ we have

$$|\tilde{a}^{m}(t,x) - \tilde{a}^{m}(t,y)| + |\tilde{b}^{m}(t,x) - \tilde{b}^{m}(t,y)| \le c|\tilde{x} - \tilde{y}| + o(1)$$
(2.1)

$$\sup_{x \in G_m, n} \mathbb{E}[|\tilde{Y}_n^m(x)|^3] \le cm^{\frac{-3}{2}} \quad for \ all \quad n \ge f(m),$$

$$(2.2)$$

and that there are functions a, b from $\mathbb{R} \times [0, T]$ to $\mathbb{R}^{d^2}, \mathbb{R}^{d'}$ respectively with bounded first and second derivatives so that uniformly for $x \in G_m$,

$$\sup_{x \in G_m, t} \left| \int_0^t \tilde{a}^m(s, x) \, ds - \int_0^t a(s, \tilde{x}) \, ds \right| \to 0 \tag{2.3}$$

$$\sup_{x \in G_m, t} \left| \int_0^t \tilde{b}^m(s, x) \, ds - \int_0^t b(s, \tilde{x}) \, ds \right| \to 0.$$
(2.4)

Suppose further that

$$\tilde{X}^m_{f(m)} \Longrightarrow X_0$$

and that $\mathbb{P}(X_n^m \in G_m \text{ for all } n \ge f(m)) \to 1$. Then $(\tilde{X}_{\lfloor mt \rfloor}^m, 0 < t \le T)$ converges in law to the unique solution of the SDE

$$dX = b\,dt + a\,dB, \quad X(0) = X_0.$$

Proof. This is essentially Proposition 23 in [VV2]. The first difference is that the coordinates $d'+1, \ldots, d$ of the X^m do not appear in the limiting process. A careful examination of the proof of that Proposition shows that it was not necessary to assume that all coordinates appear in the limit, as long as the auxiliary coordinates do not influence the variance and drift asymptotics.

The second difference is the introduction of the "good" set G_m , possibly a proper subset of \mathbb{R}^d . Since we assume that the processes X^m stay in G_m with probability tending to one, we can apply the Proposition 23 of [VV1] to X^m stopped when it leaves this set. Then, the probability that the stopped process is different from the original tends to zero, completing the proof.

The third difference is the weak convergence of $\tilde{X}_{f(m)}^m$ instead of \tilde{X}_0^n and that we have the bound in (2.2) only for $m \ge f(m)$. Note that for the Markov family $\hat{X}_l^m = \tilde{X}_{\max(l, f(m))}^m$ all the same conditions apply with f(m) = 0 and the initial conditions converge weakly. Moreover, for any fixed t > 0 and m large enough one has $\hat{X}_{\lfloor mt \rfloor}^m = \tilde{X}_{\lfloor mt \rfloor}^m$. \Box

We will use this proposition with $m = \lambda^{-2}$ or $\lambda = 1/\sqrt{m}$. X_n^m will correspond to the pair $(X_{1/\sqrt{m},n}, Z_{1/\sqrt{m},n})$ whereas \tilde{X}_n^m will only be the part of $X_{1/\sqrt{m},n}$ giving the SDE limit in Theorem 1.1. Moreover, many of the estimates will only work with high probability which will be treated by introducing stopping times that will not matter in the limit.

3. Evolution Equation and Estimates

In this section we show the basic estimates needed to establish the conditions of the proposition above. Recall that $\mathcal{T}_{\lambda,n} = \mathcal{T}_0 + \lambda \mathcal{V}_{\lambda,n} + \lambda^2 \mathcal{W}_{\lambda}$ where the disordered part satisfies the assumptions (1.7) and (1.8). For convenience we define $\mathcal{Y}_{\lambda,n} = \mathcal{V}_{\lambda,n} + \lambda \mathcal{W}_{\lambda}$, such that

$$\mathcal{T}_{\lambda,n} = \mathcal{T}_0 + \lambda \mathcal{V}_{\lambda,n} + \lambda^2 \mathcal{W}_{\lambda} = \mathcal{T}_0 + \lambda \mathcal{Y}_{\lambda,n}.$$

Then the assumptions imply that for small λ

$$\mathbb{E}(\|\mathcal{Y}_{\lambda,n}\|^{6+\epsilon}) = \mathcal{O}(1), \quad \mathbb{E}(\mathcal{Y}_{\lambda,n}) = \lambda \mathcal{Y} + o(1). \tag{3.1}$$

For the proof of Theorem 1.1 we will fix some time T > 0 and obtain the SDE limit up to time T > 0 which is fixed but arbitrary. In principle we could work with estimates that are valid with high probability in order to obtain the limit process. However, for the sake of keeping the arguments and estimates simpler, it will be easier to work with a cut off on the randomness and almost sure estimates. The cut off bound will approach infinity for λ going to zero in a way that it does not affect the limit.

Proposition 3.1. Without loss of generality we can assume

$$\|\mathcal{Y}_{\lambda,n}\| < K_{\mathcal{Y}}\lambda^{s-1} \quad \text{for some } \frac{2}{3} < s < 1 \text{ and } K_{\mathcal{Y}} > 0. \tag{3.2}$$

Proof. Assumption (1.7) and Markov's inequality yield

$$\mathbb{P}(\|\mathcal{Y}_{\lambda,n}\| \ge C\|) \le \frac{\mathbb{E}(\|\mathcal{Y}_{\lambda,n}\|^{6+\epsilon})}{C^{6+\epsilon}} \le \frac{k}{C^{6+\epsilon}}$$
(3.3)

for some fixed *k*, uniformly for small λ .

Now let *s* be such that $2/(6 + \epsilon) < 1 - s < 1/3$ and define the truncated random variable $\tilde{\mathcal{Y}}_{\lambda,n}$ by

$$\widetilde{\mathcal{Y}}_{\lambda,n} = \begin{cases} \mathcal{Y}_{\lambda,n} & \text{ if } \|\mathcal{Y}_{\lambda,n}\| < K\lambda^{s-1} \\ 0 & \text{ else} \end{cases}$$

By the choice of s, $(1 - s) > \frac{2}{6+\epsilon} > \frac{1}{5+\epsilon}$ and we obtain

$$\mathbb{E}(\|\mathcal{Y}_{\lambda,n} - \widetilde{\mathcal{Y}}_{\lambda,n}\|) = \int_{\|\mathcal{Y}_{\lambda,n} > K\lambda^{s-1}\|} \|\mathcal{Y}_{\lambda,n}\| d\mathbb{P} \le \int_{K\lambda^{s-1}}^{\infty} C \cdot (6+\epsilon) \frac{k}{C^{7+\epsilon}} dC$$
$$\le \frac{(6+\epsilon)k}{(5+\epsilon)K^{5+\epsilon}} \lambda^{(5+\epsilon)(1-s)} = o(\lambda)$$

and similarly

$$\mathbb{E}(\|\mathcal{Y}_{\lambda,n} - \widetilde{\mathcal{Y}}_{\lambda,n}\|^2) \le \frac{(6+\epsilon)k}{(4+\epsilon)K^{4+\epsilon}}\lambda^{(4+\epsilon)(1-s)} = o(1)$$

for $\lambda \to 0$. Thus, using $\tilde{\mathcal{Y}}_{\lambda,n}$ instead of $\mathcal{Y}_{\lambda,n}$ in (1.13), (1.14) and (1.15) does not change the quantities V, g(M) and $\hat{g}(M)$. Hence, the SDE limits mentioned in Theorem 1.1 for $\tilde{\mathcal{Y}}_{\lambda,n}$ and $\mathcal{Y}_{\lambda,n}$ are the same.

Let us assume that Theorem 1.1 is correct for $\widetilde{\mathcal{Y}}_{\lambda,n}$ and obtain its validity for using $\mathcal{Y}_{\lambda,n}$ by showing that we obtain the same limit SDE. From (3.3)

$$\mathbb{P}(\mathcal{Y}_{\lambda,n} \neq \widetilde{\mathcal{Y}}_{\lambda,n}) \leq \frac{k}{K^{6+\epsilon} \lambda^{(6+\epsilon)(s-1)}} = c \, \lambda^{(6+\epsilon)(1-s)} = c \lambda^{2+\delta}$$

where the last equations define c > 0 and $\delta > 0$. Hence,

$$\mathbb{P}\Big(\|\mathcal{Y}_{\lambda,n}\| > K\lambda^{s-1} \text{ for some } n = 1, 2, \dots, \lfloor \lambda^{-2}T \rfloor\Big) \leq Tc\lambda^{\delta}$$

which approaches zero for $\lambda \to 0$. Therefore, introducing a stopping time $T_{\lambda} := \min\{n : \mathcal{Y}_{\lambda,n} \neq \tilde{\mathcal{Y}}_{\lambda,n}\}$ and considering the stopped process $X_{\lambda,n\wedge T_{\lambda}}$ one obtains the same distributional limit process up to time *T* (in fact for arbitrary *T*). But for the stopped processes there is no difference when replacing $\mathcal{Y}_{\lambda,n}$ by $\tilde{\mathcal{Y}}_{\lambda,n}$. \Box

Thus we may assume Eq. (3.2) without loss of generality and we will do so from now on. Moreover, as the spectral radius of Γ_0 and Γ_2 are smaller than 1, using a basis change, we may assume:¹

$$\|\Gamma_0\| \le e^{-\gamma}, \quad \|\Gamma_2\| \le e^{-\gamma}, \quad \text{where } \gamma > 0. \tag{3.4}$$

Before obtaining the evolution equations, we will first establish that the pair $(X_{\lambda,n}, Z_{\lambda,n})$ is a Markov process. Let us define the following subgroup of $GL(d, \mathbb{C})$.

$$\mathbb{G} = \left\{ \begin{pmatrix} \mathbf{1} & 0 \\ C & D \end{pmatrix} \in \operatorname{Mat}(d, \mathbb{C}) : \text{ where } D \in \operatorname{GL}(d_2, \mathbb{C}) \right\}.$$

¹ Even if Γ_0 or Γ_2 are not diagonalizable, one can make the norm smaller than one as one can make the off diagonal terms of Jordan blocks arbitrarily small.

Now let \mathcal{X}_1 and \mathcal{X}_2 be equivalent, $\mathcal{X}_1 \sim \mathcal{X}_2$, if $\mathcal{X}_1 = \mathcal{X}_2 \mathcal{Q}$ for $\mathcal{Q} \in \mathbb{G}$. As different representatives differ by multiplication from the right, multiplication from the left defines an action on the equivalence classes. Therefore, the evolution of the equivalence classes $[\mathcal{X}_{\lambda,n}]_{\sim}$ is a Markov process. As

$$\begin{pmatrix} A & B \\ C & D \end{pmatrix} \begin{pmatrix} \mathbf{1} & \mathbf{0} \\ -D^{-1}C & D^{-1} \end{pmatrix} = \begin{pmatrix} A - BD^{-1}C & BD^{-1} \\ \mathbf{0} & \mathbf{1} \end{pmatrix}$$
(3.5)

we see that the equivalence class $[\mathcal{X}_{\lambda,n}]_{\sim}$ is determined by the pair $(X_{\lambda,n}, Z_{\lambda,n})$.

Let us further introduce the following commuting matrices of size $d_0 + d_1$,

$$R = \begin{pmatrix} \mathbf{1} & \mathbf{0} \\ \mathbf{0} & U \end{pmatrix}, \quad S = \begin{pmatrix} \Gamma_0 & \mathbf{0} \\ \mathbf{0} & \mathbf{1} \end{pmatrix}; \quad R, S \in \operatorname{Mat}(d_0 + d_1, \mathbb{C}), \tag{3.6}$$

Note that *R* is unitary and that

$$\mathcal{R} = \begin{pmatrix} R & \mathbf{0} \\ \mathbf{0} & \mathbf{1} \end{pmatrix} \in \mathbf{U}(d). \tag{3.7}$$

for \mathcal{R} as defined in (1.3). As Γ_0^n is exponentially decaying, we refer to the d_0 dimensional subspace corresponding to this matrix block as the decaying directions of \mathcal{T}_0^n . Similarly, the d_2 dimensional subspace corresponding to the entry Γ_2^{-n} are referred to as growing directions.

The evolution of $\mathcal{X}_{\lambda,n}$ is given by

$$\mathcal{X}_{\lambda,n} = \mathcal{R}^{-n} \mathcal{T}_{\lambda,n} \mathcal{R}^{n-1} \mathcal{X}_{\lambda,n-1}.$$
(3.8)

Therefore, let

$$\mathcal{R}^{-n}\mathcal{T}_{\lambda,n}\mathcal{R}^{n-1} = \begin{pmatrix} T^A_{\lambda,n} & T^B_{\lambda,n} \\ T^C_{\lambda,n} & T^D_{\lambda,n} \end{pmatrix}.$$

Here, A, B, C, D are used as indices to indicate that we use the same sub-division of the matrix as we did when defining $A_{\lambda,n}$, $B_{\lambda,n}$, $C_{\lambda,n}$ and $D_{\lambda,n}$.

The action on the equivalence class of $\mathcal{X}_{\lambda,n-1} \sim \begin{pmatrix} X_{\lambda,n-1} & Z_{\lambda,n-1} \\ \mathbf{0} & \mathbf{1} \end{pmatrix}$ gives

$$\begin{pmatrix} T_{\lambda,n}^A & T_{\lambda,n}^B \\ T_{\lambda,n}^C & T_{\lambda,n}^D \end{pmatrix} \begin{pmatrix} X_{\lambda,n-1} & Z_{\lambda,n-1} \\ \mathbf{0} & \mathbf{1} \end{pmatrix} = \begin{pmatrix} T_{\lambda,n}^A X_{\lambda,n-1} & T_{\lambda,n}^A Z_{\lambda,n-1} + T_{\lambda,n}^B \\ T_{\lambda,n}^C X_{\lambda,n-1} & T_{\lambda,n}^C Z_{\lambda,n-1} + T_{\lambda,n}^D \end{pmatrix}.$$

Transforming the matrix on the right hand side into the form as in (3.5) we can read off the evolution equations

$$Z_{\lambda,n} = \left(T_{\lambda,n}^{A} Z_{\lambda,n-1} + T_{\lambda,n}^{B}\right) \left(T_{\lambda,n}^{C} Z_{\lambda,n-1} + T_{\lambda,n}^{D}\right)^{-1}$$
(3.9)

and

$$X_{\lambda,n} = T^A_{\lambda,n} X_{\lambda,n-1} - \left(T^A_{\lambda,n} Z_{\lambda,n-1} + T^B_{\lambda,n}\right) \left(T^C_{\lambda,n} Z_{\lambda,n-1} + T^D_{\lambda,n}\right)^{-1} T^C_{\lambda,n} X_{\lambda,n-1}.$$
(3.10)

For more detailed calculations, let

$$\mathcal{Y}_{\lambda,n} = \mathcal{V}_{\lambda,n} + \lambda \mathcal{W}_{\lambda} =: \begin{pmatrix} V_{\lambda,n}^{A} & V_{\lambda,n}^{B} \\ V_{\lambda,n}^{C} & V_{\lambda,n}^{D} \end{pmatrix}, \text{ then} \\ \mathcal{R}^{-n} \mathcal{Y}_{\lambda,n} \mathcal{R}^{n-1} = \begin{pmatrix} R^{-n} V_{\lambda,n}^{A} R^{n-1} & R^{-n} V_{\lambda,n}^{B} \\ V_{\lambda,n}^{C} R^{n-1} & V_{\lambda,n}^{D} \end{pmatrix}.$$
(3.11)

From (1.1), (1.2), (3.6) and (3.7) one finds

$$T_{\lambda,n}^{A} = S + \lambda R^{-n} V_{\lambda,n}^{A} R^{n-1}, \quad T_{\lambda,n}^{B} = \lambda R^{-n} V_{\lambda,n}^{B}, \quad T_{\lambda,n}^{C} = \lambda V_{\lambda,n}^{C} R^{n-1},$$

$$T_{\lambda,n}^{D} = \Gamma_{2}^{-1} + \lambda V_{\lambda,n}^{D}.$$
(3.12)

We will first consider the Markov process $Z_{\lambda,n}$ and denote the starting point by $Z_0 = B_0 D_0^{-1}$.

Proposition 3.2. For λ small enough and some constant K_Z we have the uniform bound

$$\|Z_{\lambda,n}\| \le K_Z(e^{-\gamma n/2} + \lambda^s) = \mathcal{O}(e^{-\gamma n/2}, \lambda^s)$$
(3.13)

with γ as in (3.4). This implies $Z_{\frac{1}{\sqrt{m}},\lfloor tm \rfloor} \Rightarrow 0$ in law.

Proof. Take λ small enough, such that $e^{\gamma} - K_{\mathcal{Y}}\lambda^s(1 + \max(||Z_0||, 1)) > e^{\gamma/2}$ (with $K_{\mathcal{Y}}$ as in (3.2)) and

$$\frac{(1+K_{\mathcal{Y}}\lambda^{s})\max(\|Z_{0}\|,1)+K_{\mathcal{Y}}\lambda^{s}}{e^{\gamma}-K_{\mathcal{Y}}\lambda^{s}(1+\max(\|Z_{0}\|,1))} \leq e^{-\gamma/2}\max(\|Z_{0}\|,1).$$
(3.14)

Then, using (3.9) we find for $||Z_{\lambda,n-1}|| \le \max(||Z_0||, 1)$

$$\|Z_{\lambda,n}\| \le \frac{(1+K_{\mathcal{Y}}\lambda^{s})\|Z_{\lambda,n-1}\| + K_{\mathcal{Y}}\lambda^{s}}{e^{\gamma} - K_{\mathcal{Y}}\lambda^{s}\|Z_{\lambda,n-1}\|} \le e^{-\gamma/2}\max(\|Z_{0}\|, 1) < \max(\|Z_{0}\|, 1).$$

Hence, inductively, $||Z_{\lambda,n}|| < \max(||Z_0||, 1)$ for $n \ge 1$. Thus, using this equation and (3.14) again leads to

$$||Z_{\lambda,n}|| \leq e^{-\gamma/2} ||Z_{\lambda,n-1}|| + K_{\mathcal{Y}} \lambda^s.$$

By induction this yields the bound

$$\|Z_{\lambda,n}\| \le e^{-\gamma n/2} \|Z_0\| + \frac{1 - e^{-\gamma n/2}}{1 - e^{-\gamma/2}} K_{\mathcal{Y}} \lambda^s$$

proving the proposition. \Box

Remark. Note that the estimates show that $T_{\lambda,n}^C Z_{\lambda,n-1} + T_{\lambda,n}^D$ is invertible. Using $D_{\lambda,n} = T_{\lambda,n}^C B_{\lambda,n-1} + T_{\lambda,n}^D D_{\lambda,n-1} = (T_{\lambda,n}^C Z_{\lambda,n-1} + T_{\lambda,n}^D) D_{\lambda,n-1}$ it follows inductively also that $D_{\lambda,n}$ is invertible. Hence, $X_{\lambda,n}$ and $Z_{\lambda,n}$ are always well defined for small λ under assumption (3.2). Hence, under the assumptions of Theorem 1.1 they will be well defined up to $n = T\lambda^{-2}$ with probability going to one as $\lambda \to 0$.

Next, let the reminder term $\widetilde{\Xi}_{\lambda,n}$ be given by

$$(T_{\lambda,n}^D + T_{\lambda,n}^C Z_{\lambda,n-1})^{-1} = \Gamma_2 + \widetilde{\Xi}_{\lambda,n}, \qquad (3.15)$$

and define

$$\Xi_{\lambda,n} := -T^A_{\lambda,n} Z_{\lambda,n-1} \Gamma_2 V^C_{\lambda,n} R^{n-1} - (T^A_{\lambda,n} Z_{\lambda,n-1} + \lambda R^{-n} V^B_{\lambda,n}) \widetilde{\Xi}_{\lambda,n} V^C_{\lambda,n} R^{n-1}.$$
(3.16)

Furthermore let

$$V_{\lambda,n}^X := V_{\lambda,n}^A - \lambda V_{\lambda,n}^B \Gamma_2 V_{\lambda,n}^C.$$
(3.17)

The upper index X should indicate that this is the important combination of the random parts $\mathcal{Y}_{\lambda,n}$ that will contribute to the SDE limit for the process $X_{\lambda,n}$. As we will establish, the 'reminder' part expressed in the $\Xi_{\lambda,n}$ terms will be of too low order and not matter in the limit. By (3.10) and (3.12) one obtains

$$X_{\lambda,n} = SX_{\lambda,n-1} + \lambda R^{-n} V_{\lambda,n}^X R^{n-1} X_{\lambda,n-1} + \lambda \Xi_{\lambda,n} X_{\lambda,n-1}.$$
(3.18)

The following estimates will be needed to obtain the SDE limit.

Lemma 3.3. Let $\mathbb{E}_{X,Z}$ denote the conditional expectation given that $X_{\lambda,n-1} = X$ and $Z_{\lambda,n-1} = Z$.

(i) For small λ one has the bounds

$$\mathbb{E}_{X,Z}(\Xi_{\lambda,n}) = \mathbb{E}(\Xi_{\lambda,n} | Z_{\lambda,n-1} = Z) = \mathcal{O}(\lambda^{2s-1} \| Z \|, \lambda^{3s-1})$$
(3.19)

$$\mathbb{E}_{X,Z}(\|\Xi_{\lambda,n}\|^2) = \mathcal{O}(\|Z\|^2, \lambda^2, \lambda \|Z\|)$$
(3.20)

$$\Xi_{\lambda,n} = \mathcal{O}(\|Z_{\lambda,n-1}\|\lambda^{s-1},\lambda^{3s-1}).$$
(3.21)

(ii) $V_{\lambda,n}^X$ is independent of $Z_{\lambda,n-1}$ and $X_{\lambda,n-1}$ and there is a matrix V_0 and a constant K such that

$$\mathbb{E}(V_{\lambda,n}^X) = \lambda V_0 + o(\lambda) \tag{3.22}$$

$$V_{\lambda,n}^X = \mathcal{O}(\lambda^{s-1}) \tag{3.23}$$

$$\mathbb{E}(\|V_{\lambda,n}^X\|^3) \le K = \mathcal{O}(1).$$
(3.24)

(iii)

$$\mathbb{E}_{X,Z}\left(X_{\lambda,n}X_{\lambda,n}^*\right) = SXX^*S + \|X\|^2 \cdot \mathcal{O}(\lambda^2, \lambda^{2s}\|Z\|).$$
(3.25)

Moreover, there is a function K(T) such that

$$\mathbb{E}(\|X_{\lambda,n}\|^2) \le K(T) \quad \text{for all } n < T\lambda^{-2}.$$
(3.26)

Proof. Note that (3.2) implies the uniform bounds

$$V_{\lambda,n}^{\#} = \mathcal{O}(\lambda^{s-1}) \text{ for } \# \in \{A, B, C, D, X\}$$
 (3.27)

As $T_{\lambda,n}^D = \Gamma_2^{-1} + \lambda V_{\lambda,n}^D$, $T_{\lambda,n}^A = S + \lambda R^{-n} V_{\lambda,n}^A R^{n-1}$ one finds

$$\widetilde{\Xi}_{\lambda,n} = \mathcal{O}(\lambda^{s}) \quad \text{and} \quad (T^{A}_{\lambda,n}Z + \lambda R^{-n}V^{B}_{\lambda,n})\widetilde{\Xi}_{\lambda,n}V^{C}_{\lambda,n}R^{n-1} = \mathcal{O}(\lambda^{3s-1}, \lambda^{2s-1}||Z||).$$
(3.28)

Using (1.8) we see that $\mathbb{E}(T_{\lambda,n}^A Z \Gamma_2 V_{\lambda,n}^C R^{n-1}) = \mathcal{O}(\lambda ||Z||)$ which together with (3.28) gives (3.19). (Note that $V_{\lambda,n}^A$, $V_{\lambda,n}^B$ and $V_{\lambda,n}^C$ are independent of $Z_{\lambda,n-1}$.) The moment condition (1.7) also yields $\mathbb{E}(||T_{\lambda,n}^A Z \Gamma_2 V_{\lambda,n}^C R^{n-1}||^2) = \mathcal{O}(||Z||^2)$. Combining this with (3.28), using Cauchy Schwarz in the form $\mathbb{E}(||A + B||^2) \leq \left(\sqrt{\mathbb{E}(||A||^2)} + \sqrt{\mathbb{E}(||B||^2)}\right)^2$ and using $\mathcal{O}(\lambda^{3s-1}, \lambda^{2s-1} ||Z||) \leq \mathcal{O}(\lambda, ||Z||)$ we find for some constant *K* that $\mathbb{E}_{X,Z}(||\Xi_{\lambda,n}||^2) \leq K(||Z|| + \lambda)^2$ giving (3.20). Finally, (3.27) yields $||T_{\lambda,n}^A Z \Gamma_2 V_{\lambda,n}^C R^{n-1}|| = \mathcal{O}(||Z||\lambda^{s-1})$ which combined with (3.28) gives (3.21).

To get (ii) note that Eq. (3.22) follows from (1.8), (3.27) yields (3.23) and the moment condition (1.7) implies (3.24).

For part (iii) note that by (3.18) one has

$$\mathbb{E}_{X,Z}(X_{\lambda,n}X_{\lambda,n}^*) = SXX^*S + \lambda R^{-n}\mathbb{E}(V_{\lambda,n}^X)R^{n-1}XX^*S + \lambda \left[R^{-n}\mathbb{E}(V_{\lambda,n}^X)R^{n-1}XX^*S\right]^* + \lambda \mathbb{E}_{X,Z}(\Xi_{\lambda,n})XX^*S + \lambda \left[\mathbb{E}(\Xi_{\lambda,n})XX^*S\right]^* + \mathcal{O}\left(\lambda^2 \|X\|^2 \mathbb{E}_{X,Z}\left((\|V_{\lambda,n}^X\| + \|\Xi_{\lambda,n}\|)^2\right)\right).$$

Using (3.19), (3.22) and $\mathbb{E}_{X,Z}((||V_{\lambda,n}^X|| + ||\Xi_{\lambda,n}||)^2) = \mathcal{O}(1)$ one finally obtains Eq. (3.25). The latter estimate follows from (3.13), (3.21), (3.24) and Cauchy-Schwarz. For (3.26) note that the Hilbert-Schmidt norm is given by $||X||_{HS}^2 = \text{Tr}(XX^*)$. Then (3.13) and (3.25) imply that for some constant *K* one finds

$$\mathbb{E}\left(\left\|X_{\lambda,n}\right\|_{HS}^{2}\right) \leq \begin{cases} \mathbb{E}\left(\left\|X_{\lambda,n-1}\right\|_{HS}^{2}\right)\left(1+K\lambda^{2s}\right) & \text{ for } n \leq s/\gamma\ln(\lambda^{-2})\\ \mathbb{E}\left(\left\|X_{\lambda,n-1}\right\|_{HS}^{2}\right)\left(1+K\lambda^{2}\right) & \text{ for } n > s/\gamma\ln(\lambda^{-2}). \end{cases}$$

By induction, for small λ and $n < T\lambda^{-2}$,

$$\mathbb{E}\left(\left(\|X_{\lambda,n}\|_{HS}^{2}\right) \le (1+K\lambda^{2s})^{s/\gamma\ln(\lambda^{-2})}(1+K\lambda^{2})^{T\lambda^{-2}}\|X_{0}\|^{2} < e^{K+TK}\|X_{0}\|^{2}.$$

As all norms are equivalent, this finishes the proof. \Box

4. Proof of Theorem 1.1, The Limit of $X_{\lambda,n}$

We need to split up the $(d_0 + d_1) \times (d_0 + d_1)$ matrix $X_{\lambda,n}$ into the corresponding blocks. Therefore, let

$$P_0 = (\mathbf{1} \ \mathbf{0}) \in \text{Mat}(d_0 \times (d_0 + d_1)), \quad P_1 = (\mathbf{0} \ \mathbf{1}) \in \text{Mat}(d_1 \times (d_0 + d_1))$$

Then, using (3.6) one finds

$$P_0 S = \Gamma_0 P_0, \quad P_1 S = P_1, \quad P_0 R^n = P_0, \quad P_1 R^n = U^n P_1.$$
 (4.1)

Moreover, for any $(d_0 + d_1) \times (d_0 + d_1)$ matrix M one has

$$M = \begin{pmatrix} P_0 M \\ P_1 M \end{pmatrix} = \begin{pmatrix} M P_0^* & M P_1^* \end{pmatrix}.$$
(4.2)

.

Proposition 4.1. There is a function K(T) such that for all $n < T\lambda^{-2}$ one has

$$\mathbb{E}(\|P_0 X_{\lambda,n}\|_{HS}^2) \le e^{-2\gamma n} \|P_0 X_0\|_{HS}^2 + K(T)\lambda^{2s}$$

In particular, for any function $f(n) \in \mathbb{N}$ with $\lim_{n \to \infty} f(n) = \infty$ one has

$$P_0 X_{\frac{1}{\sqrt{n}}, f(n)} \Longrightarrow (0 \ 0).$$

Proof. Multiplying (3.25) by P_0 from the left and P_0^* from the right, taking expectations and using the bound (3.26) gives

$$\mathbb{E}(P_0 X_{\lambda,n} X_{\lambda,n}^* P_0^*) = \Gamma_0 \mathbb{E}(P_0 X_{\lambda,n-1} X_{\lambda,n-1}^* P_0^*) \Gamma_0^* + \mathcal{O}(\lambda^{2s})$$

which leads to

$$\mathbb{E}(\|P_0X_{\lambda,n}\|_{HS}^2) \le e^{-2\gamma} \mathbb{E}(\|P_0X_{\lambda,n-1}\|_{HS}^2) + \mathcal{O}(\lambda^{2s}).$$

where the bound for the error term is uniform in *n* for $n < \lambda^{-2}T$. Induction yields the stated result. \Box

Finally, let us consider the part with an interesting limit. Multiplying (3.18) by P_1 from the left and using (4.1), (4.2) one finds

$$P_{1}X_{\lambda,n} = P_{1}X_{\lambda,n-1} + \lambda U^{-n}P_{1}V_{\lambda,n}^{X}(P_{1}^{*}U^{n-1}P_{1}X_{\lambda,n-1} + P_{0}^{*}P_{0}X_{\lambda,n-1}) + \lambda P_{1}\Xi_{\lambda,n}(P_{1}^{*}P_{1}X_{\lambda,n-1} + P_{0}^{*}P_{0}X_{\lambda,n-1})$$
(4.3)

We immediately obtain the following estimate.

Proposition 4.2. For $n < \lambda^{-2}T$ one has uniformly

$$\mathbb{E}(\|P_1X_{\lambda,n}-P_1X_0\|^2) \leq \mathcal{O}(n\lambda^{2s}).$$

This implies for any function $f(n) \in \mathbb{N}$ with $\lim_{n \to \infty} f(n)n^{-s} = 0$ that

$$P_1 X_{\frac{1}{\sqrt{n}}, f(n)} \implies P_1 X_0$$

in law for $n \to \infty$.

Proof. Using the estimates of Lemma 3.3 one finds similarly to (3.25) that

$$\mathbb{E}_{X,Z}((P_1X_{\lambda,n} - P_1X_0)(P_1X_{\lambda,n} - P_1X_0)^*) = P_1XX^*P_1^* + \|X\|^2\mathcal{O}(\lambda^2, \lambda^{2s}\|Z\|).$$

Using (3.26) and $||Z_{\lambda,n-1}|| \leq O(1)$ from (3.13) we find therefore that uniformly for $n < \lambda^{-2}T$

$$\mathbb{E}((P_1 X_{\lambda,n} - P_1 X_0)(P_1 X_{\lambda,n} - P_1 X_0)^*) = \mathbb{E}((P_1 X_{\lambda,n-1} - P_1 X_0)(P_1 X_{\lambda,n-1} - P_1 X_0)^*) + \mathcal{O}(\lambda^{2s})$$

Taking traces (Hilbert-Schmidt norm) and induction yield the result.

In order to use Proposition 2.1 we need to consider stopped processes. So for any λ , let T_K be the stopping time when $||P_1X_{\lambda,n}||$ is bigger then K. We define the stopped process by

$$P_1 X_{\lambda,n}^K := P_1 X_{\lambda, T_K \wedge n}, \quad P_0 X_{\lambda,n}^K := P_0 X_{\lambda,n} \cdot \mathbf{1}_{n \le T_K}, \quad Z_{\lambda,n}^K := Z_{\lambda,n} \cdot \mathbf{1}_{n \le T_K}$$

where

$$1_{n < T_K} = 1$$
 for $n \le T_K$ and $1_{n < T_K} = 0$ for $n > T_K$.

As long as $n \le T_K$, (3.18) and Lemma 3.3 give $||P_0 X_{\lambda,n}|| \le (e^{-\gamma} + \mathcal{O}(\lambda^s))||P_0 X_{\lambda,n-1}|| + \mathcal{O}(\lambda^s)$. An induction similar as in Proposition 3.2 yields for any finite *K*

$$\|P_0 X_{\lambda,n}^K\| < K_P(e^{-\gamma/2n} + \lambda^s), \quad \text{for some constant } K_P = K_P(K).$$
(4.4)

For the limit, we will scale $\lambda = 1/\sqrt{m}$ and $n = \lfloor tm \rfloor$. First, define the good set

$$G_m = G_m(K) := \{ (X, Z) : ||Z|| < 2K_Z m^{-s/2}, ||P_0X|| < 2K_P m^{-s/2} \},$$

then by the estimates (3.13) and (4.4) one has

$$(X_{1/\sqrt{m},n}^{K}, Z_{1/\sqrt{m},n}^{K}) \in G_m \quad \text{for} \quad n > s \, \ln(m) \,/\, \gamma.$$

$$(4.5)$$

For the variances in the SDE limit we need to recognize the connection to the matrix V and the functions g(M), $\hat{g}(M)$ as defined in (1.13), (1.14) and (1.15). Using the notations as introduced in (1.9) combined with (3.11) and (3.17) one obtains

$$P_1 V_{\lambda,n}^X P_1^* = (V_{\lambda,11} + \lambda W_{\lambda,11}) - \lambda (V_{\lambda,12} + \lambda W_{\lambda,12}) \Gamma_2 (V_{\lambda,21} + \lambda W_{\lambda,21}).$$
(4.6)

Therefore, using the functions h, \hat{h} as defined in (1.10) and W as defined in (1.11) one finds

$$\mathbb{E}(P_1 V_{\lambda,n}^X P_1^*) = \lambda P_1 V_0 P_1^* + o(\lambda) = \lambda W + o(\lambda)$$
(4.7)

$$\mathbb{E}((P_1 V_{\lambda,n}^X P_1^*)^\top M P_1 V_{\lambda,n}^X P_1^*) = h(M) + o(1)$$
(4.8)

$$\mathbb{E}((P_1 V_{\lambda,n}^X P_1^*)^* M P_1 V_{\lambda,n}^X P_1^*) = \widehat{h}(M) + o(1).$$
(4.9)

Here the error terms $o(\lambda)$ and o(1) are uniform in the limit $\lambda \to 0$.

Next we have to consider the conditional distribution of the differences $Y_{\lambda,n} = Y_{\lambda,n}(X, Z)$ given that $X_{\lambda,n-1} = X$, $Z_{\lambda,n-1} = Z$, i.e. for Borel sets of matrices A,

$$\mathbb{P}(Y_{\lambda,n}(X,Z)\in\mathcal{A}):=\mathbb{P}\big(P_1X_{\lambda,n}-P_1X\in\mathcal{A}\ \big|\ X_{\lambda,n-1}=X,\ Z_{\lambda,n-1}=Z\big),$$

Using (4.3) one has

$$Y_{\lambda,n} = \lambda U^{-n} P_1 V_{\lambda,n}^X (P_1^* U^{n-1} P_1 X + P_0^* P_0 X) + \lambda P_1(\Xi_{\lambda,n} | Z_{\lambda,n-1} = Z) X$$
(4.10)

where $(\Xi_{\lambda,n}|Z_{\lambda,n-1} = Z)$ is a random matrix variable distributed as $\Xi_{\lambda,n}$ conditioned to $Z_{\lambda,n-1} = Z$, this simply means that in (3.15) and (3.16) one replaces $Z_{\lambda,n-1}$ by Z.

Proposition 4.3. Assume $(X, Z) \in G_m$, $m = \lambda^{-2}$, thus $P_0 X = \mathcal{O}(\lambda^s)$ and $Z = \mathcal{O}(\lambda^s)$. Then one finds for $Y_{\lambda,n} = Y_{\lambda,n}(X, Z)$ the uniform estimates (uniform in X, Z, n)

$$\mathbb{E}(Y_{\lambda,n}) = \lambda^2 U^{-n} W U^{n-1} P_1 X + o(\lambda^2)$$
(4.11)

$$\mathbb{E}(Y_{\lambda,n}^{\top}MY_{\lambda,n}) = \lambda^2 (P_1 X)^{\top} U^{\top n-1} h(\bar{U}^n M U^{-n}) U^{n-1} P_1 X + o(\lambda^2)$$
(4.12)

$$\mathbb{E}(Y_{\lambda,n}^*MY_{\lambda,n}) = \lambda^2 (P_1 X)^* U^{*n-1} \,\widehat{h}(U^n M U^{-n}) \, U^{n-1} P_1 X + o(\lambda^2) \tag{4.13}$$

$$\mathbb{E}(\|Y_{\lambda,n}\|^3) \le \lambda^3 K_Y \|X\|^3 \quad for some uniform K_Y > 0.$$
(4.14)

Note that any covariance of real and imaginary entries of $Y_{\lambda,n}$ can be obtained by varying *M* in (4.12) and (4.13). Moreover, one obtains uniformly for 0 < t < T

$$\lim_{m \to \infty} \int_0^t m \mathbb{E}\left(Y_{\frac{1}{\sqrt{m}}, \lfloor sm \rfloor}\right) ds = t V P_1 X$$
(4.15)

$$\lim_{m \to \infty} \int_0^t m\mathbb{E}\left(Y_{\sqrt{m},\lfloor sm \rfloor}^\top M Y_{\sqrt{m},\lfloor sm \rfloor}\right) ds = t(P_1 X)^\top g(M) P_1 X$$
(4.16)

$$\lim_{m \to \infty} \int_0^t m \mathbb{E}\left(Y^*_{\frac{1}{\sqrt{m}}, \lfloor sm \rfloor} M Y_{\frac{1}{\sqrt{m}}, \lfloor sm \rfloor}\right) ds = t (P_1 X)^* \widehat{g}(M) P_1 X$$
(4.17)

where V, g and \hat{g} are as in (1.13), (1.14) and (1.15)

Proof. Given $X_{\lambda,n-1} = X$, $P_0 X = \mathcal{O}(\lambda^s)$, $Z_{\lambda,n-1} = Z = \mathcal{O}(\lambda^s)$ and using the estimates Eqs. (3.19), (3.22) and (4.10) yields

$$\mathbb{E}(Y_{\lambda,n}) = \lambda \mathbb{E}(U^{-n} P_1 V_{\lambda,n}^X P_1^* U^* U^n P_1 X) + \mathcal{O}(\lambda^{3s}) = \lambda^2 U^{-n} W U^{n-1} P_1 X + o(\lambda^2)$$

which implies (4.11). Using (3.23), (3.21) and $Z_{\lambda,n-1} = Z = \mathcal{O}(\lambda^s)$ we get

$$Y_{\lambda,n} = \lambda U^{-n} P_1 V_{\lambda,n}^X P_1^* U^{n-1} P_1 X + \mathcal{O}(\lambda^{2s}).$$
(4.18)

Together with (4.8) and (4.9) this proves (4.12) and (4.13). Finally, (4.14) follows from (4.18) and (1.7).

Letting $u = U^{-n} = U^{n*}$ we have the terms uWU^*u^* , $\overline{uUh}(u^\top Mu)U^*u^*$ and $uU\widehat{h}(u^*Mu)U^*u^*$ appearing in (4.11), (4.12) and (4.13), respectively. On the Abelian compact group $\langle U \rangle$ generated by the unitary U, the functions

$$u \mapsto uWu^*, \quad u \mapsto \overline{u} \,\overline{U} \,h(u^\top M u) \,U^* \,u^*, \quad u \mapsto u \,U \,\widehat{h}(u^* M u) \,U^* \,u^*$$

are polynomials of the eigenvalues of u as h, \hat{h} are linear and all $u \in \langle U \rangle$ are simultaneously diagonalizable. For any such polynomial p(u) one finds

$$\lim_{m \to \infty} \int_0^t p(U^{-\lfloor ms \rfloor}) \, ds = \lim_{m \to \infty} \frac{t}{m} \sum_{k=1}^m p(U^{-k}) = t \, \int_{\langle U \rangle} p(u) \, du \tag{4.19}$$

uniformly for t < T, where du denotes the Haar measure on $\langle U \rangle$. Applied to (4.11), (4.12), (4.13) this yields (4.15), (4.16) and (4.17). \Box

Let $f(n) \in \mathbb{N}$ with $\lim_{n\to\infty} f(n) = \infty$ and $\lim_{n\to\infty} f(n)n^{-s} = 0$, then by Proposition 4.1 and 4.2 we find for large enough *K* that $X_{1/\sqrt{n}, f(n)}^K \Longrightarrow \begin{pmatrix} 0 & 0 \\ 0 & \mathbf{1}_{d_1} \end{pmatrix} X_0$ where we used a subdivision in blocks of sizes d_0 and d_1 . For sake of concreteness let us set $f(n) = \lfloor n^{\alpha} \rfloor$ with some $0 < \alpha < s$. From (4.5) we find for $m \to \infty$,

$$\mathbb{P}\left((X_{1/\sqrt{m},n}^{K}, Z_{1/\sqrt{m},n}^{K}) \in G_m \text{ for all } Tm > n > f(m)\right) \to \mathbb{1}$$

Together with Proposition 4.3 we see that the stopped processes $(X_{1/\sqrt{m},n}^{K}, Z_{1/\sqrt{m},n}^{K})$ for n = 1, ..., mT satisfy the conditions of Proposition 2.1 with $\tilde{X}_{n}^{m} = P_{1}X_{1/\sqrt{m},n}^{K}$, the good sets G_{m} and $f(m) = \lfloor m^{\alpha} \rfloor$. Thus, with Proposition 4.1 it follows $X_{1/\sqrt{m}, \lfloor tm \rfloor}^{K} \Longrightarrow \begin{pmatrix} \mathbf{0} \\ \Lambda_{t}^{K} \end{pmatrix} X_{0}$, uniformly for 0 < t < T, where $\Lambda_{t}^{K} = \Lambda_{t \wedge T_{k}}$ denotes the stopped process of Λ_{t} as described in Theorem 1.1 with stopping time T_{K} when $\|P_{1}\Lambda_{t}X_{0}\| > K$. As we

have this convergence for all such stopping times T_K , $||P_1 \Lambda_t X_0||$ is almost surely finite and as the final time T was arbitrary, one obtains $X_{1/\sqrt{m}, \lfloor tm \rfloor} \Longrightarrow \begin{pmatrix} \mathbf{0} \\ \Lambda_t \end{pmatrix} X_0$ for any t > 0. Together with Proposition 3.2 this finishes the proof of Theorem 1.1.

5. Application to Random Schrödinger Operators

The main purpose of this section is the proof of Theorem 1.2. However, we will also obtain a description for limits of eigenvalue processes in a critical scaling. For this we will consider slightly more general operators as (1.17). More precisely, we study the limiting eigenvalue process for $n \to \infty$ with $\lambda^2 n$ constant and *d* fixed for more general random $nd \times nd$ matrices given by

$$(H_{\lambda,n}\psi)_k = \psi_{k+1} + \psi_{k-1} + (A + \lambda V_k)\psi_k$$
(5.1)

where $\psi = (\psi_1, \ldots, \psi_n)$, $\psi_0 = \psi_{n+1} = 0$ and $\psi_j \in \mathbb{C}^d$. Here, *A* is a general Hermitian matrix, and the V_k are general i.i.d. Hermitian matrices with $\mathbb{E}(V_k) = \mathbf{0}$ and $\mathbb{E}(||V_k||^{6+\varepsilon}) < \infty$. We dropped the index *d* now as *d* will be fixed from now on and sometimes we may also drop the index *n*. Moreover, for simplicity, we can assume that *A* is diagonal; indeed, this can be achieved by the change of basis $\psi_n \mapsto O^* \psi_n$ where O^*AO diagonalize *A* (and replaces V_n by O^*V_nO).

The eigenvalue equation $H_{\lambda}\psi = E\psi$ is a recursion that can be written in the matrix form as follows.

$$\begin{pmatrix} \psi_{k+1} \\ \psi_k \end{pmatrix} = T_k \begin{pmatrix} \psi_k \\ \psi_{k-1} \end{pmatrix} \quad \text{where} \quad T_k = T_{\lambda,k}^E = \begin{pmatrix} E\mathbf{1} - A - \lambda V_k & -\mathbf{1} \\ \mathbf{1} & \mathbf{0} \end{pmatrix}. \tag{5.2}$$

The $T_{\lambda,k}^E$ are called transfer matrices. Now, *E* is an eigenvalue of $H_{\lambda,n}$ if there is a nonzero solution (ψ_1, ψ_n) to

$$\begin{pmatrix} 0\\\psi_n \end{pmatrix} = T_n \cdots T_1 \begin{pmatrix} \psi_1\\0 \end{pmatrix}$$

or equivalently, when the determinant of the top left $d \times d$ block of $T_n \cdots T_1$ vanishes. So we can study the eigenvalue equation through the products

$$T_{[1,k]} = T_k \cdots T_1$$

which are the focus of our next theorems.

5.1. Elliptic and hyperbolic channels and SDE limits. The matrices T_k satisfy

$$T^*\mathcal{J}T = \mathcal{J}$$
 where $\mathcal{J} = \begin{pmatrix} \mathbf{0} & \mathbf{1}_d \\ -\mathbf{1}_d & \mathbf{0} \end{pmatrix}$,

the definition of elements of the hermitian symplectic group HSp(2d). In particular, they are all invertible. The T_k are all perturbations of the noiseless matrix

$$T_* := T_{0,1}^E$$

This matrix is also block diagonal with d blocks of size 2, and the eigenvalues of $T_{0,1}^E$ are exactly the 2d solutions of the d quadratics

$$z + z^{-1} = E - a_i$$
, a_i is an eigenvalue of A.

So the solutions are on the real line or on the complex unit circle, depending on whether $|E - a_j|$ is less or more than two. We call the corresponding generalized eigenspaces of $T_* = T_{0,1}^E$ elliptic (<2), parabolic (=2) and hyperbolic (>2) channels. Elliptic and hyperbolic channels correspond to two-dimensional eigenspaces, while parabolic channels correspond to a size 2 Jordan block. Traditionally, this notation refers to the solutions of the noiseless ($\lambda = 0$) recursion that are supported in these subspaces for every coordinate ψ_n .

Pick an energy E, such that there are no parabolic channels and at least one elliptic channel. Suppose that A is diagonalized so that $|E - a_j| > 2$ for $j = 1, ..., d_h$ and $|E - a_j| < 2$ for $j > d_h$. Correspondingly, we define the hyperbolic eigenvalues γ_j and elliptic eigenvalues z_j of T_* by

$$\gamma_j + \gamma_j^{-1} = E - a_j, \qquad |\gamma_j| < 1, \qquad \text{for } j = 1, \dots, d_h$$

 $z_j + z_j^{-1} = E - a_{j+d_h}, \qquad |z_j| = 1, \text{ Im}(z_j) > 0, \qquad \text{for } j = 1, \dots, d_e = d - d_h.$

Furthermore we define the diagonal matrices

$$\Gamma = \operatorname{diag}(\gamma_1, \dots, \gamma_{d_h}), \quad Z = \operatorname{diag}(z_1, \dots, z_{d_e}). \tag{5.3}$$

In order to complete the description of the limiting eigenvalue process, we need to consider a family of limiting SDE by varying the energy in the correct scaling. More precisely, define the $2d_e \times 2d_e$ unitary matrix U and the $2d \times 2d$ matrix Q by

$$U = \begin{pmatrix} \bar{Z} \\ & Z \end{pmatrix}, \quad \mathcal{Q} = \begin{pmatrix} \Gamma & & \Gamma^{-1} \\ & \bar{Z} & Z \\ \mathbf{1}_{d_h} & & & \mathbf{1}_{d_h} \\ & & \mathbf{1}_{d_e} & \mathbf{1}_{d_e} \end{pmatrix}$$
(5.4)

so that Q diagonalizes T_* to a form as in (1.2) that is used for Theorem 1.1

$$\mathcal{T}_* := \mathcal{Q}^{-1} T_* \mathcal{Q} = \begin{pmatrix} \Gamma & & \\ & U & \\ & & \Gamma^{-1} \end{pmatrix}.$$

Furthermore, let

$$\mathcal{T}_{k} = \mathcal{T}_{\lambda,k}^{\varepsilon,\sigma} := \mathcal{Q}^{-1} \, \mathcal{T}_{\lambda,k}^{E+\lambda^{2}\varepsilon} \, \mathcal{Q} = \mathcal{T}_{*} + \lambda \sigma \, \mathcal{V}_{k} + \lambda^{2} \varepsilon \mathcal{W} \,, \quad \mathcal{T}_{[1,k]} = \mathcal{T}_{\lambda,[1,k]}^{\varepsilon,\sigma} := \mathcal{T}_{k} \cdots \mathcal{T}_{1}$$
(5.5)

with

$$\mathcal{V}_{k} = \mathcal{Q}^{-1} \begin{pmatrix} -V_{k} \\ \mathbf{0} \end{pmatrix} \mathcal{Q}, \quad \mathcal{W} = \mathcal{Q}^{-1} \begin{pmatrix} \mathbf{1}_{d} \\ \mathbf{0} \end{pmatrix} \mathcal{Q}.$$
(5.6)

The parameter σ is somewhat redundant, however, it will be useful for replicating the argument of [VV1] where this scaling parameter was also introduced. The scaling $\varepsilon \lambda^2 \sim \varepsilon/n$ means that a unit interval of ε should contain a constant order of eigenvalues. In order to get limiting SDEs we consider a Schur complement as before, thus define the $2d_e \times 2d_e$ matrices

$$\widehat{\mathcal{T}}_{\lambda,n}^{\varepsilon,\sigma} = \left(\mathcal{P}_{\leq 1}^{\varepsilon} \left[\mathcal{T}_{\lambda,[1,n]}^{\varepsilon,\sigma} \mathcal{X}_{0}\right]^{-1} \mathcal{P}_{\leq 1}\right)^{-1} \quad \text{with} \quad \mathcal{P}_{\leq 1} = \begin{pmatrix} \mathbf{1}_{d_{h}+2d_{e}} \\ \mathbf{0}_{d_{h} \times (d_{h}+2d_{e})} \end{pmatrix}$$
(5.7)

Then by Theorem 1.1 we obtain the correlated family (parameters σ , ε) of limiting processes

$$\begin{pmatrix} \mathbf{0}_{d_h} \\ U^{-\lfloor tn \rfloor} \end{pmatrix} \widehat{\mathcal{T}}_{1/\sqrt{n}, \lfloor tn \rfloor}^{\varepsilon, \sigma} \Longrightarrow \begin{pmatrix} \mathbf{0}_{d_h} \\ \Lambda_t^{\varepsilon, \sigma} \end{pmatrix} \begin{pmatrix} \mathcal{P}_{\leq 1}^* \mathcal{X}_0^{-1} \mathcal{P}_{\leq 1} \end{pmatrix}^{-1} \quad \text{for } n \to \infty, \quad (5.8)$$

where for fizzed (ε, σ) , the process $\Lambda_t^{\varepsilon, \sigma}$ satisfies some SDE in t.

Remark 5.1. For $\varepsilon = 0$ and $\sigma = 1$, up to some conjugation, the matrix $\widehat{T}_{\lambda,n}^{0,1}$ corresponds to the reduced transfer matrix as introduced in [Sa1] for the scattering of a block described by H_{λ} of a finite length *n* inserted into a cable described by H_0 of infinite length ('*n* = ∞ '). Thus we obtain that in the limit $\lambda^2 n = \text{const.}, n \to \infty$, the process of the reduced transfer matrix as defined in [Sa1] is described by a SDE, proving Conjecture 1 in [Sa1].

To get to the GOE limit we need to express the limit SDEs more explicitly. Therefore, let us split the potential V_1 into the hyperbolic and elliptic parts, i.e. let

$$V_1 = \begin{pmatrix} V_h & V_{he} \\ V_{he}^* & V_e \end{pmatrix} \quad \text{where} \quad V_h \in \operatorname{Mat}(d_h \times d_h), \quad V_e \in \operatorname{Mat}(d_e \times d_e).$$
(5.9)

Moreover, define

$$Q = \int_{\langle Z \rangle} \mathbf{z} \mathbb{E} (V_{he}^* (\Gamma^{-1} - \Gamma)^{-1} V_{he}) \, \bar{\mathbf{z}} \, d\mathbf{z}, \quad \mathcal{S} = \begin{pmatrix} (\bar{Z} - Z)^{-1} & \mathbf{0} \\ \mathbf{0} & (\bar{Z} - Z)^{-1} \end{pmatrix} \quad (5.10)$$

where $d\mathbf{z}$ denotes the Haar measure on the compact Abelian group $\langle Z \rangle$ generated by the diagonal, unitary matrix Z. As we will see, Q will give rise to a drift term coming from the hyperbolic channels. In fact, this is the only influence of the hyperbolic channels for the limit process. Moreover, to simplify expressions, we will be interested in one specific case.

Definition. We say that the matrix $Z = \text{diag}(z_1, \ldots, z_{d_e})$ with $|z_j| = 1$, $\text{Im}(z_j) > 0$ is **chaotic**, if all of the following apply for all $i, j, k, l \in \{1, \ldots, d_e\}$,

$$z_i z_j z_k z_l \neq 1, \quad \overline{z}_i z_j z_k z_l \neq 1$$

$$\overline{z}_i \overline{z}_j z_k z_l \neq 1 \quad \text{unless } \{i, j\} = \{k, l\}.$$

The following observation corresponds to Lemma 8 in [VV1].

Lemma 5.2. Let the eigenvalues a_j , j = 1, ..., d of A be simple and let I be the interval with fixed hyperbolic and elliptic channels as considered, i.e.

$$I = \{E \in \mathbb{R} : |E - a_j| > 2 \text{ for } j = 1, \dots, d_h \text{ and } |E - a_j| < 2 \text{ for } j > d_h \}.$$

Then, for Lebesgue almost all $E \in I$, the matrix Z as defined above is chaotic and moreover, for any diagonal, unitary matrix Z_* there is a sequence n_k such that $Z^{n_k+1} \rightarrow Z_*$.

Proof. By the definitions above, $z_j = e^{i\varphi_j}$ where $\varphi_j = \arccos((E - a_{j+d_h})/2) \in (-\pi, \pi)$. We will show that for almost all *E*, the vector $\varphi = \varphi(E) = (\varphi_1, \dots, \varphi_{d_e})$ has no non-zero integer vector orthogonal to it. It is not difficult to see that *Z* is chaotic in this case and the orbit Z^n is dense in the torus of diagonal unitary matrices.

It is enough to show that for any non-zero integer vector w the set of energies $E \in I$ where $w \cdot \varphi(E) = 0$ is finite. Clearly, $E \mapsto w \cdot \varphi(E)$ is analytic on I and therefore it either has finitely many zeros or is constant zero. Taking the derivative with respect to E we get

$$(w \cdot \varphi(E))' = \sum_{j=1}^{d_e} \frac{-w_j}{\sqrt{1 - \frac{1}{4}(E - a_{j+d_h})^2}}.$$

As all the values a_{j+d_h} are different, each summand has a singularity at a different value. Hence, this derivative can only be identically zero on I if w is the zero vector. Thus, for $w \neq 0, E \mapsto w \cdot \varphi(E)$ is not the zero function. \Box

Proposition 5.3. (i) The family of processes $\Lambda_t^{\varepsilon,\sigma}$ as in Eq. (5.8) or Theorem 5.4 satisfy SDEs of the form

$$d\Lambda_t^{\varepsilon,\sigma} = S \begin{pmatrix} \varepsilon \mathbf{1} - \sigma^2 Q \\ -\varepsilon \mathbf{1} + \sigma^2 Q \end{pmatrix} \Lambda_t^{\varepsilon,\sigma} dt + \sigma S \begin{pmatrix} d\mathcal{A}_t & d\mathcal{B}_t \\ -d\mathcal{B}_t^* & -d\mathcal{C}_t \end{pmatrix} \Lambda_t^{\varepsilon,\sigma}$$
(5.11)

with $\Lambda_0^{\varepsilon,\sigma} = \mathbf{1}$ and σ, ε fixed, where $\mathcal{A}_t, \mathcal{B}_t, \mathcal{C}_t$ are jointly Gaussian complex-valued $d_e \times d_e$ matrix Brownian motions, independent of ε and σ , with $\mathcal{A}_t^* = \mathcal{A}_t, \mathcal{C}_t^* = \mathcal{C}_t$ and certain covariances.

(ii) If A and V_n are real symmetric then we obtain

$$C_t = \overline{\mathcal{A}_t} = \mathcal{A}_t^\top \quad and \quad \mathcal{B}_t^\top = \mathcal{B}_t.$$

(iii) If Z is chaotic then \mathcal{B}_t is independent of \mathcal{A}_t and \mathcal{C}_t . Also, \mathcal{A}_t and \mathcal{C}_t have the same distribution. Moreover, with the subscript t dropped, we have the following:

$$\mathbb{E}|\mathcal{A}_{ij}|^{2} = \mathbb{E}|\mathcal{B}_{ij}|^{2} = t \mathbb{E}|(V_{e})_{ij}|^{2}$$

$$\mathbb{E}(\mathcal{A}_{ii}\mathcal{A}_{kk}) = t \mathbb{E}((V_{e})_{ii}(V_{e})_{kk}),$$

$$\mathbb{E}(\mathcal{A}_{ij}\mathcal{C}_{ij}) = \mathbb{E}(\mathcal{A}_{ij}\overline{\mathcal{C}}_{ji}) = \mathbb{E}(\mathcal{B}_{ij}\overline{\mathcal{B}}_{ji}) = t \mathbb{E}((V_{e})_{ij})^{2}$$

and whenever $\{i, j\} \neq \{k, l\}$ one finds

$$\mathbb{E}(\mathcal{A}_{ij}\mathcal{A}_{kl}) = \mathbb{E}(\mathcal{A}_{ij}\mathcal{C}_{kl}) = \mathbb{E}(\mathcal{B}_{ij}\mathcal{B}_{kl}) = 0$$

and for any i, j, k, l,

$$\mathbb{E}(\mathcal{B}_{i\,i}\mathcal{B}_{kl})=0.$$

All other covariances are obtained from $A_t = A_t^*$, $C_t = C_t^*$.

Proof. Let us stick to the case $\sigma = 1$. Note that

$$Q^{-1} = S_{\Gamma,Z} \begin{pmatrix} \mathbf{1}_{d_h} & \mathbf{0} & -\Gamma^{-1} & \mathbf{0} \\ \mathbf{0} & \mathbf{1}_{d_e} & \mathbf{0} & -Z \\ \mathbf{0} & -\mathbf{1}_{d_e} & \mathbf{0} & \bar{Z} \\ -\mathbf{1}_{d_h} & \mathbf{0} & \Gamma & \mathbf{0} \end{pmatrix}$$
(5.12)

where

$$S_{\Gamma,Z} = \begin{pmatrix} -S_{\Gamma} & & \\ & S_{Z} & \\ & & -S_{\Gamma} \end{pmatrix}, \quad S_{\Gamma} = (\Gamma^{-1} - \Gamma)^{-1}, \quad S_{Z} = (\bar{Z} - Z)^{-1} \quad (5.13)$$

we chose the sign on S_{Γ} this way, so that $S_{\Gamma} > 0$ is a positive diagonal matrix. With (5.6) and (5.9) this leads to

$$\mathcal{V}_{1} = \mathcal{S}_{\Gamma,Z} \begin{pmatrix} -V_{h}\Gamma & -V_{he}\bar{Z} & -V_{he}Z & -V_{h}\Gamma^{-1} \\ -V_{he}^{*}\Gamma & -V_{e}\bar{Z} & -V_{e}Z & -V_{he}^{*}\Gamma^{-1} \\ V_{he}^{*}\Gamma & V_{e}\bar{Z} & V_{e}Z & V_{he}^{*}\Gamma^{-1} \\ V_{h}\Gamma & V_{he}\bar{Z} & V_{he}Z & V_{h}\Gamma^{-1} \end{pmatrix}, \quad \mathcal{W} = \mathcal{S}_{\Gamma,Z} \begin{pmatrix} \Gamma & \mathbf{0} & \mathbf{0} & \Gamma^{-1} \\ \mathbf{0} & \bar{Z} & Z & \mathbf{0} \\ \mathbf{0} & -\bar{Z} & -Z & \mathbf{0} \\ -\Gamma & \mathbf{0} & \mathbf{0} & \Gamma^{-1} \end{pmatrix}$$
(5.14)

In the notations as introduced in Sect. 1 and used for Theorem 1.1 we have $\Gamma_2 = \Gamma$ and

$$V_{\lambda,11}U^* = \mathcal{S}\left(\begin{pmatrix} -V_e & -V_e \\ V_e & V_e \end{pmatrix} + \lambda \epsilon \begin{pmatrix} \mathbf{1}_{d_e} & \mathbf{1}_{d_e} \\ -\mathbf{1}_{d_e} & -\mathbf{1}_{d_e} \end{pmatrix}\right)$$
(5.15)

$$V_{\lambda,12}\Gamma V_{\lambda,21}U^* = \mathcal{S} \begin{pmatrix} V_{he}^* S_{\Gamma} V_{he} & V_{he}^* S_{\Gamma} V_{he} \\ -V_{he}^* S_{\Gamma} V_{he} & -V_{he}^* S_{\Gamma} V_{he} \end{pmatrix}$$
(5.16)

with S as in (5.10). In order to calculate the drift term, note that using the definition of Q in (5.10) we obtain

$$\int_{\langle Z \rangle} \begin{pmatrix} \mathbf{z} \ \mathbf{0} \\ \mathbf{0} \ \mathbf{z} \end{pmatrix} \mathbb{E} \begin{pmatrix} \varepsilon \mathbf{1} - V_{he}^* S_{\Gamma} V_{he} & \varepsilon \mathbf{1} - V_{he}^* S_{\Gamma} V_{he} \\ -\varepsilon \mathbf{1} + V_{he}^* S_{\Gamma} V_{he} & -\varepsilon \mathbf{1} + V_{he}^* S_{\Gamma} V_{he} \end{pmatrix} \begin{pmatrix} \mathbf{\bar{z}} \ \mathbf{0} \\ \mathbf{0} \ \mathbf{z} \end{pmatrix} d\mathbf{z} = \begin{pmatrix} \varepsilon \mathbf{1} - Q & \mathbf{0} \\ \mathbf{0} & -\varepsilon \mathbf{1} + Q \end{pmatrix}$$

where we used that for any $d_e \times d_e$ matrix M one finds

$$\int_{\langle Z \rangle} \mathbf{z} \, M \, \mathbf{z} \, d\mathbf{z} = \lim_{n \to \infty} \frac{1}{n} \sum_{k=1}^{n} Z^k M Z^k = \left(\lim_{n \to \infty} \frac{1}{n} \sum_{k=1}^{n} (z_i z_j)^k M_{ij} \right)_{ij} = \mathbf{0}$$

as we have $|z_i z_j| = 1$ and $\operatorname{Im}(z_i) > 0$, $\operatorname{Im}(z_j) > 0$ implying that $z_i z_j \neq 1$ for any $i, j \in \{1, \ldots, d_e\}$. Therefore, application of Theorem 1.1 gives (5.11) with $\mathcal{A}_t = \mathcal{A}_t^*$, $\mathcal{C}_t = \mathcal{C}_t^*$. In order to express the covariances as described by (1.12) in more detail recall $Z = \operatorname{diag}(z_1, \ldots, z_{d_e}), |z_j| = 1$, leading to

$$\int_{\langle Z \rangle} \prod_{j=1}^{d_e} \mathbf{z}_{jj}^{n_j} d\mathbf{z} = \chi \left(\prod_{j=1}^{d_e} z_j^{n_j} \right) \quad \text{with} \quad \chi(z) = \begin{cases} 1 & \text{for } z = 1 \\ 0 & \text{else} \end{cases}$$
(5.17)

where \mathbf{z}_{jj} is the *j*-th diagonal entry of the diagonal matrix $\mathbf{z} \in \langle Z \rangle$, and n_j are integers. This leads to the following covariances,

$$\mathbb{E}((\mathcal{A}_{t})_{ij}(\mathcal{A}_{t})_{kl}) = \mathbb{E}((\mathcal{A}_{t})_{ji}(\mathcal{A}_{t})_{kl}) = \mathbb{E}((\mathcal{C}_{t})_{ij}(\mathcal{C}_{t})_{kl}) = \mathbb{E}((\mathcal{C}_{t})_{ji}(\mathcal{C}_{t})_{kl})$$

$$= t \mathbb{E}((V_{e})_{ij}(V_{e})_{kl}) \chi(\bar{z}_{i}z_{j}\bar{z}_{k}z_{l});$$

$$\mathbb{E}((\mathcal{B}_{t})_{ij}(\mathcal{B}_{t})_{kl}) = t \mathbb{E}((V_{e})_{ij}(V_{e})_{kl}) \chi(z_{i}z_{j}z_{k}z_{l});$$

$$\mathbb{E}((\overline{\mathcal{B}_{t}})_{ij}(\mathcal{B}_{t})_{kl}) = t \mathbb{E}((\overline{V_{e}})_{ij}(V_{e})_{kl}) \chi(\bar{z}_{i}\bar{z}_{j}z_{k}z_{l}).$$

The correlations between the Brownian motions are given by

$$\mathbb{E}((\mathcal{A}_t)_{ij}(\mathcal{C}_t)_{kl}) = \mathbb{E}((\overline{\mathcal{A}_t})_{ji}(\mathcal{C}_t)_{kl}) = t \mathbb{E}((V_e)_{ij}(V_e)_{kl}) \chi(z_i \bar{z}_j \bar{z}_k z_l);$$

$$\mathbb{E}((\mathcal{A}_t)_{ij}(\mathcal{B}_t)_{kl}) = \mathbb{E}((\overline{\mathcal{A}_t})_{ji}(\mathcal{B}_t)_{kl}) = t \mathbb{E}((V_e)_{ij}(V_e)_{kl}) \chi(z_i \bar{z}_j z_k z_l);$$

$$\mathbb{E}((\mathcal{C}_t)_{ij}(\mathcal{B}_t)_{kl}) = \mathbb{E}((\overline{\mathcal{C}_t})_{ji}(\mathcal{B}_t)_{kl}) = t \mathbb{E}((V_e)_{ij}(V_e)_{kl}) \chi(\bar{z}_i z_j z_k z_l).$$

This shows part (i) for $\sigma = 1$. Changing V_1 to σV_1 immediately gives the general case. If V_e is almost surely real, which is the case if O^*V_1O is almost surely real, then one has $C_t = \overline{A}_t$ and $\mathcal{B}_t = \mathcal{B}_t^{\top}$ giving part (ii). Part (iii) follows from using the chaoticity assumption in the equations for the covariances. \Box

5.2. Limiting eigenvalue statistics. The convergence to the SDE limit as in (5.8) should firstly be interpreted for fixed ε and σ . However, considering direct sums of matrices for finitely many pairs (ε , σ) one obtains joint convergence to a random field (ε , σ , t) $\mapsto \Lambda_t^{\varepsilon,\sigma}$ in terms of finite dimensional distributions. For fixed σ , t, the left hand side of (5.8) is clearly analytic in $\varepsilon \in \mathbb{C}$. Moreover, all estimates made for the general setup are uniform for ε varying in compact sets. Using the bounds (3.13) and (3.26) we can therefore apply [VV1, Corollary 15] and see that for fixed σ and t there is a unique² version such that $\varepsilon \mapsto \Lambda_t^{\varepsilon,\sigma}$ is analytic. In particular, using this analytic version, we can define the random set { $\varepsilon \in \mathbb{C}$: $f(\Lambda_t^{\varepsilon,\sigma}) = 0$ } for fixed (σ , t) and an analytic function $f : \text{Mat}(d, \mathbb{C}) \to \mathbb{C}$. Unless $f(\Lambda_t^{\varepsilon,\sigma})$ is the zero function in ε , this random set consists of isolated points by analyticity and can be seen as a point process which we may denote by zeros_{ε} $f(\Lambda_t^{\varepsilon,\sigma})$.

Theorem 5.4. Consider the process $\mathcal{E}_{\sigma,n}$ of eigenvalues of $n(H_{\frac{\sigma}{\sqrt{n}},n} - E)$ and let n_k be an increasing sequence such that $Z^{n_k+1} \to Z_*$ for $k \to \infty$ with Z being the unitary, diagonal $d_e \times d_e$ matrix defined in (5.3). Then, \mathcal{E}_{σ,n_k} converges to the zero process of the determinant of a $d_e \times d_e$ matrix,

$$\mathcal{E}_{\sigma,n_k} \Longrightarrow \operatorname{zeros}_{\varepsilon} \det \left(\left(\bar{Z}_* \ Z_* \right) \Lambda_1^{\varepsilon,\sigma} \begin{pmatrix} \mathbf{1}_{d_e} \\ -\mathbf{1}_{d_e} \end{pmatrix} \right).$$

Proof. Without loss of generality we restrict to the case $\sigma = 1$. We won't need the precise form of the limit SDE but it is important how we obtain this SDE. Therefore we need to look at the matrix parts giving the Schur complement as in the proof of Theorem 1.1. Hence, using U and $\mathcal{T}_{\lambda,[1,n]}^{\varepsilon,1}$ as above let

$$\mathcal{R} = egin{pmatrix} \mathbf{1}_{d_h} & \ & U \ & \mathbf{1}_{d_h} \end{pmatrix}, \quad \mathcal{X}_0 = egin{pmatrix} \mathbf{1}_{d_h} & \mathbf{0} & -\mathbf{1}_{d_h} \ & \mathbf{0} & \mathbf{1}_{2d_e} & \mathbf{0} \ & \mathbf{0} & \mathbf{0} & \mathbf{1}_{d_h} \end{pmatrix}$$

² Unique in the sense of a uniquely induced distribution on the set of analytic functions.

and

$$\mathcal{X}_{\lambda,n}^{\varepsilon} = \mathcal{R}^{-n} \mathcal{T}_{\lambda,[1,n]}^{\varepsilon,1} \mathcal{X}_0.$$
(5.18)

Using blocks of sizes $d_h + 2d_e$ and d_h , let

$$\mathcal{X}_{\lambda,n}^{\varepsilon} = \begin{pmatrix} A_{\lambda,n}^{\varepsilon} & B_{\lambda,n}^{\varepsilon} \\ C_{\lambda,n}^{\varepsilon} & D_{\lambda,n}^{\varepsilon} \end{pmatrix}, \quad X_{\lambda,n}^{\varepsilon} = A_{\lambda,n}^{\varepsilon} - B_{\lambda,n}^{\varepsilon} (D_{\lambda,n}^{\varepsilon})^{-1} C_{\lambda,n}^{\varepsilon}.$$
(5.19)

Then by Theorem 1.1, $X_{\varepsilon,1/\sqrt{n},\lfloor tn \rfloor} \Longrightarrow \begin{pmatrix} \mathbf{0} \\ \Lambda_t^{\varepsilon} \end{pmatrix}$, with the process $\Lambda_t^{\varepsilon} = \Lambda_t^{\varepsilon,1}$ as in (5.8) and Theorem 5.4. Let us define

$$\Theta_0 := \mathcal{X}_0^{-1} \mathcal{Q}^{-1} \begin{pmatrix} \mathbf{1}_d \\ \mathbf{0} \end{pmatrix} \begin{pmatrix} \mathbf{0} & \Gamma^{-1} - \Gamma \\ (\bar{Z} - Z) & \mathbf{0} \end{pmatrix} = \begin{pmatrix} \mathbf{0} & \mathbf{0} \\ \mathbf{1}_{d_e} & \mathbf{0} \\ -\mathbf{1}_{d_e} & \mathbf{0} \\ \mathbf{0} & \mathbf{1}_{d_h} \end{pmatrix}$$
(5.20)

as well as

$$M_{\lambda,n}^{\varepsilon} = \begin{pmatrix} \mathbf{1}_{d_{e}} & \mathbf{0} \\ -\left(D_{\lambda,n}^{\varepsilon}\right)^{-1} C_{\lambda,n}^{\varepsilon} \begin{pmatrix} \mathbf{0} \\ \mathbf{1}_{d_{e}} \\ -\mathbf{1}_{d_{e}} \end{pmatrix} (D_{\lambda,n}^{\varepsilon})^{-1} \end{pmatrix} \in \mathrm{GL}(d,\mathbb{C})$$
(5.21)

Then,

$$\mathcal{X}_{\lambda,n}^{\varepsilon} \Theta_0 M_{\lambda,n}^{\varepsilon} = \begin{pmatrix} X_{\lambda,n}^{\varepsilon} \begin{pmatrix} \mathbf{0} \\ \mathbf{1} \\ -\mathbf{1} \end{pmatrix} B_{\lambda,n}^{\varepsilon} (D_{\lambda,n}^{\varepsilon})^{-1} \\ \mathbf{0} & \mathbf{1}_{d_h} \end{pmatrix}$$
(5.22)

Let us also define

$$\Theta_n^* := \begin{pmatrix} \mathbf{0} & \mathbf{1}_{d_e} \\ \Gamma^{-1} & \mathbf{0} \end{pmatrix} \begin{pmatrix} \mathbf{1}_d & \mathbf{0} \end{pmatrix} \mathcal{QR}^n = \begin{pmatrix} \mathbf{0} & \bar{Z}^{n+1} & Z^{n+1} & \mathbf{0} \\ \mathbf{1}_{d_h} & \mathbf{0} & \mathbf{0} & \mathbf{1}_{d_h} \end{pmatrix}.$$
 (5.23)

An energy $E + \lambda^2 \varepsilon$ is an eigenvalue of $H_{\lambda,n}$, precisely if there is a solution to the eigenvalue equation with $\psi_0 = 0$ and $\psi_{n+1} = 0$, i.e. if and only if

$$\det\left(\begin{pmatrix} \mathbf{1}_d \ \mathbf{0} \end{pmatrix} \mathcal{T}_{\lambda,[1,n]}^{E+\lambda^2\varepsilon} \begin{pmatrix} \mathbf{1}_d \\ \mathbf{0} \end{pmatrix}\right) = 0.$$
 (5.24)

As $\mathcal{T}_{\lambda,[1,n]}^{E+\lambda^2\varepsilon} = \mathcal{QR}^n \mathcal{X}_{\lambda,n}^{\varepsilon} \mathcal{X}_0^{-1} \mathcal{Q}^{-1}$, this is equivalent to

$$\det\left(\Theta_{n}^{*}\mathcal{X}_{\lambda,n}^{\varepsilon}\Theta_{0}M_{\lambda,n}^{\varepsilon}\right) = 0$$
(5.25)

Using Theorem 1.1, (5.22) and (5.23), we see that along a subsequence n_k of the positive integers where Z^{n_k+1} converges to Z_* , we find for $\lambda_k = 1/\sqrt{n_k}$

$$\Theta_{n_k}^* \mathcal{X}_{\lambda_k, n_k}^{\varepsilon} \Theta_0 M_{\lambda_k, n_k}^{\varepsilon} \Longrightarrow \begin{pmatrix} (\bar{Z}_* \ Z_*) \Lambda_1^{\varepsilon} \begin{pmatrix} \mathbf{1}_{d_e} \\ -\mathbf{1}_{d_e} \end{pmatrix} & \mathbf{0} \\ \mathbf{0} & \mathbf{1}_{d_h} \end{pmatrix}.$$
(5.26)

As already established above, there is a unique holomorphic version of the random process $\varepsilon \mapsto \Lambda_{\varepsilon,1}$. In fact, using uniform boundedness of Θ_n as well as (5.22) and the bounds (3.13), (3.26) we find that $\mathbb{E} \| \Theta_{n_k}^* \mathcal{X}_{\varepsilon,\lambda_k,n_k} \Theta_0 M_{\varepsilon,\lambda_k,n_k} \|$ is uniformly bounded for

 $\varepsilon \in \mathbb{C}$ varying in a compact set. Hence, we can apply [VV1, Corollary 15] to obtain again the existence of a unique analytic version in ε for the right hand side. Moreover, we find a realization of all random processes on the same probability space but with local-uniform convergence in ε in the Eq. (5.26) (Skorokhod embedding theorem). As the determinant is a holomorphic function, the same is true for the determinants of these matrices. As long as the (random) holomorphic determinant of the right hand side is not identically zero the local uniform convergence also implies that the discrete level sets of zeros of the determinants converge in the vague sense, i.e. the counting measures integrated against continuous, compactly supported functions converge. It is possible that certain zeros go off to infinity and disappear in the limit.

Hence, it is left to show that det $((\bar{z}_* z_*) \Lambda_1^{\varepsilon} \begin{pmatrix} 1 \\ -1 \end{pmatrix})$ is (almost surely) not identically zero in ε . Now, (5.11) can be rewritten as

$$\begin{pmatrix} \mathbf{1} \\ -\mathbf{1} \end{pmatrix} \mathcal{S}^{-1} d\Lambda_t^{\varepsilon} + \begin{pmatrix} \mathcal{Q} \\ \mathcal{Q} \end{pmatrix} \Lambda_t^{\varepsilon} dt + \begin{pmatrix} d\mathcal{A}_t & d\mathcal{B}_t \\ d\mathcal{B}_t^* & -d\mathcal{C}_t \end{pmatrix} \Lambda_t^{\varepsilon} = \varepsilon \Lambda_t^{\varepsilon} dt$$

which is the transfer matrix equation (fundamental solution) for the eigenvalue equation $D\psi = \varepsilon \psi$ where D is the random operator

$$\mathcal{D}\psi(t) = \left[\begin{pmatrix} \mathbf{1} \\ -\mathbf{1} \end{pmatrix} \mathcal{S}^{-1}\partial_t + \begin{pmatrix} \mathcal{Q} \\ \mathcal{Q} \end{pmatrix} + \begin{pmatrix} d\mathcal{A}_t & d\mathcal{B}_t \\ d\mathcal{B}_t^* & -d\mathcal{C}_t \end{pmatrix} / dt \right] \psi(t)$$

Using the Hölder continuous versions of the Brownian motions leading to measure valued white noise, one can make perfect sense of this random operator \mathcal{D} on $L^2([0, 1]) \otimes \mathbb{C}^{2d_e}$, by choosing the random domain of Hölder continuous functions $\psi(t)$ such that $\mathcal{D}\psi(t)$ (at first defined as a measure in Ito rough-path integration sense) is a continuous function. (A typical procedure for first-order one-dimensional operators with measure-valued potential).

The zero determinant condition above yields an eigenvector ψ satisfying the boundary conditions $\psi(0) = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \psi_1$ (i.e. $\begin{pmatrix} 1 & 1 \end{pmatrix} \psi(0) = 0$) and $(\bar{Z}_* Z_*) \psi(1) = 0$. One can check that the operator is symmetric with these boundary conditions. Indeed, using integration by parts one finds for continuous $\psi(t)$, $\varphi(t)$ in the domain with these boundary conditions, that

$$\int_{0}^{1} (\mathcal{D}\psi(t))^{*}\varphi(t) dt - \int_{0}^{1} \psi^{*}(t)\mathcal{D}\varphi(t) dt = -\left[\psi^{*}(t)\left(\sum_{Z=1}^{S_{Z}^{-1}}\right)\varphi(t)\right]_{0}^{1}$$
$$= \psi^{*}(0)\left(\frac{1}{1}\right)S_{Z}^{-1}(\mathbf{10})\varphi(0) + \psi^{*}(1)\left(\sum_{Z=1}^{Z}\right)S_{Z}^{-1}(\mathbf{0}Z_{*})\varphi(1) = 0$$

In the second line we used the boundary conditions first for φ and then for ψ . Hence, the set of eigenvalues ε of \mathcal{D} with these boundary conditions is a subset of the real line and in fact discrete and it is equal to the zero set in ε of the right hand side of (5.26). \Box

5.3. Limiting GOE statistics. In this subsection we will prove Theorem 1.2 by reduction to the work in [VV1]. Without loss of generality we focus on energies E smaller than 0 and consider r = 1. The more general case needs some more care and notations in the subdivision into elliptic and hyperbolic channels, but the main calculations remain the same. We need to consider the SDE limit as described above a bit more precisely for this particular Anderson model as in (5.1) with $A = \mathbb{Z}_d$ and V_n as in (1.18).

In Proposition 5.3, especially for the definitions of V_h , V_e and V_{he} it was assumed that A is diagonal. So in order to use the calculations above we need to diagonalize \mathbb{Z}_d and see how this unitary transformation changes V_n .

We let $d \ge 2$, then \mathbb{Z}_d is diagonalized by the orthogonal matrix O given by

$$O_{jk} = \sqrt{2/(d+1)} \sin(\pi jk/(d+1)).$$
(5.27)

The corresponding eigenvalue of \mathbb{Z}_d with eigenvector $(O_{1j}, O_{2j} \dots, O_{dj})$, the *j*-th column vector of O, is given by

$$a_j = 2\cos(\pi j/(d+1)), \quad j = 1, \dots, d.$$
 (5.28)

Note that all these eigenvalues are different and Lemma 5.2 is applicable. From now on we will always use an energy E where Z is chaotic.

For -2 < E < 0 there is $d_h < d$ such that

$$2\cos(\pi j/(d+1)) - E > 2$$
 for $j = 1, \dots, d_h$ and (5.29)

$$2 < 2\cos(\pi j/(d+1)) - E < 2$$
 for $j = d_h + 1, \dots, d.$ (5.30)

So we have d_h hyperbolic and $d_e = d - d_h$ elliptic channels and the upper $d_h \times d_h$ block of $O^*\mathbb{Z}_d O$ corresponds to the hyperbolic channels. Using (1.18) and the notations as in (5.9) we have

$$\begin{pmatrix} V_h & V_{he} \\ V_{he}^* & V_e \end{pmatrix} = O^\top \begin{pmatrix} v_1 & \mathbf{0} \\ & \ddots \\ \mathbf{0} & v_d \end{pmatrix} O, \quad \mathbb{E}(v_j) = 0, \quad \mathbb{E}(v_j \, v_k) = \delta_{jk}.$$
(5.31)

Let *E* be such that *Z* is chaotic, then by Proposition 5.3 (iii) we need to consider the following the covariances

$$\mathbb{E}(|(V_e)_{ij}|^2) = \mathbb{E}\left|(O^{\top}V_1O)_{i+d_h, j+d_h}\right|^2 = \langle |O_{i+d_h}|^2, |O_{j+d_h}|^2\rangle$$
(5.32)

$$\mathbb{E}((V_e)_{ii}(V_e)_{jj}) = \mathbb{E}\left((O^{\top}V_1O)_{i+d_h, i+d_h}(O^{\top}V_1O)_{j+d_h, j+d_h}\right) = \langle |O_{i+d_h}|^2, |O_{j+d_h}|^2 \rangle.$$
(5.33)

Here, by $|O_i|^2$ we denote the vector $(|O_{k,i}|^2)_{k=1,...,d}$ and $\langle \cdot, \cdot \rangle$ denotes the scalar product. As stated in [VV1], one finds

$$(d+1) \langle |O_i|^2, |O_j|^2 \rangle = \begin{cases} 3/2 & \text{for } i = j \\ 1 & \text{for } i \neq j. \end{cases}$$
(5.34)

Let us further calculate the drift contribution Q from the hyperbolic channels as introduced above. Using chaoticity, it is not hard to see from (5.10) that Q is diagonal. Moreover one has

$$Q_{jj} = \mathbb{E}(V_{he}^* S_{\Gamma} V_{he})_{jj}) = \sum_{k=1}^{d_h} (S_{\Gamma})_{kk} \mathbb{E}([(V_{he})_{kj}]^2) = \sum_{k=1}^{d_h} \frac{\langle |O_k|^2, |O_{j+d_h}|^2 \rangle}{\gamma_k^{-1} - \gamma_k}.$$
 (5.35)

It follows that Q is a multiple of the unit matrix, more precisely

$$Q = q \mathbf{1}$$
 with $q = \frac{1}{d+1} \sum_{k=1}^{d_h} (\gamma_k^{-1} - \gamma_k)^{-1}$. (5.36)

Note that $|q| < \max_k |\gamma_k^{-1} - \gamma_k| < \max_k |E - a_k| = ||E - A|| = ||E - \mathbb{Z}_d|| \le |E| + 2$ uniformly. Thus, using Proposition 5.3 we obtain the following SDE limits,

$$d\Lambda_t^{\varepsilon,\sigma} = \mathcal{S}\left(\varepsilon - \sigma^2 q\right) \begin{pmatrix} \mathbf{1} & \mathbf{0} \\ \mathbf{0} & -\mathbf{1} \end{pmatrix} \Lambda_t^{\varepsilon,\sigma} dt + \sigma \mathcal{S} \begin{pmatrix} d\mathcal{A}_t & d\mathcal{B}_t \\ -d\mathcal{B}_t^* & -d\overline{\mathcal{A}}_t \end{pmatrix} \Lambda_t^{\varepsilon,\sigma}$$
(5.37)

where A_t and B_t are independent matrix Brownian motions, A_t is Hermitian, B_t complex symmetric, i.e.

$$\mathcal{A}_t^* = \mathcal{A}_t, \quad \mathcal{B}_t^\top = \mathcal{B}_t \tag{5.38}$$

with covariance structure

$$\mathbb{E}(|(\mathcal{B}_t)_{ij}|^2) = \mathbb{E}(|(\mathcal{A}_t)_{ij}|^2) = \mathbb{E}((\mathcal{A}_t)_{ii}(\mathcal{A}_t)_{jj}) = \begin{cases} \frac{3}{2}t/(d+1) & \text{for } i = j\\ t/(d+1) & \text{for } i \neq j \end{cases}.$$
 (5.39)

All covariances which do not follow are zero. Except for the additional drift $\sigma^2 q$ which can be seen as a shift in ε , this is the exact same SDE as it appears in [VV1]. In fact, the matrix S here corresponds to iS^2 as in [VV1] and the process there corresponds to the process above conjugated by $|S|^{1/2}$.

Thus, from now on the proof to obtain the $Sine_1$ kernel and GOE statistics follows precisely the arguments as in [VV1].

First take *E* as in Lemma 5.2 so that *Z* is chaotic, and take a sequence n_k such that $Z^{n_k+1} \to \mathbf{1}$, then, for the point process as in Theorem 5.4 we find $\mathcal{E}_{\sigma,n_k} \Longrightarrow \mathcal{E}_{\sigma} = \operatorname{zeros}_{\varepsilon} \operatorname{det}((11) \Lambda_1^{\varepsilon,\sigma} \begin{pmatrix} 1 \\ -1 \end{pmatrix})$. Defining $\widehat{\Lambda}_t^{\varepsilon,\sigma} = \sigma^{-1}(\Lambda_t^{\varepsilon,\sigma,\sigma} - 1)$ we find

$$\sigma^{-1}\mathcal{E}_{\sigma} = \operatorname{zeros}_{\varepsilon} \det \left((\mathbf{1} \ \mathbf{1}) \widehat{\Lambda}_{\mathbf{1}}^{\varepsilon,\sigma} \begin{pmatrix} \mathbf{1} \\ -\mathbf{1} \end{pmatrix} \right)$$

where $\widehat{\boldsymbol{\Lambda}}_{0}^{\varepsilon}=\boldsymbol{0}$ and

$$d\widehat{\Lambda}_{t}^{\varepsilon,\sigma} = (\varepsilon - \sigma q)\mathcal{S}\begin{pmatrix}\mathbf{1}\\-\mathbf{1}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{\varepsilon,\sigma} + \mathbf{1})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{B}_{t}\\-d\mathcal{B}_{t}^{*} & -d\overline{\mathcal{A}}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{\varepsilon,\sigma} + \mathbf{1})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{B}_{t}\\-d\mathcal{B}_{t}^{*} & -d\overline{\mathcal{A}}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{\varepsilon,\sigma} + \mathbf{1})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{B}_{t}\\-d\mathcal{B}_{t}^{*} & -d\overline{\mathcal{A}}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{*})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{A}_{t}\\-d\mathcal{A}_{t}^{*} & -d\overline{\mathcal{A}}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{*})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{A}_{t}\\-d\mathcal{A}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{*})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{A}_{t}\\-d\mathcal{A}_{t} & -d\overline{\mathcal{A}}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{*})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{A}_{t}\\-d\mathcal{A}_{t} & -d\overline{\mathcal{A}}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{*})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{A}_{t}\\-d\mathcal{A}_{t} & -d\overline{\mathcal{A}}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{*})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{A}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{t}^{*})dt + \mathcal{S}\begin{pmatrix}d\mathcal{A}_{t} & d\mathcal{A}_{t}\end{pmatrix}(\sigma\widehat{\Lambda}_{$$

By [SV, Theorem 11.1.4] this SDE converges for $\sigma \to 0$ to the solution of the SDE with $\sigma = 0$ which is a matrix-valued Brownian motion with drift and explicitly solvable. Thus, for $\sigma \to 0$ one has $\widehat{\Lambda}_t^{\varepsilon,\sigma} \Longrightarrow \widehat{\Lambda}_t^{\varepsilon}$ which satisfies the same SDE with $\sigma = 0$ above, therefore

$$\widehat{\Lambda}_t^{\varepsilon,\sigma} \stackrel{\sigma \to 0}{\Longrightarrow} \widehat{\Lambda}_t^{\varepsilon} = \varepsilon t \, \mathcal{S} \begin{pmatrix} \mathbf{1} \\ -\mathbf{1} \end{pmatrix} + \mathcal{S} \begin{pmatrix} \mathcal{A}_t & \mathcal{B}_t \\ -\mathcal{B}_t^* & -\overline{\mathcal{A}}_t \end{pmatrix}.$$

Using analytic versions in ε one obtains by similar arguments as above that

$$\sigma^{-1}\mathcal{E}_{\sigma} \stackrel{\sigma \to 0}{\Longrightarrow} \operatorname{zeros}_{\varepsilon} \det\left(\begin{pmatrix} \mathbf{1} \ \mathbf{1} \end{pmatrix} \widehat{\Lambda}_{1}^{\varepsilon} \begin{pmatrix} \mathbf{1} \\ -\mathbf{1} \end{pmatrix} \right) = \operatorname{spec} \left(\operatorname{Re}(\mathcal{B}_{1} - \mathcal{A}_{1}) \right)$$

where $spec(\cdot)$ denotes the spectrum and $Re(\cdot)$ the entry-wise real part of a matrix. The latter equation is a simple calculation using the relations from above. Similar to Proposition 9 in [VV1], the convergence can be realized jointly.

Lemma 5.5. Let Z be chaotic, let n_k be a sequence such that $Z^{n_k+1} \to \mathbf{1}$ and let σ_k be sequence with $\sigma_k \to 0$ such that $\frac{1}{\sigma_k} \|Z^{n_k+1} - \mathbf{1}\| \to 0$. Consider the regularized Schur complements $\widehat{T}_{\lambda,n}^{\varepsilon,\sigma}$ of the transfer matrices as defined in (5.7). Then define the regularized versions $\mathcal{X}_{\lambda,n}^{\varepsilon,\sigma}$ and the part $X_{\lambda,n}^{\varepsilon,\sigma}$ as in (5.18) and (5.19) but this time keeping the σ . Choose \mathcal{X}_0 such that the corresponding Schur complement X_0 exists and let $\widehat{X}_0 = \begin{pmatrix} \mathbf{0} \\ \mathbf{1} \end{pmatrix} X_0$, the starting point for the SDE limit. Then, for t > 0, we find for $k \to \infty$ that

$$\frac{1}{\sigma_k} \left(X_{\frac{1}{\sqrt{n_k}}, \lfloor tn_k \rfloor}^{\varepsilon \sigma_k, \sigma_k} - \widehat{X}_0 \right) \implies \begin{pmatrix} \mathbf{0} \\ \widehat{\Lambda}_t^{\varepsilon} \end{pmatrix} \widehat{X}_0$$

jointly for $t \in [0, 1]$ *and* ε *varying in any finite subset of* \mathbb{C} *. Moreover, for the eigenvalue process* $\mathcal{E}_{\sigma_k, n_k, d}$ *of* $(H_{\lambda_k, n_k, d} - E)$ *we find*

$$\frac{n_k}{\sigma_k} \mathcal{E}_{\sigma_k, n_k, d} \implies \text{spec} \left(\text{Re}(\mathcal{B}_1 - \mathcal{A}_1) \right)$$

Proof. The proof for the first statement works very similar to above using Proposition 2.1. Therefore we let $\sigma_{\lambda} \to 0$ for $\lambda \to 0$ with $\sigma_{\lambda_k} = \sigma_k$ for $\lambda_k = 1/\sqrt{n_k}$ and consider the process

$$\widehat{X}_{\lambda,n} = \frac{1}{\sigma_{\lambda}} \left[X_{\lambda,n}^{\varepsilon \sigma_{\lambda}, \sigma_{\lambda}} - \widehat{X}_0 \right].$$

For $\sigma_{\lambda} \widehat{X}_{\lambda,n} + \widehat{X}_0 = X_{\lambda,n}^{\varepsilon \sigma_{\lambda}, \sigma_{\lambda}}$ the drift term for each step is of order $\lambda^2 \varepsilon \sigma_{\lambda}$ and the diffusion term of order $\lambda \sigma_{\lambda}$. Similar to (3.18) one obtains therefore an equation of the form

$$\widehat{X}_{\lambda,n} = \begin{pmatrix} \Gamma \\ 1 \end{pmatrix} \widehat{X}_{\lambda,n} + \lambda R^{-n} V^X_{\lambda,n} R^{n-1} (\sigma_\lambda \widehat{X}_{\lambda,n} + \widehat{X}_0) + \mathcal{O}.$$

where the second term of $V_{\lambda,n}^X$ in (3.17) gets an additional σ_{λ} factor and the drift component of the first term, $V_{\lambda,n}^A$, is proportional to $\varepsilon \lambda$. As $\sigma_{\lambda} \to 0$ the estimates on the reminder terms improve and the drift and diffusion terms will not depend on $X_{\lambda,n}$ in the limit anymore. Therefore, we get the Brownian motion with drift, $\widehat{X}_{1/\sqrt{n},\lfloor tn \rfloor} \Longrightarrow \begin{pmatrix} \mathbf{0} \\ \widehat{\Lambda}_t^\varepsilon \end{pmatrix} \widehat{X}_0$.

To see the convergence of the eigenvalue processes we need to follow the calculations of Sect. 5.2 and use the analytic version with uniform convergence for compacts in ε . Note that for this case $\widehat{X}_0 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ in blocks of sizes d_h and $2d_e$. With similar notations as in Sect. 5.2 (but keeping the σ -dependence and the upper σ -index) we obtain with $\sigma = \sigma_{\lambda}$ that

$$\Theta_n^* \mathcal{X}_{\lambda,n}^{\varepsilon\sigma,\sigma} \Theta_0 M_{\lambda,n}^{\varepsilon\sigma,\sigma} = \begin{pmatrix} (\mathbf{0} \, \bar{z}^{n+1} \, z^{n+1}) \, (\sigma \, \widehat{X}_{\lambda,n} + \widehat{X}_0) \begin{pmatrix} \mathbf{0} \\ \mathbf{1} \\ -\mathbf{1} \end{pmatrix} \, (\mathbf{0} \, \bar{z}^{n+1} \, z^{n+1}) \, \widehat{Z}_{\lambda,n} \\ (\mathbf{1} \, \mathbf{0} \, \mathbf{0}) \, \sigma \, \widehat{X}_{\lambda,n} \begin{pmatrix} \mathbf{0} \\ \mathbf{1} \\ -\mathbf{1} \end{pmatrix} \, \mathbf{1}_{d_h} \end{pmatrix}$$

where $\widehat{Z}_{\lambda,n} = B_{\lambda,n}^{\varepsilon\sigma,\sigma} (D_{\lambda,n}^{\varepsilon\sigma,\sigma})^{-1}$. Note that by the choice of σ_k as above one has

$$\sigma_k^{-1} \left(\mathbf{0} \ \bar{Z}^{n_k+1} \ Z^{n_k+1} \right) \widehat{X}_0 \left(\begin{array}{c} \mathbf{0} \\ \mathbf{1} \\ -\mathbf{1} \end{array} \right) = \sigma_k^{-1} \left(\bar{Z}^{n_k+1} - Z^{n_k+1} \right) \to 0.$$

Hence, for $\lambda_k = 1/\sqrt{n_k}$ we have

$$\Theta_n^* \mathcal{X}_{\lambda_k, n_k}^{\varepsilon \sigma_k, \sigma_k} \Theta_0 M_{\lambda_k, n_k}^{\varepsilon \sigma_k, \sigma_k} \begin{pmatrix} \sigma_k^{-1} \mathbf{1} \\ \mathbf{1} \end{pmatrix} \implies \begin{pmatrix} (\mathbf{1} \mathbf{1}) \widehat{\Lambda}_1^{\varepsilon} \begin{pmatrix} \mathbf{1} \\ -\mathbf{1} \end{pmatrix} \mathbf{0} \\ \mathbf{0} & \mathbf{1}_{d_h} \end{pmatrix}.$$

Using analytic versions with uniform convergence locally in ε , the zero processes in ε of the determinants also converge, hence $\frac{n_k}{\sigma_k} \mathcal{E}_{\sigma_k, n_k, d} \implies \text{spec} (\text{Re}(\mathcal{B}_1 - \mathcal{A}_1))$. \Box

Proof of Theorem 1.2. We still restrict to the case r = 1. For any energy $E \in (-4, 4)$, the number of elliptic channels $d_e = d_e(d)$ for the transfer matrices of $H_{\lambda,n,d}$ will go to ∞ as $d \to \infty$. By Lemma 5.2 we find for Lebesgue almost all such energies that the following two things hold:

1. For any *d* there is no parabolic channel (i.e. $|E - a_j| \neq 2$ for all *j*)

2. For any *d* the conditions of Lemma 5.2 apply.

Take such an energy *E* and take sequences $n_k = n_k(d)$ and $\sigma_k = \sigma_k(d)$ satisfying the conditions of Lemma 5.5.

Re($\mathcal{B}_1 - \mathcal{A}_1$) is a real, symmetric $d_e \times d_e$ random matrix whose distribution depends only on d_e . As noted in [VV1, Section 4] its distribution can be written as $(d+1)^{-1/2}(K+b\mathbf{1})$ where *b* is a standard Gaussian random variable and *K* an independent real symmetric matrix with mean zero and Gaussian entries such that $\mathbb{E}(K_{ii}^2) = 5/4$ and $\mathbb{E}(K_{ij}^2) = 1$ for $i \neq j$. As explained in [VV1] the bulk eigenvalue process $s(d_e)$ of $\sqrt{d_e}(K+b\mathbf{1})$ converges locally to the Sine₁ process by methods of [ESYY] when d_e converges to ∞ .

Thus, for the eigenvalue processes $\mathcal{E}_{\sigma,n,d}$ of $H_{\sigma/\sqrt{n},n,d} - E$ we find $\frac{\sqrt{d d_e} n_k(d)}{\sigma_k(d)} \mathcal{E}_{\sigma_k,n_k,d}$ $\Rightarrow s(d_e)$ and $s(d_e) \Rightarrow$ Sine₁ in the topology of weak convergence. Thus we find some diagonal sequence (k_j, d_j) such that with $n_j = n_{k_j}(d_j)$, $\sigma_j = \sigma_{k_j}(d_j)$, $d_{j,e} = d_e(d_j)$ one finds $\frac{\sqrt{d_j d_j,e} n_j}{\sigma_j} \mathcal{E}_{\sigma_j,n_j,d_j} \Rightarrow$ Sine₁. \Box

Remark 5.6. In order to obtain a version of the GOE and the Sine₁ kernel in the limit, it was very imported to have chaoticity of Z coming from the non-degeneracy of the eigenvalues of the matrix $A = \mathbb{Z}_d$. This is why we had to take scaling limits of random operators $H_{\lambda,n,d}$ on a $n \times d$ grid embedded in \mathbb{Z}^2 . Taking grids $n \times d_1 \times \ldots \times d_m$ embedded in \mathbb{Z}^{m+1} and corresponding random operators, this non-degeneracy is no longer true. One still obtains some limiting eigenvalue process fixing the lengths d_1, \ldots, d_m of m directions and taking $n \to \infty$ and $\sigma = \lambda/\sqrt{n}$ to zero. However, in the last step taking $d_1, \ldots, d_m \to \infty$ in a uniform way one obtains some complicated correlated random matrix ensemble with additional symmetries for which proving universality is a challenging problem.

A. Correlations Along Different Directions and SDE Limit on the Flag Manifold

Let T_0 have eigenvalues of absolute value *c* different from 1, and T_0 is diagonalized (or in Jordan form) so that the corresponding eigenspace are also the span of coordinate vectors and have no Jordan blocks. Then applying Theorem 1.1 to the products of $T_{\lambda,n}/c$ gives another SDE limit. Moreover, the convergence in law holds jointly for the processes corresponding to magnitudes 1 and *c* (and in fact all magnitudes). Let us specify the covariance structure of the driving matrix-valued Brownian motions for the different processes. Towards this, we define

$$h_{1c}(M) := \lim_{\lambda \to 0} \mathbb{E}(V_{\lambda,11}^{\top} M V_{\lambda,11}^{(c)}), \quad \widehat{h}_{1c}(M) := \lim_{\lambda \to 0} \mathbb{E}(V_{\lambda,11}^{*} M V_{\lambda,11}^{(c)})$$

where now *M* is a $d_1(1) \times d_1(c)$ matrix, where $d_1(c)$ is the total dimension of all eigenspaces corresponding to eigenvalues of absolute value *c*. $V_{\lambda,11}^{(c)}$ denotes the corresponding $d_1(c) \times d_1(c)$ block of $V_{\lambda,n}$. Similarly, we define $h_{cc'}$ and $\hat{h}_{cc'}$ for any two

absolute values c, c' (see also (1.10)). As before, we also need the $d_1(c) \times d_1(c)$ unitaries U_c (like U in (1.2)) so that T_0 restricted to the eigenspaces of magnitude c acts like cU_c .

Theorem A.1. The convergence of Theorem 1.1 holds jointly along all eigenspaces corresponding to absolute values c of eigenvalues of T_0 that correspond to eigenspaces without Jordan block. We will denote the corresponding process for the magnitude c by $\Lambda_t^{(c)}$. Then, the covariance of the driving Brownian motions $\mathcal{B}, \mathcal{B}'$ for the magnitudes c, c' are given by

$$\mathbb{E}(\mathcal{B}_t^{\top} M \mathcal{B}_t') = g_{cc'}(M)t, \quad \mathbb{E}(\mathcal{B}_t^* M \mathcal{B}_t') = \widehat{g}_{cc'}(M)t$$
(A.1)

where

$$g_{cc'}(M) = \frac{1}{cc'} \int_{\langle U_c, U_{c'} \rangle} \overline{u} \, \overline{U}_c \, h_{cc'}(u^\top M v) \, U_{c'}^* v^* \, d(u, v), \tag{A.2}$$

$$\widehat{g}_{cc'}(M) = \frac{1}{cc'} \int_{\langle U_c, U_{c'} \rangle} u U_c \,\widehat{h}_{cc'}(u^* M v) \, U_{c'}^* v^* \, d(u, v). \tag{A.3}$$

Here, $\langle U_c, U_{c'} \rangle$ denotes the (block diagonal) compact Abelian group generated by $\binom{U_c}{U_{c'}}$, and d(u, v) denotes the Haar measure on $\langle U_c, U_{c'} \rangle \ni \binom{u}{v}$.

Proof. Consider the products of the direct sums $\tilde{\mathcal{T}}_{\lambda,n} := \mathcal{T}_{\lambda,n}/c \oplus \mathcal{T}_{\lambda,n}/c' = \begin{pmatrix} \mathcal{T}_{\lambda,n}/c \\ \mathcal{T}_{\lambda,n}/c' \end{pmatrix}$. In an adequate basis we can apply Theorem 1.1 directly with U being replaced by $\tilde{U} = U_c \oplus U_{c'}$ and function h being replaced by $\tilde{h} \begin{pmatrix} M_0 & M_1 \\ M_2 & M_3 \end{pmatrix} = \begin{pmatrix} h_{cc}(M_0)/c^2 & h_{cc'}(M_1)/(cc') \\ h_{cc'}(M_2)/(cc') & h_{c'c'}(M_3)/c'^2 \end{pmatrix}$. A similar equation holds for the replacement of \hat{h} . Then Theorem 1.1 leads directly to the given statement. \Box

If the eigenvalues of \mathcal{T}_0 are of different absolute value, then the matrix product process grows at different directions at different exponential rates. Hence there is no hope to get a matrix limit of the process that captures all the directions and all the different SDE limits $\Lambda_t^{(c)}$ with their covariances at the same time. First consider powers of the matrix \mathcal{T}_0 in the case it is diagonalizable and all the eigen-

First consider powers of the matrix \mathcal{T}_0 in the case it is diagonalizable and all the eigenvalues are of different positive absolute value. Then high powers of \mathcal{T}_0 take most vectors close to the direction of the top eigenspace. A natural way to understand the second eigenvector through typical behavior is through the action of \mathcal{T}_0 on two-dimensional subspaces. A high power of \mathcal{T}_0 will take two-dimensional eigenspaces into a two-dimensional space spanned by the top two eigenvectors of \mathcal{T}_0 .

A flag is a nested sequence of subspaces of all dimensions up to d. The set of all such flags forms a compact manifold. By the above argument, a high power of T_0 takes most flags close to the flag given by the nesting of the subspaces spanned by the top k eigenvectors.

The above picture still holds when we add perturbations and consider the products $\mathcal{T}_{\lambda,n} \cdots \mathcal{T}_{\lambda,1}$. So nothing interesting happens in this case. Things become more interesting when there are more than one eigenvalue of \mathcal{T}_0 for a given absolute value. If this holds for the top one, then the direction of the action of a typical vector becomes dependent on the randomness, even in the limit. The deterministic dynamics only gives that the vector will be in the subspace spanned by the eigenvectors corresponding to the top absolute

value. In this sense, the different exponential rates will still determine certain subspaces of the flag in the limit so that the limiting process will be in a specific submanifold that is invariant and attracting under the action of T_0 .

Our next theorem shows how this happens. More precisely, we will consider a flag which is typical for the behavior of powers of \mathcal{T}_0 . This happens if the *k*-dimensional spaces of the flag do not include directions that are spanned by subsets of eigenvectors of \mathcal{T}_0 corresponding to eigenvalues of lower order. The matrix products applied to this flag will give a flag-valued process. This is described in Theorem A.2.

As only invertible matrices act on a flag, suppose that for small λ all $\mathcal{T}_{\lambda,n}$ are invertible with probability one, i.e., there is λ_0 such that for all $0 \leq \lambda < \lambda_0$, $\mathbb{P}(\mathcal{T}_{\lambda,n})$ is invertible for all n = 1. Suppose further that \mathcal{T}_0 is diagonalizable and that we chose a basis such that

$$\mathcal{T}_0 = \begin{pmatrix} c_1 U_{c_1} & \mathbf{0} \\ & \ddots \\ \mathbf{0} & c_k U_{c_k} \end{pmatrix}, \quad \text{where} \quad 0 < c_1 < c_2 < \cdots < c_k, \qquad (A.4)$$

with the U_{c_i} being unitary $d(c_i) \times d(c_i)$ matrices.

A flag can be represented by an invertible $d \times d$ matrix \mathcal{F} where the *last p* column vectors, denoted by $\mathcal{F}^{(p)}$, span the *p*-dimensional subspace. \mathcal{F}_1 and \mathcal{F}_2 represent the same flag if and only if $\mathcal{F}_1 = \mathcal{F}_2 M$ for an invertible lower triangular matrix M. This forms an equivalence relation and we denote the equivalence class of \mathcal{F} by $[\mathcal{F}]$. Denoting the group of invertible, lower triangular $d \times d$ matrices by $\Delta(d)$ the flag manifold has

$$\mathbb{F} = \operatorname{GL}(d, \mathbb{C}) / \Delta(d).$$

The stable submanifold \mathbb{F}^s is the set of all flags such that the $d(c_1) + \cdots + d(c_j)$ dimensional subspace is spanned by the last $d(c_1) + \cdots + d(c_j)$ vectors in the standard basis, i.e.

$$\mathbb{F}^{s} = \left\{ \begin{bmatrix} \begin{pmatrix} a_{1} & \mathbf{0} \\ \mathbf{0} & a_{k} \end{pmatrix} \end{bmatrix} : \text{ for all } j, a_{j} \in \mathrm{GL}(d(c_{j})) \right\} \subset \mathbb{F}.$$

This is an attractor by the deterministic dynamics given by the action of \mathcal{T}_0 and the set of points in \mathbb{F} that is attracted is given by

$$\mathbb{F}^{a} = \left\{ \begin{bmatrix} \begin{pmatrix} a_{1} & * \\ \mathbf{0} & a_{k} \end{pmatrix} \end{bmatrix} : \text{ for all } j, a_{j} \in \mathrm{GL}(d(c_{j})), * \text{ arbitrary} \right\}.$$
(A.5)

To counteract all the rotations let

$$\widehat{\mathcal{R}} = \begin{pmatrix} U_{c_1} & \mathbf{0} \\ & \ddots \\ \mathbf{0} & U_{c_k} \end{pmatrix} \in \mathrm{U}(d).$$

Theorem A.2. Let \mathcal{T}_0 be as in (A.4) and let $[\mathcal{F}_0] \in \mathbb{F}^a$ be represented in the form as described in (A.5). Furthermore let $\mathcal{F}_{\lambda,n} = \widehat{\mathcal{R}}^{-n} \mathcal{T}_{\lambda,n} \cdots \mathcal{T}_{1,\lambda} \mathcal{F}_0$.

Then, for fixed t > 0 and $n \to \infty$ we have $[\mathcal{F}_{1/\sqrt{n}, \lfloor tn \rfloor}] \Longrightarrow [\mathcal{F}_t]$ in law with

$$\mathcal{F}_t = \begin{pmatrix} \Lambda_t^{(c_1)} a_1 & \mathbf{0} \\ & \ddots & \\ \mathbf{0} & \Lambda_t^{(c_k)} a_k \end{pmatrix}.$$

Here, $\Lambda_t^{(c_j)}$ are the correlated processes for the different magnitudes c_j of eigenvalues of \mathcal{T}_0 whose correlations are described in Theorem A.1. Note that $[\mathcal{F}_t] \in \mathbb{F}^s$.

Remark. If \mathcal{T}_0 can not be brought into the structure as in (A.4) in general then one still obtains the SDE limits on the Grassmannians G(p, d) for $d_2 as in the proof. <math>G(p, d)$ denotes the space of p-dimensional subspaces of \mathbb{C}^d .

Corollary A.3. Let $\mathbb{G} \subset \operatorname{GL}(d, \mathbb{C})$ be an algebraic group such that the quotient $\operatorname{GL}(d, \mathbb{C})/\mathbb{G}$ is compact. Further more, let \mathcal{T}_0 be as above. Then, for \mathcal{X}_0 in some stable manifold,

$$\widehat{\mathcal{R}}^{-n}\mathcal{T}_{1/\sqrt{n},}\cdots\mathcal{T}_{1/\sqrt{n},1}\mathcal{X}_0\,/\,\mathbb{G}\implies \mathcal{X}_t\,/\,\mathbb{G}$$

where \mathcal{X}_t satisfies some SDE.

Proof. Under the conditions, $\operatorname{GL}(d, \mathbb{C}) / \mathbb{G}$ is a complex compact algebraic variety and hence a complete algebraic variety. Thus, \mathbb{G} is a parabolic subgroup which contains a Borel subgroup. We therefore find some $\mathcal{G} \in \operatorname{GL}(d, \mathbb{C})$ such that the isomorphic conjugate group $\mathbb{G}' = \mathcal{G} \mathbb{G} \mathcal{G}^{-1}$ contains the Borel subgroup $\Delta(d)$, i.e. $\Delta(d) \subset \mathbb{G}'$. Therefore, $\operatorname{GL}(d, \mathbb{C}) / \mathbb{G}'$ is itself a quotient of the flag manifold and with \mathcal{F}_0 and $\mathcal{F}_{\lambda,n}$ as above we find $\mathcal{F}_{1/\sqrt{n},\lfloor nt \rfloor} / \mathbb{G}' \Rightarrow \mathcal{F}_t / \mathbb{G}'$. On easily notices that $M \sim_{\mathbb{G}'} M'$ if and only if $M\mathcal{G} \sim_{\mathbb{G}} M'\mathcal{G}$, and therefore, $\mathcal{F}_{1/\sqrt{n},\lfloor nt \rfloor} \mathcal{G} / \mathbb{G} \Rightarrow \mathcal{F}_t \mathcal{G} / \mathbb{G}$. Hence, we obtain the limiting process when choosing $\mathcal{X}_0 = \mathcal{F}_0 \mathcal{G}$ with \mathcal{F}_0 in the form as above. \Box

Proof of Theorem A.2. As $[\mathcal{F}_0] \in \mathbb{F}^a$ we can represent it by

$$\mathcal{F}_0 = \begin{pmatrix} a_1 & * \\ \mathbf{0} & a_k \end{pmatrix}, \text{ for all } j, a_j \in \mathrm{GL}(d(c_j)), * \text{ arbitrary.}$$

Let G(p, d) denote the Grassmannian manifold of *p*-dimensional subspaces of \mathbb{C}^d . Note that $\mathcal{F}^{(p)} \in G(p, d)$. As \mathbb{F} can be seen as a submanifold of $\prod_{p=1}^d G(p, d)$ it will be sufficient to prove $\mathcal{F}^{(p)} \Rightarrow \mathcal{F}^{(p)}_t$ in G(p, d) jointly for any (fixed) *p*.

As the action of \mathcal{T} and $c\mathcal{T}$ on \mathbb{F} or G(p, d) is the same, we may for fixed p scale the matrices such that $d_2 in the sense of the definitions of <math>d_1, d_2$ in the Sect. 1.1 (Note that this basically means $c_j = 1$ for some $j, d_2 = d(c_1) + d(c_2) + \cdots + d(c_{j-1})$ and $d_1 = d(c_j)$.) Now for $\mathcal{F}_1, \mathcal{F}_2 \in \mathrm{GL}(d, \mathbb{C})$ one finds that

$$\mathcal{F}_1^{(p)} = \mathcal{F}_2^{(p)} \quad \text{if and only if} \quad \mathcal{F}_1 = \mathcal{F}_2 \begin{pmatrix} M_1 & \mathbf{0} \\ * & M_2 \end{pmatrix}, \quad M_2 \in \mathrm{GL}(p), \ M_1 \in \mathrm{GL}(d-p).$$
(A.6)

Using blocks of size $d_0 + d_1$ and d_2 and representing $[\mathcal{F}_0] \in \mathbb{F}^a$ as above we find

$$\mathcal{F}_0 = \begin{pmatrix} A_0 & B_0 \\ \mathbf{0} & D_0 \end{pmatrix} \quad \text{with} \quad A_0 = \begin{pmatrix} a_{00} & a_{01} \\ \mathbf{0} & a_{11} \end{pmatrix} \tag{A.7}$$

where D_0 , a_{00} and a_{11} are invertible. Note that in fact $a_{11} = a_j$ for some j as in the notations above and that a_{00} contains the a_k for k > j and D_0 contains the a_k for k < j. So we can choose $\mathcal{X}_0 = \mathcal{F}_0$ and consider the processes $\mathcal{X}_{\lambda,n}$ as above. Then clearly $\mathcal{F}_{\lambda,n}^{(p)} = \mathcal{X}_{\lambda,n}^{(p)}$ and in terms of representatives in G(p, d) they are equivalent to

$$\begin{pmatrix} A_{\lambda,n} & B_{\lambda,n} \\ C_{\lambda,n} & D_{\lambda,n} \end{pmatrix} \begin{pmatrix} \mathbf{1} & \mathbf{0} \\ -D_{\lambda,n}^{-1} C_{\lambda,n} & D_{\lambda,n}^{-1} \end{pmatrix} = \begin{pmatrix} X_{\lambda,n} & Z_{\lambda,n} \\ \mathbf{0} & \mathbf{1}_{d_2} \end{pmatrix}.$$
 (A.8)

Note that from the proof of Theorem 1.1 the inverse $D_{\lambda,n}^{-1}$ exists for small λ (with sufficiently high probability) and therefore, as we consider invertible matrices here, we

also find that $X_{\lambda,n}$ is invertible. As $X_{\frac{1}{\sqrt{n}},\lfloor tn \rfloor}\begin{pmatrix} 0\\ \mathbf{1}_{d_1} \end{pmatrix} \Rightarrow \begin{pmatrix} 0\\ \Lambda_t D_0 \end{pmatrix}$ with Λ_t invertible, we find for $n \sim \lambda^{-2}$ and large *n* that $\begin{pmatrix} \mathbf{1}_{d_0} & X_{\lambda,n}\begin{pmatrix} 0\\ \mathbf{1}_{d_1} \end{pmatrix}$ is invertible. Hence, the right hand side of (A.8) represents the same *p*-dimensional subspace as

$$\begin{pmatrix} X_{\lambda,n} & Z_{\lambda,n} \\ \mathbf{0} & \mathbf{1}_{d_2} \end{pmatrix} \begin{pmatrix} X_{\lambda_n}^{-1} \begin{pmatrix} \mathbf{1} \\ \mathbf{0} \end{pmatrix} & \mathbf{0} \\ \mathbf{0} & \mathbf{0} & \mathbf{1} \end{pmatrix} = \begin{pmatrix} \mathbf{1} & X_{\lambda,n} \begin{pmatrix} \mathbf{0} \\ \mathbf{0} \end{pmatrix} & Z_{\lambda,n} \\ \mathbf{0} & \mathbf{0} & \mathbf{1}_{d_2} \end{pmatrix}$$
(A.9)

Therefore by Theorem 1.1 we find

$$\mathcal{F}_{\frac{1}{\sqrt{n}},\lfloor tn\rfloor}^{(p)} \implies \begin{pmatrix} \mathbf{1}_{d_0} \\ \Lambda_t a_{11} \\ \mathbf{1}_{d_2} \end{pmatrix}^{(p)} = \mathcal{F}_t^{(p)}. \tag{A.10}$$

The last equation is easy to see if one realizes that the last p column vectors end somewhere inside the a_{11} term and therefore span indeed the same p-dimensional subspace as \mathcal{F}_t . Clearly, looking at this convergence jointly in p we obtain the correlations as in Theorem A.1. \Box

B. Jordan Blocks, Critical Scalings and Application at Band Edges

Without loss of generality we will focus on the eigenvalues of size 1 of T_0 . Let us introduce the notation J_k for the standard $k \times k$ Jordan block with eigenvalue 1, and N_k for the standard Jordan block with eigenvalue 0, i.e.

$$J_k = \begin{pmatrix} 1 & 1 & \mathbf{0} \\ \ddots & \ddots & \\ & \ddots & 1 \\ \mathbf{0} & & 1 \end{pmatrix} = \mathbf{1} + N_k$$

If a Jordan block of the form $e^{i\theta} J_k$ appears in (a possible conjugation of) \mathcal{T}_0 then we will do a λ -dependent conjugation. This trick was already used in [SS1] to analyze the Lyapunov exponent and density of states at a bandedge for a one-dimensional Schrödinger operator. The main point is the following observation. Define the λ -dependent, diagonal $k \times k$ matrices

$$S_{\lambda,\alpha,k} = \operatorname{diag}(1, \lambda^{\alpha}, \dots, \lambda^{(k-1)\alpha})$$

then

$$S_{\lambda,\alpha,k}^{-1} J_k S_{\lambda,\alpha,k} = \mathbf{1}_k + \lambda^{\alpha} N_k.$$
(B.1)

Now using blocks of sizes d_0, d_1, d_2 as before let

$$\mathcal{T}_{0} = \begin{pmatrix} \Gamma_{0} \\ e^{i\theta} J_{d_{1}} \\ \Gamma_{2}^{-1} \end{pmatrix}, \quad \mathcal{R} = \begin{pmatrix} \mathbf{1} \\ e^{i\theta} \mathbf{1} \\ \mathbf{1} \end{pmatrix}, \quad \mathcal{S}_{\lambda,\alpha} = \begin{pmatrix} \mathbf{1}_{d_{0}} \\ S_{\lambda,\alpha,d_{1}} \\ \mathbf{1}_{d_{2}} \end{pmatrix} \quad (B.2)$$

with Γ_1 and Γ_2 having spectral radius smaller than one as before. Conjugating $\mathcal{T}_{\lambda,n}$ by $\mathcal{S}_{\lambda,\alpha}$ will give a new drift term of order λ^{α} coming from (B.1), but it also brings a diffusion term of order $\lambda^{1-(d_1-1)\alpha}$ from conjugating $\lambda \mathcal{V}_{\lambda,n}$. The diffusion has thus order $\lambda^{2-2(d_1-1)\alpha}$ and the most interesting SDE limit arises from balancing the new drift term

and the diffusion term, i.e. $\alpha = 2 - 2(d_1 - 1)\alpha$, leading to $\alpha = \alpha(d_1) = 2/(2d_1 - 1)$. For smaller α , the drift term dominates and for larger α , the diffusion term dominates.

In fact, only the lower left corner entry³ of the middle $d_1 \times d_1$ block of $S_{\lambda,\alpha}^{-1} \mathcal{V}_{\lambda,n} S_{\lambda,\alpha}$ will be of order $\lambda^{\alpha/2}$, all other terms from the conjugation will be at least of order $\lambda^{3\alpha/2}$. Hence, for the case as in (B.2) we find

$$\mathcal{S}_{\lambda,\alpha(d_1)}^{-1}\mathcal{T}_{\lambda,n}\mathcal{S}_{\lambda,\alpha(d_1)} = \widehat{\mathcal{T}}_0 + \lambda^{1/(2d_1-1)}\widehat{\mathcal{V}}_n + \lambda^{2/(2d_1-1)}\mathcal{N} + \lambda^{3/(2d_1-1)}\widetilde{\mathcal{V}}_{\lambda,n}$$

where

$$\widehat{\mathcal{T}}_{0} = \begin{pmatrix} \Gamma_{0} \\ e^{i\theta} \mathbf{1} \\ \Gamma_{2}^{-1} \end{pmatrix}, \quad \mathcal{N} = \begin{pmatrix} \mathbf{0} \\ e^{i\theta} N_{d_{1}} \\ \mathbf{0} \end{pmatrix}, \quad \widehat{\mathcal{V}}_{n} = \begin{pmatrix} \mathbf{0} \\ V_{11,n} \\ \mathbf{0} \end{pmatrix}. \tag{B.3}$$

Furthermore, $V_{11,n}$ has only one entry v_n in the lower left corner, and the v_n are i.i.d. random variables with mean zero,

$$V_{11,n} = \begin{pmatrix} \mathbf{0} & \mathbf{0}_{(d_1-1)\times(d_1-1)} \\ v_n & \mathbf{0} \end{pmatrix}.$$

Therefore, application of Theorem 1.1 gives an SDE limit in the scaling $\lambda^{\alpha_k} n = \lambda^{2/(2k-1)} n = t$:

Theorem B.1. Let $\mathcal{T}_{\lambda,n}$ be given as in (1.1) and let the assumptions as on page 5 and (B.2) be satisfied. Moreover let $S_{\lambda,\alpha}$ be defined as above with $\alpha = \alpha(d_1) = 2/(2d_1-1)$. Let

$$\mathcal{X}_{\lambda,n} = \mathcal{R}^{-n} \mathcal{S}_{\lambda,\alpha}^{-1} \mathcal{T}_{\lambda,n} \cdots \mathcal{T}_{\lambda_1} \mathcal{S}_{\lambda,\alpha} \mathcal{X}_0$$

with \mathcal{X}_0 as before and let $X_{\lambda,n}$ be the corresponding Schur complement as before. Then

$$X_{\frac{1}{\sqrt{n^{2d_{1}-1}}},\lfloor nt \rfloor} \implies X_{t} = \begin{pmatrix} \mathbf{0} \\ \Lambda_{t} \end{pmatrix} X_{0}$$
$$d\Lambda_{t} = N_{d_{1}}\Lambda_{t}dt + \begin{pmatrix} \mathbf{0} & \mathbf{0} \\ dB_{t} & \mathbf{0} \end{pmatrix} \Lambda_{t}, \quad \Lambda_{0} = \mathbf{1}$$
(B.4)

where B_t is a complex Brownian motion with covariances

$$\mathbb{E}(B_t^2) = e^{-2i\theta} \mathbb{E}(v_n^2), \quad \mathbb{E}(|B_t|^2) = \mathbb{E}(|v_n|^2).$$

Note that for a vector $x(t) = \Lambda_t x(0)$ Eq. (B.4) is equivalent to

$$x_1^{(d_1)} = x_1 B' \tag{B.5}$$

and $x_{j+1} = x_1^{(j)}$, the *j*th derivative of x_1 , and B' is the (distributional) derivative of the Brownian motion term.

³ If the variance of that entry happens to be identically zero (no randomness) or of lower order in λ , then the diffusion term is of order $\lambda^{1-(k-2)\alpha}$ (or lower again). This may lead to other interesting scalings as for smaller Jordan blocks.

Remark. The original drift term coming from $\lambda^2 W_{\lambda}$ is of too low order after the conjugation with $S_{\lambda,\alpha}$ to matter in the limit. If one wants an additional drift term in (**B**.5) on the right hand side coming from an added term $\lambda^{\beta}W$ then the conjugation $S_{\lambda,\alpha}^{-1}\lambda^{\beta}WS_{\lambda,\alpha}$ needs to produce a term of order $\lambda^{\frac{2}{2d_1-1}} = \lambda^{\alpha}$. If W is not zero in the lower left corner of the corresponding $d_1 \times d_1$ block for the SDE limit, then one needs $\beta - (d_1 - 1)\alpha = \alpha$, i.e. $\beta = d_1\alpha = 2d_1/(2d_1 - 1)$.

Jordan blocks do appear at so-called band-edges for transfer matrices of one-dimensional random Schrödinger operators with some finite range hopping. Similar as in Sect. 1.2 consider the random family of random real symmetric matrices $H_{\lambda,n}^{(d)}$ acting on $\mathbb{C}^n \ni \psi = (\psi_1, \dots, \psi_n)$ given by

$$(H_{\lambda,n}^{(d)}\psi)_k = \sum_{j=0}^{2d} (-1)^j \binom{2d}{j} \psi_{k-d+j} + \lambda v_k \,\psi_k, \tag{B.6}$$

where $\psi_j = 0$ for j < 1 and j > n. We may sometimes drop the index n. The v_k are independent, identically distributed real random variables with variance $\mathbb{E}(v_k^2) = 1$. Note that for d = 1 this operator corresponds to (5.1) with A = -2. The eigenvalue equation $H_{\lambda}^{(d)}\psi = E\psi$ can be rewritten as

$$\vec{\psi}_k = (T + (E - \lambda v_k) S) \vec{\psi}_{k-1}, \text{ where } \vec{\psi}_k = (\psi_{k+d}, \psi_{k+d-1}, \dots, \psi_{k-d+1})^\top$$

and *S* and *T* are $2d \times 2d$ matrices given by: $S_{1,d} = 1$ and all other entries of *S* are zero; $T_{1,k} = (-1)^{k+1} \binom{2d}{2d-k}$, $T_{j,j-1} = 1$ for $j \ge 2$ and all other entries of *T* are zero, i.e.

$$T = \begin{pmatrix} \binom{2d}{2d-1} & \cdots & \binom{2d}{1} & -\binom{2d}{0} \\ 1 & & 0 \\ & \ddots & & \vdots \\ & & 1 & 0 \end{pmatrix}.$$

For E = 0 and $\lambda = 0$ the transfer matrix *T* is equivalent to a Jordan block⁴ of maximum size for the eigenvalue 1. In order to bring it into the Jordan form, let us define the Pascal-triangle type matrix *M* by $M_{jk} = \binom{2d-j}{k-1}$ for $k + j \le 2d + 1$ and zero for all other entries, then one has $M_{jk}^{-1} = (-1)^{j+k} \binom{j-1}{2d-k}$ for $k + j \ge 2d + 1$ and all other entries zero, i.e.

$$M = \begin{pmatrix} 1 & 2d-1 & \binom{2d-1}{2} & \cdots & 1\\ 1 & 2d-2 & \cdots & 1\\ 1 & \cdots & 1 & \\ \vdots & \ddots & & \\ 1 & & & & \end{pmatrix}, \quad M^{-1} = \begin{pmatrix} & & & 1\\ & 1 & -1\\ & 1 & -2 & 1\\ & \ddots & \cdots & & \vdots\\ 1 & \cdots & -\binom{2d-1}{2} & 2d-1 & -1 \end{pmatrix}.$$

Then some calculation shows $M^{-1}TM = J_{2d}$ where J_{2d} is the Jordan matrix as defined above. For the conjugation of the whole transfer matrix $T + E - \lambda v_k S$ we also need

⁴ In fact E = 0 is at the edge of the spectrum of the operator $H_0^{(d)}$ in the limit $n \to \infty$; it is the upper edge for *d* odd and the lower edge for *d* even.

to calculate $M^{-1}SM$. Its entries are given by $(M^{-1}SM)_{j,k} = M_{j,1}^{-1}S_{1,d}M_{d,k}$ which is only not zero if j = 2d and $k \le d + 1$ in which case $(M^{-1}SM)_{2d,k} = \binom{d}{k-1}$, i.e.

$$M^{-1}SM = \begin{pmatrix} 0 & \cdots & \cdots & 0 \\ \vdots & & & \vdots \\ 0 & \cdots & & \cdots & 0 \\ 1 & d & \binom{d}{2} & \cdots & 1 & 0 & \cdots & 0 \end{pmatrix}$$

In particular the lower left corner has the entry 1. As above let $\alpha = \frac{2}{4d-1}$ and as in the remark scale energy differences by $E = \epsilon \lambda^{2d\alpha}$ to obtain

$$\mathcal{T}_{\lambda,k} := \mathcal{S}_{\lambda,\alpha}^{-1} M^{-1} (T + (\lambda^{2d\alpha} \epsilon - \lambda v_k) S) M \mathcal{S}_{\lambda,\alpha} = \mathbf{1} - \lambda^{\frac{\alpha}{2}} v_k Q + \lambda^{\alpha} [\mathcal{N}_{2d} + \epsilon Q] + \mathcal{O}(\lambda^{\frac{3\alpha}{2}}).$$

Then, for any vector $x \in \mathbb{C}^{2d}$ we find

$$\mathcal{T}_{n^{-1/\alpha}, \lfloor nt \rfloor} x \implies x(t) \text{ with } x(0) = x, \quad x_1^{(2d)} = x_1 B' + \epsilon x_1, \quad x_{j+1} = x_1^{(j)}$$

where B' is the distributional derivative of a standard, real, one-dimensional Brownian motion.

Following the arguments of [KVV] or the arguments of the proof of Theorem 5.4 one could show that (along suitable subsequences so that the boundary conditions converge) the eigenvalue process of $n^{2d} H_{n^{-1/\alpha},n}^{(d)}$ with $\alpha = 2/(4d-1)$ converges to the process of eigenvalues of the random operator

$$\partial_x^{2d} - B'$$

acting on the interval [0, 1] with appropriate boundary conditions. For periodic boundary conditions this is a generalization of the random Hill operator (at d = 1).

Acknowledgments Open access funding provided by Institute of Science and Technology (IST Austria).

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Communicated by H.-T. Yau