

Craters, boulders and regolith of (101955) Bennu indicative of an old and dynamic surface

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Small, kilometre-sized near-Earth asteroids are expected to have young and frequently refreshed surfaces for two reasons: collisional disruptions are frequent in the main asteroid belt where they originate, and thermal or tidal processes act on them once they become near-Earth asteroids. Here we present early measurements of numerous large candidate impact craters on near-Earth asteroid (101955) Bennu by the OSIRIS-REx (Origins, Spectral Interpretation, Resource Identification, and Security-Regolith Explorer) mission, which indicate a surface that is between 100 million and 1 billion years old, predating Bennu's expected duration as a near-Earth asteroid. We also observe many fractured boulders, the morphology of which suggests an influence of impact or thermal processes over a considerable amount of time since the boulders were exposed at the surface. However, the surface also shows signs of more recent mass movement: clusters of boulders at topographic lows, a deficiency of small craters and infill of large craters. The oldest features likely record events from Bennu's time in the main asteroid belt.

NASA's OSIRIS-REx (Origins, Spectral Interpretation, Resource Identification, and Security-Regolith Explorer) asteroid sample return mission arrived at near-Earth asteroid (NEA) (101955) Bennu on 3 December 2018. An imaging campaign during the Approach phase of the mission collected panchromatic images with the OSIRIS-REx Camera Suite (OCAMS) PolyCam imager^{1–3}. Images collected by the OCAMS MapCam imager¹ during the Preliminary Survey phase of the mission were combined with approach-phase imaging to produce a three-dimensional shape model of the asteroid, revealing a spheroidal spinning-top shape with a diameter of 492 ± 20 m (ref. ⁴), as predicted by radar observations⁵.

Over the past three decades, ground-based and spacecraft observations of asteroids, combined with theoretical and computational advances, have transformed our understanding of small NEAs (diameters $< \sim 10$ km). Observations of NEA shapes, spins and sizes combined with theoretical analyses that have provided insight into their interior properties suggest that NEAs with diameters $> \sim 200$ m are 'rubble piles': gravitationally bound, unconsolidated fragments with very low bulk tensile strength^{6,7}.

Rubble-pile asteroids originate from the main asteroid belt, where catastrophic collisions between larger objects create a population of gravitationally reaccumulated remnants⁸. Small asteroids

have limited collisional lifetimes in the main belt (~ 0.1 to 1 billion years), and their residence time in the main belt can be shorter than the age of the Solar System due to Yarkovsky drift-induced ejection⁹. After departing the main belt, NEAs are subject to further evolutionary processes, such as rotational spin-up due to thermal torques or tidal effects caused by close planetary flybys⁷. These processes can alter their global and surface morphologies. Studies of the rubble-pile NEA (25143) Itokawa found large boulders exposed on its surface, seemingly rapid degradation of impact craters and evidence of substantial movement of surface material¹⁰. This suggests that Itokawa has undergone dynamical events^{10–12} that operate on timescales shorter than its expected residence time in near-Earth space (~ 10 million years)⁷.

Detailed study of Bennu's surface geology, particularly the abundance of its craters and morphology of its boulders, provides constraints on the surface age, which is important to disentangle evolutionary processes that operated in near-Earth space from those that operated in the main belt.

Rubble-pile nature of Bennu

The measured density of $1,190 \text{ kg m}^{-3}$ and inferred high bulk porosity of Bennu^{4,13} and the lack of either high surface slopes or

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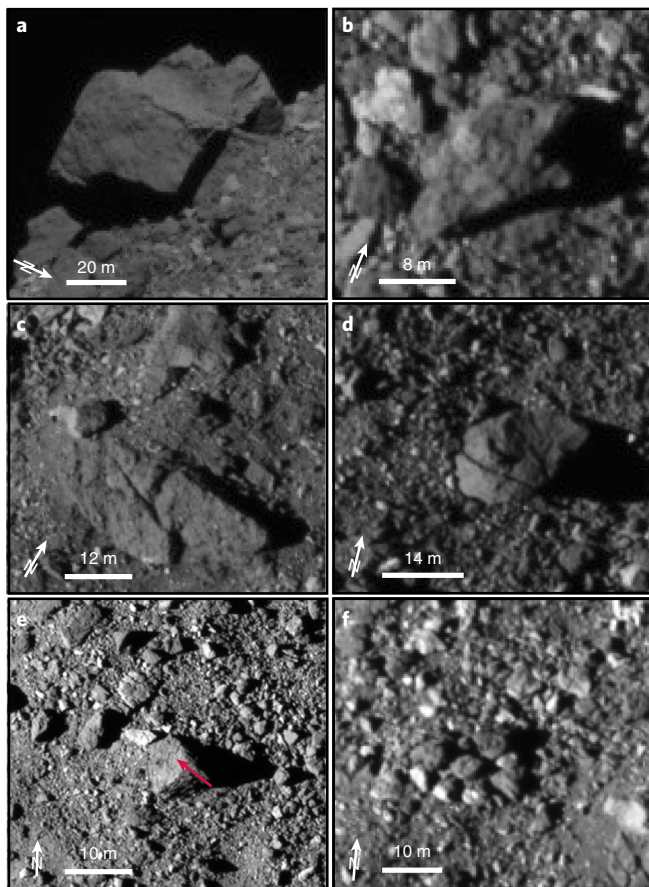


Fig. 1 | The boulders of Benu can be large and are sometimes fractured or brecciated. **a**, A boulder located at 48° S and 125° E with a diameter of approximately 56 m and height of over 20 m relative to the surrounding surface of Benu. **b**, A brecciated boulder located at 6° S and 247° E that is approximately 21 m in diameter with large constituent pieces showing measurable geometric albedo differences. **c**, A boulder with a diameter of approximately 40 m located at 42° N and 129° E that shows a complex web of large fractures. **d**, A boulder with a diameter of approximately 20 m located at 11° S and 258° E with a single linear fracture. **e**, A boulder with a diameter of approximately 10 m located at 5° N and 310° E with a nonlinear fracture (red arrow). **f**, A cluster of metre-sized boulders centred at 44° N and 111° E. Images taken on: **a**, 1 December 2018 from a spacecraft distance of 31.5 km; **b,d**, 2 December 2018 from a distance of 24.0 km; **c**, 2 December 2018 from a distance of 23.8 km; **e**, 2 December 2018 from a distance of 24.2 km; **f**, 2 December 2018 from a distance of 23.6 km.

substantial topographic relief indicate that Benu is a rubble pile. Benu's density requires 25–50% macroporosity if it is constructed primarily of CI (bulk density of $1,570 \text{ kg m}^{-3}$) or CM (bulk density of $2,200 \text{ kg m}^{-3}$) chondrite-like material¹⁴. If the microporosity present in these meteorite classes is also considered¹⁵, the total porosity of Benu may be as high as 60%. In addition, the slope at each point on the surface of Benu—determined from the combination of the shape, mass and spin state—shows a relaxed distribution with values averaging approximately 17°, and almost entirely below typical angles of approximately 30° allowed by the angle of repose of terrestrial materials and found on other similarly sized NEAs^{13,16}.

Boulders dominate the local topography of Benu, some with heights >20 m (Fig. 1a). The most prominent boulder on Benu was first detected with ground-based radar and estimated to be 10 to 20 m in diameter². This same boulder is apparent in PolyCam images and measures approximately 56 m in its longest dimen-

sion (Fig. 1a). There are three identified boulders with long axes exceeding 40 m and more than 200 boulders larger than 10 m (ref. ²). Boulders in the tens-of-metres size range are larger than plausible ejecta from any of the large crater candidates on Benu¹⁷, and also unlikely to be meteorites that Benu could have accreted in its current orbit, suggesting instead that their origins trace back to the formation of Benu in the asteroid belt.

Boulders on Benu have albedo and colour diversity¹, with some showing these differences within distinct metre-sized clasts in an otherwise unfragmented rock. We interpret such assemblages as impact breccias (Fig. 1b). Processes capable of creating breccias spanning tens of metres with metre-sized clasts imply energetic events that far exceed what Benu can support^{18,19}.

The possible inherited origin of Benu's largest boulders supports the idea that rubble piles form as reaccumulated remnants of disruptive collisions of larger asteroids in the main asteroid belt⁸. Furthermore, the existence of breccias suggests that they are a record of the parent body's accretion, that they formed during impact regolith gardening on the surface of that parent body or that they originated during the catastrophic disruption event that formed Benu. The noted albedo and colour diversity of the boulders, and the distinct metre-scale components visible in some of them, may point to the compositional diversity of Benu's parent body and/or its catastrophic impactor.

Boulder geology of Benu

The spatial distribution of boulders on the surface of Benu is not uniform. We find concentrations of boulders in some local topographic lows⁴ (tens-of-metres elevation differences relative to the surrounding terrain), with boulder abundances up to an order of magnitude greater than the global average (Fig. 2). These collections of boulders stand in contrast to topographic lows on Itokawa, which are distinct for their lack of large boulders and collections of small grains¹¹.

The boulders on Benu's surface also exhibit diversity in size, geologic context and morphology. To date, boulders >8 m in diameter have been adequately resolved with PolyCam images, for which we have measured a size-frequency distribution best fit with a power-law index of -2.9 ± 0.3 (ref. ²). Many of these boulders appear to be resting on top of the surface, while some are partially buried, pointing to active burial and/or exhumation processes. Several examples of imbricated boulders have been identified, although these locations are smaller in extent than the imbricated regions observed on Itokawa¹¹, with no obvious correlation between imbrication and fine-grained deposits. Both rounded and angular boulders are present on the surface, which may suggest a variety of formation mechanisms, compositions and/or boulder evolutionary processes.

We observe fractured boulders exhibiting multiple fracture types. Some of the most dramatic examples include large, linear fractures that appear to split boulders into two or more pieces (Fig. 1c,d). These occur at all resolvable scales and within some of the largest boulders on the surface. In contrast, other boulders exhibit nonlinear fractures that suggest some interaction between the fracture-driving mechanisms and the rock bulk structure (Fig. 1e). We also found examples of discrete, yet tightly clustered metre-scale boulders that appear to have fractured in situ, and remain in clusters with minimal displacement (Fig. 1f). Complex networks of fractures also occur in some boulders (Fig. 1c,d), with many deep fractures crossing each other at various angles, although some are clearly linear. These numerous and morphologically varied fractures may be produced by one or a combination of processes, such as large-scale impact events, micrometeoroid impacts and thermal fatigue. The latter two processes may also be responsible for the shallow fractures and surficial features observed on visibly textured boulders, which indicate exfoliation, near-surface disaggregation or regolith production processes (for example, refs. ^{20–22}).

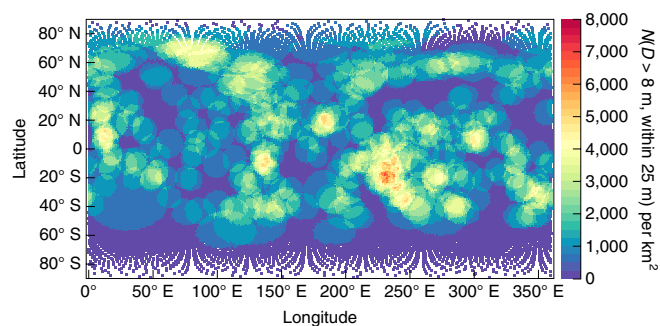


Fig. 2 | Boulder abundance map of the surface of Bennu. The abundance of boulders for each location on the surface of Bennu based on a 49,152-facet shape model of the surface, where the boulder abundance (N) is calculated by counting the number of boulders larger than 8 m within a radius of 25 m in each facet and then normalized to square kilometre.

Although boulder fracture could potentially represent past processing on Bennu's parent body, the abundance of fractured boulders and some cases where boulders appear to have disaggregated in situ points to surface processes active in Bennu's recent geologic history, since it evolved to a near-Earth orbit. However, these fracture formation mechanisms need time to operate, suggesting that the surface has not been dynamically refreshed since Bennu's transition from the main belt to its near-Earth orbit, where a typical NEA's dynamical lifetime is on the order of 10 million years²³. Breakdown due to micrometeoroid bombardment and thermal fatigue is predicted to be faster and slower, respectively, in the main belt than in near-Earth space^{20,22,24}. However, the relative efficiencies of these and other active processes are not well constrained, making it difficult to use fractures to assess absolute surface age. Some processes also act over multiple timescales, such as thermal fatigue, which may generate fractures over different spatial scales owing to diurnal and annual thermal cycles.

Craters of Bennu

Bennu has experienced a number of impacts that have transformed its surface. We have identified several tens of candidate impact craters, which range in size from approximately 10 m to more than 150 m in diameter. The characteristics of distinct candidate impact craters include circular features with raised rims and depressed floors, and/or clear textural differences (apparent concentration or lack of boulders) between the interior and exterior of the crater. Less-distinct candidate craters have subdued rims or an absence of raised rims, shallow interiors, and lack of contrast between the interior and exterior boulder populations. Based on current image data, we have identified 12 distinct, and at least 40 less-distinct, candidate craters. Notably, several large distinct craters are located on Bennu's equatorial ridge, suggesting that the ridge is an old feature (Fig. 3).

We used the population of large distinct candidate craters (diameter $D > 50$ m) to estimate the age of Bennu's surface. Assuming that the craters record impact events, they are primarily a record of Bennu's history in the main asteroid belt²⁵. Crater scaling laws can convert impact parameters to crater diameters, although for small rubble-pile bodies there is added uncertainty due to their microgravity regime^{26,27}. By applying Bennu's physical properties to these scaling relationships (for example, a crater scaling law for dry soil with a strength of 0.18 MPa (ref. ²⁶)), we can estimate the ratio of crater to projectile diameters. The size-frequency distribution of main-belt projectiles striking Bennu is assumed to follow the collisional evolution results²⁵, while the intrinsic collision probability of Bennu with a main-belt projectile is assumed to be fairly similar to Gaspra, a relatively low inclination asteroid residing in the innermost region of the main belt (where the intrinsic

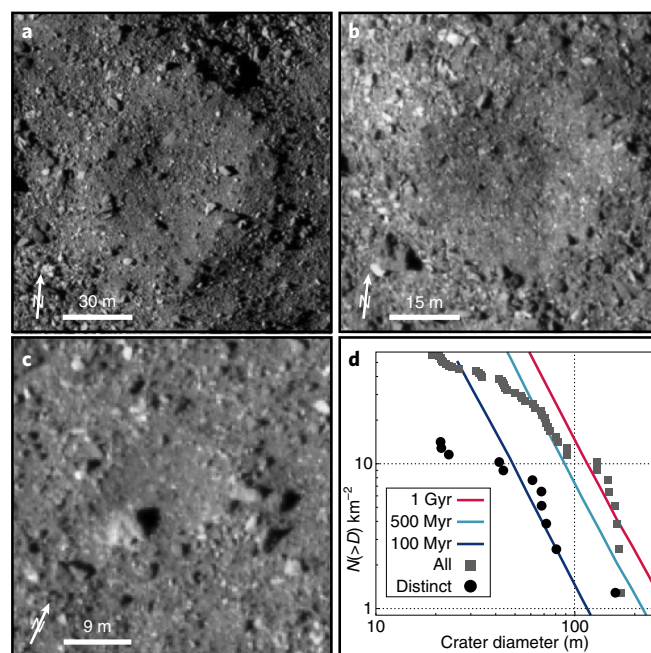


Fig. 3 | Examples of Bennu's craters. **a**, A feature on Bennu's surface that meets all of the criteria to be considered a candidate crater, including clear topography associated with its rim. This candidate crater is centred at 3° S and 152° E and has a diameter of 81 m. **b**, A distinct candidate crater located at 5° S and 126° E with diameter of 44 m differs in texture between the inside and outside of its rim and shows a distinct lack of boulders. **c**, Example of a less-distinct candidate crater located at 54° N and 68° E, with some textural differences between the inside and outside of the circular feature, but that shows only hints of a circular shape with no clear topography. **d**, The established 'distinct' candidate craters provide a lower bound on age by comparing their distributions to the expected crater production function (see Methods), and we use the entire population of less-distinct candidate craters to estimate an upper bound. In both groups, the change in size-frequency distribution appears around $D = 50$ m. Images taken on: **a, b**, 2 December 2018 from a distance of 23.7 km; **c**, 2 December 2018 from a distance of 23.5 km.

collisional probability is $P_i = 2.8 \times 10^{-18} \text{ km}^{-2} \text{ yr}^{-1}$)²⁸. These components, when combined with Bennu's cross-section²⁸, can be fit to Bennu's $D > 50$ m craters. We find that it would take between 100 million and 1 billion years to explain the origin of Bennu's largest crater candidates (Fig. 3d).

However, cratering into low-strength material under low-gravity conditions may lead to larger crater diameters, which in turn could lead to younger age estimates²⁷. Conversely, cratering into high-porosity material may lead to reduced diameters and older age estimates²⁹. It is possible that determining the surface exposure age of the returned sample will quantitatively constrain Bennu's crater retention age and provide a better understanding of which aspects play dominant roles in crater formation on Bennu and other high-porosity, low-strength targets.

The imaging and topographic data allowed identification of craters approximately 10 m and larger. The observations show a depletion of small craters ($\sim 10 \text{ m} < D < 50 \text{ m}$) relative to expectations based on the production rate of large craters (Fig. 3d). The depletion of small craters has also been found on other NEAs including Itokawa and Eros^{30,31}. The prevalence of boulders on the surface can potentially stifle the formation of small craters, whereby impactors strike and break boulders rather than making craters³². Conversely, the depletion of small craters may reflect,

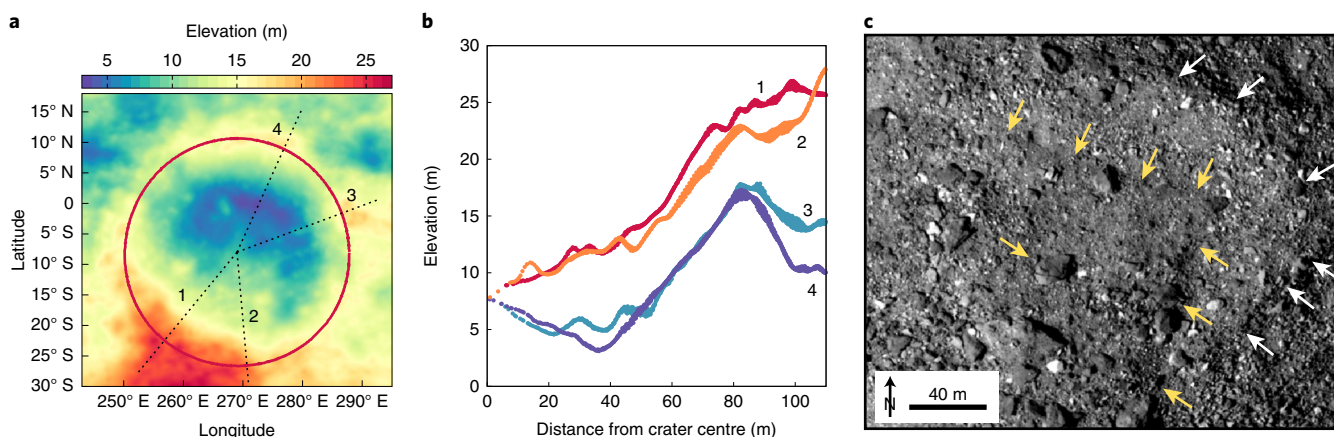


Fig. 4 | Flow of material into a $D = 160$ m candidate crater. **a**, A large candidate crater is centred near the equator at 8° S and 269° E, and initial measurements indicate a diameter of 160 m. The drawn circle outlines the crater rim and four dotted lines indicate profiles along which elevation was extracted radially from the centre of the crater outward. **b**, The elevation profiles for the different regions of the crater, where the profiles 1 and 2 show that the southwest region of the crater is elevated relative to the rest of the crater shown with profiles 3 and 4. The mass movement appears to have overtopped the crater rim and covered parts of the crater with metres of material. **c**, Image showing the relationship between the material flow and the candidate crater. White arrows indicate the crater rim, and yellow arrows indicate the edge of the flow which has entered the crater from the west (the flow correlates with the elevated portion of topographic profiles 1 and 2). Stratigraphic relationships show that the flow occurred after the formation of the crater. Leftmost yellow arrow indicates additional material movement that has partly buried the westernmost portion of a larger boulder (which is also shown in Fig. 1c). Image used for **c** was taken on 1 December 2018 from a distance of 31.8 km.

as previously postulated, crater erasure due to surface material movement and/or seismic shaking^{33,34}. There are clear examples on some large candidate craters on Bennu of material movement and crater infill, where the thickness of the fill layer is comparable to the depth of small craters (Fig. 4)⁴.

Regolith of Bennu

The interiors of many small candidate impact craters ($D < 20$ m) are largely devoid of resolvable boulders (Fig. 3). These locations may be reservoirs for smaller particles produced or exposed during the crater formation process. Similarly, boulder-fracturing processes or abrasion and mechanical erosion between boulders during surface material movement could each contribute to the production of fine grains more widely across the surface of Bennu.

There is some evidence that fine-grained material (of the centimetre-scale sizes that are ingestible by the OSIRIS-REx sample mechanism³⁵ and of smaller, micrometre-scale sizes) is present despite not being resolved with current imaging. The measured thermal inertia is consistent with a population of centimetre-sized particles². The phase reddening observed with the MapCam images suggest some photometric contribution by micrometre-sized particles². Thermal emission spectra¹⁴ exhibit evidence of a surface dominated by particles greater than $125\ \mu\text{m}$ at spatial scales of approximately 80 m, but these data cannot provide more specific information on the range of particle sizes greater than $125\ \mu\text{m}$ or rule out the presence of a small fraction of particles smaller than $125\ \mu\text{m}$.

Finally, certain regions only a few metres in size have large albedo differences and lack observable boulders, suggesting that they are dominated by unresolved (< 1 m) particles¹. Other fine-particulate patches appear as surficial layers indiscriminately draped over boulder and inter-boulder areas alike². However, low-albedo deposits do not mask the outlines of boulders. The dark material comprising these patches may be dust or fine particles.

History of Bennu

The large boulders on the surface of Bennu may provide information about the composition and geology of its parent body, as well as the collision that disrupted it. The observed impact breccias may have formed during the evolution of its parent body, through

repeated impact events on its surface over most of Solar System history, or during the large impact event that resulted in the formation of Bennu. Alternatively, these breccias may even date to the accretion of the original parent body in the protoplanetary disk.

The retention of large craters on Bennu's equatorial ridge requires that the surface age predates the expected approximately 10-million-year duration as a NEA. There is no clear geologic indication of the process that formed the ridge, and given its relation to the large craters it could be a feature preserved from the formation of Bennu³⁶, which would make it the oldest feature on its surface^{4,13,31}. Bennu's surface therefore also recorded processes from its time in the main belt; the formation timescales of the largest craters suggest that Bennu recorded hundreds of millions of years of history during this period.

Bennu retains very old craters despite evidence of continued and varied surface evolution. The processes that have removed small craters may be size limited or spatially localized and therefore cannot efficiently erase larger craters. The crater infill observed on the largest distinct crater has deposited an approximately 5-m-thick layer of material inside the crater and has partially degraded a large swath of the crater rim (Fig. 4). If surface material movement of this scale were to act widely and frequently, it could contribute to large-scale resurfacing of the asteroid. However, the old age of the surface of Bennu indicates that this type of event may either be localized, or of low frequency, possibly occurring only during its time as an NEA.

Resurfacing and surface movement will have influenced and resorted the fine-grained surface material that is the final target of the OSIRIS-REx mission³⁷. The returned sample of this material will tell us about processes that occurred since Bennu has been a NEA, while Bennu was in the main belt, and likely processes that occurred on its original parent body and in the solar nebula long before Bennu formed.

Online content

Any methods, additional references, Nature Research reporting summaries, source data, statements of data availability and associated accession codes are available at <https://doi.org/10.1038/s41561-019-0326-6>.

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Author contributions

K.J.W. led the mapping, analysis and manuscript writing. E.R.J., R.-L.B., O.S.B., E.B.B., H.C.C., J.L.M. and T.J.M. contributed to the mapping, analysis and writing of the manuscript. D.S.L. leads the mission and contributed to analysis and writing. M.D., C.M.H., M.P., S.R.S. and D.T. contributed to mapping and manuscript writing. E.A., K.J.B., C.B.B., W.F.B., C.A.B., K.N.B., B.C.C., M.G.D., D.N.D., J.P.D., C.M.E., D.R.G., A.R.H., R.M., J.M., P.M., M.C.N., M.E.P., B.R., A.R., D.J.S., H.C.C., S.A.S., H.C.M.S. and F.T. all contributed to the mapping, analysis or manuscript writing. The entire OSIRIS-REx Team made the Benu encounter possible.

Competing interests

The authors declare no competing interests.

Additional information

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Methods

Initial boulder identification was carried out following the methods outlined in ref. ². Subsequent detailed mapping and geologic analyses of boulders were performed by a visual analysis of PolyCam and MapCam data using the Small Body Mapping Tool (SBMT), which projects spacecraft images onto a shape model³⁸. Boulders were mapped by drawing an ellipse around the resolved boulder margins; this method allows for the analysis of both long and intermediate axis lengths, as well as boulder orientation. Boulders were viewed under a range of viewing geometries including various phase angles and illumination angles. Detailed boulder morphology was assessed using a combination of unprojected images which facilitated fine-scale analyses, and projected images within SBMT, which provides geologic context. Boulder abundance (Fig. 2) was calculated using a 49,152-facet shape model⁴, where the boulder abundance was calculated by counting the number of boulders larger than 8 m within a 25 m radius in each facet and then normalizing to 1 km². Image for Fig. 1a is ocams20181201t055746s307_pol_iofl2pan_63551 taken on 1 December 2018 from a spacecraft distance of 31.5 km. Fig. 1b,d is from image ocams20181202t072303s706_pol_iofl2pan_63785 taken on 2 December 2018 with a spacecraft distance 24.0 km. Fig. 1c is taken from image ocams20181202t082747s619_pol_iofl2pan_63714 taken on 2 December 2018 with a spacecraft distance of 23.8 km. Fig. 1e is taken from image 20181202T064001S485_pol_iofl2pan taken on 2 December 2018 with a spacecraft distance of 24.2 km. Fig. 1f is taken from image 20181202T084918S806_pol_iofl2pan taken on 2 December 2018 with a spacecraft distance of 23.6 km.

Crater identification and measurement was performed using a combination of projected and unprojected PolyCam and MapCam images, as well as stereophotoclinometry-derived topography data⁴. All mapping was carried out in SBMT by mapping ellipses around the maximum extent of the resolvable crater rim. Multiple members of the team mapped the surface for craters and only those mapped by multiple members as distinct crater candidates were counted in the 'distinct' category for the purposes of analysis. All mapped individual craters were included in the 'non-distinct' group. To calculate surface age, we used the largest

craters to estimate a range of possible surface ages based on the impactor size distribution found in the main belt, an average main-belt impact probability and impact velocity ($P_i = 2.8 \times 10^{-18} \text{ km}^{-2} \text{ yr}^{-1}$ and $v_i = 5.3 \text{ km s}^{-1}$)^{25,39}, and a crater scaling law for dry soil with a strength of 0.18 MPa (ref. ²⁶). The clearly established 'distinct' candidate craters, normalized to one square kilometre, provide a lower bound on age, and we use the entire population of less-distinct candidate craters to estimate an upper bound. In both groups, the change in size-frequency distribution appears around $D = 50 \text{ m}$. Image ocams20181202t083822s735_pol_iofl2pan_64172 was used for Fig. 3a,b and was taken on 2 December 2018 from a spacecraft range of 23.7 km. Image for Fig. 3c was ocams20181202t091159s321_pol_iofl2pan_64104 and was taken on 2 December 2018 from a spacecraft range of 23.5 km. Image ocams20181201t051455s588_pol_iofl2pan_63071 was used for Fig. 4c and was taken on 1 December 2018 from a spacecraft distance of 31.8 km.

Many of the geologic assessments relied on elevation, which was derived from shape model v14. The construction of the shape model, and different versions of the shape model, and calculation of elevation is described in detail in a companion paper⁴.

Data availability

Raw through to calibrated datasets will be available via the Planetary Data System (PDS) (<https://sbn.psi.edu/pds/resource/orex/>). Data are delivered to the PDS according to the OSIRIS-REx Data Management Plan available in the OSIRIS-REx PDS archive. Higher-level products, for example, global mosaics and elevation maps, will be available in the PDS one year after departure from the asteroid.

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