

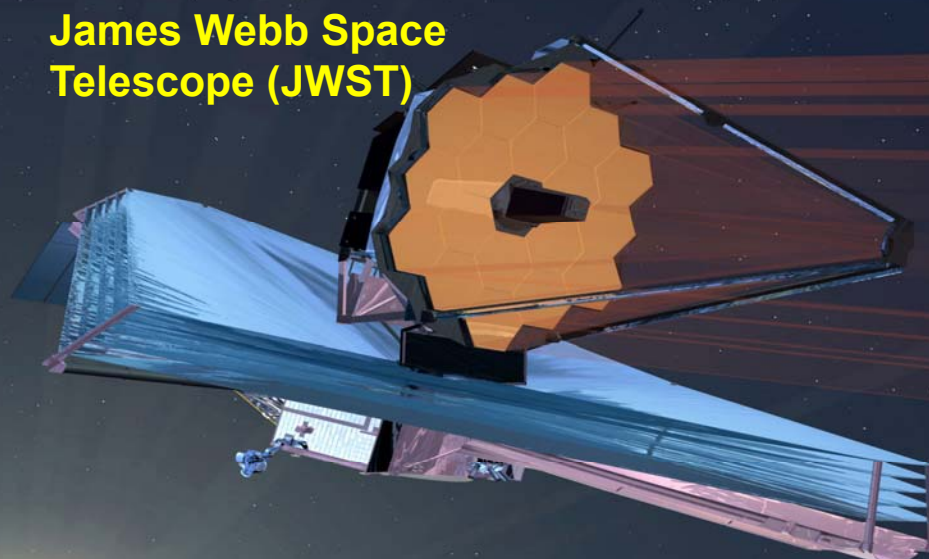
NASA's Work in Exoplanet Hunting Satellites and Robotic Servicing of Satellites

Kevin H. Miller
NASA Goddard Space Flight Center
March 26th 2019



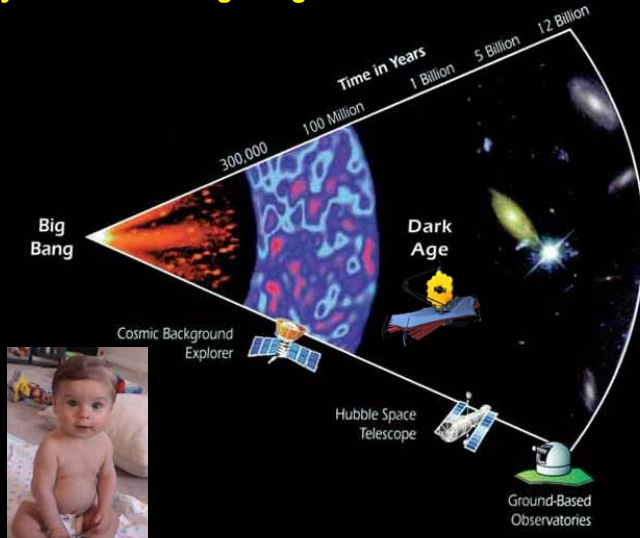
Ramapo College of New Jersey

James Webb Space Telescope (JWST)



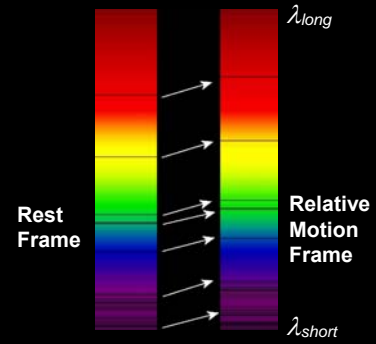
- JWST is the “follow-on” mission to the Hubble Space Telescope (HST)
 - Wavelength overlap with HST but coverage is not the same.
- First space telescope to be “built” on-orbit – too large to be launched already assembled.
- Mission concept formulated in 1995, 2018 launch date.

Primary Science Goal for JWST is to observe the Universe when it first began to emit light, approximately 200 Million years after the Big Bang



Distant astronomical sources have redshifts (z) of 10 or more

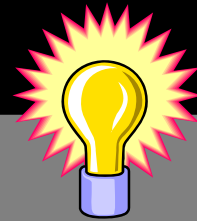
$$\lambda_{motion} = \lambda_{rest} + z \lambda_{rest}$$



Due to the Doppler shift of the emitted light, looking back that far in time requires the ability to make infrared observations



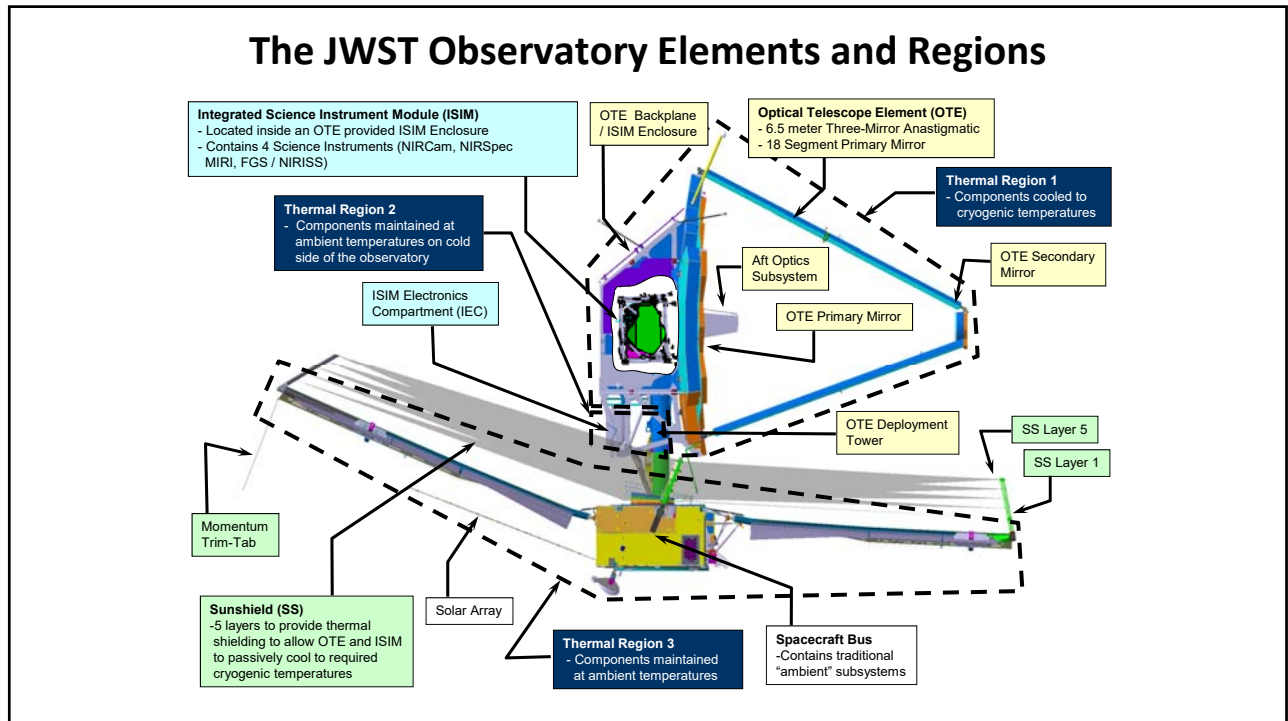
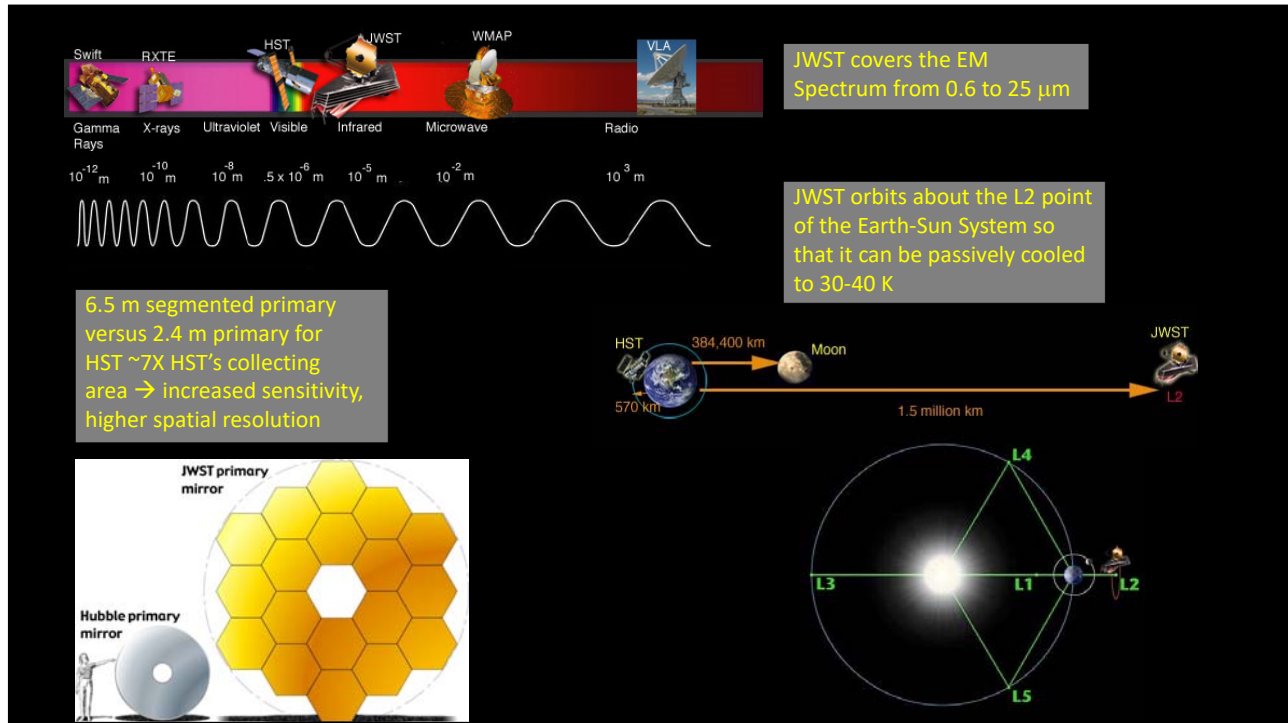
$$V = 224844 \text{ km/s}$$

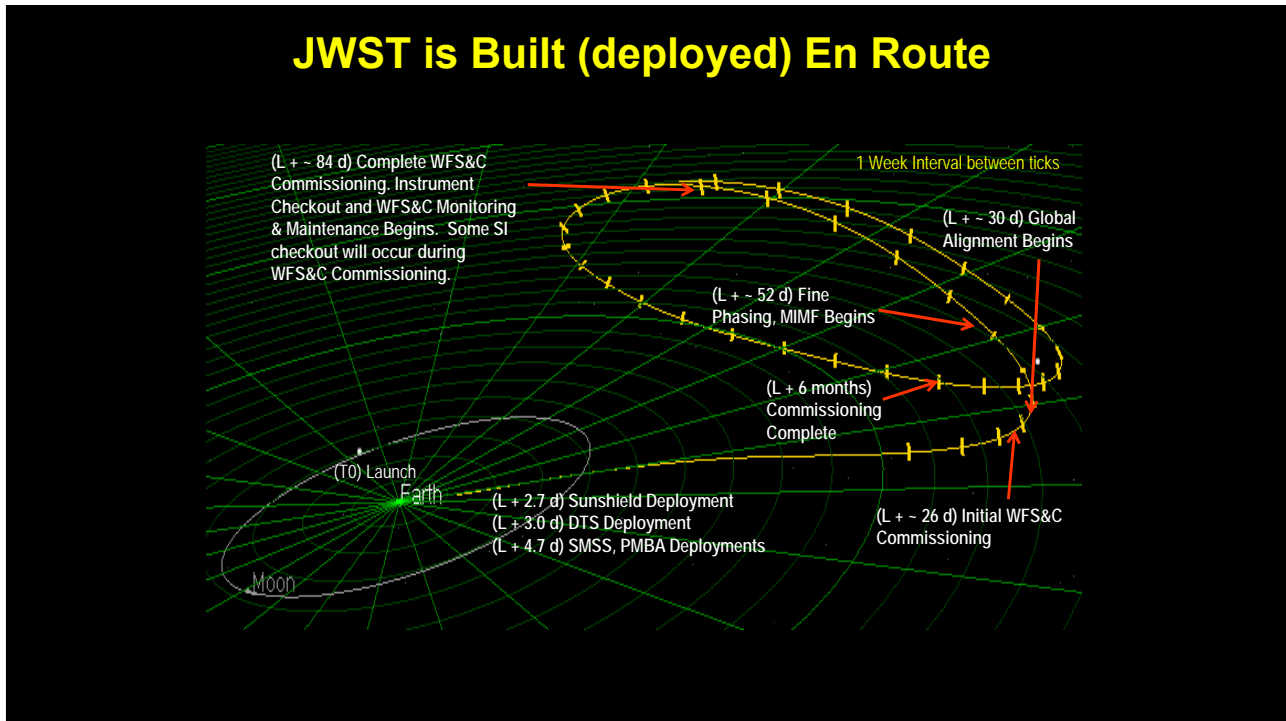


In the infrared, the hotter an object is → the brighter it appears



Wavelength (nm)







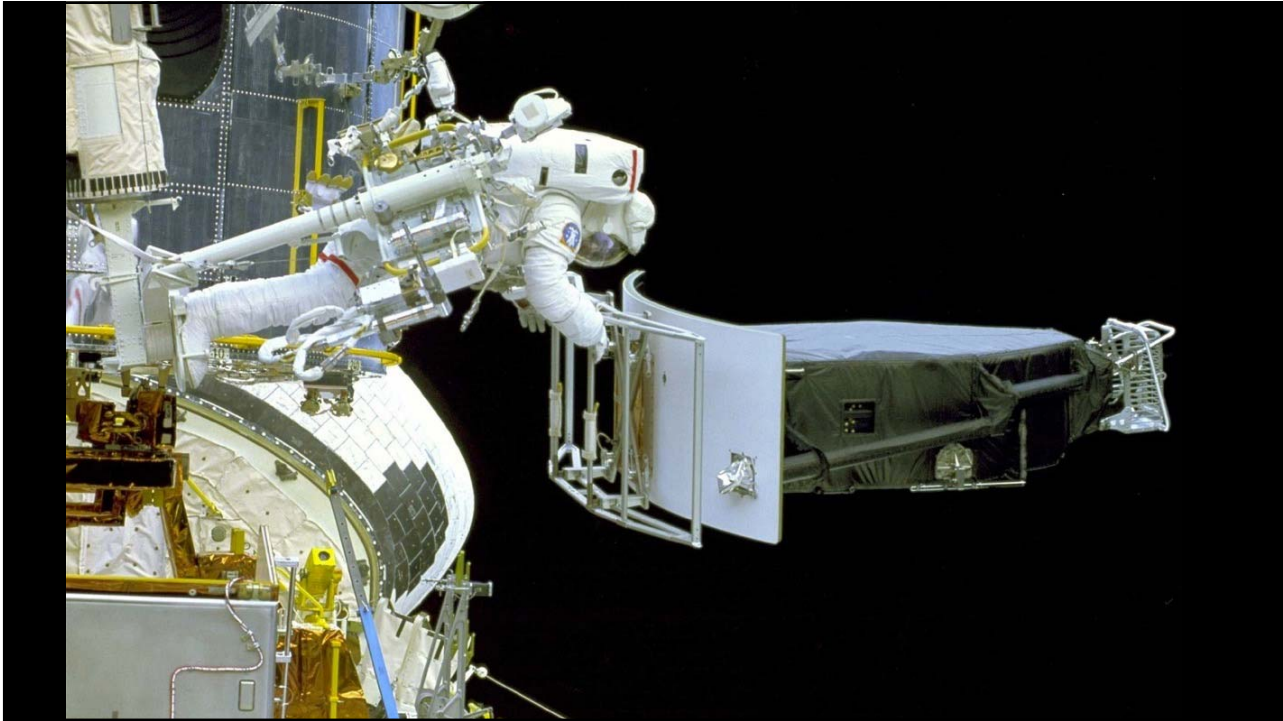


Why Servicing?

Satellite servicing allows us to maintain, repair, and upgrade our satellites in-orbit, drastically reducing the cost of conducting science and exploration

- **To expand our knowledge and understanding of the Earth and the universe**
 - Upgrades to critical satellites allow us to leverage technological advancements
- **To protect our national interests and maintain U.S. space leadership**
 - Servicing offers resilience in a dynamic threat environment
 - Satellite servicing helps America maintain and extend the lifespan of its key assets, and the technologies can be applied to key NASA missions
- **To provide economic and cost benefits**
 - Modularity and serviceability cut down on costs by delivering upgraded instruments and by extending satellites' lifespans





RESTORE-L

1 Autonomous Rendezvous, Inspection

2 Autonomous Capture

3 Telerobotic Refuel & Relocate

The diagram illustrates the RESTORE-L mission process. It features three numbered steps on the left, each accompanied by a small satellite icon. Step 1 shows a satellite approaching a larger satellite. Step 2 shows the satellite capturing the larger satellite. Step 3 shows the satellite performing a refueling operation on the larger satellite. In the center, a large satellite with two robotic arms is shown. To the right, a smaller satellite is shown with a large antenna dish.

Era of One and Done

The infographic displays the orbits of numerous NASA satellites and spacecraft. The background is a dark space with a large orange sun on the left. The orbits are shown as curved lines around the sun and planets. The satellites are labeled with their names, including: TRACE, ACE, Polar, TWINS (Instrument), Messenger, LAGEOS, LRO, RHESSI, SORNO, IMAGE, FAST, IBEX, Cassini, Juno, Galileo, Mars Science Laboratory, MAVEN, MMS, Solar-B, IBEX, Cassini, Juno, Galileo, Mars Science Laboratory, MAVEN, THEMIS, SDO, Aquia, Terra, Aura, NPP, NuSTAR, Spitzer, Astro-H, Fermi, Swift, FUSE, Integral, IUE, EUVE, Compton GRO, QuikSCAT, ACRIMSAT, Landsat 7, TOPEX, CALPISO, GRACE, SORCE, GOES, GPM, TDRSS, LDCM, CloudSat, Aquarius, WMAP, JWST, HST, SWAS, RXTE, GALEX, WMAP, JWST, HST, SWAS, RXTE, GALEX, WMAP, JWST, HST, SWAS, RXTE, GALEX, WMAP. Three yellow circles highlight the orbits of HST, JWST, and Compton GRO.



TESS

Project Description

NASA's next Exoplanet hunter

Launched April 2018

George Ricker (P.I.)
Massachusetts Institute of Technology

collaboration including:
NASA Goddard, NASA Ames, MIT Lincoln Lab, Orbital ATK, STScI, SAO, Harvard/Smithsonian, MPA-Germany, Las Cumbres Observatory, Geneva Observatory, OHP-France, University of Florida, Aarhus University-Denmark, Harvard College Observatory, Vanderbilt University

Transit Method

PLANET QUEST
THE SEARCH FOR ANOTHER EARTH

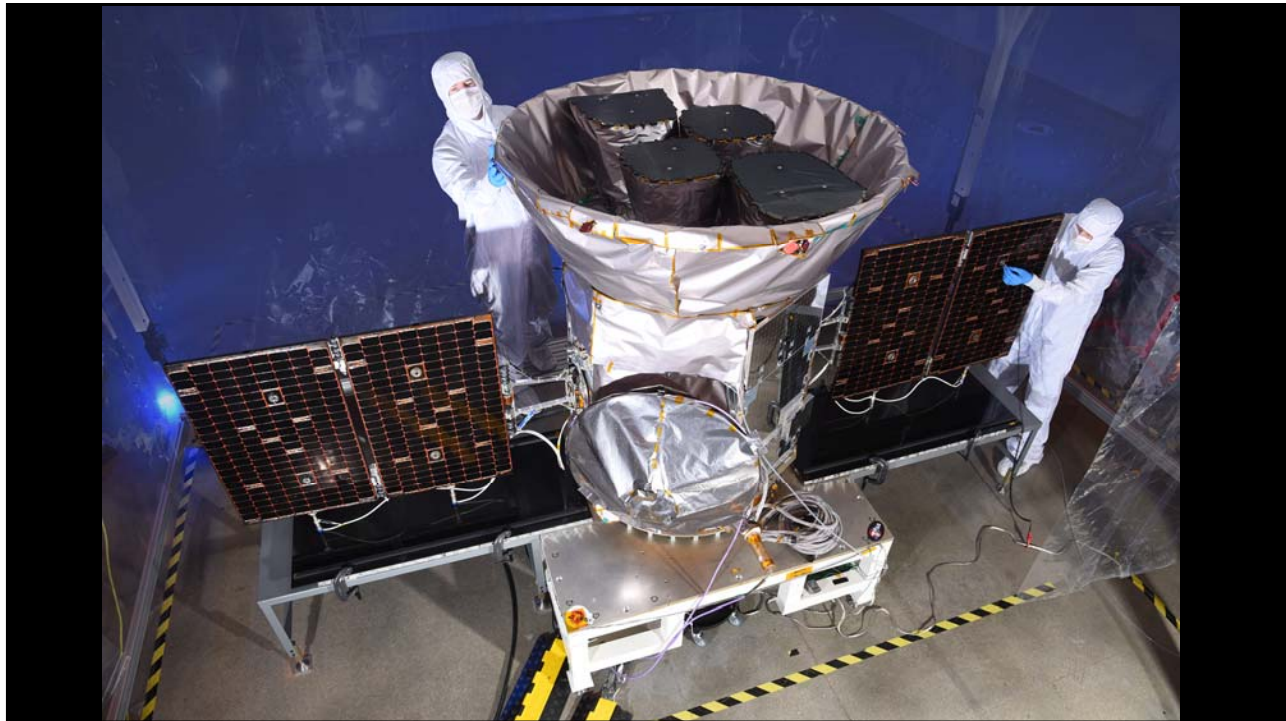
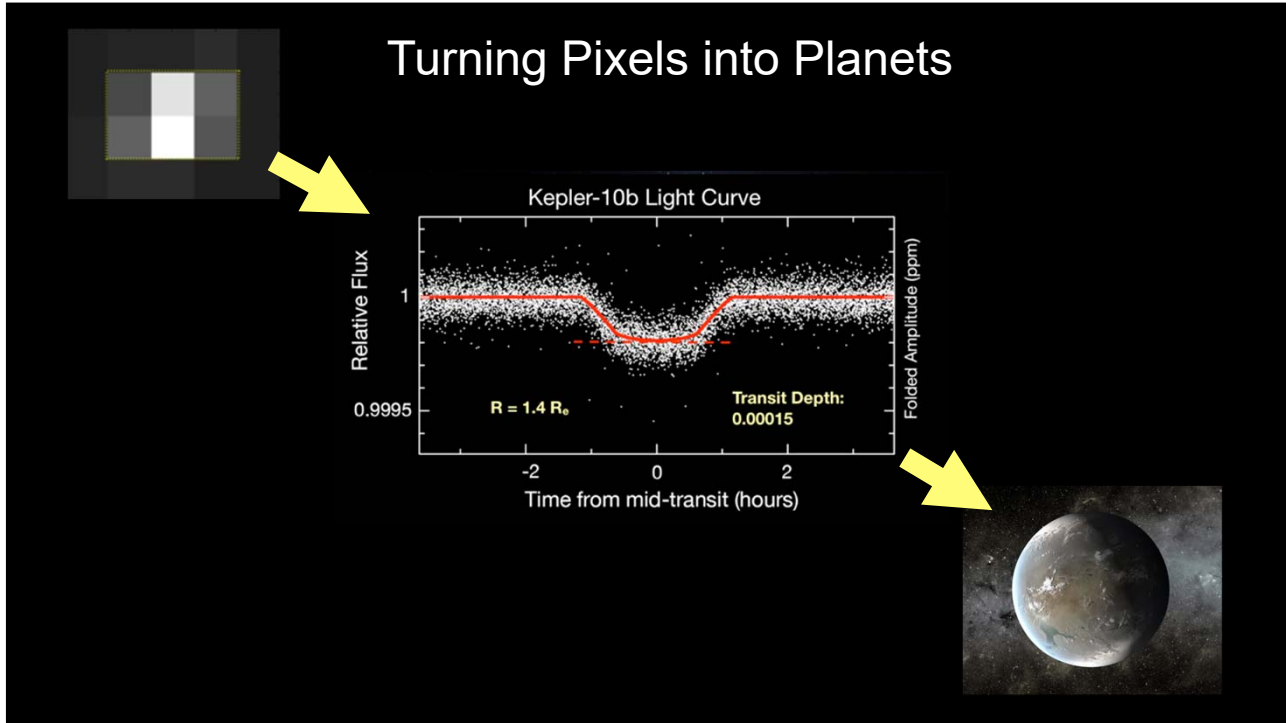


LIGHT

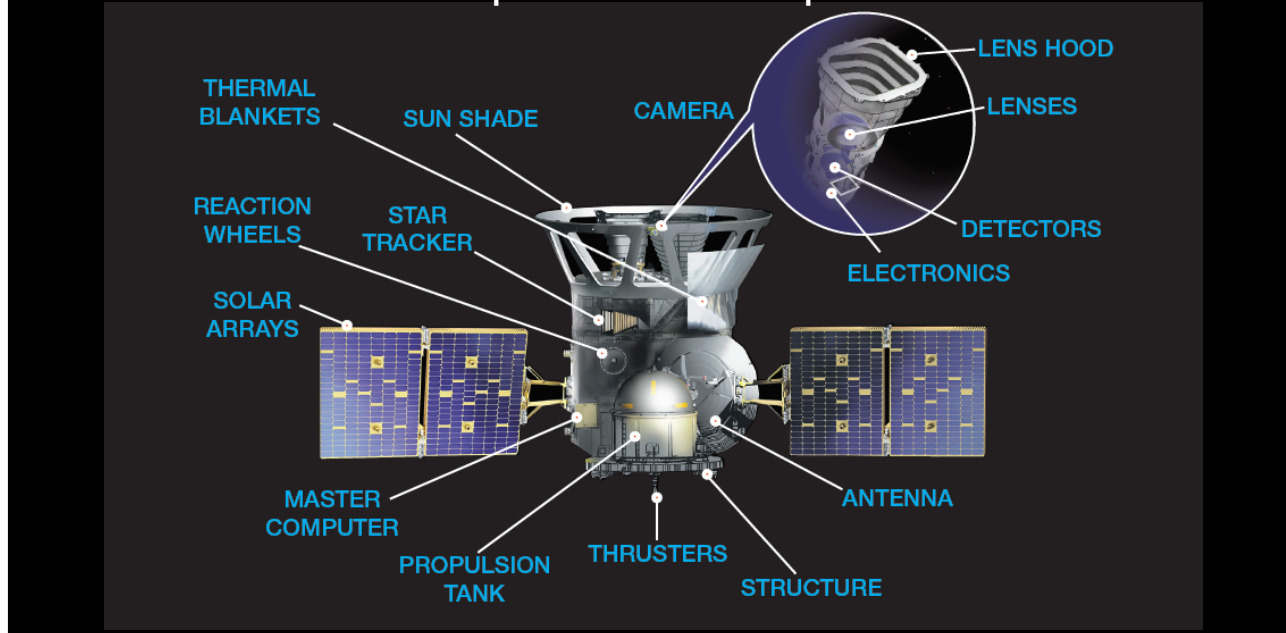
TIME

LIGHT

TIME

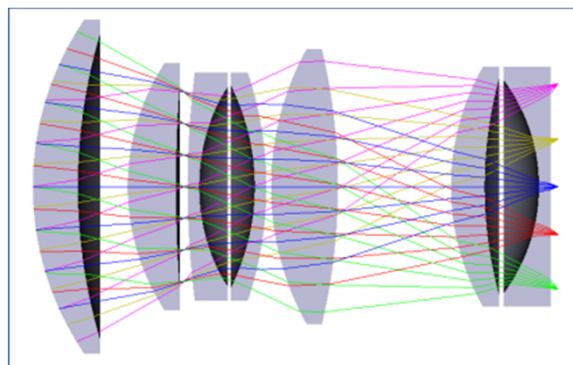
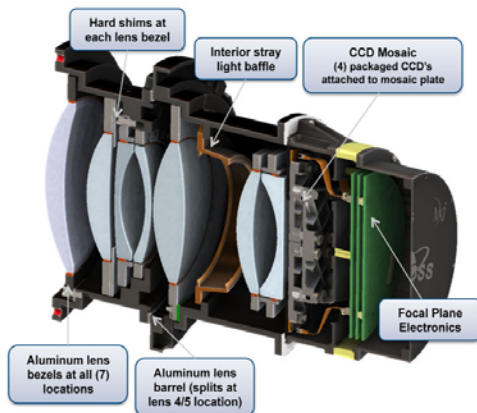


TESS Spacecraft Components



TESS Lens Assembly Characterization

- Contains 7 distance Ohara glasses
- Lens assembly is a Hybrid Petzval Design
- Operational Wavelength Range: 0.6 – 1.0 μm
- Operational Temperature Range: 183 – 213 K
- Index Characterization Wavelength Range: 0.42 – 1.1 μm
- Index Characterization Temperature Range: 120 – 300 K



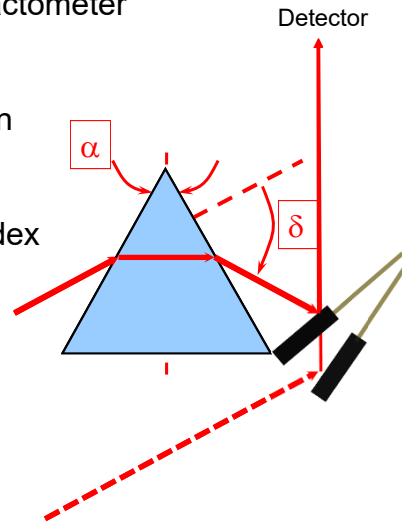
CHARMS Capabilities

- Absolute minimum deviation refractometer (in vacuum)
- Wavelength coverage: 0.35 to 5.6 μm
- Temperature coverage: 15 K (using LHe) to 340+ K (67 C)
- Single measurement ABSOLUTE accuracies as good as 5×10^{-6} at cryo (depending on material)
- Measures absolute refractive index, $n(\lambda, T)$
- Accurate values of thermo-optic coefficient, dn/dT , and spectral dispersion, $dn/d\lambda$, derived from measured $n(T)$

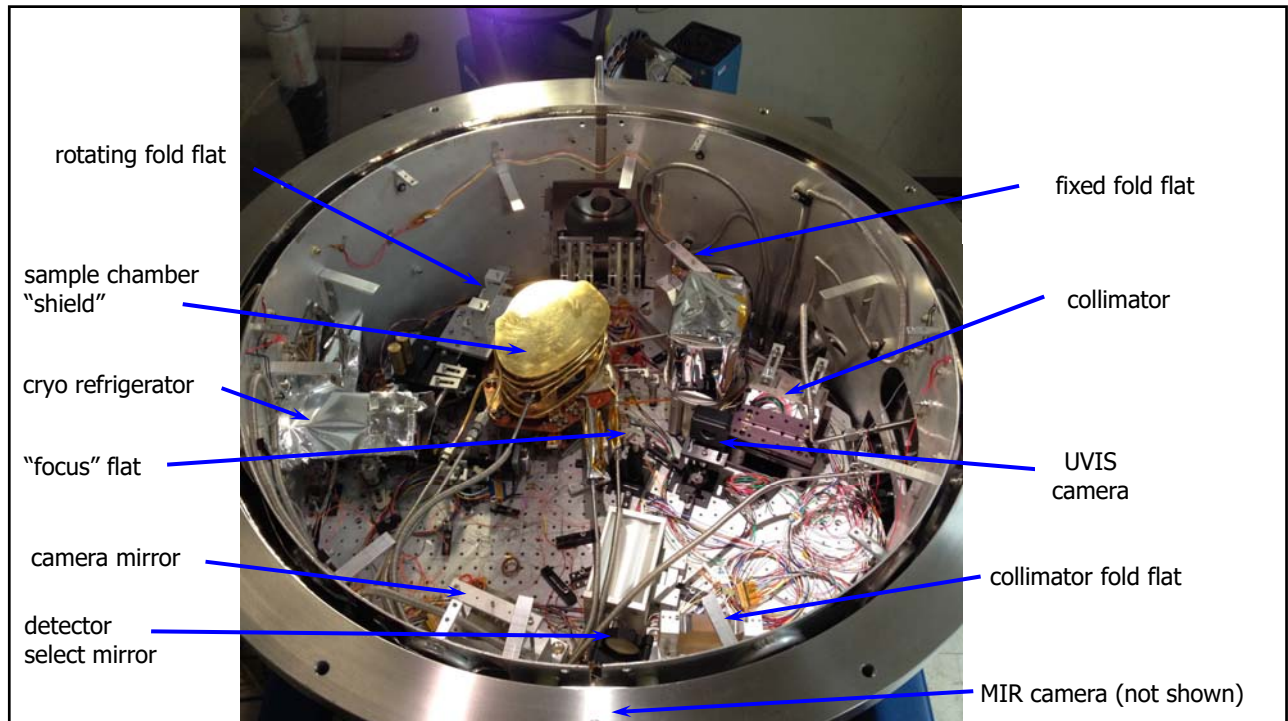
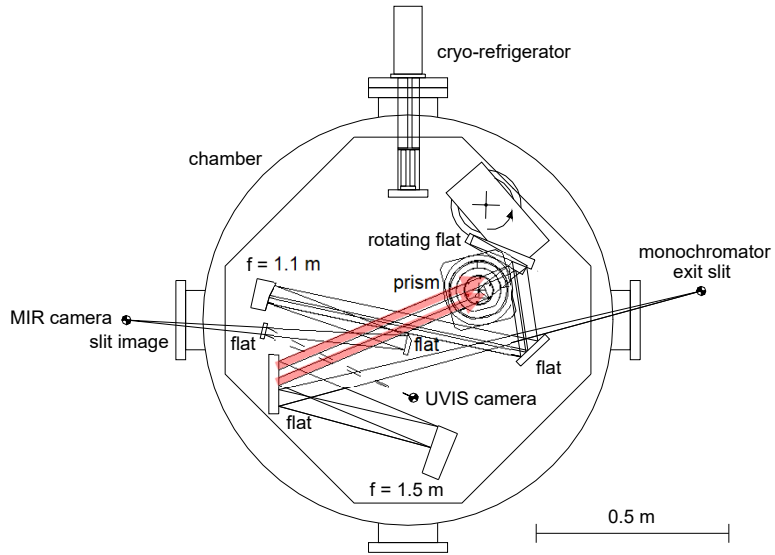
CHARMS: Operation and Capabilities

- CHARMS is a minimum deviation refractometer
- Five simple steps:
 1. Measure the apex angle of the prism
 2. Establish the condition of min deviation
 3. Measure angle of undeviated beam
 4. Measure angle of deviated beam
 5. Compute deviation angle; compute index

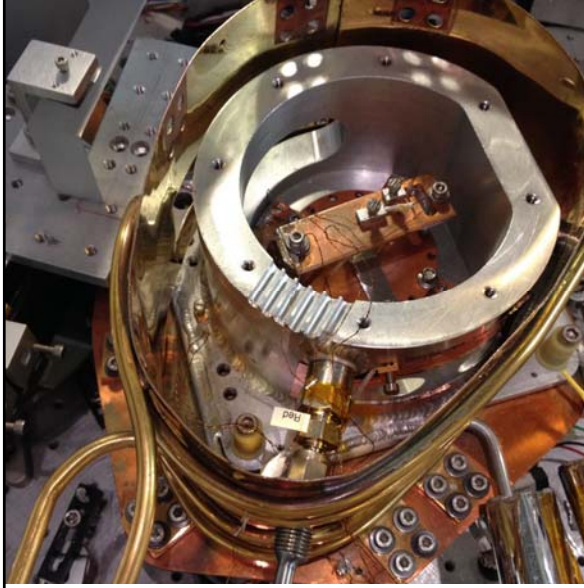
$$n = \frac{\sin\left(\frac{\alpha + \delta}{2}\right)}{\sin\left(\frac{\alpha}{2}\right)}$$



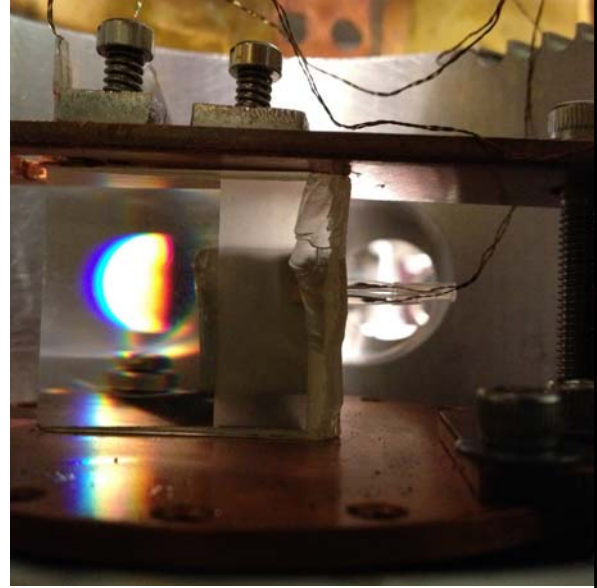
CHARMS optical layout



Top view of sample chamber

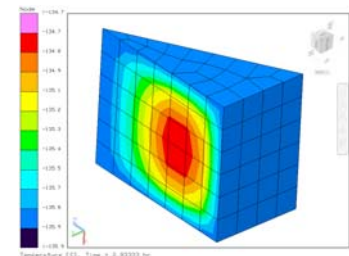
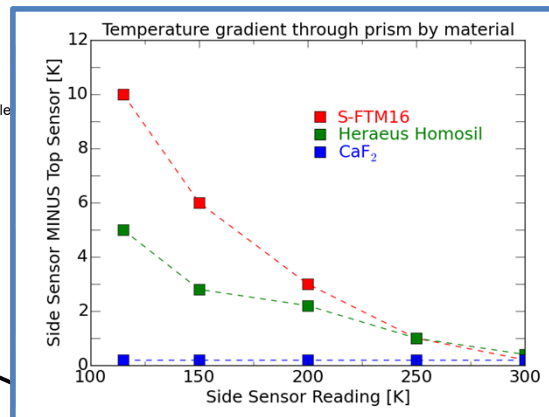
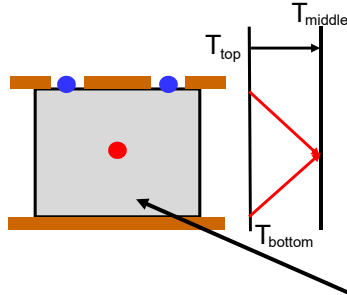


Eye level with prism



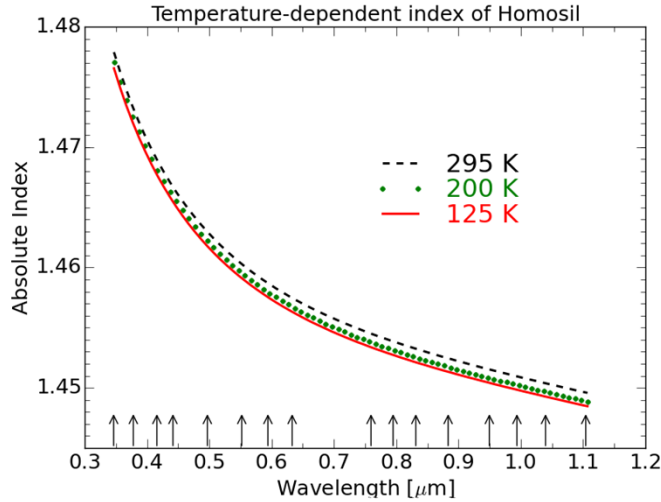
Sample Temperature, T

- sample sandwiched between two cryogen-cooled copper plates at essentially same T
- two T sensors on **top of prism**
- T_{sample} attributed to reading from sensor halfway up **side** of non-refracting face



Courtesy of S. Scola – NASA LaRC

CHARMS Measurements of Heraeus Homosil



Sellmeier Equation

$$n^2(\lambda, T) - 1 = \sum_{i=1}^3 \frac{S_i(T) \cdot \lambda^2}{\lambda^2 - \lambda_i^2(T)}$$

$$S_i(T) = \sum_{j=0}^3 S_{ij} \cdot T^j$$

$$\lambda_i(T) = \sum_{j=0}^3 \lambda_{ij} \cdot T^j$$

$$AAR = \frac{\sum_{k=1}^n |index_{measured} - index_{fit}|}{n}$$

Homosil_AAR = 2.04 x 10⁻⁶

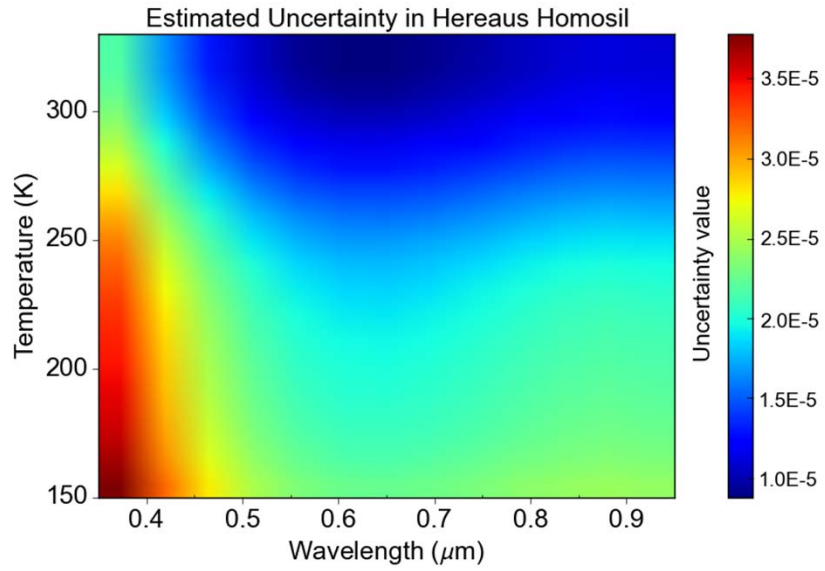
Example of Bookkeeping Error Budget

index n	apex α	deviation δ	dn/dλ	dn/dT	dn/dα	dn/dδ	dλ	dT	da	dδ	→ dn										
SENSITIVITIES																					
15.974	100 deg	0.175 rads	0.595 deg	0.080 rads	0.00040nm	0.000120K	-2.95rad	0.00040nm	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-3.3E-06	0.00150 deg	0.4 sec	###	7.9E-05	9.5E-05
14.574	20	0.349 rads	9.319 deg	0.183 rads	0.00040nm	0.000120K	-1.35rad	2.798rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-2.3E-06	0.00150 deg	0.4 sec	###	4.7E-05	7.4E-05
14.574	30	0.524 rads	14.321 deg	0.250 rads	0.00040nm	0.000120K	-0.93rad	1.788rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-1.8E-06	0.00150 deg	0.4 sec	###	3.4E-05	6.4E-05
14.574	40	0.698 rads	19.796 deg	0.346 rads	0.00040nm	0.000120K	-0.73rad	1.267rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-1.5E-06	0.00150 deg	0.4 sec	###	2.4E-05	5.6E-05
14.574	50	0.873 rads	26.038 deg	0.454 rads	0.00040nm	0.000120K	-0.63rad	0.932rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-1.5E-06	0.00150 deg	0.4 sec	###	1.8E-05	5.0E-05
14.574	60	1.057 rads	31.915 deg	0.557 rads	0.00040nm	0.000120K	-0.58rad	0.730rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-1.4E-06	0.00150 deg	0.4 sec	###	1.5E-05	5.0E-05
2.6	10	0.175 rads	16.195 deg	0.283 rads	0.00040nm	0.000120K	-9.27rad	5.588rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-2.3E-05	0.00150 deg	0.4 sec	###	1.6E-04	1.7E-04
2.6	15	0.262 rads	24.677 deg	0.431 rads	0.00040nm	0.000120K	-6.27rad	3.603rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-1.5E-05	0.00150 deg	0.4 sec	###	9.4E-05	1.2E-04
2.6	20	0.349 rads	33.676 deg	0.588 rads	0.00040nm	0.000120K	-4.80rad	2.669rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-1.2E-05	0.00150 deg	0.4 sec	###	6.7E-05	9.1E-05
2.6	25	0.436 rads	43.491 deg	0.759 rads	0.00040nm	0.000120K	-3.95rad	1.910rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-9.7E-06	0.00150 deg	0.4 sec	###	5.0E-05	7.7E-05
2.6	30	0.524 rads	54.587 deg	0.953 rads	0.00040nm	0.000120K	-3.23rad	1.429rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-8.4E-06	0.00150 deg	0.4 sec	###	3.7E-05	6.7E-05
3.4	10	0.175 rads	24.475 deg	0.427 rads	0.00040nm	0.000120K	-13.95rad	5.479rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-3.4E-05	0.00150 deg	0.4 sec	###	1.4E-04	1.6E-04
3.4	14	0.244 rads	34.959 deg	0.610 rads	0.00040nm	0.000120K	-10.11rad	3.734rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-2.5E-05	0.00150 deg	0.4 sec	###	9.8E-05	1.2E-04
3.4	18	0.314 rads	46.295 deg	0.807 rads	0.00040nm	0.000120K	-8.03rad	2.707rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-2.0E-05	0.00150 deg	0.4 sec	###	7.1E-05	9.6E-05
3.4	22	0.384 rads	59.895 deg	1.028 rads	0.00040nm	0.000120K	-6.75rad	1.994rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-1.6E-05	0.00150 deg	0.4 sec	###	5.2E-05	8.0E-05
4.0	10	0.175 rads	30.806 deg	0.538 rads	0.00040nm	0.000120K	-17.48rad	5.377rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-4.3E-05	0.00150 deg	0.4 sec	###	1.4E-04	1.6E-04
4.0	12.5	0.218 rads	39.130 deg	0.683 rads	0.00040nm	0.000120K	-14.13rad	4.134rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-3.2E-05	0.00150 deg	0.4 sec	###	1.1E-04	1.3E-04
4.0	15	0.262 rads	47.947 deg	0.837 rads	0.00040nm	0.000120K	-11.50rad	3.267rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-2.9E-05	0.00150 deg	0.4 sec	###	8.8E-05	1.1E-04
4.0	17.5	0.305 rads	57.461 deg	1.003 rads	0.00040nm	0.000120K	-10.39rad	2.668rad	0.10 nm	4.0E-05	0.1 K	1.2E-05	0.00014 deg	0.5 sec	#	-2.5E-05	0.00150 deg	0.4 sec	###	6.8E-05	9.2E-05

uncertainty governed by all eight quantities in the red box for each measurement for a given specimen (green box)

so, a refractometer should **not** list a single number for accuracy

Measurement Uncertainties



TESS: "First-Light" Image





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Summer Internship Deadline is April 1st : <https://intern.nasa.gov>

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