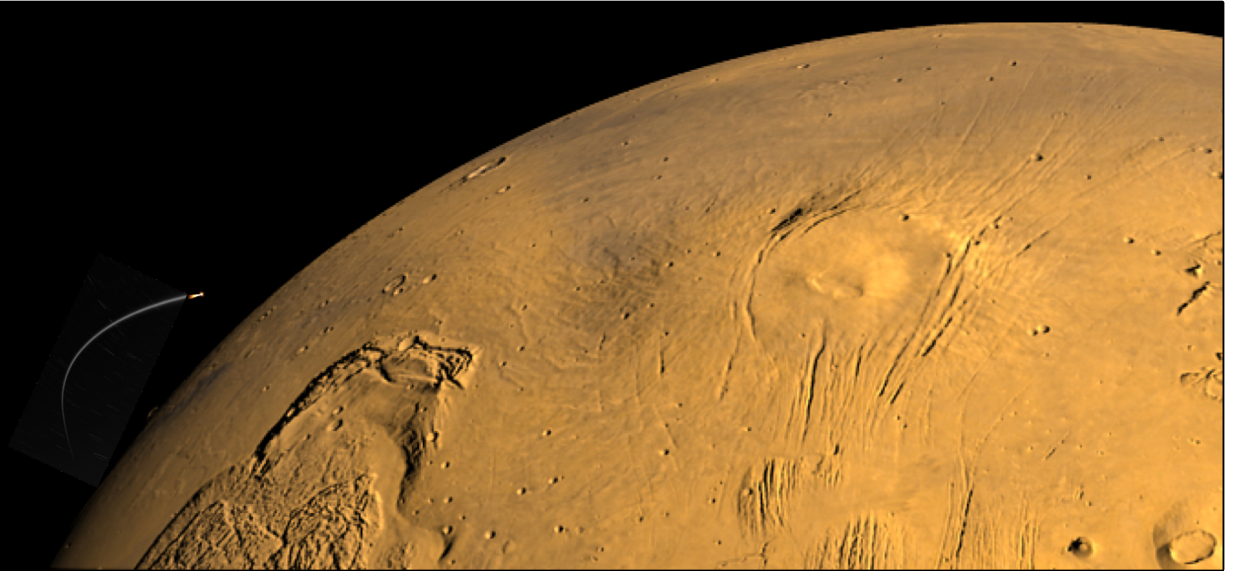


Mars Ascent Vehicle



Jet Propulsion Laboratory
California Institute of Technology



MARSHALL
SPACE FLIGHT CENTER

Mars Ascent Vehicle Propulsion System Solid Motor Technology Plans
Andrew Prince / MAV Solid Propulsion Lead, NASA MSFC

March/2019



Mars Ascent Vehicle Study



Summary

- *Co-authors: Rachel McCauley, Timothy Kibbey, Lisa McCollum, Britt Oglesby, Philip Stenfanski*
- Potential Mars Sample Return Campaign
- Assumptions
- Motor Sizing
- Propellant Selection
- Nozzle and Controls
- Development and Qualification Testing
- Future Work

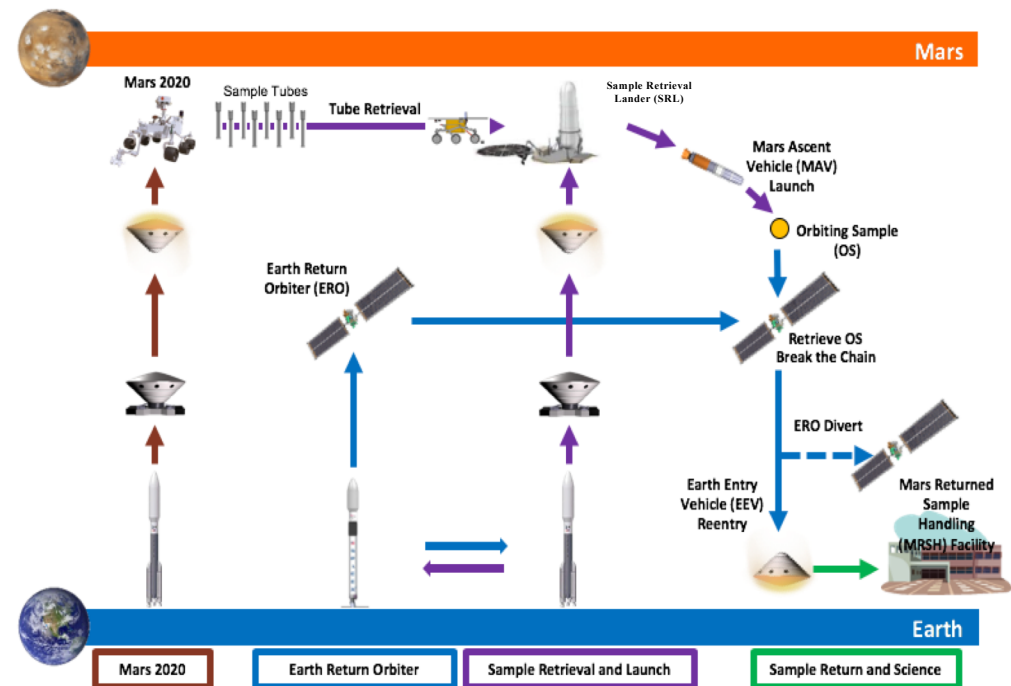


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Potential Mars Sample Return Campaign

- Mars 2020 rover
 - Collect and cache samples
- Earth Return Orbiter (ERO)
 - Enter Mars orbit ready to receive samples and transport back to earth
- Sample Retrieval Lander
 - Places Mars Ascent Vehicle (MAV) on Mars for sample stow and launch to ERO

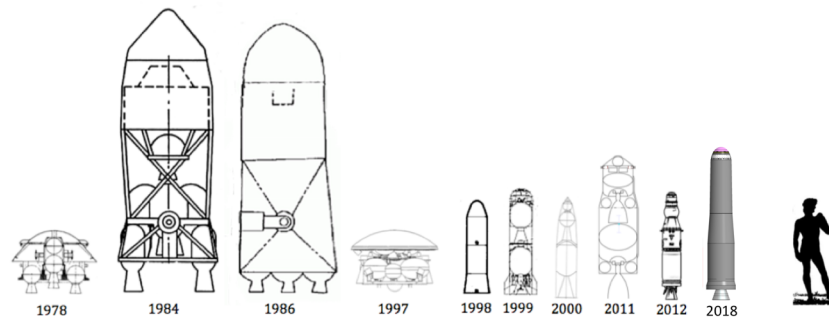




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MAV Propulsion



MAV Concept History

- Currently MAV is trading between hybrid and solid propulsion with a selection to be made in September 2019
- This presentation is about the methodologies and progress toward developing the solid propulsion vehicle



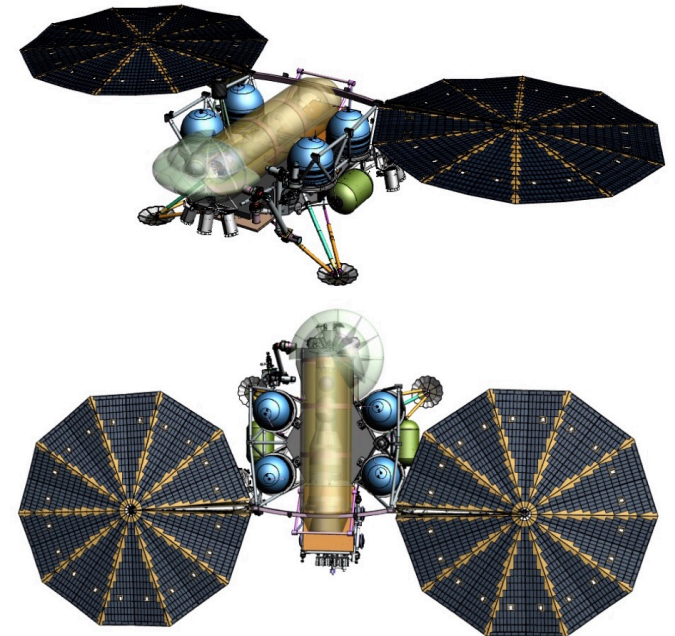
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Ground Rules and Assumptions

- Mass, length and diameter are driven by the lander
 - Length is shared with payload, avionics and Reaction Control System (RCS)
- Landing site selection will affect low temperature requirements
- Maximum shock will be parachute snap

| Assumption | Value |
|-----------------------------------|------------|
| Maximum GLOM (kg) | 400.0 |
| Maximum Vehicle Length (m) | 3.0 |
| Vehicle Diameter (m) | 0.57 |
| Payload Length Length (m) | 0.5 |
| Altitude (m) | 343,000.0 |
| Maximum Angle of Attack (degrees) | 4.0 |
| Launch PBMT (°C) | -20 (+/-2) |
| Storage Temperature Min/Max (°C) | -70/40 |



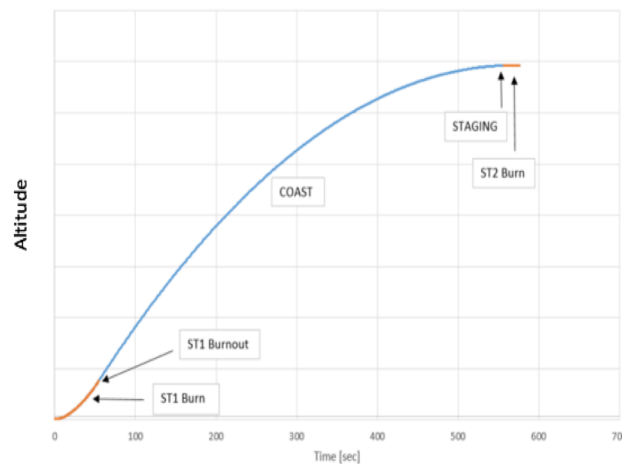


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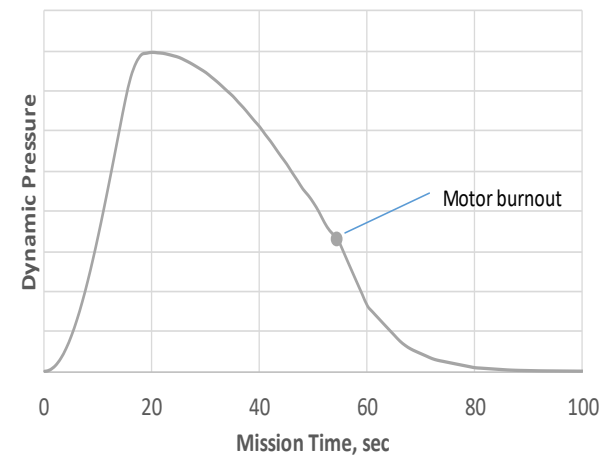


Design Methodology

- First Stage: High initial thrust to overcome gravity losses; Burn time and throttling to minimize max Q (Boost-Sustain)
- Second Stage: Insensitive to burn time variation; Sensitive to I_{sp} variation

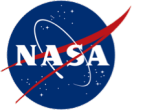


Mission Flight Profile



First Stage Dynamic Pressure

For More Information, Contact: andrew.s.prince@nasa.gov



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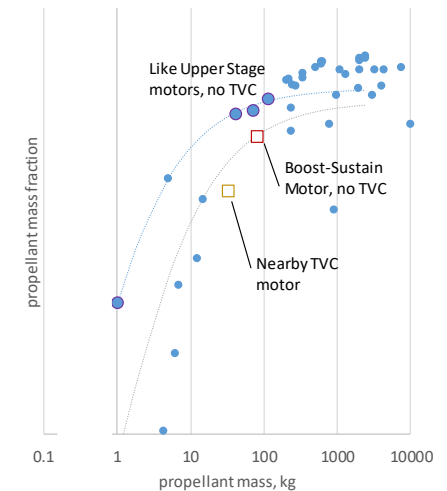
Propellant Mass Fraction Model

- A non-dimensional relationship was derived for propellant mass fraction (pmf)
 - Like sized motors were surveyed based on pmf and propellant mass
 - A subset of boost-sustain motors yields a slightly lower curve due to added insulation for the longer burn times

$$f_i = f_{i_{min}} + C_{ref} \left(\frac{m_{p_{ref}}}{m_p} \right)^{\frac{2}{3}}$$

$$pmf = \frac{1}{1 + f_i}$$

- Where,
 - $f_{i_{min}}$ = minimum inert mass or the limit as propellant goes to infinity
 - C_{ref} = slope of data
 - $m_{p_{ref}}$ = a reference propellant mass driving the location of inflection



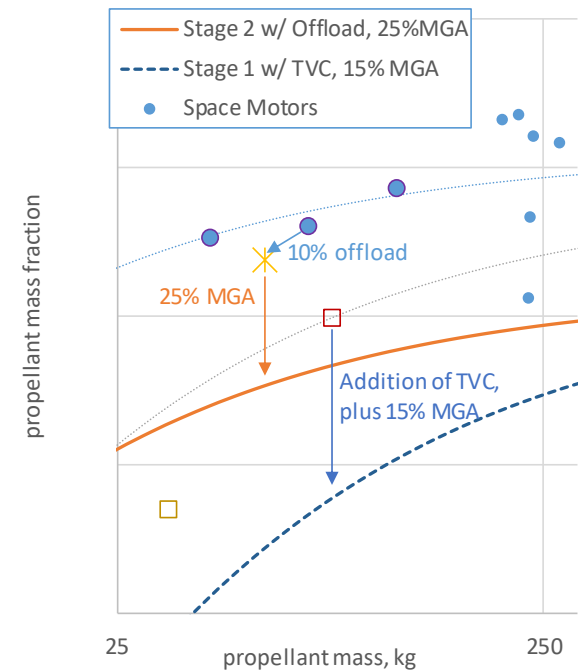


Mars Ascent Vehicle Study



MAV Motor Model

- Modification to the pmf model were made to account for MAV specifics
 - Additional interstage structures were accounted for by assuming 10% propellant offload
 - A 25% MGA assumed for the second stage
 - Additional inert mass added to the larger first stage for increased TVC
- The first stage is similar to a commercially available system allowing a 15% MGA to be assumed



First and Second Stage Adjusted Trends

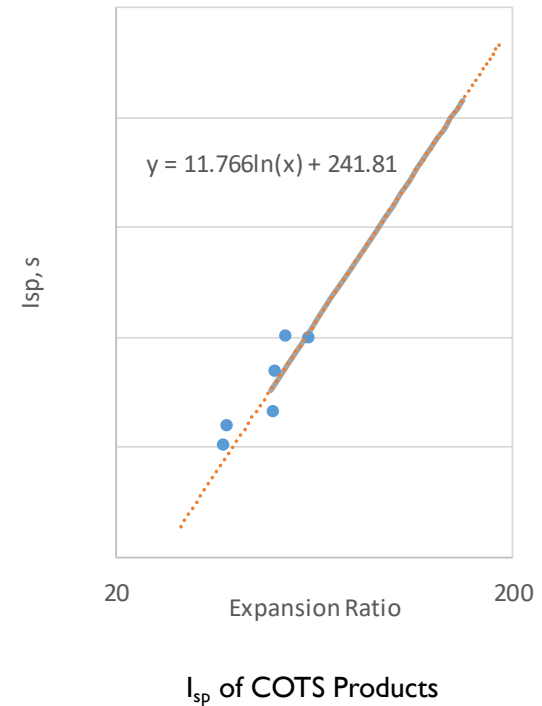


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Motor Sizing

- Modified COTS solution:
 - Minimize Gross Lift Off Mass (GLOM)
 - I_{sp} assigned to each motor based on Commercial Off The Shelf (COTS) motors and 3 DOF analysis
 - Propellant mass allowed to vary to meet orbital assumptions while minimizing GLOM
- Optimum solution:
 - GLOM limited to 400 kg
 - I_{sp} allowed to move along trend as required to meet orbital assumptions





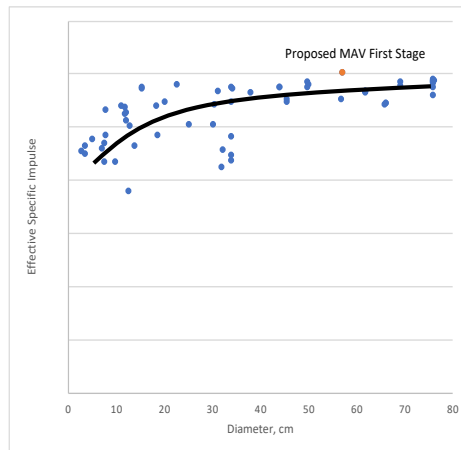
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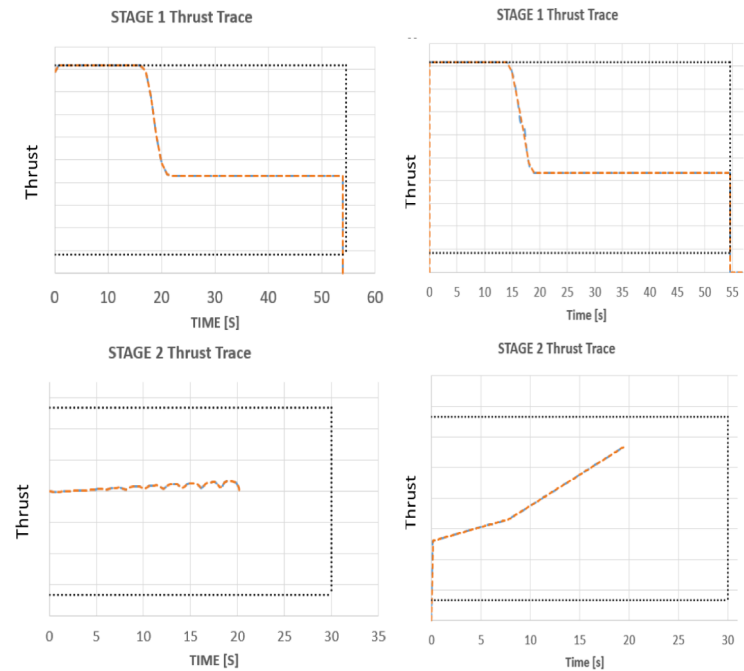
Thrust Traces for Both Solutions

- The optimum solution requires challenging I_{sp} values that are above the trend of other COTS products

| Parameter | Isp, sec | | GLOM, kg |
|---------------|----------|-----|----------|
| Stage | 1 | 2 | |
| Modified COTS | 288 | 291 | 419 |
| Optimum | 300 | 293 | 399 |



COTS Isp vs. Diameter



Modified COTS

Optimum



Mars Ascent Vehicle Study



Propellant Selection

- A set of COTS propellants were surveyed based on a set of specific assumption
 - -70 °C/ +40 °C storage and -20 °C Operation
 - Ranked density-impulse
 - Effects of Planetary Protection procedures
 - Bio-reduction (heat or radiation)
 - Bio-barriers
 - End-of-mission procedures
 - TRL level – Similar mission histories



Mars Ascent Vehicle Study



Nozzle and Controls

- With low operational temperature assumptions freezing slag is concern
 - Subsonic splitline vectorable nozzle could get entrained with slag and freeze up
 - Therefore a super sonic splitline was selected
- RCS sizing will rely on 6 DOF results when received
 - Cold gas vs hydrazine
 - Minimize mass
 - Favors minimal Q at first stage burnout



Mars Ascent Vehicle Study



Development and Qualification Testing Planning

- Defining a development/qualification is important for planning purposes
- More motors can reduce risk and increase cost requiring these to be balanced
- A qualitative matrix of risk with varied numbers of motors was derived based on assumption parameters qualified
- A set of 3 development and 3 qualification motors were selected by the project
 - Flight test is considered a qualification motor in Dev/Qual Plan

| OPTION | SUB-SCALE TESTING | | | FULL-SCALE TESTING | | | | LIKELIHOOD X CONSEQUENCE | FINAL RISK SCORE |
|--------|----------------------|-----------------|-----------|----------------------|-----------------|---------------|---------------------------------|--------------------------|------------------|
| | PLANETARY PROTECTION | THERMAL CYCLING | COLD-SOAK | PLANETARY PROTECTION | THERMAL CYCLING | COLD-SOAK | FLIGHT TEST OR FLIGHT-LIKE TEST | | |
| 1 | X | X | X | 3 DMs + 8 QMs | 3 DMs + 8 QMs | 3 DMs + 8 QMs | 5 QMs | 1X2 | 3 |
| 2 | 2X | 2X | 2X | 3 DMs + 6 QMs | 3 DMs + 6 QMs | 3 DMs + 6 QMs | 4 QMs | 2X2 | 6 |
| 3 | 3X | 3X | 3X | 3 DMs + 4 QMs | 3 DMs + 4 QMs | 3 DMs + 4 QMs | 3 QMs | 3X2 | 9 |
| 4 | X | X | X | 3 DMs + 4 QMs | 3 DMs + 4 QMs | 3 DMs + 4 QMs | 3 QMs | 3X2 | 9 |
| 5 | 2X | 2X | 2X | 3 DMs + 3 QMs | 3 DMs + 3 QMs | 3 DMs + 3 QMs | 2 QMs | 2X3 | 11 |
| 6 | 3X | 3X | 3X | 2 DMs + 2 QMs | 2 DMs + 2 QMs | 2 DMs + 2 QMs | 1 QM | 2X4 | 14 |

Dev/Qual Risk Matrix

| | Stage 1 | Stage 2 |
|----------------------|-----------|-----------|
| Development | 3 | 3 |
| Qualification | 3 | 3 |
| Flight Test | 1 | 1 |
| Inert Mass Simulator | 1 | 1 |
| Flight | 2 | 2 |
| Total Motors | 10 | 10 |

Dev/Qual Plan

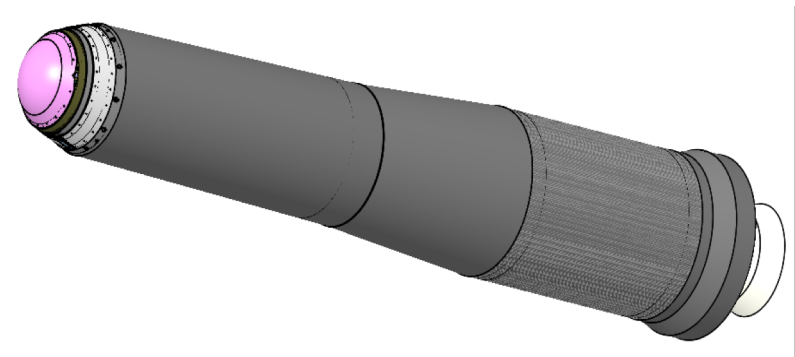


Mars Ascent Vehicle Study



Future Work

- Refine and iterate with other subsystems
 - Trade Isp (expansion ratio) with vehicle mass (interstage)
 - Trade aero stability with flow feature mass and location and design
- Refine design models (CAD) for minimum mass



Current MAV Solid Vehicle Concept