

1 **Statistical Modeling of Extreme Precipitation with TRMM Data**

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ABSTRACT

12 This paper improves upon an existing extreme precipitation monitoring sys-
13 tem based on the Tropical Rainfall Measuring Mission (TRMM) daily product
14 (3B42) using new statistical models. The proposed system utilizes a regional
15 modeling approach, where data from similar locations are pooled to increase
16 the quality of the resulting model parameter estimates to compensate for the
17 short data record. The regional analysis is divided into two stages. First,
18 the region defined by the TRMM measurements is partitioned into approxi-
19 mately 28,000 non-overlapping clusters using a recursive k-means clustering
20 scheme. Next, a statistical model is used to characterize the extreme precipi-
21 tation events occurring in each cluster. Instead of applying the block-maxima
22 approach used in the existing system, where the Generalized Extreme Value
23 probability distribution is fit to the annual precipitation maxima at each site
24 separately, the present work adopts the peak-over-threshold method of clas-
25 sifying points as extreme if they exceed a pre-specified threshold. Theoreti-
26 cal considerations motivate using the Point Process framework for modeling
27 extremes. The fitted parameters are used to estimate trends and to construct
28 simple and intuitive average recurrence interval (ARI) maps which reveal how
29 rare a particular precipitation event is. This information could be used by
30 policy makers for disaster monitoring and prevention. The new methodol-
31 ogy eliminates much of the noise that was produced by the existing models
32 due to a short data record, producing more reasonable ARI maps when com-
33 pared with NOAA's long-term Climate Prediction Center ground-based ob-
34 servations. Furthermore, the proposed methodology can be applied to other
35 extreme climate records.

36 **1. Introduction**

37 The effective monitoring and measurement of extreme precipitation events form an integral com-
38 ponent for understanding the underlying nature of extreme climate phenomena, and are crucial for
39 evaluating future changes and impacts of precipitation extremes. Many recent studies have found
40 a marked increase in the frequency and intensity of extreme precipitation events occurring in the
41 last few decades (Donat et al. 2016, Min et al. 2011, Alexander et al. 2006). Changes in the behav-
42 ior of extreme precipitation phenomena are among the most important aspects of global climate
43 change, with significant implications for human society and the environment. For example, a study
44 of the spatial heterogeneity of such changes found that regions where high-intensity precipitation
45 is less common are especially prone to increases in precipitation totals and extremes (Donat et al.
46 2016); unfortunately, the infrastructure in these regions is particularly ill-adapted to deal with ex-
47 treme precipitation. A rise in the frequency and severity of extreme climate events also exacts
48 a large human and economic toll. For example, in October 2013, Typhoon Fitow led to record
49 winds and flooding throughout eastern China, shutting down roadways, schools, and hospitals,
50 and resulting in an estimated \$10 billion USD in total damages (ESCAP/WMO 2013). In mid-
51 August 2016, a storm system in southern Louisiana resulted in unprecedented precipitation and
52 flooding, with some areas receiving in excess of 280 mm of rain in a single day. The storm, which
53 brought roughly 3 times as much rain over Louisiana than Hurricane Katrina did in 2005, was
54 later described as being an event occurring with 0.2% probability in any given year (Di Liberto
55 2016). More recently in October 2016, Hurricane Matthew ravaged the Western Atlantic causing
56 widespread power outages and flooding, and causing over \$8 billion in total damage. Hurricane
57 Matthew led to the deaths of over 500 people in Haiti alone, and was the strongest storm to hit the
58 country in over 50 years.

59 Satellite-based retrieval algorithms based on the measurements made by the Tropical Rainfall
60 Measuring Mission (TRMM) and the more recent Global Precipitation Measurement (GPM) satel-
61 lites have provided a rich source of precipitation data at the global scale. The TRMM Multi-
62 satellite Precipitation Analysis (TMPA; Huffman et al. 2007) combines precipitation estimates
63 from a variety of satellite systems to provide estimates at fine scales (3 hourly, $0.25^\circ \times 0.25^\circ$) with
64 quasi-global coverage ($50^\circ\text{S} - 50^\circ\text{N}$); moreover, TMPA estimates are available in both real-time
65 (3B42-RT) and post-real-time (3B42) data products.

66 One of the most common approaches for modeling extreme values of hydrological variables
67 is to adopt the framework of statistical extreme value theory, where precipitation intensities are
68 assumed to be random draws from an underlying probability distribution, and characterizing ex-
69 treme value behavior is equivalent to characterizing the upper tail of this distribution (Leadbetter
70 et al. 1983, Katz et al. 2002, Shane and Lynn 1964, Chan et al. 2014). Although physical models
71 can quite accurately describe the processes generating precipitation, from a probabilistic point of
72 view, the true data generating process producing precipitation intensities is almost never known in
73 practice. Thus, one typically uses a set of data to select a distribution from a pre-specified fam-
74 ily of distributions that describe the tail behavior. To translate the estimates of the fitted model
75 parameters to terms easily understood by policy makers and the general public, one can construct
76 average recurrence intervals (ARIs) that describe the rarity of precipitation events. For example, a
77 precipitation event with an ARI of 10 years means that it occurs on average once every 10 years.
78 The amount of precipitation corresponding to the 10 year ARI is referred to as the 10 year return
79 level. Note that a 10 year ARI does not mean that the event will occur once every 10 years; it
80 simply means that in any given year, there is a 10% probability of such an event occurring, and
81 that the occurrence of the event in one year does not preclude it from occurring in another year.

82 Extreme value distributions (EVDs) like the Generalized Extreme Value (GEV) and Generalized

83 Pareto (GP) distributions have commonly been used for the modeling of precipitation and temper-
84 ature extremes. EVDs have been used to analyze trends and changes in daily temperature (Brown
85 et al. 2008), to project changes in seasonal precipitation extremes using ensembles of climate mod-
86 els (Kharin et al. 2007, Fowler and Ekström 2009), and to study the spatial and spatio-temporal
87 behavior of extreme precipitation (Wang et al. 2017, Schindler et al. 2012). Serinaldi and Kilsby
88 (2014) used the GP distribution to model precipitation extremes, focusing specifically on the im-
89 pact of threshold selection on the tail behavior of the fitted GP distributions. Using a point process
90 model, Heaton et al. (2011) discovered significant increases in the intensity of extreme weather
91 in parts of the continental United States (CONUS). Schindler et al. (2012) modeled extreme pre-
92 cipitation across the UK using an inhomogeneous Poisson point process, accounting for annual
93 cycles using a sinusoidal model for the location and scale parameters of the corresponding GEV
94 distribution. The point process approach to extreme value analysis has also been used to detect
95 trends in ozone levels (Smith 1989), as well as to generate stochastic climate scenarios to facilitate
96 the modeling of precipitation extremes (Furrer and Katz 2008).

97 The extreme precipitation monitoring system proposed in Zhou et al. (2015) uses measurements
98 taken from the TMPA data series to construct ARI maps for the purpose of disaster preparation
99 and monitoring. While the TRMM extreme precipitation monitoring system is a highly effective
100 framework in general, the statistical modeling of the system Zhou et al. (2015) used suffers from
101 several limitations. First, data from each of the grid points in the TMPA domain are considered to
102 be independent, an assumption that is questionable in practice. Second, only the annual maxima
103 values for each grid location are considered to be extreme, meaning that only 16 data points are
104 available for model fitting at each location. As a result, there is a high degree of uncertainty in the
105 parameter estimates and resulting ARI maps. Furthermore, the annual maxima approach cannot
106 accommodate multiple extreme events occurring during the same year, for example during differ-

107 ent seasons.

108 In this paper, we propose an alternative methodology for the statistical modeling of the TRMM
109 extreme precipitation monitoring system that overcomes the above limitations. In section 2, we
110 outline the two stages of our proposed algorithm which first partitions the map into disjoint clus-
111 ters of similar sites, then fits an appropriate statistical model to the pooled data in each cluster.
112 In section 3, we present the results of our methodology when estimating return levels and trends
113 in extreme precipitation, and compare the return level estimates to those in Zhou et al. (2015).
114 Section 4 demonstrates that our procedure is general enough to be used to analyze extreme climate
115 events other than precipitation; in this case, we analyze surface air temperature data. We conclude
116 with a discussion covering several possible extensions of our work.

117 **2. Methodology**

118 To overcome the above-mentioned shortcomings of the existing TRMM extreme precipitation
119 monitoring system, we implement a two-stage methodology that 1) partitions the map into rela-
120 tively homogeneous non-overlapping regions, and 2) fits an appropriate statistical distribution to
121 the data from each of the regions from the first stage. We are not proposing a completely novel
122 methodology for extreme-value analysis, but rather an alternative framework for modeling the
123 TRMM data that improves upon the methodology of Zhou et al. (2015). All of the results in this
124 paper are based on the TRMM 3B42 daily precipitation record (NASA GES DISC 2016).

125 *a. Regional clustering*

126 The idea of pooling similar sites into one common region has a rich history in the hydrological
127 literature (Cunnane 1989, Hosking et al. 1985, Hosking and Wallis 1988), has also been utilized in
128 precipitation analysis (Buishand 1991), and fits into the broader framework of regional frequency

129 analysis (Hosking and Wallis 1993, Hosking and Wallis 1997).

130 There are two general approaches for clustering sites in a regional analysis of extreme climate
131 events. In the first approach, regions are clustered based on their site characteristics (e.g. loca-
132 tional and topographic information), not at-site statistics such as the time series of annual maxima
133 or threshold exceedances, i.e. Smithers and Schulze (2001), Satyanarayana and Srinivas (2008),
134 Wang et al. (2017), and Hosking and Wallis (1997). An alternative framework for regional par-
135 titioning is to use the data themselves as input into the clustering algorithm. For example, the
136 location similarity measures in Bernard et al. (2013) and Bador et al. (2015) use the time series
137 of annual maxima themselves as variables in the clustering algorithm, the goal being to achieve
138 max-stability within each cluster. Despite the merits of these clustering methods, there are two po-
139 tential drawbacks with this approach. First, using the same data to both form the regional clusters
140 and to test for homogeneity within those clusters will almost certainly lead to a biased assessment
141 of homogeneity (Hosking and Wallis 1997). Furthermore, the clustering results will change every
142 time data are added to the model, e.g. if data from the GPM IMERG data product were to be added
143 to the statistical model.

144 With these considerations, here we adopt a clustering scheme based on site characteristics using
145 a recursive k-means clustering algorithm with spatial location (longitude, latitude), topography
146 (derived from 5' National Geophysical Data Center [NGDC] TerrainBase Global DTM Version
147 1.0 [Row III and Hastings 1994], and binned into 0.25° resolution), and the 90th percentile of
148 precipitation values (all variables standardized) as input to the algorithm. The k-means algorithm
149 seeks to partition the data (here, the map) into k non-overlapping groups (where the number of
150 clusters k is pre-specified) so as to minimize the sum of squared distances from each data point
151 to its assigned cluster's center in feature space. See Hastie et al. (2009) for more details about
152 k-means clustering and its implementation.

153 Our recursive k-means algorithm first partitions the map into approximately 30 large clusters;
154 each cluster is further partitioned into another set of 30 clusters, resulting in about 900 clusters in
155 total. This process is repeated a final time for each of the resulting regions; if there are less than 30
156 grid points in a particular region, we skip this final step for that region. This entire process yields
157 28,221 non-overlapping regions, for an average of about 20 grid points per cluster, which follows
158 the guidelines set forth in Hosking and Wallis (1997). Figure 1 illustrates the idea behind the re-
159 cursive clustering scheme. Note that the region a given cluster covers need not be contiguous, and
160 one can weight the inputs of the algorithm to adjust their relative importance. The results of our
161 algorithm are displayed in Figure 2 for the first two clustering operations.

162 Next, we implement the homogeneity test given in Viglione et al. (2007) which combines
163 the “Hosking and Wallis heterogeneity statistic” (Hosking and Wallis 1997) with the bootstrap
164 Anderson-Darling statistic (Scholz and Stephens 1987) to decide if the distributions of extreme
165 precipitation intensity for different sites within each cluster are the same. 21,112 of 28,221 re-
166 gions were identified as being acceptably homogeneous. We did not correct for multiple testing
167 since the Hosking and Wallis statistic is not a formal test statistic, and therefore the number of het-
168 erogeneous regions is almost certainly overestimated. Since regional analysis will produce more
169 accurate statistical estimates than a single-site analysis even with slight or moderate degrees of
170 homogeneity (Hosking and Wallis 1997), we do not expect our results to be greatly affected by the
171 heterogeneity in some clusters.

172 *b. Statistical modeling*

173 The next stage is to fit an appropriate probability distribution to the pooled extreme precipita-
174 tion data in each resulting cluster. The estimated parameters of the fitted distributions will then
175 characterize the underlying behavior of extreme precipitation events in that region.

176 1) CHOICE OF AN APPROPRIATE DISTRIBUTION

177 We begin by reviewing some of the common approaches to extreme value modeling, motivating
178 our choice to adopt the Point Process (PP) framework to model precipitation extremes.

179 To model extreme values, Zhou et al. (2015) utilize the block maxima approach where only the
180 largest annual precipitation values are considered to be extreme, and where the *Generalized Ex-*
181 *treme Value (GEV)* distribution is used to model the resulting extreme values. See Leadbetter et al.
182 (1983) for the theoretical justification for using the GEV distribution to model sample maxima.
183 The GEV cumulative distribution function is given by

$$F_{GEV}(x; \mu, \sigma, \xi) = \begin{cases} \exp \left\{ - \left[1 + \frac{\xi(x-\mu)}{\sigma} \right]^{-\frac{1}{\xi}} \right\} & \text{if } \xi \neq 0 \\ \exp \left\{ - \exp \left(-\frac{x-\mu}{\sigma} \right) \right\} & \text{if } \xi = 0, \end{cases} \quad (1)$$

184 where μ is the location parameter, $\sigma > 0$ is the scale parameter, and ξ is the shape parameter.
185 Extreme value modeling using block maxima to fit the GEV distribution has widely been used for
186 modeling hydrological extreme data (see, e.g., Katz et al. 2002 and the references therein), but
187 has the obvious limitation that a large number of observations are discarded, resulting in a short
188 data record. One approach for dealing with this limitation of the block maxima approach is to
189 adopt the peak-over-thresholds (POT) method, where observations are considered extreme if they
190 exceed a pre-specified threshold (Todorovic and Zelenhasic 1970, Davison and Smith 1990). For
191 large enough thresholds, the distribution of threshold exceedances will approximately follow the
192 *Generalized Pareto (GP)* distribution (Leadbetter et al. 1983).

193 The framework of point processes (PP) unifies the two approaches discussed above (see Cox and
194 Isham 1980 for the general theory of point processes; some applications to environmental model-
195 ing via the PP approach can be found in Smith 1989 and Smith and Shively 1995). According to
196 PP theory, the occurrence time and intensity of an event which exceeds a pre-specified threshold

197 will approximately follow a Poisson PP (assuming the threshold is sufficiently large). Moreover,
198 the intensity function of the PP is parameterized by a $GEV(\mu, \sigma, \xi)$ distribution corresponding to
199 the annual maximum distribution of the observed process (Leadbetter et al. 1983, Coles 2001).
200 Using the PP framework offers the advantage that its likelihood is parameterized in terms of the
201 GEV parameters in (1), since these parameters are invariant to the choice of threshold. Further-
202 more, this parameterization allows non-stationarity to easily be incorporated into the model by
203 modeling the GEV parameters as functions of time or other covariates. These parameters are often
204 easier to interpret than those of the corresponding GP models. See Coles (2001) for more details
205 regarding the equivalence of the GP and PP approaches to extreme value modeling.

206 With the above considerations in mind, we proceed using the PP framework. Several practical
207 considerations must be addressed before proceeding to fit a model to the data.

208 2) THRESHOLD SELECTION

209 The problem of selecting the threshold ω in both the GP and PP approaches is an instance of
210 the bias-variance tradeoff commonly encountered in statistics; a threshold that is too low may
211 lead to model bias, while a threshold that is too large may yield larger variability in the resulting
212 parameter estimates. See Serinaldi and Kilsby (2014) for more on the issue of threshold selection
213 in POT models and methods to correct for model bias due to short data records.

214 There are many reasonable, data-driven methods for selecting the threshold ω . For instance,
215 one can set ω equal to some large percentile of the data, e.g. the 95th or 99th percentile of daily
216 precipitation values. Another approach is to model the threshold as a time-varying function (Coles
217 2001), e.g. as a step function

$$\omega(t) = \omega_i \text{ if } t \in T_i, \quad (2)$$

218 where the T_i are disjoint sets indexing time, and where the ω_i are pre-determined constants. In
219 our analysis, we adopt the threshold function in (2) where we let $T_i, i = 1, \dots, 12$ correspond to the
220 different months and where the ω_i in each region correspond to the 99th percentile of precipitation
221 values for the pooled data in that region and month. Since the function in (2) has abrupt jumps at
222 the end of each component, we smooth the threshold function in (2) via cubic splines.

223 3) SPATIAL AND TEMPORAL DEPENDENCE

224 Since extreme precipitation events tend to occur in temporal clusters (e.g. spans of 2-3 days at a
225 time), in practice, the assumption of independent observations underlying the PP framework will
226 be violated. To deal with this problem, we adopt a commonly used declustering procedure that first
227 partitions the threshold exceedances at each site into separate temporal clusters, then only retains
228 the cluster maxima for subsequent model fitting. Here, we add data points (precipitation values)
229 to each temporal cluster until 5 consecutive points fall below the (99th percentile) threshold. For
230 more details on this particular declustering scheme, see, e.g., section 5.3.2 in Coles (2001).

231 There is also the problem of likely spatial dependence arising from the regional clustering proce-
232 dure. It is not always clear how to effectively incorporate spatial dependence into an extreme-value
233 based statistical model. Even recent attempts at incorporating spatial dependence into a regional
234 analysis (see, e.g., Wang et al. 2014) require a subjective specification of a dependence structure.
235 Misspecification of this dependence structure can introduce significant bias into the model, defeat-
236 ing the purpose of modeling such dependence in the first place. As pointed out in Katz et al. (2002)
237 and Hosking and Wallis (1988), inter-site correlation introduces little bias (if any) into point esti-
238 mates of quantiles, but results in underestimation of the standard errors of model parameters. For
239 these reasons, we do not attempt to model the spatial dependence in this work.

240 4) MODEL FITTING

241 Several methods, such as maximum likelihood estimation (MLE) (Ferguson 1996), L-moments
242 (Hosking 1990, 2006), and Bayesian estimation can be used for model fitting and parameter es-
243 timation, though we found the Bayesian framework to be too computationally intensive for our
244 analysis. When experimenting with these different model fitting techniques, we found there to
245 be a minimal difference overall in the parameter estimates due to the relatively large sample sizes
246 obtained as a result of the clustering step. Furthermore, the only way to obtain confidence intervals
247 for parameter estimates in the L-moment framework is to apply the parameteric bootstrap, making
248 this approach relatively computationally expensive. Because of these considerations, we decided
249 to proceed using the MLE approach. All model fitting was carried out using the “extRemes”
250 package available in the R computing environment (Gilleland and Katz 2016).

251 5) NON-STATIONARITY

252 Under the assumption of stationarity in the time series, finding the return levels and recurrence
253 intervals is straightforward. In the case of non-stationarity, however, the situation is more com-
254 plicated since the properties of the underlying distribution vary with time (we take the term “non-
255 stationary” to refer to any statistical model whose parameters are expressed as a function of time).
256 Risk forecasts based on stationary models will ignore time-dependent changes in the distribution
257 of extreme precipitation intensity, leading to potentially unrealistic estimates of risk. Several mea-
258 sures have been recently proposed to address this difficulty: these include the effective return level
259 (Katz et al. 2002, Cooley 2013), the Design Life Level (Rootzén and Katz 2013), and the Non-
260 Stationary Extreme Value Analysis (NEVA) framework of Cheng et al. (2014). Here we have
261 chosen to use the effective return level, though the other two methods can also be used depending
262 on one’s goals.

263 As a first approximation appropriate to many locations, we model the location and scale param-
 264 eters of the PP model with the first-order sinusoidal functions

$$\mu(t) = \alpha_0 + \alpha_1 \cdot \sin\left(\frac{2\pi t}{365.25}\right) + \alpha_2 \cdot \cos\left(\frac{2\pi t}{365.25}\right) \quad (3)$$

$$\log \sigma(t) = \beta_0 + \beta_1 \cdot \sin\left(\frac{2\pi t}{365.25}\right) + \beta_2 \cdot \cos\left(\frac{2\pi t}{365.25}\right); \quad (4)$$

265 the annual periodicity of these functions ensures that the effective return levels need only be com-
 266 puted for each day of the year (e.g. for $t = 1, \dots, 365$ as opposed to each day in the entire time
 267 series), yielding one return level map for each day of the year for any specified ARI.

268 For thoroughness, we compared the model defined by (3) alone, i.e. assuming time-dependent
 269 location parameter and constant scale and shape parameters, to the model defined by both (3) and
 270 (4). The latter model better explains the data in 74% of the regions according to both the Akaike
 271 information criterion (AIC) and Bayesian information criterion (BIC) (it is worth noting that the
 272 AIC can result in model overfitting, while the BIC, which penalizes additional parameters, can
 273 lead to underfitting). Furthermore, both the AIC and BIC indicate the non-stationary model de-
 274 fined by (3) and (4) is superior to the stationary model in 94% of the regional clusters. Therefore,
 275 we adopt the non-stationary model defined by (3) and (4) throughout the rest of the paper unless
 276 stated otherwise.

277 3. Results

278 In this section, we discuss the return level and trend estimates of the non-stationary PP model.

279 *a. Return level estimates*

280 After fitting a distribution to the data in each region, the resulting parameter estimates are used
 281 to construct return level maps that convey the rarity of precipitation events. It is important to note

282 that due to the short data record, estimates of lower probability are subject to high uncertainty.
283 As remarked in Parzybok et al. (2011), ARI results obtained from extreme value analysis are
284 expected to be reliable for twice the data length. Since we are using 16 years of TRMM data in
285 our analysis, the model will be able to identify a 32-year ARI event relatively accurately.

286 Some examples of the return level maps for CONUS are given in Figure 3. Comparing the maps
287 for January 1 and July 1 reveals that there can be significant variability in the severity of extreme
288 events throughout the year. For example, much of the west coast has substantially higher return
289 levels in January than in July, whereas the return levels are relatively stable among these 2 dates
290 for much of the east coast. Our findings are consistent with the results of Agel et al. (2015), who
291 found that the intensity on extreme days in the Northeast is relatively invariant to the season.

292 Figures 4a and 4b show model diagnostic plots for the data from the cluster containing Los
293 Angeles. To produce the QQ plot in 4a, the parameters of the fitted PP model are converted to the
294 equivalent GP distribution (the quantiles are from threshold excesses of the data). The QQ plot in
295 4a indicates a reasonable model fit, with the empirical data distribution having a thicker upper tail
296 than the fitted distribution. The Z-plot in 4b is yet another gauge of model fit tailored specifically
297 for the PP model fit (Smith and Shively 1995). Under the PP model, the waiting times between
298 events should follow a mean-one exponential distribution. Therefore, the Z-plot is a QQ plot that
299 compares the quantiles of empirical waiting times against the quantiles of a mean-one exponential
300 distribution. Figure 4b does not indicate any obvious departures from model assumptions.

301

302 Figure 4c shows some of the fitted return level curves for several extreme precipitation events
303 which occurred in Los Angeles in late 2004 - early 2005. The threshold for extreme events varies
304 from around 1 mm in the summer (not surprising if you have ever spent a summer in Los Angeles)
305 to about 38 mm in February. According to our model, one event crosses the 100-year return

306 level curve, corresponding to an event that occurs in any given year with about 1% probability (as
307 always, one should interpret such estimates after considering sampling variability, for example,
308 via confidence bands for the return level curves). In fact, the 2004-2005 winter season proved to
309 be one of the wettest seasons on record for Los Angeles county.

310 Finally, to capture the uncertainty in the parameter estimates used to make the return level maps,
311 we calculate 95% normalized confidence ranges (NCR) following the procedure in Zhou et al.
312 (2015). For each region and for a given ARI (in years), we compute the difference between
313 the upper and lower limits of the 95% confidence interval for the return levels, then divide this
314 difference by the point estimate of the return levels. The NCR offers the advantage that it is
315 independent of units of measurement, and can thus be used to compare regions with very different
316 mean precipitation. Smaller values of the NCR imply a more confident estimate of the ARI; for
317 example, an NCR value of 1 corresponds to an ARI estimate that lies within 100% of its magnitude
318 with 95% confidence. Since the return level estimates vary according to the time of year, we take a
319 conservative approach and compute the maximum value the NCR obtains during the year. Figure
320 5 reveals that the majority of the regions on the map correspond to high confidence estimates (e.g.
321 $\text{NCR} < 1$), both for 5 and 20 year ARIs. The general pattern in the NCR maps is very similar
322 to the results of Zhou et al. (2015), with low confidence regions primarily located in exceedingly
323 dry areas such as Northern Africa, the Arabian peninsula, and the southeast Pacific Ocean, though
324 the values in the 5 and 20 year NCR maps based on our methodology are generally much smaller
325 than those in Zhou et al. (2015). As pointed out in Zhou et al. (2015), as the data length of the
326 TRMM-GPM precipitation records increases, the degree of confidence in the ARI estimates will
327 increase even further.

328 *b. Comparison to previous models*

329 To put our results into perspective, we compare the return level maps resulting from our
330 posed methodology with those based on the annual maxima/GEV framework as in Zhou et al.
331 (2015). Both methods are applied to the same 3B42 daily precipitation data, but because Zhou
332 et al. (2015) did not use the data from 2013 in their analysis, we restrict the data for our model to
333 the 1998 – 2012 span to facilitate model comparisons. As a benchmark for comparison, we also
334 show the return level maps generated using NOAA’s Climate Prediction Center (CPC) daily uni-
335 fied precipitation dataset, which is a gauge-based, gridded, and quality controlled product derived
336 from daily and hourly precipitation measurements from 1948 – 2012, where measurements were
337 taken from over 13,000 stations (8,000 before 2012) over CONUS. The CPC data also have the
338 same 0.25° spatial resolution as the 3B42 data. The CPC data were modeled using the single-site,
339 annual maxima/GEV framework in Zhou et al. (2015). To make our results directly comparable to
340 both of these sets of return level maps which were constructed under the assumption of stationar-
341 ity (implying a single return level map for the entire year), we also assume stationarity in our PP
342 approach and thus do not allow for seasonality in the rest of this section. That is, we take a single
343 threshold for the entire time series (the 99th percentile of precipitation values) of a given region,
344 and assume that the location, scale and shape parameters do not vary with time or other covariates.

345 In Figure 6, we compare the return level maps corresponding to ARIs of 2 and 25 years produced
346 using the three different approaches stated above. The most striking feature of these diagrams is
347 the reduction in noise when using the regional analysis over the existing single-site methodology.
348 In the return level maps corresponding to an ARI of 25 years, for example, the return level map
349 based on the TRMM data using the single-site block maxima approach is quite coarse, with many
350 isolated grid points exhibiting return levels that are in sharp contrast to their surrounding neigh-

351 bors. The short data record for this approach (15 data points per site) means that the GEV model
352 fitting procedure could not effectively separate the signal from the statistical noise. Of course, it
353 is possible that some of the isolated “spikes” in the return level maps reflect actual contrasts in
354 precipitation extremes. However, since the same GEV method was used on both the 65-year CPC
355 data and the 15 year TRMM data, and since using a longer data record smoothed away most of the
356 spikes, it is reasonable to conclude that most of the contrasts were indeed a result of the short data
357 record. From the maps, it is apparent that our methodology results in a smoother return level map
358 when compared with the single-site, annual-maxima framework, capturing the general pattern in
359 the CPC results using less data.

360 *c. Model fit*

361 To assess how well the stationary PP approach models the observed data, we constructed several
362 diagnostic plots including kernel density plots as well as QQ plots. The results for one randomly
363 selected region, corresponding to 4 grid points in Western Colombia, are displayed in Figure 7.
364 The density and QQ plots indicate that both the PP and single-site GEV models fit to the TRMM
365 3B42 series explain the data reasonably well (note the bimodality in the empirical distribution of
366 the block maxima model - this issue is discussed further in the Discussion section). Figure 7 also
367 includes return level plots for both methods, which plot the return levels (in mm) expected to occur
368 on average once during the corresponding recurrence interval (given in years). The return level
369 plots suggest that the two models differ in their characterizations of the tail behavior of extreme
370 events. Indeed, at the 5% level of significance, the PP model fit implies a finite upper bound
371 for extreme precipitation intensity, while the GEV model fit indicates unbounded tail behavior.
372 The 95% confidence limits (dashed gray lines) indicate a higher level of confidence in the results
373 produced by the PP method than the single-site GEV approach. We also note that the 95% NCR

374 maps corresponding to our method in the stationary setting (not included here for brevity) are very
375 similar to those in Figure 5, indicating an overall increase in statistical confidence.

376 *d. Case study*

377 We applied our methodology to evaluate the severity of a particular climate event, Typhoon
378 Fitow, the strongest Typhoon to hit mainland China in more than 60 years. Specifically, we es-
379 timated the annual probabilities of the precipitation event that occurred on 6 October 2013 for
380 the non-stationary PP model with regional clustering, as well as for the stationary GEV model of
381 annual maxima without regional clustering used in Zhou et al. (2015).

382 Figure 8 shows the 1 day precipitation total on 6 October 2013 over China's Zhejiang province,
383 as well as the predicted annual probabilities of the corresponding precipitation intensities of both
384 models. The estimated probabilities for the precipitation totals recorded during this event are gen-
385 erally higher under the PP model than those of the GEV model, implying that such extreme events
386 are more common than the existing method in Zhou et al. (2015) would have predicted. Most of
387 the probabilities under the GEV model are less than 0.01, and given the short length of the data
388 record, the validity of such estimates is questionable. Though there are also low probability events
389 (< 0.01) predicted by the PP model, more than 80% of the predicted probabilities are larger than
390 3%, thus the reliability of the PP estimates is less affected by the short data record. The PP model
391 predictions in Figure 8 reveal that there were 3 distinct regions of particularly rare precipitation
392 intensity, with the largest region overlapping with the area of heaviest precipitation. The GEV
393 approach failed to make the distinction between these 3 regions.

394 *e. Trends in extreme precipitation intensity*

395 A straightforward modification of the non-stationary PP model allows an analysis of long-term
396 trends. A simple starting point is to model the GEV location parameter as a linear function of
397 time, i.e.

$$\mu(t) = \mu_0 + \mu_1 \cdot t, \quad (5)$$

398 and to assume constant scale and shape parameters. In this setup and for any fixed probability p ,
399 the coefficient μ_1 measures the change in the GEV quantile function over the data period (given t
400 is scaled to lie in $[0, 1]$); positive values of μ_1 reflect more intense extreme precipitation events and
401 negative values reflect less intense extreme events. To visualize the results, we adopt the approach
402 used in Katz et al. (2002) and set $p = 0.5$ and compute the percentage change in the median of
403 the fitted GEV distribution over the data period; intuitively, we are calculating how much the un-
404 derlying distributions of extreme precipitation intensities shifted from 1998 to 2013. The percent
405 changes in the medians of extreme precipitation intensities are shown in Figure 9 (only trends
406 significant at the 5% level are shown). We stress that these results should not be extrapolated to
407 periods outside of the data record and are only used here to study the behavior of extreme events
408 from 1998-2013.

409 Figure 9 shows generally increasing intensities of extreme precipitation in the tropical ITCZ,
410 including the tropical Indian Ocean, Maritime continent, West Pacific warm pool, Caribbean and
411 Gulf regions. Decreases in extreme precipitation are observed in most of the tropical and sub-
412 tropical land regions, i.e. South America, tropical and south Africa, north and west Australia,
413 consistent with the results of Wu and Lau (2016). Negative trends are also observed over most
414 of CONUS, especially in the southwest US, contributing to the drying trend in the region (Prein
415 et al. 2016). However, decreases in extreme precipitation in the mid-latitude oceans in the Pacific

416 and north Atlantic, together with increases in extreme precipitation in the southern (north) edge of
417 the subtropical jet in the northern and southern hemisphere could indicate an equator-ward shift
418 of heavy precipitation regions as opposed to a general expansion of the ITCZ (Zhou et al. 2011,
419 Lucas et al. 2014).

420 We emphasize that only linear trends in time have been investigated here, and therefore
421 our model can only detect static increases/decreases in precipitation extremes. One possible
422 workaround to this problem would be to use the average temperature within each cluster as a
423 covariate instead of time; the resulting model could then capture more complex behaviors in the
424 global precipitation system. In addition, since the data record is relatively short, the estimated
425 trends might be capturing part of a longer-period fluctuation. For example, even models that cor-
426 rectly identify a trend over a short time period may fail to identify a reversal of the trend if such a
427 reversal occurred over a time span longer than the data record (Fu et al. 2010, Kunkel et al. 2013).

428 **4. Application to surface air temperature data**

429 The generality of the PP framework implies that our clustering and model fitting procedures
430 can easily be applied to model various types of data other than precipitation data. As a proof of
431 concept, in this section we apply our methodology to analyze trends in extreme temperature in-
432 tensity. Specifically, we use surface air temperature data from NOAA's NCEP North American
433 Regional Reanalysis (NARR) product (NOAA/NCEP 2004). The data are daily surface temper-
434 atures (in degrees Celsius) spanning from 1 Jan. 1979 to 31 Dec. 2013 over North America at
435 a resolution of approximately 0.3 degrees (32 km) at the lowest latitude, and the number of grid
436 squares is 349×277 . Here, we restrict our analysis to CONUS. More information about the NARR
437 product can be found at <http://www.esrl.noaa.gov/psd/data/gridded/data.narr.html>
438 (Mesinger et al. 2006). Again, we stress that the results from the short data record cannot be ex-

439 trapolated into the future.

440 We used 50 clusters for the first round of k-means and 30 clusters for the second round, resulting
441 in a total of 1500 disjoint regions. We used location and the 90th percentile of temperature values
442 as input for clustering, though more extensive analyses should consider a more comprehensive set
443 of variables. The Viglione et al. (2007) homogeneity test identified 1431 out of 1500 regions as
444 being acceptably homogeneous. Next, we fit a non-stationary PP model to the data in each region
445 following the procedure outlined in Section 2. Since we will be examining long-term trends, for
446 the threshold function in (2), we took one threshold per year, taken to be the 95th percentile of tem-
447 perature intensities for that year (using the 95th percentile instead of the 99th percentile produced
448 more stable parameter estimates). As before when examining trends in precipitation extremes, we
449 assumed constant scale and shape parameters and a linear trend in the location parameter. A map
450 showing the percent change of the median of the fitted extreme temperature distributions is shown
451 in Figure 10, along with a map of average temperatures for comparison. Only trends significant at
452 the 5% level are shown.

453 According to our model, most of CONUS experienced an increase in the intensities of extreme
454 temperature events during this time period. Figure 10 indicates that the largest increase in the
455 medians of extreme temperatures was about 4% in southern Louisiana and eastern Texas. The
456 east coast also showed a consistent increase in extreme temperature intensities, with the largest
457 increase of about 2% occurring in eastern Maryland and Delaware. The trends are reversed near
458 parts of the Rocky Mountains, with decreases in the median of temperature intensities as large as
459 2% in western Colorado. Some smaller decreases are observed in the northern Great Plains and
460 parts of central California. These results are generally in line with the analyses and projections
461 of Schoof and Robeson (2016), who predict a consistent increase across the United States in the
462 number of excessively warm days over the 21st century. Our findings are also consistent with the

463 behavior of extreme heat waves over this time period, particularly with the increased number of
464 extreme heat waves occurring from 2000-2010 (Kunkel et al. 2013). Notably, unlike the findings
465 in Peterson et al. (2013), our results do not reflect any cooling trends over the “warming hole”
466 (Meehl and Arblaster 2012, Kunkel et al. 2006) in the southeastern United States. The phase re-
467 versal of the Interdecadal Pacific Oscillation in the tropical Pacific in the late 1990s may explain
468 the disappearance of the warming hole after 2000 (Meehl et al. 2015), and therefore part of the
469 difference in our findings may be due to differences in the data period (1950-2007 in Peterson et al.
470 2013 vs. 1979-2013 here). Once again, we emphasize that we have assumed a simple linear trend
471 in time, and that more complicated trend structures would be able to capture more sophisticated
472 behavior in temperature extremes.

473 **5. Discussion**

474 In this paper, we propose an alternative methodology for the statistical modeling of the TRMM
475 extreme precipitation monitoring system. Our regional clustering algorithm, in conjunction with
476 the POT approach for modeling extremes, allows us to leverage more data than the single-site
477 block maxima method, yielding more accurate estimates of the regional ARIs. The resulting return
478 level maps produced by our method (Figure 6) reveal that our algorithm can more effectively
479 separate out the statistical noise than the existing Zhou et al. (2015) approach. Our model provides
480 a useful tool for studying the global and regional characteristics and trends of extreme variables,
481 whether these are precipitation events or other climate events.

482 There are several possible extensions to our analysis. First, in this paper we only consider
483 1-day precipitation totals. More complete information about return levels and trends in extreme
484 precipitation can be obtained by considering multi-day cumulative precipitation totals, e.g. 3 or
485 5 day precipitation totals reflecting the severity of multiple-day precipitation events. However,

486 when modeling such accumulated precipitation events, we noticed significant multi-modality
487 in the intensity of the accumulated precipitation events. While multimodality in precipitation
488 occurrences and intensity has been previously reported (Schindler et al. 2012, Tye et al. 2016),
489 we are not aware of any statistical models that have specifically been developed to model
490 multimodality in accumulated precipitation totals. We are currently developing a framework
491 based on mixture modeling that would be able to deal with this realistic scenario.

492 Second, we did not attempt to model the spatial dependence among grid locations in each
493 regional cluster. Future studies should aim at developing models that are flexible enough to
494 accommodate a wide range of dependence structures while being careful to avoid over-fitting.

495 Finally, we chose to adopt first-order sinusoidal functions to represent the GEV location and
496 scale parameters when estimating return levels. While this choice may be a reasonable first
497 approximation for modeling seasonality at all locations, a more flexible seasonal cycle would be
498 more appropriate. Effectively modeling the seasonal cycle can be beneficial for assessing the
499 variability in extreme events throughout the year at any location; the resulting effective return
500 levels can be crucial for public policy and disaster relief planning, especially during months where
501 extreme precipitation events are particularly intense. A more realistic and flexible seasonal cycle
502 warrants further study.

503

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677 **LIST OF FIGURES**

678 **Fig. 1.** Illustration of recursive clustering algorithm. In this example, CONUS is initially clustered
679 into 6 distinct regions (marked by different colors). Each region is further clustered (e.g.
680 region A is itself partitioned into 5 clusters); this process is repeated for each resulting
681 cluster (e.g. region B is further partitioned into 7 clusters). 35

682 **Fig. 2.** Results of the clustering algorithm. Each color corresponds to a different cluster. While
683 there are over 28,000 distinct clusters, only those created during the first two stages are
684 depicted. 36

685 **Fig. 3.** Return level maps for CONUS resulting from the non-stationary PP model using the TRMM
686 3B42 daily product. The left column contains the maps corresponding to the 2 year return
687 levels on January 1 (top) and July 1 (bottom). The right column contains the maps corre-
688 sponding to the 25 year return levels on January 1 (top) and July 1 (bottom). 37

689 **Fig. 4.** Non-stationary PP model diagnostic plots (A-B) and return level plot (C) for the cluster
690 containing Los Angeles. A) QQ plot. B) Z plot: The solid gray line is the regression fit of Z_k
691 on the expected values of the observed order statistics under the model. The dashed orange
692 line is a 45° reference line, and the dashed gray lines are 95% confidence bounds. C) Return
693 level plot: Fitted precipitation return levels in Los Angeles for December 2003 - May 2006.
694 The orange curve corresponds to the seasonal threshold, the red curve corresponds to the 2
695 year return level, and the green dashed curve corresponds to the 100 year return level. The
696 95% confidence bounds are indicated by gray dot-dashed curves. 38

697 **Fig. 5.** Maximum of daily 95% NCRs of estimated 5 year (top plot) and 20 year (bottom plot) return
698 levels from the non-stationary PP model. White values correspond to NCR values above 2. . . . 39

699 **Fig. 6.** Comparison of the return level maps produced by the CPC measurements (GEV model, CPC
700 daily unified product), GEV-based TRMM model (TRMM 3B42 product), and the stationary
701 PP TRMM model (TRMM 3B42 product). 40

702 **Fig. 7.** Comparison of model fit using the PP approach (top row) against the block maxima / GEV
703 approach (bottom row) for a randomly selected regional cluster corresponding to 4 grid
704 points in Western Colombia (for the block maxima approach, we randomly selected one of
705 these 4 grid points). Left: Kernel density plots. Black (solid) curves are empirical data,
706 blue (dashed) curves are model fit. To create the PP density plot, the empirical density of
707 the annual maxima of the data are calculated (black solid line) and compared to the GEV
708 distribution implied by the fitted PP (blue dashed curve). Middle: QQ Plots. Right: Return
709 level plots. The dashed curves are 95% confidence bounds. 41

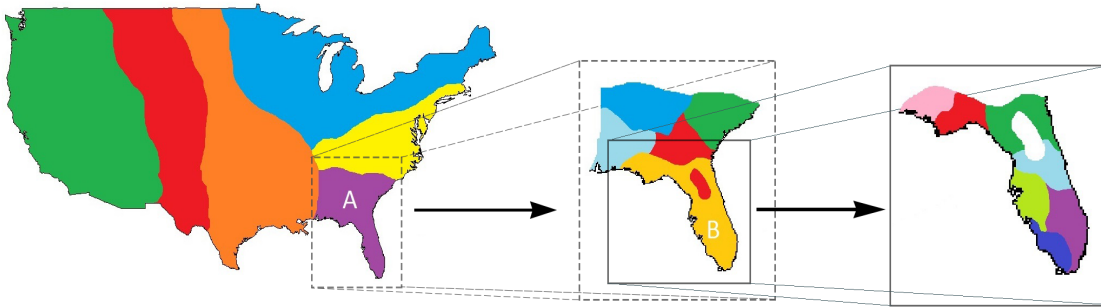
710 **Fig. 8.** Typhoon Fitow (6 October 2013) precipitation in mm (left) and predicted annual proba-
711 bilities for the non-stationary PP model (middle) and stationary GEV model (right). Only
712 precipitation levels greater than 50mm and their corresponding probabilities are shown for
713 clarity. Note the different probability scales. 42

714 **Fig. 9.** Percent change in the median of the fitted GEV distribution of extreme precipitation intensi-
715 ties. Positive changes reflect more intense extreme precipitation events and negative changes
716 reflect less intense extreme events (only trends significant at the 5% level are shown). . . . 43

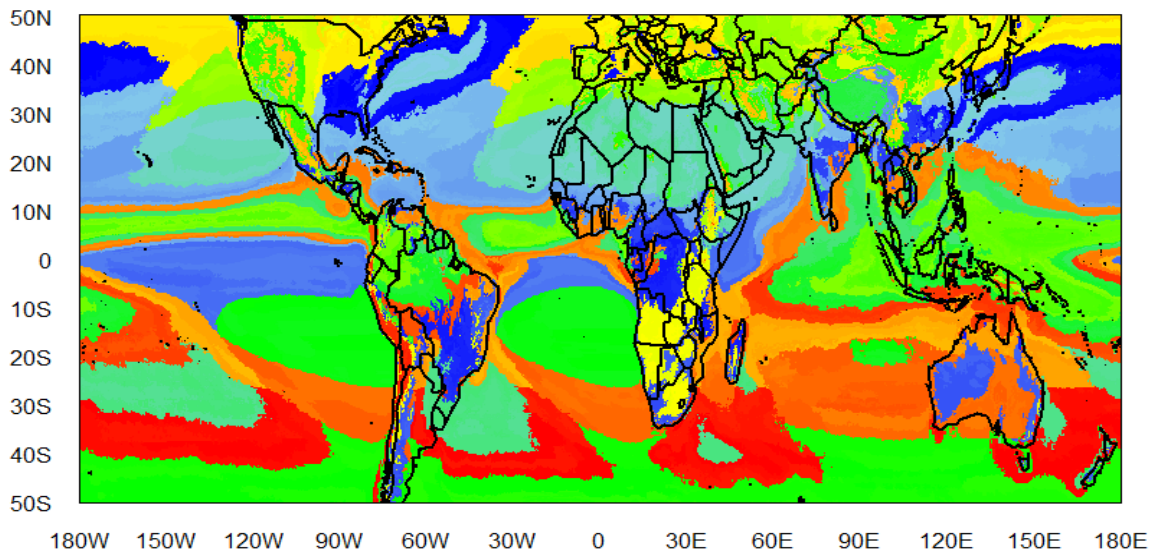
717 **Fig. 10.** Left: Mean surface air temperatures in CONUS, 1979 - 2013 (NCEP North American Re-
718 gional Reanalysis product). Right: Percent change in the median of the distribution of

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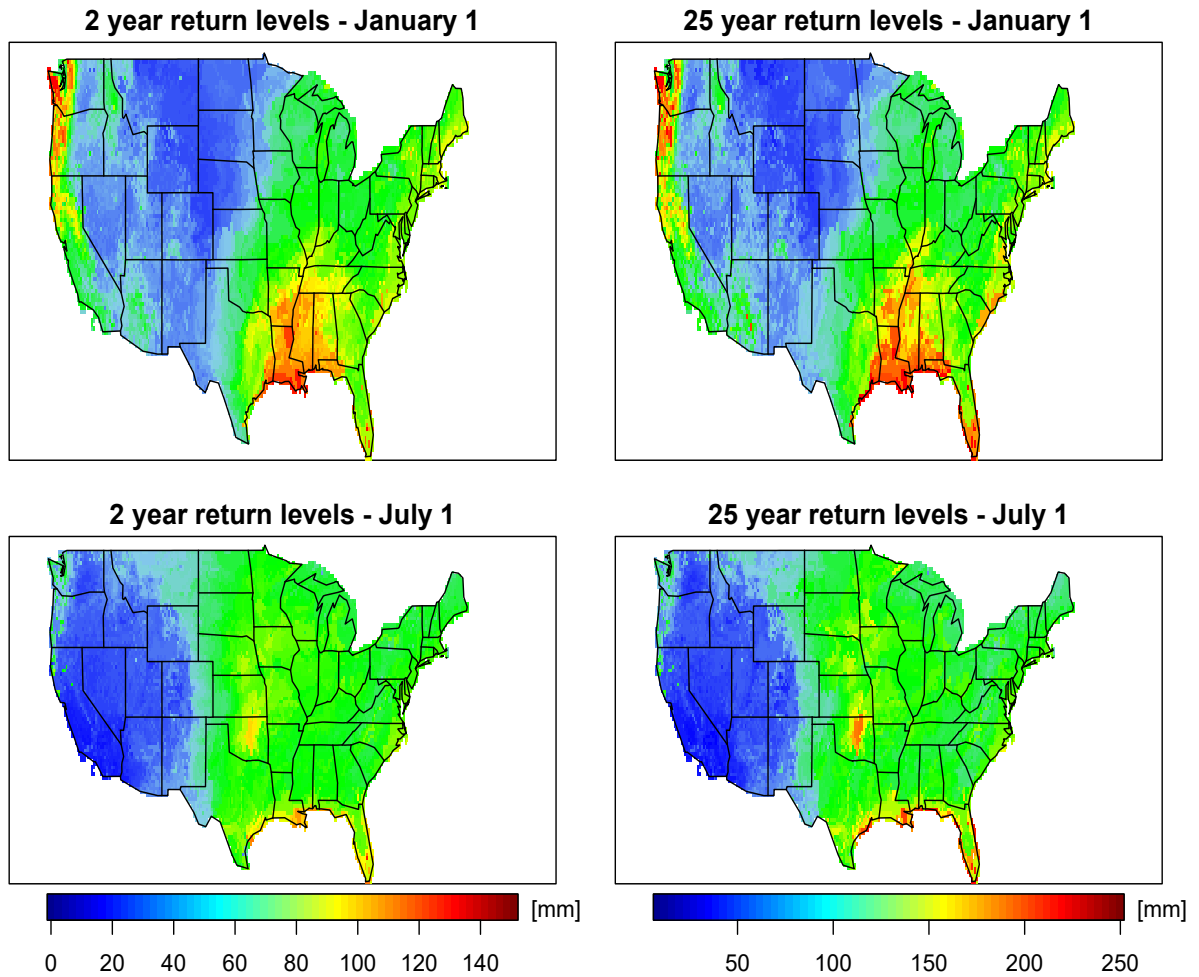
temperature extremes from the non-stationary PP model (only trends significant at the 5% level are shown). 44



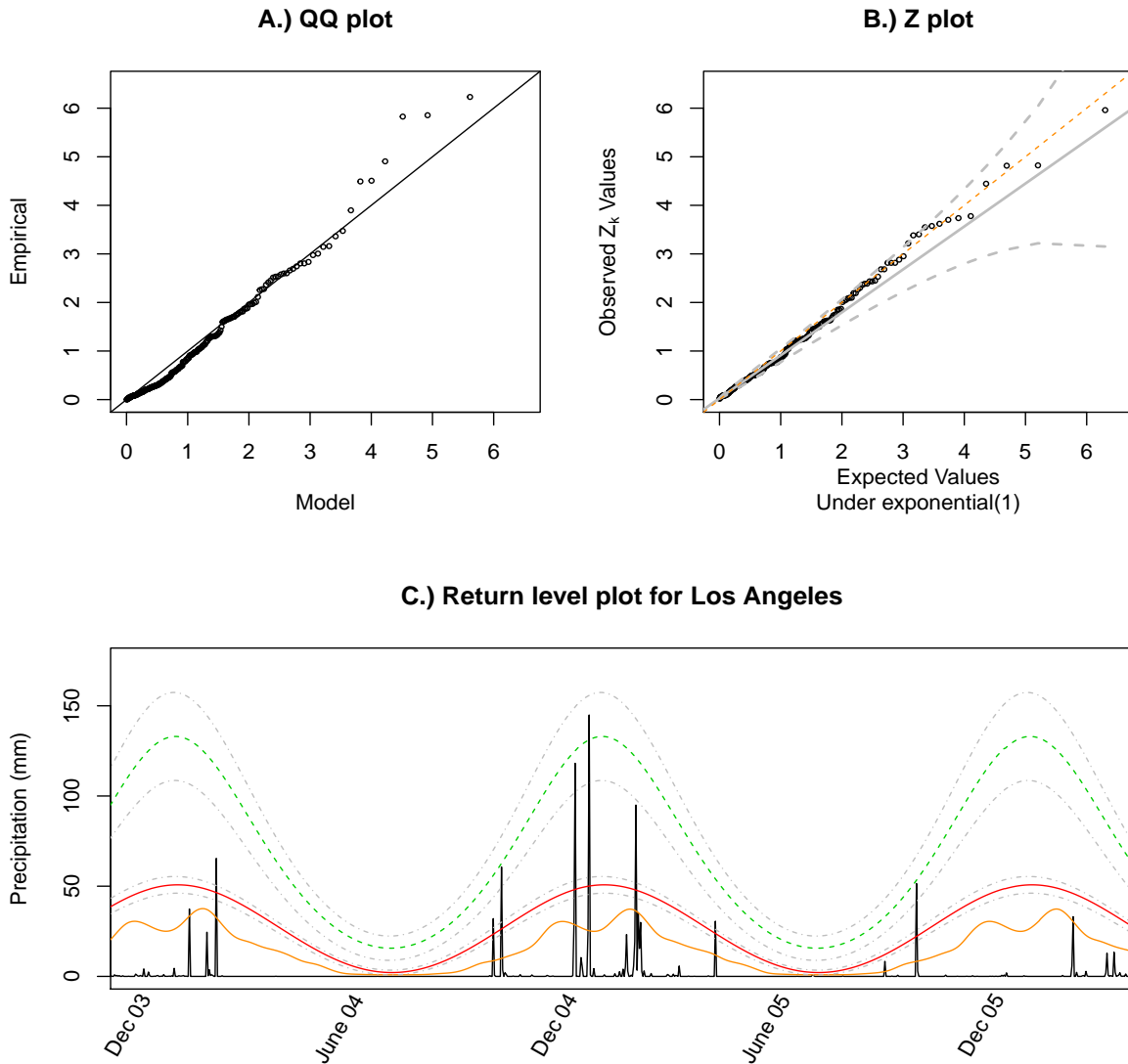
721 FIG. 1. Illustration of recursive clustering algorithm. In this example, CONUS is initially clustered into 6
722 distinct regions (marked by different colors). Each region is further clustered (e.g. region A is itself partitioned
723 into 5 clusters); this process is repeated for each resulting cluster (e.g. region B is further partitioned into 7
724 clusters).



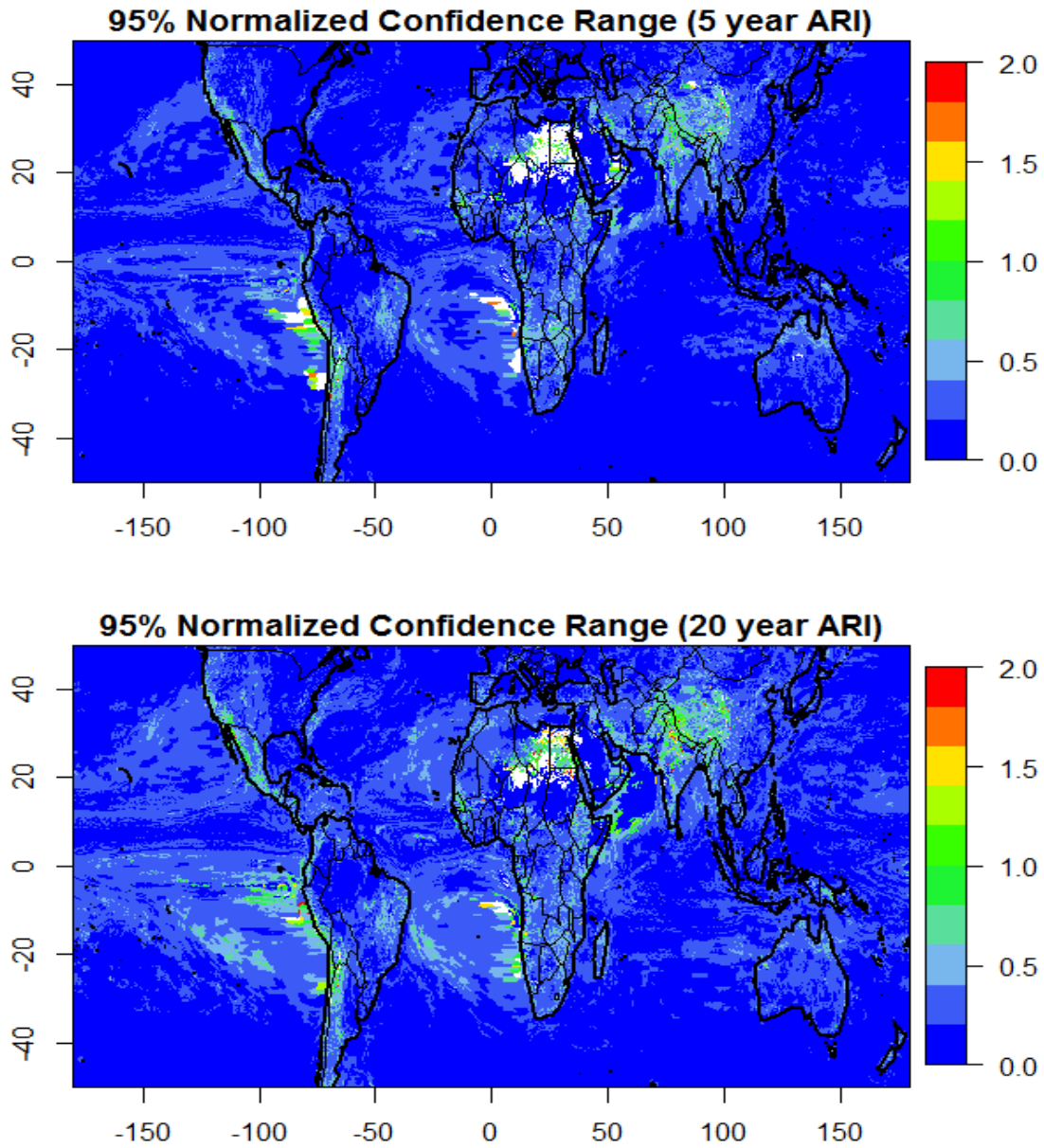
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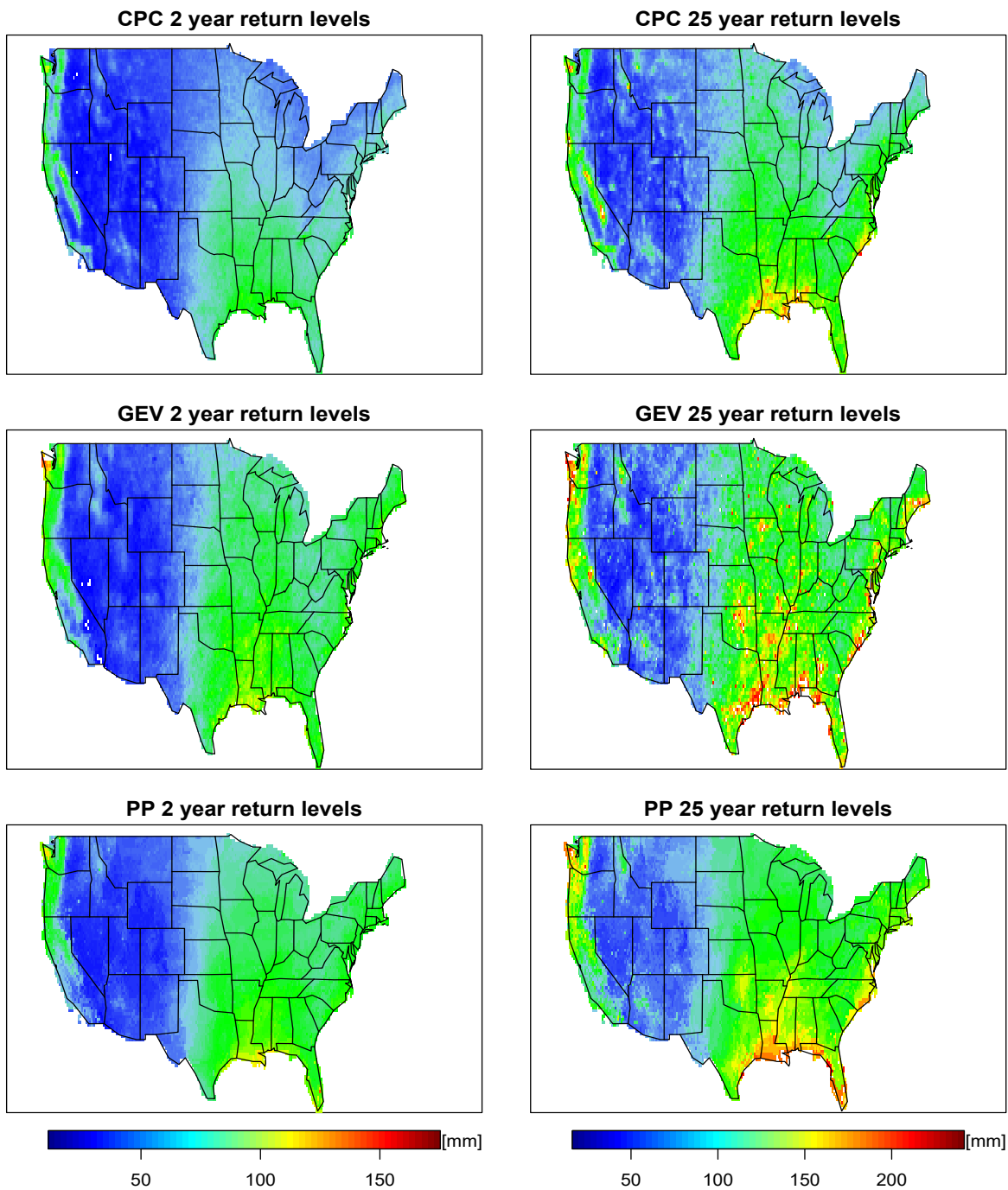
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 728 daily product. The left column contains the maps corresponding to the 2 year return levels on January 1 (top)
 729 and July 1 (bottom). The right column contains the maps corresponding to the 25 year return levels on January
 730 1 (top) and July 1 (bottom).



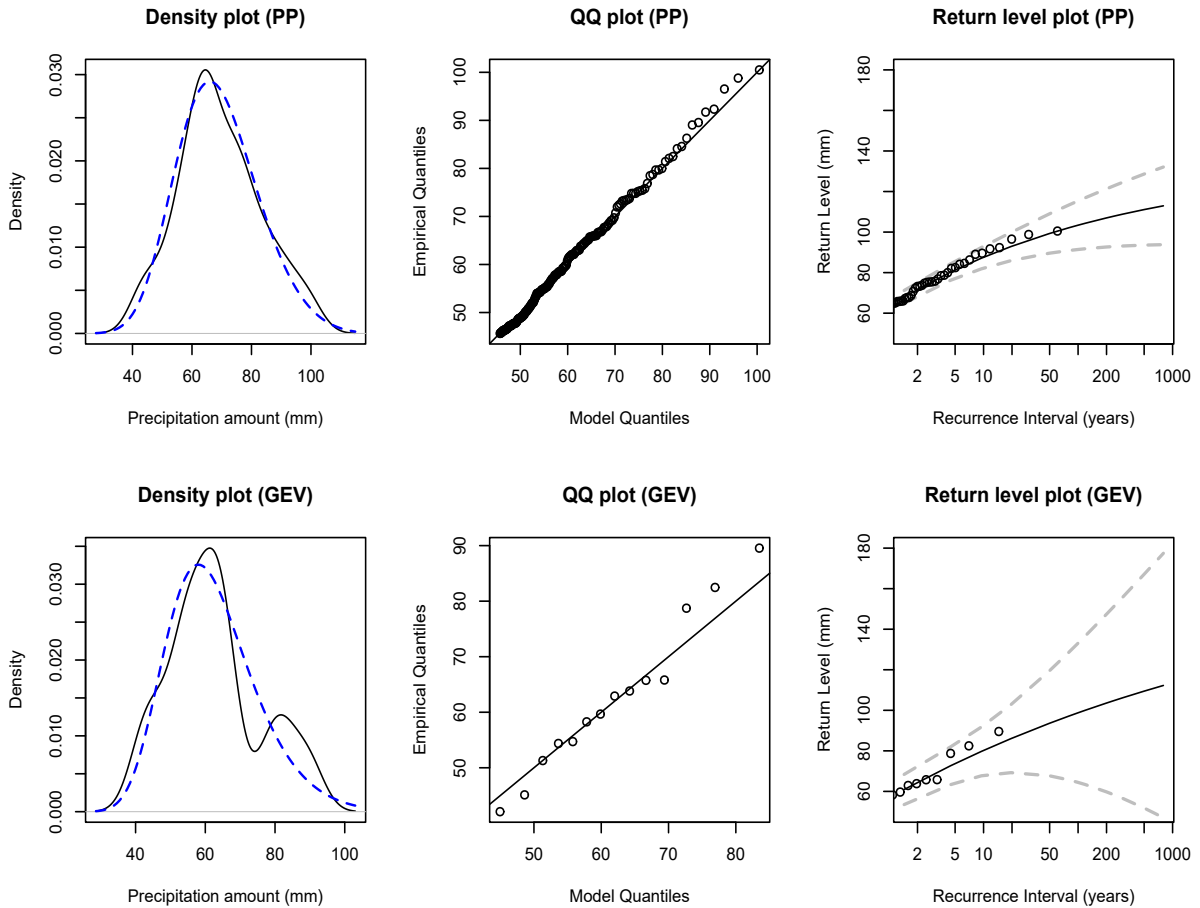
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 732 Los Angeles. A) QQ plot. B) Z plot: The solid gray line is the regression fit of Z_k on the expected values of
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 736 to the 2 year return level, and the green dashed curve corresponds to the 100 year return level. The 95%
 737 confidence bounds are indicated by gray dot-dashed curves.



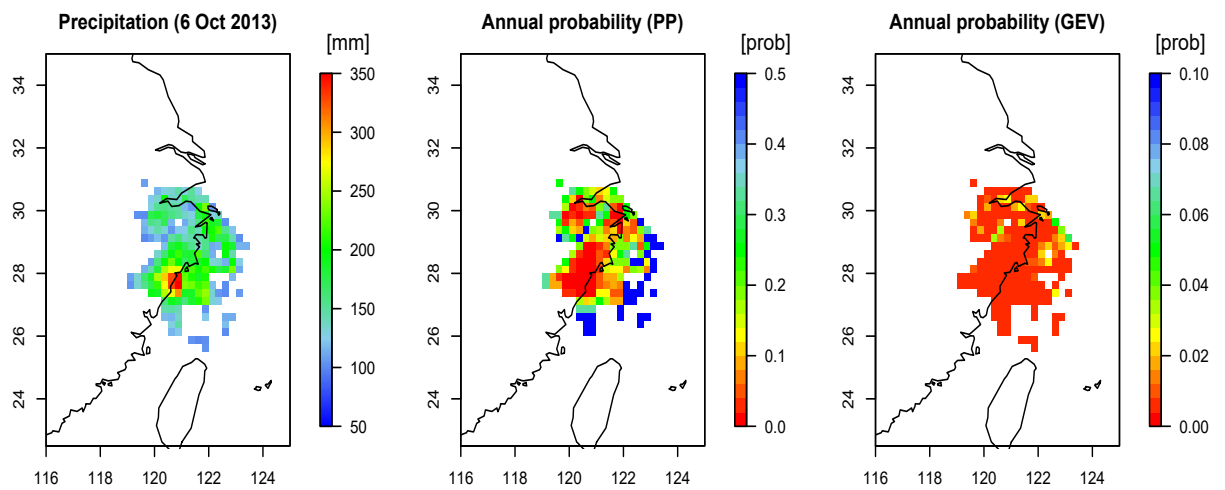
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 739 from the non-stationary PP model. White values correspond to NCR values above 2.



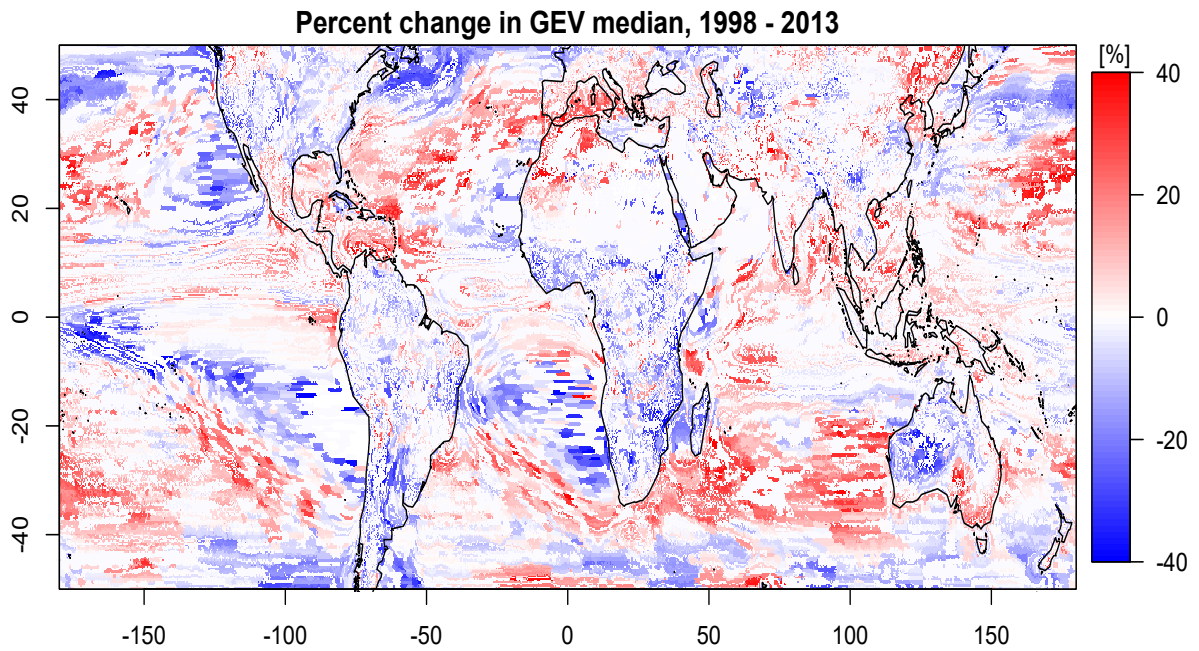
740 FIG. 6. Comparison of the return level maps produced by the CPC measurements (GEV model, CPC daily uni-
 741 fied product), GEV-based TRMM model (TRMM 3B42 product), and the stationary PP TRMM model (TRMM
 742 3B42 product).



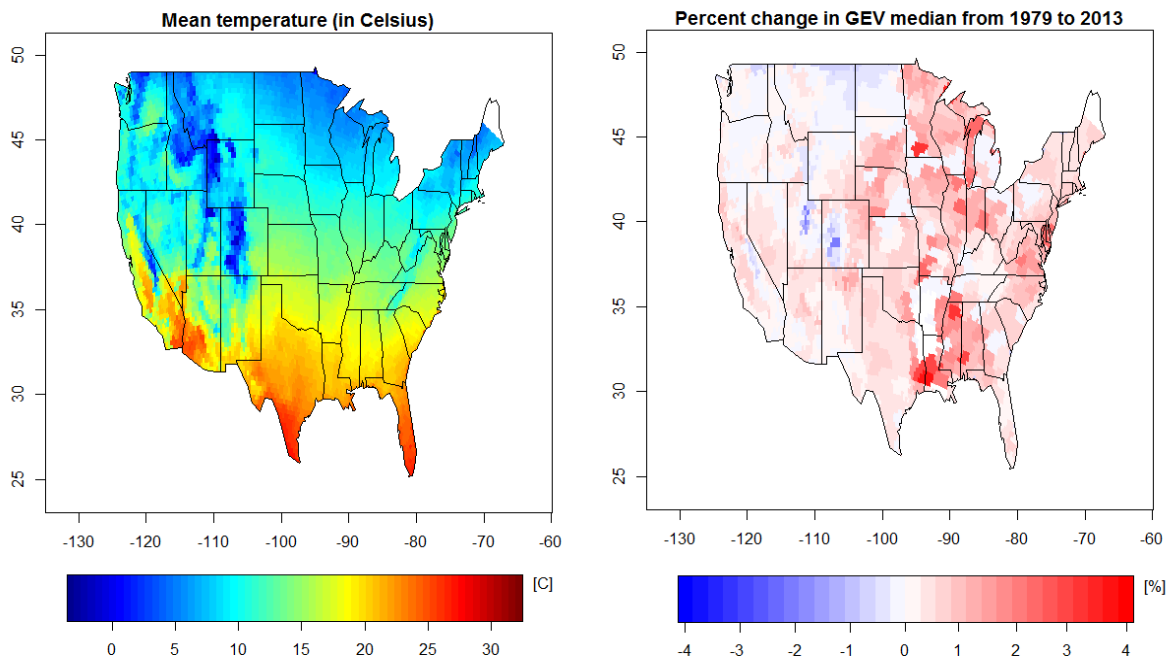
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750 FIG. 8. Typhoon Fitow (6 October 2013) precipitation in mm (left) and predicted annual probabilities for
 751 the non-stationary PP model (middle) and stationary GEV model (right). Only precipitation levels greater than
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754 Positive changes reflect more intense extreme precipitation events and negative changes reflect less intense
755 extreme events (only trends significant at the 5% level are shown).



756 FIG. 10. Left: Mean surface air temperatures in CONUS, 1979 - 2013 (NCEP North American Regional
 757 Reanalysis product). Right: Percent change in the median of the distribution of temperature extremes from the
 758 non-stationary PP model (only trends significant at the 5% level are shown).