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1 **Transparent Planning For Biodiversity And Development In The Urban Fringe**

2
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23 **Abstract**

24 In Australia, over 50% of threatened species occur within the urban fringe and accelerating
25 urbanisation is now a key threat. Biodiversity near and within urban areas brings much social
26 benefit but its maintenance involves complex tradeoffs between competing land uses. Urban
27 design typically views biodiversity as a development constraint, not a value to be optimised into
28 the future. We argue that decisions could be more transparent and systematic and we
29 demonstrate that efficient development solutions can be found that avoid areas important for
30 biodiversity. We present a case study in the context of land use change across the City of
31 Wyndham, a local Government west of Melbourne, Australia. We use recent advances in reserve
32 design tools to identify the best tradeoffs between competing values. We suggest that
33 government agencies could adopt similar approaches to identify efficient planning solutions for
34 both biodiversity and development in urban environments.

36 **Introduction**

37 Consistent with a worldwide trend, the size of Australian cities has increased dramatically over
38 the last 100 years (UNFPA, 2007). Increasing numbers of people are choosing to live in urban
39 environments, with approximately 75% of Australians living in the metropolitan areas of capital
40 or smaller cities and this is projected to increase to 90% by the year 2011 (Newton et al., 2001).
41 Rapidly increasing urbanisation rates pose one of the greatest threats to the substantial
42 biodiversity of the urban fringe (Goddard, Dougill & Benton 2010; J. Williams et al., 2001) and
43 create an urgent need to improve conservation planning practices in those areas. The
44 biodiversity of remnant areas proximal to cities is considered nationally and internationally
45 significant, with over 40% of nationally listed threatened ecological communities (Newton et al.,
46 2001) and more than 50% of threatened species occurring in urban fringe areas (Yencken &
47 Wilkinson, 2000). While the literature is clear that the expansion and intensification of human
48 settlement has serious implications for biodiversity (Miller & Hobbs, 2002; Pickett &
49 McDonnell, 1993; Stenhouse, 2004), the loss of natural ecosystems within and adjacent to the
50 limits of a city also poses risks to public health and the quality-of-life of urban citizens (Binning,
51 Cork, Parry, & Shelton, 2001; Boland & Hundhammar, 1999).

52 Conservation planning in the urban fringe poses many challenges. Firstly, a long-term strategic
53 view is required, as ad-hoc conservation planning efforts will ultimately fail to protect remnant
54 patches of vegetation (Pressey, Humphries, Margules, Vane-Wright, & Williams, 1993) either
55 from outright loss or gradual degradation due to the incremental pressures of urbanisation.

56 Urban development is inherently hostile to nature conservation, as built up areas and their
57 attendant infrastructure are impermeable to the dispersal and movement to a range of organisms.

58 Secondly, protection of habitat for biodiversity in urban fringe areas involves tradeoffs between a
59 complex range of land uses including housing, industrial development, agricultural production
60 and conservation, and the intensity of the pressures placed on natural areas is often much higher
61 than other regions. The inflated cost of land means that conservation budgets can often be more
62 efficiently allocated elsewhere to achieve conservation objectives. Vegetation cleared for
63 development is often required to be ‘offset’ by revegetation elsewhere (eg. (Department of
64 Environment and Conservation (NSW), 2005; Victorian Government, 2002). However, the
65 inflated cost of land for revegetation in urban areas tends to direct investment away from peri-
66 urban areas. There are many ecological challenges to implementing offsetting policies including
67 that biodiversity assets are relatively fixed spatially and temporally and, unlike other land uses,
68 cannot be readily transposed from one area to another (S.A. Bekessy et al. 2008).

69 Despite the introduction of planning legislation and frameworks to preserve biodiversity, many
70 cities around the world are facing a looming extinction crisis; short-term economic gains
71 consistently win over biodiversity concerns on a localised case-by-case basis. The problem of
72 cumulative impacts stems from the difficulty of demonstrating that while each single land use
73 change can have a low overall impact on biodiversity, the accumulation of individual changes
74 over time and within a region might well constitute a major impact (Theobald et al 1997). There
75 is often little scientific input into the biodiversity aspects of the urban planning process and
76 consideration of biodiversity is typically ad-hoc (Bekessy & Gordon, 2007). Frequently, the
77 urban design response to nature conservation is to view biodiversity along with other factors,
78 such as flood risk, as a development constraint, rather than a value to be optimised into the
79 future. Tools such as planning charrettes (Steiner et al., 1999) are often used to incorporate a

80 range of stakeholder views, but the public transparency and democracy of such approaches can
81 be lacking (Margerum, 2005).

82 Opportunities exist to substantially improve the way that biodiversity is considered in urban
83 planning through the development of tools that optimise the trade-off between conservation
84 objectives and other competing demands of urbanisation within ecological, legislative and policy
85 constraints (A. Gordon et al. 2009). We argue that it is possible to use existing conservation
86 planning tools to transparently and objectively find an efficient urban planning solution that
87 accommodates biodiversity and development. We demonstrate this approach to land use
88 allocation decisions using spatial representations of biodiversity attributes and a spectrum of
89 development scenarios within the City of Wyndham, a municipality on the western fringe of
90 Melbourne. This method builds on recent advancements in ecological modelling and
91 mathematical optimisation to facilitate transparent decisions based on optimal trade-offs between
92 competing values (A Moilanen, 2007; A Moilanen et al., 2005). Maps can be produced that
93 identify areas with high biodiversity and areas of low biodiversity that would be most suitable
94 for development from the perspective of species conservation. Tradeoffs can be then made
95 explicitly by incorporating other social or economic requirements in the optimisation process.
96 The modelling output is spatially explicit and visually compelling, addressing an identified need
97 in urban biodiversity planning (Sandström, Angelstama, & Khakeec, 2006). We do not argue
98 that the tool should be used to determine concrete planning outcomes, but that it should be used
99 to inform the decision-making process in order to achieve more strategic and transparent
100 conservation planning in urban environments.

101

102 **Methods**

103 The following section outlines the steps taken to create development plans that are spatially
104 optimized for biodiversity while incorporating a range of social and economic requirements.
105 First, we describe the study site, which is a designated growth corridor that contains highly
106 threatened vegetation and species. Second, we describe the development of the various layers
107 that will be optimised, including habitat maps for threatened fauna species, the condition of the
108 vegetation, and layers representing a sample of other elements that planners need to consider, in
109 this case proximity to public transport, flood risk and the cost of maintaining remnant vegetation.
110 Third, we describe the process of finding landscape designs that optimize across these layers
111 using the ZONATION software.

112 **Study Site**

113 The city of Wyndham is located on the south western fringe of the urban extent of greater
114 Melbourne (see map, Figure 1) and has been identified as a key growth area to accommodate
115 future urban expansion (Victorian Department of Sustainability and Environment, 2002). The
116 area is at the eastern extremity of the vast volcanic plain that stretches from the South Australian
117 border region in the west of the state of Victoria to the northern suburbs of Melbourne. The area
118 is characterised by low rainfall and heavy clay soils, which can produce extreme seasonal
119 drought stress particularly in *El Nino* years. This typically results in limited woody tree and
120 shrub growth. Apart from the riparian vegetation associated with the major rivers and streams
121 and a few large freshwater wetlands, the pre-European vegetation of the study area would have
122 been largely treeless.

123 Lowland temperate grasslands are among the most threatened ecosystems in Australia, with less
124 than 1% of the original extent remaining (Barlow, 1998). The Basalt Plains Grassland
125 Community – to which treeless remnants within the study area belong – is listed as critically
126 endangered under the Commonwealth *EPBC Act 1999*. Threats to the community are current:
127 over 50% of remnants present around Melbourne in 1985 were lost in the following 15 years as a
128 result of continuing urban development and poor management practices (N. S. G. Williams,
129 McDonnell, & Seager, 2005) and losses continue to occur in the rural landscape as a
130 consequence of pasture improvement and cropping. Further, the study area occurs within the
131 Victorian volcanic plains bioregion, which is under-represented by conservation reserves
132 compared to other bioregions around Melbourne (M. McCarthy, Thompson, & Williams, 2006).

133 Numerous isolated and often highly degraded grassland remnants persist in the heavily
134 developed parts of the eastern section of the study area. Many of these remnants are the legacy
135 of the inability of past planning processes to appropriately accommodate biodiversity
136 requirements. Notwithstanding the ongoing site management issues, some of these reserves
137 retain significant biodiversity and are highly valued by sections of the local community. The
138 study area supports populations of more than 50 state or federally listed fauna species and
139 numerous threatened plant species. Part of the Western Port Phillip Bay (Western Shoreline) and
140 Bellarine Peninsular RAMSAR (Convention on Wetlands) listed site is located within the study
141 area and is therefore considered a site of national significance.

142 As a designated growth area under *Melbourne 2030* (Victorian Department of Sustainability and
143 Environment, 2002), approximately 30,000 new homes will be constructed in the area over the
144 next 30 years, along with intensive commercial and industrial development.

145 **Habitat Maps**

146 Binary maps were created for each of the rare and threatened fauna species (Victorian
147 Department of Sustainability and Environment, 2003) known to occur within the study area,
148 indicating the presence or absence of ‘potential habitat’. Potential habitat was defined as
149 including all land uses and all vegetation and wetland types that may support individuals of the
150 subject taxa. Rules defining each of these binary maps were elicited from various specialist
151 ecologists with local field experience by posing the question, “What land uses and vegetation
152 and or wetland types as defined by the available spatial data, never comprise habitat for this
153 species?” Once this was satisfactorily determined the residual landscape became ‘potential
154 habitat’. This data was supplemented with limited field assessments. It is acknowledged that the
155 potential habitat models (syn distribution maps) do not reflect the suitability and viability of
156 habitat for species and populations. In addition, the models have not been subject to any
157 rigorous evaluation and should be considered indicative only, for the purposes of demonstrating
158 the method. See Wintle et al. (2005) for a description of data requirements for more accurate
159 habitat modelling.

160

161 Potential habitat or distribution maps were compiled within a GIS, using vector data resolved to
162 1:25,000 scale, relating to land use, vegetation type, wetlands and watercourses. Maps were
163 built for 32 birds, 4 mammals, 2 amphibians, 3 fish, 4 reptiles, and one invertebrate. The habitats
164 of threatened plant species were not specifically mapped, as the distribution of rare species
165 within the study area is idiosyncratic and closely tied to the specific land use histories and land
166 use intensities that have operated at any particular site. Hence, vegetation extent and condition

167 was used as a coarse surrogate for the distribution of flora species. See Elith and Burgman
168 (2002) for a description of data requirements for more accurate habitat modelling of rare plants.

169 **Mapping Vegetation Extent And ‘Habitat Condition’**

170 As much of the study area is privately owned land, existing vegetation mapping, which has
171 historically focussed on public land, proved to be inadequate. Therefore, remnant vegetation
172 across Wyndham was mapped employing field reconnaissance, Aerial Photograph Interpretation
173 (API) of recent 1:5,000 scale digital aerial photography and advice from Government agency
174 officers, environmental consultants and local naturalists. Vegetation was classified in
175 accordance with the established Victorian typological framework (Victorian Government, 2002).
176 Line work was digitally captured and subsequently ground-truthed.

177 A surface representing ‘habitat condition’ was generated, ranking the entire study area on the
178 basis of observed site attributes measured against an appropriate archetype or benchmark and
179 landscape attributes. A full description of this benchmarking approach, including the attributes
180 employed and their weightings within a combined condition index, is provided in Parkes et al.
181 (2003). Scores for structure and composition (score range 1-25) and the relative abundance and
182 dominance of exotic weeds (score range 1-15) were allocated to homogeneous ‘patches’ of
183 vegetation. Constraints to site access precluded a detailed appraisal of the condition of
184 vegetation and habitat, and sites supporting native vegetation were largely assessed from
185 roadsides. Simple landscape attributes were generated for patches of vegetation within a GIS,
186 including patch size (range 1-15), scaled density of habitat/vegetation (range 1-10) and distance
187 to the core area of a large local remnant (score range 1-5) (Parkes et al., 2003).

188 **Cost Layers**

189 Figure 2 presents a set of cost layers that were developed for use in the various planning
190 scenarios. Biodiversity cost (Figure 2(a)) was calculated using the ‘landscape context’ GIS layer
191 (DSE Corporate library; Wilson and Lowe (2003)), which represents the condition of the site and
192 connectedness to other vegetation within the region. We assumed that sites with a lower
193 landscape context score would be more costly to restore and maintain, hence these sites were
194 allocated a lower value for biodiversity (and a higher potential value for development). Figure
195 2(b) presents biodiversity cost added to flood cost, which assumes a lower potential value for
196 development in flood-prone sites. Figure 2(c) includes proximity to rail, whereby potential value
197 for development decreases with distance from the existing rail line (proximity to the railway line
198 was used, rather than proximity to railway stations because new stations are proposed under the
199 planning document *Melbourne 2030*). Areas were weighted by their perpendicular distance from
200 the rail line according to Table 1. Figure 2 (d) presents a cost layer that is a sum of the three cost
201 layers, biodiversity, flood risk and rail line proximity.

202 **Spatial Optimisation**

203 The objective of the optimisation process is to select an arrangement of habitat patches that
204 maximizes habitat quality, species richness and rarity, while maintaining habitat connectivity.
205 Economic and social factors were also included as potential ‘costs’ or ‘benefits’ to be optimised.
206 The optimisation procedure was conducted for a range of scenarios given different proportions of
207 the landscape available for habitat protection (see Table 2).

208 Landscape solutions were calculated using the ZONATION method and software (A Moilanen,
209 2007; A Moilanen et al., 2005; A. Moilanen & Kujala, 2006). ZONATION ranks all cells in the

210 landscape according to representation of biodiversity features, complementarity and the degree
211 of habitat connectivity. The algorithm considers the full landscape to start with, and then
212 iteratively discards grid cells of lowest value from the edge of the remaining area, thus
213 maintaining a high degree of structural connectivity in the remaining habitat. (The condition of
214 removal from edge improves computational efficiency, but it can be relaxed if so wished). The
215 Zonation algorithm differs from target-based planning or maximum coverage reserve selection
216 (see Moilanen (2007) for details). Instead of finding a single optimal solution, such as the least
217 expensive set of sites that achieves targets, it generates a hierarchy of solutions. The hierarchy is
218 generated via a strategy of minimization of marginal loss, the iterated removal of that cell whose
219 loss causes the smallest decrease in the conservation value of the remaining reserve network.
220 Thus, instead of a single selection of sites, it generates a gradation of conservation priority
221 throughout the landscape (such as Figure 3(a)) and an associated set of curves (such as Figure 9),
222 describing how well each species (or land cover type) does at any given level of cell removal.
223 Specification of species weights, connectivity requirements and the so-called cell-removal rule
224 result in a balanced species representation at each level of landscape availability. The
225 hierarchical structure of the solution means that the best 1% is within the best 2% of the
226 landscape which is within the best 5%, and so on, which allows for easy visualisation of results.
227 Any given top fraction of landscape can be simply identified after a ZONATION run, because
228 the removal hierarchy of cells is saved. Likewise, any given least useful fraction of the
229 landscape can be identified, which was the objective in this study – to identify areas most
230 suitable for urban development. The nature of the ZONATION algorithm allows it to be run on
231 data sets in the order of millions of landscape elements (grid cells) combined with hundreds of

232 species, which facilitates a direct link between statistical habitat suitability modelling on GIS
233 grids and ZONATION.

234 The ZONATION meta-algorithm, as given by Moilanen (2007) is simple: (1) Start from the full
235 landscape. Set rank $r = 1$. (2) Calculate marginal loss following from the removal of each
236 remaining site i , δ_i . (3) Remove the cell with smallest δ_i , set removal rank of i to be r , set $r=r+1$,
237 and return to 2 if there are any cells remaining in the landscape. The critical part of the
238 algorithm is the definition of marginal loss, where many complications can be introduced. These
239 include techniques for generating reserves that have been aggregated in a species-specific
240 manner, distribution smoothing (A Moilanen et al., 2005; A Moilanen & Wintle, 2006) and the
241 boundary quality penalty (A Moilanen & Wintle, 2007). The algorithm allows uncertainty
242 analysis, aiming at robust reserves that are likely to contain the species (A Moilanen et al., 2006;
243 A Moilanen & Wintle, 2006). The technique of replacement cost analysis (Cabeza & Moilanen,
244 2006) can be used to evaluate the conservation value of an unconstrained optimal solution
245 against solutions that either forcibly include proposed/existing reserve areas or forcibly exclude
246 areas required for agricultural-urban development. The ZONATION software and a user manual
247 (A. Moilanen & Kujala, 2006) are freely available via the website
248 (www.helsinki.fi/science/metapop).

249 There are three basic alternatives for the so-called cell removal rule, used in step (2) of the
250 ZONATION meta-algorithm, namely core-area, additive benefit function and targeting benefit
251 function. Each of these corresponds to slightly different assumptions about the planning
252 objective, how local quality is valued and how biodiversity features are traded off against
253 each other. In this study we used the core-area algorithm (A Moilanen, 2007; A Moilanen et al.,
254 2005). It has the properties that (i) species weights and land cost are included in prioritisation,

255 (ii) high-quality locations are preferred for all species even if the occurrences are in species-poor
256 areas. Compared to additive benefit functions or target-based planning, the core-area algorithm
257 generally produces solutions which have lower average representation levels, but higher
258 minimum representation across species and higher local quality for selected locations (A
259 Moilanen, 2007).

260 Technically, the core-area algorithm defines marginal loss caused by the loss of cell i as:

$$261 \quad \delta_i = \max_j \frac{Q_{ij}(S)w_j}{c_i}, \quad (\text{equation 1})$$

262 where w_j is the weight of species j and c_i is the cost of adding cell i to the reserve network. The
263 weight can be used to prioritise species according to, for example, their taxonomic uniqueness or
264 some measure of global rarity. Cell cost can be any measure of (opportunity) cost following the
265 allocation of the cell for conservation – here cost was related to flood proneness or proximity to
266 railway.

267 The critical part of the equation is $Q_{ij}(S)$, the proportion of the remaining distribution of species j
268 located in cell i in the remaining set of cell, S . When a part of the distribution of a species is
269 removed, the proportion located in each remaining cell goes up. This means ZONATION tries
270 to retain core areas of all species until the end of cell removal even if the species is initially
271 widespread and common. The min-max facilitates the algorithm feature that occurrences are not
272 treated as additive, but that high-quality locations are strongly preferred for species. Figure 3
273 illustrates the workflow we used with ZONATION in this study.

274

275 **Results**

276 A map of the growth area prioritised for the biodiversity attributes only (scenario 1) is presented
277 in Figure 4. Cells are ranked 0-1, where a value of 0.98 would indicate that 98% of cells would
278 be removed from the landscape before that cell would be chosen for development. Several
279 ‘hotspots’ can be identified, as well as areas more preferable for development.

280 Optimised solutions for a range of development scenarios are presented in Figures 5-8. The red
281 areas represent those that would be chosen for development and the remaining cells are graded
282 light to dark, with darker areas indicating higher priority for biodiversity. In each figure, (a)
283 represents the ZONATION output, ranking cells from highest value to lowest value; (b)
284 represents the difference between rankings for the scenario compared with figure 5 (biodiversity
285 only), where lighter areas represents cells that have increased in their ranking, and darker areas
286 have decreased in their ranking; and (c) represents the lowest ranked 10% of the landscape,
287 which could be deemed most suitable for development (apart from Figures 4 and 8 which only
288 displays ZONATION output and lowest ranked 10% of the landscape).

289 Figure 9 presents plots for each scenario of the proportion of the landscape lost against the
290 minimum proportion of habitat available to any of the species modelled. This figure describes
291 how robust any given level of cell removal is to the species that suffer the greatest (proportional)
292 loss of habitat. Overall, it is apparent that 10% of the landscape could be developed with
293 relatively minor (4% average) biodiversity loss, and that the differences between scenarios are
294 small in this respect. Thus, flood-prone areas could be avoided and proximity to rail preferred
295 with minor biodiversity consequences. The only significant difference between scenarios is
296 between the market-gardens scenario (scenario 5; Figure 9d) and other scenarios. In scenario 5

297 more land is available for development, and the development of the market-gardens has little
298 impact on biodiversity, which is apparent from Figure (9d) as the loss of 10% of the landscape
299 results in close to zero biodiversity loss. In all scenarios the influence of flood avoidance or
300 proximity to rail is only apparent at high levels of habitat loss (not shown).

301 **Discussion And Conclusions**

302 This case study demonstrates a method that can improve rigour and transparency in urban
303 planning, while incorporating scientifically derived criteria for biodiversity conservation. The
304 process involves gathering data, identifying and weighting key values according to stakeholder
305 preference, and modelling to produce visual representations of possible scenarios that have been
306 optimised according to the chosen values.

307 The method confers several advantages to the planning process. Firstly, it recognises that the
308 ecological foundations of a site are less portable than other considerations (Fallding, 2004). The
309 modelling method provides a mechanism for making tradeoffs in the least harmful way for
310 biodiversity, incorporating the spatial distribution of biodiversity early on in development
311 planning. Setting biodiversity as an underlying value to be optimised encourages tradeoffs to be
312 made in a more timely and transparent way.

313 Secondly, it encourages decision-makers to explicitly rank priorities. The objective function for
314 the optimisation can be decided upon using a democratic process, whereby stakeholders openly
315 debate and decide upon appropriate weightings for competing values. The implications of
316 different weightings for biodiversity conservation, or different valuation philosophies (van der
317 Windt, Swart, & Keulartz, 2007) can then be explored. In addition, the tool provides
318 opportunities for the community to be exposed to the complexities and consequences of land use.

319 This could serve to further democratise both the planning process and the planning outcomes and
320 increase the level of public transparency. The tool provides powerful visual representations of
321 the planning scenarios that can be used to integrate objectives and explore tradeoffs.

322 Thirdly, the tool highlights dilemmas between competing objectives and encourages discussion
323 of the implications of different tradeoffs. In the Wyndham case study, several competing
324 sustainability objectives were explored. The dilemma of prioritising biodiversity conservation
325 over public transport-oriented development was examined. The spatial configuration of least
326 valuable cells was identified while varying the weighting given to the competing objectives. A
327 further sustainability dilemma was highlighted between biodiversity protection and local food
328 production. The development scenarios were initially developed masking out the area currently
329 used for market gardens, as these areas were deemed commercially valuable and hence
330 unavailable for housing development. Furthermore, local food production has emerged as a
331 significant priority for greenhouse gas reduction. However, if biodiversity was the major
332 community concern in the region, and food production was a low priority, the market gardens
333 would be designated for development as the areas of least impact on biodiversity (Figure 9).

334 The implications of alternative biodiversity conservation policies can also be explored. For
335 example, a 'triage' approach would weight critically endangered species higher than less
336 threatened species (M. C. Bottrill et al. 2008). Alternatively, least endangered species would be
337 prioritised if the focus biodiversity policies aim to preserve those species that are most likely to
338 become critically endangered in years to come (McIntyre, Barrett, Kitching, & Recher, 1992).
339 Policy choices of this kind are typically made without explicitly exploring the implications of
340 different trade-offs (McIntyre et al., 1992).

341 Finally, the exercise can also lead to the identification of alternative development approaches
342 that could reduce environmental impact. For example, despite some changes in sub-division
343 size, Melbourne's peri-urban regions continue to represent housing densities significantly below
344 those employed in cities of international comparison (Scheurer & Buxton, 2005). If the average
345 housing density could be increased even slightly, the area required to fit 30,000 new homes
346 would be substantially reduced (Scheurer & Buxton, 2005). While this tool provides a
347 transparent mechanism for articulating tradeoffs in urban planning, it does not indicate whether
348 decisions are ultimately 'acceptable'. The decision to clear habitat to meet competing objectives
349 is a social one, but should be made acknowledging the risks to environmental and other
350 concerns. A decision theory framework that articulates costs, benefits and risks could be useful
351 in this context (Possingham, 2001).

352 A key limitation of the case study presented here is that the quality of the landscape optimisation
353 depends on the quality of the underlying data. In this scenario, the species distribution models
354 and habitat quality assessments undertaken may not be adequate or sufficiently accurate
355 surrogates of the region's biodiversity to appropriately inform the allocation of land use (see M.
356 A. McCarthy et al., 2004). Data quality was further reduced by access constraints restricting
357 surveys on private property. Error and uncertainty in underlying GIS maps has been shown to
358 translate into 'inefficient, unrealistic or erroneous' land management decisions (Rae, Rothley, &
359 Dragicevic, 2007). Ideally landscape optimisation within the urban context would be informed
360 by spatially and statistically explicit models of the habitat and potential for persistence of the
361 entire indigenous biota. Such a data set would require a substantial and possibly unrealistic
362 amount of additional genetic and biophysical inventory, modelling and research. In addition, its
363 assembly would require an extended lead up period before the decision making process to ensure

364 that seasonal detectability issues typical of grasslands are addressed (Garrard, Bekessy, &
365 Wintle, 2008). In urban areas, biodiversity is routinely considered at the project assessment
366 phase when decisions about spatial arrangement have already been made (Fallding, 2004).
367 Identifying the minimum biodiversity data set required to make robust decisions for biodiversity
368 conservation and analysing of the impact of underlying uncertainty (A Moilanen et al., 2006) on
369 the selection of priority areas for conservation in the peri-urban context will be the focus of
370 further research.

371 The modelling tool presented here assists in identifying areas that best represent a sub-set of the
372 species present in the region, but the tool tells us little about the likely persistence of those
373 species into the future. Maintaining the viability of species requires consideration of a multitude
374 of factors including landscape elements (such as the fragmentation of habitat and the size and
375 shape of remnants and the types of land uses being carried out with in the matrix), and the
376 requirements of individual species (such as mode of dispersal, rate of replacement and response
377 to urban impacts). Although a simple concept, incorporating ‘species viability’ in the evaluation
378 of conservation planning options remains a significant challenge to conservation planners
379 (Margules & Pressey, 2000). Nevertheless, the method proposed here is a step towards adapting
380 conservation planning methods to planning of urban development zones. The approach is novel
381 in that we use ‘reserve design’ tools in an inverse manner to identify areas of least impact on
382 biodiversity assets that are consequently preferable for development.

383

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395

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Table 2 Description of the development scenarios used in the optimisation procedure, including the variables maximised and the weighting used to prioritise values.

Table 1. Weightings used to create the cost layer representing proximity to the existing rail line.

Distance from the rail line	Weighting
<2 km	4
2-3 km	3
3-5 km	2
>5 km	1

Table 2 Description of the development scenarios used in the optimisation procedure, including the variables maximised and the weighting used to prioritise values.

Scenario	Objective of prioritisation	Weighting
Scenario 1: Priority given to biodiversity only	Maximal balanced species representation according to habitat maps for 50 listed fauna species. Maximize habitat quality (ranked using the habitat hectares approach (Parkes et al., 2003).	Critically endangered x 10 Endangered x 5 Vulnerable x 3 Rare x 1 Habitat quality x 10
Scenario 2: Biodiversity maximised, while priority also given to allowing development near existing railway	Efficient biodiversity representation away from railways as implemented via the cost layer which was scaled by proximity to rail. Biodiversity as per scenario 1.	Biodiversity layers weighted as per scenario 1. Equal weighting given to proximity to railway
Scenario 3: Biodiversity maximised, while priority also given to development near existing railway, and away from flood prone areas	Efficient biodiversity representation away from railways and flood-prone areas. Biodiversity as per scenario 1. Proximity to railway as per scenario 2. Areas with highest risk of 1 in 100 year flood ranked lowest.	Biodiversity layers weighted as per scenario 1 Proximity to railway and flood risk weighted equally
Scenario 4: Same as scenario 3	Same as scenario 3	Same as scenario 3, with five times greater weighting given to proximity to railway
Scenario 5: Areas current used as market gardens made available for development	Same as scenario 1	Same as scenario 1

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Figure 9 Plots of proportion of the landscape lost against the minimum proportion of habitat available to any of the species modelled. These figures describe how robust any given level of cell removal is to the species that suffer the greatest (proportional) loss of habitat.

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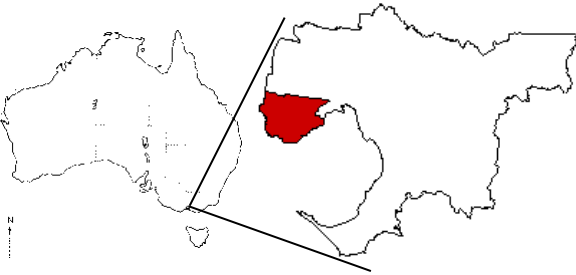


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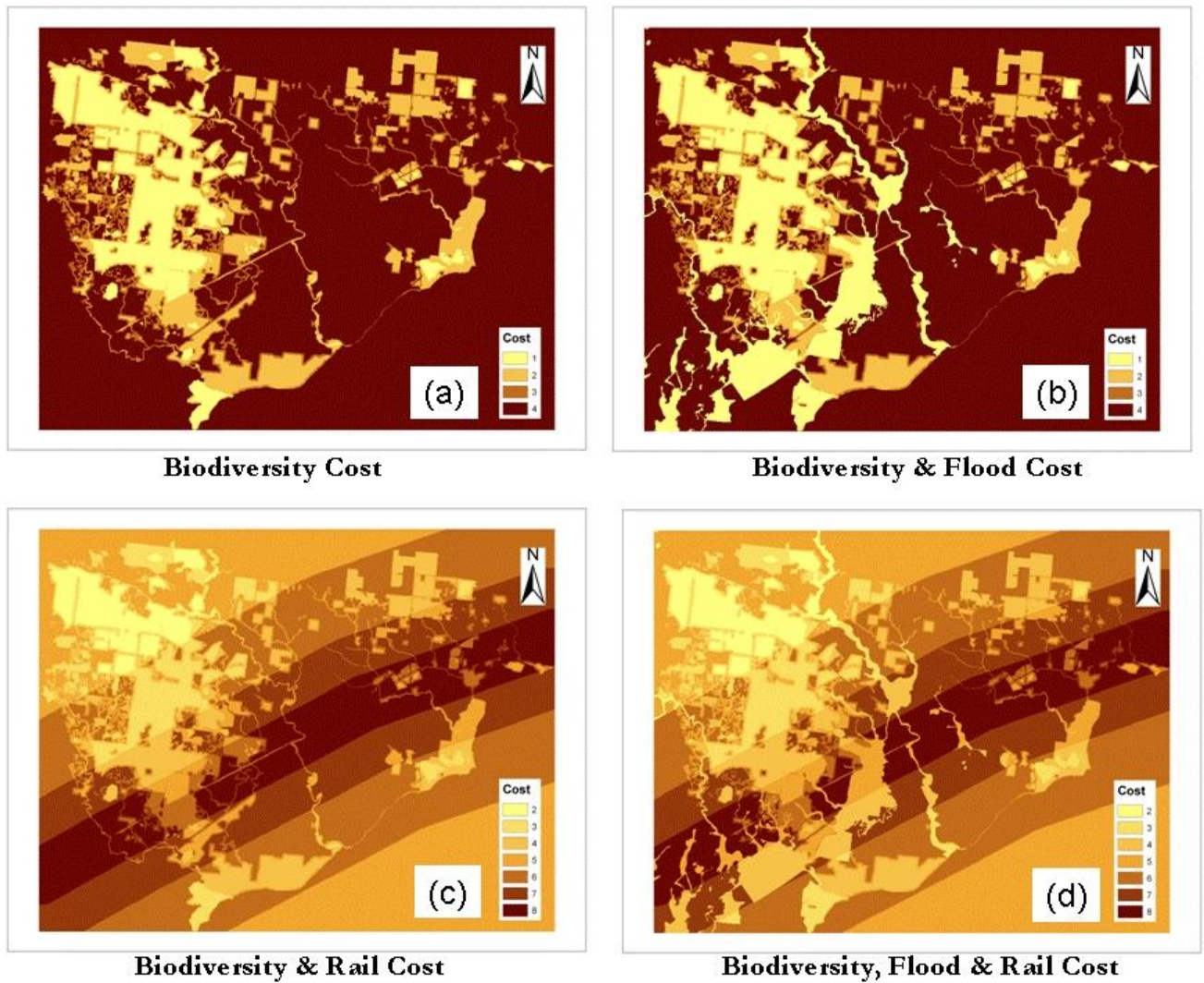


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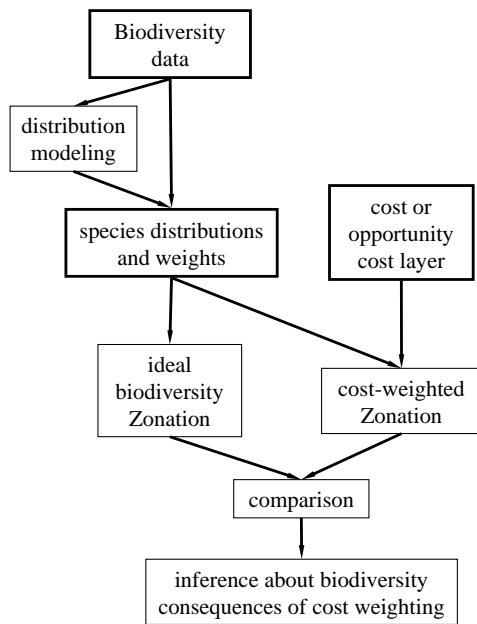


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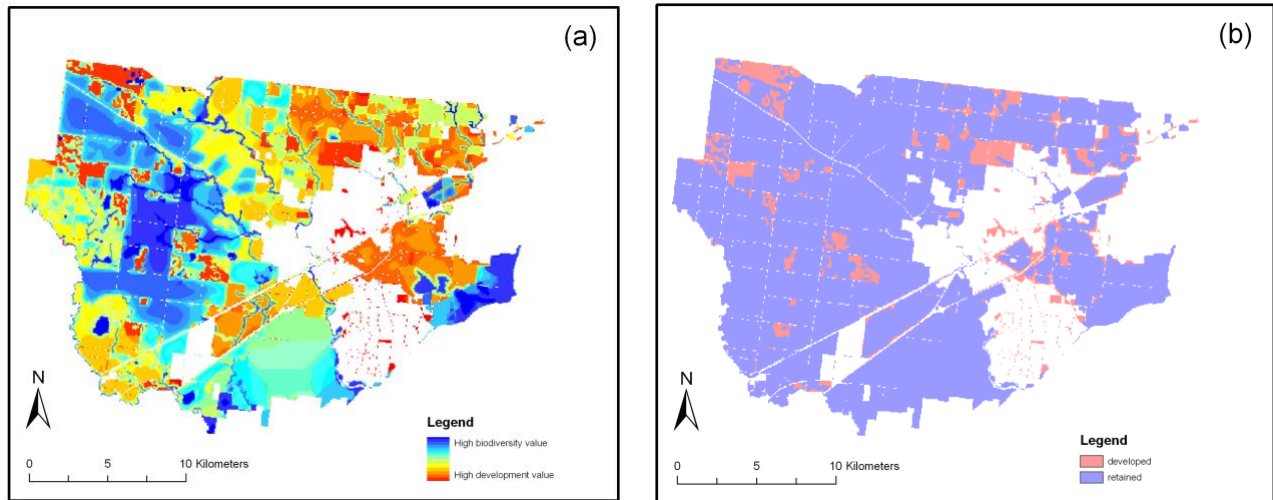


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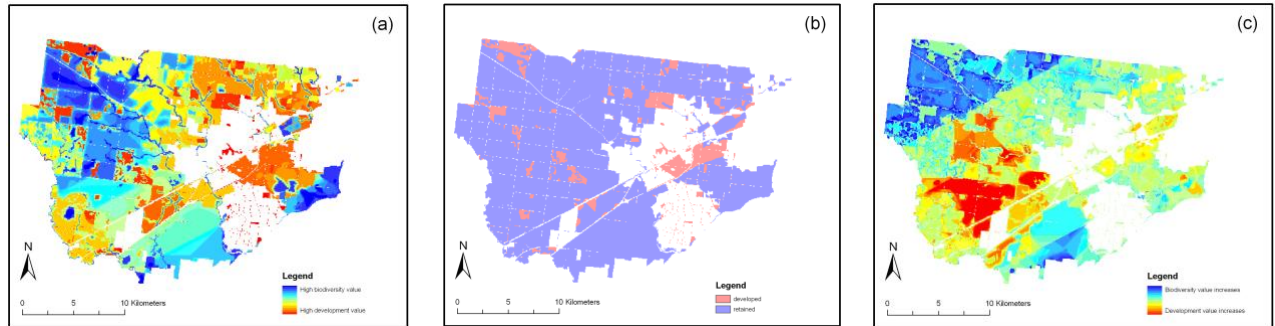


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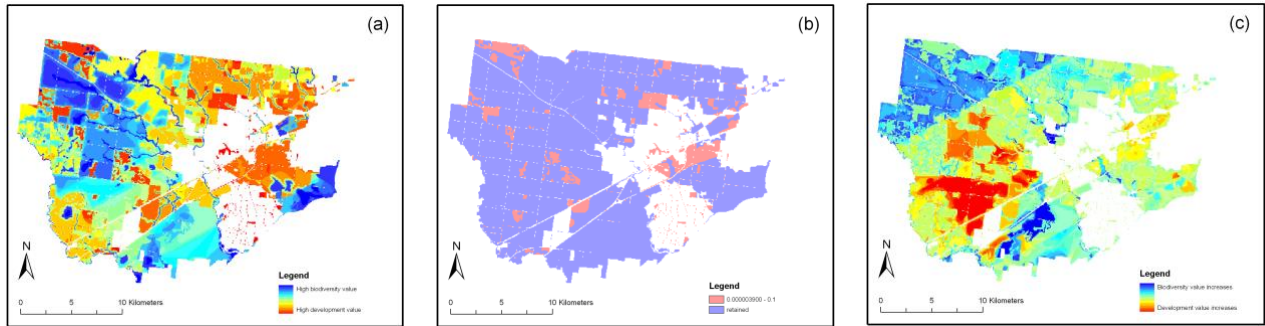


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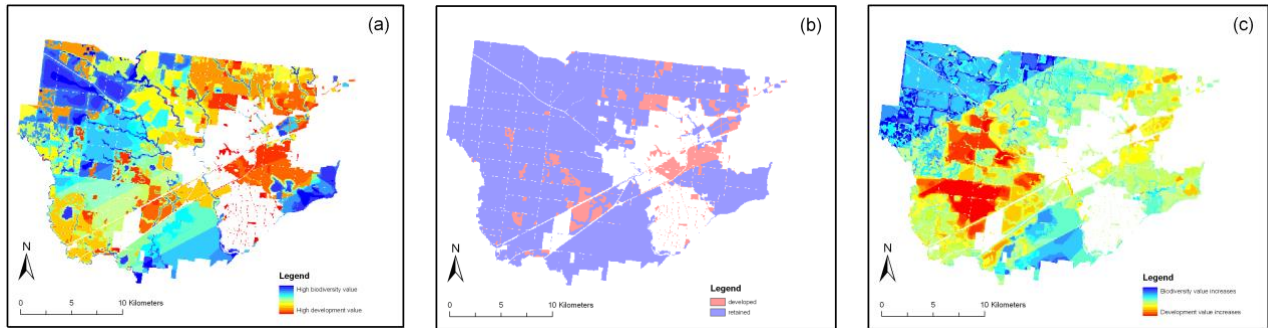


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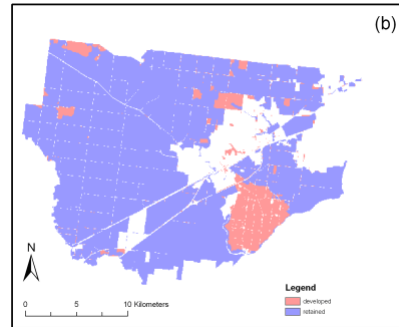
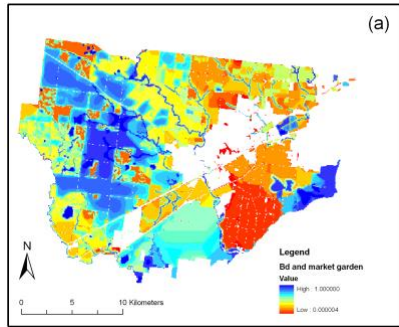


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