**Abstract** – This paper presents a new type of thermally actuated switch for wireless communication system operated at low gigahertz frequencies. The switch is driven by a metal electrothermal actuator, which can generate large displacement and high contact force at lower temperatures. The MEMS switch utilizing the parallel four-beam actuator requires driving voltage of 0.07 V for an 8 μm displacement. RF performances are improved by suspending the structure 25 μm from the substrate using MetalMumps process. An ON state insertion loss of -0.27 dB at 10 GHz and an OFF state isolation of -40 dB at 10 GHz are achieved on low resistivity silicon substrate.

**Keywords** – Electrothermal actuator, low resistivity substrate, RF MEMS switch, low driving voltage, MetalMumps

I. INTRODUCTION

Wireless communication technology is rapidly growing around the world and this trend is likely to continue for the growth of emerging consumer, microwave and millimetre wave circuits and systems also. However, some off-chip bulky passive elements such as varactor or PIN diodes, inductors, quartz crystals, and SAW filters, have become limiting for the chip scaling down [1]. Hence, RF MEMS featuring small size, low weight and high performance can be considered a future enabling technology to replace these off-chip passive elements [2].

In previous work, PIN diodes were used for the RF switching of an antenna arrays for the purpose of beam steering. However, PIN diodes have lower Q at high frequencies and therefore high insertion loss. Compared with the PIN diodes, MEMS switches offer higher Q at high frequencies, low insertion loss, higher isolation and smaller packaging size. Also the idea of System on Chip (SOC) becomes more realistic on the communication system due to compatibility of MEMS switch with the IC process. Hence, the integration of MEMS switches into RF subsystems is expected to provide benefits.

In the past, various actuation approaches have been demonstrated utilizing various operation principles such as electrothermal actuation, the electrostatic actuation, the piezoelectric actuation, and the electromagnetic actuation. Among all of these processes, electrostatic and electrothermal actuators are most attractive. The electrostatic actuators offers low power dissipation and high driving frequency, but suffers from less functional robustness, high actuation voltage and small range of controllable displacement. In contrast, the electrothermal actuators have capability in generating relatively large actuation displacement and force, but a relatively high power consumption as compared with the electrostatic actuators. Therefore, the actuation method should be selected according to the application requirements of the switches [3].

Here, we propose a thermally actuated RF latching switch that is used to replace PIN Diodes, which were used for switching the beam of a patch antenna with thirteen hexagonal element (PATHIE) array operating at frequency range of 2.4 -5.8 GHz as illustrate in Fig 1.

![Layout of patch antenna with thirteen hexagonal elements](image-url)
Fig. 1. Layout and A typical beam-forming circuit for the single-feed circularly polarized patch antenna array

The proposed RF MEMS switch is optimized by using MetalMumps process [4], a commercially available Multiproject Project Wafer (MPW) service. Through MetalMumps process the substrate loss (a trench 25-μm deep is carved under the device, resulting in a suspended switch) can be reduced substantially. Also, it can provide a good solution for the integration of MEMS with IC. Hence, bring the concept of System on chip (SOC) into reality.

II. DESIGN OF RF MEMS SWITCH

A. Operational Principle

Fig 2 shows the operational principle of thermally actuated MEMS switch. A V-shaped actuator, which is made of pre-curved nickel beams, is employed to provide lateral motion in the wafer plane. This switch adopted a piece of silicon nitride as an isolation layer between the driving structure and contact structure. When voltage is applied on the beam, an electrothermal actuator generates movement due to expansion of its material and allows contact heads to move forward and connect to RF signal lines to turn on the switch, as illustrated in Fig 2(b). On removing the driving voltage, the switch returns back to its original position due to internal restoring force of the beam, as illustrated in Fig 2(a).

B. Actuator Design

Fig. 3. Schematic diagram of the V shape parallel beams thermal driven structure

Thermal actuators are very good candidates for RF MEMS switch as it offers high contact force and low contact resistance with a low actuation voltage. In this work, V-shaped electrothermal actuator beams are chosen for their rectilinear displacement caused by joule heating and their design and flexibilities. The beam is normally designed with careful considerations such that temperature is below 450°C to prevent plastic deformation and surface oxidation [5], higher force is generated to allow better contacts and lower metallic losses, which translate in lower switch insertion loss. Therefore, following equations were kept in mind, while designing structure [6].

\[
d = \left[ l^2 + 2(l)l' - l \cos(\theta) \right]^{1/2} - l \sin(\theta) \quad (1)
\]

\[
F = N \frac{Ew^3l}{4l^5} d \quad (2)
\]

Where

- \( d \) = actuator displacement
- \( l \) = length of the beam
- \( l' \) = elongation of the beam due to thermal
expansion

\[ \theta = \text{prebend angle of the beam} \]

\[ F = \text{applied force} \]

\[ N = \text{Number of actuators} \]

\[ E = \text{Young Modulus} \]

\[ t = \text{beam thickness} \]

\[ w = \text{beam width} \]

The Fig 3 illustrates V shaped actuators in our switch. Clearly, device performances can be improved by changing the structure of the beam. Practically, at a given temperature beam displacement can be increased by increasing the beam length or reducing the bending angle. The actuators exhibit an output force which is directly affected by the thickness and width of the beam [6].

<table>
<thead>
<tr>
<th>TABLE 1</th>
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<tr>
<td>Properties of Polysilicon and Nickel</td>
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</table>

<table>
<thead>
<tr>
<th>Material</th>
<th>( \alpha ) (ppm/k)</th>
<th>( \rho ) (Ωm)</th>
<th>( K ) (W/mK)</th>
<th>( E ) (GPa)</th>
<th>( Q )</th>
</tr>
</thead>
<tbody>
<tr>
<td>Polysilicon</td>
<td>2.5</td>
<td>3.1x10^-5</td>
<td>65</td>
<td>165</td>
<td>2.33x10^-13</td>
</tr>
<tr>
<td>Nickel</td>
<td>12</td>
<td>8x10^-8</td>
<td>91</td>
<td>210</td>
<td>6.28x10^-13</td>
</tr>
</tbody>
</table>

Nickel is chosen for the actuator building material as figure of merit of nickel \( Q = \frac{\alpha^2}{KE} \), where \( \alpha \) is the thermal expansion coefficient, \( k \) is the thermal conductivity, and \( E \) is the Young modulus, is better than polysilicon. Also, thermal expansion coefficient of nickel (see small inset in Table 1) is high compare with polysilicon, therefore exhibit same displacement at a lower temperature [7-8].

The area of proposed microswitch is approximately 1000 μm x 470 μm. Dimension of a single V beam actuator is 1000 μm in length, 10 μm width, 20 μm thickness, 10 μm offset at the centre, and 1.05° prebending angle respectively. The RF signal lines are separated from the contact head by 8 μm and contact area is designed to be 70 μm X 20 μm.

### III. FABRICATION

The device is optimized on a low resistivity substrate (1-2 Ω-cm) using MetalMumps technology, a recent commercially available multi project wafer process and simulated in virtual clean room simulation module (Visualize in Fabviewer) in Intellisuite software. The design process includes a 2 μm thick isolation layer on starting silicon wafer [Fig 4 (a)]. This is followed by the deposition of a 0.5 μm thick sacrificial layer (oxide 1) defining the area where the trench under the device will be patterned at the end of the process [see Fig 4 (b)]. Afterwards, two sequential silicon-nitride layers (nitride 1 + nitride 2) are deposited and patterned [see Fig 4 (c)] forming structural connection as well as electrical and thermal isolations between actuator and RF signal lines. Then, access pads are defined in a second sacrificial layer [see Fig 4 (d)]. The wafer is patterned with 20 μm thick structural nickel layer into the patterned resist stencil [see Fig 4 (e)]. After electroplating, gold layer is electroplated [see Fig 4 (f)]. Finally, KOH solution is used to form a 25 μm deep trench in the silicon substrate [see Fig 4 (g)].
IV. SIMULATION RESULTS

The structure was simulated using Intellisuite software. The ends of the beams were fixed and the boundary was set at the temperature of 25°C at the end of the beams. When voltage is applied at the end of the beams, current flow through the beams and generates heat. Hence, actuators generate movement due to expansion of its material. Fig 5 and Fig 6 shows the measured static displacement and maximum temperature as a function of driving voltage for an electroplated Ni parallel four-beam actuator. It indicates that the displacement and temperature increased with the driving voltage as expected. For an 8 µm maximum displacement a dc bias voltage of 0.07 V and 55°C maximum temperature (In Fig 6 the circle shows the point at which the contact occurs) are required.

Fig. 7 indicates measured contact force. Under a 0.1 V driving voltage, the actuator provide a contact force of approximate 3.3 mN, which is directly applied on micro switches to provide stable contacts.

Fig 8-11 illustrates S parameter results for the on and off state for RF MEMS switch in the frequency range of 1GHz to 10 GHz using COMSOL Multiphysics. The plot shows that micro switch on the low resistivity substrate has an isolation of about -70 dB at 1 GHz and about -40 dB at 10
GHz. Higher contact force provides low RF insertion loss thus insertion loss of about -0.27 dB at 10 GHz is obtained for the same switch. Also, switch shows good return loss at the frequency range of 1GHz to 5 GHz. The measured RF results confirm the approach to suspending the structures on a low resistivity substrate to obtain high performances of switch at low gigahertz frequencies.

V. CONCLUSION

An electrothermally actuated lateral contact microswitch for RF applications is designed on a low resistivity silicon substrate using MetalMumps process. Electrothermal actuation is used as the driving principle as it provides higher contact force thus lower insertion loss. Measured insertion loss and isolation are -0.27 dB and -40 dB at 10 GHz respectively. The return loss of the switch is also better than -20 dB at frequency range of 1GHz to 5 GHz. It is verified that RF performances can be improved by suspending the switch 25 μm above the substrate. This technique would possibly allow the switch to be integrated with active circuitry manufactured on a low resistivity substrate in a system on chip concept, while sustaining good RF performances. It is expected that the proposed MEMS switches will provide good performances compared with PIN diodes.

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