

Efficient Trajectory Options Allocation for the Collaborative Trajectory Options Program

Presenter: O. Rodionova

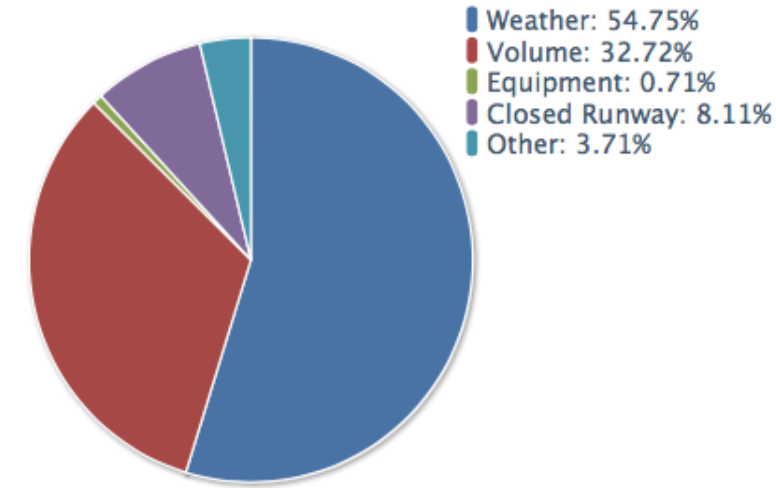
Co-authors: A. Evans, H. Arneson, and B. Sridhar

DASC 2017

September 19th

Traffic Flow Management (TFM)

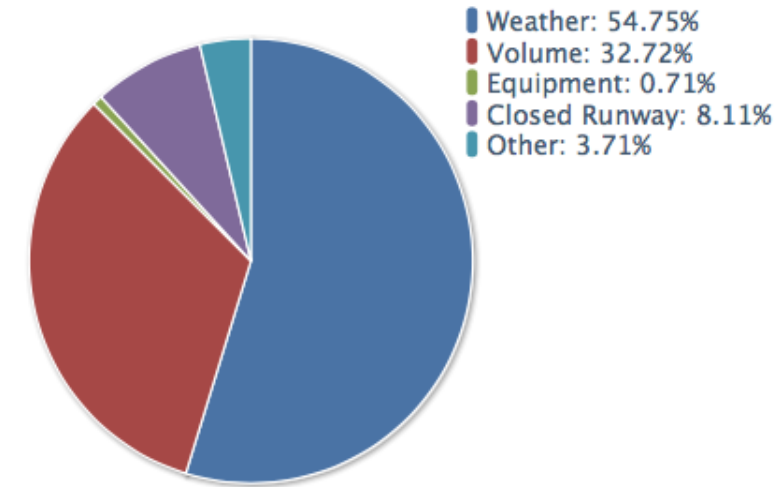
- Main function: balancing demand and capacity
- Severe (convective) weather:
 - Reduces the airspace capacity
 - Major cause of disruptions and delays in the National Airspace System (NAS)



Bureau of Transportation Statistics: Causes of National Aviation System Delays. May, 2012 – May, 2017

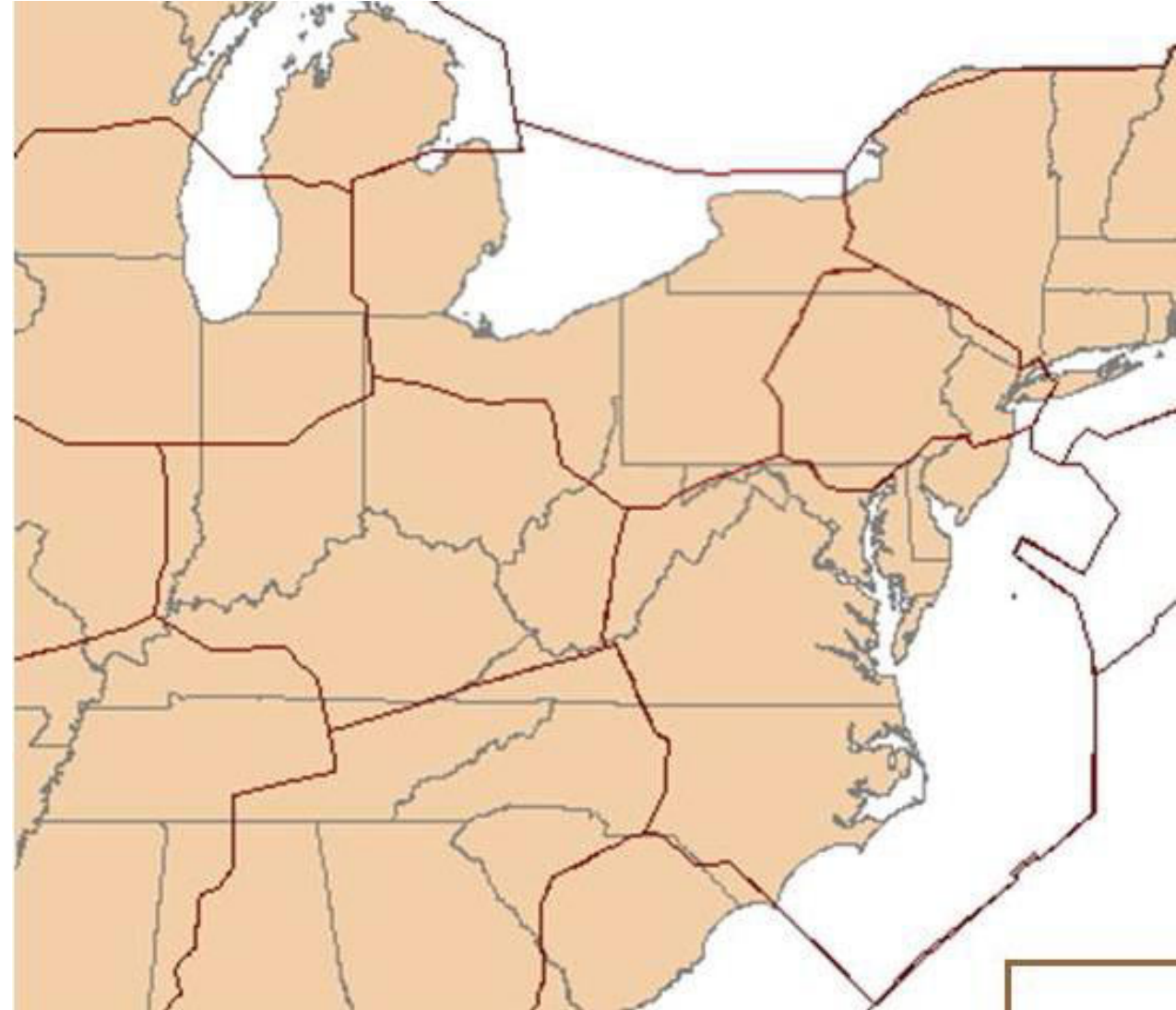
Traffic Flow Management (TFM)

- Main function: balancing demand and capacity
- Severe (convective) weather:
 - Reduces the airspace capacity
 - Major cause of disruptions and delays in the National Airspace System (NAS)
- Traffic Management Initiatives (TMIs):
 - Ground Delay Program (GDP)
 - Airspace Flow Program (AFP)
 - Collaborative Trajectory Options Program (CTOP)



Bureau of Transportation Statistics: Causes of National Airspace System Delays. May, 2012 – May, 2017

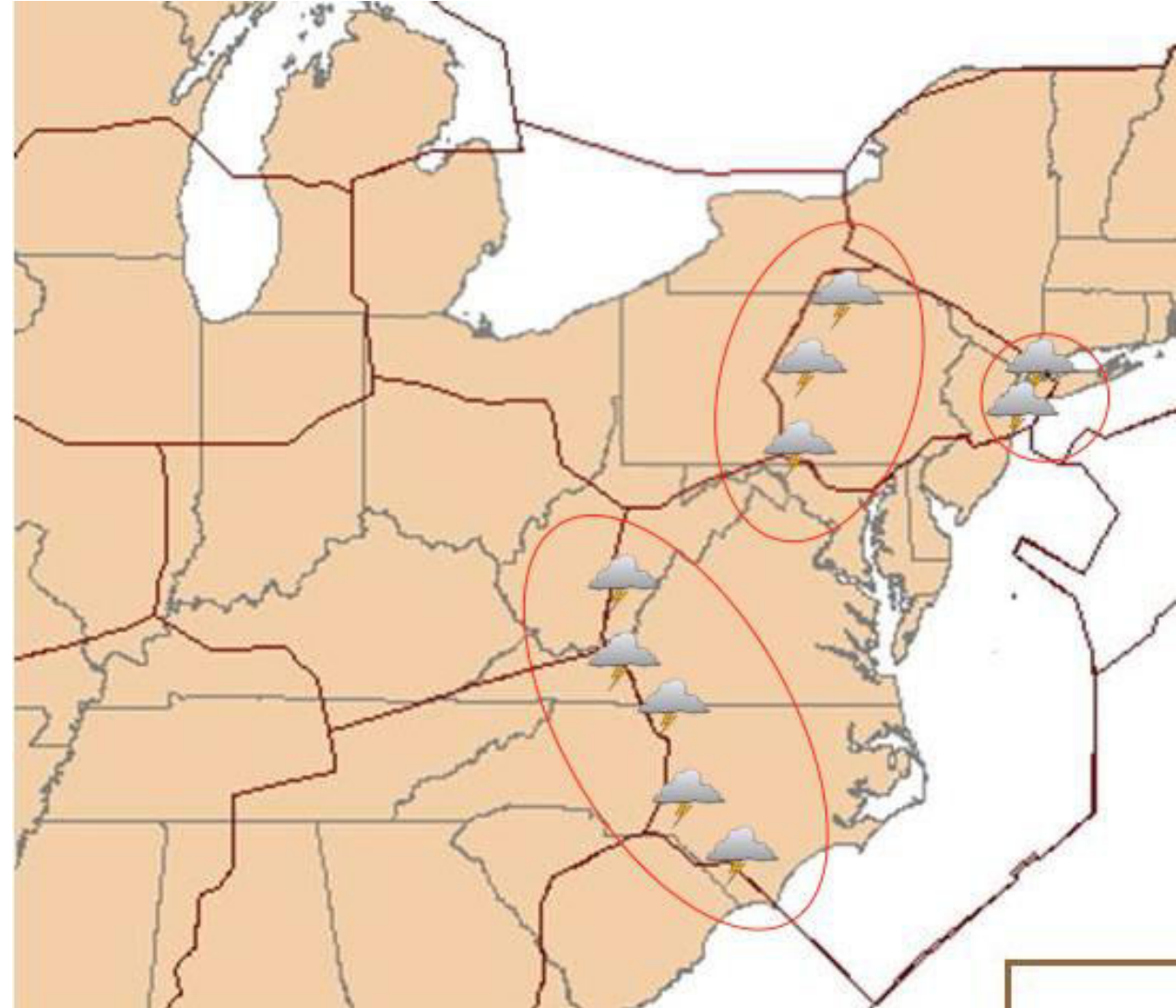
Collaborative Trajectory Options Program (CTOP)



Collaborative Trajectory Options Program (CTOP)

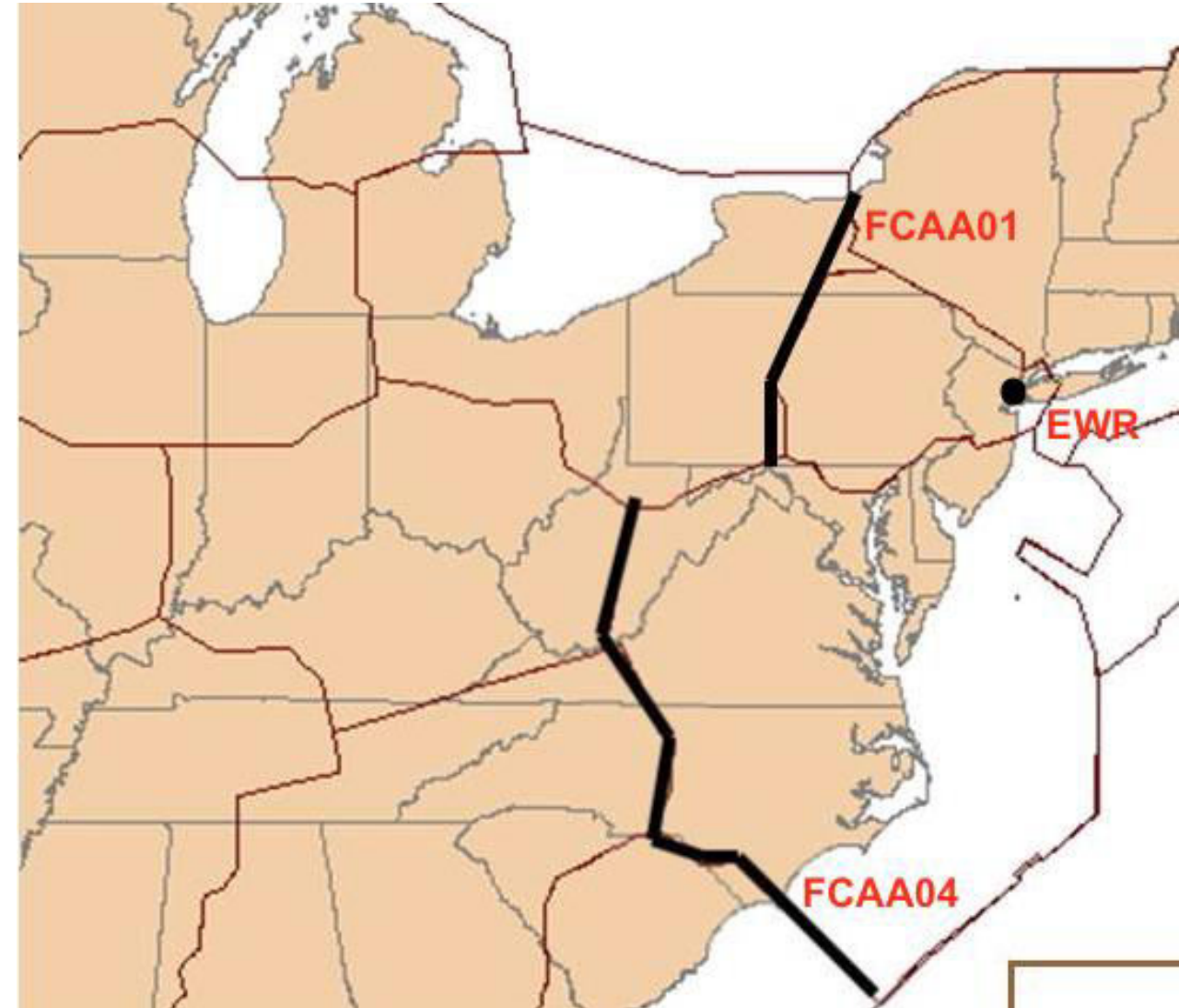
1. TFM identifies areas with reduced capacities

- Weather forecast
- Demand



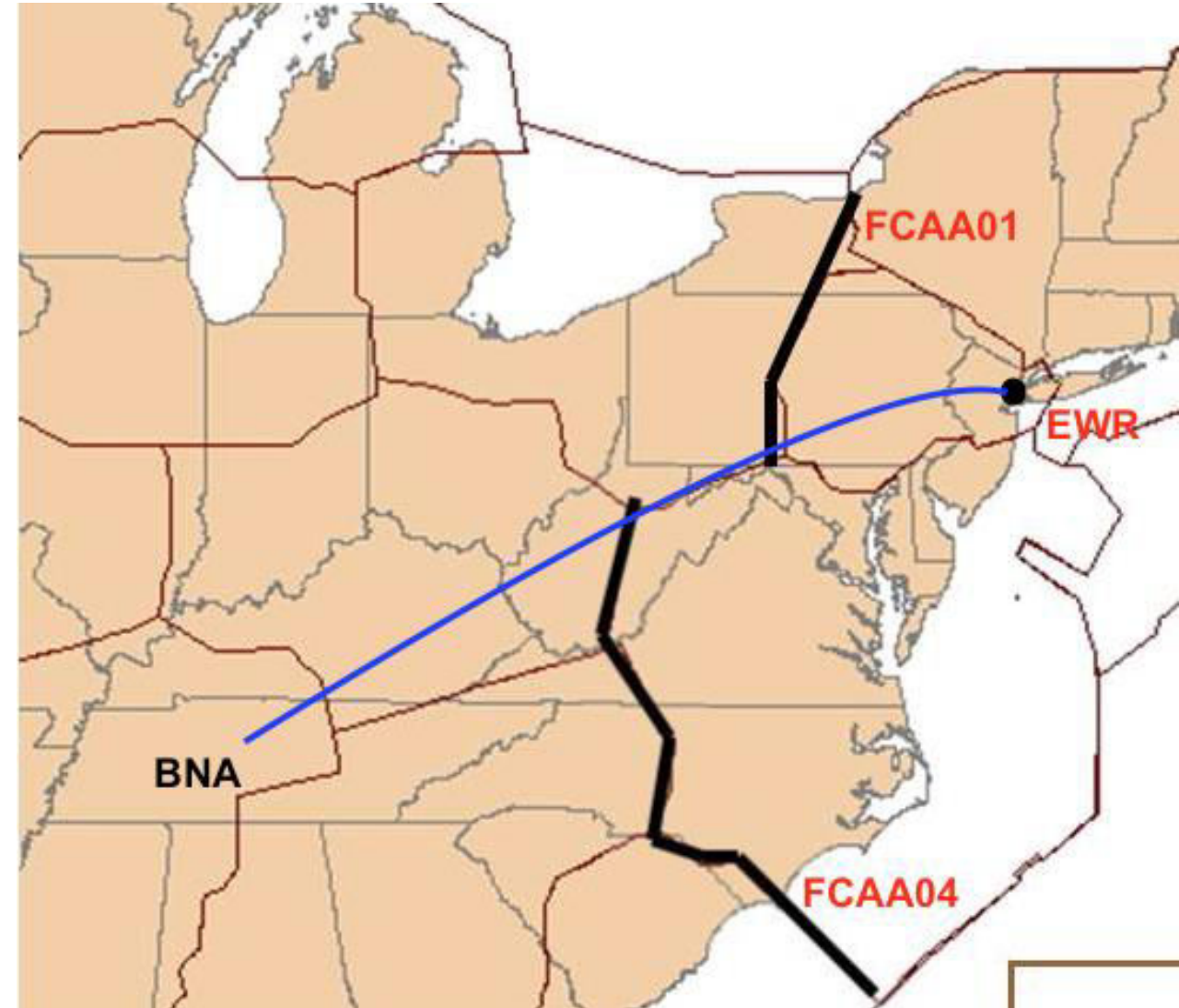
Collaborative Trajectory Options Program (CTOP)

1. TFM identifies areas with reduced capacities
 - Weather forecast
 - Demand
2. TFM sets Flow Constrained Areas (FCAs)
 - Position
 - Start and end times
 - Capacity



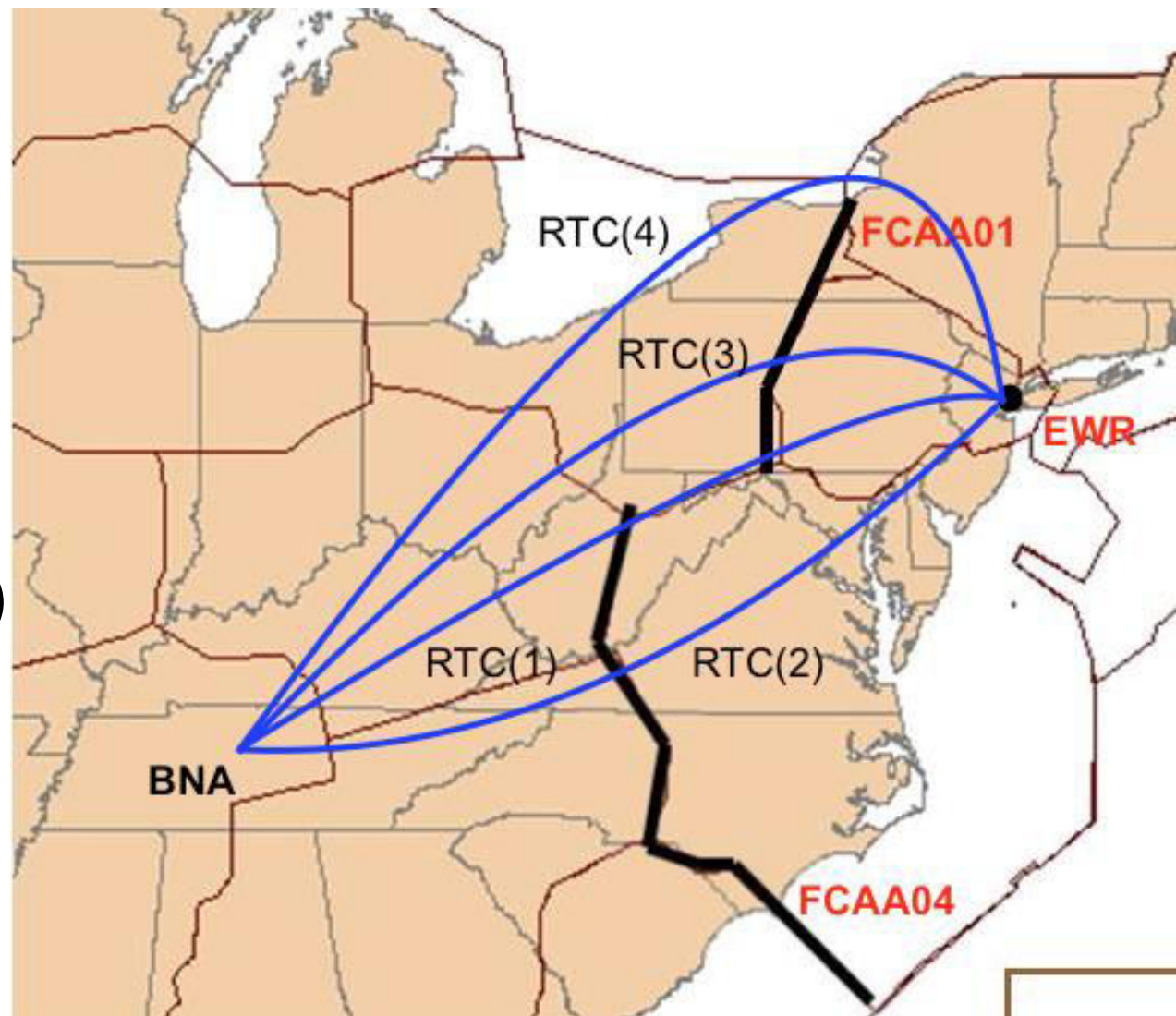
Collaborative Trajectory Options Program (CTOP)

1. TFM identifies areas with reduced capacities
 - Weather forecast
 - Demand
2. TFM sets Flow Constrained Areas (FCAs)
 - Position
 - Start and end times
 - Capacity
3. TFM identifies affected flights
 - Exempted flights
 - Non-exempted flights



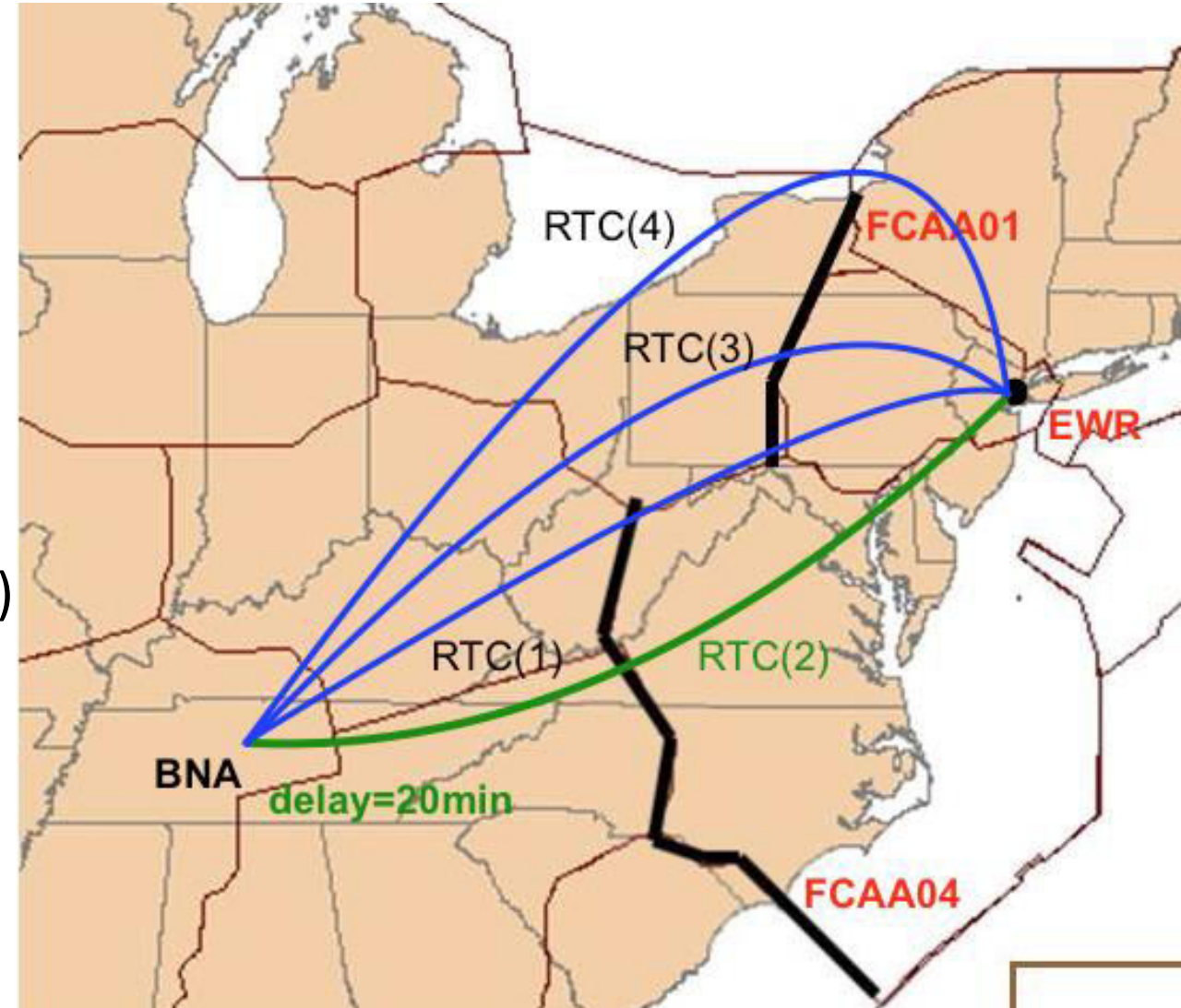
Collaborative Trajectory Options Program (CTOP)

1. TFM identifies areas with reduced capacities
 - Weather forecast
 - Demand
2. TFM sets Flow Constrained Areas (FCAs)
 - Position
 - Start and end times
 - Capacity
3. TFM identifies affected flights
 - Exempted flights
 - Non-exempted flights
4. Airlines submit Trajectory Options Sets (TOSs)
 - Relative Trajectory Cost (RTC) for each option



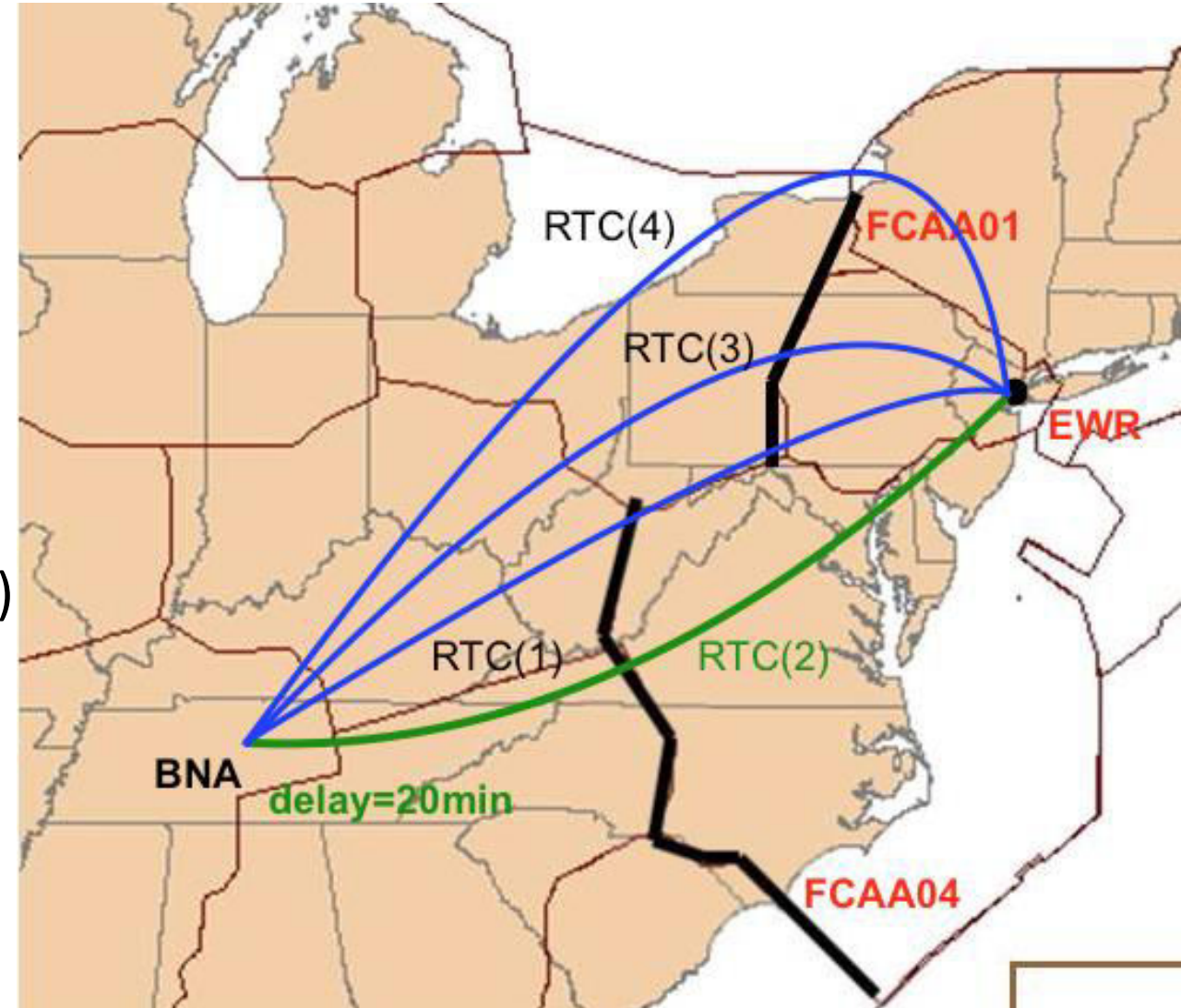
Collaborative Trajectory Options Program (CTOP)

1. TFM identifies areas with reduced capacities
 - Weather forecast
 - Demand
2. TFM sets Flow Constrained Areas (FCAs)
 - Position
 - Start and end times
 - Capacity
3. TFM identifies affected flights
 - Exempted flights
 - Non-exempted flights
4. Airlines submit Trajectory Options Sets (TOSs)
 - Relative Trajectory Cost (RTC) for each option
5. TFM schedules flights satisfying FCA capacity
 - Assign routes from TOSs
 - Assign ground delays (transform into EDCTs)



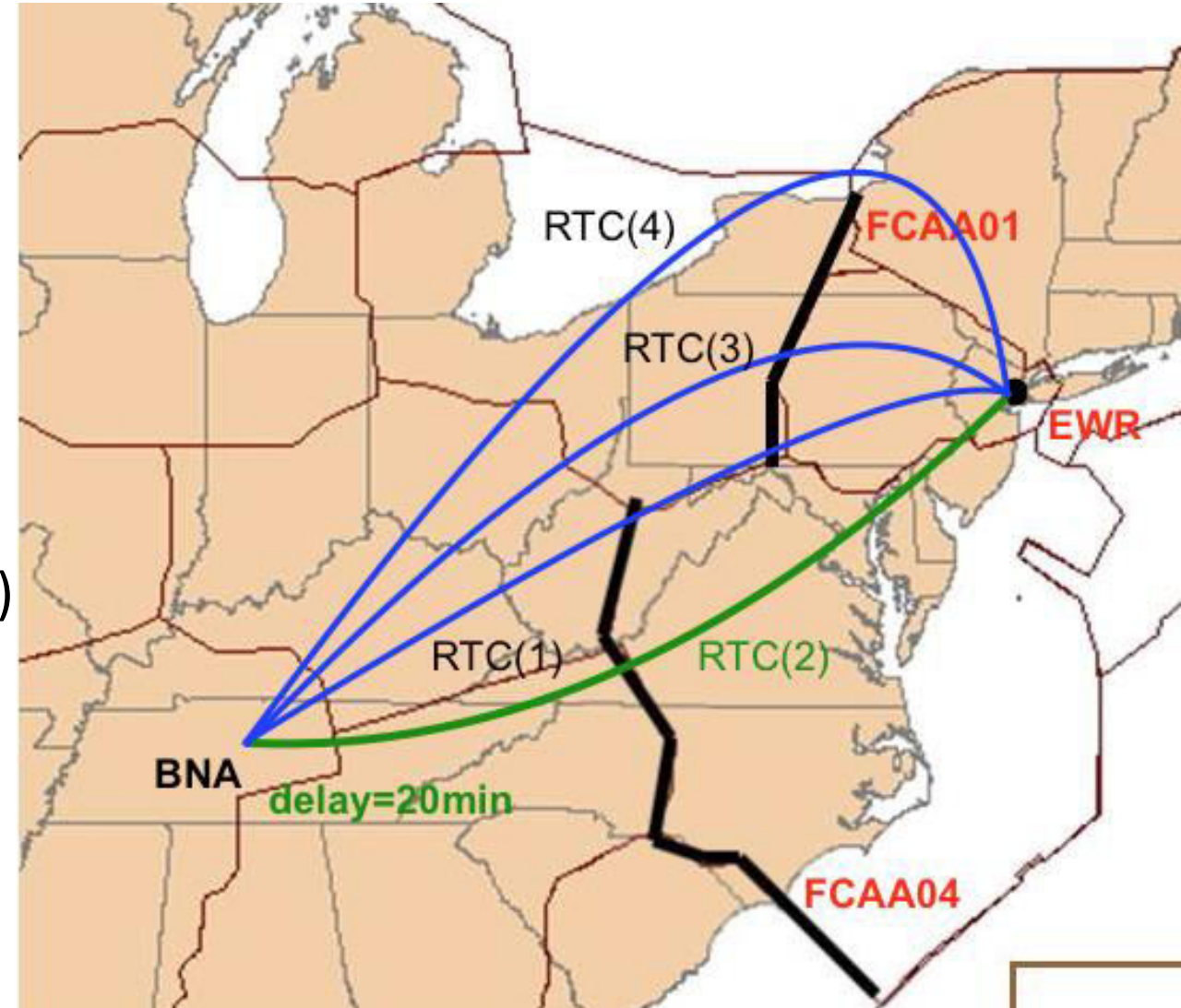
Collaborative Trajectory Options Program (CTOP)

1. TFM identifies areas with reduced capacities
 - Weather forecast
 - Demand
2. TFM sets Flow Constrained Areas (FCAs)
 - Position
 - Start and end times
 - Capacity
3. TFM identifies affected flights
 - Exempted flights
 - Non-exempted flights
4. Airlines submit Trajectory Options Sets (TOSs)
 - Relative Trajectory Cost (RTC) for each option
5. TFM schedules flights satisfying FCA capacity
 - Assign routes from TOSs
 - Assign ground delays (transform into EDCTs)
6. Schedule is adjusted
 - Airlines perform cancellations and substitutions
 - TFM runs compression



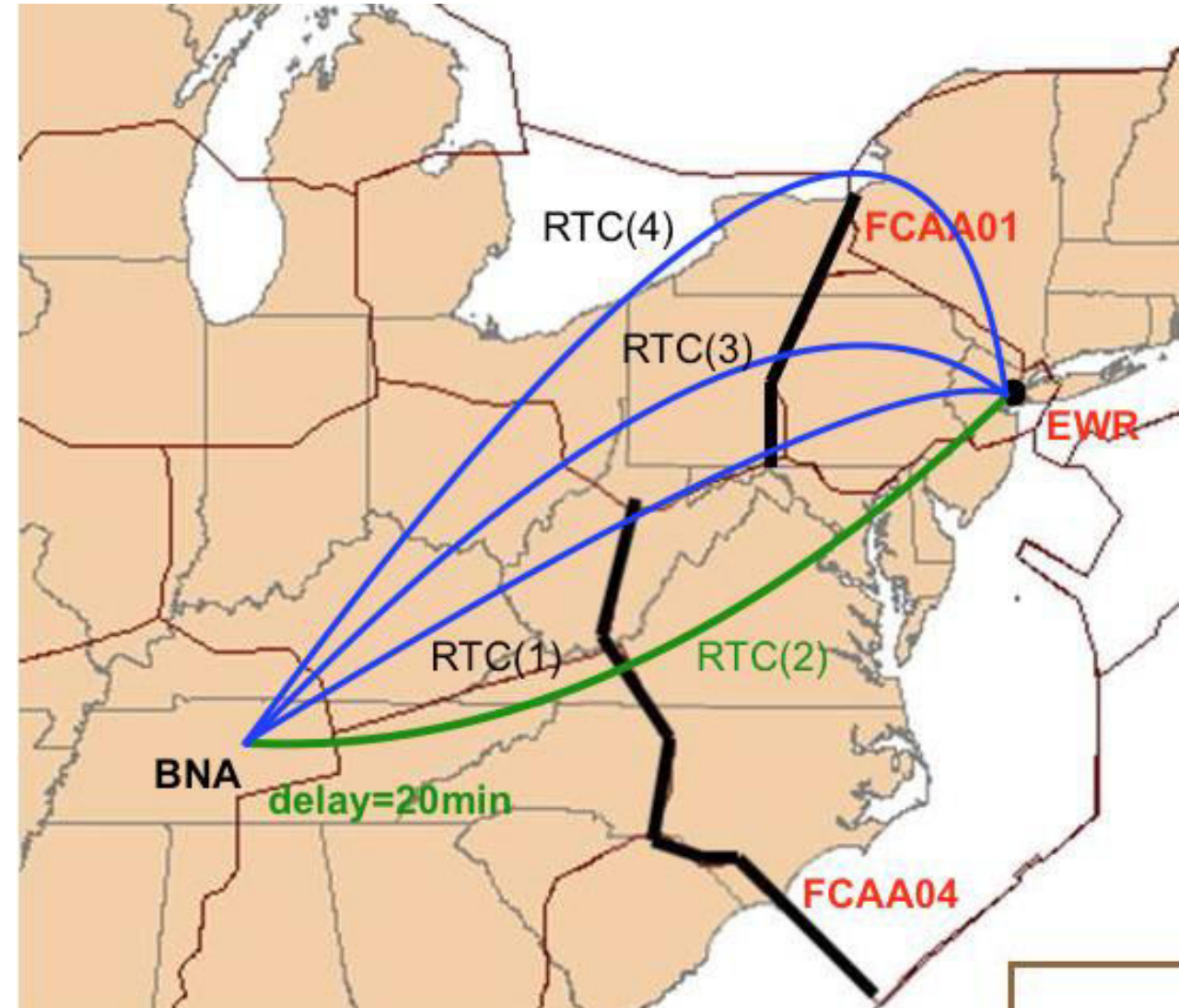
Collaborative Trajectory Options Program (CTOP)

1. TFM identifies areas with reduced capacities
 - Weather forecast
 - Demand
2. TFM sets Flow Constrained Areas (FCAs)
 - Position
 - Start and end times
 - Capacity
3. TFM identifies affected flights
 - Exempted flights
 - Non-exempted flights
4. Airlines submit Trajectory Options Sets (TOSs)
 - Relative Trajectory Cost (RTC) for each option
5. TFM schedules flights satisfying FCA capacity
 - Assign routes from TOSs
 - Assign ground delays (transform into EDCTs)
6. Schedule is adjusted
 - Airlines perform cancellations and substitutions
 - TFM runs compression



Problem statement

- Given
 - Flow Constrained Areas (FCAs)
 - Airline Trajectory Option Sets (TOSs)
- For each flight, assign
 - Route from Trajectory Option Set (TOS)
 - Ground delay
- Subject to
 - Flow Constrained Area (FCA) capacity constraints



Comparison to current approach

- Current approach
 - Based on First Come First Served principle
(perceived as equitable by airlines)
 - Consecutive FCAs not supported
 - Airborne delays not accounted for

Comparison to current approach

- Current approach
 - Based on First Come First Served principle
(perceived as equitable by airlines)
 - Consecutive FCAs not supported
 - Airborne delays not accounted for
- Proposed approach
 - Global optimization
 - Constraints at multiple FCAs satisfied simultaneously
 - Airborne delay accounted for
 - Equity metric in optimization

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms
FCA capacities		

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms
<p data-bbox="191 368 606 429">FCA capacities</p> <p data-bbox="191 534 851 595">Space-based allocation</p> <ul data-bbox="191 618 835 1168" style="list-style-type: none"><li data-bbox="191 618 738 839">• Minimum time spacing between flights<li data-bbox="191 862 588 1001">• Even flight distribution<li data-bbox="191 1023 835 1168">• Suited for stochastic optimization		

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms
FCA capacities Space-based allocation <ul style="list-style-type: none">• Minimum time spacing between flights• Even flight distribution• Suited for stochastic optimization	System efficiency => Equity =>	

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms
<p>FCA capacities</p> <p>Space-based allocation</p> <ul style="list-style-type: none">• Minimum time spacing between flights• Even flight distribution• Suited for stochastic optimization	<p>System efficiency =></p> <p>Total system cost</p> <ul style="list-style-type: none">• Ground delays• Airborne delays• Relative Trajectory Cost (RTC) <p>Equity =></p>	

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms
<p>FCA capacities</p> <p>Space-based allocation</p> <ul style="list-style-type: none">• Minimum time spacing between flights• Even flight distribution• Suited for stochastic optimization	<p>System efficiency =></p> <p>Total system cost</p> <ul style="list-style-type: none">• Ground delays• Airborne delays• Relative Trajectory Cost (RTC) <p>Equity =></p> <p>Max-Min Fairness Scheme</p> <ul style="list-style-type: none">• Maximum average airline cost	

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms
<p>FCA capacities</p> <p>Space-based allocation</p> <ul style="list-style-type: none">• Minimum time spacing between flights• Even flight distribution• Suited for stochastic optimization	<p>System efficiency =></p> <p>Total system cost</p> <ul style="list-style-type: none">• Ground delays• Airborne delays• Relative Trajectory Cost (RTC) <p>Equity =></p> <p>Max-Min Fairness Scheme</p> <ul style="list-style-type: none">• Maximum average airline cost	<p>Flight priority order</p> <ul style="list-style-type: none">• Ration-by-Schedule (RBS) principle

Resource allocation problem: overview

Resources	Performance metrics	Allocation algorithms
FCA capacities Space-based allocation <ul style="list-style-type: none">• Minimum time spacing between flights• Even flight distribution• Suited for stochastic optimization	System efficiency => Total system cost <ul style="list-style-type: none">• Ground delays• Airborne delays• Relative Trajectory Cost (RTC) Equity => Max-Min Fairness Scheme <ul style="list-style-type: none">• Maximum average airline cost	Flight priority order <ul style="list-style-type: none">• Ration-by-Schedule (RBS) principle Global optimization <ul style="list-style-type: none">• Minimize the total system cost, and• Maximum average airline cost simultaneously

Ration-by-Schedule (RBS)

Ration-by-Schedule (RBS)

- For each flight, calculate its Initial Arrival Time (IAT)
 - For each route option from TOS, calculate the Estimated Arrival Time (ETA) at its first (primary) FCA
 - Choose the minimum among these Estimated Arrival Times (ETAs)

Ration-by-Schedule (RBS)

- For each flight, calculate its Initial Arrival Time (IAT)
 - For each route option from TOS, calculate the Estimated Arrival Time (ETA) at its first (primary) FCA
 - Choose the minimum among these Estimated Arrival Times (ETAs)
- Order flights based on their Initial Arrival Times (IATs) in a priority list

Ration-by-Schedule (RBS)

- For each flight, calculate its Initial Arrival Time (IAT)
 - For each route option from TOS, calculate the Estimated Arrival Time (ETA) at its first (primary) FCA
 - Choose the minimum among these Estimated Arrival Times (ETAs)
- Order flights based on their Initial Arrival Times (IATs) in a priority list
- For each flight from the priority list, find the best (minimum-cost) available route and delay allocation

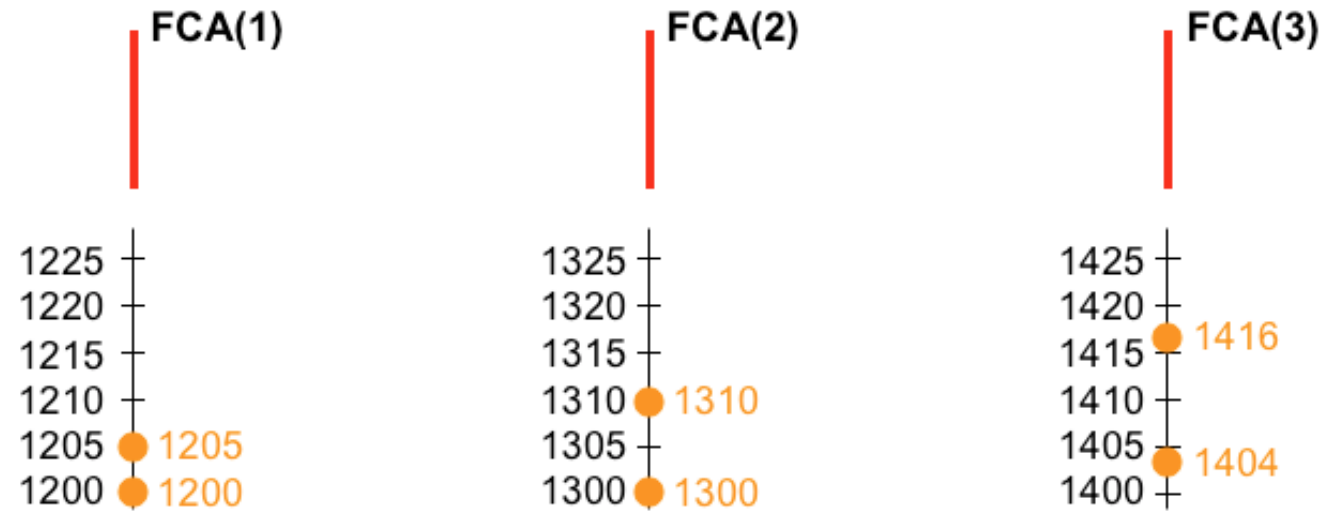
Ration-by-Schedule (RBS)

- For each flight, calculate its Initial Arrival Time (IAT)
 - For each route option from TOS, calculate the Estimated Arrival Time (ETA) at its first (primary) FCA
 - Choose the minimum among these Estimated Arrival Times (ETAs)
- Order flights based on their Initial Arrival Times (IATs) in a priority list
- For each flight from the priority list, find the best (minimum-cost) available route and delay allocation
 - For each route option from TOS, find the best available arrival time at the first (primary) FCA satisfying the spacing constraints at this FCA
 - Calculate the total cost (RTC + ground delay) for each option

Ration-by-Schedule (RBS)

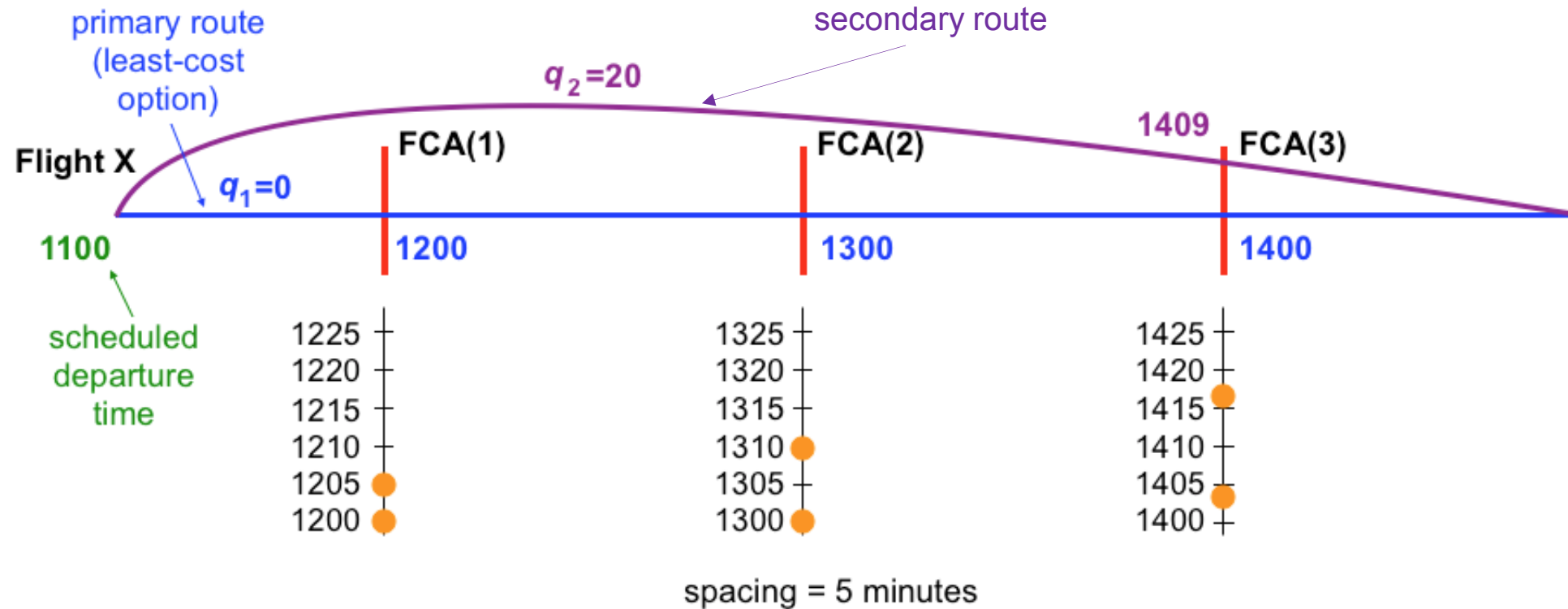
- For each flight, calculate its Initial Arrival Time (IAT)
 - For each route option from TOS, calculate the Estimated Arrival Time (ETA) at its first (primary) FCA
 - Choose the minimum among these Estimated Arrival Times (ETAs)
- Order flights based on their Initial Arrival Times (IATs) in a priority list
- For each flight from the priority list, find the best (minimum-cost) available route and delay allocation
 - For each route option from TOS, find the best available arrival time at the first (primary) FCA satisfying the spacing constraints at this FCA
 - Calculate the total cost (RTC + ground delay) for each option
 - Choose the option with the least total cost
 - Assign the selected route and the associated delay to flight

RBS scheduling example



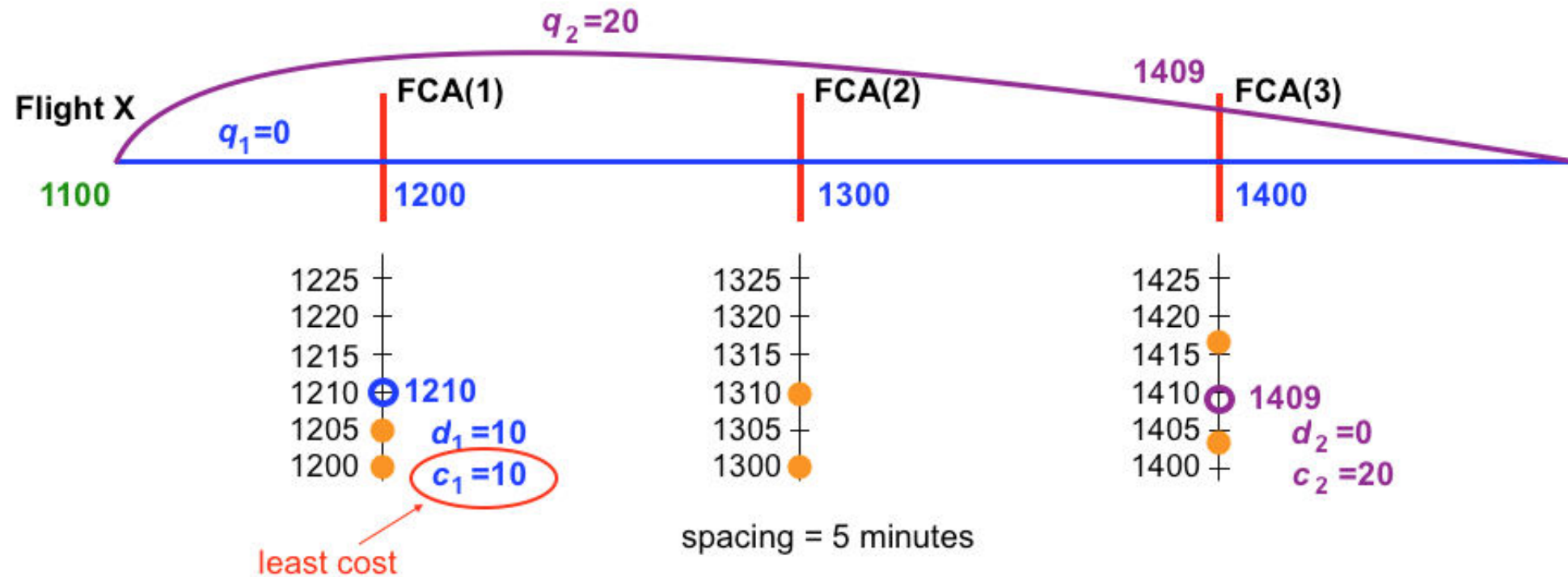
spacing = 5 minutes

RBS scheduling example



q_j Relative Trajectory Cost (RTC) of route j

RBS scheduling example

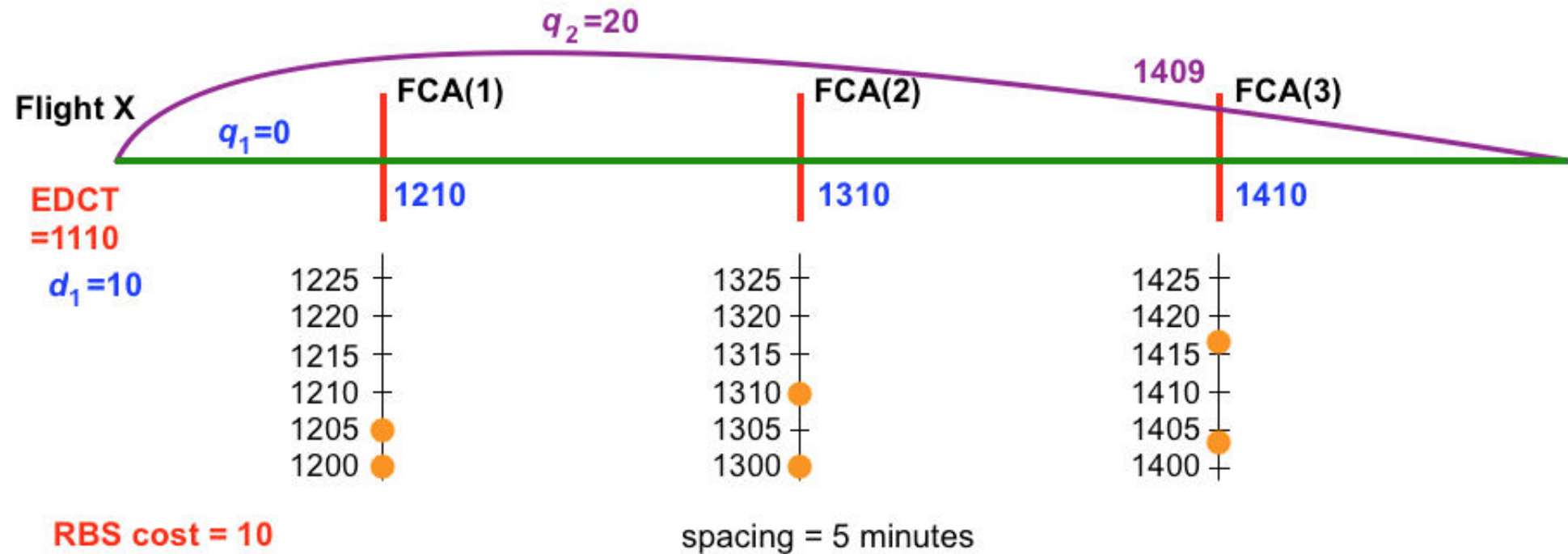


q_j Relative Trajectory Cost (RTC) of route j

c_j Total cost of route option j

d_j Ground delay on route j

RBS scheduling example

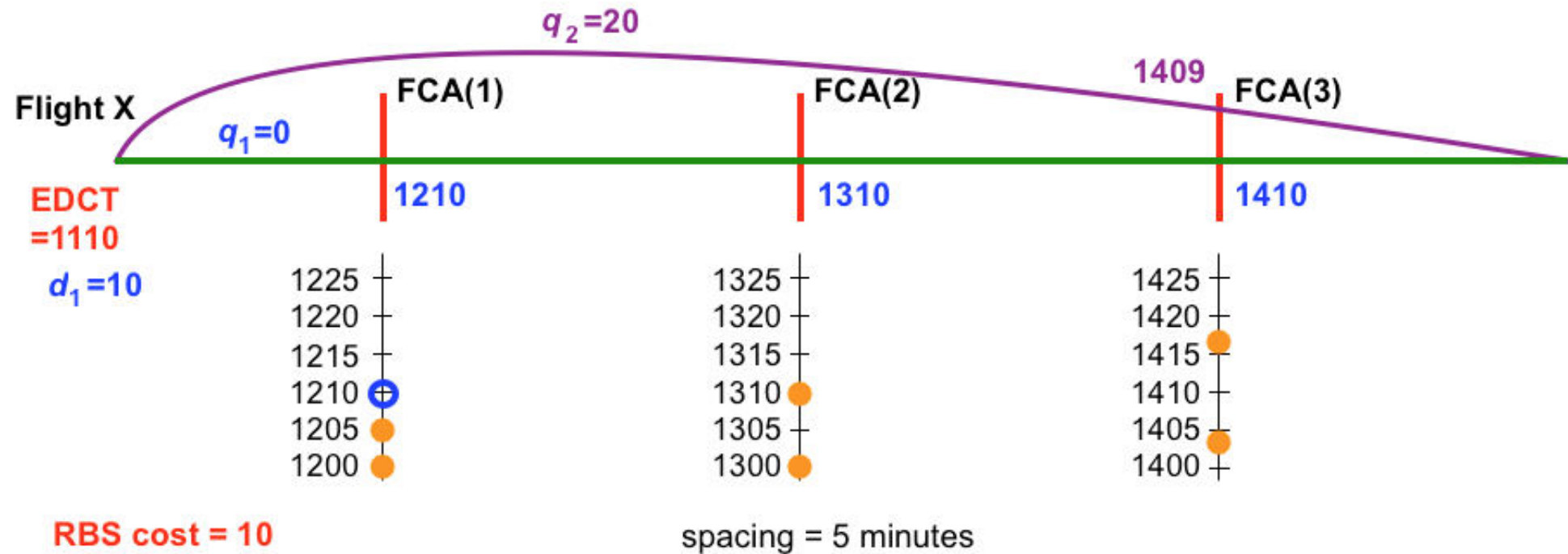


q_j Relative Trajectory Cost (RTC) of route j

c_j Total cost of route option j

d_j Ground delay on route j

RBS scheduling example

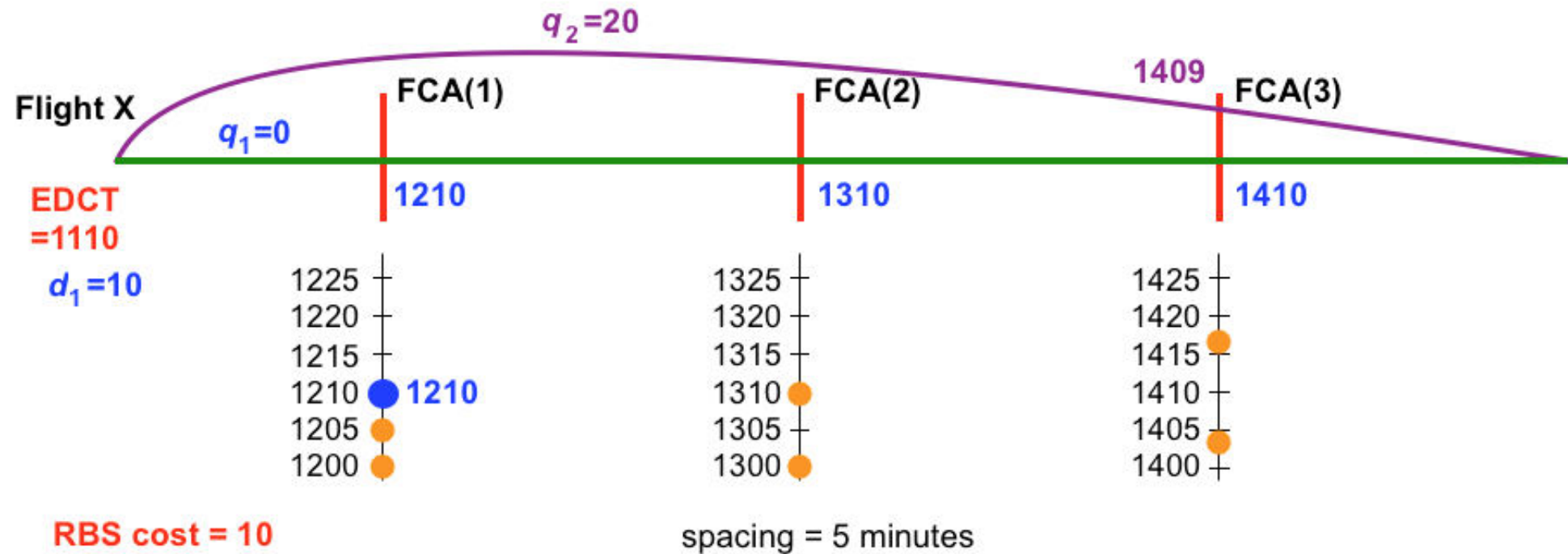


q_j Relative Trajectory Cost (RTC) of route j

c_j Total cost of route option j

d_j Ground delay on route j

RBS scheduling example

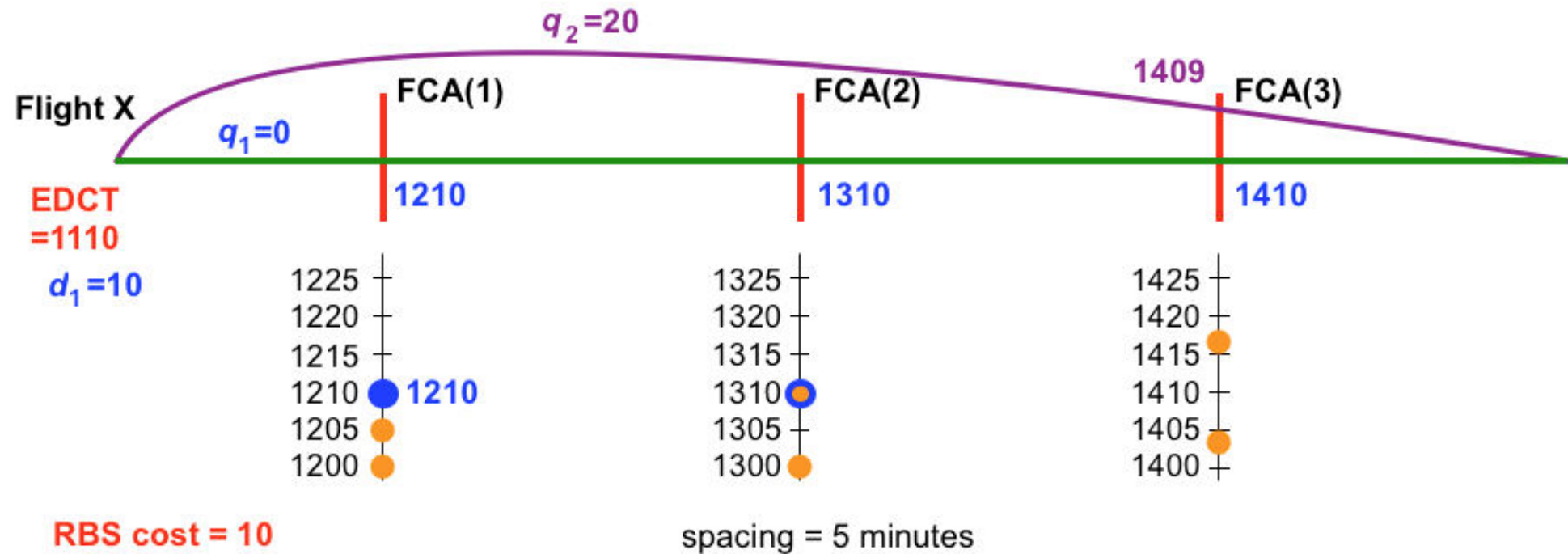


q_j Relative Trajectory Cost (RTC) of route j

c_j Total cost of route option j

d_j Ground delay on route j

RBS scheduling example

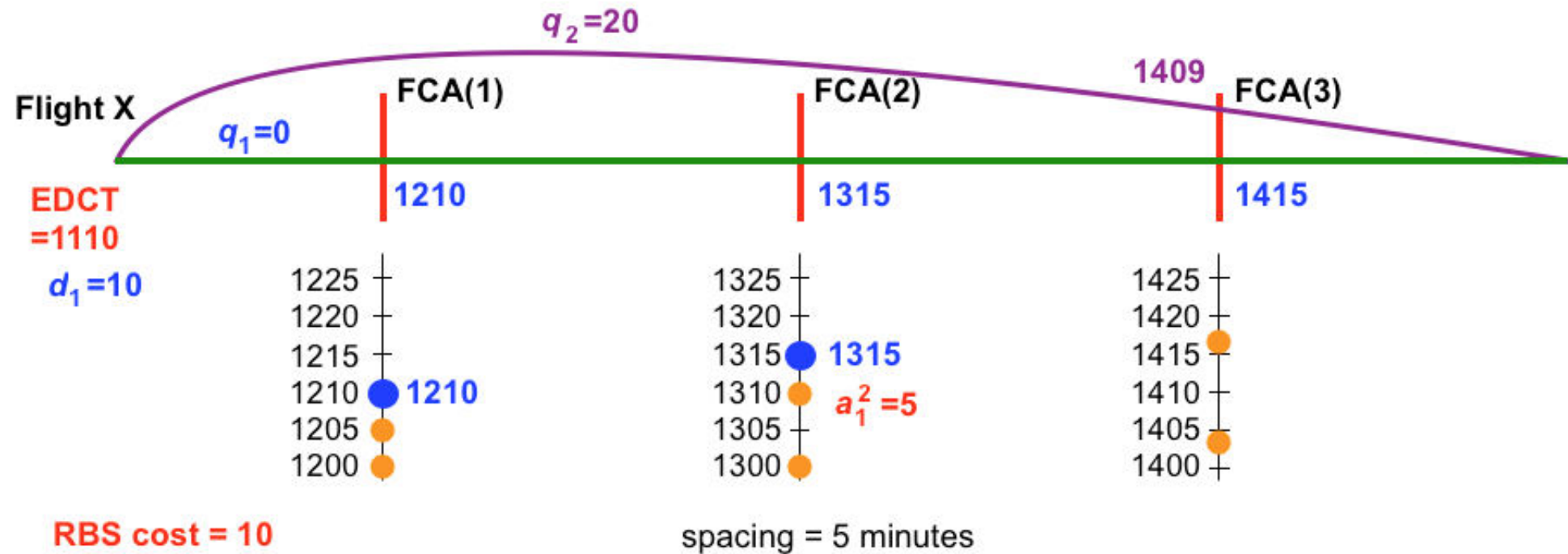


q_j Relative Trajectory Cost (RTC) of route j

c_j Total cost of route option j

d_j Ground delay on route j

RBS scheduling example



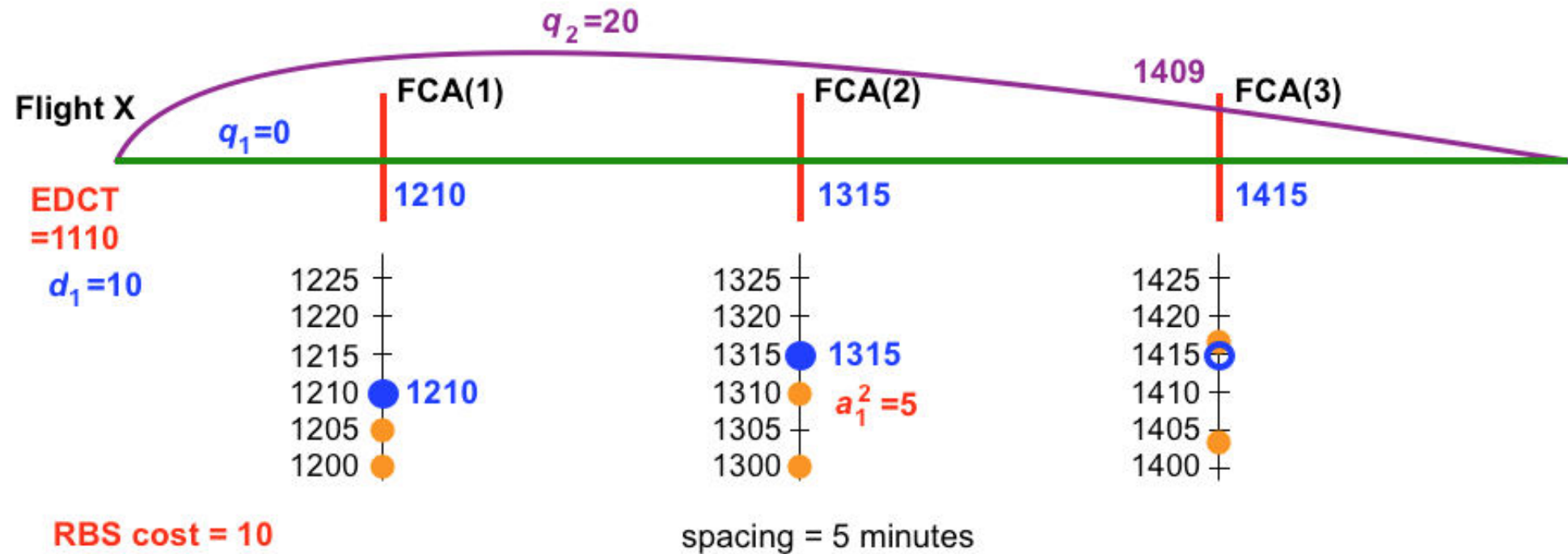
q_j Relative Trajectory Cost (RTC) of route j

d_j Ground delay on route j

c_j Total cost of route option j

a_j^k Airborne delay on route j before entering FCA k

RBS scheduling example



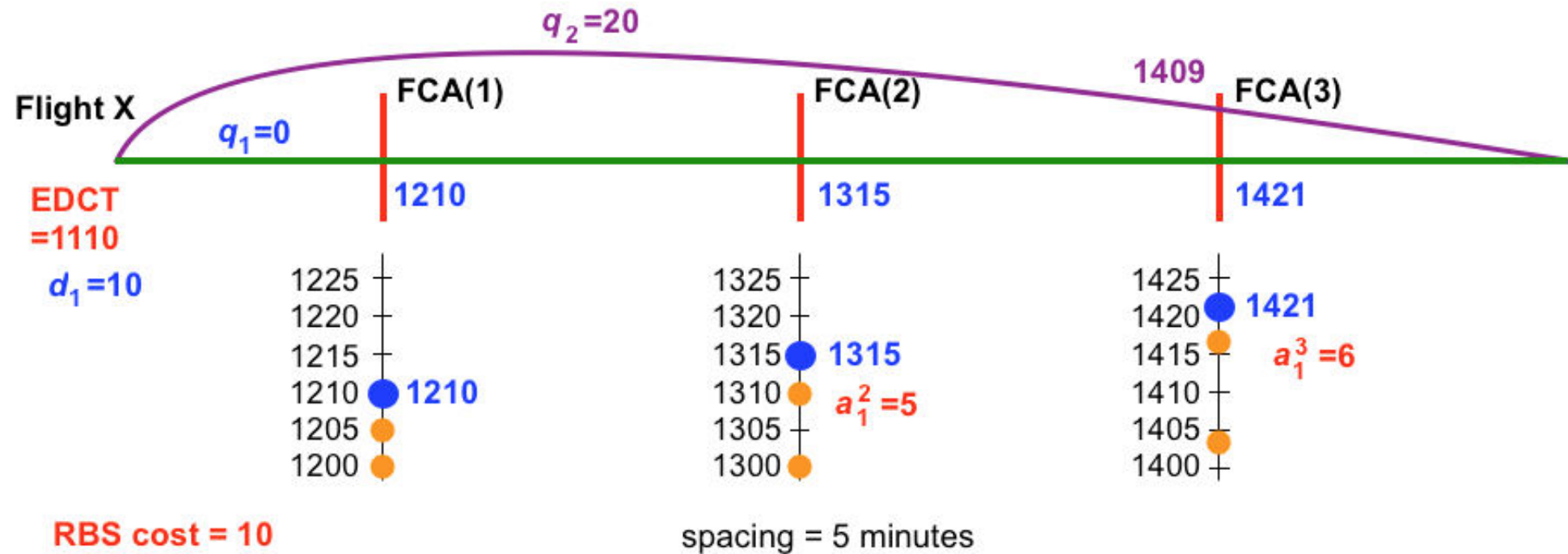
q_j Relative Trajectory Cost (RTC) of route j

d_j Ground delay on route j

c_j Total cost of route option j

a_j^k Airborne delay on route j before entering FCA k

RBS scheduling example



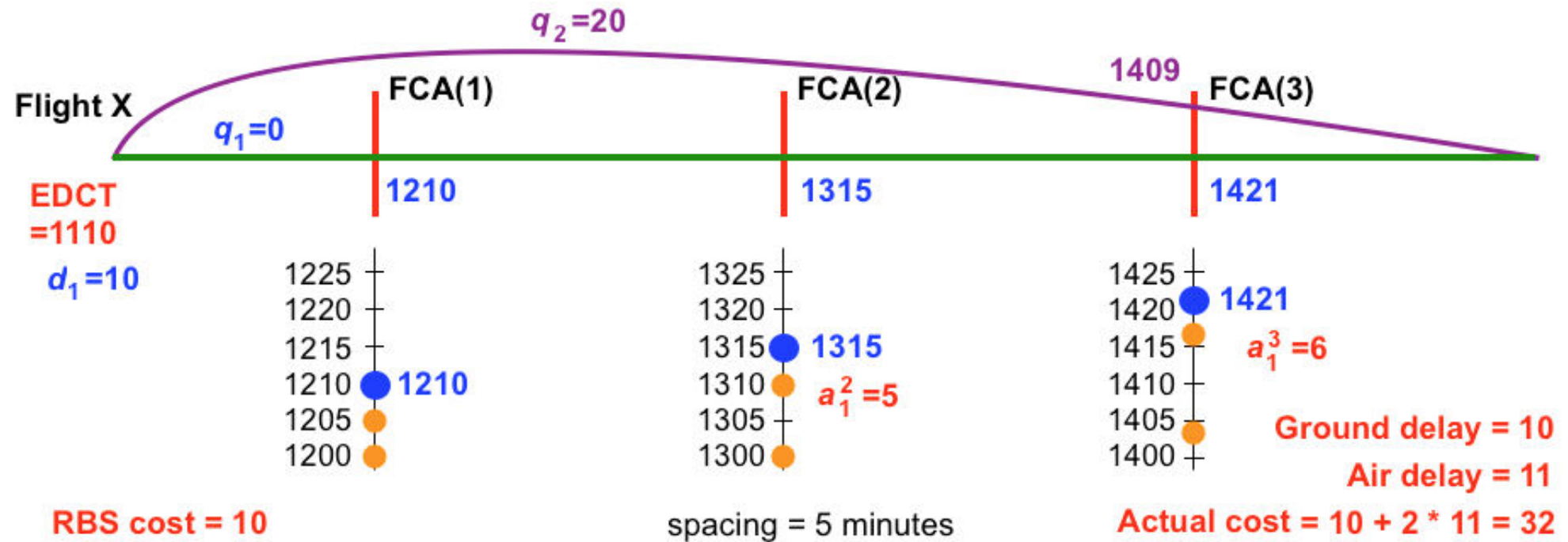
q_j Relative Trajectory Cost (RTC) of route j

d_j Ground delay on route j

c_j Total cost of route option j

a_j^k Airborne delay on route j before entering FCA k

RBS scheduling example



q_j Relative Trajectory Cost (RTC) of route j

d_j Ground delay on route j

c_j Total cost of route option j

a_j^k Airborne delay on route j before entering FCA k

Mixed-Integer Linear Program (MILP) formulation

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

Input data

N number of flights

N^A number of airlines

Λ^u set of flights of airline u

N^u number of flights of airline u

N_i number of routes of flight i

q_{ij} RTC of route j of flight i

Ω_{ij} set of FCAs along route j of flight i

Decision variables

δ_{ij} = 1 if route j is assigned to flight i

d_{ij} ground delay of flight i on route j

a_{ij}^k airborne delay of flight i on route j at FCA k

c_i total cost of route and delay allocation for flight i

y maximum average airline cost

Mixed-Integer Linear Program (MILP) formulation

$$\begin{aligned} \min_{\delta, d, a, y} \quad & \alpha \sum_{i=1}^N c_i + \omega y \\ \text{s.t.} \quad & c_i = \sum_{j=1}^{N_i} \left(q_{ij} \delta_{ij} + d_{ij} + 2 \sum_{k \in \Omega_{ij}} a_{ij}^k \right), \quad i = 1, \dots, N \end{aligned}$$

Input data

- N number of flights
- N^A number of airlines
- Λ^u set of flights of airline u
- N^u number of flights of airline u
- N_i number of routes of flight i
- q_{ij} RTC of route j of flight i
- Ω_{ij} set of FCAs along route j of flight i

Decision variables

- δ_{ij} = 1 if route j is assigned to flight i
- d_{ij} ground delay of flight i on route j
- a_{ij}^k airborne delay of flight i on route j at FCA k
- c_i total cost of route and delay allocation for flight i
- y maximum average airline cost

Mixed-Integer Linear Program (MILP) formulation

$$\begin{aligned} \min_{\delta, d, a, y} \quad & \alpha \sum_{i=1}^N c_i + \omega y \\ \text{s.t.} \quad & c_i = \sum_{j=1}^{N_i} \left(q_{ij} \delta_{ij} + d_{ij} + 2 \sum_{k \in \Omega_{ij}} a_{ij}^k \right), \quad i = 1, \dots, N \end{aligned}$$

Input data

- N number of flights
- N^A number of airlines
- Λ^u set of flights of airline u
- N^u number of flights of airline u
- N_i number of routes of flight i
- q_{ij} RTC of route j of flight i
- Ω_{ij} set of FCAs along route j of flight i

Decision variables

- δ_{ij} = 1 if route j is assigned to flight i
- d_{ij} ground delay of flight i on route j
- a_{ij}^k airborne delay of flight i on route j at FCA k
- c_i total cost of route and delay allocation for flight i
- y maximum average airline cost

Mixed-Integer Linear Program (MILP) formulation

$$\begin{aligned} \min_{\delta, d, a, y} \quad & \alpha \sum_{i=1}^N c_i + \omega y \\ \text{s.t.} \quad & c_i = \sum_{j=1}^{N_i} \left(q_{ij} \delta_{ij} + d_{ij} + 2 \sum_{k \in \Omega_{ij}} a_{ij}^k \right), \quad i = 1, \dots, N \\ & y \geq \frac{1}{N^u} \sum_{i \in \Lambda^u} c_i, \quad u = 1, \dots, N^A \end{aligned}$$

Input data

- N number of flights
- N^A number of airlines
- Λ^u set of flights of airline u
- N^u number of flights of airline u
- N_i number of routes of flight i
- q_{ij} RTC of route j of flight i
- Ω_{ij} set of FCAs along route j of flight i

Decision variables

- δ_{ij} = 1 if route j is assigned to flight i
- d_{ij} ground delay of flight i on route j
- a_{ij}^k airborne delay of flight i on route j at FCA k
- c_i total cost of route and delay allocation for flight i
- y maximum average airline cost

Mixed-Integer Linear Program (MILP) formulation

$$\begin{aligned} \min_{\delta, d, a, y} \quad & \alpha \sum_{i=1}^N c_i + \omega y \\ \text{s.t.} \quad & c_i = \sum_{j=1}^{N_i} \left(q_{ij} \delta_{ij} + d_{ij} + 2 \sum_{k \in \Omega_{ij}} a_{ij}^k \right), \quad i = 1, \dots, N \\ & y \geq \frac{1}{N^u} \sum_{i \in \Lambda^u} c_i, \quad u = 1, \dots, N^A \end{aligned}$$

Input data

- N number of flights
- N^A number of airlines
- Λ^u set of flights of airline u
- N^u number of flights of airline u
- N_i number of routes of flight i
- q_{ij} RTC of route j of flight i
- Ω_{ij} set of FCAs along route j of flight i

Decision variables

- δ_{ij} = 1 if route j is assigned to flight i
- d_{ij} ground delay of flight i on route j
- a_{ij}^k airborne delay of flight i on route j at FCA k
- c_i total cost of route and delay allocation for flight i
- y maximum average airline cost

Mixed-Integer Linear Program (MILP) formulation

$$\begin{aligned}
 \min_{\delta, d, a, y} \quad & \alpha \sum_{i=1}^N c_i + \omega y \\
 \text{s.t.} \quad & c_i = \sum_{j=1}^{N_i} \left(q_{ij} \delta_{ij} + d_{ij} + 2 \sum_{k \in \Omega_{ij}} a_{ij}^k \right), \quad i = 1, \dots, N \\
 & y \geq \frac{1}{N^u} \sum_{i \in \Lambda^u} c_i, \quad u = 1, \dots, N^A \\
 & \sum_{j=1}^{N_i} \delta_{ij} = 1, \quad i = 1, \dots, N
 \end{aligned}$$

Input data

- N number of flights
- N^A number of airlines
- Λ^u set of flights of airline u
- N^u number of flights of airline u
- N_i number of routes of flight i
- q_{ij} RTC of route j of flight i
- Ω_{ij} set of FCAs along route j of flight i

Decision variables

- δ_{ij} = 1 if route j is assigned to flight i
- d_{ij} ground delay of flight i on route j
- a_{ij}^k airborne delay of flight i on route j at FCA k
- c_i total cost of route and delay allocation for flight i
- y maximum average airline cost

Mixed-Integer Linear Program (MILP) formulation

$$\begin{aligned}
 & \min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y \\
 \text{s.t. } & c_i = \sum_{j=1}^{N_i} \left(q_{ij} \delta_{ij} + d_{ij} + 2 \sum_{k \in \Omega_{ij}} a_{ij}^k \right), \quad i = 1, \dots, N \\
 & y \geq \frac{1}{N^u} \sum_{i \in \Lambda^u} c_i, \quad u = 1, \dots, N^A \\
 & \sum_{j=1}^{N_i} \delta_{ij} = 1, \quad i = 1, \dots, N \\
 & d_{ij} + \sum_{k \in \Omega_{ij}} a_{ij}^k \leq M \delta_{ij}, \quad i = 1, \dots, N; j = 1, \dots, N_i
 \end{aligned}$$

Input data

- N number of flights
- N^A number of airlines
- Λ^u set of flights of airline u
- N^u number of flights of airline u
- N_i number of routes of flight i
- q_{ij} RTC of route j of flight i
- Ω_{ij} set of FCAs along route j of flight i

Decision variables

- δ_{ij} = 1 if route j is assigned to flight i
- d_{ij} ground delay of flight i on route j
- a_{ij}^k airborne delay of flight i on route j at FCA k
- c_i total cost of route and delay allocation for flight i
- y maximum average airline cost

Mixed-Integer Linear Program (MILP) formulation

$$\begin{aligned}
 & \min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y \\
 \text{s.t.} \quad & c_i = \sum_{j=1}^{N_i} \left(q_{ij} \delta_{ij} + d_{ij} + 2 \sum_{k \in \Omega_{ij}} a_{ij}^k \right), \quad i = 1, \dots, N \\
 & y \geq \frac{1}{N^u} \sum_{i \in \Lambda^u} c_i, \quad u = 1, \dots, N^A \\
 & \sum_{j=1}^{N_i} \delta_{ij} = 1, \quad i = 1, \dots, N \\
 & d_{ij} + \sum_{k \in \Omega_{ij}} a_{ij}^k \leq M \delta_{ij}, \quad i = 1, \dots, N; j = 1, \dots, N_i
 \end{aligned}$$

If flights i and f cross FCA k within its period of activity, then their ETAs should be separated by at least minimum spacing.

Input data

- N number of flights
- N^A number of airlines
- Λ^u set of flights of airline u
- N^u number of flights of airline u
- N_i number of routes of flight i
- q_{ij} RTC of route j of flight i
- Ω_{ij} set of FCAs along route j of flight i

Decision variables

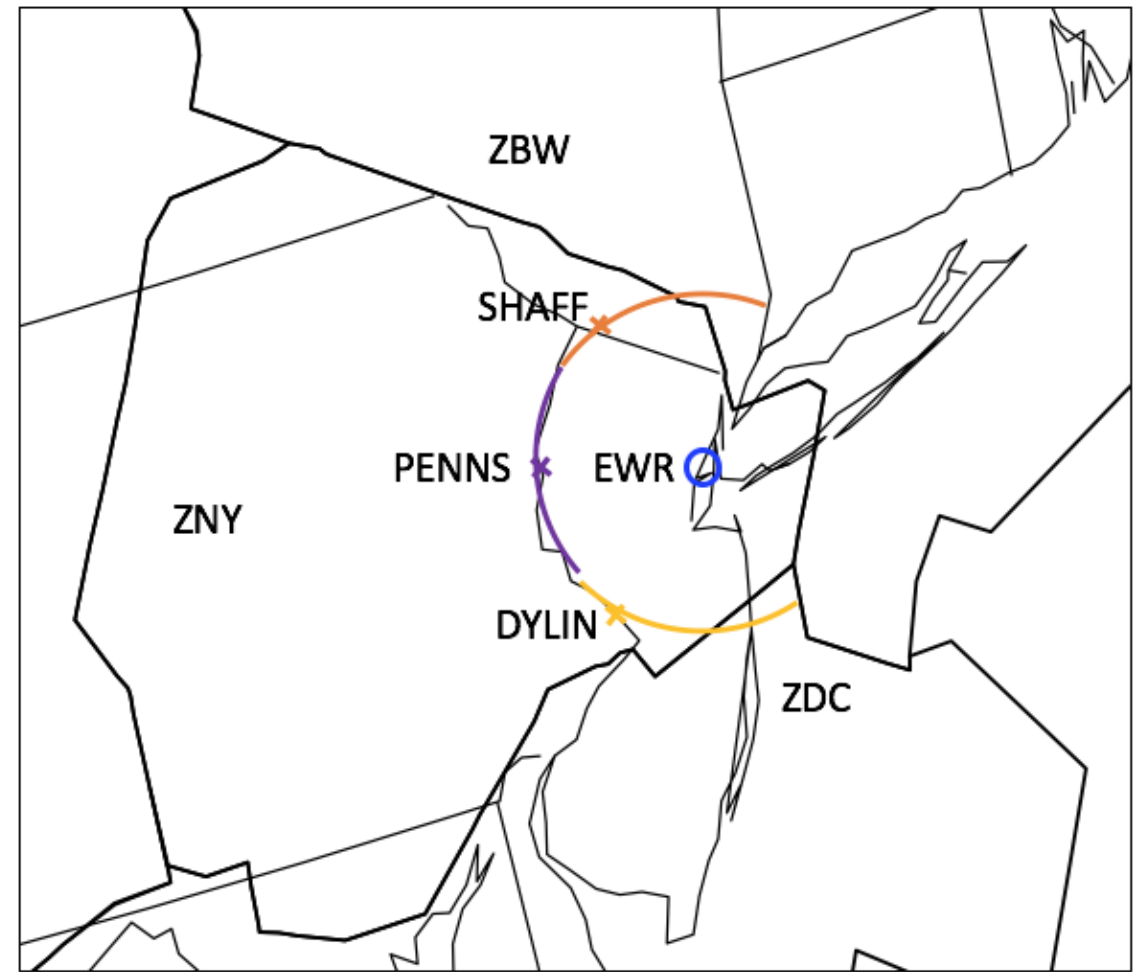
- δ_{ij} = 1 if route j is assigned to flight i
- d_{ij} ground delay of flight i on route j
- a_{ij}^k airborne delay of flight i on route j at FCA k
- c_i total cost of route and delay allocation for flight i
- y maximum average airline cost

Test case

- July 14th 2015

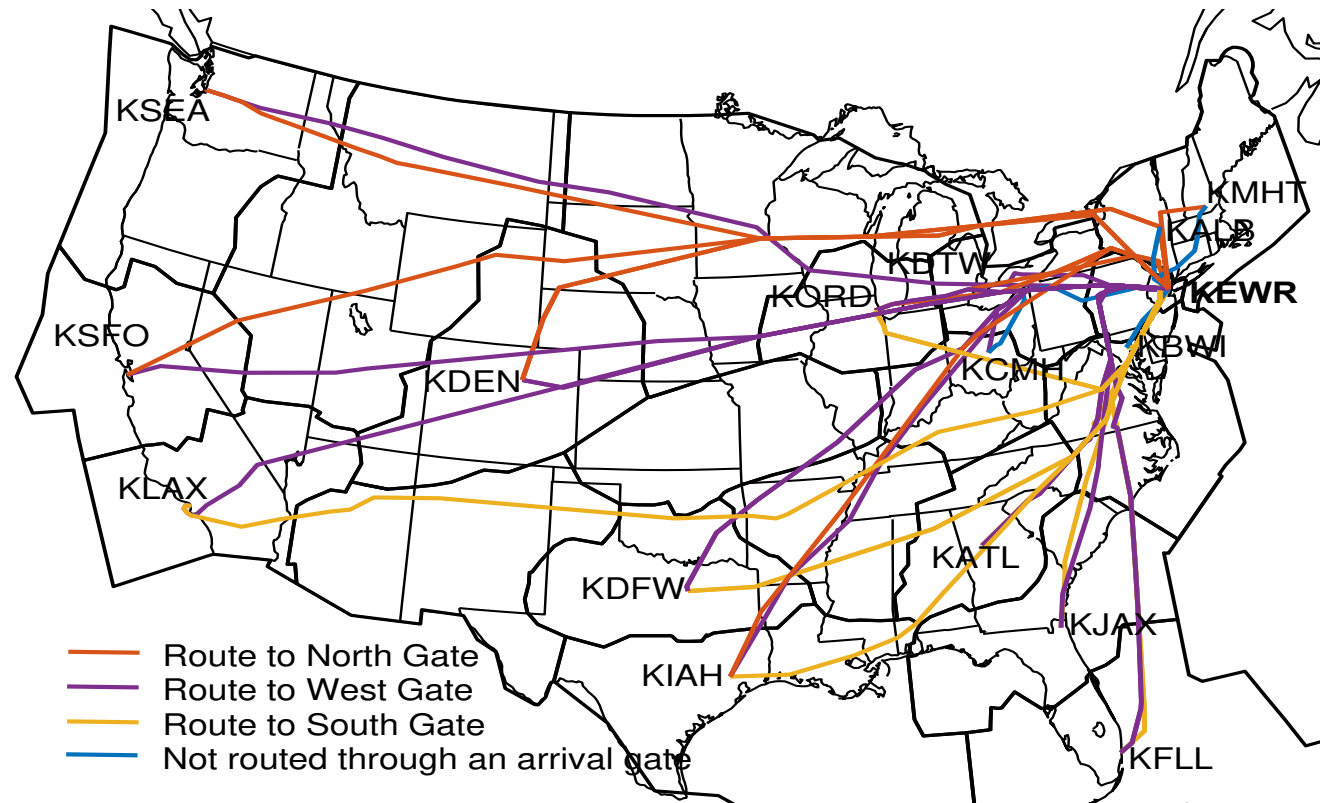
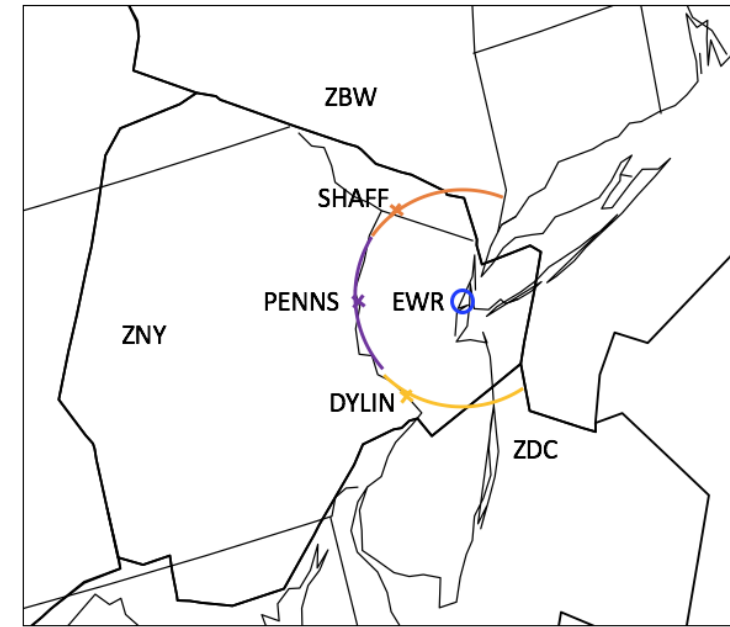
Test case

- July 14th 2015
- Four FCAs:
 - Newark Liberty International Airport (EWR)
 - SHAFF (north gate)
 - PENNS (west gate)
 - DYLIN (south gate)
- One hour period of activity
 - 0800Z-0900Z

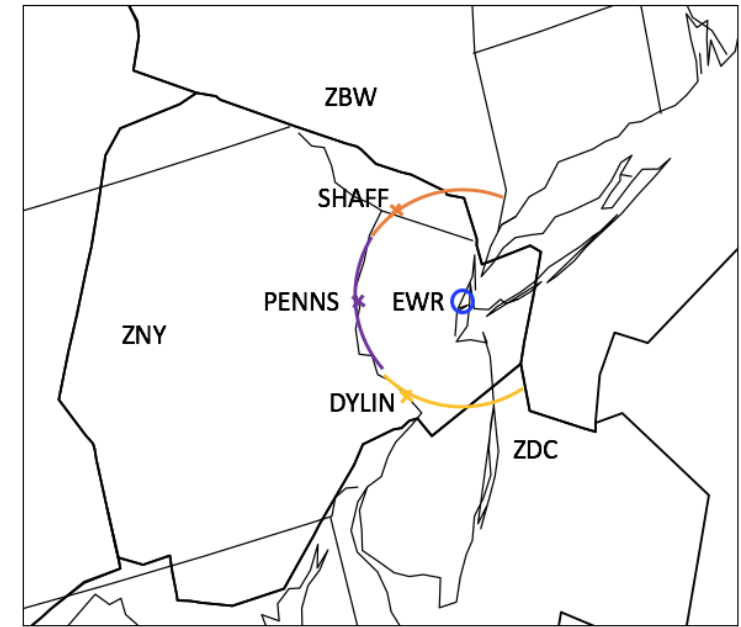
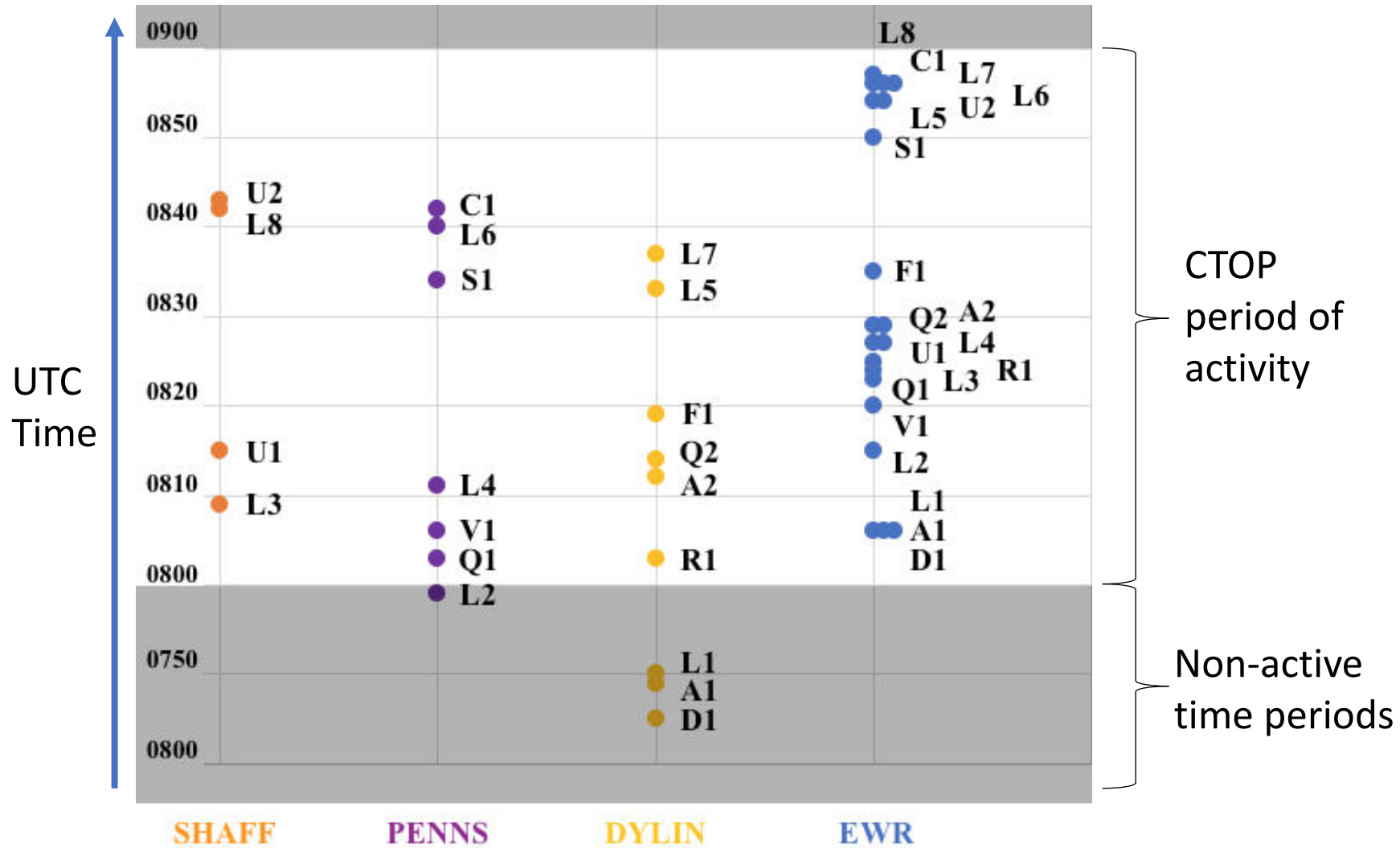


Test case

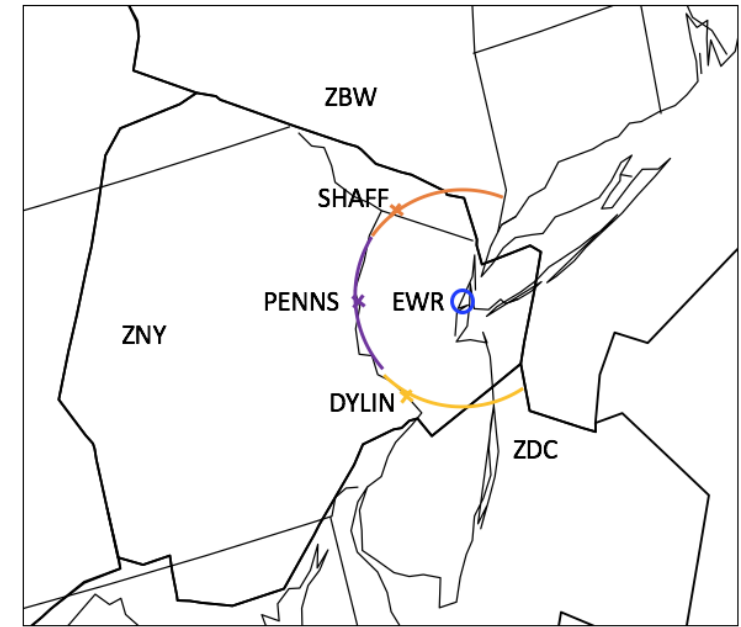
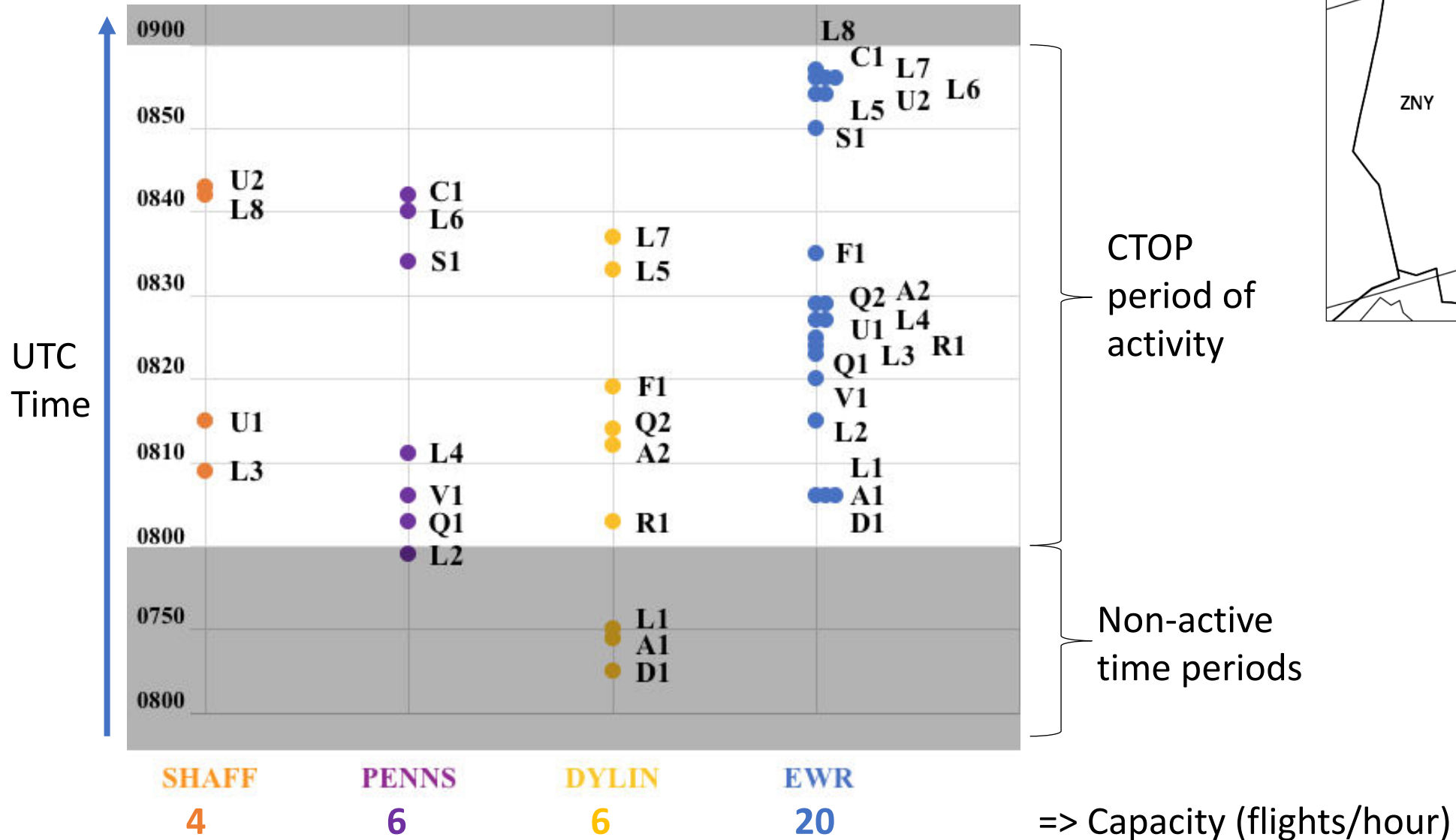
- July 14th 2015
- Four FCAs:
 - Newark Liberty International Airport (EWR)
 - SHAFF (north gate)
 - PENNS (west gate)
 - DYLIN (south gate)
- One hour period of activity
 - 0800Z-0900Z
- 20 flights destined at EWR
 - 2-3 options for each flight
 - FCA crossing times within 0800Z-0900Z



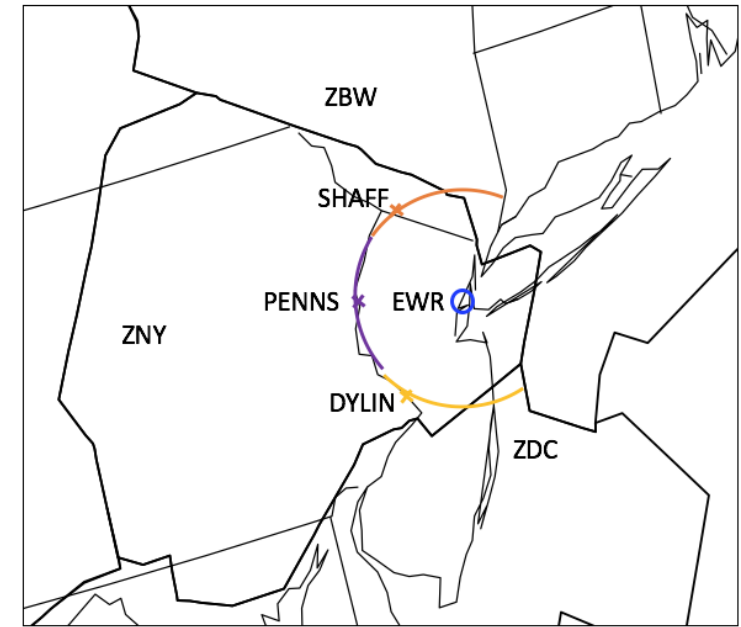
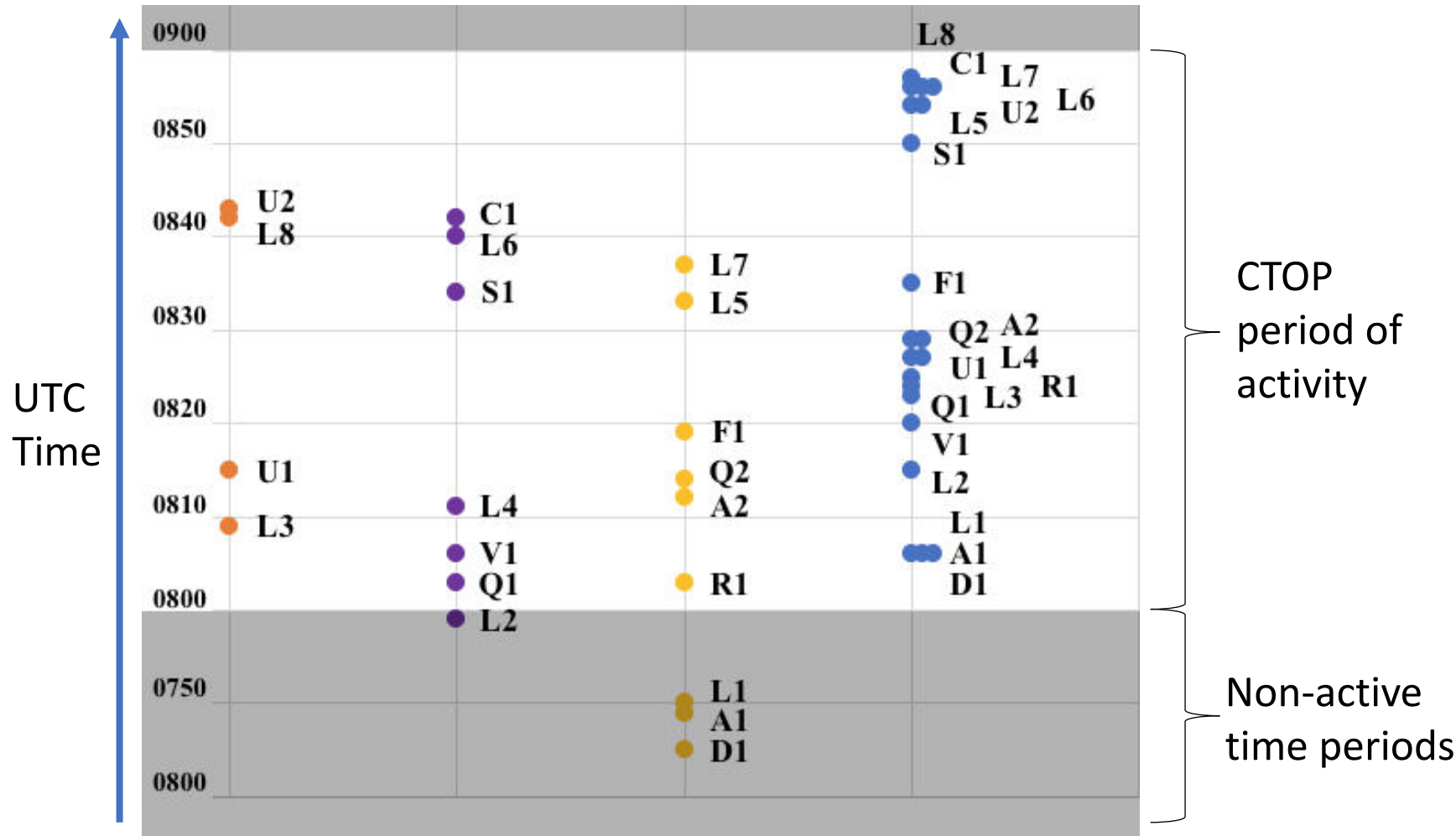
Test case: initial demand



Test case: initial demand



Test case: initial demand



SHAFF	PENNS	DYLIN	EWR
4	6	6	20
15	10	10	3

=> Capacity (flights/hour)

=> Spacing (minutes)

Efficiency metrics

$$\sum_{flights} \left(RTC + Delay_{ground} + 2 \sum_{FCAs} Delay_{air} \right)$$

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency metrics

$$\overbrace{\sum_{flights} \left(RTC + Delay_{ground} + 2 \sum_{FCAs} Delay_{air} \right)}^{\text{Actual cost}}$$

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency metrics

$$\begin{array}{c} \text{Actual cost} \\ \sum_{\text{flights}} \left(\underbrace{RTC + \text{Delay}_{\text{ground}}}_{\text{Ground cost}} + 2 \underbrace{\sum_{\text{FCAs}} \text{Delay}_{\text{air}}}_{\text{Airborne cost}} \right) \end{array}$$

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency metrics

$$\begin{array}{c} \text{Estimated cost (MILP)} \\ = \\ \text{Actual cost} \\ \left. \sum_{flights} \left(\underbrace{RTC + Delay_{ground}}_{\text{Ground cost}} + 2 \underbrace{\sum_{FCAs} Delay_{air}}_{\text{Airborne cost}} \right) \right\} \\ = \\ \text{Estimated cost (RBS)} \end{array}$$

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

Airborne cost = 2 x Airborne delay

Efficiency of allocation methods

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

	RBS	MILP
	Minutes	
Estimated total cost	143	134
Actual total cost	201	134
Total ground cost	143	120
Total airborne cost	58	14
Maximum flight cost	22	35
Maximum ground delay	20	14
Maximum airborne delay	6	2

Estimated cost : cost yielded by the allocation algorithm

Actual cost = Ground cost + Airborne cost

Ground cost = RTC + Ground delay

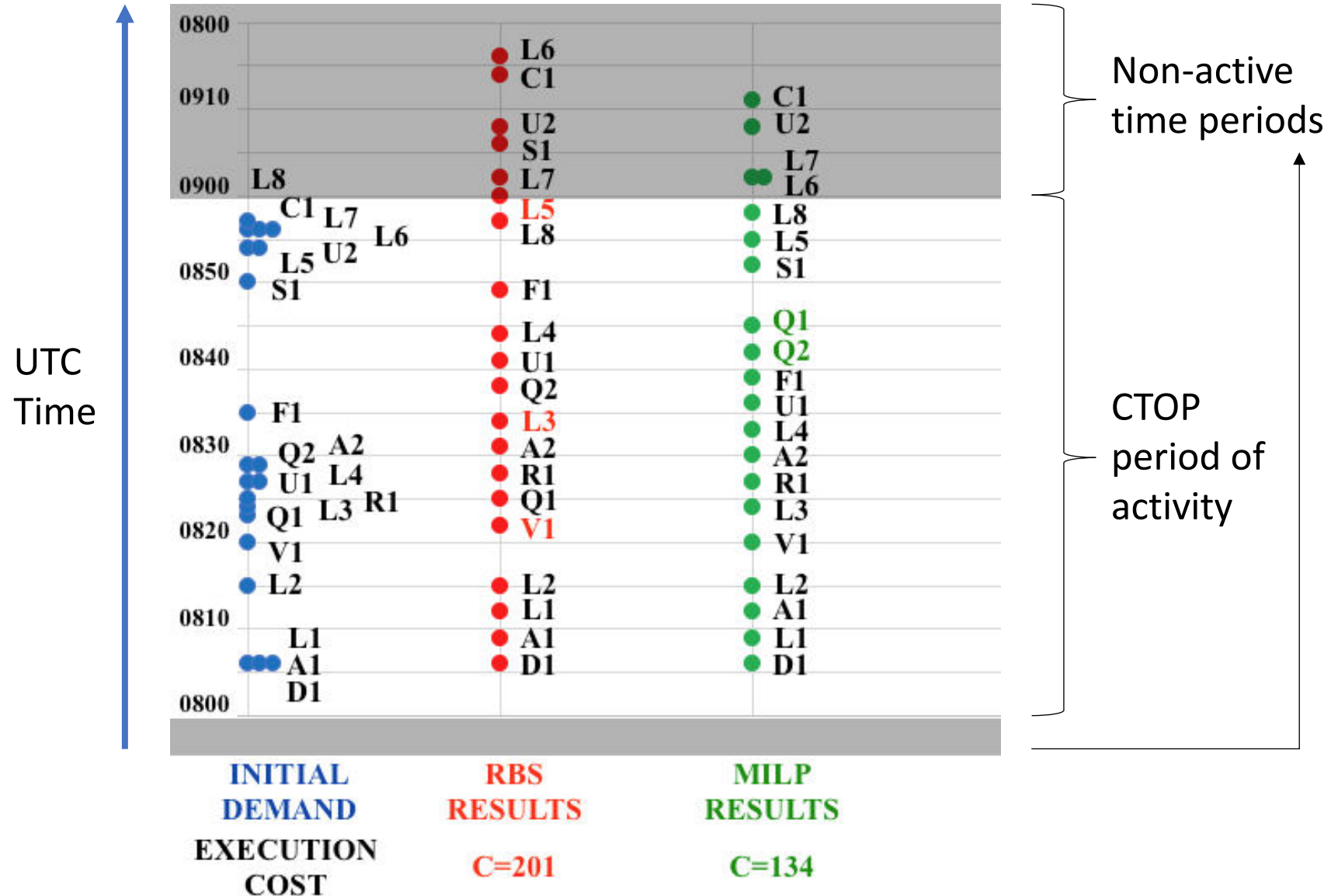
Airborne cost = 2 x Airborne delay

Resulting allocation

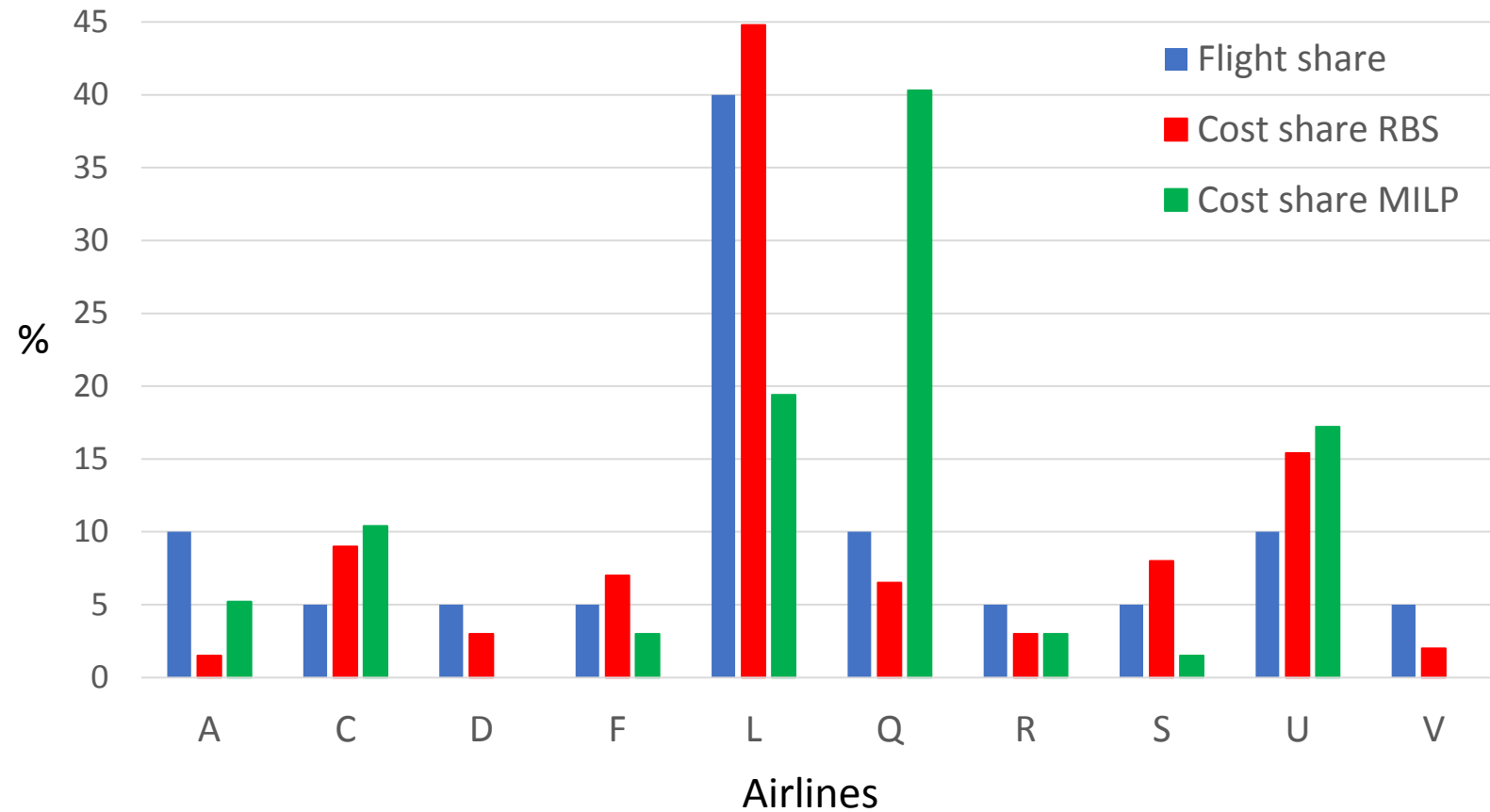
Allocation at EWR

Capacity: 20

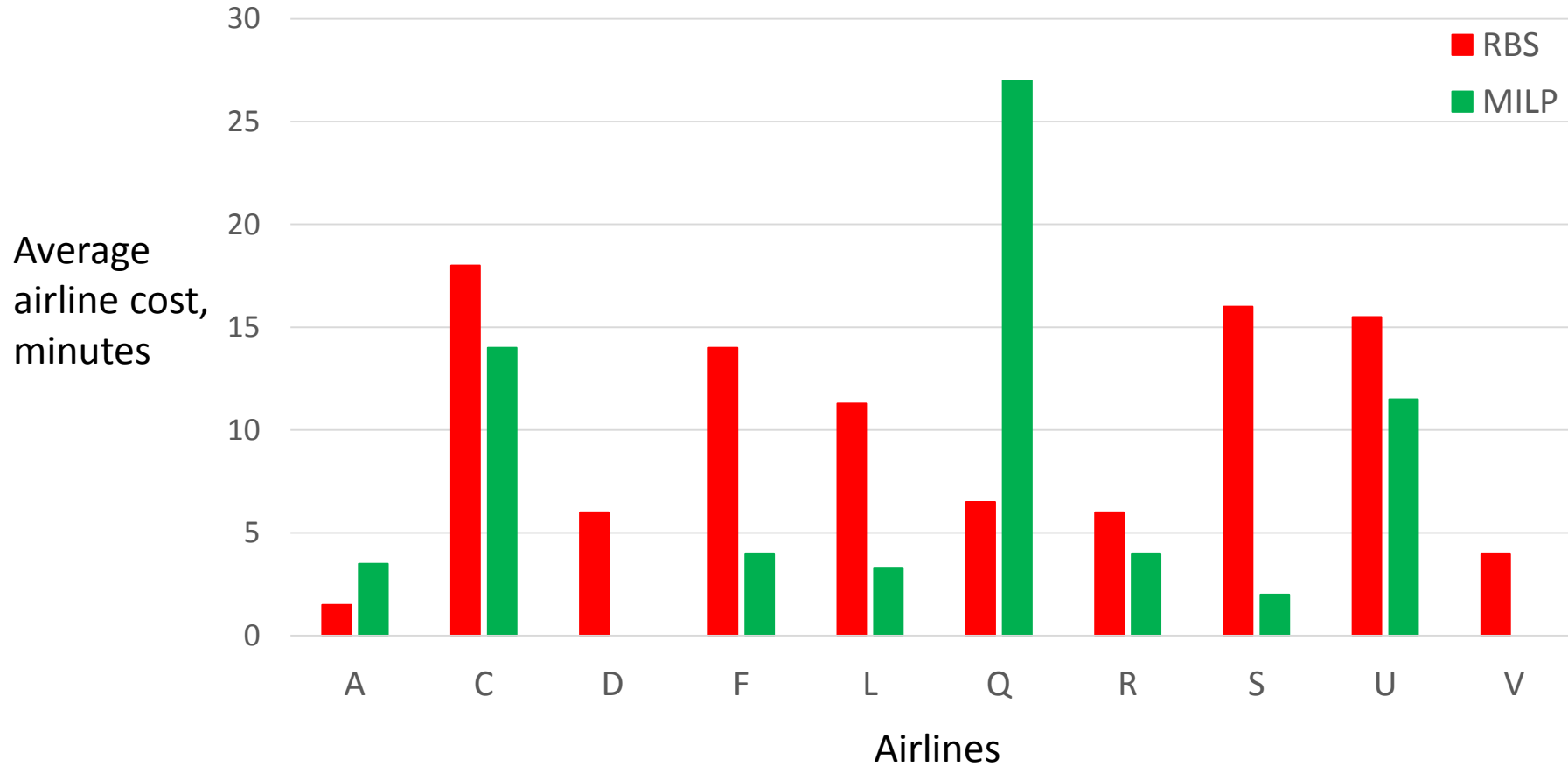
Spacing: 3 minutes



Equity of allocation methods: cost share

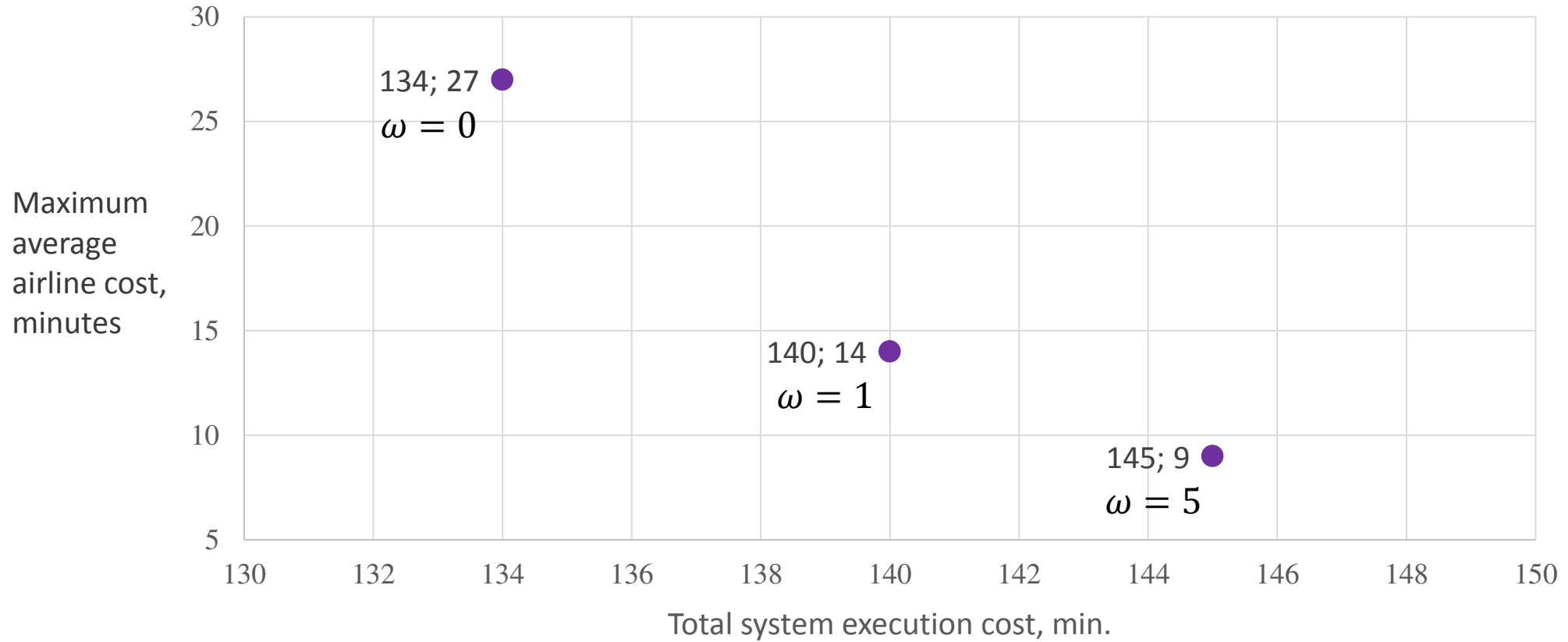


Equity of allocation methods: average airline cost



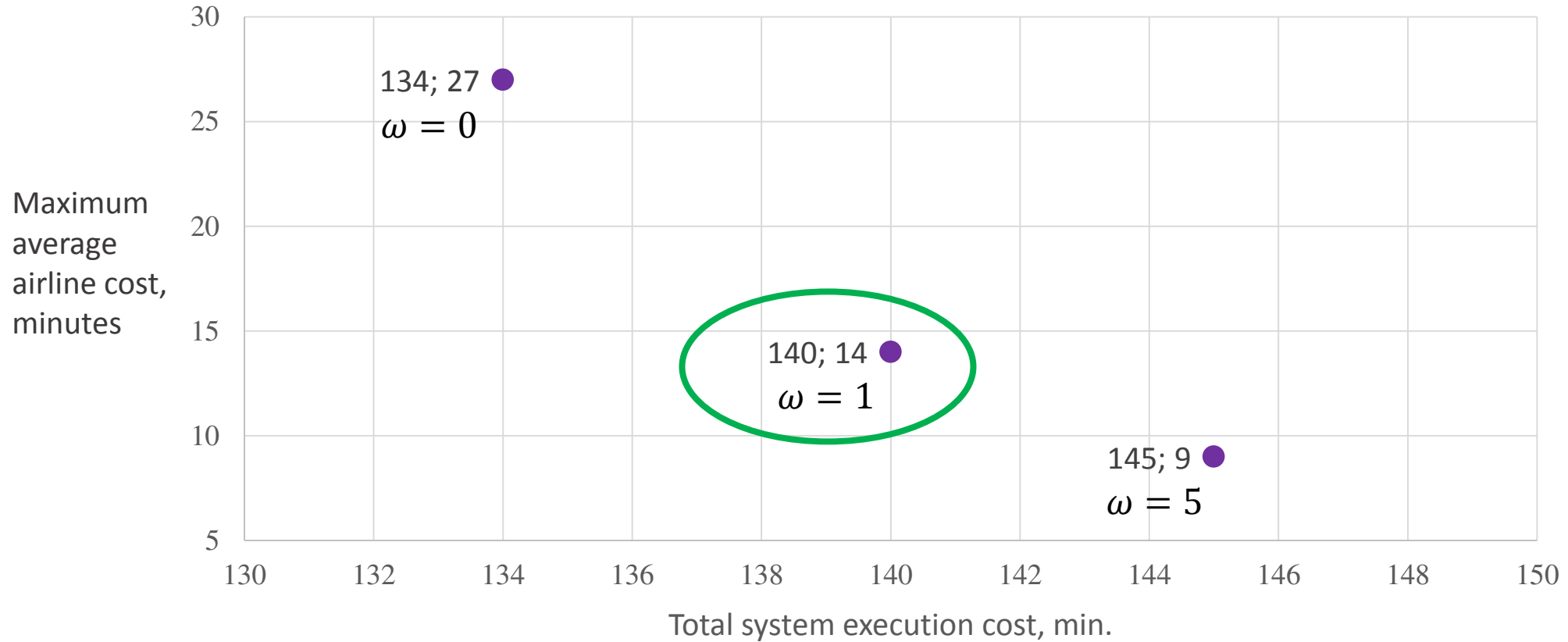
Efficiency and equity trade-off

$$\min_{\delta, d, a, y} \sum_{i=1}^N c_i + \omega y$$



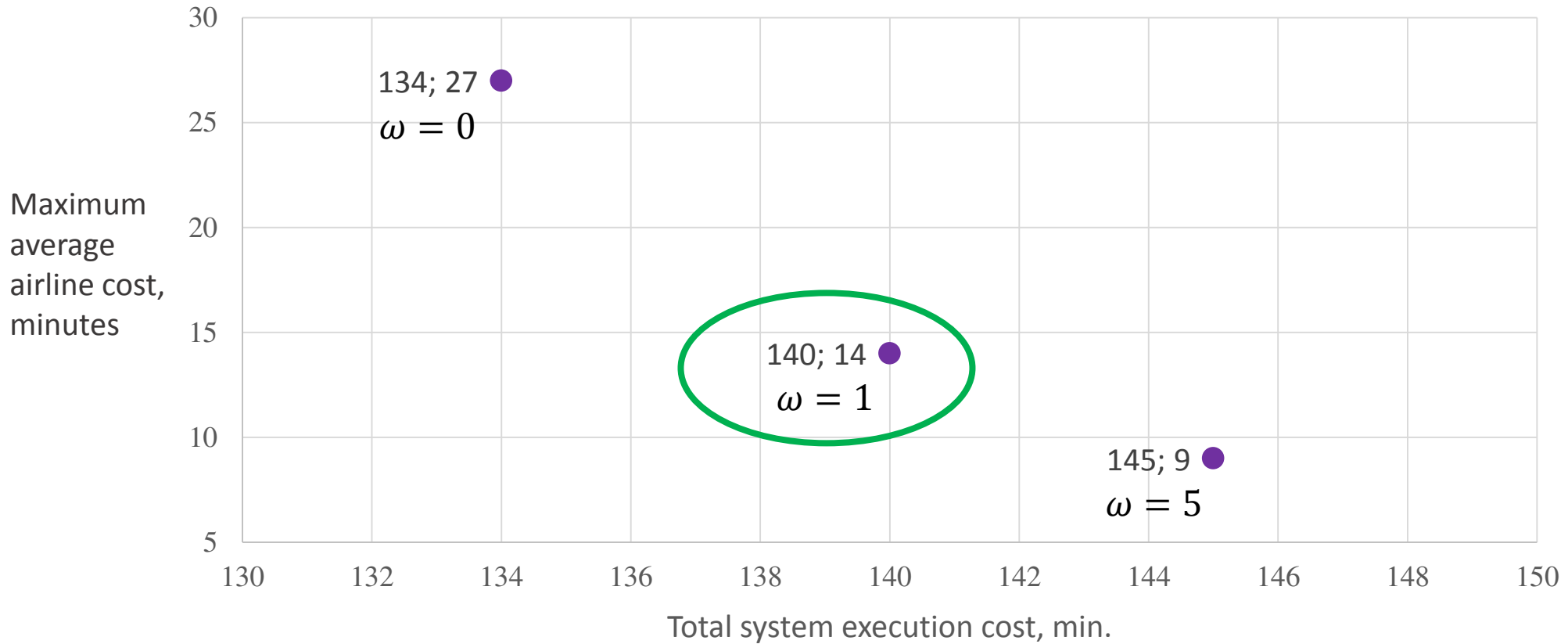
Efficiency and equity trade-off

$$\min_{\delta, d, a, y} \sum_{i=1}^N c_i + \omega y$$



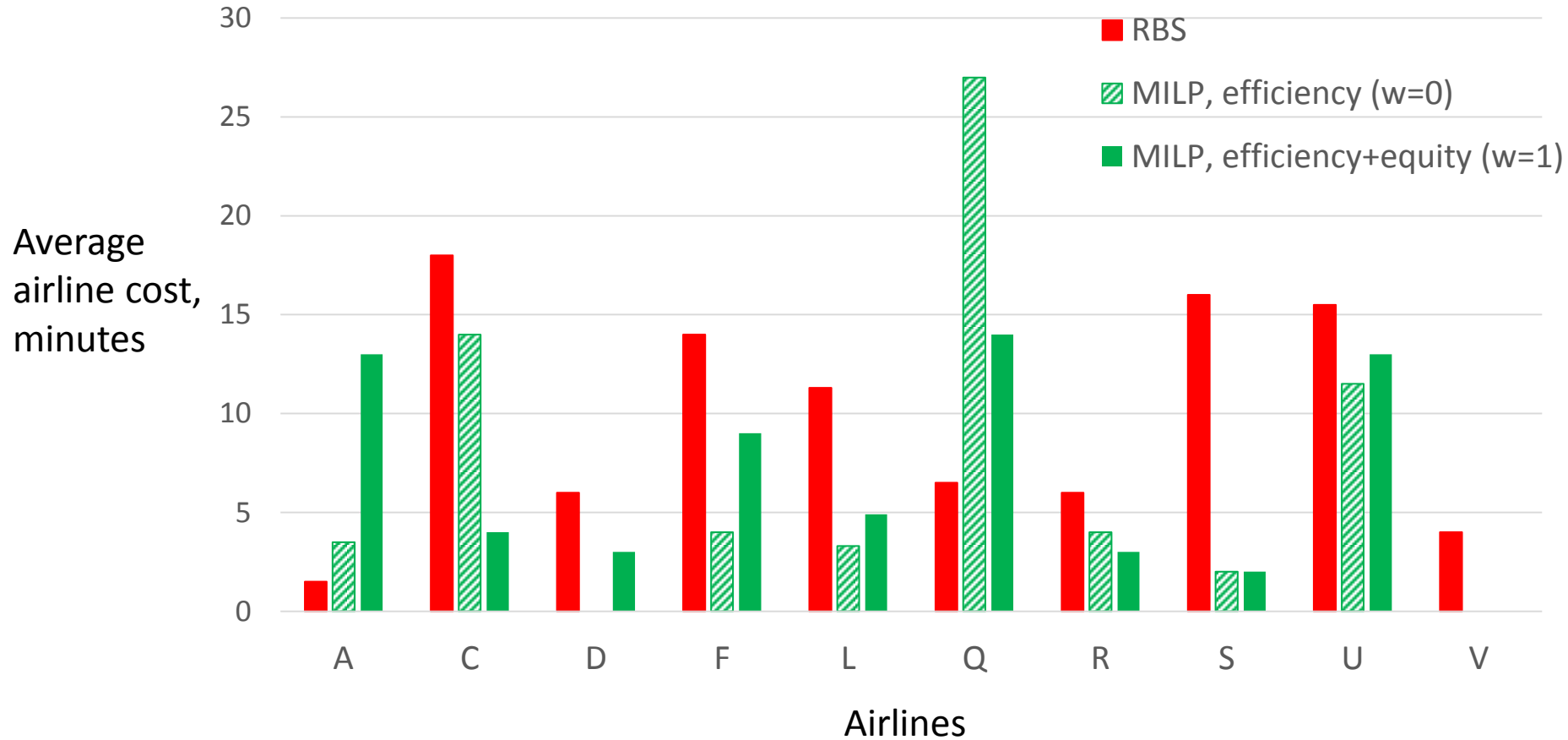
Efficiency and equity trade-off

$$\min_{\delta, d, a, y} \sum_{i=1}^N c_i + \omega y$$



RBS:
201, 18

Improved equity: average airline cost



Conclusion

Conclusion

- Space-based allocation → Uniform flight distribution

Conclusion

- Space-based allocation → Uniform flight distribution
- Constraints at multiple FCAs simultaneously → More predictable schedule (in deterministic conditions)

Conclusion

- Space-based allocation → Uniform flight distribution
- Constraints at multiple FCAs simultaneously → More predictable schedule (in deterministic conditions)
- Global optimization with airborne delays → Improved efficiency compared to RBS

Conclusion

- Space-based allocation → Uniform flight distribution
- Constraints at multiple FCAs simultaneously → More predictable schedule (in deterministic conditions)
- Global optimization with airborne delays → Improved efficiency compared to RBS
- Equity metric in optimization → Improved equity for airlines

Future work

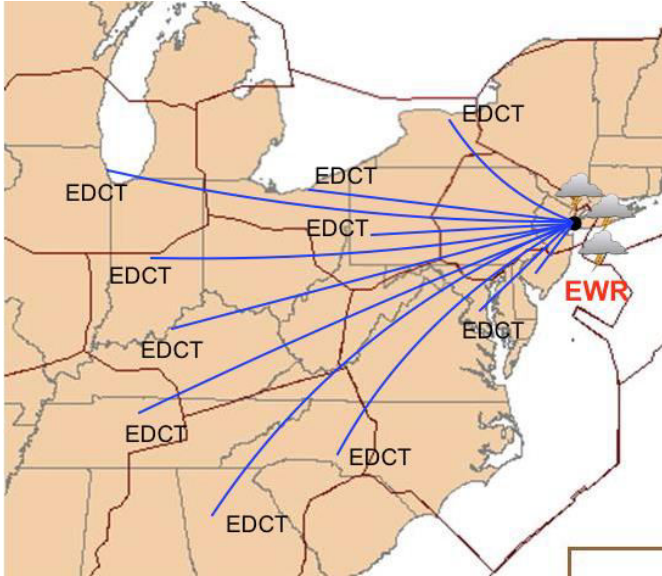
- Extend to larger test case
(longer period of activity, more flights)
- Predictability of developed method
(with demand and capacity uncertainties)
- Stochastic formulation of the optimization problem
- Exempted and pop-up flights

Contact: olga.p.rodionova@nasa.gov

Appendices

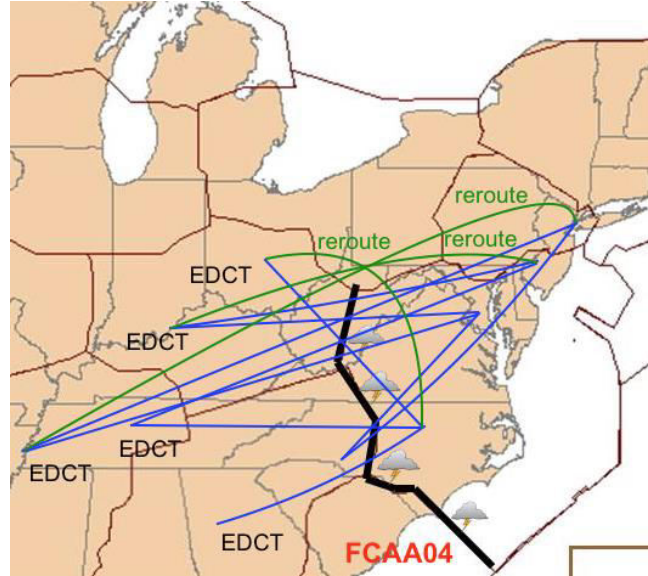
Traffic Management Initiatives (TMIs)

GDP



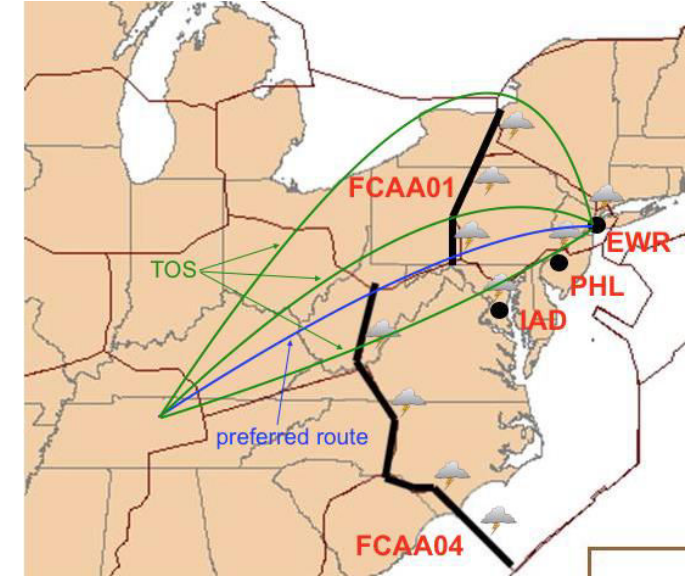
- Arrival airport
- Ground delays =>
 - Expected Departure Clearance Time (EDCT)

AFP



- Flow Constrained Area (FCA)
- Ground delays => EDCTs
- Reroutes
 - Specified by TFM

CTOP (GDP + AFP + CDM)



- Multiple FCA and multiple airports
- Ground delays => EDCTs
- Reroutes
 - Trajectory Option Set (TOS) => specified by flight operators

Resource allocation problem: overview

- What resources must be allocated?
- What allocation criteria are to be used?
- Which allocation algorithm is to be used?

- => FCA capacities

- Capacity-based allocation

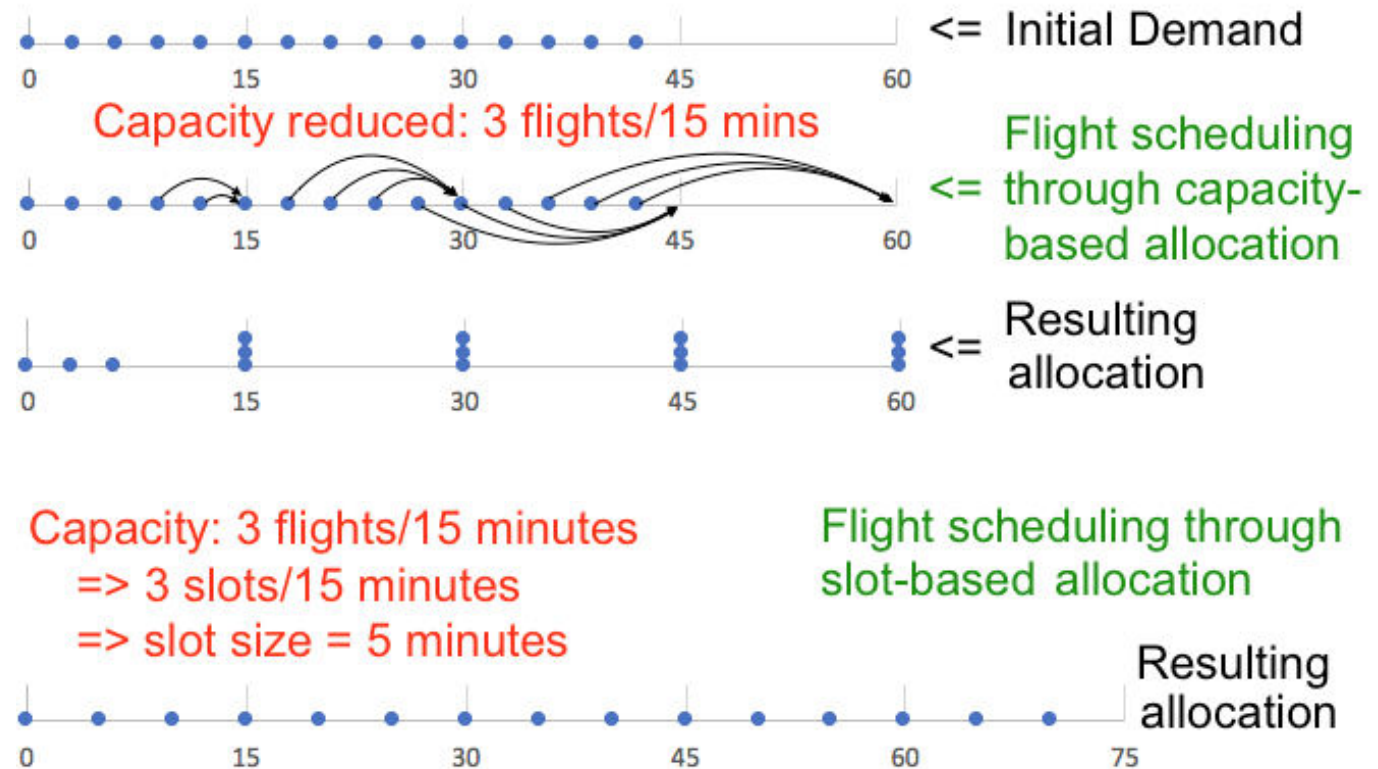
- Sector capacities

- Slot-based allocation

- GDP, AFP and CTOP

- Space-based allocation

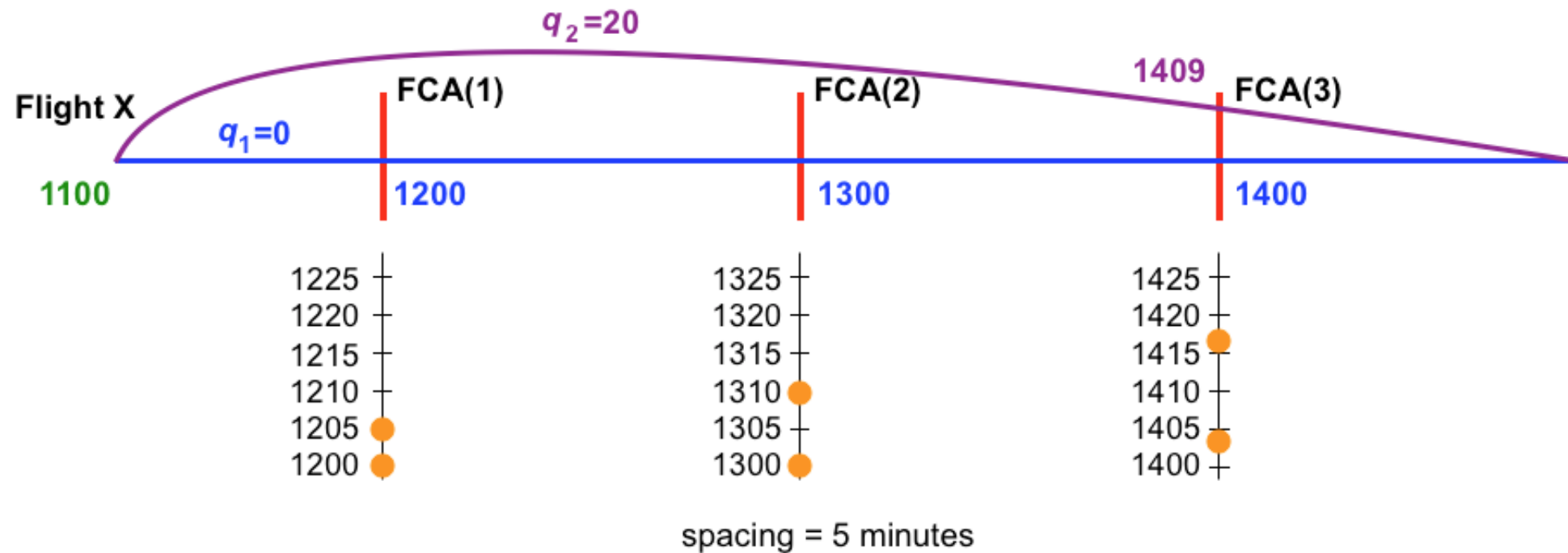
- MIT, MinIT, TBFM



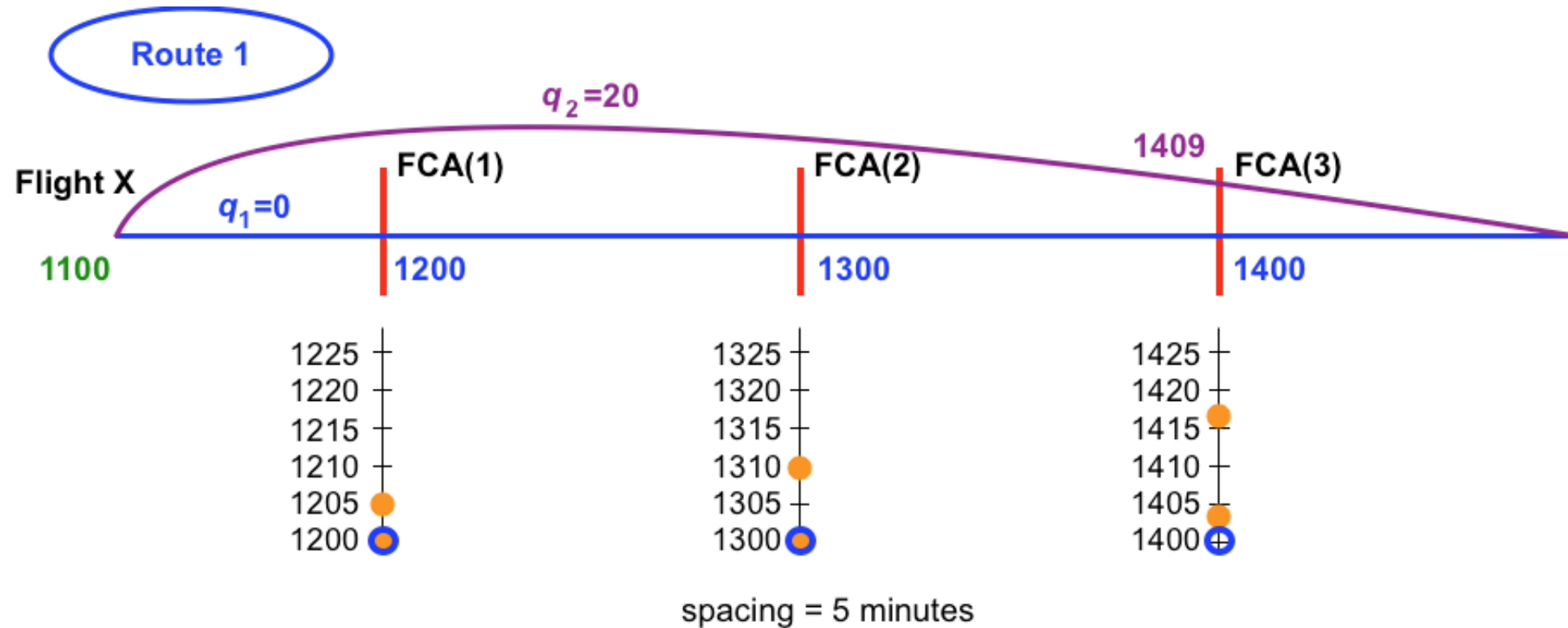
RBSall: considering all FCAs simultaneously

- For each flight, calculate its Initial Arrival Time (IAT)
 - For each route option from TOS, calculate the Estimated Arrival Time (ETA) at its first (primary) FCA
 - Chose the minimum among these ETAs
- Order flights based on their IATs in a priority list
- For each flight from the priority list, find the best (minimum-cost) available route and delay allocation satisfying the spacing constraints **at all FCAs along this route at the same time**

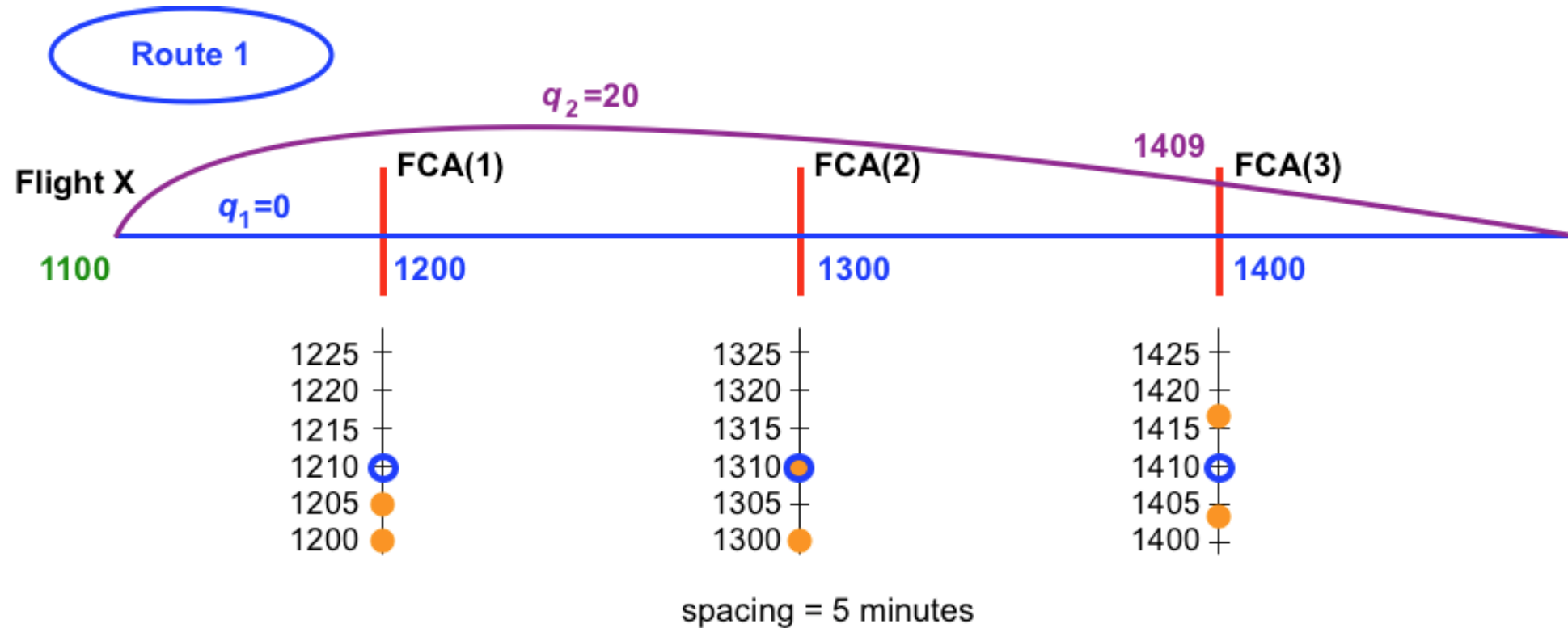
RBSall scheduling example



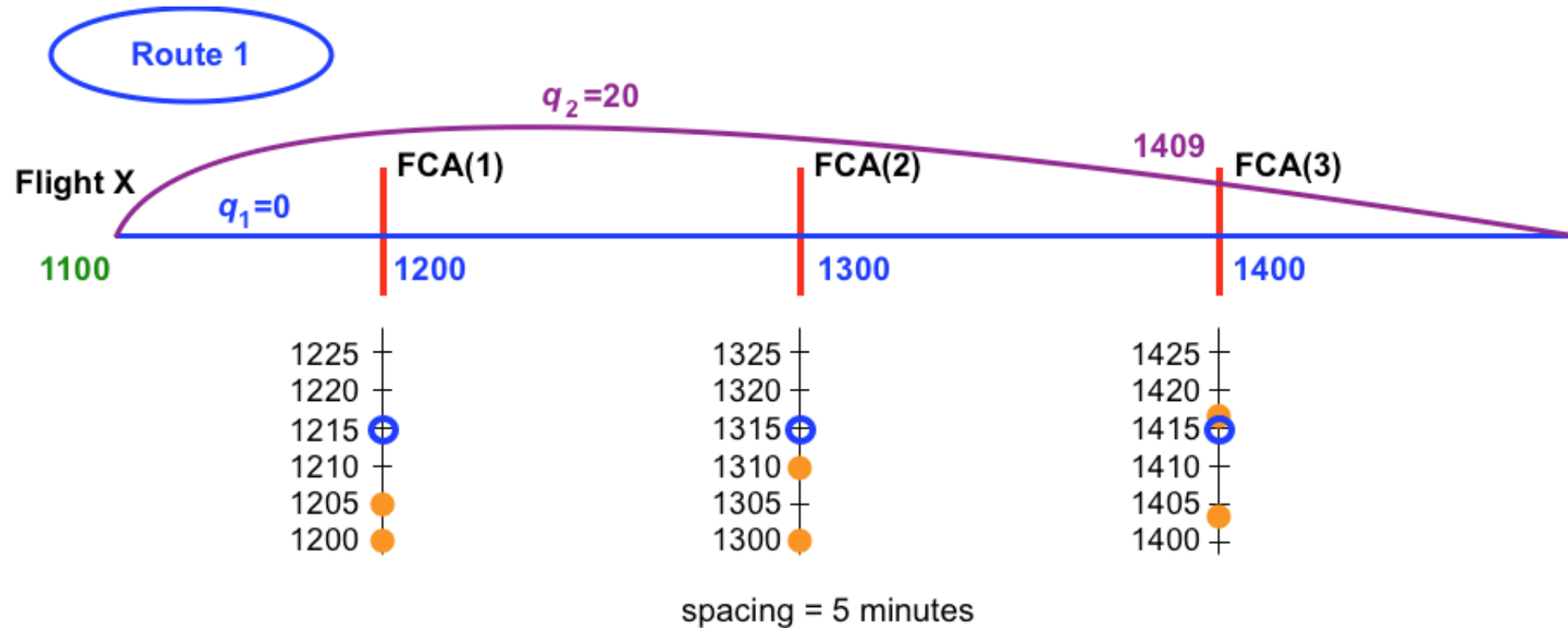
RBSall scheduling example



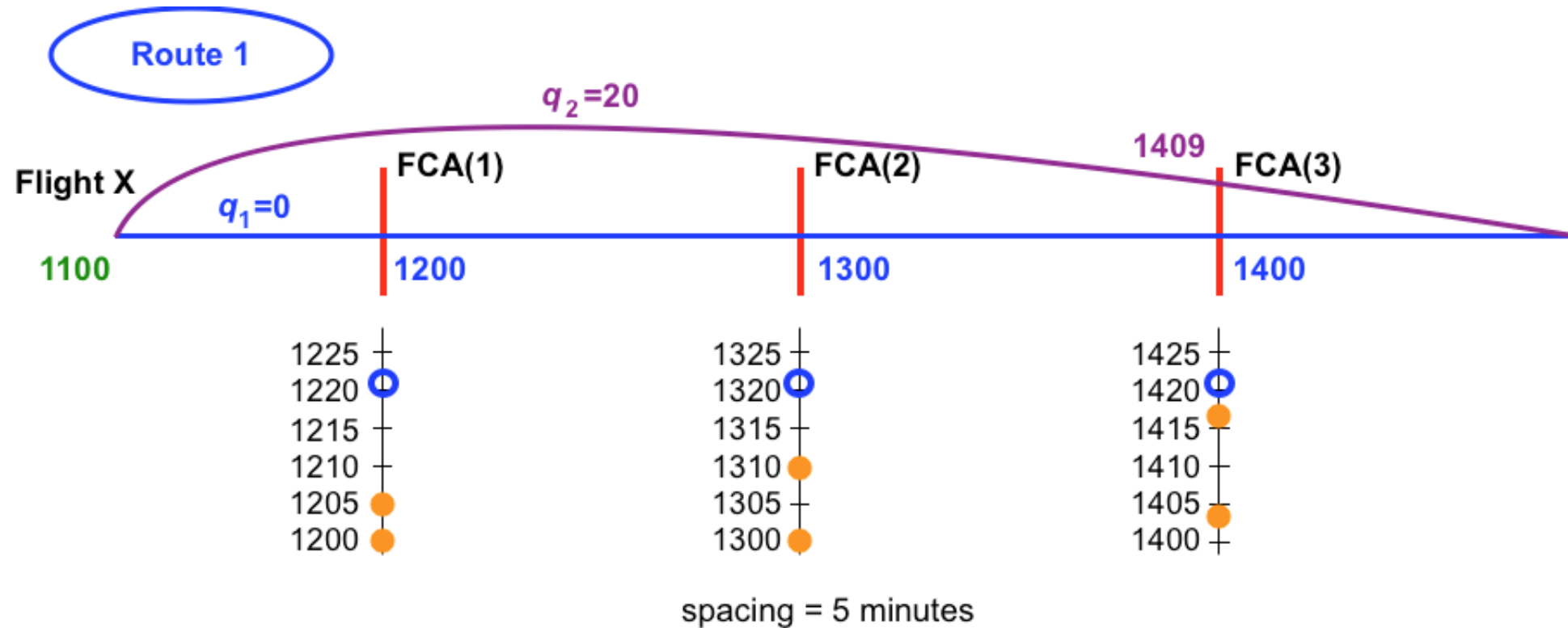
RBSall scheduling example



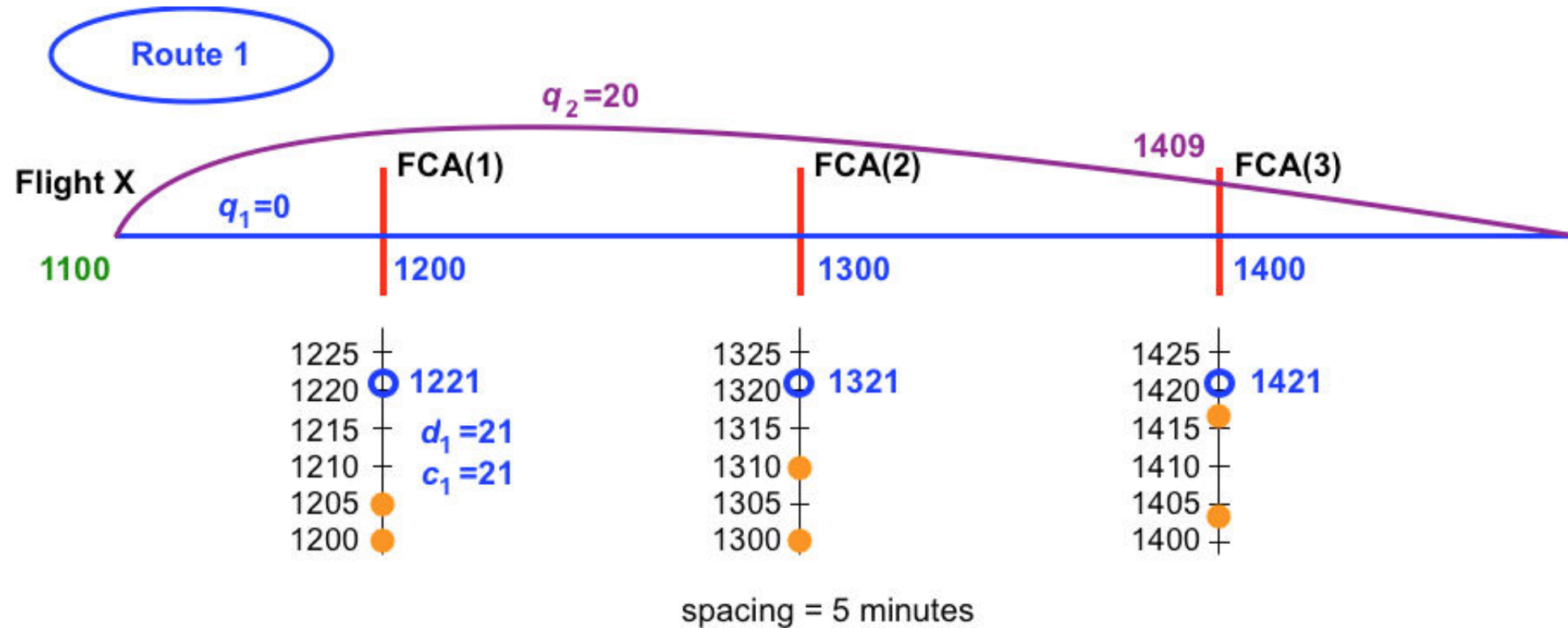
RBSall scheduling example



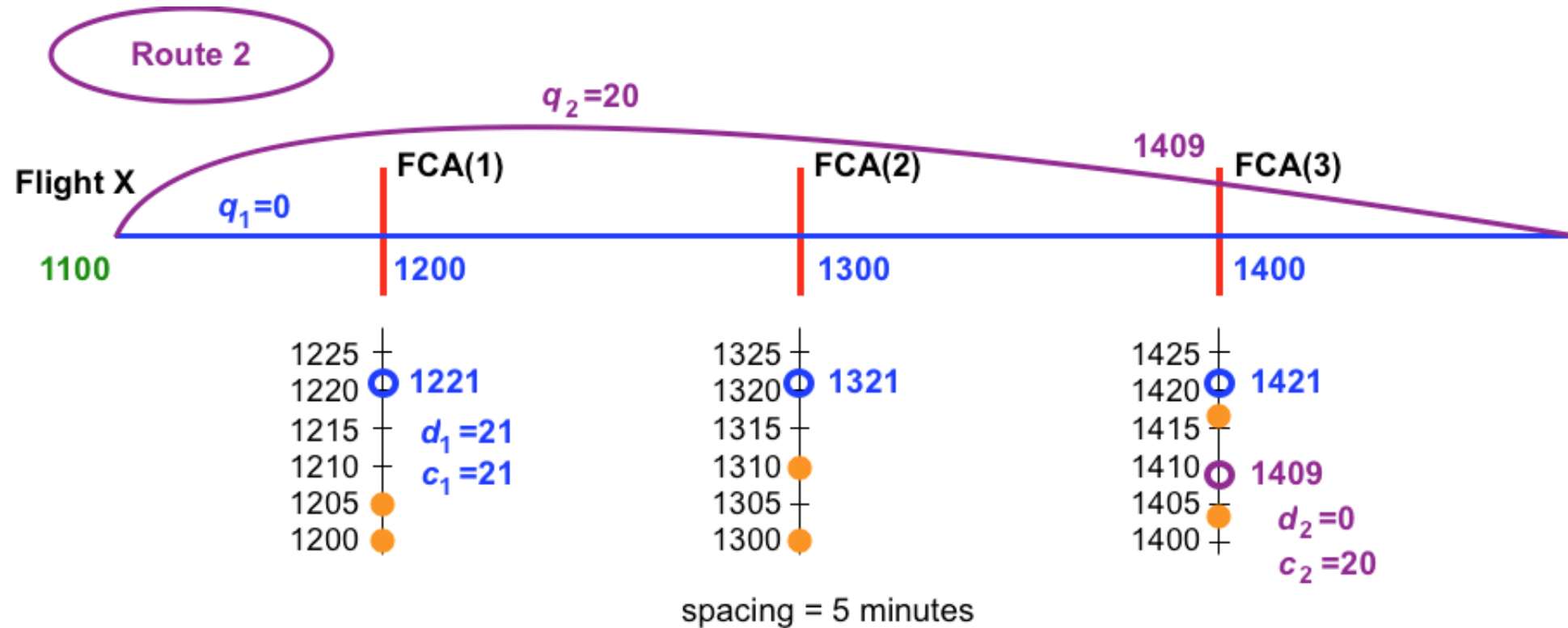
RBSall scheduling example



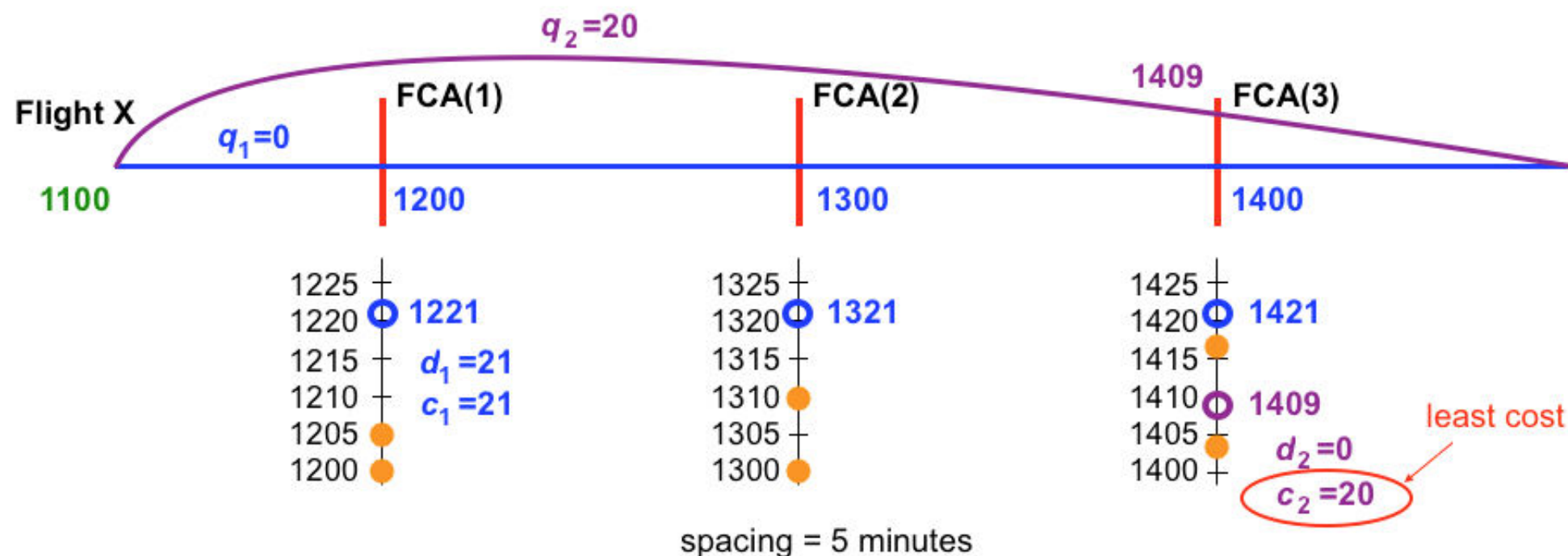
RBSall scheduling example



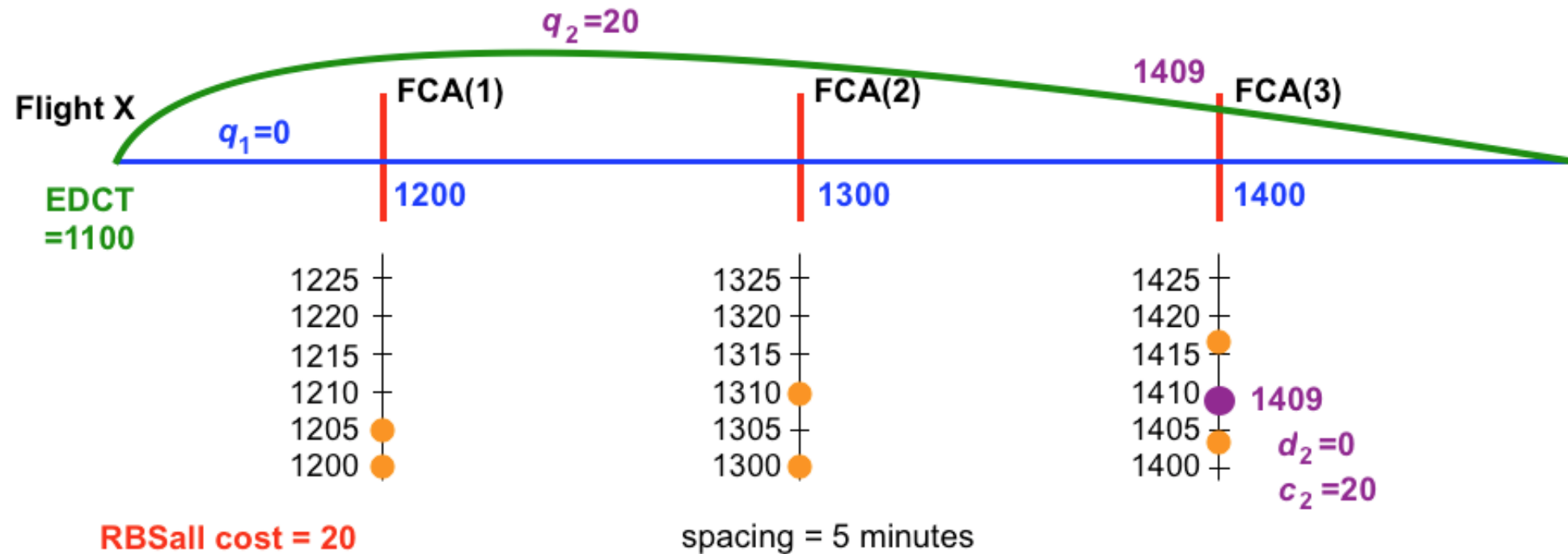
RBSall scheduling example



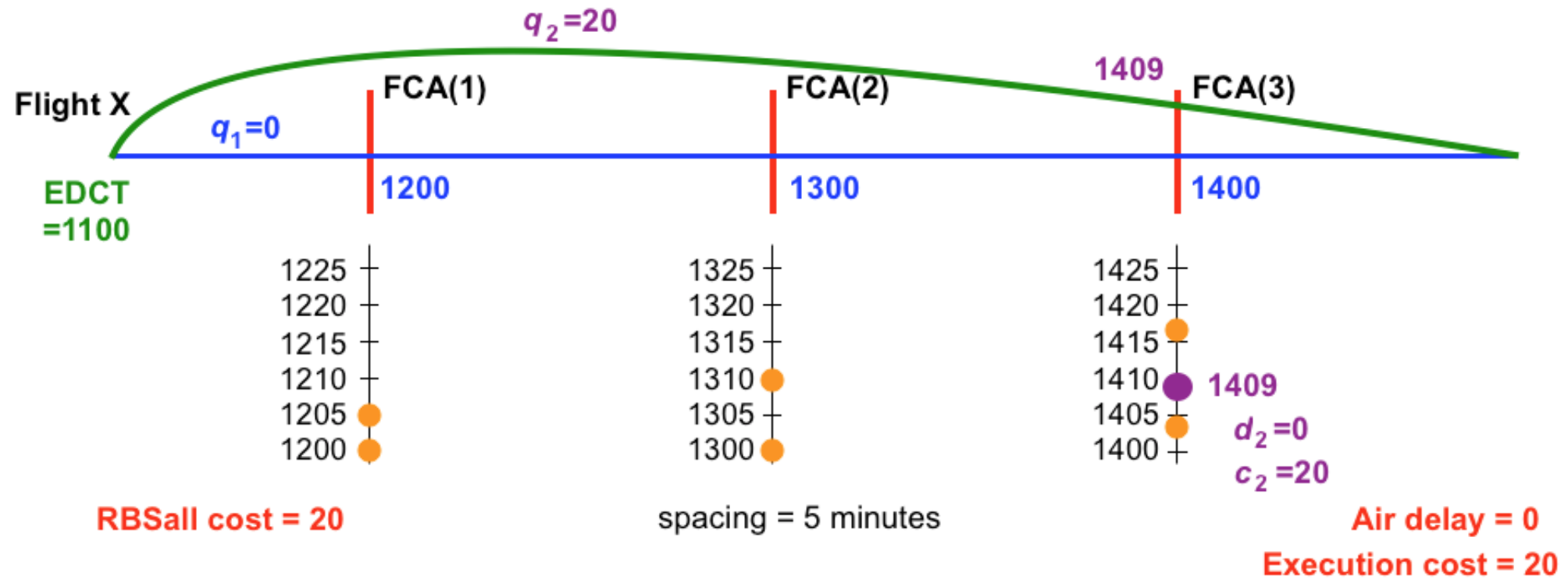
RBSall scheduling example



RBSall scheduling example



RBSall scheduling example



MILP formulation: full

$$\min_{\delta, d, a, y} \alpha \sum_{i=1}^N c_i + \omega y$$

$$\text{s.t. } c_i = \sum_{j=1}^{N_i} \left(\beta q_{ij} \delta_{ij} + d_{ij} + \gamma \sum_{h=2}^{H_{ij}} a_{ij}^{k_{ij}^h} \right)$$

$$d_{ij} + \sum_{h=2}^{H_{ij}} a_{ij}^{k_{ij}^h} \leq M \delta_{ij}$$

$$\tau_i^k = \sum_{j \in \Phi_i^k} \left(t_{ij}^k \delta_{ij} + d_{ij} + \sum_{m \in \Omega_{ij}; 2 \leq \text{id}(m) \leq \text{id}(k)} a_{ij}^m \right)$$

$$M v_{i,f}^k + \tau_i^k - \tau_f^k \geq \sum_{l=0}^{L^{k+1}} \frac{S^{k,l}}{2} (x_i^{k,l} + x_f^{k,l})$$

$$M(1 - v_{i,f}^k) + \tau_f^k - \tau_i^k \geq \sum_{l=0}^{L^{k+1}} \frac{S^{k,l}}{2} (x_i^{k,l} + x_f^{k,l})$$

$$y \geq \frac{1}{Nu} \sum_{i \in \Lambda^u} c_i$$

$$\sum_{j=1}^{N_i} \delta_{ij} = 1$$

$$\tau_i^k \geq \sum_{l=0}^{L^{k+1}} S^{k,l} x_i^{k,l}$$

$$\tau_i^k < \sum_{l=0}^{L^{k+1}} E^{k,l} x_i^{k,l}$$

$$\sum_{l=0}^{L^{k+1}} x_i^{k,l} \leq 1$$

$$y, d_{ij}, a_{ij}^k \geq 0$$

$$a_{ij}^k \leq A_{ij}^k$$

$$\delta_{ij}, x_i^{k,l}, v_{i,f}^k \in \{0,1\}$$

$$i = 1, \dots, N$$

$$j = 1, \dots, N_i$$

$$k = 1, \dots, Z$$

$$l = 0, \dots, L^k + 1$$