

Nonequilibrium Steady-State Fluctuations in Actively Cooled Resonators

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We analyze heat and work fluctuations in the gravitational wave detector AURIGA, modeled as a macroscopic electromechanical oscillator in contact with a thermostat and cooled by an active feedback system. The oscillator is driven to a steady state by the feedback cooling, equivalent to a viscous force. The experimentally measured fluctuations are in agreement with our theoretical analysis based on a stochastically driven Langevin system. The asymmetry of the fluctuations of the absorbed heat characterizes the oscillator's nonequilibrium steady state and reveals the extent to which a feedback cooled system departs from equilibrium in a statistical mechanics perspective.

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Cold-damping feedback efficiently reduces the thermal noise motion of an oscillator by applying a viscous force. Since its first application in electrometers [1], it succeeded in a wide variety of devices [2,3], from nano- to macroscopic resonators, and in a variety of implementations, including both optical and electrical forces. In basic research, cold damping is considered in order to reduce below the level of intrinsic quantum fluctuations the uncertainty due to thermal noise of the position of macroscopic bodies [4], and to improve the behavior of gravitational wave detectors [5]. In this Letter we experimentally investigate the fluctuations of thermodynamic quantities of a cold-damped electromechanical oscillator: the resonant-bar gravitational wave detector AURIGA [6]. In particular we verify that they are consistent with recent theories of nonequilibrium phenomena.

After the seminal works of Ref. [7], which introduced the fluctuation relation (FR) concerning the probability density function (PDF) of the entropy production rate in nonequilibrium systems, a large number of papers have been devoted to similar problems (see, for instance, Ref. [8] for a review). One finds that the FR for some properly identified observable (called dissipation function) is quite generally valid in systems of physical interest [9]. After the experimental evidence obtained for dragged colloidal particles [10], electrical circuits [11], and mechanical oscillators [12], the FR has become a standard tool to characterize nonequilibrium systems. Here, following Ref. [13], we focus on the FR for the PDF of the power necessary to maintain a dissipative system in a nonequilibrium steady state (NESS). A specific FR, obtained for the fluctuations of the injected power in a stochastically

driven Langevin system [14], was recently confirmed in a simple electrical realization of that model [15]. Actually, this FR accurately fits the fluctuations of the injected power in wave turbulence as well [16]. We also show that the AURIGA detector, which is maintained in a NESS by an external driving in a feedback cooling scheme, can be described as a mechanical oscillator forced by a stochastic driving. We then analyze its behavior and demonstrate that (a) the statistics of its thermodynamic variables show a characteristic asymmetry between positive and negative fluctuations and (b) the statistics of the injected power are in agreement with the FR of Ref. [14]. These results reveal the extent to which a feedback cooled system departs from equilibrium in a statistical mechanics perspective and prove the limits of usual assumption that cold-damped oscillators at temperature T_0 are equivalent to higher-loss ones, in thermodynamic equilibrium at a temperature $T_{\text{eff}} < T_0$.

AURIGA is based on a 2.2×10^3 kg, 3 m long bar made of a low-loss aluminum alloy (Al5056), cooled to liquid helium temperature $T_0 = (4.6 \pm 0.2)$ K. The fundamental longitudinal mode of the bar, sensitive to gravitational waves, has effective mass $M = 1.1 \times 10^3$ kg and resonance frequency $\omega_0/2\pi \sim 900$ Hz. The bar resonator motion is detected by a capacitive transducer followed by a double stage dc-SQUID amplifier; the displacement sensitivity is about 5×10^{-20} m/ $\sqrt{\text{Hz}}$ over a ~ 100 Hz bandwidth around ω_0 , largely limited by thermal noise. The detector can be modeled by three coupled low-loss resonators: two mechanical ones (the bar and a plate of the capacitive transducer) and an LC electrical one [17,18]. The dynamics is described by three normal modes at

separate frequencies, 865.7, 914, 953 Hz, with quality factors, respectively, of 1.2×10^6 , 0.88×10^6 , 0.77×10^6 , determined by mechanical losses in the bar and the transducer and by dielectric losses in the electrical components. Each mode is modeled as a series-RLC electrical oscillator with an effective inductance L , capacitance C , and resistance R , which assume different values for the 3 oscillators (Fig. 1). These modes are electromechanical rather than purely mechanical, but each one collects a significant fraction of the energy of the two mechanical resonators. From the detector calibration we estimate that the energy injected by an impulsive excitation of the longitudinal mode of the bar is shared by the 3 modes in the ratio 48:36:16.

For the sole purpose of improving the electronics stability and easing the data analysis, AURIGA employs an electronic feedback cooling scheme on the detector (Fig. 1), which is equivalent to a viscous force on the oscillators [19]. The dynamics of each electromechanical oscillator is described by the equations

$$(L - L_{\text{in}}) \frac{d^2 q(t)}{dt^2} + R \frac{dq(t)}{dt} + \frac{q(t)}{C} = V_T(t) - V_d(t), \quad (1a)$$

$$V_d(t) = L_{\text{in}} \frac{dI_s(t)}{dt}, \quad (1b)$$

$$I(t) + I_d(t) = I_s(t), \quad (1c)$$

where the current I_s is the observable, q is the charge on the capacitor, $I = \frac{dq(t)}{dt}$ the current through the inductance L , V_d is the voltage at the node where the feedback is applied, and L_{in} is the input inductance of the SQUID amplifier. In thermodynamic equilibrium, each oscillator is driven by the stochastic voltage: $V_T(t) = \sqrt{2k_B T_0 R} \Gamma(t)$, where Γ is a Gaussian white process. This should hold even in our nonequilibrium case, since the feedback cooling concerns only 3 modes, out of the very many degrees of freedom of the thermal bath, and is not expected to significantly affect the thermal noise due to the bath. The noise due to the SQUID can be neglected at moderate feedback gains, as

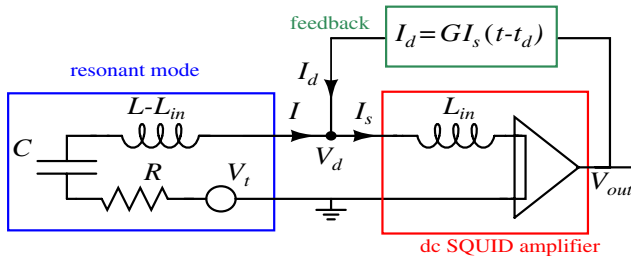


FIG. 1 (color online). The normal mode is approximated, around its resonance frequency, by a series-RLC circuit. The dc SQUID is represented as a current amplifier. The observable is the current I_s , and the electronic feedback cooling is obtained by sending back a current I_d which is a delayed copy of I_s reduced by $G \ll 1$. The SQUID output voltage is $V_{\text{out}} = A I_s$ with $A = 2.6 \times 10^6 \Omega$.

those used in this experiment. The very high quality factor of the oscillators implies that the currents I_s , I_d , and I oscillate at $\omega_r = 1/\sqrt{LC}$ with amplitude and phase changing appreciable only on time scales of several cycles. Thus, the quasiharmonic approximation $I(t) = \hat{I}(t) \times \sin[\omega_r t + \hat{\phi}(t)]$, like the analogous ones for I_s and I_d , seems appropriate. Operatively this is implemented by considering the signal only in a narrow frequency band around ω_r . Near resonance, a feedback force equivalent to a viscous damping can be obtained with the feedback current

$$I_d(t) = G I_s(t - t_d), \quad (2)$$

where $t_d = \frac{\pi}{2\omega_r}$ and $G \ll 1$. Equation (1b) includes memory effects due to contributions from times $t - t_d$, because of the constraints (1c) and (2); in the quasiharmonic approximation we have $I_s(t - t_d) \simeq \omega_r q_s(t)$. Hence each oscillator obeys

$$L \frac{dI_s(t)}{dt} + I_s(t)[R + R_d] + \frac{q_s(t)}{C} = \sqrt{2k_B T_0 R} \Gamma(t) \quad (3)$$

with $I_s(t) = \frac{dq_s(t)}{dt}$. Here $R_d = G \omega_r L_{\text{in}}$ expresses the viscous damping on the oscillator due to the feedback loop; the feedback efficiency is defined as $g = R_d/R$. The quasiharmonic approximation is valid as long as the feedback damped oscillator is still a low-loss one. In Eq. (3) the driving is the same white process of Eq. (1): this is confirmed experimentally by the Lorentz-shaped power spectrum of the current I_s around the resonance [19]. Equation (3) is not invariant under time reversal ($q'_s = q_s$, $I'_s = -I_s$, $t' = -t$) and does not satisfy the Einstein relation. Nevertheless, it is formally identical to that describing an oscillator with damping $R + R_d$, in equilibrium at the fictitious “effective temperature” $T_{\text{eff}} = T_0/(1 + g)$. The discrepancy between T_{eff} and the thermal bath temperature T_0 reveals the nonequilibrium nature of the phenomenon. Hence, the feedback cooled oscillator is usually treated as an equilibrium system, with T_{eff} derived from the experimental value of $\langle \hat{I}_s^2(t) \rangle = 2 \frac{k_B T_{\text{eff}}}{L}$, even if no bath at T_{eff} is present.

Multiplying Eq. (3) by $I_s(t)$ and integrating between t and $t + \tau$, in the quasiharmonic approximation we get an expression for the average power $P_\tau = \frac{1}{\tau} \times \int_t^{t+\tau} I_s(t') V_T(t') dt'$ injected by the stochastic thermal force during a time τ :

$$P_\tau = \Delta U_\tau + \frac{R + R_d}{\tau} \int_t^{t+\tau} I_s^2(t') dt', \quad (4)$$

where $\Delta U_\tau = \frac{U(t+\tau) - U(t)}{\tau}$, $U(t)$ being the stored energy

$$U(t) = \frac{1}{2} L I_s^2(t) + \frac{1}{2} \frac{q_s^2(t)}{C} = \frac{1}{2} L \hat{I}_s^2(t). \quad (5)$$

The term proportional to R represents the heat dissipated by the oscillator toward the bath, while that proportional to

R_d is the work done by the oscillator on the feedback:

$$W_\tau = -\frac{1}{\tau} \int_t^{t+\tau} I_d(t') V_d(t') dt' = \frac{R_d}{\tau} \int_t^{t+\tau} I_s^2(t') dt'. \quad (6)$$

Notice that the last identity is strictly valid only within the quasiharmonic approximation, which relates both $I_s(t - t_d)$ and $dI_s(t)/dt$ to the instantaneous current $I_s(t)$. Further, if $\tau = N \frac{2\pi}{\omega_r}$, N integer, in the same approximation we can also write

$$W_\tau = \frac{1}{\tau} \frac{R_d}{2} \int_t^{t+\tau} \hat{I}_s^2(t') dt'. \quad (7)$$

By energy conservation we obtain the heat Q_τ , absorbed by the oscillator from the bath and averaged in a time τ :

$$Q_\tau = \Delta U_\tau + W_\tau. \quad (8)$$

To study nonequilibrium properties, we focused on the lowest frequency mode out of the three, which is well separated in frequency from the other two and is thus our best approximation of a single oscillator. The sampled current $I_s(t)$ was processed via the AURIGA data analy-

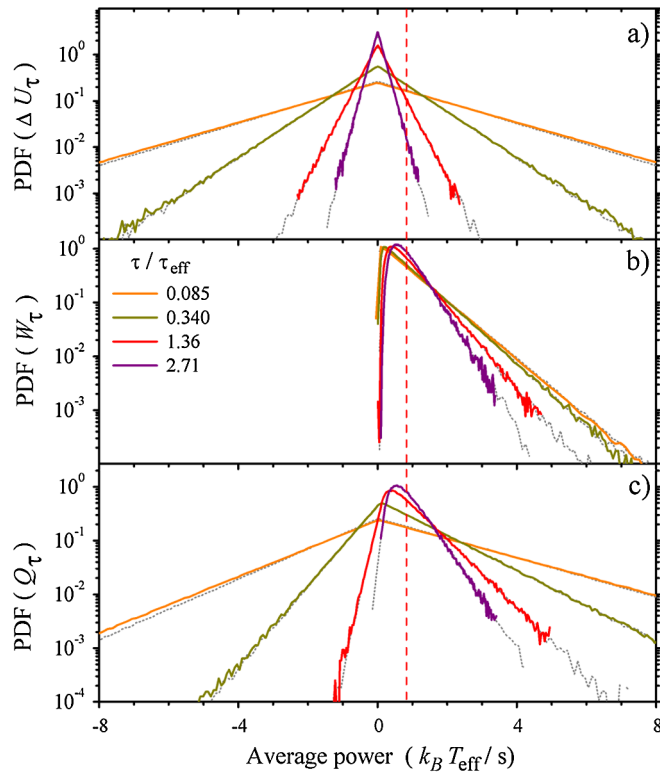


FIG. 2 (color online). PDF [units of $s/(k_B T_{\text{eff}})$] of (a) the time averaged energy difference ΔU_τ , (b) the work W_τ , and (c) the heat Q_τ averaged at increasing values of the ratio τ/τ_{eff} . Data were collected by AURIGA in a 10 day time span. The dashed vertical line at $0.84 k_B T_{\text{eff}}/s$ corresponds to the mean value of W_τ . The dotted lines are obtained by numerical simulation of Eq. (3) for a 50 day time span. The discrepancies observed at short τ between experimental and numerical data are within the uncertainty due to the experimental error in τ_{eff} .

sis and integrated over the resonance in a 10 Hz bandwidth to obtain the current amplitude $\hat{I}_s(t)$ in the harmonic approximation. From dedicated calibration of AURIGA we measure $L = (1.67 \pm 0.01) \times 10^{-4}$ H and $L_{\text{in}} = (1.48 \pm 0.01) \times 10^{-6}$ H. A first set of data covers a continuous 10 day time span in March 2008. The data yield $\omega_r/2\pi = 865.7$ Hz, $T_{\text{eff}} = (21.1 \pm 0.2)$ mK, and decay time $\tau_{\text{eff}} = (2.36 \pm 0.04)$ s; hence we estimate $g = 207 \pm 10$, $R = (6.8 \pm 0.5) \times 10^{-7} \Omega$, and $G = (1.74 \pm 0.06) \times 10^{-2}$. The quality factor $\omega_r \tau_{\text{eff}}/2 \simeq 6.5 \times 10^3$ is high enough to justify the quasiharmonic approximation leading to Eq. (3). Figures 2(a) and 2(b) show the PDF of the energy difference ΔU_τ and of the work done by the oscillator W_τ averaged over growing times τ : they are calculated from Eqs. (5) and (7) after dividing the experimental data in contiguous time intervals of duration τ . Figure 2(c) shows the corresponding heat Q_τ exchanged by the oscillator with the bath averaged over the time τ , computed via the energy conservation of Eq. (8). The fluctuations of Q_τ are asymmetric, as expected for a NESS. Figure 2 also shows excellent agreement with numerical simulations of Eq. (3).

The PDF of ΔU_τ is symmetric with respect to zero, as for an equilibrium oscillator. It has exponential tails which decay faster for longer τ . The PDF of W_τ is highly asymmetric. From Eq. (7) and $\langle \hat{I}_s^2(t) \rangle = 2k_B T_{\text{eff}}/L$ we infer that W_τ is positive and has mean value $\simeq 0.84 k_B T_{\text{eff}}/s$. Hence, Q_τ takes negative values only for short integration times, with the characteristic time scale given by the cold-damped oscillator decay time $\tau_{\text{eff}} = 2L/(R + R_d)$. For $\tau \gg \tau_{\text{eff}}$ the contribution of the time averaged energy is negligible. So in the presence of feedback ($R_d > 0$) there is a net heat transfer from bath to oscillator: this is the energy flux that feeds the NESS and makes the PDF of the heat asymmetric. On the contrary, if the feedback were switched off, we would have $R_d = 0$ and $W_\tau = 0$; hence $Q_\tau = \Delta U_\tau$ from Eq. (8). In this case the PDF of Q_τ would be symmetric with respect to its (zero) mean value, as in Fig. 2(a), but with $T_{\text{eff}} = T_0$.

The PDF of the injected power P_τ is essentially identical to that of Q_τ , shown in Fig. 2(c), since $P_\tau \approx Q_\tau$ when $g \gg 1$. Notice that of the two terms in Eq. (4), only ΔU_τ is responsible for the negative values of P_τ . Thus, large positive values of P_τ are dominated by the contribution of the dissipated power [the integral in (4)] more than they are for small values of P_τ . The transition between these two regimes affects the shape of the PDF, which has been calculated in Ref. [14]. In a limit of large integration times it obeys

$$f(\tilde{\epsilon}_\tau) \equiv \lim_{\tau \rightarrow \infty} \frac{\ln \text{PDF}(\tilde{\epsilon}_\tau)}{\tau} = \begin{cases} -\gamma(1 - 2\tilde{\epsilon}_\tau) & \text{if } \tilde{\epsilon}_\tau \leq \frac{1}{3} \\ -\frac{\gamma}{4\tilde{\epsilon}_\tau}(\tilde{\epsilon}_\tau - 1)^2 & \text{if } \tilde{\epsilon}_\tau \geq \frac{1}{3}, \end{cases} \quad (9)$$

where $\tilde{\epsilon}_\tau = P_\tau L/(k_B T_0 R)$ is the reduced injected power and $\gamma = (R + R_d)/L = 2/\tau_{\text{eff}}$. A remarkable singularity, located at $\tilde{\epsilon}_\tau = 1/3$, is present in the second derivative

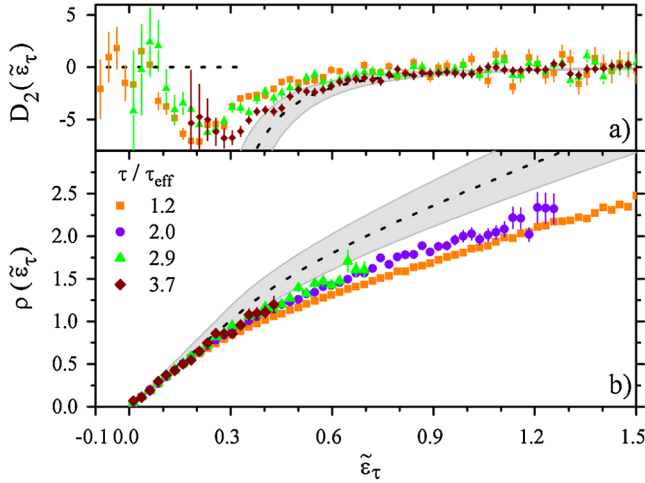


FIG. 3 (color online). Comparison between theory (dashed lines) and experimental data at increasing values of the ratio $\tau/\tau_{\text{eff}} = 1.2, 2.0, 2.9, 3.7$: the data set is, respectively, 828, 768, 729, 457 days long. (a) Plot of second derivative $D_2(\tilde{\epsilon}_\tau)$; the experimental data of D_2 for $\tau/\tau_{\text{eff}} = 2.0$ are not shown for clarity. (b) Plot of $\rho(\tilde{\epsilon}_\tau)$. Vertical error bars on experimental points of both plots come from statistical uncertainty. The shaded areas on the theoretical curves represent the uncertainty due to the experimental errors on the parameters, τ_{eff} , T_{eff} , and T_0 .

of $f(\tilde{\epsilon}_\tau)$. In Fig. 3(a) we plot the quantity $D_2(\tilde{\epsilon}_\tau) \equiv \partial^2 f(\tilde{\epsilon}_\tau)/\partial \tilde{\epsilon}_\tau^2$ evaluated from the output of AURIGA in the time span May 2005–May 2008; here $T_{\text{eff}} = (22 \pm 1)$ mK and $\tau_{\text{eff}} = (2.4 \pm 0.2)$ s. A valley is clearly visible in the experimental data, which we interpret as a precursor of the asymptotic singularity. The agreement with the asymptotic theory consistently improves as τ/τ_{eff} grows. This indicates that the asymptotic relation of Eq. (9) holds even in the presence of a harmonic pinning potential [14].

Equation (9) easily leads to the FR for the injected power, i.e., to the ratio between the probability of positive and negative fluctuations of $\tilde{\epsilon}_\tau$. If we define $\rho(\tilde{\epsilon}_\tau) = \lim_{\tau \rightarrow \infty} \frac{1}{\tau} \ln \frac{\text{PDF}(\tilde{\epsilon}_\tau)}{\text{PDF}(-\tilde{\epsilon}_\tau)}$, we have

$$\rho(\tilde{\epsilon}_\tau) = \begin{cases} 4\gamma\tilde{\epsilon}_\tau, & \text{if } \tilde{\epsilon}_\tau < \frac{1}{3}; \\ \gamma\tilde{\epsilon}_\tau\left(\frac{7}{4} + \frac{3}{2\tilde{\epsilon}_\tau} - \frac{1}{4\tilde{\epsilon}_\tau^2}\right), & \text{if } \tilde{\epsilon}_\tau \geq \frac{1}{3}. \end{cases} \quad (10)$$

As shown in Fig. 3(b), positive values of $\tilde{\epsilon}_\tau$ are exponentially more probable than negative ones. Two conflicting features determine the details of the experimental curves: the agreement with the asymptotic theory improves with τ/τ_{eff} , but the statistics blur at large values of $\tilde{\epsilon}_\tau$ since negative events are rarer. For this reason a slope change is clearly seen for small values of τ/τ_{eff} where the precursor of the singularity occurs as shown in Fig. 3(a), while it becomes barely visible at longer integration times.

In conclusion, we demonstrate that the actively cooled AURIGA detector is well described by the Langevin model of Eq. (3), which led us to evaluate the power P_τ injected by the stochastic thermal force, the work W_τ done on the feedback, and the heat Q_τ exchanged with the thermal bath. The statistics of P_τ are consistent with Eq. (9), and with the consequent nonlinearity of the FR. The fluctuations of Q_τ are asymmetric as expected for a NESS.

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