Physics-Based Simulation Techniques for Smalland Large-Signal Device Noise Analysis in RF Applications

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Invited Paper

Abstract—The paper presents a review on physics-based noise simulation techniques for RF semiconductor devices, starting with the small-signal case but with greater stress on noise in large-signal (quasi)-periodic operation. The nonautonomous (forced) operation case will be considered, which is relevant to all RF applications apart from oscillators. Besides their importance in device design, physics-based noise models can also suggest viable and correct strategies to implement circuit-oriented models, e.g., compact models. From this standpoint, the connection between physics-based and circuit-oriented modeling will be discussed both in the small-signal and in the large-signal case, with particular stress on the treatment of colored noise in the large-signal periodic regime.

Index Terms—Circuit modeling, circuit noise, semiconductor device modeling, semiconductor device noise.

I. INTRODUCTION

DURING the last few years, dramatic progress has been made in CAD tools for the noise analysis of RF and microwave analog circuits. Noise simulation, formerly limited to linear circuits, was extended to the less widely understood large-signal regime, with direct application to analog RF subsystems such as mixers and frequency multipliers. However, progress in circuit simulation tools was not entirely paralleled in the development of device noise models, although the final result of the noise simulation is as good as the noise models implemented in the simulator. In many modeling areas involving noise operation, controversial points remain.

A first example concerning the apparently well-established field of small-signal noise modeling is the quest for a satisfactory compact MOS noise model relating in a simple way the device noise performances to physical and technological parameters. In a sense, compact noise FET models could be bypassed

Manuscript received May 24, 2002; revised October 1, 2002. This work was supported in part by the Center of Excellence on Multimedia Radiocommunications (CERCOM) of Politecnico di Torino and by the Italian Ministry of Research (MIUR) through the COFIN 2000 project, and of the "Progetto giovani ricercatori" of Politecnico di Torino. The review of this paper was arranged by Editor D. B. M. Klaassen.

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Digital Object Identifier 10.1109/TED.2003.810477

in circuit design, since measurement-based, partly empirical approaches developed in the field of microwave FETs (see e.g., [1], [2]) have been proposed since the late seventies on the assumption that the short-channel FET physics is too complex to make a real, analytical compact model worth developing: such models have been successfully applied to MOSFETs, e.g., in [3]. On the other hand, although the search for predictive compact MOS noise models has led to a great deal of work in the RF community, in many circuit simulators the actual device models available are legacy ones, sometimes even hardly correct (e.g., only valid for long-channel devices [4]).

A second example is a comparative lack of deep understanding of some of the device noise properties in the largesignal regime. Since the pioneering paper of Dragone [5], it has been more or less widely understood that fast noise mechanisms (i.e., those characterized by a white spectrum in small-signal operation) are modulated, in large-signal conditions, by the instantaneous working point. Such a modulation enables to extract, somewhat empirically, from the small-signal power spectrum the statistical information on the frequency-converted large-signal noise (i.e., the so-called sideband correlation matrix). Unfortunately, in many circuits the most important noise mechanisms are those leading, in small-signal operation, to a colored (e.g., 1/f) spectrum. Several approaches have been proposed to model the frequency conversion of such slow fluctuations [6], [7], but a satisfactory solution has not been found yet. Thus, it is not well understood at present up to which extent an accurate large-signal noise device model can be extracted from information (also experimental) on small-signal

Physics-based numerical noise simulation can give, in the long term, a satisfactory answer to many noise modeling problems encountered in RF and microwave analog circuit design. First, a noise simulator based on the numerical solution of a transport model rather than on approximate analytical approaches makes available a direct link between the device technology and its noise behavior. This is particularly true in small-signal noise analysis, which can be performed independently of the embedding circuit so as to directly evaluate the device noise parameters as a function of frequency. However, physics-based noise analysis can also be exploited as a direct

way to test large-signal circuit-oriented noise models from the standpoint of structure and consistency, thus providing a manageable test set whereon virtual measurements can be readily made.

The aim of the present paper is to provide a comprehensive review of physics-based noise simulation of RF and microwave devices both in the linear and nonlinear (large-signal) regime. The analysis will be confined to nonautonomous (i.e., forced) device operation, thus excluding from the treatment the oscillator case, which still is a matter of advanced research [8]. As in many other fields, also in noise simulation the whole development of the underlying physical theory was largely complete well before numerical noise simulations were attempted. Noise simulation in an engineering sense was perhaps founded by the paper of Shockley et al. of 1966 [9], which established as a viable analysis tool the so-called impedance field method, basically a Green's function technique describing the device noise as the superposition of microscopic fluctuations properly propagated to the device terminals. The impedance field method and related techniques were widely exploited for the small-signal noise analysis of the most important classes of devices, above all bipolar, see, e.g., the papers by Van Vliet et al. [10]-[12]. Despite the several quasi-two-dimensional implementations of the IFM, the first full two-dimensional (2-D) physics-based numerical noise model was presented only in 1989 by Filicori and Ghione [13], [14] and was extended to the bipolar case by Bonani et al. [15], who also developed the first large-signal noise analysis in the quasi-periodic regime [16]. Small- and largesignal physics-based FET noise analyses based on the so-called active line quasi-2-D approach were successfully developed by the University of Lille (IEMN) group (see [17], [18] and references therein).

Although the small-signal noise analysis has been recently implemented in a few commercial device simulators (e.g., Integrated Systems Engineering DESSIS [19], Avant! Corp. Taurus-Device [20]), large-signal noise simulation, which requires one to analyze the active device together with the embedding circuit, still is a matter of research: both time- and frequency-domain, namely Harmonic Balance, methods are in principle feasible, but up to now frequency-domain techniques only have been proposed due to their efficiency in device analysis and to the fact that they are a direct extension of the small-signal treatment. Moreover, it should be stressed that numerical noise analysis, already at the small-signal level, can show unexpected complexities in seemingly well-known cases; as an example, see the GR noise in short uniform samples [21] or the thermal noise in low-doping resistor (see [22, ch. 4]). While many of the phenomena numerical simulation can help in unveiling were already known, at least at a qualitative level, the availability of this new tool has greatly widened the opportunities for analysis and understanding of the noise behavior. This is even more true in large-signal noise analysis, where careful interpretation of the frequency conversion of slow fluctuations can also lead to a better insight into the possible structure of compact noise models.

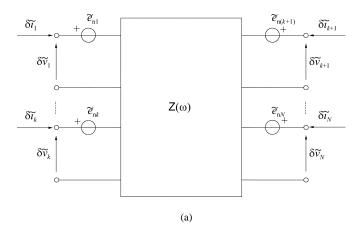
The paper is organized as follows. Section II is devoted to the circuit representation of noisy devices, both in small-signal and large-signal forced regime. In Section III the available approaches for physics-based noise analysis, again in linearity and for large-signal excitations, are briefly reviewed, with particular emphasis on frequency-domain Green's function-based approaches. A discussion on the application of physics-based simulation to the development and validation of circuit-oriented noise models is developed in Section IV, again with a greater emphasis on the large signal case. Finally, conclusions are summarized in Section V.

II. CIRCUIT REPRESENTATION OF NOISY DEVICES

The occurrence of noise, in the form of *fluctuations* of the electrical variables at the terminals of any device, is an unavoidable feature strictly related to carrier transport in semiconductors. From a circuit perspective, the customary representation is based on the assumption that fluctuations cause a perturbation of the electrical device working point and that, therefore, noise can be interpreted as a small-amplitude random signal superimposed to the currents and voltages at the device ports. In other words, noise is represented as a set of impressed (voltage or current) electrical sources connected to the device terminals, namely the device noise generators, which are described through zero-average stochastic processes. Since, at a circuit level, the physically meaningful quantity is the noise power exchanged, the noise generators are usually characterized by their second-order statistical properties: these are sufficient to derive system-oriented parameters, such as the noise figure for a two-port device [22].

From a circuit standpoint, the representation of noise depends on device operation that also influences the statistical properties of the stochastic processes describing fluctuations. In this paper, we shall consider only the case of forced operation; this basically covers all of the main applications, with the important exclusion of autonomous systems, i.e., oscillators. We shall consider separately two cases: 1) the small-signal (SS) regime, occurring if the forcing term is made of the superposition of a continuous bias (DC) and of a small-amplitude time-varying term and 2) the large-signal, (quasi-)periodic (LS) regime, corresponding to a device excitation made of (quasi-)periodically time-varying signals. The steady-state working point in LS operation is again (quasi-)periodically time-varying, though the nonlinear behavior of the device (and of other nonlinear circuit elements, if any) results in the generation of frequency components at all of the linear combinations (with integer coefficients) of the input frequencies: such components will be denoted as harmonics. Once the noise generators have been characterized, they can be implemented into circuit simulators in order to perform system-level noise estimations: as a matter of fact, almost all commercial simulators now allow, either in the time or frequency domain, for noise analysis, in some cases both in SS and LS conditions. Representative examples are SPICE [23], [24], Agilent ADS (Advanced Design System) [25], Cadence Design Systems SpectreRF [26], AWR Microwave Office [27], and Avista Design Systems SP/XL-RF [28]. A recent review on circuit CAD tools for RF applications can be found in [29].

¹These correspond, for strictly periodic operation, to integer multiple frequencies of the fundamental, while in quasi-periodic conditions the intermodulation products are also taken into consideration.



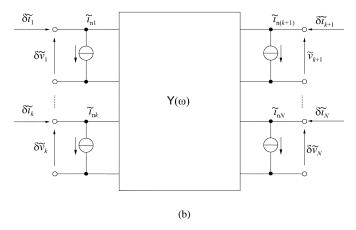


Fig. 1. Equivalent circuit of a noisy N-port device in SS operation: (a) series and (b) parallel representation.

A. SS Operation

In the simple case of SS operating regime, the N-port device is represented as a linear N-port whose port voltages $\delta \boldsymbol{v}(t)$ and currents $\delta \boldsymbol{i}(t)$ are the (small-change) variations of the corresponding total variables with respect to the dc working point. With $\boldsymbol{e}_{\mathrm{n}}(t)$ being the vector of open circuit noise voltage generators at the N ports, such stochastic processes are *stationary* [22] and therefore are completely characterized in the frequency domain by the corresponding *correlation matrix* $\mathbf{S}_{\mathbf{e}_{\mathrm{n}},\,\mathbf{e}_{\mathrm{n}}}(\omega)$ (ω is the angular frequency). This implicitly assumes that the linearized device can be represented by a small-signal impedance matrix $\mathbf{Z}(\omega)$, thus leading to the series representation shown in Fig. 1(a) as

$$\delta \tilde{\boldsymbol{v}}(\omega) = Z(\omega) \cdot \delta \tilde{\boldsymbol{z}}(\omega) + \tilde{\boldsymbol{e}}_{n}$$
 (1a)

where the Fourier transformation of the time-domain signal x(t) is denoted as $\tilde{x}(\omega)$, and we have assumed to Fourier-transform even the noise generators, although this is a mathematically critical procedure [30] based on the hypothesis that the dc working point is a stable equilibrium of the dynamic model with respect to small variations.

With the assumption that the linearized device admits an admittance matrix representation, noise can be equivalently de-

scribed by the vector $\dot{\mathbf{i}}_{n}(t)$ of short circuit noise current generators, leading to the parallel description [see Fig. 1(b)]

$$\delta \tilde{\mathbf{i}}(\omega) = \mathbf{Y}(\omega) \cdot \delta \tilde{\mathbf{v}}(\omega) + \tilde{\mathbf{i}}_{\mathbf{n}}$$
 (1b)

where $Y = Z^{-1}$ and

$$\tilde{\boldsymbol{i}}_{n} = \mathbf{Y}(\omega) \cdot \tilde{\boldsymbol{e}}_{n}.$$
 (2)

Equation (2) shows that the series and parallel noise representations are equivalent and that

$$S_{\boldsymbol{e}_{n},\boldsymbol{e}_{n}}(\omega) = Z(\omega) \cdot S_{\boldsymbol{i}_{n},\boldsymbol{i}_{n}}(\omega) \cdot Z^{\dagger}(\omega)$$
 (3a)

$$\mathbf{S}_{i_{n},i_{n}}(\omega) = \mathbf{Y}(\omega) \cdot \mathbf{S}_{e_{n},e_{n}}(\omega) \cdot \mathbf{Y}^{\dagger}(\omega)$$
 (3b)

where † denotes Hermitian conjugation.

From the standpoint of circuit simulations, noise analysis is a simple small-signal analysis which takes as inputs the noise generators, whose power and correlation spectra are assumed to be known as a function of frequency. The output is the correlation matrix for the equivalent noise generators at the outer ports of the whole circuit (see e.g., [31]): several techniques are available to perform such calculations [32], [33], which laid the basis for efficient numerical physics-based noise analysis [22]. Circuit oriented models can be exploited to describe the correlation spectra of the noise generators as a function of the device dc operating point: some of them have, to various degrees of approximation, a connection to the physical device structure (the so-called *compact models*, see, e.g., [34]), others are based on experimental results only, e.g., the Pospieszalski two-temperature model [1], originally devised for noise analysis of microwave FETs, and the so-called PRC model [2], [35]: see [36] for a comparison with reference to microwave FETs. In any case, linear RF applications mostly deal with white noise spectra (thermal and shot noise), while in low-frequency operation colored noise becomes important, in particular generation-recombination (GR) and 1/f noise. Notice, however, that linear filtering of white noise through circuit transfer functions can give a colored nature to the output noise generators, e.g., even for a simple RC low-pass filter the white thermal noise of the resistance may result in colored fluctuations on the load.

B. LS Operation

Operating the device under quasi-periodic large-signal conditions means that a periodic forcing signal is applied to at least one of the device ports, thus making quasi-periodic in time, in steady-state conditions, all of the device electrical (port voltages and currents) and physical (carrier densities and electric field) variables. This means that any variable x(t) can be expanded in Fourier series

$$x(t) = \sum_{k=-\infty}^{+\infty} X_k e^{j\omega_k t}$$
 (4)

where ω_k are the harmonic (angular) frequencies² and X_k are the corresponding complex (harmonic) amplitudes, satisfying $X_{-k} = X_k^*$ (* denotes complex conjugate). In practice, the Fourier series has to be truncated to a finite harmonic order $N_{\rm L}$, so that $2N_{\rm L}+1$ independent real numbers are required to characterize completely the truncated Fourier series [22], [16]. According to the usual assumption that noise is a small-change variation of the steady state, a linear perturbation analysis around the time-varying periodic working point (the so-called small-signal large-signal analysis [37]) can be carried out [22]. As a consequence, the linearized device (and circuit) becomes a linear periodically time-varying (LPTV) system [6]. From a circuit standpoint, the consequence of the LPTV nature of the linearized device is that the variations of the port voltages and currents with respect to the steady state can be expressed through a phasor-like analysis as [37], [16]

$$\delta x(t) = \left\{ \sum_{k=-N_{\rm S}}^{N_{\rm S}} \delta X_k^+ e^{j\omega_k^+ t} \right\}$$
 (5)

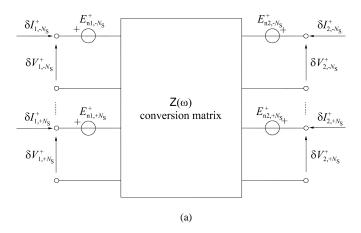
where $\omega_k^+ = \omega_k + \omega$ corresponds to the *upper sideband* of the kth harmonic, i.e., a frequency displaced by an amount ω from the kth harmonic itself. A truncated representation has been already used in (5), where $N_{\rm L} = 2N_{\rm S}$ (see [37] for details). Notice that each port voltage and current is thus represented as a vector with $2N_{\rm S} + 1$ complex components, the various *sideband amplitudes* [22]. The linear relationship between the voltage and current variations is expressed through a *conversion matrix* [37] (Z or Y) that relates the sideband amplitudes, thus accounting for frequency conversion effects among the sidebands (see [16] for further details)

$$\delta \mathbf{V}^{+} = \mathbf{Z}(\omega) \cdot \delta \mathbf{I}^{+}, \qquad \delta \mathbf{I}^{+} = \mathbf{Y}(\omega) \cdot \delta \mathbf{V}^{+}.$$
 (6)

In the previous equation, we have assumed that both the impedance and admittance representations are possible, and we have collected all of the port sideband amplitudes into a single vector ($\delta {m V}^+$ for voltages and $\delta {m I}^+$ for currents), each having $N \times (2N_{\rm S}+1)$ rows for an N-port circuit.

Concerning noise, the stochastic processes representing fluctuations, both at a circuit and microscopic level, are amplitude modulated by the time-varying noiseless working point, and therefore they are converted into *cyclostationary* processes [6], [16]: the most important feature is that, being nonstationary, such processes have correlated frequency components. Cyclostationarity implies that such correlation takes place only for those frequencies having the same distance from a harmonic of the noiseless steady state. The second order statistical properties are thus described through the so-called *sideband correlation matrix* (SCM) S [16], [38] that represents the correlation spectra between the various sidebands. By denoting as I_n^+ and E_n^+ the sideband (stochastic) amplitudes of the noise generators, a formal generalization of (1) is easily derived, thus leading to

 $^2{\rm In}$ the simplest case of periodic operation, $\omega_k=k\omega_0$ where k is a positive integer and $\omega_0=2\pi/T,T$ being the period of the excitation.



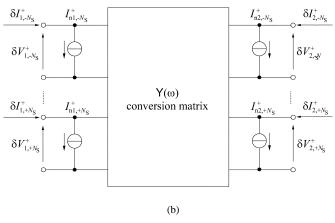


Fig. 2. Equivalent circuit of a noisy two-port device in LS operation: (a) series and (b) parallel representation. The left part of the linear multifrequency representation is the sideband expansion of physical port 1, and the right part corresponds to physical port 2.

the series and parallel representations of a noisy device in LS operation as a linear, multifrequency multiport

$$\delta \mathbf{V}^{+} = \mathbf{Z}(\omega) \cdot \delta \mathbf{I}^{+} + \mathbf{E}_{\mathbf{n}}^{+} \tag{7a}$$

$$\delta I^{+} = Y(\omega) \cdot \delta V^{+} + I_{n}^{+}. \tag{7b}$$

Notice that, in analogy with the remark in Section II-A, the sideband amplitudes $E_{\rm n}^+$ and $I_{\rm n}^+$ of the cyclostationary noise processes require mathematical care to be consistently defined: again, the basic assumption is the stability of the limit cycle corresponding to the time-varying noiseless operating point of the device. Fig. 2 shows the linear multifrequency equivalent circuit of a noisy two-port in LS operation. The relationship between the parallel and series representation is derived in full analogy with the SS case, leading to an expression formally identical to (3).

Noise analysis in circuits driven in LS conditions received a great deal of attention for several decades because of its importance in RF applications; in particular, noise in mixers has been studied since the 1940s [39], [40], [41], and noise in switched capacitor networks has been analyzed, e.g., in [42], where a time-domain algorithm is presented. Only recently, however, general purpose CAD techniques in the frequency domain have been proposed for the analysis of large-scale circuits [38], [43]. An open research issue is the development of reliable compact device noise models in LS conditions (cyclostationary noise generators): a quite common assumption is based on the work by

Dragone [5], who derived an expression for the LS noise spectra in a memoryless (resistive) one-port as a result of the instantaneous amplitude modulation of SS white noise spectra by the device time-varying working point, based on the hypothesis that fundamental fluctuations are due to scattering events faster than the electrical variable dynamics. Clearly, this assumption ceases to hold whenever the SS spectra are not white, e.g., for GR and 1/f noise: a general discussion of this can be found in [6].

III. PHYSICS-BASED NOISE ANALYSIS

The aim of physics-based (PB) noise analysis is to evaluate the second-order statistical properties of the device noise generators (including their correlation) from the elementary, microscopic fluctuations (the microscopic noise sources) occurring within the device volume, given the noiseless working point of the device. The microscopic noise sources, assumed to be known from physical first principles, can be associated with three phenomena [44], [22]: fluctuations of the velocity of free carriers (leading to diffusion noise which, in thermal equilibrium, corresponds to thermal noise), fluctuations of the number of free carriers (leading to GR noise), and 1/f noise. The latter has been widely studied from an experimental standpoint due to its great importance in circuit applications, in particular for LS systems and oscillators where upconversion transfers part of the low-frequency noise to RF. Unfortunately, the physical origin of 1/f noise is still an open issue; several competing theories have been proposed [45], [46], but experimental verifications have shown controversial results. Basically, 1/f noise can be interpreted either as a superposition of surface or bulk GR noise spectra with a proper distribution of time constants or as the result of mobility fluctuations. Finally, a more fundamental, quantum origin of 1/f noise has been also proposed [46].

From a practical standpoint, diffusion noise is described, in SS conditions, by means of a white stochastic process [44], [22], resulting from fast microscopic intraband scattering processes. Also, the GR noise source, at least in a fundamental description [44], [21], can be described by a white process, although, in the literature, a colored Lorentzian source is often used [47]: in [21], the limits of applicability of the Lorentzian source are discussed, and it is pointed out that the white source only has general validity. Since the spectra of the microscopic diffusion and GR noise sources are white, assuming that the LS steady state is much slower then the microscopic intraband and interband scattering processes,³ the microscopic noise sources in LS operation are derived through instantaneous amplitude modulation of the SS ones, as discussed in [16]. The case of 1/f noise is much more involved: in fact, up to now no widely accepted theory has been developed tracing back such fluctuations to an SS white microscopic noise source; actually, a source directly including a 1/f frequency dependence is suggested in [47]. This means that the instantaneous amplitude modulation approach is at least questionable, and more general techniques such as the ones described in Section IV should be exploited. In any case,

further research is definitely needed in this area, unavoidably requiring experimental verifications. A partial solution can be found if 1/f noise is assumed to derive from the superposition of GR fluctuations with a proper distribution of time constants, since in this case the previous remarks on the fundamental white microscopic noise source apply; this should be a viable solution at least for certain classes of devices wherein 1/f noise seems to be related to number fluctuations.

Complex device structures are typically analyzed through "classical" PB models making use of a partial differential equation (PDE)-based description of carrier transport and of the electrostatic potential (Poisson's equation): in the simplest case, the standard drift-diffusion (DD) model is considered, made of the carrier continuity equations complemented by Poisson's equation (see, e.g., [48]). Nonstationary, more advanced carrier transport models are also possible, with the obvious drawback of increased computational cost. Concerning noise analysis, appropriate stochastic forcing terms are added to the model PDEs, thus converting the system into a set of *stochastic* PDEs, that is, the Langevin approach to noise analysis [22]: the microscopic noise sources are also called Langevin sources. The microscopic noise sources are reasonably well known for the DD model, while for nonstationary transport the matter is a current research issue [49], [50]. For the sake of simplicity, we shall confine our discussion to the case of the DD model with direct GR mechanisms, since the extension of numerically efficient noise analysis to higher order transport models [51] and to the case of trap-assisted transitions is straightforward [21].

Let us denote as $\gamma_{\alpha}(\mathbf{r}, t)$ the microscopic noise source to be included as a forcing term in equation α ($\alpha = \varphi, n, p$ denote Poisson's, electron, and hole continuity equations, respectively): for white noise sources $\gamma_{\varphi} = 0$, and the various forcing terms are assumed to be spatially uncorrelated [22]. For diffusion noise, the microscopic sources are current density fluctuations $\boldsymbol{\xi}_{\alpha}(t)$, therefore $\gamma_{\alpha} \propto \nabla \cdot \boldsymbol{\xi}_{\alpha}$ ($\alpha = n, p$) [15], [22]. For direct GR noise the γ_{α} forcing terms appear in the continuity equations only (i.e., $\gamma_{\varphi}=0$), and γ_n and γ_p are correlated. The basic assumption (in nonautonomous devices) is that such forcing terms are small enough to linearly perturb the PB model around the noiseless working point: this means that the effect of the sources propagated to the device terminals, expressed as open circuit voltage or short-circuit current fluctuations, can be linearly related to γ_{α} by means of Green's functions [22]. The short circuit noise currents are

$$i_{n,i}(t) = \sum_{\alpha = \varphi, n, p} \int_{\Omega} \int_{-\infty}^{t} G_{\alpha,i}(\mathbf{r}, t, t_1) \gamma_{\alpha}(\mathbf{r}, t_1) dt_1 d\mathbf{r}$$
(8)

where i is the terminal index, Ω is the device volume, and $G_{\alpha,i}(\boldsymbol{r},t,t_1)$ is the Green's function corresponding to injection in equation α at point \boldsymbol{r} and time t_1 , and observation on (the short-circuit current of) terminal i. By definition, the Green's functions are calculated by linearizing the PB model equations around the noiseless working point, which can be either static (for SS noise analysis) or periodically time-varying (for LS noise analysis).

³The time constants of the scattering events are of the order of less then 1 ps, therefore the instantaneous modulation is expected to hold up to more then 100 GHz.

A. SS Physics-Based Noise Analysis

Since, in SS conditions, the device noiseless working point is constant, the linearized model equations define a time-invariant linear system [22], [15]: as a consequence, the output noise processes are stationary and $G_{\alpha,i}(\mathbf{r},t,t_1) = G_{\alpha,i}(\mathbf{r},t-t_1)$. This means that (8) can be written in the frequency domain as

$$\tilde{\imath}_{n,i}(\omega) = \sum_{\alpha = \omega, n, p} \int_{\Omega} \tilde{G}_{\alpha,i}(\boldsymbol{r}, \omega) \tilde{\gamma}_{\alpha}(\boldsymbol{r}, \omega) d\boldsymbol{r}$$
(9)

and therefore the correlation spectra of the noise generators are given by [22], [15]

$$S_{i_{n,i},i_{n,j}}(\omega) = \sum_{\alpha,\beta=\varphi,n,p} \int_{\Omega} \tilde{G}_{\alpha,i}(\boldsymbol{r},\omega) \times K_{\gamma_{\alpha},\gamma_{\beta}}(\boldsymbol{r},\omega) \tilde{G}_{\beta,j}^{*}(\boldsymbol{r},\omega) d\boldsymbol{r}$$
(10)

where $K_{\gamma_{\alpha}, \gamma_{\beta}}$ is the *local noise source* [47] for spatially uncorrelated microscopic noise sources: $S_{\gamma_{\alpha}, \gamma_{\beta}}(\boldsymbol{r}, \boldsymbol{r}_{1}; \omega) = K_{\gamma_{\alpha}, \gamma_{\beta}}(\boldsymbol{r}, \omega)\delta(\boldsymbol{r} - \boldsymbol{r}_{1}).$

Since the local noise source is known as a function of the noiseless operating point, either analytically or numerically [49], [52], the most intensive task is the numerical estimation of the Green's functions. In the frequency domain, the *generalized adjoint technique* [22] proposed in [15] and implemented in several commercial [19], [20] and academic (e.g., PADRE of Bell Labs [15], FLOODS of University of Florida [53]) simulators allows for a frequency-domain evaluation with the same computational cost of a standard small-signal analysis. An alternative time-domain method for the evaluation of the Green's functions has been proposed in [54].

The SS PB noise modeling approach has been checked for several classes of devices against available analytical and experimental results [15]. Concerning RF applications, most of the recent work has been devoted to a detailed analysis of the noise properties of MOSFETs, the first full 2-D simulations, with fair agreement with measurements, being proposed in [55] and [54]. An open problem is the excess drain noise as the gate length is reduced, often experimentally observed: simulations performed with advanced nonstationary transport models [52], [56] suggest that this can be traced back to nonstationary effects at the source side of the channel and not to hot electrons at the drain end as very often assumed.

B. LS Physics-Based Noise Analysis

From a formal standpoint, the only difference between SS and LS operation is the time-varying nature of the LS device operating point: the Langevin approach is still valid, and thus (8) can be applied. In practice, however, SS and LS operation lead to quite different formulations. In fact, the linear system propagating the microscopic noise sources to the device terminals becomes *periodically time varying* (LPTV) [16], in contrast to the time-invariant system discussed in Section III-A. This has two main consequences: 1) as discussed in Section II-B, the stochastic processes describing fluctuations become cyclostationary and 2) the Green's functions become matrix operators linking the various sideband amplitudes of the microscopic noise sources to the sideband amplitudes of the output variables

[16], thus giving rise to the frequency conversion effect. For this reason, the matrix Green's functions have been termed *conversion Green's functions* (CGFs). According to these remarks, (8) is rewritten as a linear relationship between sideband amplitudes (where ω is now the sideband angular frequency)

$$I_{\mathrm{n},\,i}^{+}(\omega) = \sum_{\alpha = \omega,\,n,\,p} \int_{\Omega} G_{\alpha,i}(\boldsymbol{r},\,\omega) \cdot \Gamma_{\alpha}^{+}(\boldsymbol{r},\,\omega) \,\mathrm{d}\boldsymbol{r} \qquad (11)$$

where $\Gamma_{\alpha}^{+}(\mathbf{r}, \omega)$ is the vector of sideband amplitudes of the microscopic noise source added to equation α . The SCM of the short circuit noise generators connected to terminals i and j can therefore be derived as [16]:

$$S_{i_{n,i},i_{n,j}}(\omega) = \sum_{\alpha,\beta=\varphi,n,p} \int_{\Omega} G_{\alpha,i}(\boldsymbol{r},\omega) \cdot K_{\gamma_{\alpha},\gamma_{\beta}}(\boldsymbol{r},\omega) \cdot G_{\beta,j}^{\dagger}(\boldsymbol{r},\omega) d\boldsymbol{r} \quad (12)$$

where K is the SCM of the local noise source for spatially uncorrelated microscopic fluctuations.

Noise simulation is based on the knowledge of the noiseless device working point, which can be evaluated either in the time or frequency domain. In RF and microwave applications, in particular for multitone excitation, frequency-domain techniques based on the solution of the discretized PB model by means of the Harmonic Balance approach are well suited for LS steady-state analysis: the first implementation in a 2-D model was proposed by Dutton et al. with the PISCES-HB simulator [57], [58], [59]. A one-dimensional (1-D) implementation, including noise analysis, was proposed by the present authors in [60] and [16]. Once the LS steady-state has been evaluated, an extension of the generalized adjoint technique can be applied for the efficient computation of the CGFs [16]. A similar implementation was proposed by the University of Florida group [61]. Noise analysis in LS conditions was also studied by the research group at the University of Lille [17], [18] by extending the active line model for the analysis of FETs [62].

One of the (many) open problems in LS PB noise analysis is the best way to include in the simulation noise sources whose spectra are not white in SS conditions, i.e., equivalent GR and 1/f noise. A preliminary study, at least for the case of GR noise, has been presented in [63] and [64].

IV. FROM PB MODELS TO CIRCUIT-ORIENTED REPRESENTATIONS

From an application standpoint, PB noise analysis is important at two levels. The first is to assist the design and optimization of the device: the approach outlined in Section III allows us to express the noise spectra as a superposition integral extended to the whole device volume. This means that inspection of the integrand function in (10) and (12), the so-called *spatial noise density*, makes it possible to identify the physical regions of the device wherein noise is generated. In this way, an optimization of the device structure and doping is, at least in principle, possible.

The second level concerns compact models, for which even the comparatively simple case of SS noise still poses severe problems, at least for RF and microwave applications: a representative example is the case of high-frequency MOSFET noise analysis (see, e.g., [65], [66] and references therein). Under this respect, PB SS noise analysis has a great potential as a means to develop and validate physically sound and reliable compact models, either in the form of equivalent circuit-based approaches or of *black-box* models.

Similar remarks apply also to the case of LS noise analysis. In this regime, circuit designers very often exploit the following noise analysis technique: the device noise is described by the same models derived for SS operation as a function of the device (static) working point; since in LS conditions this becomes periodically time-varying, the stationary noise processes are modulated and transformed into cyclostationary fluctuations. This assumption, clearly, has to be proved by measurements and/or by PB LS simulations. The very process of modulation poses severe problems when nonwhite SS noise spectra are involved: as discussed in [6], [63], and [64], two interpretations are possible. Let us consider, for simplicity, a stationary SS noise process $\gamma(t)$ with power spectrum $S_{\gamma,\gamma}(\omega) = f^2 |h(\omega)|^2$, where f is a working point-dependent factor and $\tilde{h}(\omega)$ is the impulse response of a properly defined linear time-invariant system taking into account the frequency dependence of the spectrum: for a white process, $h(\omega) = 1$. Process $\gamma(t)$ can be interpreted as the output of the linear filtering of a unit white Gaussian noise process $\eta(t)$ according to the scheme in Fig. 3(a). In LS conditions, the working point becomes periodically time-varying, and therefore factor f = f(t) periodically modulates the noise process. Unfortunately, such a modulation can be performed at least in two different ways.

• $\eta(t)$ is first modulated by f(t) and thus converted into a cyclostationary process, then filtered by h(t) [see Fig. 3(b)]: this mechanism will be denoted as "MF" and leads to process $\gamma_{\rm MF}(t)$ with SCM [63], [64] as

$$(S_{\gamma_{\mathrm{MF}}, \gamma_{\mathrm{MF}}}(\omega))_{m, n} = \tilde{h}(\omega_{m}^{+}) G_{m-n} \tilde{h}^{*}(\omega_{n}^{+})$$
 (13)

where G_k is the kth harmonic amplitude of the periodic function $g(t) = f^2(t)$ and $(S)_{m,n}$ denotes the element (m, n) of the SCM.

• $\eta(t)$ is first filtered by h(t), yielding the stationary process $y_{\rm MF}(t)$, then modulated by f(t) [see Fig. 3(c)]: this mechanism will be denoted as "FM" and leads to process $\gamma_{\rm FM}(t)$ with SCM [63], [64] as

$$\left(S_{\gamma_{\text{FM}},\gamma_{\text{FM}}}(\omega)\right)_{m,n} = \sum_{k} F_{m-k} F_{n-k}^* \left|\tilde{h}(\omega_k^+)\right|^2 \qquad (14)$$

where F_k is the kth harmonic amplitude of the periodic function f(t).

If $\tilde{h}(\omega)$ is a low-pass function, it is apparent from (13) that the MF modulation scheme yields an SCM with null elements apart from (0,0), i.e., the baseband sideband, while the FM scheme (14), provided that f(t) has a large enough number of harmonics (i.e., if the device is driven in nonlinear conditions), results in an SCM with several nonzero elements. Furthermore, for white SS processes (13) and (14) yield the same result as follows:

$$(\mathbf{S}_{\gamma_{\mathrm{MF}},\gamma_{\mathrm{MF}}}(\omega))_{m,n} = (\mathbf{S}_{\gamma_{\mathrm{FM}},\gamma_{\mathrm{FM}}}(\omega))_{m,n} = G_{m-n}$$
$$= \sum_{l} F_{m-k} F_{n-k}^*. \tag{15}$$

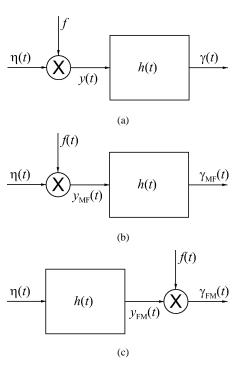


Fig. 3. System interpretation of a noise process. (a) Stationary process for SS noise analysis. (b) Cyclostationary MF process for LS noise analysis. (c) Cyclostationary FM process for LS noise analysis.

On the other hand, the case of colored SS noise requires choosing between the two possible approaches. According to the literature, the FM approach is probably the most commonly applied in circuit simulators (see, e.g., [7], [38], and [67]), but the MF approach has been exploited as well, at least for 1/f noise (see e.g., [68] and [43]). In any case, it is widely recognized in the literature that a final solution of this problem still has to be found: an important step toward the completion of this process could, and should, be provided by LS PB models, at least for particular classes of devices and microscopic noise sources. The case of GR noise in a uniform device (a doped semiconductor sample) was discussed in [63] and [64], showing that the correct modulation approach to be applied to the SS Lorentzian microscopic noise sources, for direct GR processes, is the FM scheme. However, care should be exerted in generalizing this conclusion to any device class, as the following discussion suggests.

As a case study, we shall consider the PB simulation of a pn diode: despite its simplicity, the bipolar nature of conduction in this device makes noise analysis in LS conditions complex. As shown in [22, ch. 4] for a long device, under low-injection conditions a closed-form analysis can be carried out, leading to an expression of the SS noise spectrum including both diffusion and GR noise. The well-known shot-like result is obtained [10] as

$$S_{i_{\rm n}, i_{\rm n}}(\omega) = 2q(I + 2I_{\rm S}) + 4k_{\rm B}T[\text{Re}\{Y(\omega)\} - Y(0)]$$
 (16)

where I is the dc current, $I_{\rm S}$ the saturation current of the junction, and $Y(\omega)$ the small-signal admittance as a function of frequency. Under forward bias conditions and low operating frequency, (16) is approximated by the full shot expression $S_{i_{\rm n},i_{\rm n}}(\omega)\approx 2qI$.

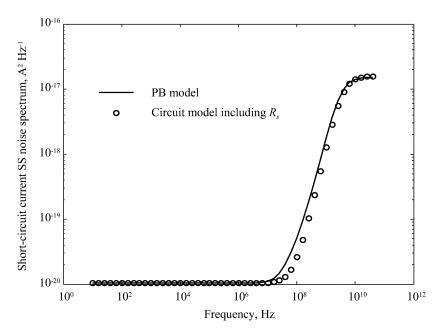


Fig. 4. Frequency dependence of the SS current noise spectrum for the short pn junction. The solid line is the PB model, and the symbols are obtained by the full shot noise formula embedding the parasitic resistance of the neutral regions.

A first simulation is performed for a short Si abrupt pn junction, with doping levels $N_{\rm A} = N_{\rm D} = 10^{16} \ {\rm cm}^{-3}$ minority carrier mobilities $\mu_n=1390~{\rm cm^2 \cdot V^{-1} \cdot s^{-1}}$ and $\mu_p=470~{\rm cm^2 \cdot V^{-1} \cdot s^{-1}}$, minority carrier lifetimes $\tau_n = \tau_p = 1 \ \mu \text{s}$, cross section normalized to 1 cm², and side lengths 6 μ m: in this case, the GR noise contribution to the SS noise spectrum is negligible, and all of the shot-like behavior is due to diffusion noise. The short-circuit current noise spectrum for a forward bias of 0.5 V is shown in Fig. 4, where the PB simulation is compared to the result of the full shot noise model (the dc current is that evaluated by the PB simulation): the frequency dependence is due to the presence of the intrinsic device capacitances and of the series, parasitic resistance $R_{\rm s}$ of the neutral regions; the high-frequency plateau is due to the thermal noise in such resistance. $R_{\rm s}$ was extracted from small-signal analysis, obtaining a value of 1 m Ω . The agreement is generally good, apart from a small discrepancy around 100 MHz, due to the fact that diffusion noise at those frequencies does not result any longer into full shot noise, since the device sides are not short anymore with respect to the (frequency-dependent) diffusion length.

The same structure was then simulated under LS conditions with a one-tone voltage excitation superimposed to a 0.5-V dc component. The input tone was applied at two frequencies: $f_{\rm a}=1$ MHz and $f_{\rm b}=1$ GHz with tone amplitudes $V_{\rm a}=0.05$ V and $V_{\rm b}=0.1$ V, respectively. The LS steady-state analysis was performed with $N_{\rm L}=6$ harmonics plus dc, so as to allow noise simulation to be performed up to the third sideband $(N_{\rm S}=3)$. Around $f_{\rm a}$, the device still exhibits SS white shot noise (see Fig. 4): the full shot noise formula can be amplitude modulated according to (15), obtaining a very good agreement with the results of the PB LS model, as shown in Table I for the diagonal and upper diagonal elements (independent of ω) of the noise current SCM. The same kind of agreement holds also for the other off-diagonal elements. Concerning the excitation at 1 GHz, we report in Fig. 5 a comparison between the PB

TABLE I SCM Elements Comparison Between the PB and the Circuit Models for the Excitation of a Short Diode at $f_{\rm a}=1$ MHz. The Elements are Measured in $10^{-20}~{\rm A^2 \cdot Hz^{-1}}$

	$V_{\rm a}=0.05~{ m V}$		$V_{\rm b}=0.1~{ m V}$	
SCM element	PB	circuit	PB	circuit
(+3, +3)	2.276	2.248	10.317	9.989
(+2, +2)	2.277	2.247	10.448	10.054
(+1, +1)	2.273	2.247	10.490	10.095
(0, 0)	2.272	2.246	10.496	10.102
(-1, -1)	2.273	2.247	10.490	10.095
(-2,-2)	2.277	2.247	10.448	10.054
(-3, -3)	2.276	2.248	10.317	9.989
(+3, +2)	1.560	1.539	8.869	8.541
(+2, +1)	1.560	1.540	8.969	8.614
(+1, 0)	1.559	1.540	8.991	8.637
(0, -1)	1.559	1.540	8.991	8.637
(-1,-2)	1.560	1.540	8.969	8.614
(-2, -3)	1.560	1.539	8.869	8.541

model and the results of the circuit approach. In the latter, full shot noise is amplitude modulated and the effect of $R_{\rm s}$ and of the junction (depletion) capacitance are embedded: the agreement is generally good, apart for a sideband frequency around 100 MHz, where already in SS conditions a discrepancy takes place.

A more complex situation arises when intrinsically colored SS noise has to be modulated. As an example, we simulated a long Si pn junction, having the same parameters as the short one, apart from the lifetimes $\tau_n = \tau_p = 160~\mu s$. The para-

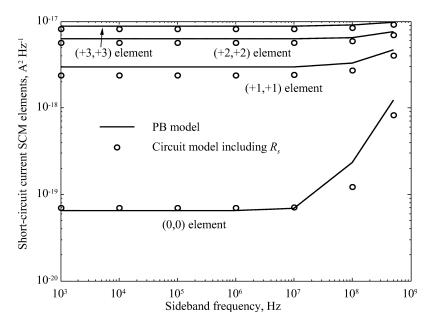


Fig. 5. Diagonal elements of the noise current SCM as a function of the sideband frequency for the short diode simulated for an input tone with amplitude 0.1 V at 1 GHz: the solid line is the PB model, and the symbols are obtained by the modulated full shot noise formula embedding the parasitic resistance and the junction capacitance.

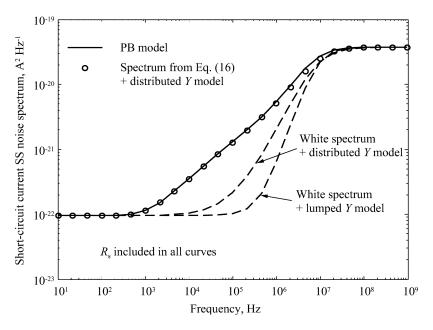


Fig. 6. Frequency dependence of the SS current noise spectrum for the long pn junction. The solid line is the PB model and the symbols are obtained by (16), embedding the parasitic resistance and the junction capacitance and using the distributed model for $Y(\omega)$. Broken lines are generated by the full shot noise formula embedding the parasitic resistance of the neutral regions.

sitic resistance is $R_{\rm s}=0.44~\Omega$. An SS simulation, including both diffusion and GR noise sources, was first carried out for a 0.5-V dc working point, and the device admittance and the noise spectrum were compared to the ones calculated according to the distributed analytical model (see [22]): the noise spectrum closely follows the theoretical estimation (16), as shown in Fig. 6, where the effect of the parasitic resistance, including its thermal noise, and of the junction capacitance have been added to the intrinsic noise spectrum. Broken curves in Fig. 6 show that poor agreement results if the full shot noise (white) approximation is exploited: this happens both if the approximate lumped or the accurate distributed expression for $Y(\omega)$ is employed.

An LS simulation, with a 0.2-V input tone at 10 MHz superimposed to the 0.5-V dc component, has then been carried out. The resulting diagonal elements of the SCM of the short-circuit noise current are reported in Fig. 7, where they are compared to the result of the modulation of (16), both following the MF and the FM schemes, and further including the effect of the parasitic resistance and of the junction capacitance: details on the implemented expressions can be found in [69]. Fig. 7 clearly shows that, at least for the device under test and the operating conditions taken into account, only the MF approach yields results in good agreement with the LS PB model. The FM scheme overestimates noise in the baseband sideband due to the high-pass

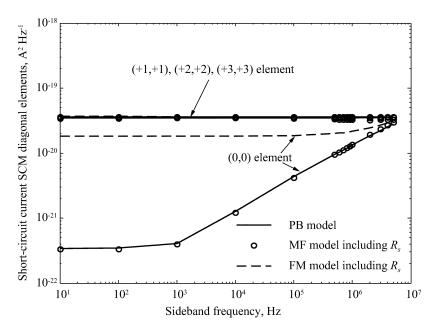


Fig. 7. Diagonal elements of the noise current SCM as a function of the sideband frequency for the long pn junction simulated for an input tone with amplitude 0.2 V at 10 MHz: the solid line is the PB model, the symbols are obtained by (16) modulated through the MF scheme and embedding the parasitic resistance and the junction capacitance, the dashed line is generated by (16) modulated through the FM scheme and embedding the parasitic resistance.

nature of the filtering function in (16). This result differs from that obtained for GR low-pass noise in a uniform resistor [63], [64], where the FM scheme has been proven to be the correct one. Furthermore, at a circuit simulation level, the FM scheme applied to other devices (e.g., microwave FETs [70]) has been demonstrated to reproduce the experimental results.

These indications point out that the choice between the two modulation schemes is likely to depend on the device under investigation and on the nature of noise sources considered. PB simulations, supported by an extensive experimental characterization, can help in identifying a correct LS modeling approach for each device class. Moreover, noise measurement techniques should be exploited in order to directly characterize converted noise in LS conditions. This is particularly important in the modeling of 1/f noise, for which a fundamental white microscopic noise source valid in all possible conditions has not yet been identified, though, as already remarked, a superposition of GR noise sources can be exploited to provide 1/f behavior at least on a limited frequency bandwidth.

V. CONCLUSION

A comprehensive review has been presented on the physics-based numerical simulation of RF analog semiconductor devices, both in the small-signal and in the periodic, forced large-signal case. The connection between PB and circuit-oriented modeling has been discussed, showing that PB simulations can be exploited to validate compact models and purely circuit oriented approaches. Concerning LS noise, the customary strategy is to modulate the noise generators characterized in small-signal conditions. The modulation scheme itself is still not well established, at least for colored SS noise. We have discussed two modulation techniques, showing that the optimum strategy depends on the device class (bipolar or FET) considered, at least for intrinsically colored noise under small-signal conditions.

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