### Hyper-X/X-43A: Dryden's Role

Laurie Grindle X-43A Flight 3 Chief Engineer NASA Dryden Flight Research Center



Lockheed Martin Interchange August 14, 2012

### X-43A (Hyper-X) Project Overview

Project Start 1995 Flt 1 6/2001 Flt 2 Flt 3 Proj. End 3/2004 11/2004 12/2004

First ever flight demonstration of an airframe-integrated scramjet powered hypersonic vehicle

Hyper-X Research Vehicle (HXRV)

Primary objective was to validate the tools, test and analysis techniques, & design methods of scramjet powered, hypersonic vehicles

HIPER

Three flight project

- Two flights at Mach 7
- One flight at Mach 10

Research Vehicle Adapter

Hyper-X Launch Vehicle (HXLV)

Hyper-X Research Vehicle (HXRV): ATK-GASL

- Hydrogen fueled scramjet engine
- Scaled version of a Mach 10 "cruise" configuration

Hyper-X Launch Vehicle (HXLV) - OSC

- Air launched from NASA's B-52
- Boosts HXRV to test condition
- Modified 1st Stage Pegasus booster

Hyper-X





- Research and Technology Objectives
- Analytical and experimental performance verification (CFD, Wind Tunnel)
- Flight Validation of Design Predictions
- Improve Scramjet Design Tools



- Flight Research and Operations
- Vehicle Build, Integration and Validation
- Ground, Flight and Range Safety
- Flight Performance Assessment
- Responsiveness to Technology Objectives  $\mathcal{H}_{uper} - \mathcal{X}$

#### NASA Dryden Flight Research Center \_\_\_\_\_ Edwards, CA





### **Highly Integrated Effort Required**



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### **Aerodynamics**



Partner Role









Partner Role







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### Guidance, Nav, & Flight Controls



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HYPER)

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### **Stage Separation**



Partner Role





Hyper-X

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Time (corr)

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### Instrumentation & Range

**DFRC** Role

Partner Role





Hyper-X



### X-43A Simulation



Partner Role



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Hyper-X



### **Test and Integration Activities**





### Flight Operations



Partner Role





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### X-43A Mission Details



ATK, GASL

-4-5



### Flight 2 – March 27, 2004















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### Flight 3 – November 16, 2004







Hyper-X

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- Why were we successful?
  - Rigorous processes for design, development, testing, and validation

 Strong technical expertise and team work between NASA, ATK GASL, Boeing & Orbital Sciences

 A dedicated project team that worked for eight years to make these revolutionary flights a reality







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# Questions ???





### **Backup Charts**





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## **Goals/Objectives of Hyper-X Program**

**GOALS:** Demonstrate, validate and advance the technology, experimental techniques, and computational methods and tools for design and performance predictions of a hypersonic aircraft powered with an airframe-integrated, scramjet engine.

### FLIGHT OBJECTIVES:

- Three flights: two @ Mach 7 and one Mach 10
- Methods verification
- Scaling confirmation *Primary Metric: Accelerate*

### TECHNOLOGY OBJECTIVES:

- Vehicle design & risk reduction
- Flight validation of design methods
- Design method enhancement
- Hyper-X Phase 2 and beyond





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## X-43A External Configuration





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Fuel: Hydrogen Igniter: Silane

Nitrogen Purge

### X-43A Internal Layout





Ground Vibration, Mode Interaction, Initial Mass Properties Testing Final Weight/Balance and Mass Properties Test

VMS Hardware-In-Loop and Aircraft-In-Loop Tests
RF Systems Tests
Fuel Systems - High Pressure Bench Test
Environmental Systems Test
Installed
Leak and Functional Test
Full
Mission Simulation With Inert Gas Test
Full Mission Simulation With Real Gas Test



✓HXRV-Adapter Systems Validation✓HXRV/Adapter Integration Tests

✓ Standalone HXLV Tests ✓ HXLV/HXRV Integration

### Hardware and Software Testing ...Preparing for Flight at DFRC



Stack Hook Release
B-52 Systems Test
B-52/Stack Integration
Combined System Test
Captive Carry





### **Hyper-X Components**



#### Launch Stack = HXLV + Adapter + HXRV

Hyper-X is a complex system with multiple interfaces.

Hyper,



### **Operations on Day of Flight**





#### **Day of Flight Ground Operations**

- Control Room Staffing
- System power up and checkout
- B-52 engine start / power transfer
- Final X-43A closeout





B-52 Take-off





### Flight Operations

- In flight systems / range checks
  - HXRV Built In Tests
  - FTS auto gain control
  - HXLV Fin Actuation System
- Launch and Free Flight

Hyper-X

## Flight 3 Right Adapter Camera Image

- Time between images is 33.3 milliseconds 1/30th of real-time.
- **Right Adapter Camera Position**

Hyper-

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