Thermal Vacuum Testing of a Proto-flight Miniature Loop Heat Pipe with Two Evaporators and Two Condensers

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This paper describes thermal vacuum testing of a proto-flight miniature loop heat pipe (MLHP) with two evaporators and two condensers designed for future small systems applications requiring low mass, low power and compactness. Each evaporator contains a wick with an outer diameter of 6.35 mm, and each has its own integral compensation chamber (CC). Miniaturization of the loop components reduces the volume and mass of the thermal system. Multiple evaporators provide flexibility for placement of instruments that need to be maintained at the same temperature, and facilitate heat load sharing among instruments, reducing the auxiliary heater power requirement. A flow regulator is used to regulate heat dissipations between the two condensers, allowing flexible placement of radiators on the spacecraft. A thermoelectric converter (TEC) is attached to each CC for control of the operating temperature and enhancement of start-up success. Tests performed include start-up, power cycle, sink temperature cycle, high power and low power operation, heat load sharing, and operating temperature control. The proto-flight MLHP demonstrated excellent performance in the thermal vacuum test. The loop started successfully and operated stably under various evaporator heat loads and condenser sink temperatures. The TECs were able to maintain the loop operating temperature within ±1K of the desired set point temperature at all power levels and all sink temperatures. The un-powered evaporator would automatically share heat from the other powered evaporator. The flow regulator was able to regulate the heat dissipation among the radiators and prevent vapor from flowing into the liquid line.

Nomenclature/Acronym

Cl	=	condenser 1
C2	=	condenser 2
CC	=	compensation chamber
CC1	=	compensation chamber 1
CC2	=	compensation chamber 2
E1	=	evaporator 1
E2	=	evaporator 2
E4	=	evaporator 4
LHP	=	loop heat pipe
MLHP	=	miniature loop heat pipe
TEC	=	thermoelectric converter
TEC1	=	thermoelectric converter 1
TEC2	=	thermoelectric converter 2

I. Introduction

A loop heat pipe (LHP) is a very versatile heat transfer device which can transport a large heat load over a long distance with a small temperature difference^{1, 2}. LHPs are being used on several commercial communications satellites and NASA's ICESat, SWIFT, AURA, GOES-N and GOES-R spacecraft³⁻¹¹. These LHPs have a single

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evaporator with a 25-mm outer diameter primary wick. For small spacecraft applications, miniaturization of the LHP is necessary in order to meet the stringent requirements of low mass, low power and compactness. When the heat source has a large thermal footprint, or several heat sources need to be maintained at similar temperatures, an LHP with multiple evaporators is highly desirable. Multiple evaporators also provide an inherent heat load sharing function among several heat source components¹². Under NASA's New Millennium Program Space Technology 8 (ST 8) Project, Goddard Space Flight Center (GSFC) has developed a Thermal Loop technology utilizing a miniature loop heat pipe (MLHP) with multiple evaporators and multiple condensers to transport heat, and thermoelectric converters (TECs) to control the loop operating temperature.

Figure 1 shows the Thermal Loop concept. At the heart of the Thermal Loop is an MLHP. Key features include: 1) multiple evaporators in a single LHP where each evaporator has its own integral compensation chamber (CC); 2) a primary wick with an outer diameter (O.D.) of 6.35mm for each evaporator; 3) multiple condensers that are attached to different radiators; 4) a TEC assembly that is attached to each CC and connected to the evaporator via flexible thermal straps; 5) a flow regulator located downstream of the condensers; 6) coupling blocks connecting the vapor line and liquid line for heat exchange; 7) ammonia working fluid; and 8) a thermal mass that is attached to each evaporator to serve as the instrument simulator.



Figure 1. Thermal Loop Experiment Concept

The benefits offered by the Thermal Loop technology are: 1) Small components that make up the MLHP reduce the mass and volume of the thermal subsystem. 2) Multiple evaporators allow multiple instruments to be placed at various locations inside the spacecraft and still be maintained at the same or similar temperatures regardless of their heat dissipations. 3) The 'off'' instruments can share the heat dissipated by the "on" instruments. This reduces or eliminates the auxiliary power required to maintain "off" instruments above the minimum temperature. Heat load sharing among evaporators is an inherent function of multi-evaporator LHPs and is automatically accomplished through internal vapor distribution among the evaporators. 4) Multiple radiators can be placed on various surfaces of the spacecraft and can be exposed to different thermal environments. As long as all the radiators together can dissipate the total heat load, some of the radiators can even face the sun, and the passive flow regulator at the downstream of the condensers can automatically regulate the heat dissipation among all condensers. 5) Traditional LHPs rely on cold-biasing and electrical heaters to maintain the CC to control the LHP set point temperature¹³⁻¹⁵. The required TEC control heater power is much less than that of using electrical heaters. Active CC cooling by the TEC is particularly useful when the loop needs to re-start within a short time. 6) TECs ensure successful start-up without start-up heaters, which are usually required in traditional LHPs.

An MLHP Breadboard was built and tested in the laboratory and thermal vacuum environments and demonstrated excellent performance¹⁵⁻²⁰. In addition, an analytical model was developed to simulate the steady state and transient operation of the MLHP²¹. Subsequently, an MLHP proto-flight unit was built for space flight validation of the Thermal Loop technology. This paper presents the design and thermal vacuum tests of the MLHP proto-flight unit.

II. Test Article and Test Setup

Figure 2 shows a picture of the MLHP proto-flight unit. Major design parameters are summarized in Table 1. The MLHP proto-flight unit consisted of two parallel evaporators with integral CCs, two parallel condensers, a common vapor transport line and a common liquid return line. Each evaporator was made of aluminum 6061 with an O.D. of

9 mm and a length of 52 mm. The primary wick was made of titanium with a pore radius of about 1.2 µm. Each CC was made of stainless steel with an O.D. of 22.2 mm and a length of 72.4 mm. The vapor line, liquid line and condensers were all made of stainless steel. The vapor line had an O.D. of 2.38 mm and a length of 1580 mm. The liquid line had an O.D. of 1.59 mm and a length of 1120 mm. Each condenser had an O.D. of 2.38 mm and a length of 1676 mm, and was serpentine and embedded in a radiator. A flow regulator consisting of capillary wicks was installed at the downstream of the two condensers. The MLHP was charged with 31.3 grams of anhydrous ammonia.



Figure 2. MLHP Proto-flight Unit

Component Material		Value		
Evaporators (2) Aluminum 6061		9 mm O.D. x 52 mm L		
Primary Wicks (2) Titanium		6.35 mm O.D. x 3.2mm I.D.		
		Porosity: 0.35		
		Hydraulic diameter of vapor groove (equivalent): 1.27 mm		
		Pore radius 1.25 μm (E1), 1.20 μm (E2)		
		Permeability: 0.8 x 10^{-14} m ² (E1), 1.0 x 10^{-14} m ² (E2)		
Secondary Wicks (2)	SS 304L	Pore radius: 45.53 µm (E1), 36.04 µm (E2)		
Bayonet Tubes (2) SS 304L		1.1 mm O.D. x 0.80 mm I.D.		
CC (2) SS 304L		22.5 mm O.D. x 21.2 mm I.D. x 76.7 mm L		
Vapor Line	SS 304L	2.38 mm O.D. x 1.37 mm I.D. x 1580 mm L		
Liquid Line	SS 304L	1.59 mm O.D. x 1.08 mm I.D. x 1102 mm L		
Condensers (2)	SS 304L	2.38 mm O.D. x 1.37 mm I.D. x 1676 mm L (each)		
Flow Regulator SS 316L shell and		Pore radius: 9.35 μm, 13.83 μm		
	wicks	Permeability: $9.11 \times 10^{-13} \text{m}^2$, $9.49 \times 10^{-13} \text{m}^2$		
Working Fluid Anhydrous		31.3 grams		
	Ammonia			

Fable 1.	. Design	Parameters	of MLHP	Proto-flight	Unit
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Each evaporator was made with a saddle, which could be attached to an aluminum thermal mass that simulated an instrument. The two instrument simulators (thermal masses) weighed 540 grams (attached to Evaporator 1) and 280 grams (attached to Evaporator 2), respectively. Each thermal mass had electric heaters that were wired into two circuits (top and bottom), and each circuit was powered with a variable voltage to provide a variable power of 0-70W. A TEC assembly consisting of two TECs made by Marlow Industries, Inc. with a model number of DT3-6, two copper straps, and a copper saddle was used between each CC and the evaporator as shown in Figure 3. Each TEC assembly was controlled by a bi-polar power supply through the MLHP Electronics Box . Changing the polarity of the applied voltage changed the TEC operation between the heating and cooling modes. Two TECs were used for redundancy. However, only one TEC was used for each CC/evaporator at any given time.

The two condensers consisted of serpentine tubes that were sandwiched between two thin aluminum plates serving as radiators. Each radiator had a surface area of 432mm x 317mm. Each evaporator was mounted on a thermal mass,

and the thermal masses, CCs, and transport lines were mounted on a base plate with standoffs supporting the transport lines. The base plate and the radiators were 152mm apart. Three aluminum coupling blocks connecting the vapor line and liquid line were installed. Each coupling block was 20 mm by 20mm by 6mm.

The MLHP proto-flight unit was placed inside a thermal vacuum chamber, as shown in Figure 4. Each radiator was cooled by a cryopanel through radation on one side (the down-facing side). Two copper cryopanels were used as radiator sinks, one for each radiator. Temperatures of the two cryopanels were set to be the same, ranging from 123K to 303K, depending on the type of test performed, although they could be independently. changed Four supplemental heaters were installed on both radiators on the up-facing sides. These supplemental heaters were activated, when needed, to prevent the ammonia working fluid from freezing. They could be independently controlled at different set point temperatures for various tests, such as the flow regulation test. Multi-layer insulation was used between the top side of the radiator and the rest of the MLHP components (evaporators, CCs, vapor line, and liquid line and thermal masses).

More than 120 type T thermocouples were used to monitor the temperatures of the MLHP, radiators, and cryopanels. Figures 5 and 6 show the thermocouple locations. Note that the thermocouple numbers are not consecutive. A data acquisition system consisting of a data logger, two personal computers, and two screen monitors was used to collect, display, and store temperature and power data every second. LabView software was as used for the command and control of the test conditions.



Figure 3. TEC Assemblies Connecting the CCs and Evaporators



Figure 4. Picture of MLHP Protoflight Unit in the Thermal Vacuum Chamber



Figure 5. Thermocouple Locations (Overall) on MLHP Proto-flight in TV Testing



Figure 6. Thermocouple Locations on Transport Lines of MLHP Proto-flight in TV Testing

III. Test Results

The NASA New millennium Program Office established a set of success criteria to be met for the MLHP proto-flight. All success criteria wet met or exceeded during the thermal vacuum test as shown in Table 2. Some test results are highlighted in the following discussions.

Test		Requirement/Success Criteria		Validation Results	Compliance
Start-up	•	An 80% success rate or better on a minimum of 20 start-ups Demonstrate over a temperature range between 273K and 308K	•	100% success on 43 start-up tests Temperature range between 273K and 308K	Exceed requirements
Heat Transport	•	75W total heat load	•	120W total heat load	Exceed requirements
Operation	•	Control the loop saturation temperature within ±3K between 273K and 308K Transient operation over full range of heat loads (10W to 100W)	•	Control the loop saturation temperature within ±1K between 273K and 313K Transient operation between 5W and 120W with rapid changes of heat load and/or sink temperature Changed saturation temperature between 273K and 313K while in operation	Exceed requirements
Heat Load Sharing	•	Demonstrate heat load sharing between two evaporators (0W to 75W)	•	Heat load sharing was demonstrated by changing 1) heat load to one evaporator (0W to 75W); and 2) CC saturation temperature	Exceed requirements
LHP Model Correlation	•	Model predictions of MLHP critical temperatures within ±5K of the test results during steady state and transient operation	•	Model predictions of the loop critical temperatures (CCs, evaporators, vapor and liquid lines) were within ±5K of the test results during steady state and transient operation.	Meet requirement

Table 2. Success Criteria and Validation Results for MLHP Proto-flight

The MLHP analytical model predicted that each evaporator could transport 100W of heat. In the early phase of the test program, it was found that evaporator E2 was damaged and could transport only 60W of heat load. By contrast, evaporator E1 could transport slightly more than 100W of heat. The exact cause of the E2 damage was not known, but most likely occurred between the time when the unit was delivered to GSFC by the vendor and when the unit was being prepared for the thermal vacuum test. The schedule constraint demanded that testing of the proto-flight unit be continued with tests that did not require more than 60W of E2 power. At the same time, a replacement evaporator (evaporator E4) was fabricated. After E4 was integrated into the proto-flight unit, the loop was tested again in the same vacuum chamber for those tests requiring more than 60W to E4. In the following discussions, E2 or E4 was clearly labeled in the data plots so there should be no misunderstanding when E2 or E4 was used in a given test.

It should also be noted that the actual loop saturation as indicated by the measured vapor line temperature was always 2K higher than the measured CC temperatures. The exact reason for this discrepancy was not known, but could be due to a new CC design that resulted in a thicker layer of liquid formed on the mesh metal attached to the inner wall of the CC. Although this is not a problem in real applications, it is important to keep in mind when examining the test results and analytical model predictions in the following discussions.

Forty three startup tests were conducted with various power profiles to the two evaporators at saturation temperatures between 273K and 308K. All startup tests were successful. Figure 7 shows the loop temperatures in a start-up test where CC1/CC2 temperatures were maintained at 273K/273K prior to start-up. The C1/C2 sinks were kept at 223K/223K. As a heat load of 10W was applied to E1, the E1 temperature rose gradually. No vapor was generated until the E1 temperature reached 283K. In other words, a wall superheat of 10K was observed at the inception of the start-

up. Prior to the vapor generation in E1, E2 was at 267K even when the E1 temperature was rising because there was no vapor connection between E1 and E2. After the loop had started, however, E2 gradually rose to 273K due to heat load sharing between the two evaporators. This test was repeated and similar results were obtained with a superheat of 5.5K at the start-up.

Similar start-up phenomena were also observed for start-up at 273K when a heat load of 10W was applied to E2 only, with a superheat of 8K.

Figure 8 depicts the temperatures in a start-up test where CC1/CC2 temperatures were kept at 273K/273K and a heat load of 50W was applied to E2. Initially the loop components were kept at around 264K except for the CCs which were kept at 273K. When the E2 temperature reached 276K, the loop started with a 3K wall superheat. With such a high heat load, not only did the E2 temperature rise quickly during the warm-up period, but E1 also shared heat from E2 soon after the loop started. Figure 9 shows the comparison between analytical model predictions and experimental data for this startup. Because the superheat required for the boiling incipience could not be known in advance, the experimentally observed superheat of 3K was used as an input parameter to the analytical model. It is seen that the model predicted all the major events correctly and correlated the critical temperatures (CC and evaporators) within $\pm 5K$ of the experimental results.

LHP start-up with a low power is usually more difficult. The MLHP proto-flight was able to start successfully between 273K and 308K with heat loads to E1/E2 of 10W/0W, 0W/10W, 5W/5W, 5W/0W, and 0W/5W. Figure 10 shows the loop temperatures for a 5W/0W start-up at 293K. Initially, the E1/E2 and vapor line temperatures were below 288K, and CC1/CC2 temperatures were maintained at 293K using TECs. As 5W was applied to the E1 thermal mass, the E1 temperature rose gradually. When E1 reached 295K, the loop started with a 2K wall superheat. During the period when E1 was warmed up, the E2 temperature continued to decrease due to the environmental condition. After the loop started, the E2 temperature increased because of heat load sharing. With only 5W to E1, however, the amount of heat that could be shared by E2 was small, and the E2 temperature rose very slowly.



Figure 7. Start-up with 10W/0W at 273K



Figure 9. Comparison of Analytical Model Predictions and Experimental Results for Startup with 0W/50W at 273K

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Time

Figure 11 shows the temperatures of the loop during the start-up at 293K with 5W/5W to E1/E2. Initially, both CC1 and CC2 were kept at 293K and E1 and E2 temperatures were below 285K. As 5W was applied to each thermal mass, E1 and E2 temperatures began to rise. Because the E1 thermal mass (540 grams) was almost twice as large as that of E2 (280 grams), the E2 temperature rose at a faster rate than E1. When the E2 temperature reached 295.5K, the loop started with a 2.5K wall superheat. As mentioned before, with only 5W to E2, the vapor generated at E2 moved toward E1 at a very slow rate, and did not appear to contribute to the rise of the E1 temperature. When the E1 temperature rose to 295.2K (2.2K wall superheat), vapor was generated in E1. The fact that E1 required a 2.2K superheat to generate vapor indicated that vapor generated in E2 had not reached E1 prior to this event, i.e. the E1 evaporator grooves were still flooded with liquid.

Figure 12 shows the loop temperatures during a start-up with a highly uneven heat load of 5W/50W to E1/E2 where TECs were used to keep the CC1/CC2 temperatures at 298K. When 5W/50W was applied, the E2 temperature rose quickly to 298K and vapor was generated in E2 without any superheat. Although the E1 thermal mass was twice that of E2 and received only 5W of power, E1 temperatures rose quickly after vapor had been generated in E2 because of the inherent heat load sharing function between the two evaporators and the high heat load of 50W applied to E2. The fact that E1 started without any superheat indicates that E1 had already received vapor from E2 and its vapor grooves had been cleared of liquid. Following the loop start-up, E2 was at a higher temperature than E1 due to the uneven heat load of 5W/50W and the heat transfer requirement.



Figure 10. Start-up with 5W/0W at 293K



Figure 11. Start-up with 5W/5W at 293K



Figure 12. Start-up with 5W/50W at 298K

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Several start-up tests were conducted under the sideways configuration where the MLHP proto-flihgt was turned 90 degrees sideways so that CC2/E2 was on a horizontal plane and was above CC1/E1 which was on another horizontal plane. However, the routing of the vapor line formed a three-dimensional geometry so that vapor could not flow directly from E1 to E2 by gravitational force alone. Figure 13 illustrates the loop temperatures for a start-up where the CC temperatures were maintained at 308K and a heat load of 10W was applied to E2. Also included are temperature profiles in the subsequent power ramp-up test and the analytical model predictions. When the E2 temperature reached 308K, the loop started without a noticeable superheat. In order for the vapor generated in E2 to reach E1, it must overcome the pressure head resulting from the gravity head. At 10W of heat load, the vapor simply

could not reach E1. In fact, E1 did not share heat in the subsequent power ramp-up test until the E2 power was increased to 50W. The model predictions of the E1, E2 and vapor line temperatures agreed very well with the experimental data for power up to 50W. At 60W, E2 (which was damaged) dried out and the LHP model could not predict the loop behavior. During the warm-up period of E2 and its thermal mass, the E2 inlet temperature fluctuated, indicating that some vapor bubbles might be present. Without any knowledge of the fluid state, the model could not predict its behavior. However, once the loop started and liquid began to move, the model predicted the E2 inlet temperature accurately.

Figure 14 shows the loop temperatures for a high power test where the cryopanels were maintained at 173K and the temperatures of both CCs were uncontrolled. Even heat loads were applied to E1/E4 from 20W/20W to 70W/70W. Both CC1 and CC2 temperatures varied with the heat loads. Test results showed that CC2 controlled the loop operating temperature and CC1 was hard filled with liquid. The E1 and E4 temperature varied with the CC2 temperature and the heat load. The loop could transport 60W/60W without any problem. At 70W/70W, the CC temperatures rose rapidly, an indication that vapor has penetrated the evaporator wick, i.e. the loop had exceeded its capillary limit.



Figure 13. Start-up with 0W/10W at 308K and Subsequent Power Ramp-up Tests in Sideways Configuration



Figure 14. High Power Test without CC Temperature Control

Figure 15 shows loop temperatures during a power cycle test where both CCs were kept at 308K by the TECs and the cryopanels were maintained at 173K. The heat load to E1/E4 was varied as follows: 75W/0W, 50W/25W, 25W/50W, 0W/75W, 5W/50W, 50W/5W, 50W/50W, and 60W/60W. Despite some large variations in the heat load, the TECs were able to control both CC temperatures at the set point temperature of 308K. The temperatures of E1 and E4 varied with the heat load to each individual evaporator due to the heat transfer requirement. This test also demonstrated once again that the loop could transport up to 120W of total heat load (60W/60W to E1/E4).

Figure 16 shows the loop temperatures where the temperatures of Radiator 1 and Radiator 2 were varied independently by setting their control heaters at different set point temperatures. Both CC1 and CC2 were controlled at 293K by TECs, and an uneven heat load of 30W/10W was applied to the E1/E2 thermal masses. The set point temperatures of control heaters for Radiator 1/Radiator 2 were varied as follows: 223K/223K, 298K/223K, 303K/223K. 223K/223K, 223K/298K, 223K/303K, and 223K/223K. The CC1/CC2 temperatures were maintained within ± 1 K of the set point temperature and E1 and E2 temperatures were unaffected by the radiator temperature variations. The flow regulator automatically balanced the heat dissipations between the two condensers. When the temperature of one radiator was raised above the CC saturation temperature, the flow regulator was able to prevent the vapor from entering the liquid line throughout the test as evidenced by the subcooled temperature of the liquid line immediately downstream of the condensers (TC119).

Figure 17 shows the loop temperatures for another radiator temperature cycle test where an uneven heat load of 5W/50W was applied to E1/E2 and both CCs were maintained at 298K using TECs. The control heater set points for Radiator 1/Radiator 2 were varied as follows: 223K/223K, 243K/223K. 298K/223K, 303K/223K, 223K/223K, 223K/303K, and 223K/223K. Again, the E1 and E2 temperatures were unaffected by the changes in the radiator temperatures. When the temperature of one of the radiators was raised higher than the loop saturation temperature, the flow regulator was able to redistribute the vapor between the two condensers and prevent the vapor from entering the liquid line.

The ability of the CC to control the loop operating temperature when the heat load distribution between the evaporators or when the condenser sink temperatures varied have been shown in Figures 15 to 17. Several tests were also performed to demonstrate that the loop operating temperature itself could be varied and the loop still performed smoothly during the transitions. Figure 18 depicts loop temperatures during a CC set point change test. In the first part of the test, a heat load of 52W/5W was applied to E1/E2 thermal masses (or instrument simulators, "IS1" or "IS2" on the figure). The temperature inside the thermal vacuum chamber surrounding the evaporators/CCs,



Figure 15. Power Cycle Test with Uneven Power at 308K



Figure 16. Flow Regulation Test with Uneven Power at 293K



Figure 17. Sink Temperature Cycle Test with Uneven Power at 298K

thermal masses, vapor line, and liquid line, was about 283K. The TECs were able to keep both CCs at 273K. The temperatures of both CCs were then raised from 273K to 298K in steps with 5K increments. Temperatures of E1, E2 and their thermal masses rose in tandem with the CC temperature rise. In the second part of the test, a heat load of 5W/50W was applied to E1/E2 thermal masses. The temperatures of both CCs were decreased in steps with 5K increments. Again, temperatures of E1, E2 and their thermal masses decreased with the CC temperatures. This test demonstrated the ability of the CCs to control the loop operating temperature when the temperatures of the CCs were changed.

For typical heat load sharing tests designed to demonstrate the ability of the unpowered evaporator to share heat from the powered evaporator, some active cooling method is provided to the unpowered evaporator or its attached thermal mass so that the amount of heat that is shared can be quantitatively determined. The MLHP proto-flight was intended for a space flight demonstration and no active cooling was incorporated in its design. Nevertheless, the heat load sharing function can still verified qualitatively by applying power to one of the evaporator thermal masses and then raising the CC set point temperature in steps. If temperatures of the un-powered evaporator/thermal mass also rise near the newly set CC temperature, one can infer that the heat source comes from the vapor generated by the powered evaporator, thus demonstrating the heat load sharing function.

Figure 19 shows the results of a heat load sharing test where a heat load of 30W was applied to E2, and the CC2 set point temperature was increased from 273K to 313K in steps with 5K increments. As the CC2 temperature increased, not only did the powered evaporator E2 and its instrument simulator rise in temperature accordingly, but the unpowered evaporator E1 and its thermal mass also rose to near the CC2 temperature.

Figure 20 shows the temperatures in a heat load sharing test where a heat load of 30W was applied to E1. The test was a mirror image of test shown in Figure 19, and similar results were obtained. Also shown in the







Figure 20. Comparison of Analytical Model Predictions (Thin Lines) and Experimental Data (thick Lines) of a Heat Load Sharing Test

figure are the analytical model predictions of the temperatures of the CCs, evaporators, and thermal masses. The model predictions were in excellent agreement with the experimental data.

Figure 21 depicts another heat load sharing test where E2 received 50W and E1 was unpowered. The CC2 temperature was increased from 298K to 313K and then decreased from 313K to 298K with 5K increments. It is seen that the temperatures of E1 and its thermal mass increased with an increasing CC2 temperature, indicating that E1 worked as a condenser and shared heat from E2. When the CC2 temperature was decreasing, both E1 and its thermal mass also decreased in temperature, indicating that E1 switched its operation back to the normal evaporator mode and dissipated heat that was stored in its thermal mass. This test illustrated that the evaporator would switch its operation automatically between the condenser and evaporator modes as the thermal condition of its surrounding environment changed.



VII. Conclusion

The MLHP proto-flight unit demonstrated excellent performance in the thermal vacuum test. The loop started successfully and operated stably under various evaporator heat loads and condenser sink temperatures. The TECs could keep the loop operating temperature within ± 1 K of the desired set point temperature at all power levels and all sink temperatures. The un-powered evaporator automatically drew heat from the other powered evaporator, demonstrating the heat load sharing function. The flow regulators could regulate the heat dissipation among the radiators, and prevent vapor from entering the liquid line when one of the condensers exhausted its heat dissipating capability. Predictions of the LHP analytical model agreed very well with experimental data in all cases that were correlated. All of the success criteria were met or exceeded.

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