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# Microcoil Spring Interconnects for Ceramic Grid Array Integrated Circuits

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# LIST OF ACRONYMS AND SYMBOLS

Ag	silver			
AU	Auburn University			
Au	gold			
CBGA	ceramic ball grid array			
CCGA	ceramic column grid array			
CTE	coefficient of thermal expansion			
Cu	copper			
DC	direct current			
EEE	electrical, electronic, and electromechanical			
HFSS	high-frequency structure simulator			
I/O	input/output			
MCS	microcoil spring			
MSFC	Marshall Space Flight Center			
Ni	nickel			
PBGA	plastic ball grid array			
Pb	lead			
PCB	printed circuit board			
Pd	palladium			
RF	radio frequency			
Sn	tin			
TC	thermal cycling			
W	tungsten			

#### TECHNICAL MEMORANDUM

## MICROCOIL SPRING INTERCONNECTS FOR CERAMIC GRID ARRAY INTEGRATED CIRCUITS

#### 1. INTRODUCTION

Current aerospace avionic designs routinely use integrated circuits packaged in the area array format. Unfortunately, the area array package trades the compliance of ribbon leads for the quantity of noncompliant solder balls, which under thermal cyclic loading, severely limits the life of the solder joints.

One approach to overcome this limitation was to replace the noncompliant balls with slightly more compliant solder columns. Another approach was to package the silicon microcircuit on an organic substrate and plastic encapsulate it rather than put it on a ceramic substrate and hermetically seal it. The coefficient of thermal expansion (CTE) of a plastic ball grid array (PBGA) more closely matched the CTE of the printed circuit board (PCB) than the CTE of a ceramic ball grid array (CBGA). There are always tradeoffs to be made and the price initially paid for using a PBGA was that the plastic absorbed moisture and moisture could initiate corrosion and result in a failure rate that was unacceptable for high reliability space flight electronics. With time, the processes and materials have improved such that the moisture absorption is much lower but a plastic encapsulated microcircuit is still not a hermetically sealed part. Electrical, electronic, and electromechanical (EEE) parts personnel prefer ceramic column grid array (CCGA) packages for highest reliability critical applications.

Reliability of various configurations of flexible interconnects for ceramic area array packages are reported in the literature.<sup>1–5</sup> Variation in test methods and test vehicle configurations make it difficult to perform direct comparisons with a high confidence level. NASA Marshall Space Flight Center (MSFC) initiated a research project to test a variety of flexible interconnects while holding constant (as nearly as possible) the ceramic substrate design, PCB design, and test methods so that reliability could be fairly compared.

A long-term human presence in space without the benefit of resupply will require confidence levels not previously required. Due to this and existing reliability data on columns, MSFC started investigating other potential flexible interconnects to improve the thermal reliability of ceramic area array packages. Preliminary assembly experiments with springs of various configurations were conducted. As a result of these preliminary experiments, a microcoil spring (MCS) was chosen and introduced into the test program.

The MCSs provide ample flexibility to withstand the shear forces resulting from the CTE mismatch and are much more robust from a handling perspective than high lead columns. However, the MCSs do not have planarized end faces which makes attachment challenging.

# 2. MICROCOIL DESIGN

The MCS (fig. 1) is fabricated from a beryllium copper (Cu) wire 0.0034 in thick and is post plated with 100 µin of tin lead (Sn63Pb37). The springs are 0.020 in diameter by 0.050 in long with a 0.010 in pitch and two to three closed coils on each end.

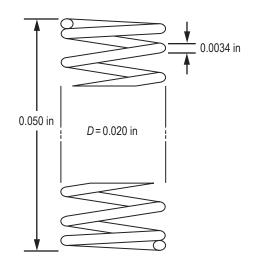


Figure 1. MCS design.

#### 3. TEST VEHICLE DESIGN AND EVALUATION

The primary ceramic substrate and PCB were designed by MSFC's Parts, Packaging, and Fabrication Branch. The ceramic substrates are 21.5 mm  $\times$  21.5 mm  $\times$  1 mm. The substrates are daisy-chained, two layers and 1 mm pitch. Each substrate consists of four channels (fig. 2) which are made up of 100 daisy-chained interconnects. The current ceramic substrates were fabricated using a thick film technique with a minimum of three layers of silver (Ag)/palladium (Pd) paste to form metallization  $\approx$ 0.001 in thick. The pad diameter has ranged from 0.025 to 0.030 in. Early in the study, 0.025 in was used due to the ball size chosen. Subsequently, the pad diameter was changed to 0.030 in to accommodate columns and MCSs. The same pad diameter is used on both the substrate and PCB. Early in the study a four-layer ceramic with tungsten (W)-nickel (Ni)-gold (Au) metallization was used, but it was abandoned due to cost. The interconnects tested with this metallization are noted in table 1.

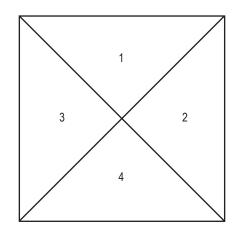


Figure 2. Ceramic channel configuration.

Test Vehicle*	No. of TV's	Ceramic Configuration	Solder Used for First Attach	Stencil Thickness/Aperture (PCB Attach)	Use
Initial MCS*	2	25 mil/Ag-Pd	Tin/lead	4 mil/100%	TC @ MSFC
95/5 CCGA	3	30 mil/Ag-Pd	Tin/lead	8 mil/100%	Vib @ AU then TC @ MSFC
85/15 CCGA*	1	25 mil/W-Ni-Au	Tin/lead	8 mil/100%	TC @ AU
90/10 CBGA*	2	25 mil/Ag-Pd	Tin/lead	4 mil/100%	TC @ MSFC
Polymer CBGA*	2	25 mil/Ag-Pd	Tin/lead	6 mil/100%	TC @ MSFC
Reworked MCS	3	30 mil/Ag-Pd	Tin/lead	6 mil/100% (1) and 4 mil/75% (2)	TC @ MSFC
MCS Vibration	1	30 mil/Ag-Pd	Tin/lead	4 mil/100%	Vib @ AU then TC @ MSFC

Table 1. Test vehicle configuration.

\*All test vehicles with asterisks were fabricated using a 0.062-in, double-sided PCB with 0.025-in-diameter pads. The remainder were fabricated using a 0.093-in, double-sided PCB with 0.030-in pads.

Unless otherwise noted, the PCB (fig. 3) is four layers, two of which are ground planes for stiffness and is designed to accommodate eight parts. The overall thickness is 0.093 in.

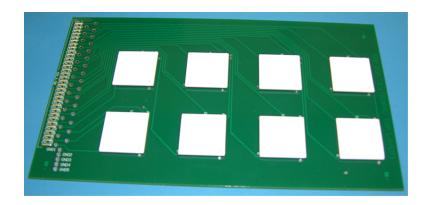


Figure 3. Test vehicle.

The following interconnects were included in the thermal cycling phase of the study:

- Sn5/Pb95 wire column (0.018×0.087 in).
- Sn15/Pb85 column (0.015×0.087 in).
- Polymer cored ball (650  $\mu$ m).
- Sn10/Pb90 solder balls (0.025 in).
- MCS (0.020×0.050 in).

Vibration testing was conducted on test vehicles with Sn5/Pb95 wire columns and MCSs.

# 3.1 Interconnect First Attach to Ceramic Substrate

Except for the Sn15/Pb85 columns, all interconnects were attached by MSFC using a twopiece fixture (fig. 4) that holds a single ceramic substrate. Solder paste is deposited onto the ceramic substrate using an automatic stencil printer. After inspection, the substrate is loaded into a graphite fixture stage (bottom) and a graphite interconnect positioning fixture (top) is lowered onto the stage. The positioning fixture has apertures that match the pattern on the ceramic with the apertures sized for the interconnect diameter being attached. After the apertures are filled with interconnects, the whole fixture is loaded onto a pallet and reflowed in a vapor phase reflow oven. For ball interconnects, the interconnect positioning fixture (top) is removed prior to reflow which aids in ball to ceramic pad alignment.

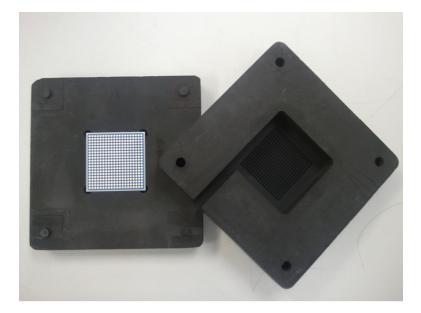


Figure 4. Interconnect attachment fixture.

For the MCS, the stencil thickness, stencil aperture size, and solder alloy were varied. The first thermal cycling test vehicles were fabricated using SnPb solder paste for attachment to both the ceramic substrate and the PCB. The stencil thickness was 0.004 in, resulting in the best thermal reliability to date. To improve yield, the solder paste for first attach (to ceramic) was changed to Sn-Ag-Cu (SAC305) to prevent its reflow and MCS movement during second attach. The stencil thickness has been optimized at 0.006 in for the MCS design currently being used. This results in the best fillets. Recently, a process step was added to remove MCS oxidation during first attach by using flux and a double reflow process which has allowed a return to SnPb paste without a decrease in yield. Thermal cycling for test vehicles fabricated using the double-pass reflow process and a 0.006-in-thick stencil is ongoing and results are not presented herein.

# 3.2 Board-Level Fabrication

Solder paste was deposited using an automatic stencil printer. Part placement was achieved using a semi-automatic, split-vision placement machine. Reflow except for rework was conducted in a vapor phase reflow oven. Endoscopic and x-ray inspections were performed prior to initiation of environmental testing. A typical MCS from the first thermal cycling test vehicle is presented in figure 5. Notice the lack of side fillets.

A typical wire column (Sn5/Pb95) is shown in figure 6. An 8-mil-thick stencil was used to attach the Sn5/Pb95 columns to both the ceramic and the PCB.

A typical polymer cored solder ball is shown in figure 7. The ball is  $650 \,\mu\text{m}$  and has a Sn-Ag over Cu finish. A 6-mil-thick stencil was used to attach the polymer cored solder balls to both the ceramic and the PCB.

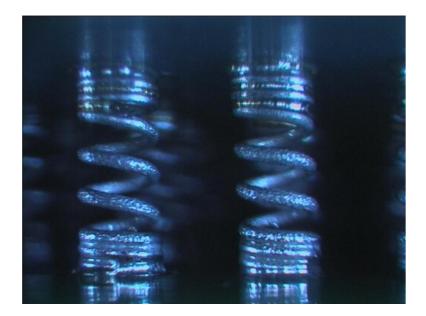


Figure 5. MCS 4-mil stencil.

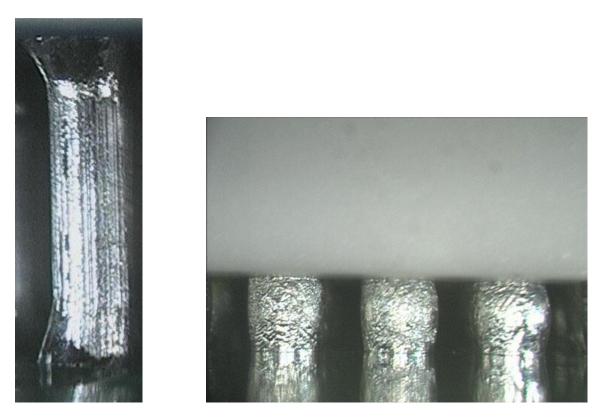


Figure 6. Typical wire column.

Figure 7. Polymer cored solder ball.

The overall test vehicle configuration is presented in table 1 along with the environmental tests performed on each unit.

#### 3.3 Thermal Cycling

Thermal cycling was conducted at MSFC and at Auburn University (AU). The range was –55 to 125 °C with 15-min dwells at the extremes. Auburn University conducted the thermal cycling of the 85/15 CCGA test vehicles. MSFC performed the thermal cycling of the remainder of the test vehicles.

The AU tests were monitored using a data logger. The failure criteria used was a 50% increase in resistance for 10 consecutive thermal cycles. The AU testing consisted of 400 interconnects per channel and one 85/15 CCGA test board with five parts. Testing was conducted in a thermal cycling chamber.

The MSFC tests were monitored using an event detector. The failure criteria were per IPC-9701A, 4.3.3.3, with a 1,000  $\Omega$  threshold. Testing was conducted in a thermal forcing unit with a custom enclosure;  $\approx$ 19 cycles per day were obtained.

A composite Weibull is shown in figure 8. The initial MCS (MCS on 25-mil pad) significantly outperformed 85/15 CCGAs and 95/5 CCGAs. The initial MCS test vehicles had many individual springs that were misaligned to the PCB pads by as much as 50%. The first recordable failure (other than one infant mortality at 400 cycles) occurred at 4,760 cycles. For space flight systems, first failure is considered a more important factor than characteristic life.

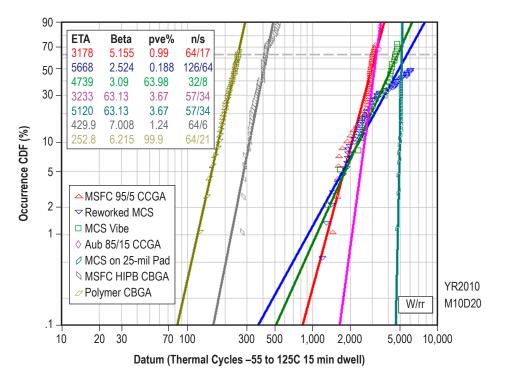


Figure 8. Thermal cycling results.

Metallographic analysis and endoscopy of failed MCSs (figs. 9 and 10) and 95/5 columns were performed to verify failure mode. All MCS failures observed were in the solder joint interface with the ceramic pad. The failures appear to have begun parallel to the interface which is expected, but as the failure propagated, a perpendicular crack developed in several of the microsections observed. Metallographic analysis was also used to verify that the Ag-Pd pad on the ceramic was not being leached into the solder joint during multiple reflows. No evidence of pad failure or significant leaching was found.

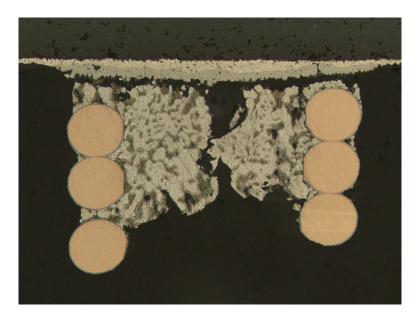


Figure 9. Failed MCS (MCS-2-U1-3) thermal cycling.

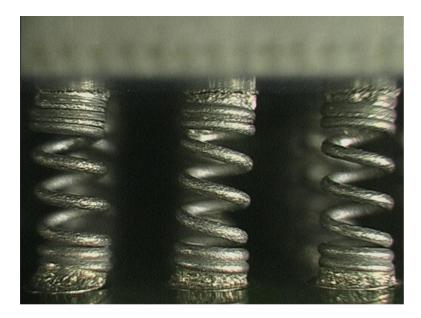


Figure 10. Failed MCS (MCS-1-U1-4) thermal cycling.

# 3.4 Vibration

Vibration testing was conducted at AU. The test vehicles used the same PCB and ceramic parts. The only difference from the thermal cycling test vehicles is that an aluminum mass was attached to each ceramic to simulate the mass of a comparably sized active ceramic package (fig. 11). One 95/5 CCGA and one MCS test vehicle were vibration tested.

Each test vehicle was hard wired to a shielded cable that attached to an event detector system. An event was recorded when the channel resistance exceeded 1,000  $\Omega$ , which in each case, constituted a failure since these resistance changes were hard and did not show intermittency. The wires were staked to the back side of the board (fig. 12).

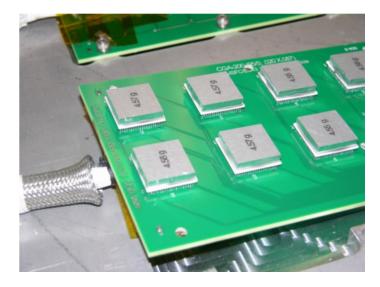


Figure 11. Vibration test vehicle.



Figure 12. Wire staking.

The test vehicles mounted to the vibration fixture and the shaker table are shown in figure 13.



Figure 13. Fixture and shaker.

Prior to performing the random vibration test a resonance search sine sweep was performed with the boards mounted in the *x* axis at a sweep range 5-2,000-5 Hz, sweep rate: two octaves per minute, amplitude 0.25 g.

The *z* axis is perpendicular to the surface of the unit under test. The *x* axis is defined as the shortest board dimension (4 in). Random vibration testing was performed at three different levels for 10 min at each level in the *x* axis and the *z* axis, for a total test time of 1 hr. The random vibration levels are presented in table 2.

The testing sequence was 0.25 g sine sweep, 5gx, 5gz, 8gz, 8gx, 10gx, and 10gz. There was a system natural frequency at  $\approx$ 420 Hz and another at 900 Hz. The MCSs were recorded as channels 1–32 and the 95/5 columns as channels 33–64. Throughout the test there were no failures of the MCSs. There were 10 failures of the 95/5 columns. The failure data are shown in table 3. The location of the failed circuits on the column grid array test board is shown in figure 14. The failures were resistance failures only. No parts were shaken off of the boards.

Level I					
20 Hz @ 20–50 Hz @ 50–1,000 Hz @ 1,000–2000 Hz @ 2,000 Hz @	0.0025 g <sup>2</sup> /Hz 6 dB/oct 0.01675 g <sup>2</sup> /Hz –6 dB/oct 0.005 g <sup>2</sup> /Hz				
Composite = 5 gm					
Leve					
20 Hz @ 20–50 Hz @ 50–1,000 Hz @ 1,000–2,000 Hz @ 2,000 Hz @ Composite = 8 gm	0.00698 g <sup>2</sup> /Hz 6 dB/oct 0.0438 g <sup>2</sup> /Hz -6 dB/oct 0.0109 g <sup>2</sup> /Hz				
Level	Ш				
20 Hz @ 20–50 Hz @ 50–1000 Hz @ 1,000–2,000 Hz @ 2,000 Hz @	0.01 g <sup>2</sup> /Hz 6 dB/oct 0.067 g <sup>2</sup> /Hz –6 dB/oct 0.02 g <sup>2</sup> /Hz				
Composite = 10 gm					

Table 2. Vibration test levels.

Table 3. Vibration failures.

g Level	Axis	Failed Channel	Time Into Run (min)	Total Vibration Time to Failure (min)
5	х	-	_	-
5	z	59	10	20
8	z	61	4	24
8	z	62	7	27
8	x	58	6	36
10	x	57	6	46
10	z	44	3	53
10	z	33	5	55
10	z	41	7	57
10	z	42	7	57
10	z	36	8	58

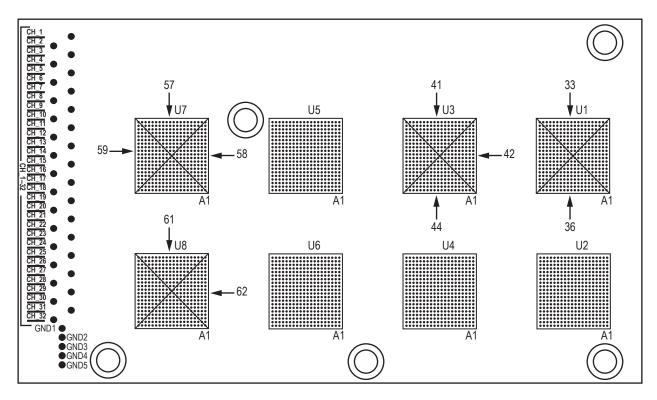


Figure 14. Vibration failure locations.

The failures were investigated by endoscopy, x-ray, and destructive physical analysis. The outer rows of columns of failed channels were subjected to endoscopic visual inspection. Cracks were observed in the columns generally at the point where the 63/37 solder fillet joined the column. Figure 15 shows examples of cracks in both the upper and lower fillets. Figure 16 shows the most extreme failure observed.

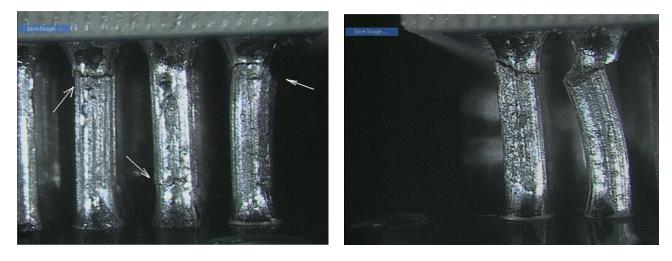


Figure 15. Column cracks.

Figure 16. Column displacement.

#### 3.5 Radio Frequency Simulation

Radio frequency simulations were run on the MCS and the column configurations. The simulation was performed from the kilohertz range up to 10 GHz. The insertion loss, the coupling (crosstalk), and the effective inductance of each configuration was simulated and compared. The simulations were done with a high-frequency structure simulator (HFSS) at MSFC in the Data and Radio Frequency Systems Branch of the Space Systems Department.

Table 4 compares the insertion loss for MCSs and columns over a frequency range of 500 MHz to 5 GHz. The insertion loss shows how much power is transferred from one end of the column or MCS to the other. The insertion loss of the MCS configuration is a little worse than the column configuration. The insertion loss of each configuration is similar at the lower frequencies. As the frequency increases, the insertion loss of the MCS increases slightly faster than the column. The difference in performance decreases as the configurations are used at lower frequencies.

Frequency	MCS (%)	Column (%)
500 MHz	98.3	98.9
1 GHz	96.4	97.9
2 GHz	89	92.5
3 GHz	79.1	85.0
4 GHz	69.1	77.0
5 GHz	59.8	69.3

Table 4. Power transferred—HFSS simulation—MCSs versus columns.

Table 5 compares coupling (crosstalk) of MCSs and columns. The coupling shows how much power is transferred from one column to an adjacent column. The coupling of the MCS versus the column is slightly better at the lower frequencies but then becomes much better at the higher frequencies. The worst coupling of the MCS configuration was about -22.9 dB (0.52% power transfer), which occurred at 4 GHz. At this frequency, the coupling of the column configuration was -13 dB (5% power transfer). However, the coupling of the MCS improves slightly as the frequency increases whereas the coupling of the column degrades. The worst coupling of the column configuration was about -10 dB (10% power transfer), which occurred at 9.9 GHz.

Table 5. Crosstalk (coupling)—HFSS simulation—MCSs versus columns.

Frequency	MCS (%)	Column (%)
500 MHz	0.086	1.19
1 GHz	0.17	0.4
2 GHz	0.59	1.5
3 GHz	1.06	2.9
4 GHz	1.4	4.4
5 GHz	1.7	5.8

The inductance of the MCS and the column configurations was calculated over the frequency range of the simulation (500 MHz to 10 GHz). The inductance of the MCS was 2.7 nH, and the inductance of the column was 2.2 nH.

#### 3.6 Inductance Measurement

The inductance of one test vehicle channel which is comprised of 100 interconnects was determined using a frequency analyzer capable of measurements up to 2.2 MHz. This frequency range was sufficient to show the inductive component of the interconnects but it was not sufficient to show parasitic capacitances which often show up in higher frequency ranges. The data for each test vehicle includes the inductive contribution due to the test leads connecting the test units and the instrument. The contribution of the test leads can be subtracted from the data. What cannot be removed is the resistance and inductance associated with the interconnections between 100 individual interconnects. It may be assumed that they are small but a more precise evaluation of the interconnects needs to be performed using an inductance/capacitance/resistance bridge or frequency response analyzer and a test fixture capable of holding individual interconnects.

The MCS DC resistance component was measured at  $\approx 3 \Omega$  and the inductive component was measured at  $\approx 484$  nH (after the inductance of the test leads is subtracted). Since there are 100 interconnects in series, the per unit resistance and inductance is calculated as follows:

- Per unit DC resistance =  $3 \Omega/100 = 0.03 \Omega$ .
- Per unit inductance = 484 nH/100 = 4.84 nH.

The column DC resistance measured at  $\approx 0.9 \Omega$  and an inductive component was measured at  $\approx 591$  nH (after the inductance of the test leads is subtracted). Since there are 100 interconnects in series, the per unit resistance and inductance is calculated as follows:

- Per unit DC resistance =  $0.9 \Omega/100 = 0.009 \Omega$
- Per unit inductance = 591 nH/100 = 5.91 nH.

## 4. STRESS ANALYSIS

A simplified finite element model of an MCS and a column was created (see fig. 17) and a stress analysis was performed to illustrate the stress on the two interconnects for given deflections (see fig. 18).

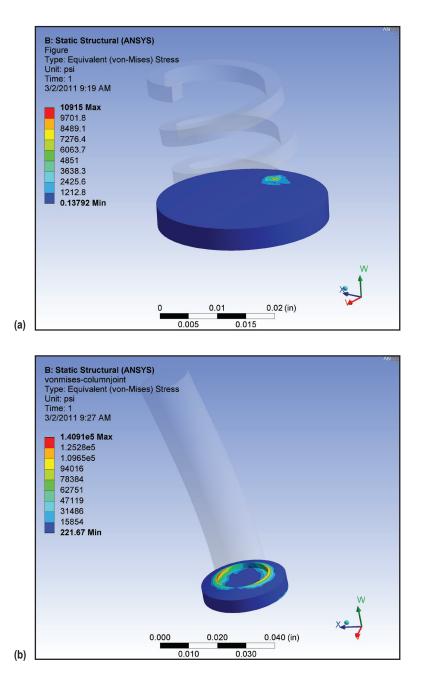


Figure 17. Simplified FEA model—(a) MCS and (b) column.

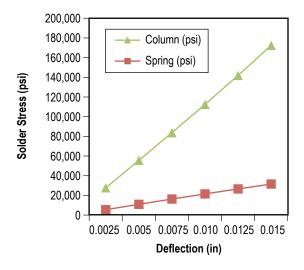


Figure 18. Solder stress—MCS versus column.

A preliminary assessment was conducted to determine the Von Mises stress in the solder joints associated with the MCS versus column configuration. This was a static analysis conducted using the finite element analysis software ANSYS Workbench. For the analysis, a deflection was assigned beginning with 0.0025 in and progressing up to 0.015 in in 0.0025-in increments. The maximum stress levels determined from this deflection are shown in table 6 regarding the solder joints for both the MCS and column configurations. These results are theoretical and have not been verified by testing.

Deflection (in)	MCS (psi)	Column (psi)
0.0025	5,455	22,248
0.0050	10,915	44,656
0.0075	16,282	67,477
0.0100	21,499	90,962
0.0125	26,571	115,360
0.0150	31,525	140,915

Table 6. Maximum stress levels.

## 5. SUMMARY

Thermal cycling and vibration testing have shown MCS interconnects to be significantly more reliable than solder columns. Also, MCS interconnects are less prone to handling damage than solder columns. While attachment of MCS parts to PCBs is more challenging than columns, they do not require shearing to obtain acceptable coplanarity.

Initial thermal cycling yielded better results than subsequent testing. The samples tested since the initial MCS reported herein were fabricated using a process that resulted in higher yields but lower reliability. The current process is very similar to the initial process except for addition of a deoxidizing step.

MCSs are expected to outperform columns in a mechanical shock environment based on deflection analysis and preliminary shock testing.

With further refinement of the attach process, it is anticipated that CGAs populated with MCSs can achieve >5,000 thermal cycles prior to first failure without the need for mechanical corner support.

MCSs can be manufactured with overall diameter as small as 0.006 in using conventional microcoiling technology. It is possible to use MCSs on column grid arrays down to 0.65-mm pitch.

An important item to note is that the MCS design has not been optimized for reliablility; only the part/PCB fabrication parameters have been varied to improve second attach. With a change in MCS parameters (i.e., number of active/closed coils, overall length), reliability could be further improved. Of course, physical changes to the MCS must be traded with changes in inductance, capacitance, crosstalk, and insertion loss.

# 6. FUTURE WORK

Testing of process improvements to remove oxidation and to improve the MCS to ceramic/ PCB fillets is ongoing. Fillets that result from depositing solder with a 0.006-in-thick stencil are shown in figure 19. The fillets are much improved, however, the open coils of the MCS are more restrained.

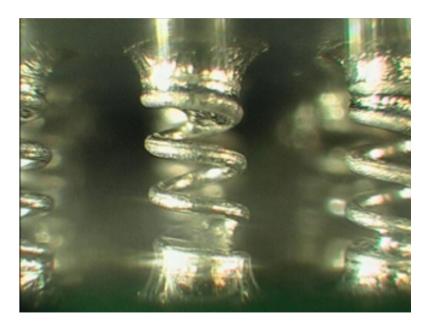


Figure 19. MCS fillet with 6-mil stencil.

An extensive mechanical shock test program is underway and is currently in the fabrication phase. Testing will be conducted by AU and will include MCSs and 95/5 columns. Completion of this study is needed to provide confidence for MCSs use in applications with high g liftoff environments.

Implementation of MCSs in a digital signal processor board has begun and is currently in the procurement phase. After fabrication completion, functional testing of the design will be conducted to judge the effects on circuit function and rise time in particular.

Testing of the current MCS design on a higher input/output (I/O) daisy-chained ceramic substrate is planned within the next year. The substrate will consist of 1,152 I/O. Also, design of a smaller diameter MCS is in process for testing on a daisy-chained ceramic substrate with 0.80-mm pitch.

A cast Sn10/Pb90 column (0.020 in diameter) is being added to the test program this year.

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14. ABSTRACT As integrated circuit miniaturization trends continue, they drive the need for smaller higher input/output (I/O) packages. Hermetically sealed ceramic area array parts are the package of choice by the space community for high reliability space flight electronic hardware. Unfortunately, the coefficient of thermal expansion mismatch between the ceramic area array package and the epoxy glass printed wiring board limits the life of the interconnecting solder joint. This work presents the results of an investigation by Marshall Space Flight Center into a method to increase the life of this second level interconnection by the use of compliant microcoil springs. The design of the spring and its attachment process are presented along with thermal cycling results of microcoil springs (MCS) compared with state-of-the-art ball and column interconnections. Vibration testing has been conducted on MCS and high lead column parts. Radio frequency simulation and measurements have been made and the MCS has been modeled and a stress analysis performed. Thermal cycling and vibration testing have shown MCS interconnects to be significantly more reliable than solder columns. Also, MCS interconnects are less prone to handling damage than solder columns. Future work that includes shock testing, incorporation into a digital signal processor board, and process evaluation of expansion from a 400 I/O device to a device with over 1,100 I/O is identified.							
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