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MODAL ANALYSIS AND CORRELATION OF INTERNATIONAL SPACE STATION EARLY CONFIGURATIONS

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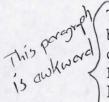
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Abstract Submitted for Consideration to The 18th International Model Analysis Conference February 7-10, 2000 San Antonio, Texas

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This paper will summarize the modal analysis and model refinement results for the International Space Station (ISS) Flight-2A mated configuration.



This personal be completed in 91 incremental assembly stages. The ISS mated Flight-2A configuration consists of two modules with docked Space Shuttle Endeavor. One of the modules is the Functional Cargo Block (FGB), also known as Zerus that what we have the started in Started Flight-2A configuration as Terus that we have the started in Started Flight-2A configuration as Terus that we have the started in Started Flight-2A configuration as Terus that we have the started flight started in Started Flight-2A configuration and the started flight Proton vehicle in November 1998. In December 1998, Space Shuttle Endeavor added the U.S. Node 1, also known as Unity.

missing GMC

To maintain structural integrity of the ISS, structural loading distributions have been rigorously analyzed through numerical simulation and taken into account during the design of the structure and mission operations. The accuracy of the analysis results is directly affected by the precision of mathematical models and estimated input forces.

A mathematical model of an ISS configuration is composed of individual component math models. Each component model is required to be correlated with ground test data. However, it is expected that on-orbit mathematical models will still contain modeling errors due to differences in boundary conditions, mass distributions, and gravitational fields. Hence, it is highly desirable to correlate on-orbit mathematical models using test data measured on orbit.

Time responses were measured during on-orbit Shuttle structural dynamic tests and Shuttle reboost. The structural responses were recorded by a combination of three instrumentation systems, including: Shuttle Inertial Measurement Unit (IMU), FGB Structural Dynamic Measurement System (SDMS), and the Shuttle payload bay video cameras.

Modal analysis was performed on the measured time data to determine frequencies, damping factors, and mode shapes. Traditional modal analysis methods using frequency response functions (FRFs) were not used since the input excitation forces were not A special modal identification method that does require input force measured. measurement was applied. Test modal parameters were then used to verify and correlate the math models.