

# Lightning Reporting At 45th Weather Squadron: Recent Improvements

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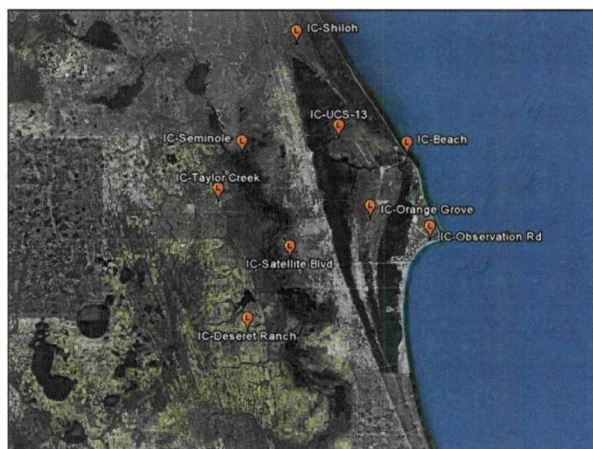
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## 1. INTRODUCTION

The 45th Weather Squadron (45 WS) is the U.S. Air Force unit that provides weather support to America's space program at Cape Canaveral Air Force Station (CCAFS), National Aeronautics and Space Administration (NASA) Kennedy Space Center (KSC), and Patrick AFB (PAFB). The weather requirements of the space program are very stringent (Harms et al., 1999). In addition, the weather in east central Florida is very complex. This is especially true of summer thunderstorms and associated hazards. Central Florida is 'Lightning Alley', the area of highest lightning activity in the United States (U.S.) (Huffines and Orville, 1999). The 45 WS uses a dense network of various weather sensors to meet the operational requirements in this environment (Roeder et al., 2003).

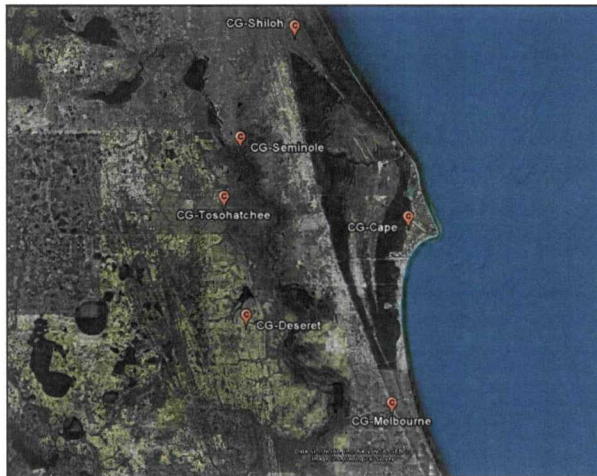
The 45 WS is especially well instrumented with lightning detection sensors. The Four Dimensional Lightning Surveillance System (4DLSS) (Murphy et al., 2008) included a major upgrade to the total lightning detection Lightning Detection And Ranging (LDAR) system (Boccippio et al., 2001). The 4DLSS was implemented operationally in April 2008. A map of the total lightning sensors of the 4DLSS is in Figure-1. The 4DLSS also

upgraded the Cloud to Ground Lightning Surveillance System (CGLSS) (Boyd et al., 2005) and integrated it into the 4DLSS. A map of the cloud to ground lightning sensors of the 4DLSS is in Figure-2. The 45 WS also uses the Launch Pad Lightning Warning System (LPLWS) (Eastern Range Instrumentation Handbook, 2009), a network of 31 surface electric field mills that has a limited total lightning detection capability. A map of the field mills in LPLWS is in Figure-3. The last lightning detection system used by 45 WS is a direct connection to the National Lightning Detection Network (NLDN) (Orville et al., 2002).



**Figure 1.** Map of the nine total lightning sensors in the Four Dimensional Lightning Surveillance System.

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**Figure 2.** Map of the six cloud to ground lightning sensors in the Four Dimensional Lightning Surveillance System.



**Figure 3.** Map of the 31 surface electric field mills in the Launch Pad Lightning Warning System.

The 45 WS uses these lightning sensors for several applications (Roeder et al., 2005). One of these applications is the evaluation of lightning launch commit criteria, the weather rules to avoid natural and rocket triggered lightning strikes to in-flight space launch vehicles (Roeder and McNamara, 2006). Another application is

lightning watches and warnings for the safety of over 25,000 personnel and protection of over \$20 billion of facilities (Weems et al., 2001). Another application is daily lightning reports to customers. Other applications include incident investigations, climatological studies for mission planning, and development of new or improved forecast tools.

The daily lightning reports include the distance and peak current of cloud-to-ground (CG) lightning strokes in the vicinity of key facilities. Nearby lightning strokes can induce potentially damaging electric currents in the electronics in satellite payloads, space launch vehicles, ground support equipment, or key facilities. The daily lightning reports are used to decide if the various electronics should be inspected and, if so, what level of inspection is required. If damage occurred, it is essential to conduct those inspections to identify and implement required fixes to avoid potential post-launch problems or early failure of the electronics that could result in degradation or mission failure, or in extreme cases, even destruction of the space launch vehicle. However, it is also important to avoid unnecessary inspections due to their financial cost and delays to space launch schedule. The lightning reports assist mission planners in weighing the risks of conducting, or not conducting, further inspections. This paper will describe the significant improvements to the 45 WS lightning reports since April 2008.

## 2. Recent Improvements to the 45 WS Lightning Reports

The 45 WS and their mission partners made five major improvements to their lightning reports from April 2008 through 2009: 1) reporting of all strokes, 2) inclusion of lightning location error ellipses

tailored to each stroke, 3) on-demand 24/7 availability of lightning reports, 4) correction of a truncation error of the peak current in the lightning database, and 5) KSC automated e-mail alerts and posting of lightning events at a website.

### 2.1 Reporting All Lightning Strokes

The recent improvements to the 45 WS lightning reports began when the 4DLSS became operational in April 2008 (Murphy et al., 2008). One of the many benefits of 4DLSS is that all return strokes per flash are reported. The previous CGLSS lightning system used by 45 WS only reported one stroke per flash. Detecting and reporting all return strokes is important since CG lightning has an average of 3.5 strokes per flash and 50% or more of these strokes have multiple ground strike locations (Cummins et al., 1998). These multiple ground strike locations have an average spacing of 3 km and can extend up to 12 km (Valine and Krider, 2002). Reporting only one stroke per flash, as done by the former CGLSS, meant these other return strokes would not be reported and potentially necessary inspections would be missed.

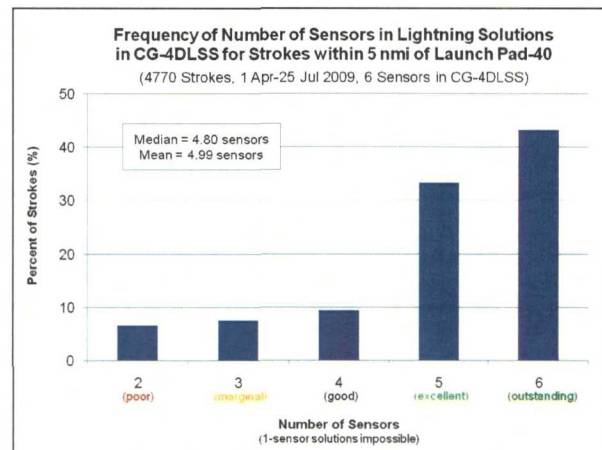
### 2.2 Lightning Location Error Ellipses Tailored To Each Stroke

Another significant improvement in the 45 WS lightning reporting procedures was the inclusion of stroke location error ellipses tailored to each individual stroke. This provided finer details for the location reporting uncertainty and overcame several previous shortfalls.

#### 2.2.1 Previous Shortfalls: single best-case 50% confidence location accuracy

The previous 45 WS lightning location accuracy had several shortfalls. A single location accuracy was used for all lightning strokes in the center of the

network and a 50th percentile confidence for the lightning location was provided. The 45 WS discovered that this location accuracy assumed all six CG lightning sensors were used in the solution. However, 4DLSS often has fewer than all six sensors per solution, even if all six sensors are operating, resulting in larger location errors and more eccentric error ellipses than previously believed. The median number of sensors per solution is 4.80 for local lightning strokes detected by 4DLSS with a distribution shown in Figure-4. Reporting a single constant location accuracy implied circularity of the error, which was misleading. In addition, the customers had requested a 50th percentile location accuracy, but more recent discussion showed this to be inadequate for space launch applications.



**Figure 4.** Distribution of number of sensors used in location solutions by 4DLSS for nearby strokes.

#### 2.2.2 Location Error Ellipses Tailored To Each Stroke With 99% and 95% Percentiles

To address this shortfall, the location accuracy and detection efficiency across the local area was obtained for all possible combinations of sensors in the solutions. As expected from a similar

study on the older 5-sensor configuration of CGLSS, the performance of the new 4DLSS is still sensitive to the central sensor on CCAFS being used in the solution (Table-1). The new CGLSS is relatively insensitive to one, or to a lesser degree even two sensors, not being used in the solution, unless one of those sensors is the central sensor on CCAFS. However, even with these performance plots, the error characteristics for each individual return stroke were still needed since these error characteristics varied based upon the geometry of the stroke location relative to the sensors used in the solution of that stroke.

**Table 1.**

4DLSS performance near the launch pads for all combinations of one sensor excluded from the lightning solution.

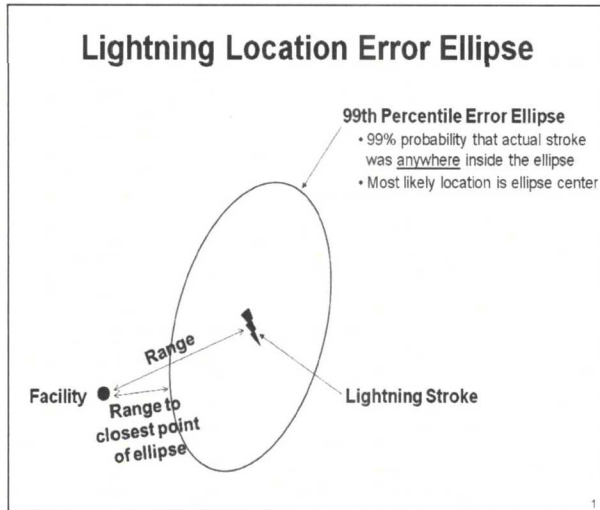
Sensor Missing	Detection Rate (%)	Location Accuracy (median) (m)
None	94%	300 m
Melbourne	93%	350 m
Deseret	93%	350 m
Tosohatchee	92%	350 m
Seminole	91%	400 m
Shilo	91%	450 m
Cape	89%	500 m

Performance is most degraded by the absence of the central Cape sensor in the lightning solution. Similar sensitivity to the Cape sensor absence is seen when higher number of sensors are excluded. See Figure-2 for the CG-lightning sensor sites. Performance estimated from isopleths of modeled performance provided by Vaisala, Inc.

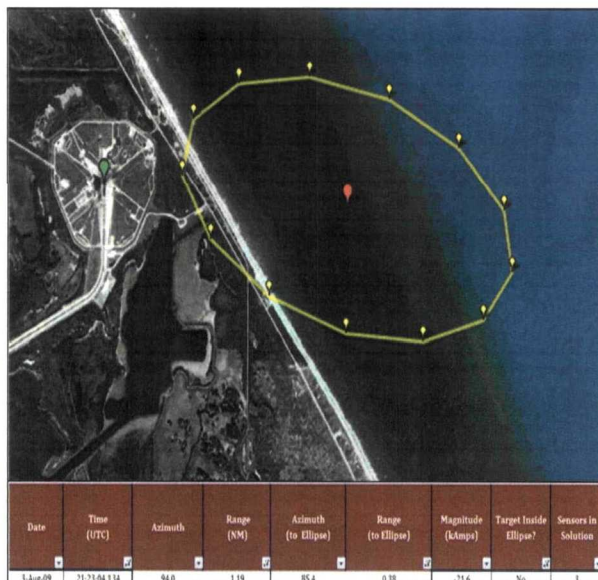
The 45 WS and their mission partners then developed an interim procedure where the raw data from 4DLSS were used to estimate the lightning error ellipses for nearby strokes tailored to each

stroke based on the number of sensors used in the solution, the distance from the sensors to the stroke, and the geometry of the sensors relative to the stroke. Kennedy Space Center requires 99th percentile error ellipses while the rest of the space launch customers use 95th percentile error ellipses. In 99%/95% of the events, the best location of the stroke will be inside the error ellipse and in 1%/5% of the events the best location of the stroke will be outside the ellipse, respectively. The product includes the distance from each key facility to the best location of nearby lightning strokes, i.e. the center of the error ellipse, the distance to the closest edge of the ellipse, and the peak current of the stroke, etc. A schematic diagram of these distances is in Figure-5 and a copy of the product is in Figure-6. For each key facility, the customer specifies a critical distance within which lightning strikes merit additional investigation. A Google-Earth visualization is also available on request (Figure 7).

Customer points of interest include launch pads, payload/space launch vehicle processing facilities, and other facilities. The 29 key facilities supported by the 45 WS daily lightning reports are listed in Table-2. If the distance to the most likely stroke location is larger than the inspection threshold for a stroke of that intensity, then the customer can be confident that inspection of the electronics is not needed. The inspection thresholds allow for the uncertainty in the peak current estimate. If the distance to the edge of the closest point of error ellipse is also larger than the inspection threshold for a stroke of that peak current, then the customer can be very confident that inspection of the electronics is not needed.



**Figure 5.** Schematic diagram of a lightning location error ellipse. Range is the distance from the facility of interest to the best location of the lightning stroke, i.e. the center of the error ellipse. The range to the closest point of the error ellipse is also provided. KSC uses 99th percentile error ellipses, while the rest of the space launch customers use 95th percentile.



**Figure 7.** Example of the Google Maps visualization provided when the lightning strike is within the critical distance. The 13 points used to approximate the location error ellipse are shown.

**TABLE-2.**

Key Facilities for which 45 WS issues daily lightning reports.

Key Facility	Primary Customer
Atlas Space Operations Center	Atlas
Area 59	Delta-IV
Astrotech	Commercial Satellite Processing Facility
Launch Complex-17A	Delta-II
Launch Complex-17B	Delta-II
Launch Complex-36	Space Florida
Launch Complex-37B	Delta-IV
Launch Complex-39A	Kennedy Space Center
Launch Complex-39B	Kennedy Space Center
Launch Complex-40	Falcon-9
Launch Complex-41	Atlas-V
Delta-IV Ops Center	Delta-IV
Falcon Launch Control Center	Falcon
Horizontal Integration Facility	Delta-IV
Joint Surveillance and Target Attack Radar System	U.S. Air Force
Ops & Checkout	Kennedy Space Center
Patrick AFB	45th Space Wing
Payload Hazardous Servicing Facility	Kennedy Space Center
Port	Navy
Range Control Cntr	45th Space Wing
Skid Strip	45th Space Wing
Shuttle Landing Facility-Runway N.	Kennedy Space Center
Shuttle Landing Facility-Runway S.	Kennedy Space Center
Shuttle Landing Facility-Mate/Demate Facility	Kennedy Space Center
Solid Motor Assembly Building	Kennedy Space Center
Shuttle Payload Integration Facility	Kennedy Space Center
Space Station Processing Facility	Kennedy Space Center
Vehicle Assembly Bld	Kennedy Space Center
Vertical Integration Facility	Atlas-V

## Confidence Ellipse Data

Number of strokes in which the center of the launch complex is inside the 99% confidence Ellipse: 3

Shuttle Complex 39A, 3 August 2009 Data from the 45th Weather Squadron Cloud-to-Ground Lightning Surveillance System II (CGLSS II)									
99% Confidence Ellipse Data									
Date	Time (UTC)	Magnitude (kA)	Azimuth	Range (NM)	Azimuth (to Ellipse*)	Range (to Ellipse*)	Magnitude (kAmps)	Target Inside Ellipse*?	Sensors in Solution
3-Aug-09	21:10:40.527	-39.8	288.4	0.46	26.3	0.11	-39.8	Yes	3
3-Aug-09	21:10:40.601	-32.2	296.4	0.42	53.3	0.42	-32.2	Yes	2
3-Aug-09	21:10:41.240	-49.1	292.9	0.61	101.9	0.09	-49.1	Yes	4

**Figure 6.** Example of the daily lightning report provided by 45 WS. For KSC, lightning strokes that are inside the operationally critical radius of 0.45 nmi are highlighted in green. Points of interest that lie inside the error ellipse are highlighted in magenta to aid interpretation of the range to ellipse.

### 2.3 On-demand 24/7 Lightning Reports

The use of error ellipses was a significant improvement over the previous method. However, due to computer security requirements, the initial process required a system administrator to copy the data from the 4DLSS workstation and hand-carry it to 45 WS. Due to the system administrator's work schedule, this meant lightning reports could not be generated nights, weekends, or holidays if a nearby lightning strike occurred during a major non-launch operation and sometimes early during a launch countdown. A workstation was installed in the 45 WS operations area with a communications link to the 4DLSS workstation on 17 Aug 09. This allowed on-demand lightning reports in near real-time without system administrator support. Within minutes, the data are now available to 45 WS for calculation of the error ellipses. Just 10 days after the

workstation was installed, the situation it was designed to mitigate occurred. During the nighttime countdown for the Space Shuttle STS-128 mission, lightning struck near the launch pad on 27 Aug 09. The on-demand lightning report showed inspection of the electronics was required. By providing the report immediately, rather than waiting for the next morning as done previously, only a 24-hour slip of the launch occurred, rather than a 48-hour slip, providing a cost avoidance of over \$1 million.

### 2.4 Fixed Truncation Error Of Peak Current

Another improvement to the 45 WS lightning reports was the discovery and correction of a truncation of the lightning stroke peak currents in the computer database used to generate the reports. The peak current was truncated, rather than rounded to the nearest integer kilo

Amp (kA). However, with an average peak current of 20 kA, this truncation was causing up to a 4% underestimate of the peak current of each stroke for average lightning.

### 2.5 KSC Automatic E-mail Alerts And Website

On their own initiative, KSC provided 24/7 automatic e-mail notification in near real-time to customers whenever a lightning stroke exceeded that customer's distance and/or intensity threshold. These e-mail use a 30 minute cycle time, so customers are notified of important lightning with an average lag time of 15 min. KSC also displays stroke locations and distance/intensity data in near real-time at a customer publically accessible website.

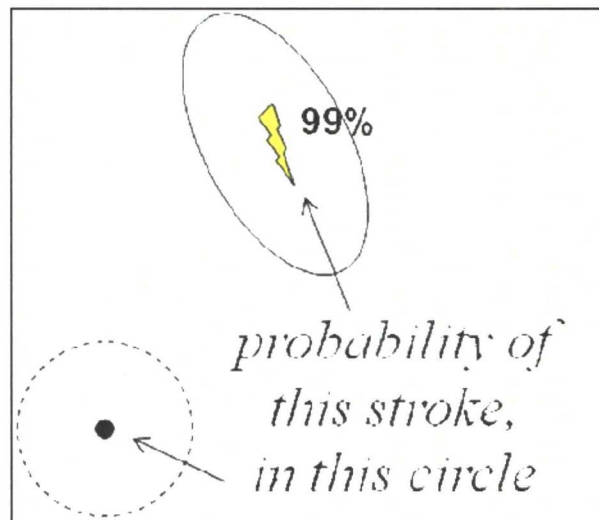
### 3. On-going Improvements to the 45 WS Lightning Reports

Further improvements to the 45 WS lightning reporting process are being pursued or considered as future projects.

#### 3.1 Probability That Any Nearby Lightning Stroke Is Within Any Radius Of Any Point Of Interest

A technique has been developed to calculate the probability that any nearby lightning stroke is within any radius of any point of interest (Figure-8). In practice, this provides the probability that a nearby lightning stroke was within a key distance of a facility, rather than the error ellipses centered on the stroke. This process takes the current bivariate Gaussian distribution of probability density provided by the current lightning location error ellipse for the most likely location of a lightning stroke and integrates it to get the probability that the stroke is inside any specified circle. This new facility-centric

technique will be much more useful to the space launch customers and may supersede the lightning error ellipse approach discussed above. The technical details of this new technique are available in Huddleston (2010) and will be presented to the 21st International Lightning Detection Conference, 21-22 Apr 10 (Huddleston et al., 2010). The KSC was considering adding error ellipses to their website displaying nearby lightning strokes in near real-time and to their automatic e-mail notifications. That effort may be superseded by this new technique.



**Figure 8.** Schematic of the new facility-centric process of calculating the probability of any stroke within any radius of any point.

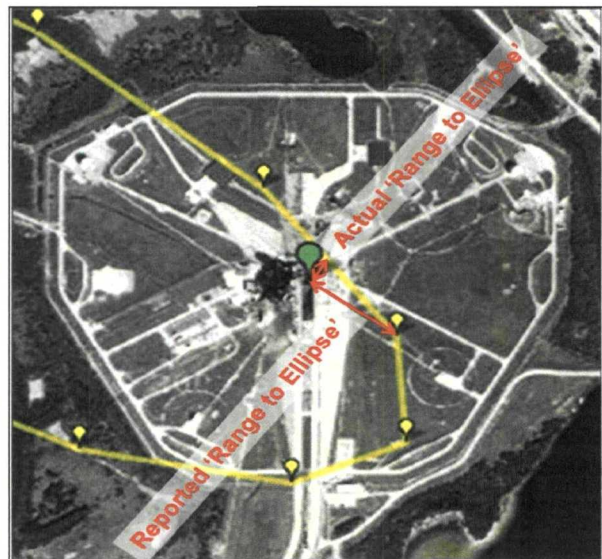
#### 3.2 Distance To The Closest Point Of Lightning Location Error Ellipse

The closest point on an ellipse to any arbitrary point cannot be found analytically. This complicates calculating the distance from a key facility to the closest point of lightning location error ellipse. This distance was initially approximated by the distance to the closest of 13 evenly spaced points on the

error ellipse. Only 13 points were used due to limitations of the Microsoft® EXCEL spreadsheet software. Unfortunately, this method can grossly overestimate the distance when the point of interest is near the ellipse and about equidistant between the 13 points (Figure-9). Under worst case conditions, the error can be up to 1.5 nmi, which is very significant when the radius for an area of interest may be only a few tenths of a nmi.

A visual basic program was developed that iterates to a much more accurate solution for the closest point on the error ellipse to the point of interest. A schematic of this iteration process is shown in Figure-10. The process begins by calculating the distance from the point of interest to eight points on the ellipse, spaced every  $\pi/4$  radians ( $45^\circ$ ) around the center of the error ellipse starting due west of the center of the ellipse. The closest of these eight points is chosen as the starting point. On the first iteration, three subsequent candidate closest points are selected on the error ellipse, the current chosen point and points spaced  $\pi/8$  radians ( $22.5^\circ$ ) (half the previous angle) to either side of that point relative to the center of the ellipse. The closest of these three points is chosen. On the next iteration three subsequent candidate closest points are selected on the error ellipse, the point chosen in the previous iteration and points spaced half the angle in the previous iteration angle to either side. The iteration is continued until the iteration angle is  $\pi/2^{16}$  radians ( $0.002727^\circ$ ). The closest of the three candidate points in that last iteration is selected as the final closest point and the iteration is ended. This is equivalent to

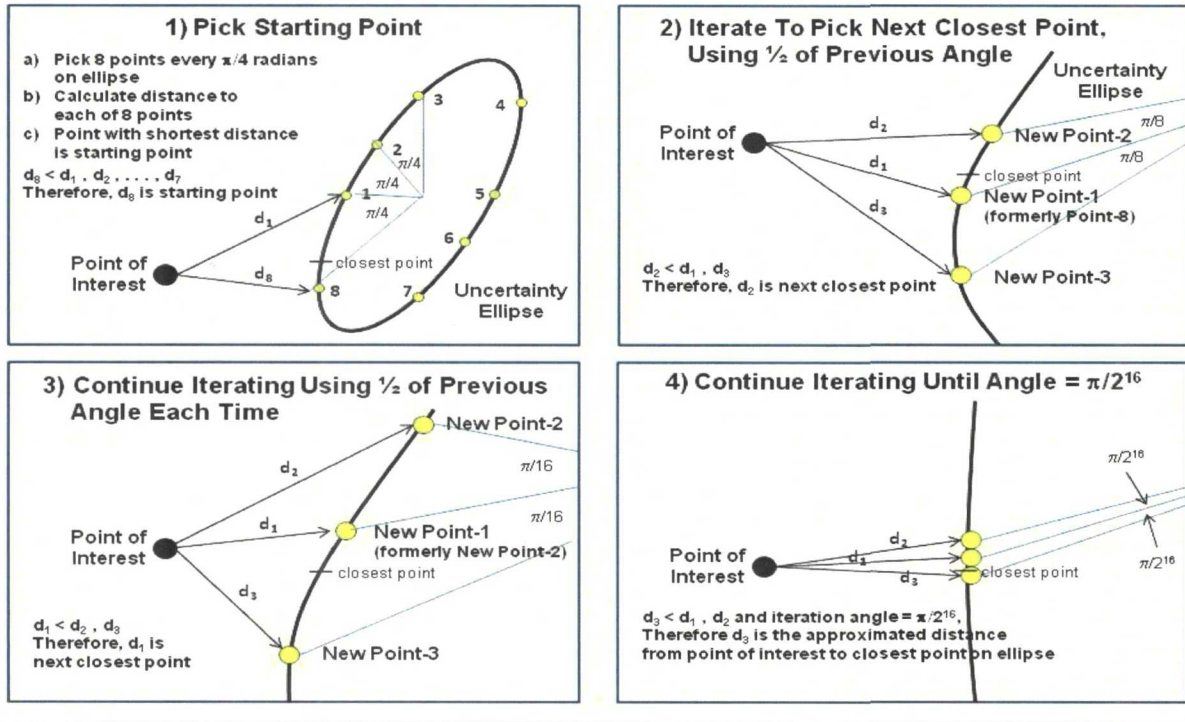
approximating the error ellipse with 65,000 points and choosing the closest of the points in just 50 iterations, which was a vast improvement over the previous method of choosing the closest of 13 evenly spaced points approximating the error ellipse. Even in a very unfavorable scenario, this method provides a location error no larger than 2.5 m, two orders of magnitude less than the best location error possible from the 4DLSS.



**Figure 9.** The previous method of estimating the distance from the facility to the closest point on the error ellipse was done using the distance to the closest of the 13 evenly spaced points used to approximate the ellipse. This method would grossly over-estimate the distance when the facility was close to the ellipse and about equidistant from the two closest 13 points. This method was replaced by a far superior method as discussed in the text and shown in Figure-10.



## Distance From Point Of Interest To Closest Point On Uncertainty Ellipse



**Figure 10.** The new method estimates the distance from a facility to the closest point of the error ellipse. The new method is far superior to the previous method since it overcomes the problem of grossly overestimating the distance under some scenarios as discussed in the text and shown in Figure-8.

### 3.3 Strong Local Lightning Strokes Sometimes Not Detected

Recent research has shown that 4DLSS can be saturated by strong local strokes and fail to detect them, especially those with peak currents of 50 KA or greater (Ward et al., 2008). However, 4DLSS excels at detecting weak local strokes. On the other hand, the wider spacing of the NLDN sensors excels at detecting those strong strokes, but loses detection efficiency for weaker strokes near CCAFS/KSC, especially those with peak currents of 7 KA or less. This suggests that combining the sensor data from both systems in real-time could lead to improved performance. The 45 WS is pursuing integrating data from nine NLDN

sensors into 4DLSS in real-time to improve the detection of strong local strokes. The nine NLDN sensors being considered are based on those closest to CCAFS/KSC and those with the best complementary geometry relative to CCAFS/KSC. The nine NLDN sensors being considered for incorporation into 4DLSS are all seven of the sensors in FL, one just across the state line in GA, and one in the Bahamas Islands. Incorporation of the sensor data from those NLDN sensors into 4DLSS in real-time will also improve the location accuracy, detection efficiency, and provide smaller and less eccentric error ellipses when only a few of the 4DLSS sensors are used in the solution. The performance of 4DLSS will not be

compromised when most of the 4DLSS sensors are used in the lightning solution.

As an interim measure, KSC is purchasing StrikeNet reports from Vaisala, Inc. when lightning strokes are detected or suspected near KSC points of interest. The StrikeNet reports include all the strokes detected by NLDN, as opposed to the more routinely available flash-only data, and so should include the strong local strokes missed by 4DLSS. The StrikeNet reports also allow cross-comparison with the 4DLSS lightning reports to identify strokes 4DLSS may have missed and to check for consistency in lightning locations and peak current. A sample StrikeNet report is in Figure-11. The StrikeNet solution is not as good as integrating the nearby NLDN sensors into 4DLSS since the stroke location, error ellipses, and peak current solutions are not optimized with all the sensor data from both systems. In addition, inconsistencies between the two reports may occur, requiring manual analysis to reconcile. However, the StrikeNet reports are available now, while the integration of the NLDN sensors into 4DLSS is still being developed. The 45 WS may acquire StrikeNet reports to support their DoD, NASA unmanned, and commercial launch customers.

### *3.4 Fault Analysis Lightning Location System*

The 45 WS considered acquiring the Fault Analysis Lightning Location System (FALLS) (Vaisala, 2009). The FALLS would have provided advanced analysis and display capabilities of error ellipses. However, given the in-house lightning reporting improvements discussed above, the 45 WS decided FALLS was not cost-effective for their mission.

### *3.5 KSC Automatic E-mail And Website*

KSC is considering adding the location error ellipses to their automatic 24/7 e-mail alerts and display error ellipses at their website so the customers can see this important data in near real time. This effort may be superseded by the new probability of any lightning stroke being inside any radius of any location, as discussed in section-3.1.

## **4. Possible Future Improvements to the 45 WS Lightning Reports**

There are two main avenues to improving the 45 WS lightning reports even further in the future: 1) improved peak current estimates and improved error estimates of the peak current accuracy, and 2) 4DLSS upgrades.

### *4.1 Improved Peak Current Estimates And Peak Current Errors*

There are five main factors in assessing the induced current hazard presented by nearby lightning: 1) the detection rate of the lightning detection system being used, 2) the distance to the stroke, 3) the error in the location, 4) the peak current of the stroke, and 5) the error in the peak current. Considerable work has been done over the years in improving and understanding the detection rate and location accuracy of lightning detection systems, including 4DLSS. However, more work is needed to improve the estimate of peak current as well as the error in the estimate of the peak current.

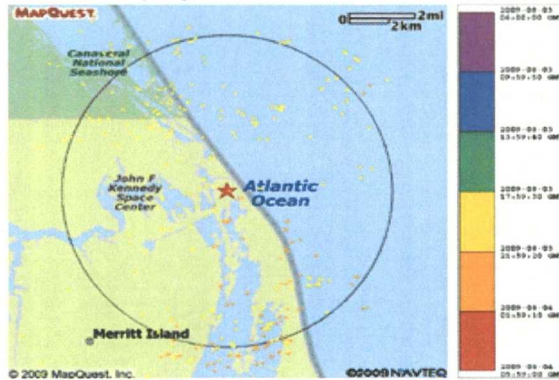
Anyone interested in helping conduct these peak current studies is encouraged to contact the corresponding author.

# STRIKEnet

## STRIKEnet Report 238904

Report Title: STRIKEnet LC39A 8-3-09  
 Total Lightning Strokes Detected: 438  
 Lightning Strokes Detected within 5 mi/8 km radius: 274  
 Lightning Strokes Detected beyond 5 mi/8 km whose confidence ellipse overlaps the radius: 164  
 Search Radius: 5 mi/8 km  
 Time Span: Aug 3, 2009 06:00:00 GMT to Aug 4, 2009 05:59:00 GMT

### Location Points For Lightning Strokes



Lightning data provided by Vaisala's NLDN and/or Environment Canada's CLDN.

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 Tucson Operations  
 2705 E. Medina Road  
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 Tel: +1 520 806 7300  
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Aug 4, 2009 06:50:43

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### Lightning Stroke Table (Note: Earliest 50 events shown. Events ordered by time.)

Date	Time	Peak Current (kA)	Distance From Center (mi/km)	Latitude	Longitude
Aug 3, 2009	19:47:58	-13.8	4.216.8	28.8419	-80.8928
Aug 3, 2009	19:48:46	-13.1	2.110.4	28.8306	-80.8202
Aug 3, 2009	19:50:04	-17.7	1.712.8	28.8224	-80.8280
Aug 3, 2009	19:52:53	-10.1	3.044.8	28.8388	-80.8411
Aug 3, 2009	19:52:53	-14.2	3.785.0	28.8491	-80.8482
Aug 3, 2009	19:55:54	-12.2	3.855.8	28.8299	-80.8583
Aug 3, 2009	19:57:40	-16.5	3.355.4	28.8480	-80.8390
Aug 3, 2009	19:58:15	-20.9	3.855.9	28.8482	-80.8435
Aug 3, 2009	19:58:29	-36.1	4.717.6	28.8315	-80.8770
Aug 3, 2009	19:58:29	-17.3	4.717.6	28.8423	-80.8723
Aug 3, 2009	19:58:29	-10.8	4.671.4	28.8409	-80.8708
Aug 3, 2009	19:58:29	-10.7	5.216.3	28.8319	-80.8850
Aug 3, 2009	19:58:29	-15.8	4.507.2	28.8419	-80.8874
Aug 3, 2009	19:58:29	-16.8	4.971.9	28.8438	-80.8740
Aug 3, 2009	19:58:29	-10.4	5.716.2	28.8291	-80.8857
Aug 3, 2009	19:58:52	-18.6	3.655.4	28.8452	-80.8403
Aug 3, 2009	19:58:52	-11.7	3.216.2	28.8423	-80.8406
Aug 3, 2009	19:58:52	-12.5	3.216.2	28.8440	-80.8383
Aug 3, 2009	19:58:52	-9.4	3.455.5	28.8352	-80.8517
Aug 3, 2009	19:59:12	-17.8	1.973.0	28.8335	-80.8180
Aug 3, 2009	19:59:32	-26.5	3.355.4	28.8521	-80.8271
Aug 3, 2009	20:00:15	-16.8	2.944.6	28.8458	-80.8245
Aug 3, 2009	20:00:35	-31.2	3.455.5	28.8462	-80.8304
Aug 3, 2009	20:00:35	-10.1	3.355.2	28.8443	-80.8376
Aug 3, 2009	20:00:35	-12.5	3.355.3	28.8468	-80.8312
Aug 3, 2009	20:00:35	-16.5	3.355.4	28.8566	-80.8056
Aug 3, 2009	20:00:35	-12.2	3.455.5	28.8506	-80.8326
Aug 3, 2009	20:02:14	-22.0	4.216.7	28.8554	-80.8475
Aug 3, 2009	20:02:14	-23.7	2.844.6	28.8478	-80.8160
Aug 3, 2009	20:02:14	-12.9	4.971.9	28.8887	-80.8454
Aug 3, 2009	20:02:14	-18.4	5.716.1	28.8735	-80.8806
Aug 3, 2009	20:03:15	-26.7	3.595.7	28.8535	-80.8313
Aug 3, 2009	20:03:15	-9.0	3.455.5	28.8434	-80.8440
Aug 3, 2009	20:04:34	-29.8	3.855.2	28.8563	-80.8373
Aug 3, 2009	20:04:34	-31.3	3.116.1	28.8494	-80.8324
Aug 3, 2009	20:04:35	-19.8	4.717.6	28.8728	-80.8288
Aug 3, 2009	20:04:35	-13.8	4.671.4	28.8712	-80.8275

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Figure 11. Sample output from a StrikeNet report, which provides stroke data from NLDN.

#### 4.1.1 Improved Peak Current Estimates

The 45 WS is interested in improving the estimates of the peak currents from 4DLSS. At present, the peak current estimate is calculated from the peak magnetic field at each sensor. The peak magnetic field is normalized to a range of 100 km and corrected for attenuation from ground propagation effects. The mean of the attenuation-corrected range-normalized peak magnetic fields is converted to peak current via a regression equation (Cummins et al., 1998). That regression equation was based primarily on data from rocket-triggered lightning. As a result, it is less representative for first strokes from natural lightning. This is important to operations since the first stroke in a flash tends to have the highest peak current. Thus, the first stroke can generally cause more induced current damage at the same distance or the same induced current damage at farther distances than subsequent return strokes.

Perhaps the best way to improve peak current estimates is to create a new regression equation based on observations of natural lightning. Unfortunately, there have been few direct peak current measurements of natural lightning. An appropriately instrumented tall tower in a wide open flat area with frequent lightning and subsequent analysis of that data should allow significantly improved peak current estimates, especially for the operationally more important first strokes. The CCAFS/KSC has a network of weather towers that would be a natural candidate for such an instrumented tower given the lightning frequency and terrain in that area. An analysis of tower height versus climatological flash density, along with surrounding terrain and logistical accessibility, should be conducted to identify the best tower to be instrumented.

For example, Tower-313 is the tallest tower in the network (500 ft) but is located near the coast. Shorter towers farther inland might be more likely to be struck by lightning since the climatological lightning flash density increases in-land. Funding for this project was not available at the time this paper was written (Jan 2010).

There may be ways to improve the range-normalized attenuation-corrected regression equation approach used at present. For example, using an average peak magnetic field weighted by distance to the stroke for each sensor, rather than a simple mean, may yield some performance improvement. Sensors farther from the stroke would receive less weight in the distance weighted average.

Another possible improvement could be separate regression equations based on stroke polarity. Likewise, different regression equations for varying peak current should also be considered, e.g. perhaps an iterative process where the regression coefficients are modified based on the peak current from the previous iteration, or a simpler approach of stratified regression equations for weak, moderate, and strong peak current.

Finally, entirely new approaches should be explored to avoid the additional uncertainties introduced by the range-normalization and the regression equation.

#### 4.1.2 Improved Peak Current Accuracy

The estimated error associated with the peak current estimates for cloud to ground lightning strokes from 4DLSS has not been as well studied as location accuracy and detection rate, especially for various combinations of sensors used in the solution for each stroke. At present, a single error estimate of  $\pm 20\%$  is used for all strokes, regardless of number of sensors used in the solution and distance of those sensors to the lightning stroke.

This is the vendor's recommendation and is based on the performance of the NLDN, which itself appears to be based on some old studies of relatively small sample size. It appears that most customers are more interested in detection rate and location accuracy than in peak current accuracy. As a result, more effort has been invested to quantify and improve the performance of the former, rather than the latter. Some lightning detection experts have suggested that the actual errors in peak current are larger than  $\pm 20\%$  (Mata, 2009).

The 45 WS is interested in improved error estimates for peak current provided by 4DLSS. One possible approach might be using the variability of the peak current estimated from each sensor for a better measure of the peak current error. This could also allow a statistical estimate of the confidence intervals and/or a high percentile, e.g. inter-quartile range, 95th or 99th percentile. A best-fit Gaussian distribution might also be applicable. The standard deviation of that best-fit Gaussian distribution could be used to generate probabilistic confidence intervals. The space launch customers could then factor the uncertainty of peak current more effectively into their decision models for inspecting mission essential electronics, just as they do now with location accuracy, i.e. determine the probability of exceeding their combined threshold of distance from their facility and peak current.

#### *4.2 4DLSS Upgrades*

The 45 WS is interested in upgrading 4DLSS since improved lightning detection will provide improved lightning reports. Four main possible approaches to upgrade CGLSS are available. First, conduct a new Network Performance Evaluation Program (NPEP) and schedule

them periodically. Second, replace the 4DLSS sensors with the new model for long-term maintenance sustainability. Third, integrate any new nearby NLDN sensors into 4DLSS. Fourth, add a new seventh sensor to 4DLSS. Unfortunately, none of these activities is currently funded.

##### *4.2.1 New And Periodic Network Performance Evaluation Program*

A Network Performance Evaluation Program (NPEP) was last accomplished for 4DLSS in summer of 2008, shortly after the system was installed. No major problems were found, but a minor radio noise problem was detected at one of the sites. A new NPEP should be conducted, since one is recommended every 1.5 years. If the previous minor radio noise problem still exists, a remediation may be worthwhile. Also the NPEP would check for any new problems. The NPEP should be repeated every 1.5 years for stable lightning detection systems that are performing well, as recommended by the vendor (Vaisala, 2008).

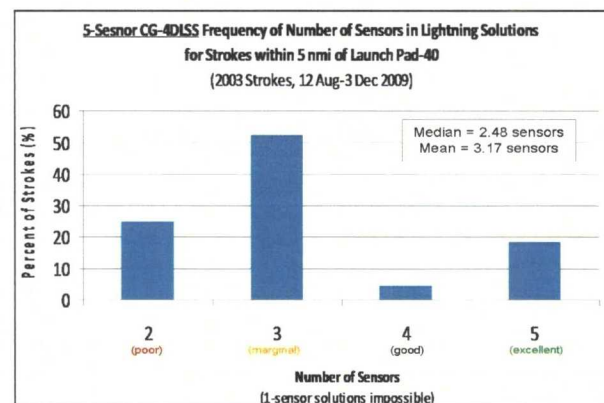
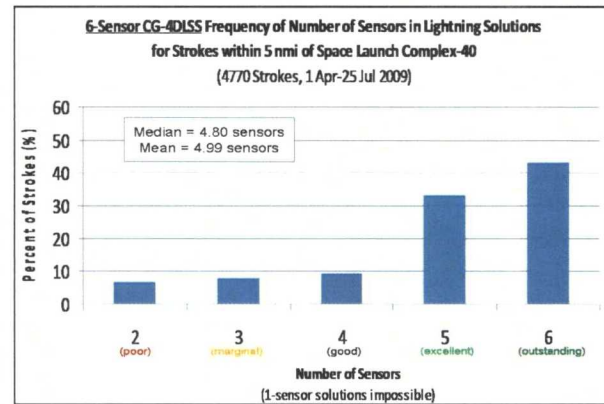
##### *4.2.2 Replace 4DLSS Sensors With New Model*

The current CG-lightning IMPACT Model 141-T sensors are no longer supported by Vaisala, Inc. This is already causing maintenance problems. For example, the Melbourne sensor was damaged by a lightning strike on 26 Jul 2009 and a replacement sensor was not available, so 4DLSS is in a temporary 5-sensor configuration at the time this paper is being written (Dec 09), rather than the nominal 6-sensor configuration. The Tosohatchee sensor was moved to the Melbourne location to replace the sole line of sight to CCAFS/KSC from the south (see Figure-2 for sensor locations). The line of sight from the west provided by Tosohatchee is duplicated in part by the

Seminole sensor. Fortunately, Vaisala is currently manufacturing the LS7001 sensor, which they plan to support for many years. This new sensor should be a simple plug-in replacement of the current sensors with no loss of performance and requiring no modification to the rest of 4DLSS. While a test of the new sensor model in 4DLSS is funded and being scheduled, the follow-on replacement of all the current sensors is not yet funded, pending results of that test. However, replacing the sensors is mission-essential to ensure sustainability of 4DLSS.

The testing of the new LS7001 sensor, and subsequent replacement of the current 4DLSS sensors, may be taking on heightened urgency. Preliminary analysis indicates that the performance loss to cloud-to-ground lightning detection was larger than expected after the loss of the Melbourne sensor on 26 Jul 09 and relocation of the Tosohatchee sensor to the Melbourne site (see Figure-2 for site locations). Before the reconfiguration, the median number of sensors per lightning solution under the nominal 6-sensor configuration was 4.80 sensors for lightning near the launch pads, close to an overall excellent performance for space launch applications. Only 14.1% of lightning solutions used only 3 or 2 sensors, corresponding to marginal or poor performance, respectively. However, under the current temporary 5-sensor configuration, the median number of sensors per solution for the same area is 2.58 sensors, for an overall performance just below marginal, although the mean is 3.29 sensors. A large 69.9% of lightning solutions used only 3 or 2 sensors for marginal to poor performance, respectively. The distribution of number of sensors per lightning solution is shown in Figure-12. The cause of this unexpectedly large drop

in performance of the temporary 5-sensor configuration of the cloud-to-ground 4DLSS is being investigated. Once diagnosed, a corrective fix will be implemented.



**Figure 12.** Frequency of number of sensors per lightning solution for strokes near the CCAFS/KSC launch pads under the nominal 6-sensor configuration (*upper figure*), and the current temporary 5-sensor configuration (*lower figure*). The Melbourne sensor was damaged on 26 Jul 09 and the Tosohatchee sensor was moved to the Melbourne site and activated on 11 Aug 09.

#### 4.2.3 Integrate Any New Nearby NLDN Sensors

In section-3, the on-going effort to inject data from nine surrounding NLDN sensor data to 4DLSS was discussed. When that effort began in early 2009,

Vaisala, Inc. was considering adding another NLDN sensor in central Florida, perhaps near Daytona Beach. If that sensor is added to NLDN, then it should also be incorporated into 4DLSS. Likewise, any other new NLDN sensors added in Florida, southern Georgia, or the Bahamas Islands should be considered for integration into 4DLSS.

If the new NLDN sensor is not added, the 45 WS may consider adding a new eighth 4DLSS sensor to 4DLSS at a distance of about 60 nmi from KSC/CCAFS. This new eighth sensor would be in addition to the new seventh sensor discussed in section 4.2.4. Or it may be more cost-effective to fund Vaisala to install and maintain such a sensor for 45 WS to ingest its data into 4DLSS. Either approach should help reduce the problem of strong local strokes sometimes not being detected by 4DLSS.

#### *4.2.4 Add A New Seventh Sensor To 4DLSS*

The performance of 4DLSS could be made more robust if a new seventh sensor was added. If this new seventh sensor is sited at a near center location, it should reduce the sensitivity to performance if the Cape sensor is not used in the solution (Table-1). In addition, the preliminary analysis of performance loss under the current temporary 5-sensor configuration suggests the gain in robustness with a new seventh sensor may be worthwhile. If this new seventh sensor is added, a location at the southwest edge of KSC should provide increased performance for lightning near the launch pads if the Cape sensor is used in the solution. If this new seventh sensor is added, moving the Seminole sensor a few miles to the northeast would optimize the performance of 4DLSS slightly, but this change may not be cost-effective. The addition of a new seventh

sensor has not yet been formally recommended by 45 WS yet so funding has not been considered.

## **5. Summary**

The 45 WS provides daily lightning reports to space launch customers at CCAFS/KSC. These reports are provided to assess the need to inspect the electronics of satellite payloads, space launch vehicles, and ground support equipment for induced current damage from nearby lightning strokes.

The 45 WS has made several improvements to the lightning reports during 2008-2009. The 4DLSS, implemented in April 2008, provides all lightning strokes as opposed to just one stroke per flash as done by the previous system.

The 45 WS discovered that the peak current was being truncated to the nearest kilo amp in the database used to generate the daily lightning reports, which led to an up to 4% underestimate in the peak current for average lightning. This error was corrected and led to elimination of this underestimate.

The 45 WS and their mission partners developed lightning location error ellipses for 99% and 95% location accuracies tailored to each individual stroke and began providing them in the spring of 2009. The new procedure provides the distance from the point of interest to the best location of the stroke (the center of the error ellipse) and the distance to the closest edge of the ellipse. This information is now included in the lightning reports, along with the peak current of the stroke. The initial method of calculating the error ellipses could only be used during normal duty hours, i.e. not during nights, weekends, or holidays. This method was improved later to provide lightning reports in near real-time,

24/7. The calculation of the distance to the closest point on the ellipse was also significantly improved later. Other improvements were also implemented.

A new method to calculate the probability of any nearby lightning stroke being within any radius of any point of interest was developed and is being implemented. This may supersede the use of location error ellipses.

The 45 WS is pursuing adding data from nine NLDN sensors into 4DLSS in real-time. This will overcome the problem of 4DLSS missing some of the strong local strokes. This will also improve the location accuracy, reduce the size and eccentricity of the location error ellipses, and reduce the probability of nearby strokes being inside the areas of interest when few of the 4DLSS sensors are used in the stroke solution. This will not reduce 4DLSS performance when most of the 4DLSS sensors are used in the stroke solution.

Finally, several possible future improvements were discussed, especially for improving the peak current estimate and the error estimate for peak current, and upgrading the 4DLSS. Some possible approaches for both of these goals were discussed.

## 6. Acknowledgements

The work by Dr. Huddleston of the KSC KSC Orbiter Mechanical Systems office was done under the KSC Employee Development Program. This included developing the program that calculates the probability of any nearby lightning stroke being within a radius of any point of interest and improving the calculation of the distance to the closest point of the error ellipse.

Mr. Jeremy Hinkley and Mr. Pete Hopman of United Space Alliance, the main contractor for Space Shuttle

operations, developed the software to calculate the distance from the point of interest to the closest point on the error ellipse. They also developed the software that accelerated the search routine to filter out lightning strokes too far to be an induced current threat, which saved time processing the remaining strokes for threat assessment.

A previous version of this paper was reviewed by Mr. John Madura, Chief of the KSC Weather Office.

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