

2010 ESMD Faculty Fellowship Project

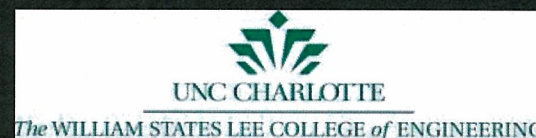
Christina L. Carmen



Tommy Morris



Peter Schmidt



Paul van Susante



Janusz Zalewski



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Purpose of the NASA ESMD Faculty Fellowship

- Prepares 5 selected university faculty to enable senior design students to complete projects during the 2010-2011 academic year with potential contribution to NASA ESMD objectives.
- The faculty gain extensive knowledge on the ESMD project and develop materials for use by their senior design students using a systems engineering approach.



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Project Goal

2010 Faculty Fellowship Solicitation

- 8 weeks on a selected ESMD project
- at Kennedy Space Center (KSC) for one week
- Incorporate project into an existing senior design course or capstone course in the 2010/2011 academic year.
- work side-by-side with a NASA technical expert.
- Gain extensive knowledge on the ESMD project and associated requirements, interfaces and issues affecting the design and potential solution(s).
- develop materials for use during the 2010/2011 academic year
- Use a systems engineering approach



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NASA ESMD

2010 Faculty Fellowship Schedule

Date	Task
June 2- July 23, 2010	Report to NASA facility for 8 weeks to work on ESMD project
July 26-30, 2010	ESMD Faculty Fellows convene at KSC
Sept. 17-18, 2010	Present at regional Space Grant Conference
Fall 2010-Spring 2011	Implement Senior Design Project



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Overview of ESMD projects

Spacecraft

Guidance, navigation, and control;
Thermal; Electrical; Avionics; Power systems; High-speed reentry;
Interoperability/Commonality; Advanced spacecraft materials; Crew/Vehicle health monitoring; Life-support systems;
Command/Communication software;
Modeling and simulation

Ground Operations

Pre-launch; Launch; Mission operations; Command, control, and communications; Landing and recovery operations

Propulsion

Methods that utilize materials found on the Moon and Mars; On-orbit propellant storage; Methods for soft-landing

Lunar & Planetary Surface Systems

Precision landing software; In-situ resource utilization; Navigation systems; Extended surface operations; Robotics; Environmental sensors and analysis; Radiation protection; Life-support systems; Electrical power and efficient power management systems



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Significance of ESMD Projects to NASA's Mission and ESMD Objectives

- Education and outreach of ESMD
- Gathering ideas while creating experience
- Create long lasting experience that translates to students for many years
- Create translation to lower level students for further development of workforce
- 600 students exposed this year alone



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Conclusions

- Bridges the gap between academia and the NASA vision and mission. Students connect to real world space-related work.
- Exposes students to new and novel approaches to space exploration that better prepare them for future space-related careers.
- Creates greater awareness of current NASA research to new faculty who have never been previously associated with or exposed to the NASA vision and mission.
- Motivates incorporation of Systems Engineering curriculum to enrich the experience and increase the knowledge base of participants.



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Individual Plans for Incorporation

Overview of faculty plans to incorporate their selected ESMD project and developed materials into a specific existing senior design or capstone course at their respective university



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ESMD-Faculty Fellowship Project

Dr. Christina L. Carmen, Ph.D.
Midwest Regional Space Grant
Meeting, Minneapolis, MN



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The University of Alabama in Huntsville

Overview

1. X-TOOLSS Project
2. X-TOOLSS Optimization Using Nastran
3. Lunar Wormbot Design Project
4. Systems Engineering Design
5. Summary



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NASA ESMD X-TOOLSS Project

- Marshall Space Flight Center (MSFC)
- X-TOOLSS (eXploration Toolset for Optimization Of Launch and Space Systems)
- Software package developed at North Carolina A & T (NCAT) via a grant from NASA
- Developed for scientists and engineers to solve optimization problems



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NASA ESMD X-TOOLSS Project

- X-TOOLSS project history began with NEVOT (Nuclear Exploration Vehicle Optimization Team)
- Today, the development and use of X-TOOLSS continues with the following:
 - North Carolina A&T State University (Computer Science dept.)
 - Marshall Space Flight Center
 - Oak Ridge National Laboratory
 - Arnold Engineering Development Center
 - And now...The University of Alabama in Huntsville (UAH)
 - First use of X-TOOLSS in a senior capstone design class



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NASA ESMD X-TOOLSS Project

- X-TOOLSS requires a code file (java script or an executable application file)
- X-TOOLSS can be used with MATLAB, COMSOL, Nastran, etc.
- The use of X-TOOLSS at UAH will focus upon the optimization of the design via FEA using Nastran
- All MAE students at UAH learn MATLAB and all mechanical engineering students learn Patran/Nastran



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X-TOOLSS Optimization Using Nastran

Example Application

- Typical application of X-TOOLSS within the UAH Mechanical and Aerospace Engineering senior capstone design class.
- CO₂ Launching Mechanism, Team 10, Spring 2010.



Figure 1: HotShot Raceway™ CO2
Dragster Launcher

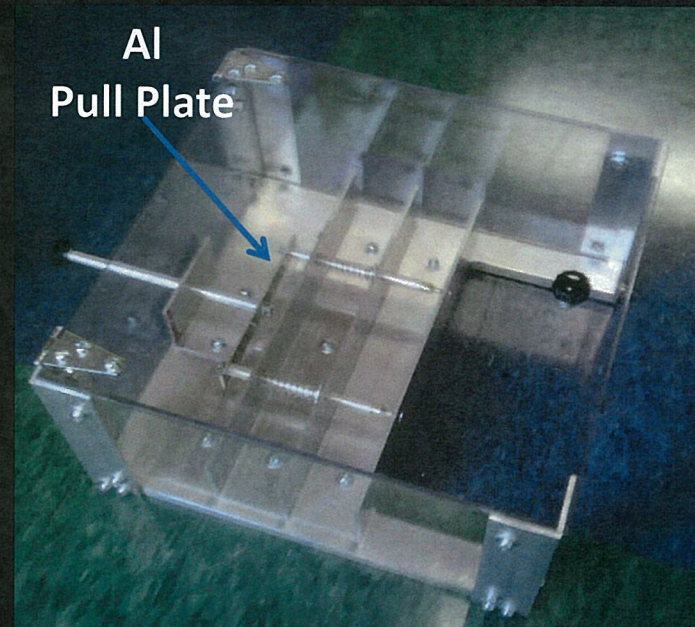


Figure 2: MAE Team 10 Final Product



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X-TOOLSS Optimization Using Nastran

Example Application

- Visualization of the Finite Element Analysis (FEA) results via computer graphics and animation provides a critical understanding of a model's behavior, how the model/part will move and how the design can be improved.

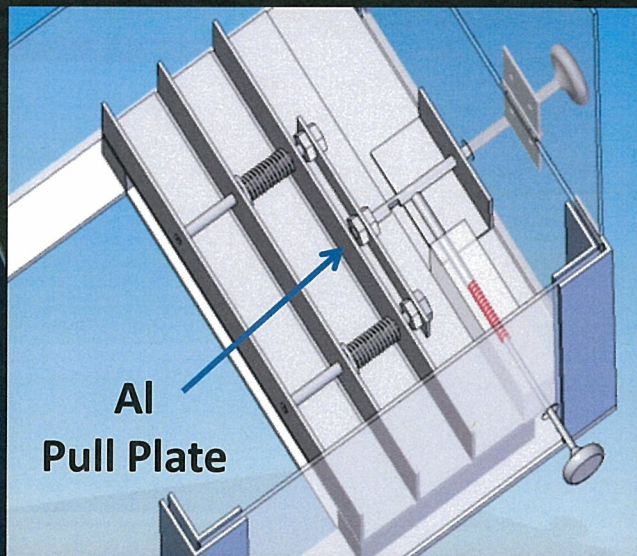


Figure 3: MAE Team 10 CAD Model



Figure 4: MAE Team 10 FEA



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X-TOOLSS Optimization Using Nastran

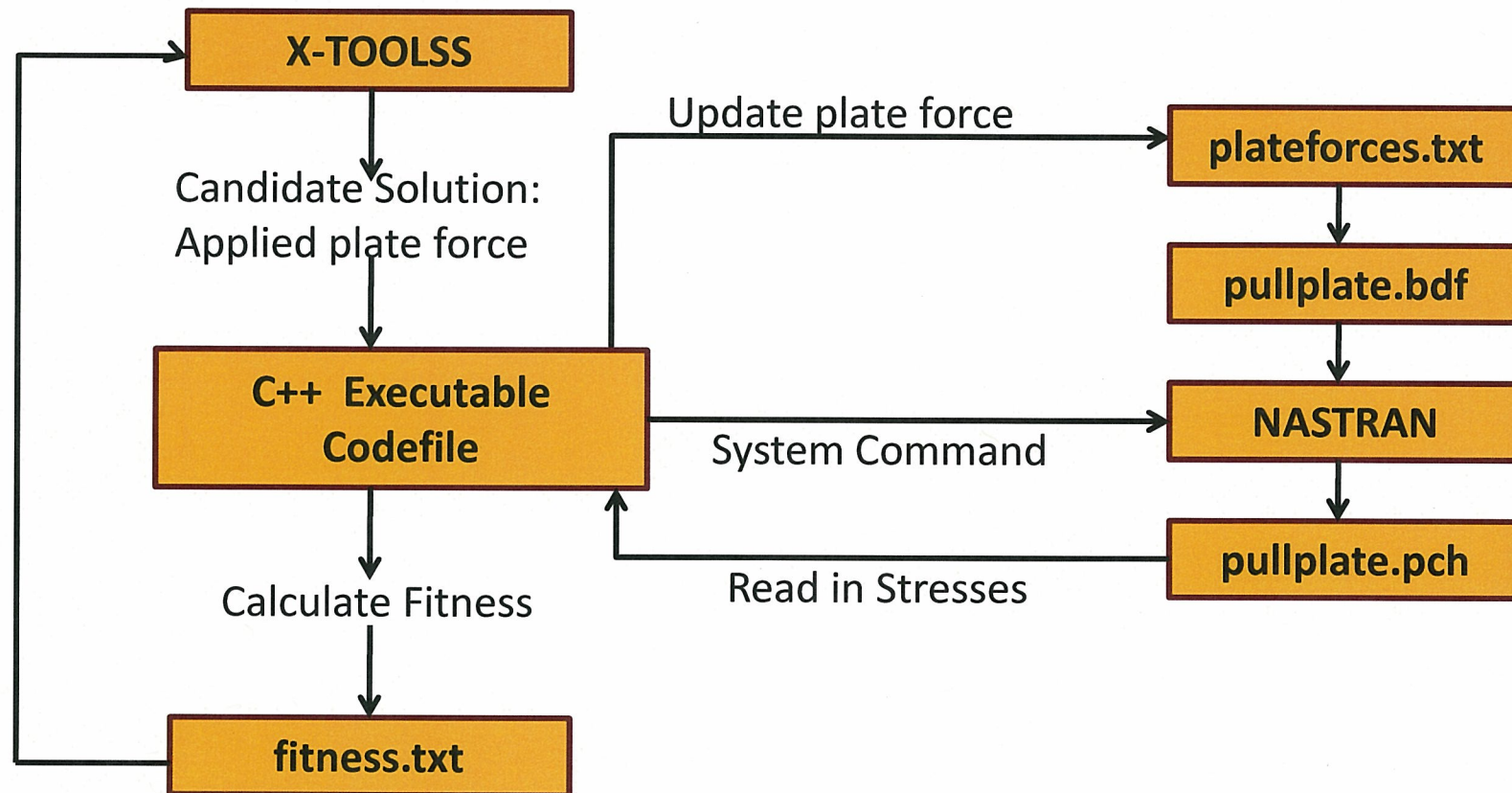


Figure 5: The X-TOOLSS/Nastran Optimization Loop

Lunar Wormbot Design Project

- Engineers at the National Space Science and Technology Center (NSSTC) in Huntsville, AL have developed conceptual designs of a “Lunar Wormbot” – a device to burrow into lunar regolith.
- UAH MAE design teams will refine the design and fabricate the hardware.
- X-TOOLSS will be utilized during the conceptual design phase.



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Lunar Wormbot Design Project

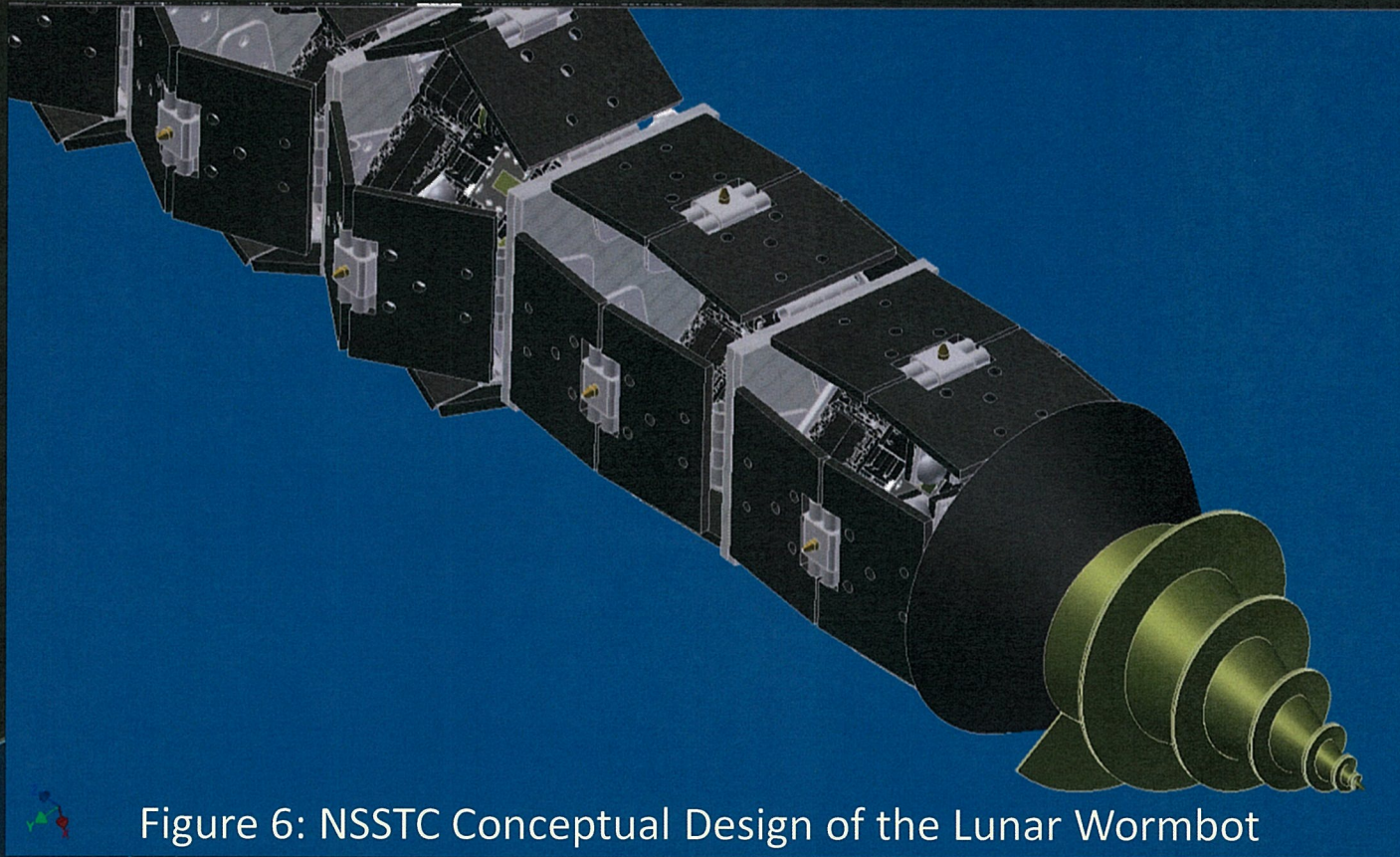


Figure 6: NSSTC Conceptual Design of the Lunar Wormbot



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Systems Engineering Design

- NASA ESMD website:
<http://education.ksc.nasa.gov/esmdspacegrant/>
- Apply SE design process to senior design projects at UAH
- Integrate lectures available at the ESMD Space Grant website in the senior Mechanical and Aerospace Engineering product realization design class at UAH.



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Tommy Morris, Ph.D.

Northeast Regional Space Grant
Meeting, New Port, RI



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Overview of Project

JSC4-36-SD Implement CODECs on FPGAs

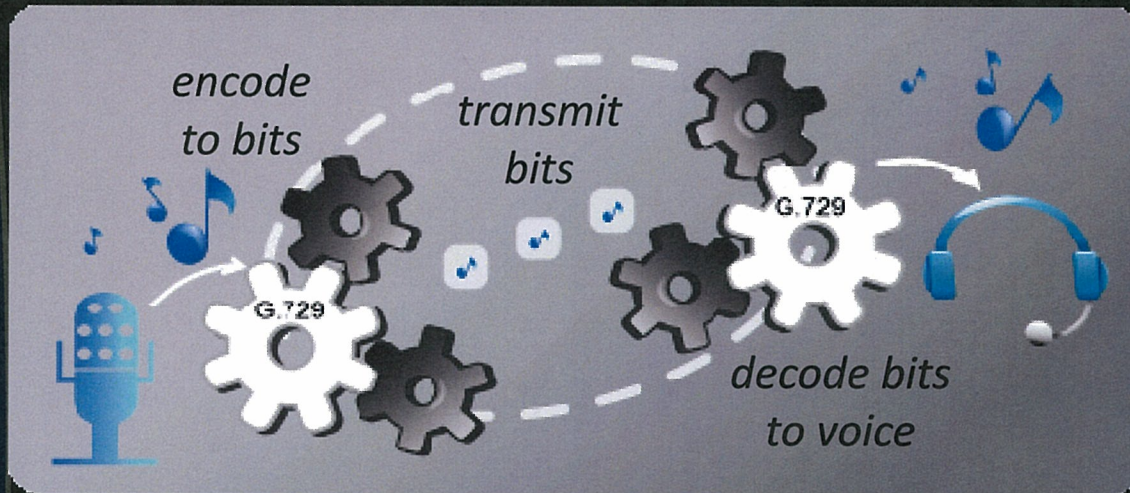
- NASA desires HDL realization of ITU G.729 CODEC with for implementation on FPGA
- No VHDL or Verilog HDL implementations found.
- Resulting Project
 - Incorporate aspects on implementing ITU G.729 CODEC in HDL into Digital Systems Design class.
 - Implement ITU G.729 encoder prototype as 2 semester senior design project during Fall 2010-Spring 2011.



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Background

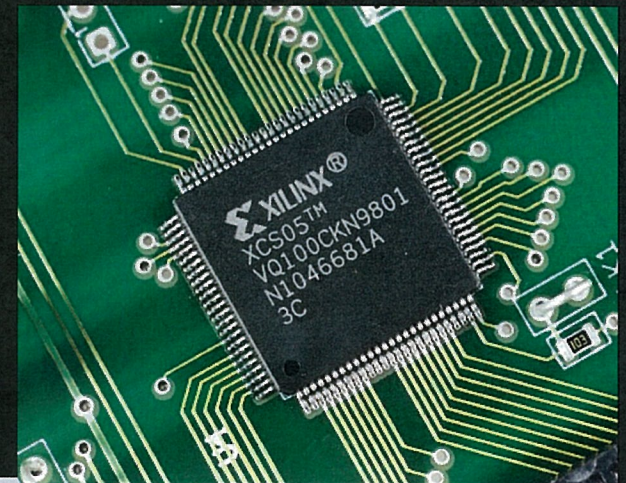


ITU G.729 is a voice CODEC (aka VOCODER).

Field Programmable Gate Array (FPGA) = Programmable microchip.

Hardware Description Language (HDL) = language used to describe digital circuits

- Concurrency
- Support for bits, bytes, etc.
- Event triggered processes



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Significance to NASA's Mission

JSC4-36-SD Implement CODECs on FPGAs

- Orion Crew Exploration Vehicle (CEV)
- HDL implementation of ITU G.729 CODEC
 - Lower power than software version.
 - Power is at a premium on space vehicles and extra planetary rovers.
 - Faster computation than software version.
 - Reduces communication latency between astronauts and ground.
 - Supports use with reconfigurable computing algorithms.
 - Potential to reduce space craft weight by reducing number of separate electronic devices in vehicle.



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Circuit Power

$$P \propto \frac{1}{2} CV^2 f$$

P = Power.

c = Capacitance.

v = Voltage.

f = Frequency.

The Hardware implementation of the CODEC will meet NASA and ITU G.729 function requirements at much lower frequency (f) than software version, leading to significantly lower power.



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Significance to NASA's Mission

JSC4-36-SD Implement CODECs on FPGAs

- Digital Signal Processing
 - Common in many areas important to NASA mission
 - communications, robotics, image processing, speech recognition, weather forecasting, RADAR, biomedicine, etc.
- HDL Design
 - NASA Avionics System Division Electronic Design Branch (EV2) current HDL projects include
 - Camera interface, voice processing, networking, space station telephony, robotics.
 - NASA contractors have many more active HDL based projects.



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Knowledge Gained

JSC4-36-SD Implement CODECs on FPGAs

- Worked with NASA engineers to understand project requirements.
 - Honeywell contracted to implement software version on embedded Xilinx MicroBlaze microcontroller.
 - Software version latency target 15 mS algorithmic delay + 6-10mS computational delay.
 - HDL version should meet or exceed this version. Latency target 15 mS algorithmic delay + 1-3 mS computational delay.
 - NASA reconfigurable computing goals.
- ITU G.729 CODEC
 - Hi intelligibility. Important to be able to understand astronauts.
 - Good compression score. Limits communication bandwidth required between vehicle and ground. Potential to lower power.
- NASA Systems
 - In flight communications and networking capabilities.
 - In flight cyber security requirements.



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Knowledge Gained

JSC4-36-SD Implement CODECs on FPGAs

- NASA Labs
 - Common configuration to simulate flight
 - Ground station electronics, Latency to simulate distance, flight side electronics
- NASA Processes
 - Chip design process at NASA.
 - Lots of FPGA work.
- NASA Research Needs
- NASA Research Funding Opportunities



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Incorporation into Classroom

JSC4-36-SD Implement CODECs on FPGAs

- Integration of project into Digital Systems Design class.
 - 3-4 in class lectures + 1 lab exercise
 - Fixed point arithmetic.
 - Shared function unit scheduling.
 - Conversion of C to HDL.
 - System Engineering Design.
 - DSP in hardware.
 - Lab Exercise: FIR Filter implementation in HDL.



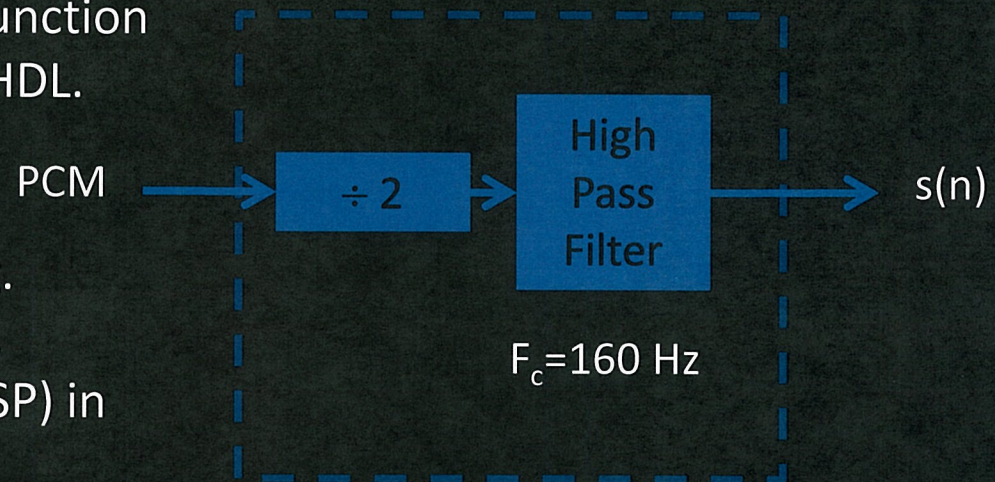
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Lab Exercise: ITU G.729 FIR Filter implementation in HDL

• Lab exercise developed to implement pre-processing function on Xilinx FPGA with Verilog HDL.

- Fixed point arithmetic.
- Shared resource scheduling.
- Finite State Machine (FSM).
- Digital Signal Processing (DSP) in Hardware.



$$H_{h1}(z) = \frac{0.46363718 - 0.92724705z^{-1} + 0.46363718z^{-2}}{1 - 1.905946465z^{-1} + 0.9114024z^{-2}}$$

$$y[n] = 7807y[n-1] - 3733y[n-2] + 1899x[n] - 3798x[n-1] + 1899x[n-2]$$

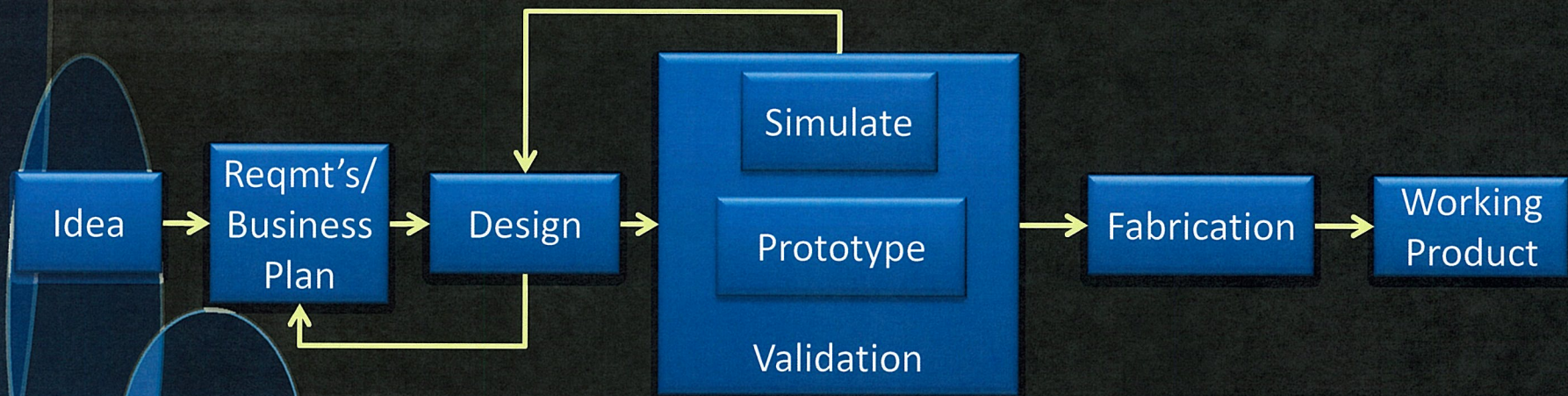


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MSU Electrical and Computer Engineering Senior Design

- 2 semester course sequence
- Capstone design experience
- Teams of 2-4 students



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Senior Design Project

- 2-3 student team.
- Implement ITU G.729 encoder in Verilog HDL.
- Validate in simulation and on Xilinx XUPV5-LX110T evaluation board.
- Managed with processes from NASA System Engineering Handbook.
- Deliver Verilog HDL to NASA EV2 Electronic Design Branch in May 2011.



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Peter L. Schmidt

Southeastern Regional Space Grant
Meeting, Charleston, SC



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Course Integration

- Material covering the basics of System Engineering will be incorporated into the course at UNC Charlotte via lecture
- A specific lecture will be given detailing the System Engineering process
- An additional lecture on documentation maintenance and configuration control is also scheduled



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Overview of knowledge gained during summer experience

- System Engineering
- On-center and NASA procedures
- Great space-flight immersion
- Specific Project Knowledge
 - Lunar Regolith Physical Properties
 - Current Design Work and Philosophy
 - Stakeholder Meetings
 - Embedded with current design team, working with design engineers tasked with the current project



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Project Definition - Cryogenic Fluid and Electrical Quick Connect System

- Quick connect functionality for both electrical and fluid connectors used in extraterrestrial
- Use of commercial off the shelf (COTS) electrical and fluid connectors as a design basis will help in minimizing system costs.
- The project's goals are to create quick connect/disconnect hardware that is operable by an astronaut wearing a space suit, in any gravity condition.
 - The hardware shall operate in zero gravity and near perfect vacuum and be adaptable to non-terrestrial locations with aggressive atmospheres and unusual contaminants.



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Project Definition (ctd) - Cryogenic Fluid and Electrical Quick Connect System

- The system shall also include an installation tool to overcome large mating forces
- The system shall feature geometry to assure correct connector alignment for engagement
- The system shall have a dust exclusion system to minimize, if not eliminate, any dust that could impinge or collect on the connector interface surfaces.
 - This design effort will include a standardization effort, such that three distinct sizes of connector systems result.



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Lunar Regolith Design Case

- Particle Shape
- Particle Size Distribution
- Composition
- Lessons Learned
- Simulants
- Hard Vacuum
- Other Planets / Bodies



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Outpost Infrastructure

- Modular Layout
- Water
- Atmosphere
- Fuel
- Process Fluids
- Electric Power (High Voltage)
- Electric Signals (Low Voltage)



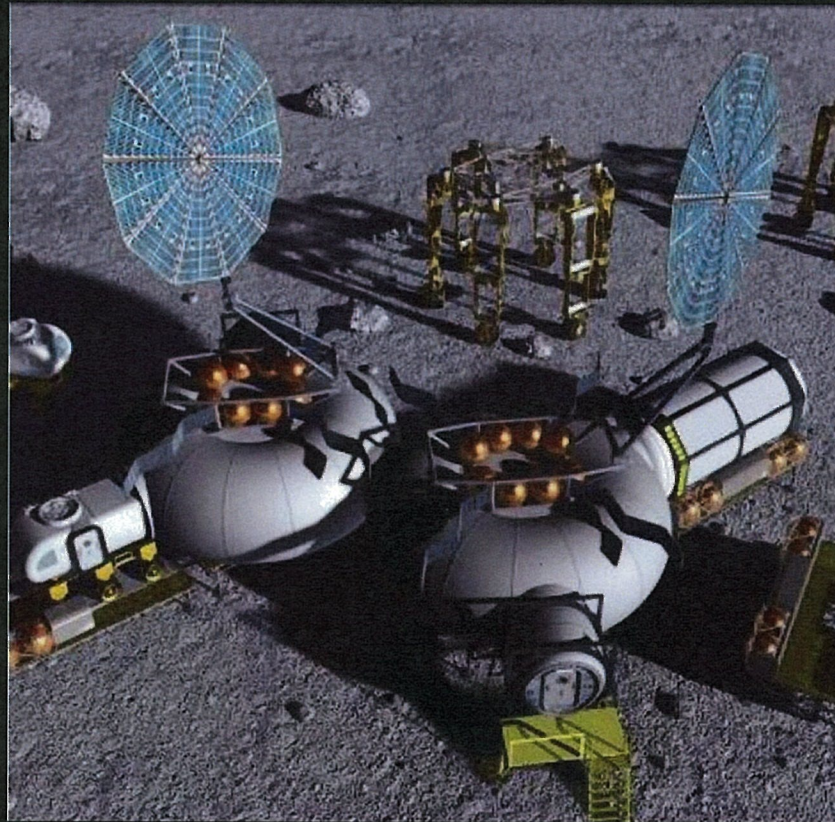
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Proposed Outpost Layout



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Complementary Technologies

- Consumables Scavenging
- Consumables Transport
- Consumables Production
- Suit Exterior Interface Station
- Construction Equipment
- Desert Operations



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Use of Existing Standards / COTS

- Mil-C-24231
- Mil-C-24217
- Mil-DTL-26482
- ISO 7241



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Paul J. van Susante

Mid-Atlantic Regional Space Grant
Meeting, Delaware



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Overview of knowledge gained during summer experience

- System Engineering
- On-center and NASA procedures
- Great space-flight immersion
- Specific Project Knowledge
 - Landing pad requirements
 - Landing pad materials and production
 - Test setup
 - Coached an Excavator design group (co-ops & interns)
 - Safety experimental procedures



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ESMD Project

NASA Field Center: Kennedy Space Center

ESMD Related Area: Lunar and Planetary Surface Systems

Project Title: Lunar Regolith Excavation O₂
Prod/Outpost Emplace

Description: Landing pad Installation and support for O₂ production. This project will investigate concepts for Lunar Regolith excavation equipment and propose solutions in the form of completed designs and prototypes.



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CSM ESMD Senior Design Projects

- Robotic Excavator, Grader, Dumper integration for lunar O₂ production, feedstock gathering and lunar outpost site preparation
- Robotic Attachment for interplanetary landing pad surface stabilization
- Lunabotics Mining Competition 2011 team



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Landing Pad Project

- Go to other planetary bodies with humans and robots
- First thing you do: land on surface
- Sustainable, repeatable
- Safety, risk mitigation
- Use local resources
- Gather feedstock for O₂ production while building a landing pad



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Apollo Lunar Landing

Apollo Landing video



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Need for landing pads

- blast streak (or 'plume') small particles (10-60 microns)
- speeds between 1.0-2.5 kilometers per second
- exhaust gases powerful enough to move rocks up to 15 cm in size.
- 1 to 3 degree elevation angle in all missions
- Apollo 15 anomaly
- Mars case, deep cratering (several feet) will occur underneath lander. Could tip over lander



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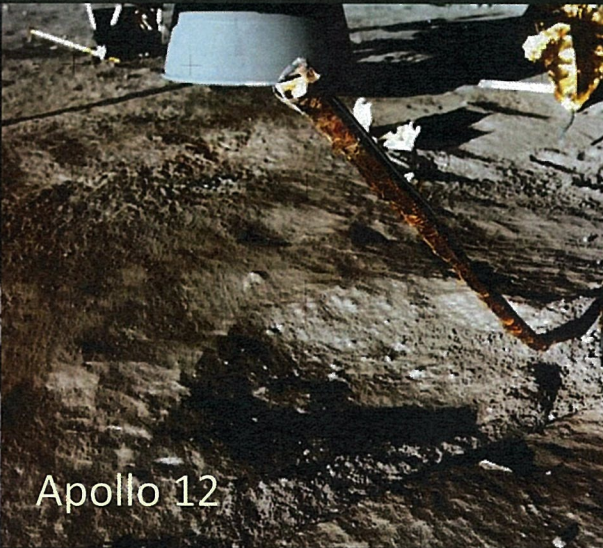


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Need for landing pads



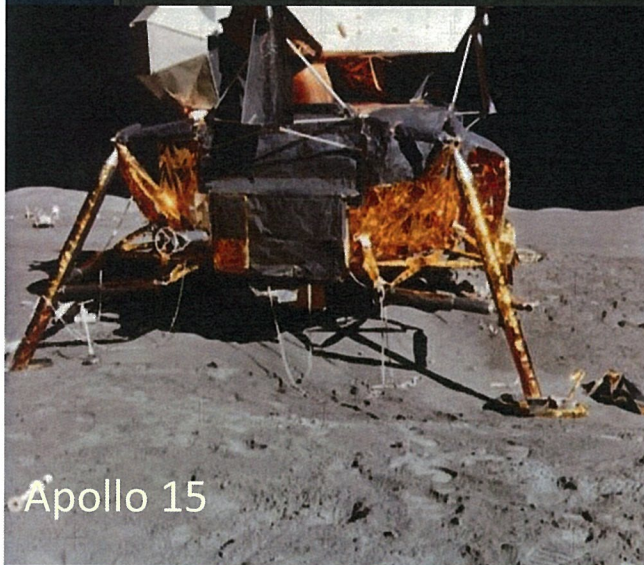
Apollo 11



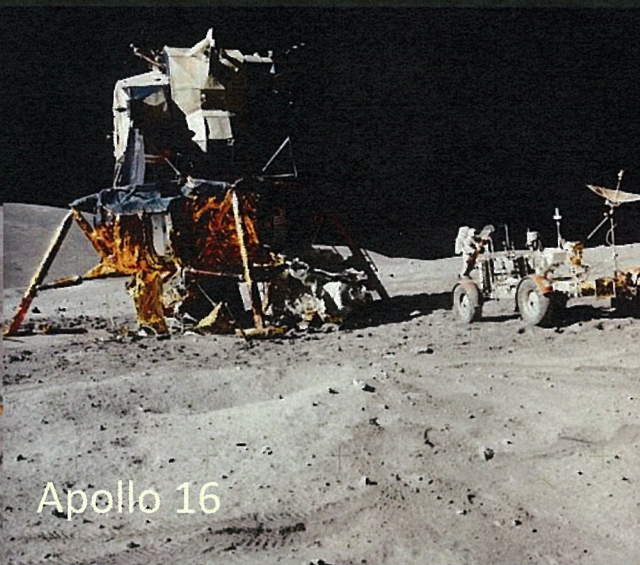
Apollo 12



Apollo 14



Apollo 15



Apollo 16



Apollo 17

Need for landing pads

- Ejecta hits surrounding hardware
- Ejecta hits landing spacecraft
- Regolith instability after landing
- Loss of visibility during landing
- Spoofing of landing sensors
- Dust deposition on hardware
- Crew exposed to plume chemicals in soil



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Requirements for Landing Pads

- frequency of use
- size
- local geography
- different zones with different loading requirements
- mechanical
- thermal
- chemical
- radiation
- meteoroids
- variety of methods to use to stabilize top layer of regolith
- surface quality of landingpad
- environment
- durability
- ease of maintenance / repair / replacement



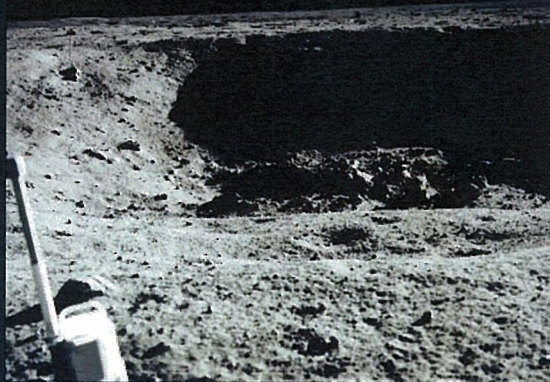
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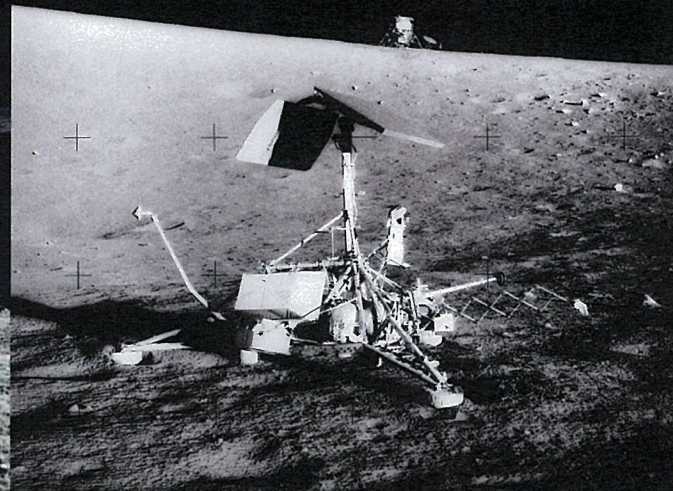
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Landing Pad Preparation

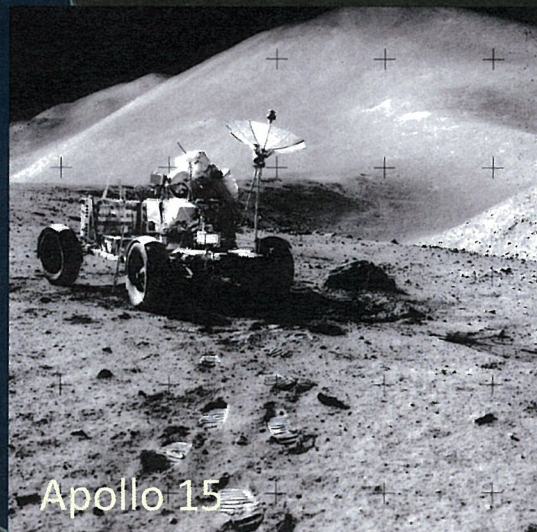
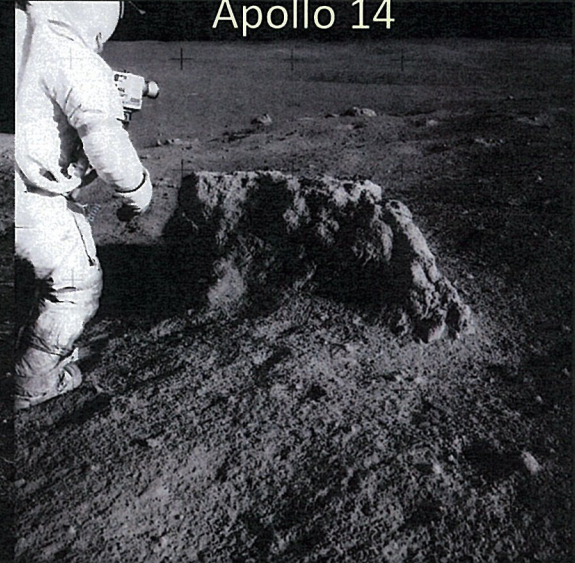
Apollo 11



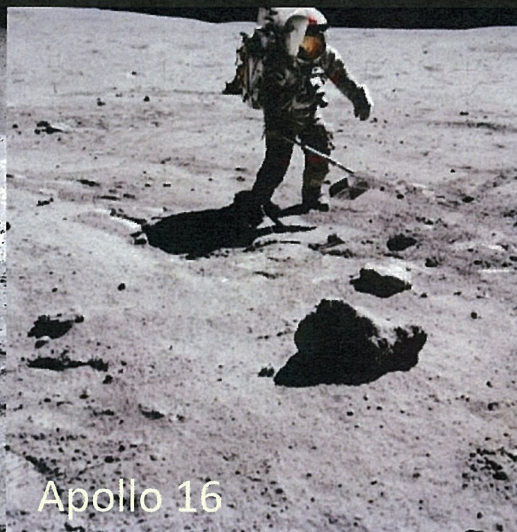
Apollo 12



Apollo 14



Apollo 15



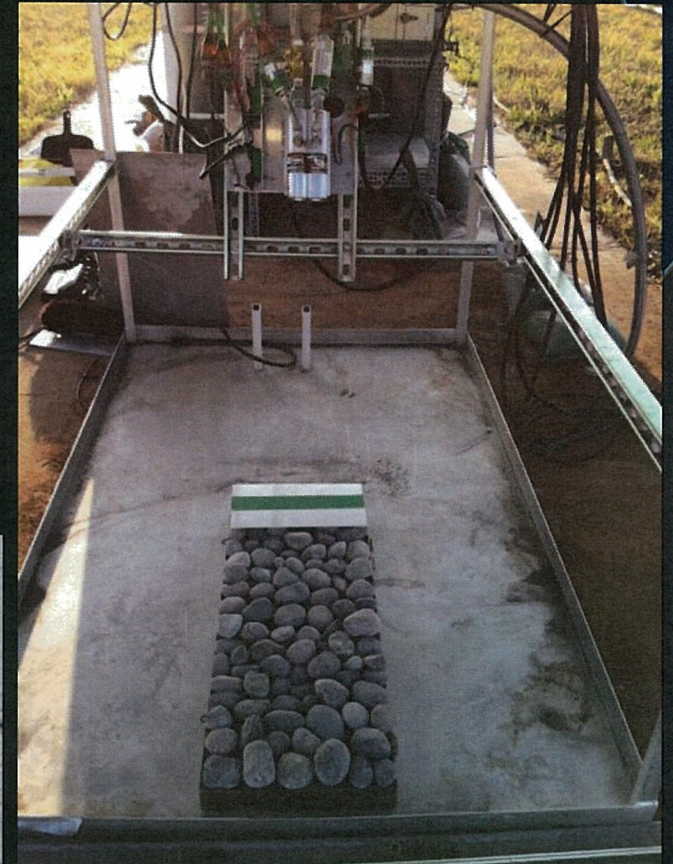
Apollo 16



Apollo 17

Landing pad stabilization options

Testing in Progress



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Landing Pad Testing at KSC



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Requirements for Soil Stabilization Tool

- mass
- power
- communication/control
- volume
- budget
- schedule
- interfaces (Chariot Quick attach or CAT-MTL)



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Conclusion

- 15 or more students in 3 senior design projects during AY 2011 (fall 2010, spring 2011)
- System Engineering Special Topic Seminar for 40-200 students
- Collaboration with KSC-NE-S on landing pad technology development
- Evaluation of knowledge of SE before and after course
- White paper with feedback to ESMD-education
- Still involved in ongoing landing pad material performance evaluation tests at KSC
- Tentatively 3 journal papers will be written on the results of the work performed over the summer



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ESMD-Faculty Fellowship Report

Janusz Zalewski

Western Regional Space Grant
Meeting, Omaha, Ne



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Janusz Zalewski
Florida Gulf Coast University
Project Topic:
Prognostics for Complex Systems
Project Sponsor:
Dr. Kai Goebel, NASA Ames



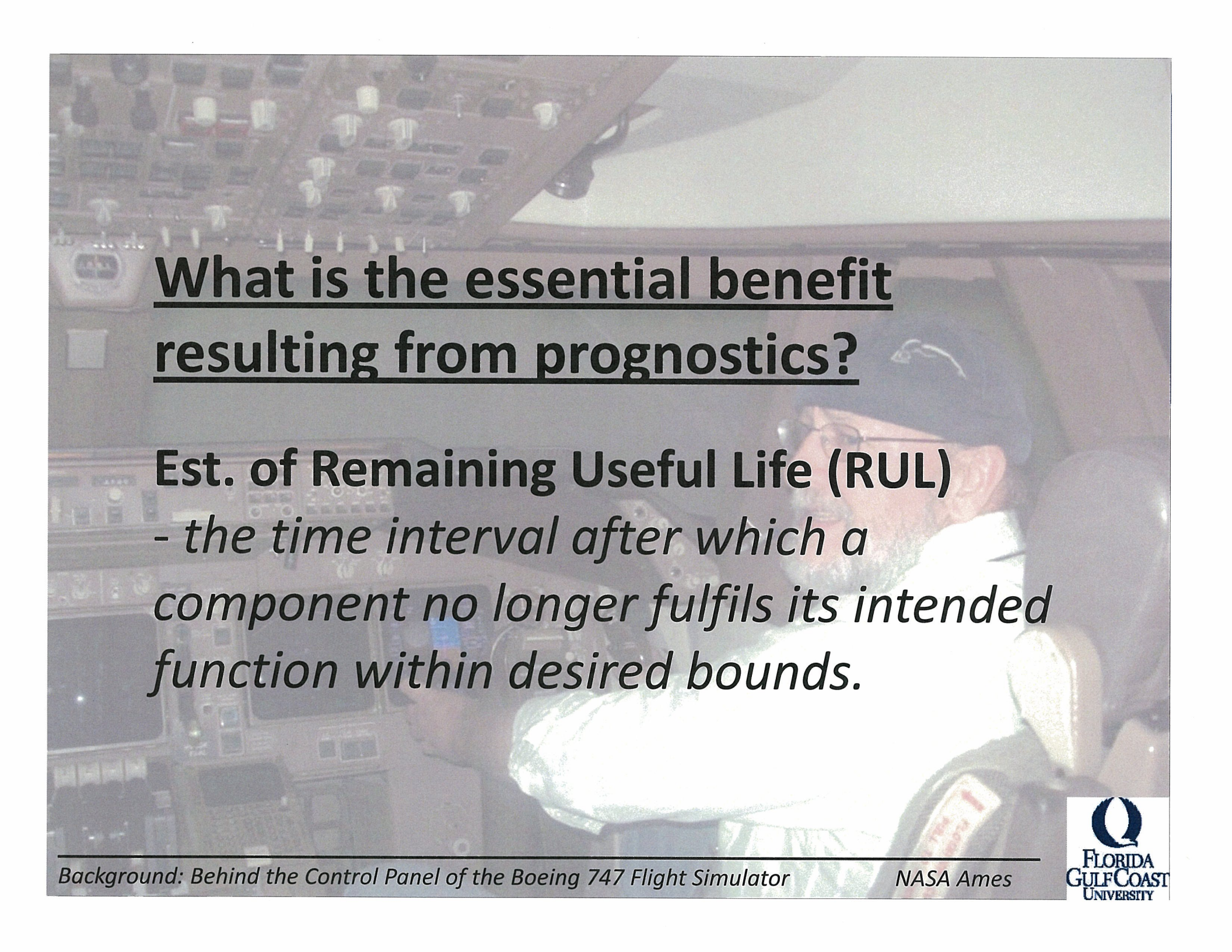
What is Prognostics?

A field of engineering, which deals with detecting and predicting faults and failures in technical systems.

What's the Context of Prognostics?

Integrated System Health Management (ISHM), which deals with *detecting, diagnosing, prognosing, and mitigating* faults and failures in technical systems.

Background: UH-60 Black Hawk Helicopter with Prognostics Equipment on Board

A person wearing a flight simulator headset and a white shirt is seated in a cockpit, looking at a control panel. The background is filled with various instruments and controls.

What is the essential benefit resulting from prognostics?

Est. of Remaining Useful Life (RUL)

- the time interval after which a component no longer fulfils its intended function within desired bounds.

2010 Summer Accomplishments (1)

- **5+ Educ. Modules on Prognostics**

<http://satnet.fgcu.edu/~zal/prognostics>

- **Definition of a Senior Design Project**
- **Review Paper on Recent Methods in Prognostics (in the works)**
- **Educational Paper on Experiences at NASA**

Background: In the Airport Traffic Control Tower Simulation Facility

NASA Ames



2010 Summer Accomplishments (2)

- Innovative way of engaging domain experts in interacting with students via Q&A exchange on the Bulletin Bd
 - Kai Goebel
 - Abhinav Saxena
 - Sankalita Saha
 - Bhaskar Saha
 - [Ole Mengshoel & Wojtek Przytula]

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- Gregory Hall
- Kai Goebel



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QUESTIONS?



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Senior Design Projects Selected



Christina Carmen (**MSFC**) University of Alabama at Huntsville
MSFC1-20-SD NASA Exploration Toolset for Optimization of Launch and Space Systems (XTOOLSS)



Thomas Morris (**JSC**) Mississippi State University
JSC4-36-SD Implement Codecs on FPGA's



Peter Schmidt (**KSC**) University of North Carolina at Charlotte
KSC1-06-SD Umbilicals and Quick Disconnect Couplings



Paul van Susante (**KSC**) Colorado School of Mines
KSC1-05-SD Lunar Regolith Excavation 02 Prod/Outpost Emplace



Janusz Zalewski (**ARC**) Florida Gulf Coast University
ARC2-07-SD Prognostics for Complex Sytems



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NASA ESMD

Space Grant Meeting Assignments

Faculty	Space Grant Meeting	Dates	KSC Attendee
Christina L. Carmen	Great Midwest Minneapolis, MN	9/17/10- 9/18/10	Diane Ingraham
Tommy Morris	Northeast Newport, RI	9/10/10- 9/11/10	Susan Sawyer
Peter Schmidt	Southeast South Carolina	TBA	Gloria Murphy
Paul J. van Susante	Mid-Atlantic Delaware	9/16/10- 9/18/10	Mandi Falconer
Janusz Zalewski	Western Omaha, NE	9/16/10- 9/18/10	Luis Rabelo

