



Integrated System Health Management: Foundational Concepts, Approach, and Implementation

Fernando Figueroa
NASA Stennis Space Center, MS

September 18, 2009





Acknowledgements

The author wishes to acknowledge the NASA Innovative Partnerships Program (IPP) for supporting the development of the technologies that enable Integrated System Health Management (ISHM) capability. Special thanks to Dr. Ramona Travis, Manager of the IPP at NASA Stennis, and to John Bailey, who as Chief of the Science and Technology Division, has been instrumental in making possible development of the ISHM area.



Outline

- Motivation
- Concepts and Approaches
 - ISHM: Background/Definition
 - ISHM Model of a system
 - Detection of anomaly indicators.
 - Determination and confirmation of anomalies.
 - Diagnostic of causes and determination of effects.
 - Consistency checking cycle.
 - Management of health information
 - User Interfaces
- Implementation
- Conclusions



Support rocket engine test mission with highly reliable, accurate measurements; reduced costs; etc.

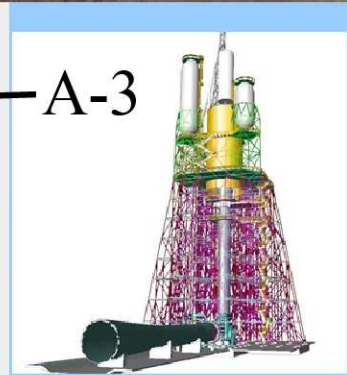
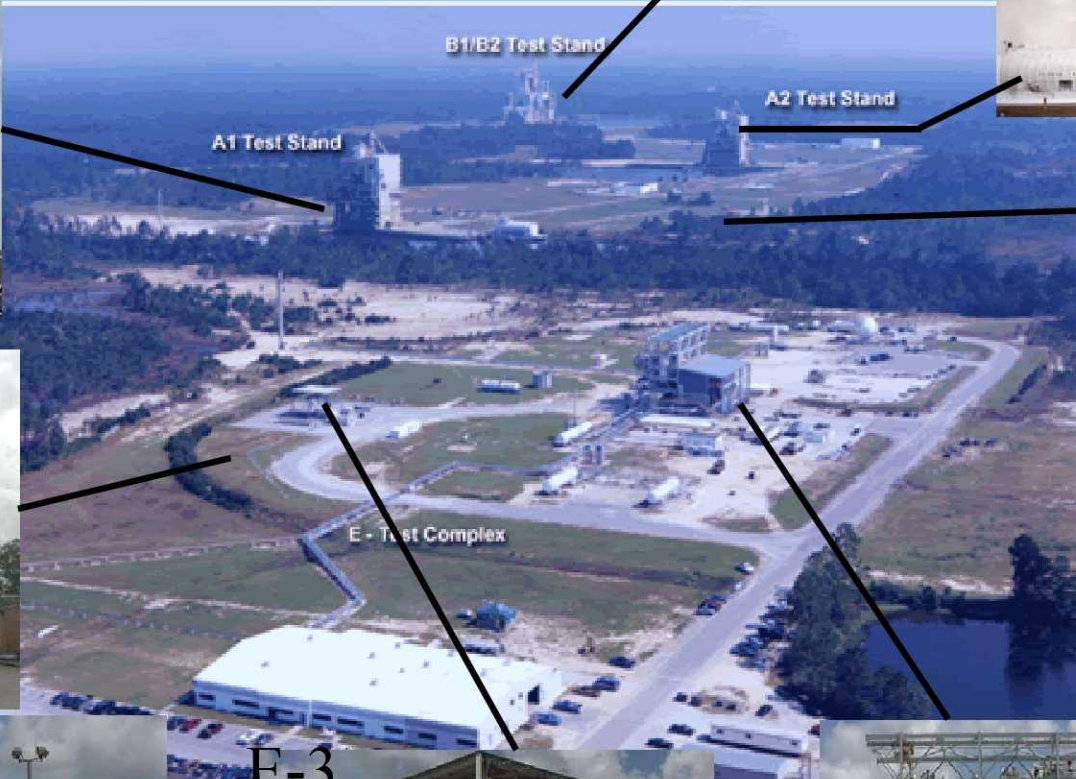


B-1/B-2

A-1



A-2



A-3

- Others:
- High-pressure Gas
 - Industrial Water



E-2



E-3



E-1



Requirements Driving ISHM

Through comprehensive and continuous vigilance

- Improve quality
 - By more accurately understanding the state of a system.
- Minimize costs
 - Of configuration
 - Of repair and calibration
 - Of operations
- Avoid downtime
 - By predicting impending failures
 - By timely intervention
 - By faster diagnosis and recovery
- Increase safety (protect people and assets)



ISHM Objectives

- Use available data, information, and knowledge to
 - Identify system state
 - Detect anomalies
 - Determine anomaly causes
 - Predict system impacts
 - Predict future anomalies
 - Recommend timely mitigation steps
 - Evolve to incorporate new knowledge

ISHM implementation is a problem of “management” of data, information, and knowledge (DIAK) focused on achieving the objectives of ISHM



Concepts and Approach



ISHM is Being Done Now ... But

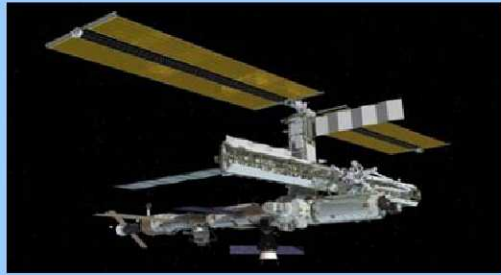


MOVE CAPABILITY TOWARD LEVELS 2 AND 1

International Space Station

Rocket Engine Test Stand

Layer 1
Vehicle/
Test Stand



Signal
threshold
violation
detection

Layer 2
Astronaut/
Test
Conductor



Added
DIaK from
on-board
users.

Layer 3
Control
Room



Added
DIaK from
broad
group of
experts.

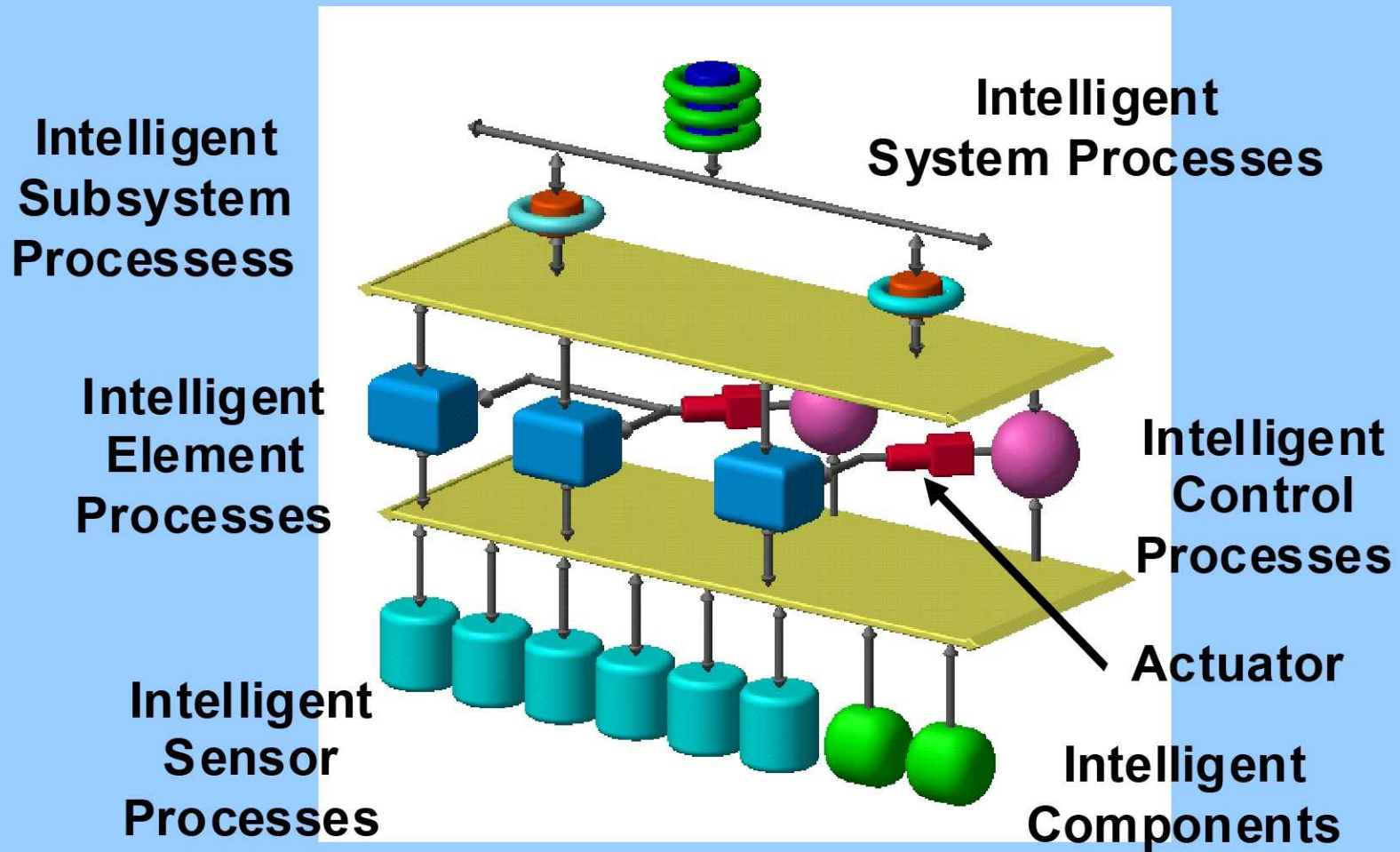
Layer 4
Back
Control
Room



Added
DIaK
resources
from larger
community

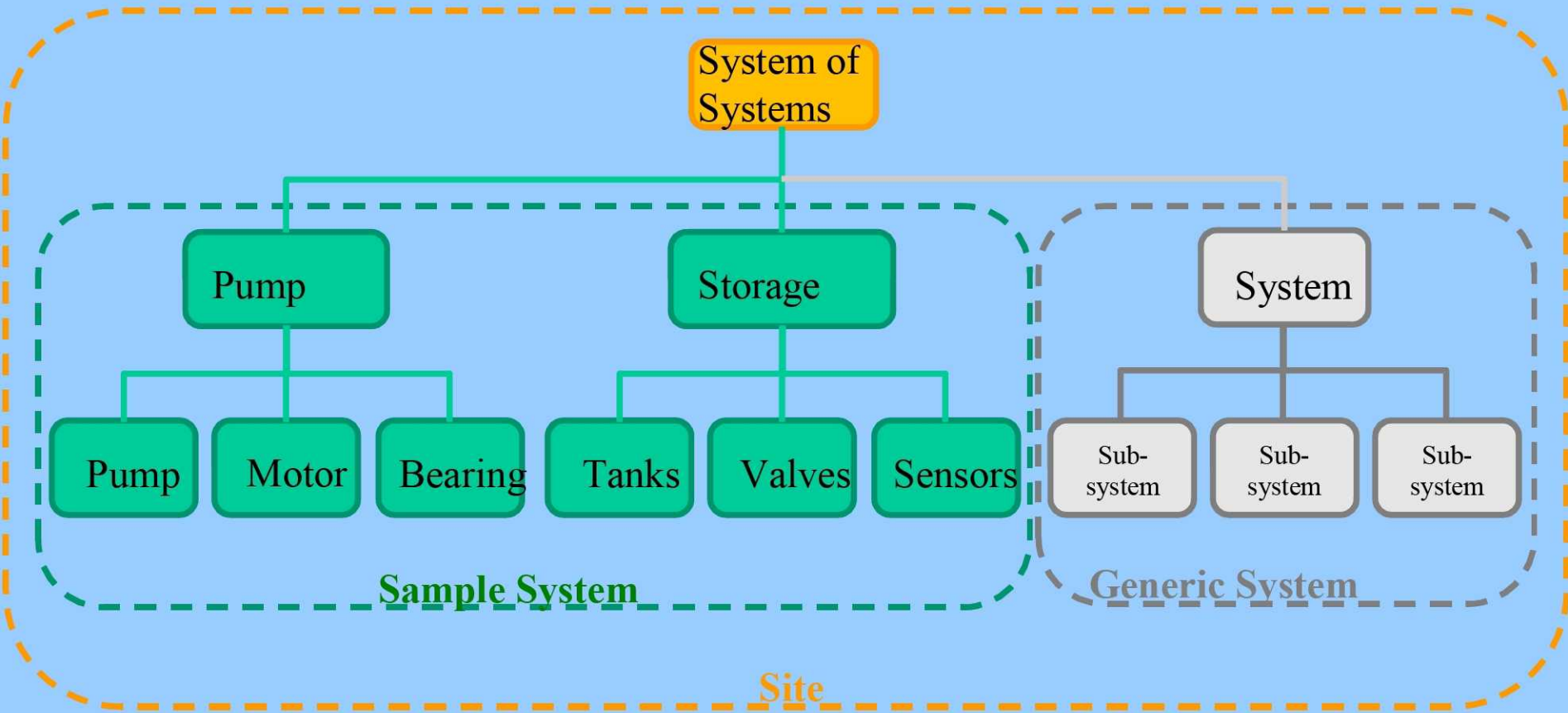


Data, Information, and Knowledge Management Architecture for ISHM (Information Architecture)



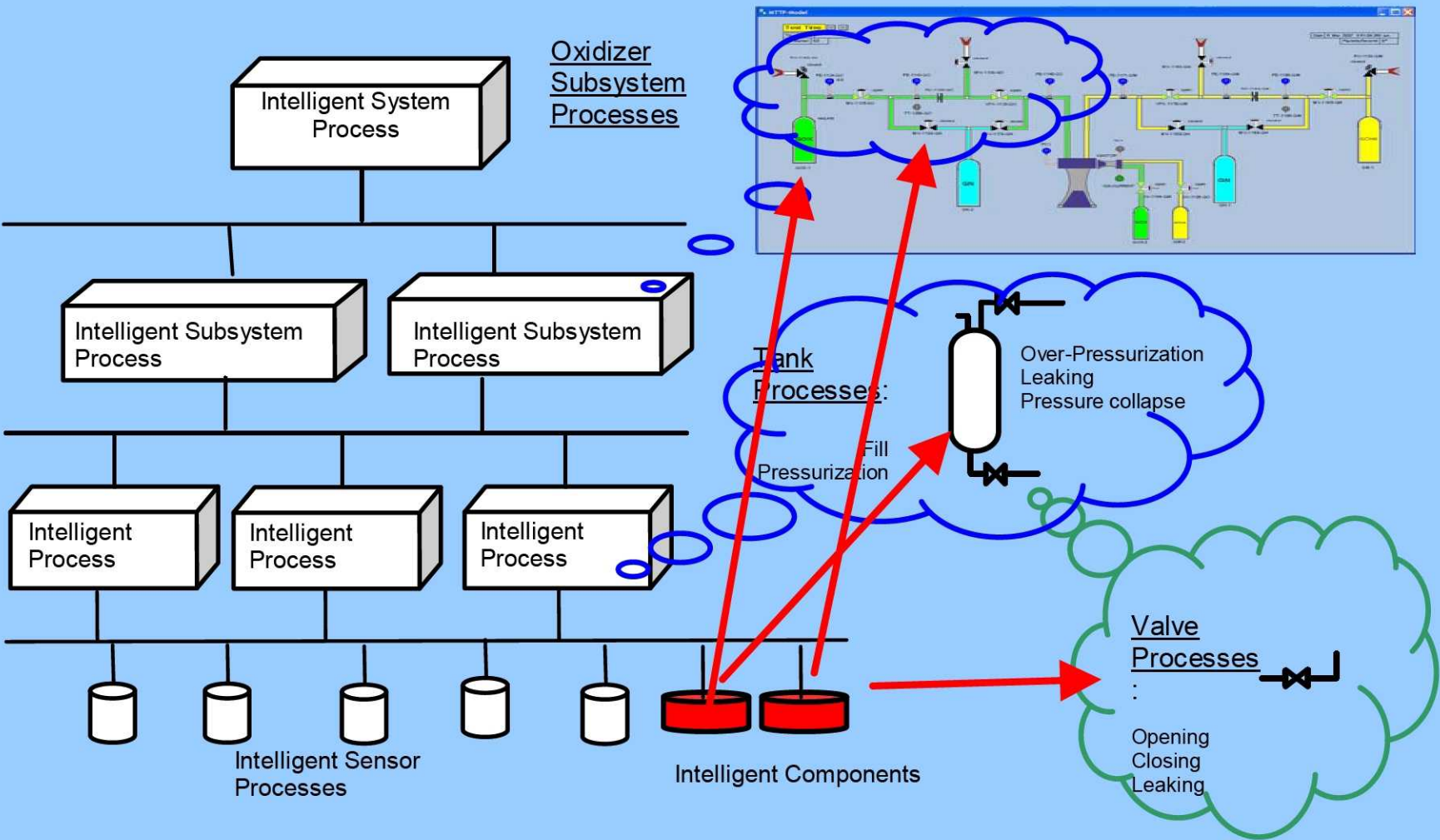


Classic architecture describing how systems are built





Correspondence between elements in the ISHM Information Architecture and processes taking place in a system

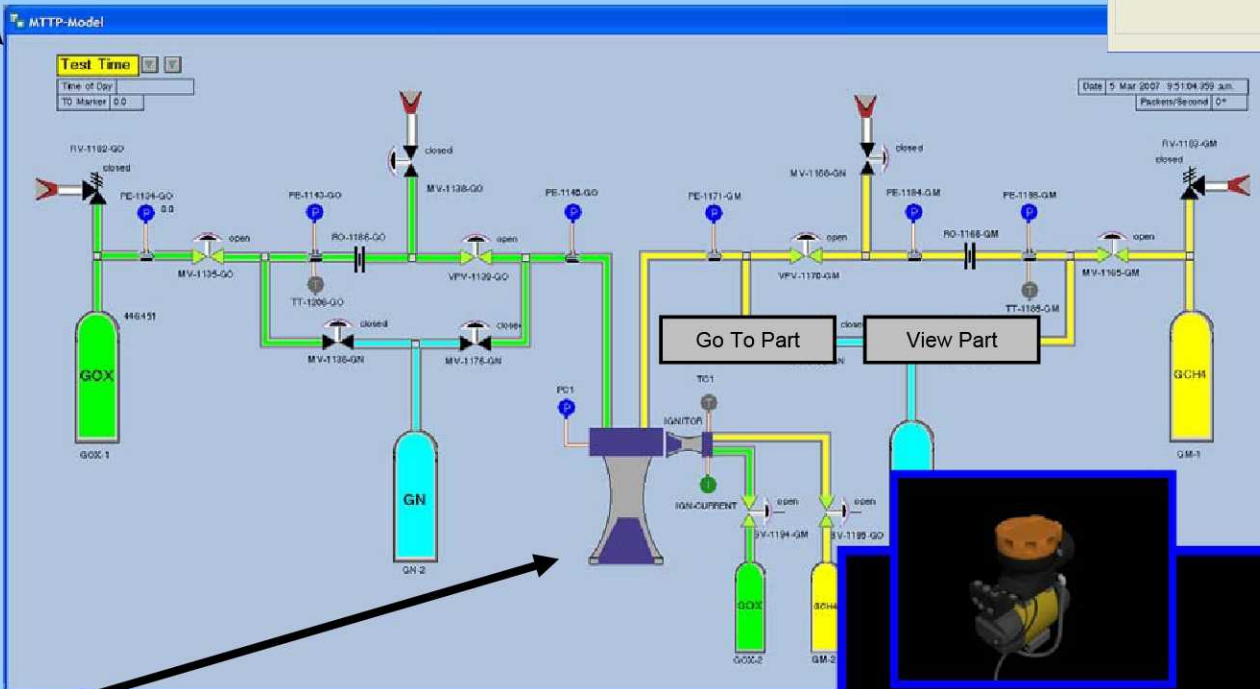




SSC Integrated System Health Management (ISHM) Capabilities

ISHM Models (Embedded Data, Information, and Knowledge):

MTTP Implementation

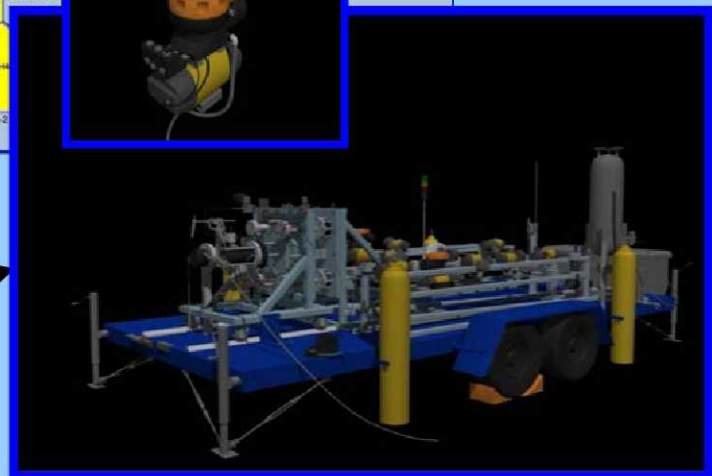


Anomaly Detection: Leaks, etc.

Intelligent Sensors: IEEE Standard+Health



MTTP



Embedding of Predictive Models

Root Cause Analysis

Integrated Awareness: 3-D Health Visualization of MTTP



John C. Stennis Space Center ISHM Partnerships for Rocket Propulsion testing

Rocket Engine Test Stand



Test Article

Open Systems Architectures

Prognostics & Anomaly Detection

Root Cause Analysis

IEEE 1451 Smart & Intelligent Sensors

Integrated Awareness



GENERAL ATOMICS
ELECTROMAGNETIC SYSTEMS

Leak: within the active range of gas sensor
Leak: through the active range of gas sensor
Leak: through the active range of gas sensor
Leak: through the active range of gas sensor



MOBITRUM
Brings you mobility®

NASA KSC

ATK

INVOCON, INC.
Innovative Concepts in Systems Engineering

NVE CORPORATION

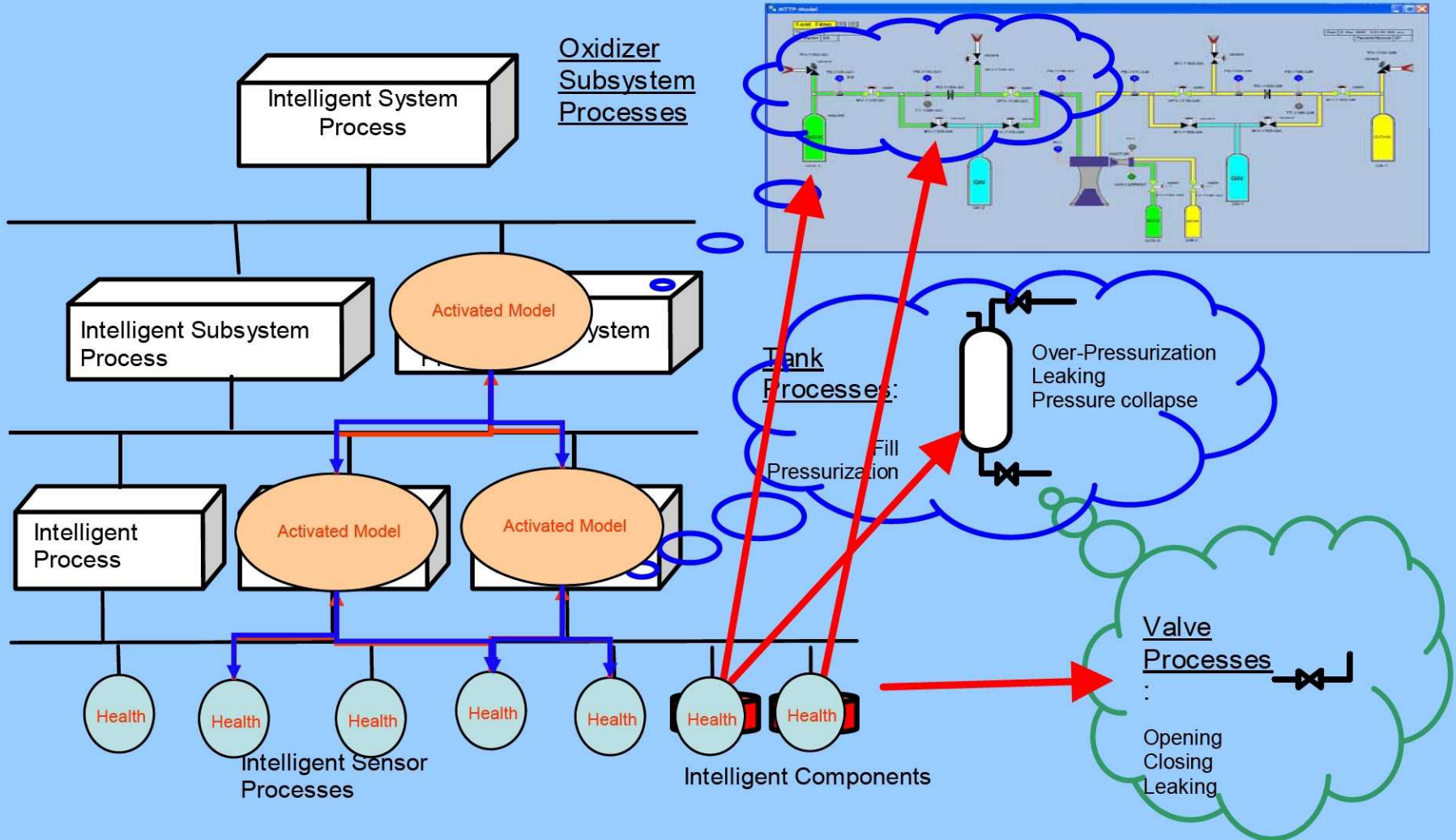
Rowan University

COLLEGE OF TECHNOLOGY
University of Houston

TOSS
plug-and-play



Detection and Confirmation of Anomalies Consistency Checking Cycle





MTTP Embedded Diagnostics

MTTP-Model

Test Time Example Rules

Time of Day 27:15:04:57.250
T0 Marker 27.86

Date 31 Jan 2007 1:33:28.75 a.m.
Packets/Second 24.609

RV-1182-GO closed
PE-1134-GO
PE-1143-GO
MV-1138-GO
PE-1140-GO
RO-1186-GO
MV-1135-GO
PE-1171-GM
MV-1168-GN
PE-1184-GM
PE-1198-GM
RO-1166-GM
RV-1183-GM closed
MV-1165-GM
TT-1185-GM
GOX-1
pressurizable-subsystem
Pressurizable

Component Electronic Data Sheets for MV-1135-GO

Basic CEDS | Extended CEDS

Template ID: 100

Component

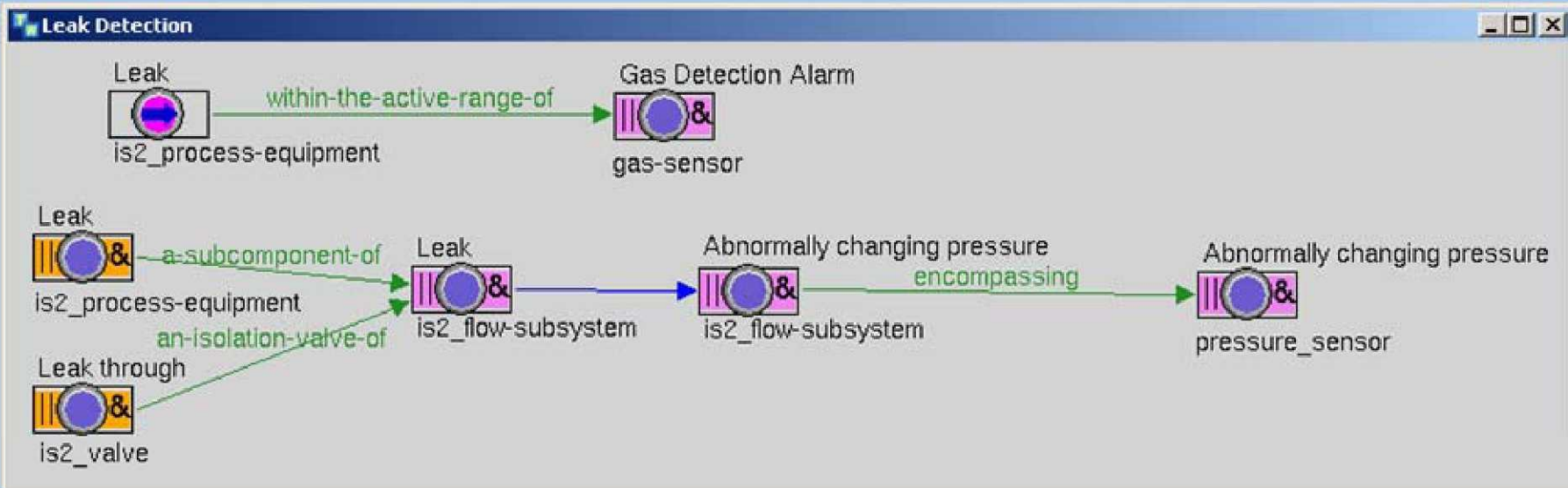
Manufacturer ID: Worcester Controls
Model Number: 10 30 SZM2120 P BC R6
Version Letter:
Serial Number: FCPF 5681

Go To Part View Part

TC-1
IGN-CURRENT
GOX-2

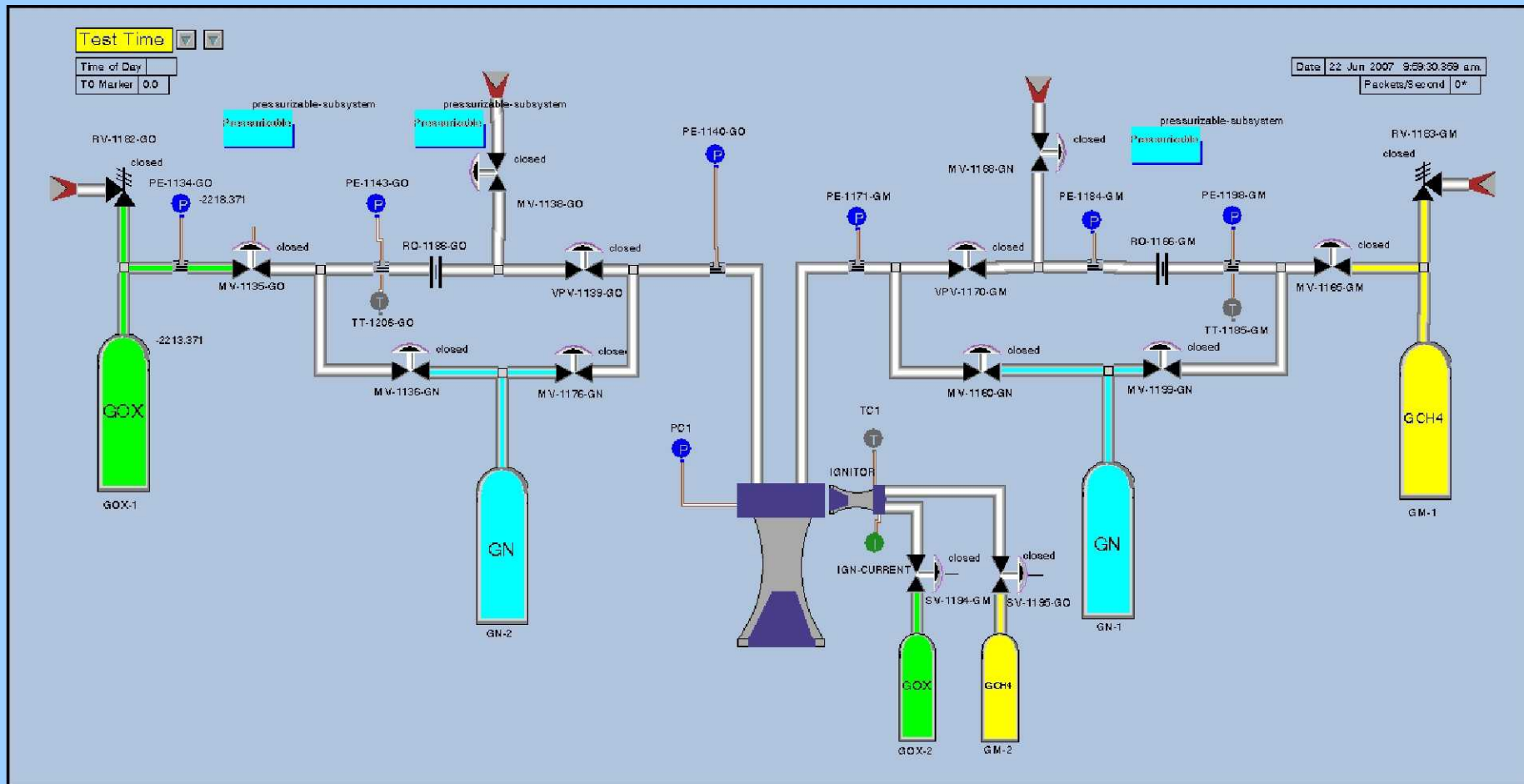


Root-Cause Tree





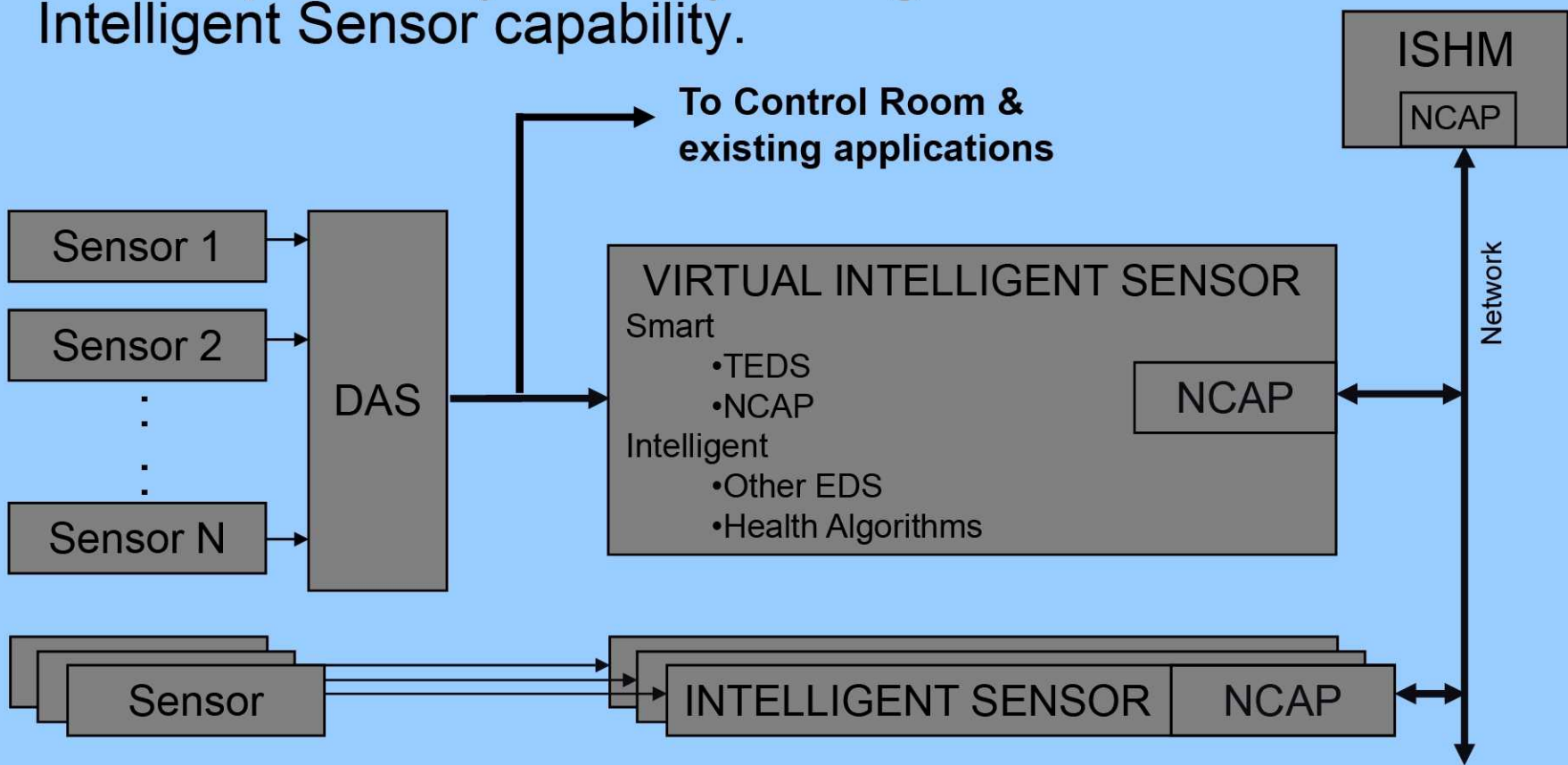
ISHM Enabling Technologies: Root Cause Analysis





Virtual Intelligent Sensors

- Provides benefits of ISHM capabilities to existing data acquisition systems by adding Virtual Intelligent Sensor capability.

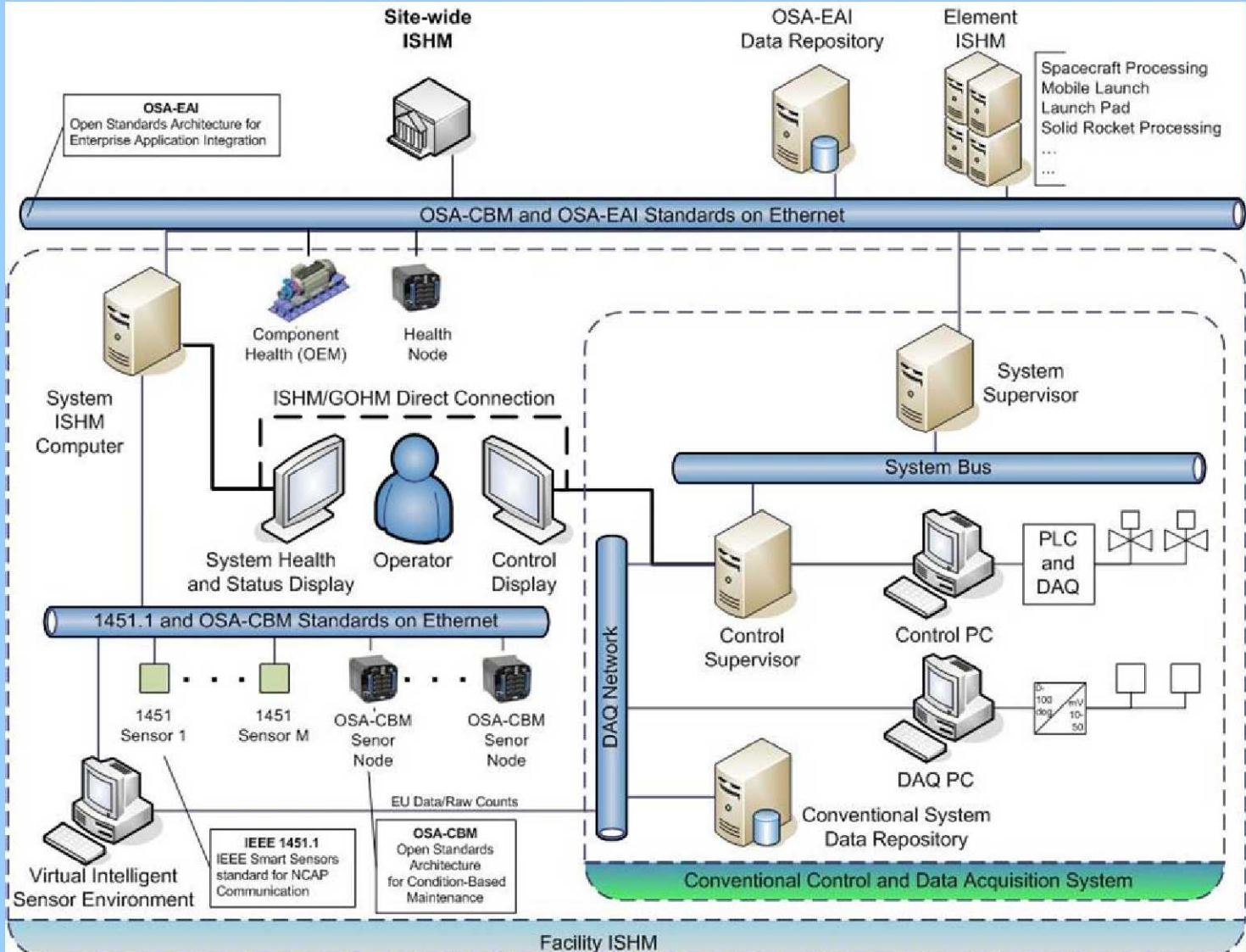




ISHM Implementations

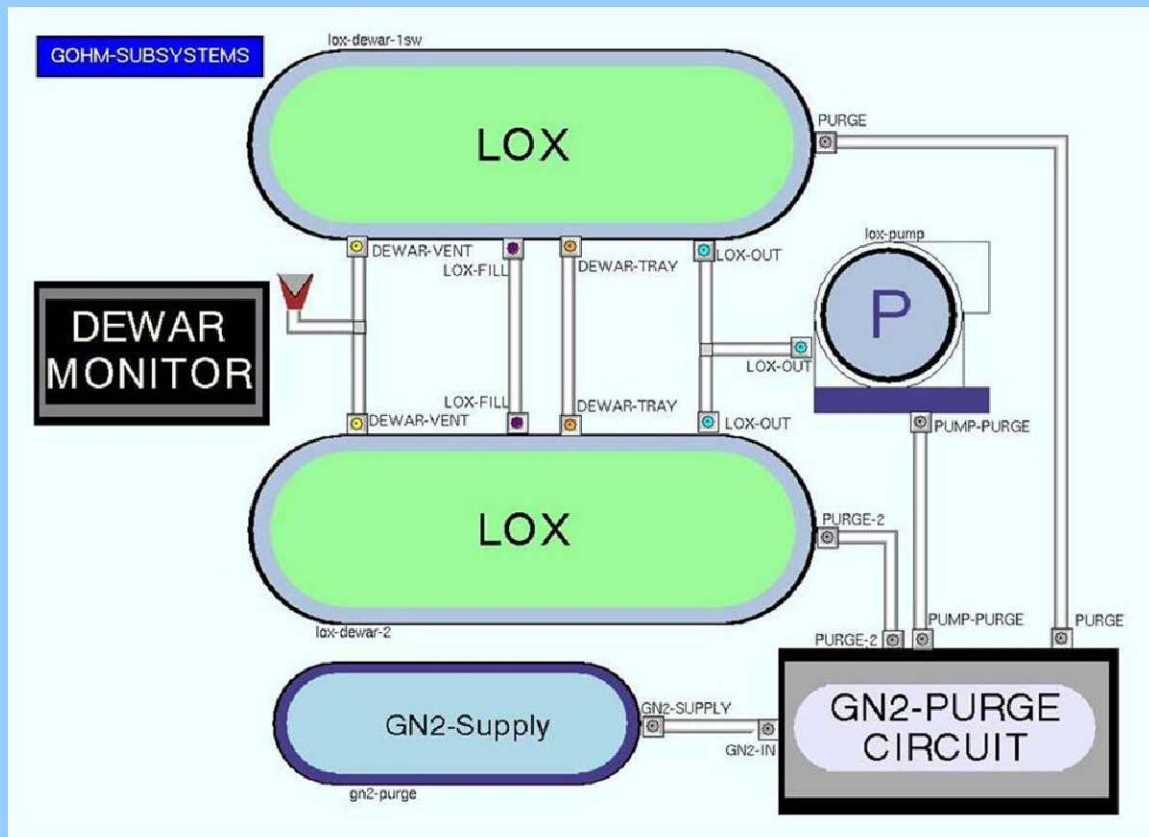


Generic Architecture to implement ISHM capability for systems with conventional equipment, with option to incorporate advanced smart/intelligent sensors and actuators.



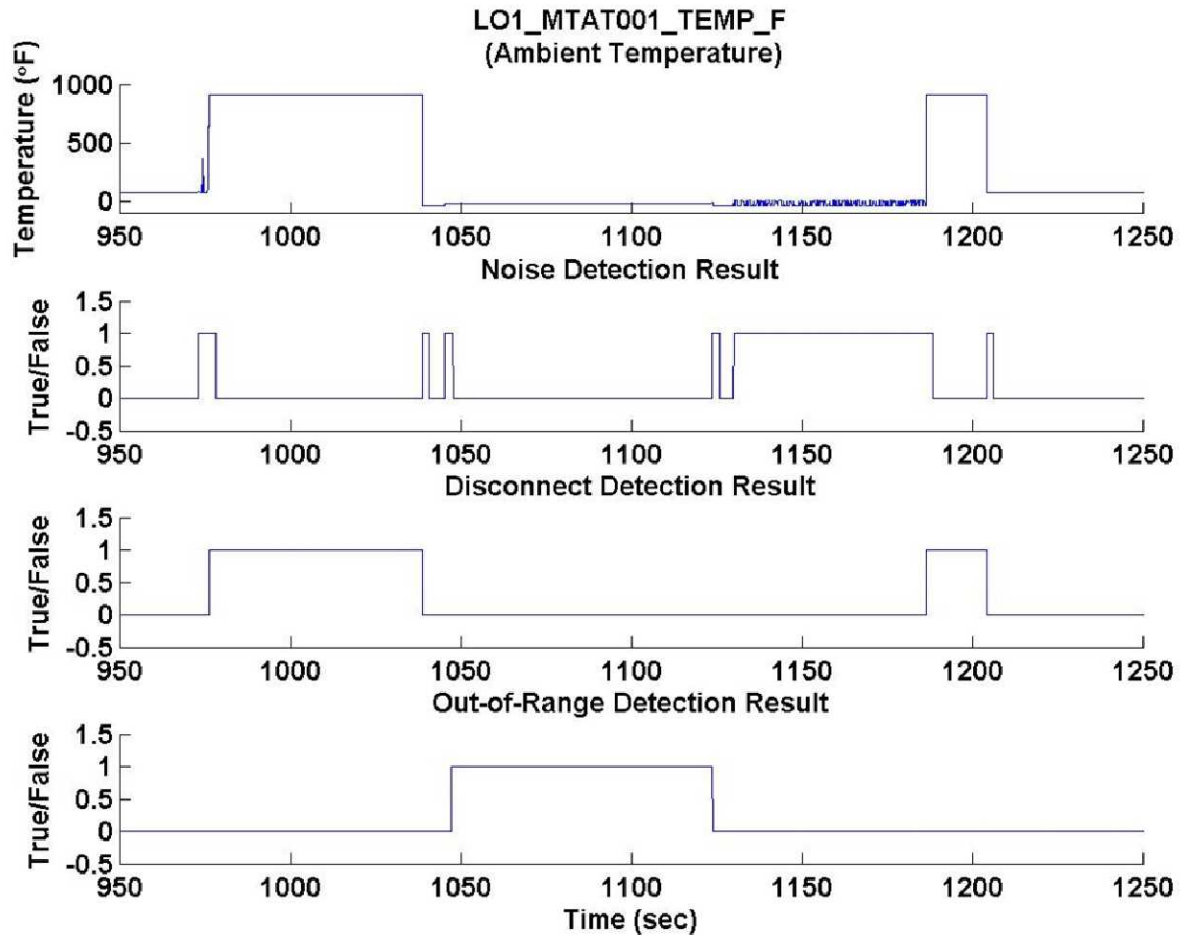


Top level view of the ISHM model of the Launch Complex 20 Facility at NASA Kennedy Space Center





Sensor anomaly indicators detected by an intelligent sensor during a pump test using the LC-20 facility at NASA Kennedy Space Center





Screenshot of the ISHM model of the LC-20 facility at KSC showing detection of a valve leak created by opening the valve manually

The screenshot displays the ISHM model interface for the LC-20 facility. The main window shows a real-time plot of GNPT104 pressure, which has dropped from approximately 30 to 5 units. The plot is titled "Real-Time Plot of GNPT104" and shows the current time as 20:17:30 on 8 Tue Apr 2008.

The schematic diagram in the KB Workspace shows the facility layout with various components labeled, including GNPT104, GNCP104, GNM V119, GNRG103, GNRG104, GNRV105, GNOR108, GNIP101, GNPG104, and GNM V109. A valve labeled "closed" is shown in the diagram.

The Alarms window displays a list of detected events:

Target	Event Name	Value
T-Junction-047-Pressure-Su...	Abnormally changing pressure	true
T-Junction-047-Pressure-Su...	Leak	suspect
T-Junction-047-Pressure-Su...	Higher Than Expected Pressure	false
T-Junction-047-Pressure-Su...	Lower Than Expected Pressure	true
Gnpt104	Abnormally changing pressure	true
Gnpt104	Higher Than Expected Pressure	false
Gnpt104	Lower Than Expected Pressure	true
X-Junction-005-Pressure-Su...	Leak	suspect

The Root Causes window displays a list of suspected causes:

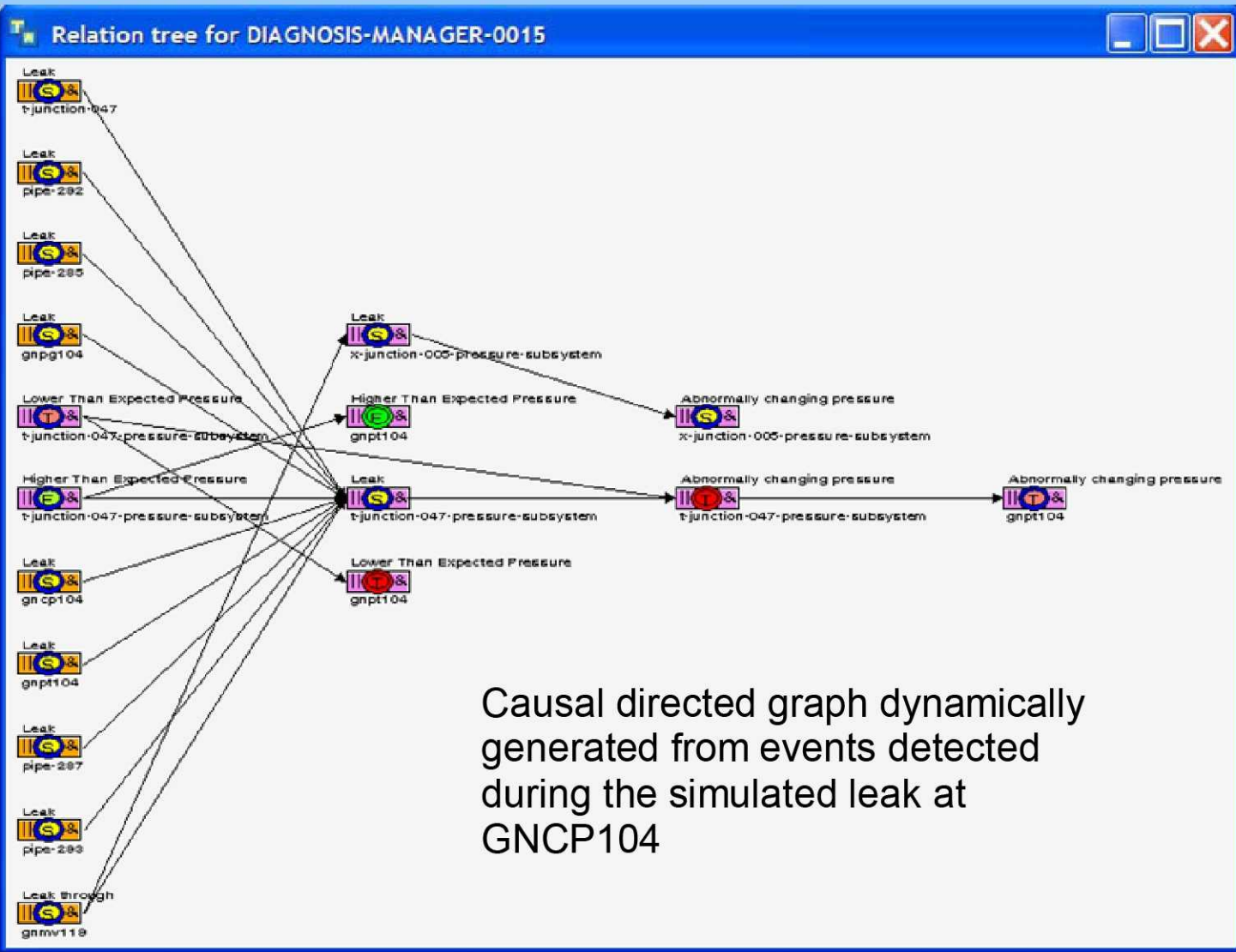
Target	Event Name	Va...	Status
Gncp104	Leak	suspect	upstream inferred
Gnpg104	Leak	suspect	upstream inferred
Gnpt104	Leak	suspect	upstream inferred
Pipe-285	Leak	suspect	upstream inferred
Pipe-287	Leak	suspect	upstream inferred
Pipe-292	Leak	suspect	upstream inferred
Pipe-293	Leak	suspect	upstream inferred
T-Junction-047	Leak	suspect	upstream inferred
Gnmv119	Leak through	suspect	upstream inferred

The Package Browser shows loaded packages including VISE Interface Classes, EDS Classes, and Class Browser Classes.

The Alarms window also shows a status bar at the bottom: ISOS-DELL-M70:1111 4/8/2008 15:17:34: Alarm: Lower Than Expected Pres



Expanded causal-directed graph generated by the detection of a leak in the subsystem where a valve was opened manually (injected leak)



Causal directed graph dynamically generated from events detected during the simulated leak at GNCP104



Pilot ISHM Implementation Chemical Steam Generator (CSG)

The screenshot displays a Telewindows Client interface for a Chemical Steam Generator (CSG) system. The main window, titled "CSG Domain Map", shows a schematic of the system with three main components: the "CSG IPA System" (yellow), "CSG LOX System" (green), and "CSG Water System" (blue). Each system is connected to a corresponding "RUNTANK" (IPA-RUNTANK, LOX-RUNTANK, WATER-RUNTANK). The main unit is labeled "CSG-1" and includes a "STEAM-PLENUM". Inputs for "LOX" and "H2O" are shown on the left. A "Real-Time Plot of PE-14A4101-IPA" is visible at the bottom left, showing a stable signal around 1000 mV/V. A detailed "CSG Unit #1" diagram is shown in a separate window, illustrating the internal piping, valves, and sensors, including various pressure (PE), temperature (TC), and flow (F) sensors, as well as control valves like "26TAGE-LOX" and "MAIN-IPA".

Blue Lines

- PE-14A4047-LO
- BLUE-LINE-DEMO-SENSOR

Red Lines

- TC-14A4132-S

EDS Attributes

Bridge Element Impedance (Ω)	351.3
Bridge Type	Full
Calibration Date	2008-07-31
Calibration Period	365
Calibrator's Initials	TS
Electronic Datasheet Name	Bridge Sensor
Full Scale Electrical Value Precision	mV/V
IEEE 1451.4 Template ID	33
Mapping Method	Linear
Maximum Electrical Output (V/V)	3.034
Maximum Excitation Level (V)	15
Maximum Physical Value	2000
Measurement Location ID	4101
Minimum Electrical Output (V/V)	0.031
Minimum Excitation Level (V)	10
Minimum Physical Value	0

Alarms

Target	Event Name	Value	S
--------	------------	-------	---

Root Cause

Target	Event Name	Value	S
--------	------------	-------	---

Repair Actions

Target	Action Name	Status
--------	-------------	--------



Pilot ISHM Implementation Chemical Steam Generator (CSG)

The screenshot displays the Telewindows Client interface for a Chemical Steam Generator (CSG). The main window shows a schematic diagram of the CSG-1 system, including components like the CSA IPA System (IPA-RUNTANK), the CSG LOX System (LOX-RUNTANK), and various pipes and valves labeled with LOX, H2O, and VENT-PIPE. A 'Test of Blue Line Dialog' window is open, showing a graph for PE-14A4047-LO with a current reading of 180.534. The graph has a high limit of 500.0 and a low limit of 100.0. Below the graph is a table of events:

Event Name	Event Time
ACHIEVED	2009/08/27 11:03:20:875
NOT-ACHIEVED	2009/08/27 11:04:49:030
ACHIEVED	2009/08/27 11:04:49:905
NOT-ACHIEVED	2009/08/27 11:04:50:453
ACHIEVED	2009/08/27 11:04:50:890
NOT-ACHIEVED	2009/08/27 11:04:51:328

On the left, the 'EDS Attributes' table lists various sensor parameters:

Attribute	Value
Bridge Element Impedance (Ω)	351.3
Bridge Type	Full
Calibration Date	2008-07-31
Calibration Period	365
Calibrator's Initials	TS
Electronic Datasheet Name	Bridge Sensor
Full Scale Electrical Value Precision	mV/V
IEEE 1451.4 Template ID	33
Mapping Method	Linear
Maximum Electrical Output (V/V)	3.034
Maximum Excitation Level (V)	15
Maximum Physical Value	2000
Measurement Location ID	4101
Minimum Electrical Output (V/V)	0.031
Minimum Excitation Level (V)	10
Minimum Physical Value	0
Nominal Excitation Level (V)	10

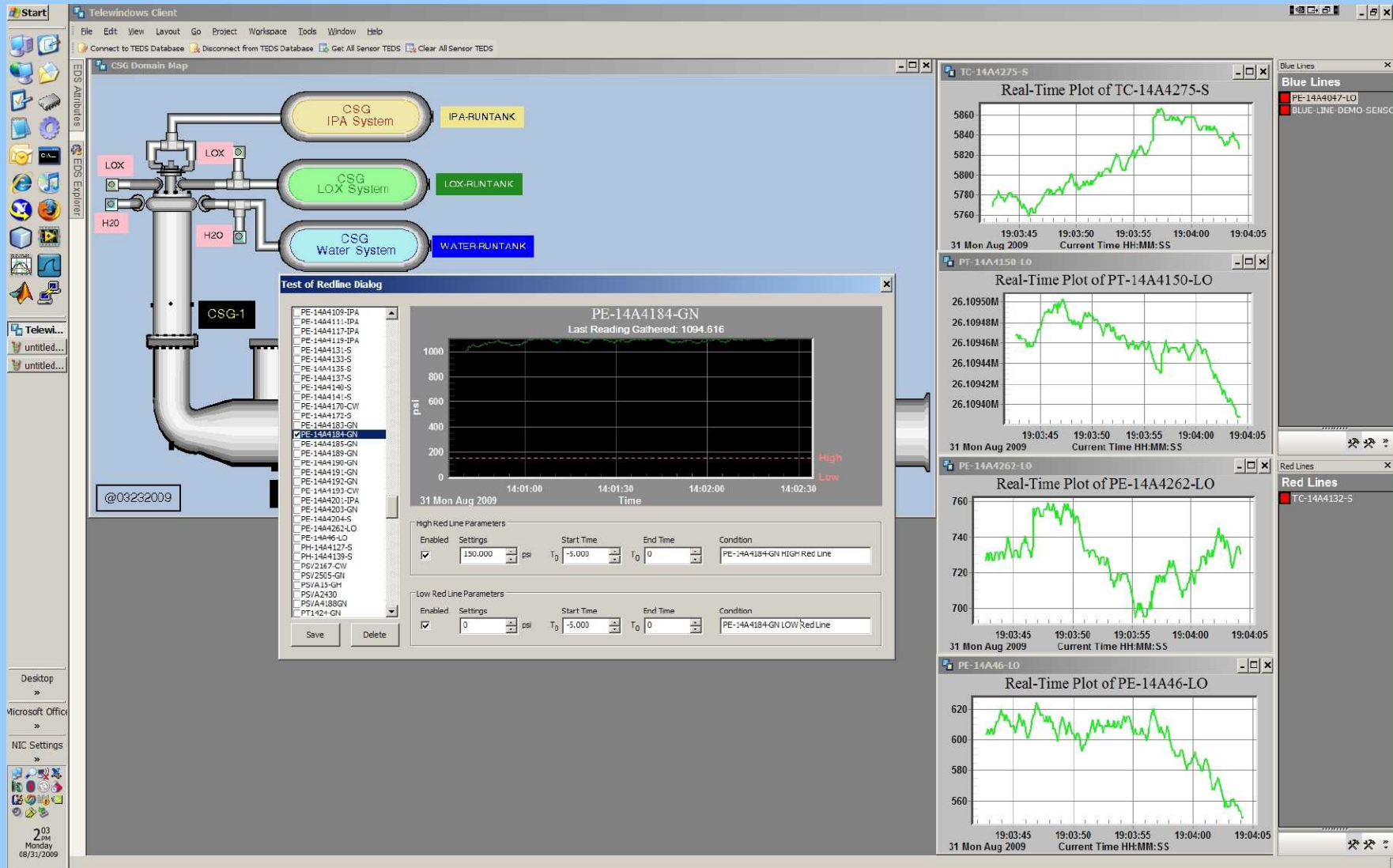
On the right, the 'Blue Lines' table shows sensor data:

Transducer	Low Limit	High Limit	Last Update Time
PE-14A4047-LO	100.0	500.0	2009/08/31 13:44:01:765
BLUE-LINE-DEMO-SENSOR	50.0	500.0	2009/08/31 13:36:53:046

Below the main window, there are sections for 'Alarms', 'Root Causes', and 'Repair Actions', each with a table for tracking these events.



Pilot ISHM Implementation Chemical Steam Generator (CSG)





Conclusions

- A sound basis to guide the community in the conception and implementation of ISHM capability in operational systems was provided.
- The concept of “ISHM Model of a System” and a related architecture defined as a unique Data, Information, and Knowledge (DIAK) architecture were described. The ISHM architecture is independent of the typical system architecture, which is based on grouping physical elements that are assembled to make up a subsystem, and subsystems combine to form systems, etc.
- It was emphasized that ISHM capability needs to be implemented first at a low functional capability level (FCL), or limited ability to detect anomalies, diagnose, determine consequences, etc. As algorithms and tools to augment or improve the FCL are identified, they should be incorporated into the system. This means that the architecture, DIAK management, and software, must be modular and standards-based, in order to enable systematic augmentation of FCL (no ad-hoc modifications).
- A set of technologies (and tools) needed to implement ISHM were described. One essential tool is a software environment to create the ISHM Model. The software environment encapsulates DIAK, and an infrastructure to focus DIAK on determining health (detect anomalies, determine causes, determine effects, and provide integrated awareness of the system to the operator). The environment includes gateways to communicate in accordance to standards, specially the IEEE 1451.1 Standard for Smart Sensors and Actuators

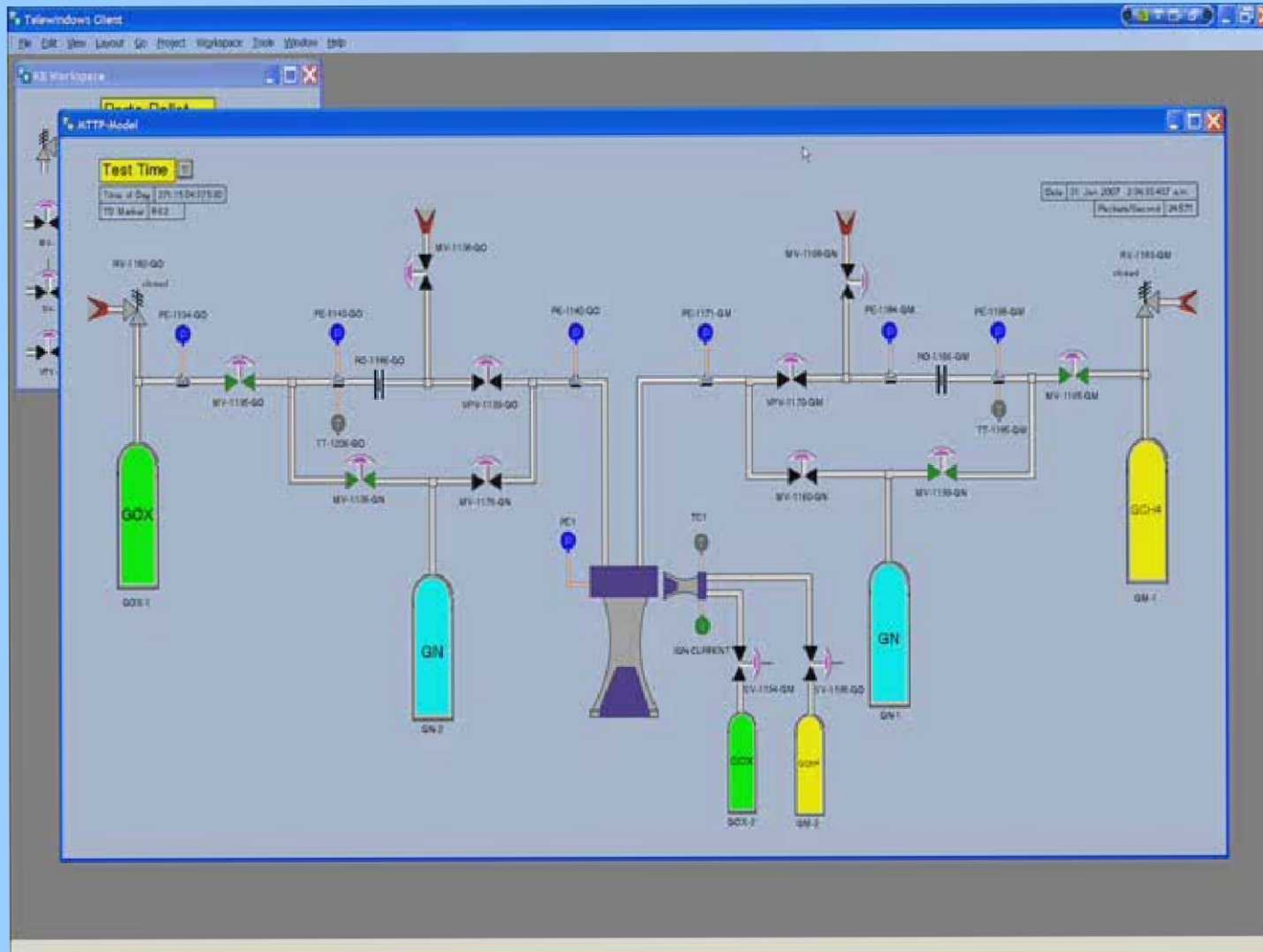


Backup Slides



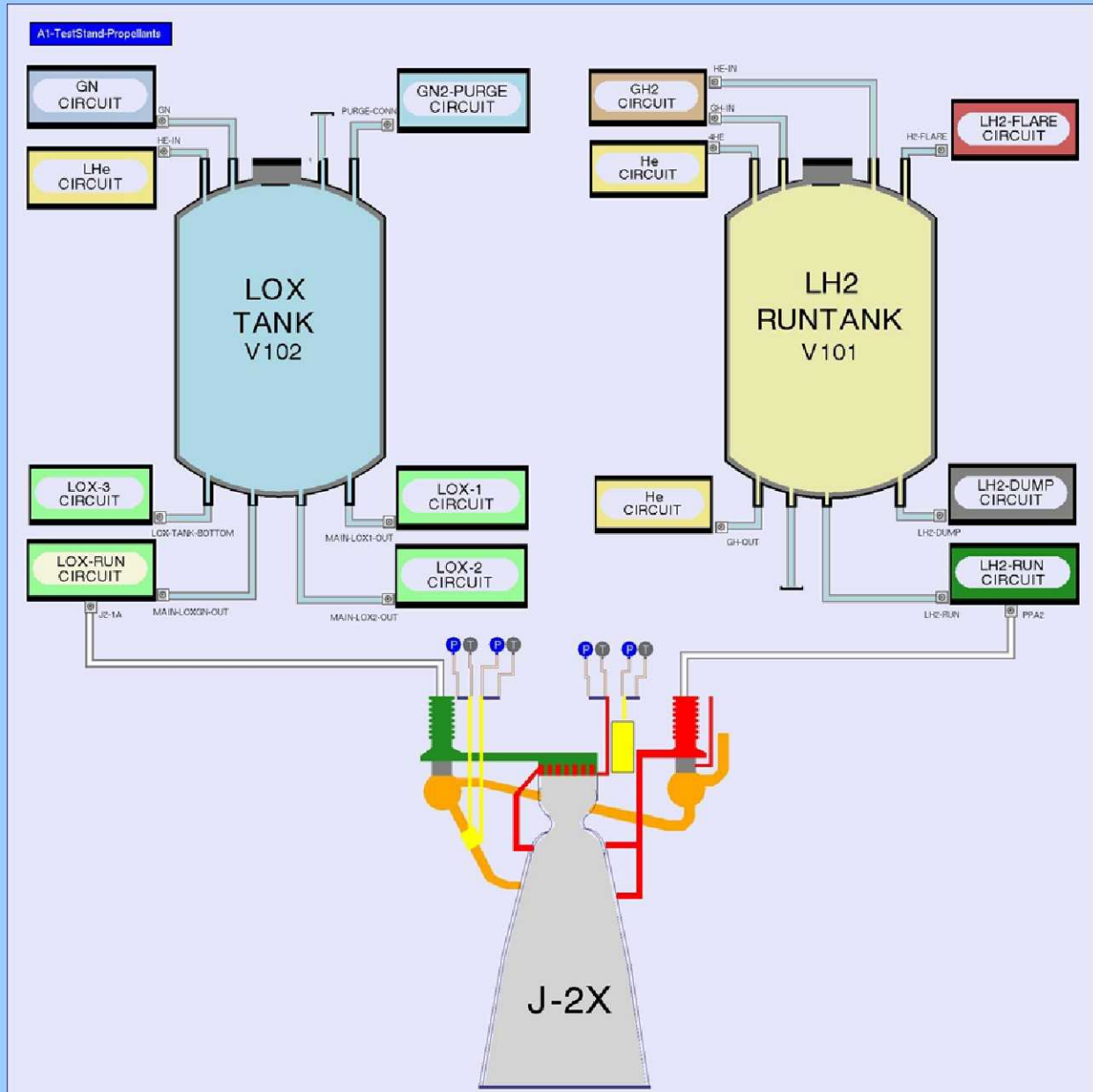
MTTP End-to-End System

Methane Thruster Testbed Project



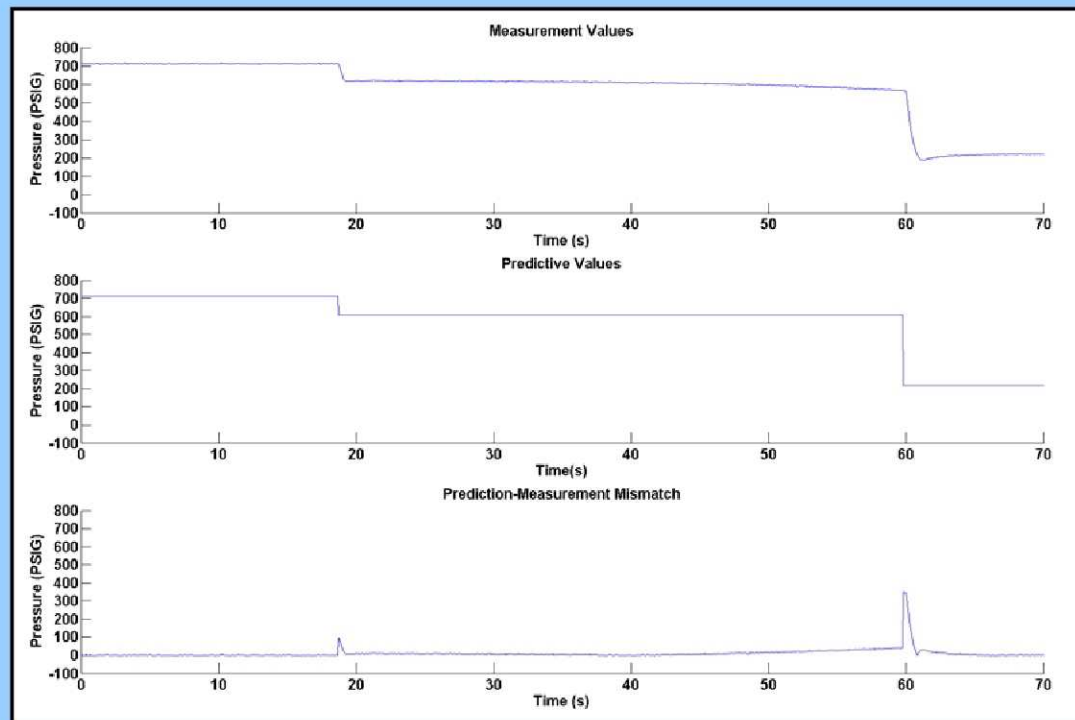
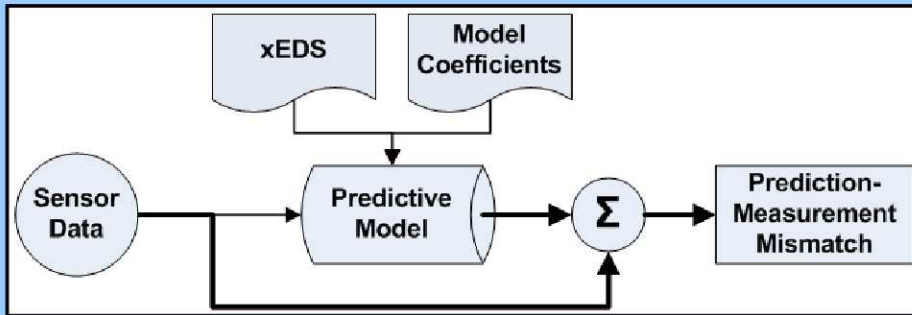


A1 and J2-X ISHM MODEL



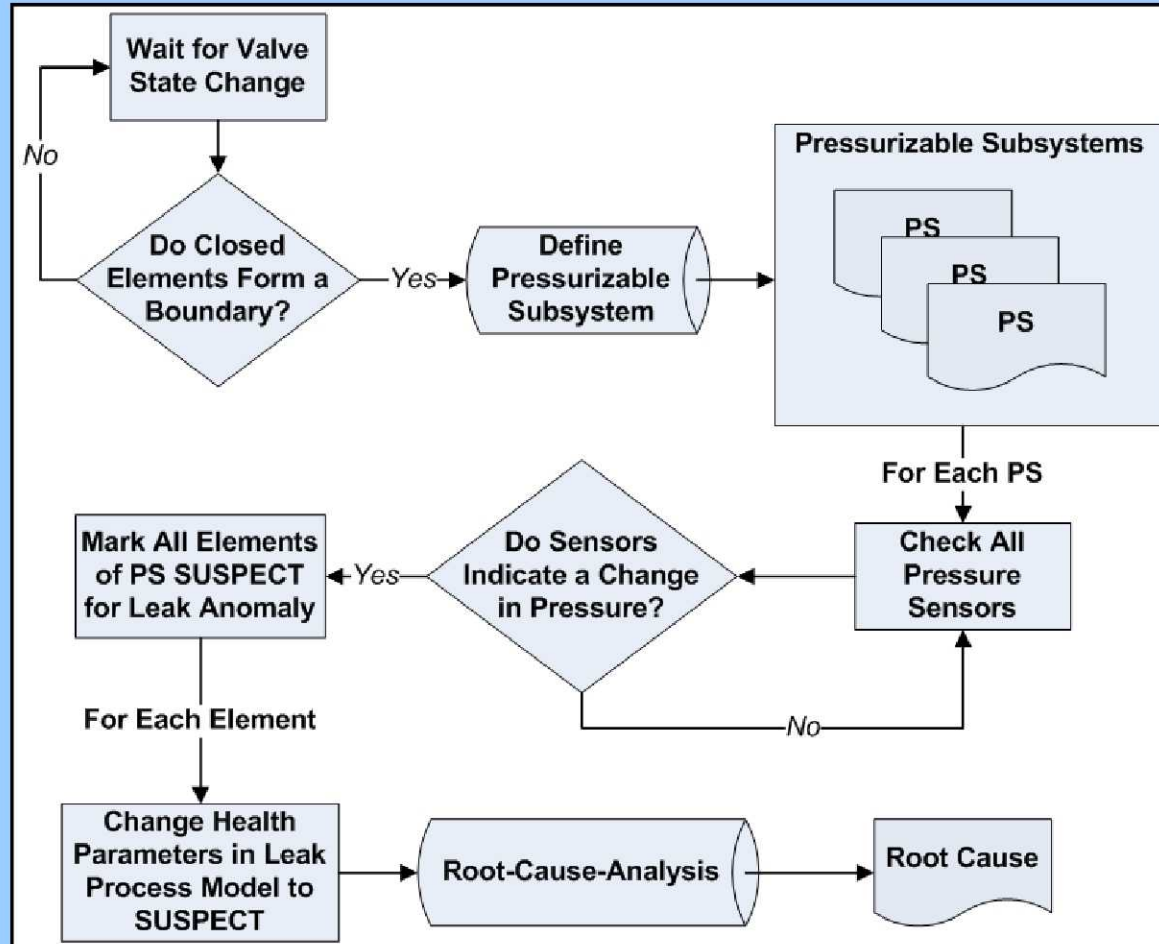


Runtime Predictive Modeling





Checking for Pressure Leaks





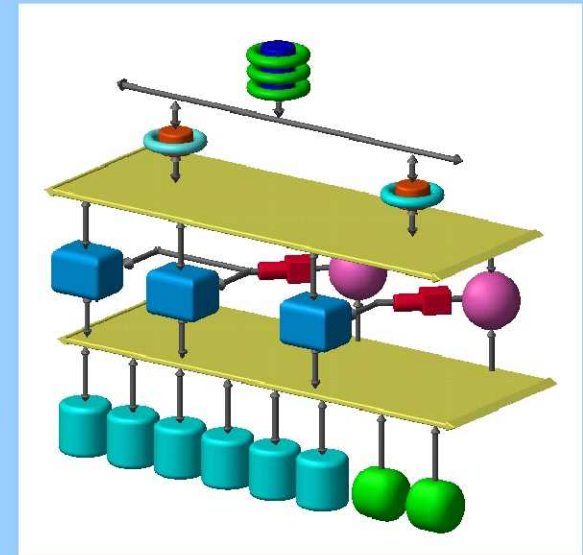
Electronic Datasheets

- **Electronic Data Sheets (EDS)**
 - **Transducer Electronic Data Sheets (TEDS)**
 - Calibration
 - **Health Electronic Data Sheet (HEDS)**
 - Codified fault conditions and system phases
 - Key detection algorithms w/ parameters
 - **Component EDS (CEDS)**
 - Manufacturing details
 - Engineering data
 - Traceability
 - **Other EDS**



Intelligent Sensors

- Smart sensor
 - NCAP (Go Active, Announce)
 - Publish data
 - Set/Get TEDS
- Intelligent sensor
 - Set/Get HEDS
 - Publish health
- Detect classes of anomalies using:
 - Using statistical measures
 - Mean
 - Standard deviation
 - RMS
 - Polynomial fits
 - Derivatives (1st, 2nd)
 - Filtering—e.g., Butterworth HP
 - FFT—e.g., 64-point
 - Algorithms for
 - Flat
 - Impulsive (“spike”) noise
 - White noise
 - Other (ANN, etc.)



Intelligent Sensors have embedded ISHM functionality and support ***Smart Sensor*** standards