Solar Power System Design for the Solar Probe+ Mission

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Solar Probe+ is an ambitious mission proposed to the solar corona, designed to make a perihelion approach of 9 solar radii from the surface of the sun. The high temperature, high solar flux environment makes this mission a significant challenge for power system design. This paper summarizes the power system conceptual design for the solar probe mission. Power supplies considered included nuclear, solar thermoelectric generation, solar dynamic generation using Stirling engines, and solar photovoltaic generation. The solar probe mission ranges from a starting distance from the sun of 1 AU, to a minimum distance of about 9.5 solar radii, or 0.044 AU, from the center of the sun. During the mission, the solar intensity ranges from one to about 510 times AM0. This requires power systems that can operate over nearly three orders of magnitude of incident intensity.

Nomenclature

Ar	=	Radiator area (m ²)
Ι	=	incident intensity (W/m ²)
Pelectric	=	power generated (W)
Rs	=	solar radius (696 000 km)
Т	=	temperature (K)
Th	=	hot-end temperature of thermal conversion system (K)
Tc	=	cold-end temperature of thermal conversion system (K)
α	=	solar absorptivity (equal to 1 minus the reflectivity)
ε _f ,ε _r	=	thermal (IR) emissivity of the front and rear surfaces
η	=	conversion efficiency
σ	=	Stefan-Boltzmann constant, $5.67 \times 10^{-8} \text{ W/m}^2\text{K}^4$

I. Background

The Solar Probe+ mission^{1,2} represents a challenging mission to send a spacecraft to explore the region close to the sun.

The proposal for a probe to fly directly into the solar corona, the source of the solar wind, was initially proposed in the mid-1970s. Earlier concepts³⁻⁸ for the mission incorporate a Jupiter flyby, to use the "gravitational slingshot" effect to cancel the Earth's orbital angular momentum, allowing the spacecraft to drop nearly directly toward the sun. This results in a mission concept which has a long flight duration before the solar encounter, and is relatively expensive, in part because of the need to incorporate a power supply which can operate both at the low intensity, low temperature environment of Jupiter orbit (about 4% of the solar intensity at Earth orbit), as well as the high intensity high temperature environment near the sun.

In 2007, NASA tasked the Applied Physics Laboratory to conduct a study to determine the feasibility of a lowercost, non-nuclear mission that would achieve the Solar Probe science objectives¹. The mission requirements imposed a significant challenge to meet the objectives: design a mission that meets difficult science objectives while mitigating the effect of the near-solar environment on spacecraft systems, develop a power system that would provide power from Earth escape through the solar encounter, and develop a low-cost spacecraft that can be achieve the required orbit using a cost-effective launch vehicle. APL partnered with Glenn Research Center to perform a

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Figure 1: Solar Probe+, a mission to explore the sun's corona. This spacecraft is designed to be operated on photovoltaic power as close as 0.042 AU from the sun. The flat solar shield protects the instrument package from the thermal environment near the sun. (Artist's conception, courtesy http://solarprobe.gsfc.nasa.gov).

trade study to develop a concept for power generation during encounter. The resulting concept was integrated into the overall APL power system design, resulting in a spacecraft able to meet the challenges of the environment.

The result is a mission called Solar Probe+, where the "Plus" represents the improvement in science objectives met by the current concept over previous concepts. The plan for the mission is to penetrate to a distance of 9.5 solar radii (i.e., 8.5 solar radii away from the surface of the sun).

Figure 1 shows an artist's conception of the design of the spacecraft. The most notable feature is the large flat solar shield, which protects the instrument package from the thermal environment near the sun.

The revised mission trajectory utilizes a Venus slingshot to bring the spacecraft in toward the sun for a first perihelion pass within four months of launch, at a perihelion distance of 0.18 Astronomical Units (AU). The primary mission will then use seven Venus flybys to decrease the perihelion, bringing its orbit incrementally closer to the sun. The mission makes a total of 24 nearsun passes over a period of 6.9 years, with a final objective of a perihelion distance of 6.6 million kilometers from the sun, significantly inside the orbit of Mercury. This will be about eight times closer than any

spacecraft has previously approached the sun.

Figure 2 shows the final orbit chosen, showing the detailed timing of the final mission encounters consisting of three passes at or within a closest approach distance of 9.5 solar radii (Rs). In this closest approach, only ten hours are spent at a distance inside of ten solar radii.

The primary features of the new orbit include:

- Multiple Venus flybys
- Fast mission, requiring only a few months to get to Venus, rather than years
- Closest approach 9.5 solar radii (0.044 AU)
- Solar intensity 510 x AM0
- Solar fly-by repeated many times

The change in orbit allows for the use of photovoltaic power generation through the solar encounter using an innovative, actively cooled solar array system. During the mission, the solar intensity varies from one to about 510 times AM0, or 700 kW/m². A significant consideration for the power system is that the power system must be able to operate over nearly three orders of magnitude of incident intensity.



Figure 2: solar probe orbit, with detail of closest approach to the sun



The most difficult criterion for the power system is the ability to operate near the sun. The equilibrium temperature of a surface illuminated by sunlight is achieved when the absorbed incident energy equals the thermally radiated infrared radiation. This can be calculated using the Stefan-Boltzmann equation:

$$\alpha \mathbf{I} = (\varepsilon_f + \varepsilon_r) \sigma \mathbf{T}^4 \tag{1}$$

where I is the incident intensity; α , the solar absorptivity (equal to 1 minus the reflectivity); ε , the thermal (IR) emissivity of the front and rear surfaces (assuming that the surface can radiate from both sides); σ , the Stefan-Boltzmann constant, and T, the temperature.

Figure 3 shows the equilibrium temperature of an uncooled flat-plate solar array, assumed to be flat on to the incident sunlight, as a function of the ratio of solar absorption to thermal emissivity (epsilon). As can be seen, even for unrealistically low values of the α/ϵ ratio, the equilibrium temperature becomes extremely hot at heliocentric distances inside of Mercury's orbit.



Figure 3: Temperature as a function of distance from the sun, for various values of a/e ratio.

Solar cells decrease in performance as the temperature increases¹⁰, and are also subject to irreversible degradation leading to eventual failure under exposure to temperatures of roughly 350°C and above. While some research has been done on design of solar cells capable of higher temperature operation¹¹⁻¹³, no existing solar array technologies are designed for operation at high temperature.

II. MESSENGER Array: an Approach to Solar Arrays for a Near Sun Mission

Approaches to solar arrays for near-sun missions include modifying any of the terms governing temperature or efficiency of the cell: the incident intensity, solar absorption, emissivity of the surface; or the temperature coefficient of the cells.

As an example of a mission with solar panels designed to operate at high solar flux using the technique of limiting the incident flux to the array and modifying solar absorption α , the "MESSENGER" mission to orbit Mercury¹⁴ has designed an array with mirrored optical surface reflectors covering replacing approximately 70% of the solar cells across the surface area of the array¹⁵. These panels reflect 70% of the incident solar energy, and hence reduce the operating temperature. The mirrors incorporate a high-emissivity silica coating, allowing efficient thermal radiation. These panels have operated (at the first Mercury fly-by) at distance of 0.4 AU from the sun¹⁵, and have been qualified in thermal vacuum testing to be capable of operating as close as 0.25 AU from the sun, at an intensity of 16 times the intensity at Earth orbit¹⁶.

The arrays use off-pointing to reduce the incident intensity at Mercury; however, the arrays were designed to tolerate the full on-sun thermal regime, in the case of a pointing failure.

This array has now successfully demonstrated operation at the nearest approach to the sun of any solar-powered mission. The solar array design used for the ESA "Venus Express" mission and the array being developed for the upcoming Bepi-Columbo Mercury orbiter both used a similar approach to thermal control.

III. Solar Probe +

The Solar Probe Plus mission design incorporates several of the methods of decreasing sensitivity to multiple intensities. The minimum power requirement for the mission is 482 Watts.

To deal with the wide variation in solar intensity between the initial operation of the spacecraft at Earth orbital distance and the closest approach, the power system design utilizes two primary power supplies. A conventional solar array is used for the portion of the trajectory from Earth to approx. 0.25 AU, where the intensity reaches 16 times the one-sun intensity. As the spacecraft approaches closer to the sun than 0.25 AU, these arrays then stow behind the shadow shield to avoid excess thermal exposure. At this distance and inward, a secondary high-flux solar array takes over as primary power source, and is used for the near-sun portion of the mission.

A. Conventional Solar Array

The main array is used from Earth to slightly inside the Mercury orbit. The array uses the MESSENGER design, described above, incorporating optical surface reflectors into the array to reduce the temperature. Since the MESSENGER array has already demonstrated in flight¹⁴ and is qualified for distances as low as 0.25 AU¹⁶, no technology or materials development is needed for the array.

The Solar Probe + primary array design uses two photovoltaic wings, each with a total area of 1.5 m^2 . The array can be off-pointed from the sun to allow operation in to approximately 0.25 AU, an intensity of 16 suns. At this distance the main solar array is folded in behind the shadow shield, where it is not exposed to high temperatures, and the secondary power supply is used.

For this array, the lowest power occurs at the farthest distance from the sun, 1 AU, and hence the array is sized to produce the minimum required mission power of 482 W at this condition. The panel incorporates 32 strings of 39 triple-junction cells. The photovoltaic cell technology baselined is the commercially-available^{17,18} space-qualified triple-junction cell technology, incorporating GaInP₂, GaAs, and Ge cells which respectively utilize the ultraviolet and blue portion, visible and near IR, and IR portions solar spectrum. The array will incorporate mirrors (optical surface reflectors) at a packing density of 2 reflectors for each cell

As Solar Probe+ approaches the Sun, the array will be tilted up to $\sim 74^{\circ}$ off the Sun to limit the incident solar flux and maintain the array within thermal limits of under 180° C.

Figure 5 shows the spacecraft with the primary solar arrays deployed.



Figure 4: Solar Probe + shown with primary array deployed, showing the spacecraft from the front perspective view (left) and rear (right).

B. High Intensity Conversion System Design Study

1. Background

Close to the sun, the main part of the spacecraft as well as the primary solar array is shadowed behind the heat shield. The solar power source needed to operate in this regime must operate at intensity from 16 to 510 times AM0 $(\sim 700 \text{ kW/m}^2)$, a factor of 32.

As a mission approaches close to the sun, the temperature of a flat-plate exposed to the sun increases. This presents the option of a possible design alternative of converting this heat, using a heat engine, rather than using photovoltaic arrays. Thermal power conversion is a demonstrated technology, and there exists a choice of conversion technologies, including thermoelectric conversion, a technology with comparatively low efficiency, but high spaceflight heritage, or Stirling conversion, which has the advantage of higher efficiency but no spaceflight heritage.

2. Analysis of Thermal Conversion

Since a heat engine runs off a temperature differential between hot and cold sides, any thermal conversion system must require a radiator to provide the low temperature "cold side" of the system, which must be not exposed to the sun, either in the shadow of an absorber or the thermal shield, or else edge-on to the incident flux. The radiator must be sized to radiate the waste energy at the cold-side temperature.

The radiator design can dominate the size and mass of the conversion system, and hence analysis of the radiator size is key to the mission design. Figure 5 shows the block diagram of the energy flow in such a thermal system. Since the power produced is proportional to the conversion efficiency η , and the radiator area proportional to the waste power radiated, which is proportional to $(1-\eta)$, the radiator area A_r depends sensitively on the conversion efficiency and the radiator temperature

$$A_{\rm r} = [(1-\eta)/(\eta)]/(\varepsilon\sigma T^4)$$
⁽²⁾

Emissivity ε for thermal radiators is typically very close to 1. If the radiator is two-sided, the area A includes both front and rear sides.

Both thermoelectric conversion and Stirling-cycle heat engines were analyzed. The thermoelectric converters, although well demonstrated in space, had too low efficiency to be viable for the mission.



Stirling converters for the Advanced Radioisotope Power Source have demonstrated 38 percent conversion efficiency^{19,20} operating at 850°C hot-end temperature (Th) and a 90°C cold-end temperatures (Tc). This is slightly over 50% of the theoretical (Carnot) efficiency. Overall system efficiency, accounting for other losses, is on the order of 26%. These efficiency numbers are roughly comparable to the best photovoltaic technologies. The efficiency scales with temperature as the Carnot efficiency, directly proportional to the difference between the hot- and cold-end temperature, and hence the conversion efficiency increases as the radiator size increases.

The requirement that the thermal system chosen varying hot-end temperatures, represents an engineering challenge for many missions. As can be

seen from figure 2, the Solar Probe is only at close approach to the sun for a duration on the order of 10 hours. Over the distance range of operation, the equilibrium temperature of the hot side of the system will vary by factor of $32^{1/4}$ = 2.4. This range of variation is outside of the normal operational bounds of typical thermal conversion systems, which typically operate at a fixed, or nearly fixed, hot-end temperature. Qualifying a conversion system to operate over this thermal input range would require some design effort.

3. High-intensity solar array: Photovoltaic array

In the photovoltaic design option, a similar radiator is used to cool the photovoltaic array, keeping the array temperature within the standard operating temperature range. Equation (2) for radiator size can be used for this design as well, where the thermal radiator is used to cool a solar array instead of a heat engine.

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Figure 6: Solar Probe+ conceptual design, showing the primary solar arrays retracted behind the heat shield.

Thermal/Stirling conversion:

- · ASRG converter has been demonstrated in ground testing
- Not yet demonstrated in space
- Hot-side Temp (.25 AU, coldest case) ~788 K
- 36% efficiency requires cold side at 315K
- Efficiency reduced to 28% at cold side of 420K
- Assumes hot-side temperature not drawn down by power system
- No significant advantage from spectral selective coatings
- · Operation over high dynamic range of input temperature is not yet demonstrated

Photovoltaic conversion:

- Thermal radiator required to keep cell temperature < 120°C (393K)
- Commercially available technology: baseline concentrator cell efficiency 35% at AM1.5
- extrapolates to 28% AM0 efficiency at 120°C operating temp
- Radiator size can be decreased if spectral selective coatings are added

Overall, the two systems were roughly comparable in temperature, efficiency and radiator area. However, the photovoltaic option used technology that was more similar to technology that has been flown in space. Furthermore, the mission trajectory requires a very high launch energy (C3). This means that the mission is highly mass constrained, and hence the power supply must be as low in mass as possible. The baseline calculations showed a lower mass for the photovoltaic power system compared to the thermal conversion system.

The thermal conversion option also requires a system that operates at peak efficiency over a wide range of temperatures. While this does not present fundamental barrier to operation, it is a regime that has not been previously developed, and would require some amount of technology development and validation.

For all of these reasons, the photovoltaic power system was chosen as both the lower mass, and also the lower risk option.

C. High Flux Solar Array Design

1. Photovoltaic Cells

The design chosen for the secondary high-flux power supply uses high-efficiency triple-junction solar cells designed for high solar concentrations. The design uses two identical high-flux arrays, one located on either side of the spacecraft.

The photovoltaic cells selected for this application are commercially-available concentrator solar cells^{21,22}. Although these cell designs are designed for terrestrial concentrator application, not for space applications, the cell technology is identical to the space cell technology^{17,18}, with the exception that the metallization used for ohmic

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In the design chosen, the secondary solar array will use concentrator solar cells cooled by pumped liquid coolant circulating to radiator. The pumped cooling loop keeps maximum temperature to below 120°C, the maximum limit allowable by the solar cell design chosen without further qualification testing.

As with the thermal system, the photovoltaic system must also be designed for a wide range of input intensities.

4. Photovoltaic versus Thermal Conversion Trade-off

The following considerations were taken into account in calculating the trade-off between thermal and photovoltaic conversion: contact to the cell is designed for a higher input solar flux. Since the underlying materials technology is identical to already-qualified space cells, space qualification was not considered to be an issue.

Each panel has 25 parallel strings of liquid-cooled solar cells, with approximately 1 cm^2 active area per cell. Each series-connected string incorporates 27 cells and an isolation diode.

The performance specifications for these cells can be obtained from the vendors as a function of both the concentration and the temperature. These specifications are nominally referenced to the terrestrial (Air-mass 1.5 Direct, 850 W/m²) solar spectrum. Because of the spectral difference between this and the space (Air-mass 0, 1367 W/m^2) spectrum, the efficiency achieved under space conditions must be slightly recalculated, and is slightly lower than the terrestrial value. Likewise, since the space one-sun intensity is slightly higher than terrestrial one-sun intensity, the effective solar concentration in space conditions must be modified from that of the design specifications. For the assumed operating conditions, the baseline cell conversion efficiency extrapolated to about 28% under space conditions, at the maximum operating temperature.

The area of the thermal radiator is minimized by operating the solar cells at the highest temperature. The vendor-specified maximum operating temperature for these cells was 120°C. Although some tests suggest that higher operating temperatures may be possible, a design-maximum temperature of 120°C was chosen for the analysis.

Spectrally selective coating designed to reflect the wavelengths of light to which the cells are unresponsive, or have low response, could be used to reduce the temperature of the cells, and hence reduce the amount of waste heat that must be radiated to space by the thermal radiators. Although this approach may be feasible, it was not assumed for the baseline design.

2. Design for Variable Incident Intensity

In order to keep the solar cells within the nominal temperature limits, a liquid cooling loop pumps coolant from the cell mounting through thermal radiators mounted on the outside of the spacecraft. The assumed temperature drop across the coolant loop was 20°. Since the cell maximum temperature is 120°C, the radiators must be sized to reject heat at 100°C (373 °K). Each of the two arrays is connected to three thermal radiators, which are located behind the heat shield, and out of the direct solar illumination. Figure 8 shows the solar array substrate and the three



Figure 7: Secondary high-flux solar-array substrate and thermal radiators (labeled). A second solar array, not shown, is located on the opposite side of the spacecraft.

thermal radiators. Since the rear side of each radiator is directed toward the spacecraft, heat rejection is by radiation from the front side of the radiator panels only, which are aimed toward space.

The fully-illuminated array is sized to produce 482 W at the farthest operating distance of 0.25AU. The main size (cost) driver is the cooling radiators. If the array area exposed to sunlight were constant, the radiators required to keep the cells cool at perihelion intensity of 510 suns would be significantly oversized at the farthest distance, receiving only 16 suns intensity. Likewise, the array which is sized to produce full power at 0.25AU would be significantly oversized at the 32 times higher illumination intensity of perihelion.

To reduce the required radiator size, the illuminated area of the solar cells is reduced as the spacecraft moves from 0.25 AU to perihelion. The secondary solar array is progressively retracted behind the solar shield as it approaches the sun, in order to keep the total incident power level on the array (and hence the heat load to the radiators) approximately constant.

At closest approach (9.5 Rs), the secondary array panels require a total equivalent cell area of only 34 cm². Several different mechanisms for retracting the array were analyzed. The mechanism finally adopted involved sliding the solar array linearly back behind a knife-edge shadow-shield affixed to the edge of the main solar heatshield. This is shown in Figure 8.

The concentrator solar cells in the secondary array are arranged in 27 linear strings, oriented parallel to the knifeedge of the shadow shield. As the solar array retracts behind the shadow shield, the number of strings exposed to solar illumination decreases, until at the closest approach, only the single outermost string is partially illuminated.

Figure 9 shows the secondary array, the associated radiators and coolant pumps, and the structure as they would be viewed with the heat shield removed. Figure 10 shows spacecraft with the relative sizes of the primary and secondary array.



Figure 8: Second solar array, shown in the deployed (left) and retracted (right) configurations.



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Figure 10: Front view of the final Solar Probe design, viewed from the front (heat-shield) side. Shown to scale with both solar arrays deployed, showing relative sizes of the two arrays.

IV. Conclusion

Solar Probe is a challenging mission for a solar powered system. The closest approach of 9.5 solar radii is eight times closer to the sun that any spacecraft has ever approached the sun. The solar intensity at closest approach is 510 times AM0

A photovoltaic power supply was designed for the Solar Probe Plus mission, using an innovative approach using pumped cooling loop and a two-power supply solution.

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