



GFSSP Training Course Lectures

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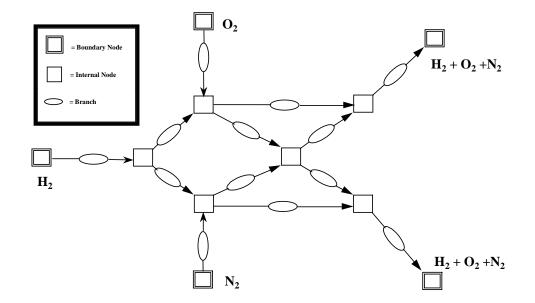
Thermal & Fluids Analysis Workshop

NASA/Ames Research Center & San Jose University August 18-22, 2008



INTRODUCTION & OVERVIEW





Marshall Space Flight Center GFSSP Training Course





CONTENT

- Introduction
 - Background
 - Course Outline
- Overview
 - Network Flow or Navier Stokes Analysis
 - Network Definition
 - Data Structure
 - Mathematical Formulation
 - Program Structure
 - Graphical User Interface
 - Resistance & Fluid Options
 - Advanced Options
 - Applications







BACKGROUND -1

- GFSSP stands for <u>Generalized Fluid System Simulation</u> <u>Program</u>
- It is a general-purpose computer program to compute pressure, temperature and flow distribution in flow network
- It was primarily developed to analyze
 - Internal Flow Analysis of Turbopump
 - Transient Flow Analysis of Propulsion System
- GFSSP development started in 1994 with an objective to provide a generalized and easy to use flow analysis tool







BACKGROUND -2

DEVELOPMENT HISTORY

- Version 1.4 (Steady State) was released in 1996
- Version 2.01 (Thermodynamic Transient) was released in 1998
- Version 3.0 (User Subroutine) was released in 1999
- Graphical User Interface, VTASC was developed in 2000
- Selected for NASA Software of the Year Award in 2001
- Version 4.0 (Fluid Transient and post-processing capability) is released in 2003





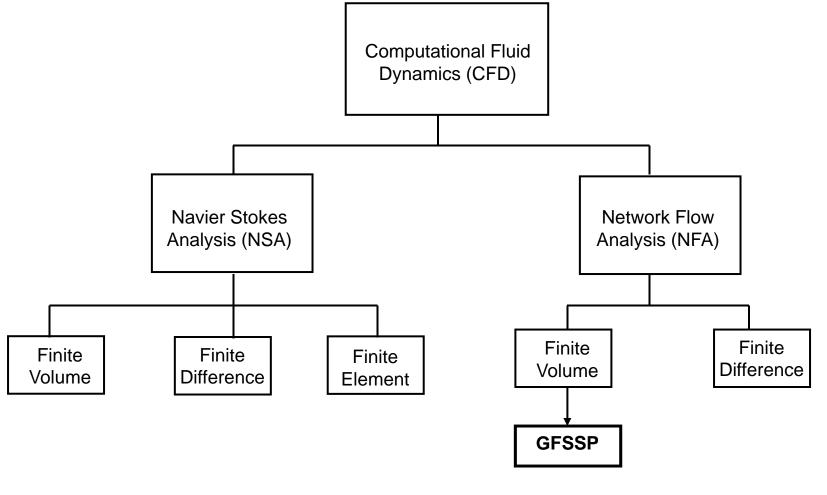


COURSE OUTLINE

- 1. Introduction & Overview
- 2. Graphical User Interface
- 3. Mathematical Formulation
- 4. User Subroutine
- 5. Pressurization, Waterhammer & Conjugate Heat Transfer
- 6. Tutorials (Afternoon)



NETWORK FLOW OR NAVIER STOKES ANALYSIS - 1







NETWORK FLOW OR NAVIER STOKES ANALYSIS - 2

Navier Stokes Analysis

- Suitable for detailed flow analysis within a component
- Requires fine grid resolution to accurately model transport processes
- Used after after preliminary design

Network Flow Analysis

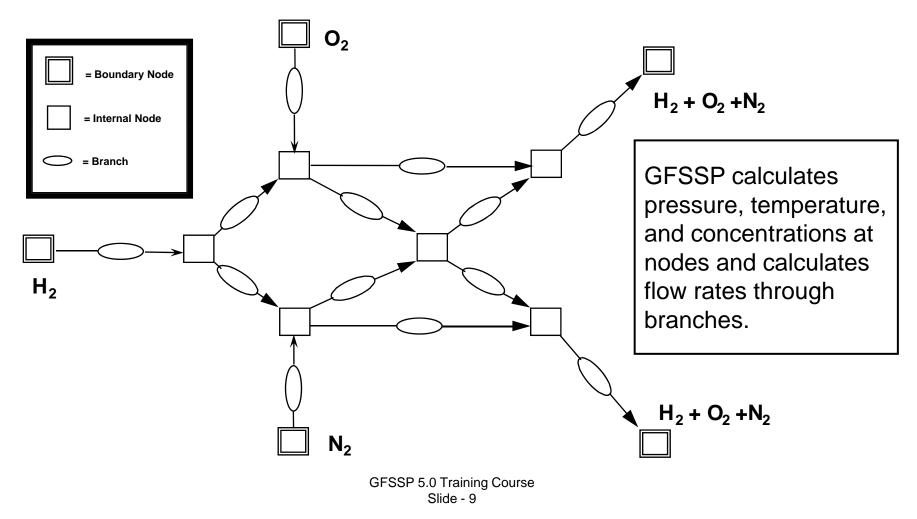
- Suitable for flow analysis of a system consisting of several components
- Uses empirical laws of transport process
- Used during preliminary design

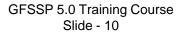




NETWORK DEFINITION – 1

GFSSP FLOW CIRCUIT





At internal nodes, all dependent variables must be guessed for steady flow and specified for transient

NETWORK DEFINITIONS - 2

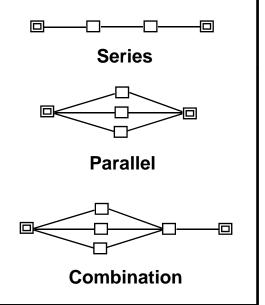
- At boundary nodes, all dependent ۲ variables must be specified
- Internal node П —□— Branch

flow.

- **Boundary node**

- **Network:**





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NETWORK DEFINITIONS - 3

UNITS AND SIGN CONVENTIONS

- Units
 - Length
 - Area
 - Pressure
 - Temperature
 - Mass injection Ibm/sec Ibm/sec
 - Heat Source

- External (input/output) Internal (inside GFSSP)
- inches
- inches²
- psia
- °F

- Btu/s OR Btu/lbm- Btu/s OR Btu/lbm
- Sign Convention
 - Mass input to node = positive
 - Mass output from node = negative
 - Heat input to node = positive
 - Heat output from node = negative

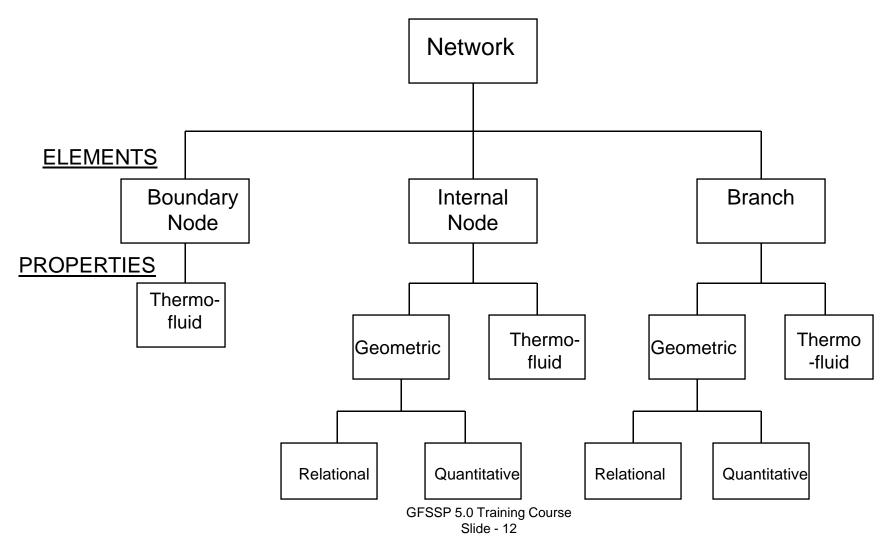


- feet
 - feet² - psf
 - °R





DATA STRUCTURE









MATHEMATICAL FORMULATION - 1 MATHEMATICAL CLOSURE - 1

Principal Variables:

Unknown Variables	Available Equations to Solve
1. Pressure	1. Mass Conservation Equation
2. Flowrate	2. Momentum Conservation Equation
3. Temperature	3. Energy Conservation Equation (First or Second Law of Thermodynamics)
4. Specie Concentrations	4. Conservation Equations for Mass Fraction of Species
5. Mass	5. Thermodynamic Equation of State





MATHEMATICAL FORMULATION - 2

MATHEMATICAL CLOSURE -2

Auxiliary Variables:

Thermodynamic Properties & Flow Resistance Factor

Unknown Variables Available Equations to Solve

Density Specific Heats Viscosity Thermal Conductivity Flow Resistance Factor

Equilibrium Thermodynamic Relations [GASP, WASP & GASPAK Property Programs] Empirical Relations



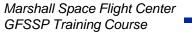


MATHEMATICAL FORMULATION - 3

BOUNDARY CONDITIONS

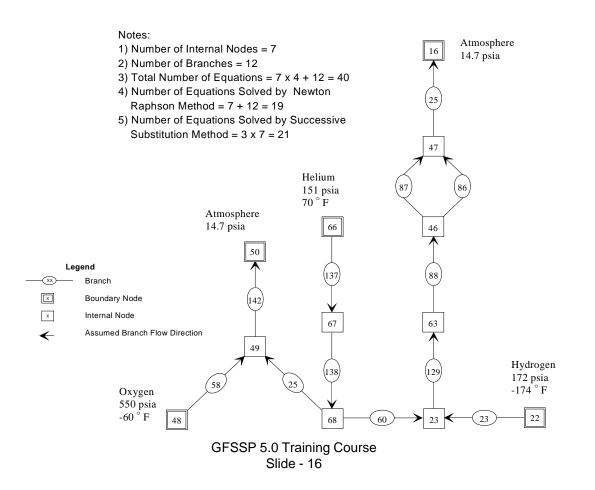
- Governing equations can generate an infinite number of solutions
- A unique solution is obtained with a given set of boundary conditions
- User provides the boundary conditions





MATHEMATICAL FORMULATION - 3

A TYPICAL FLOW CIRCUIT



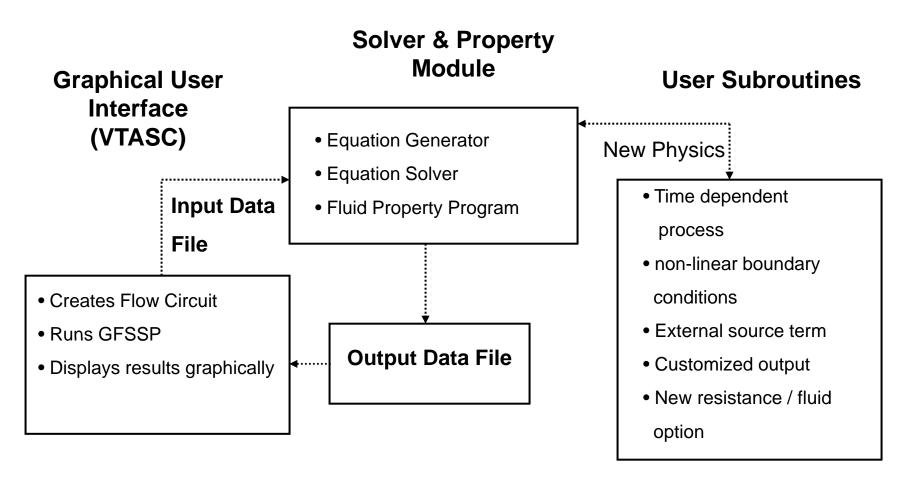








PROGRAM STRUCTURE

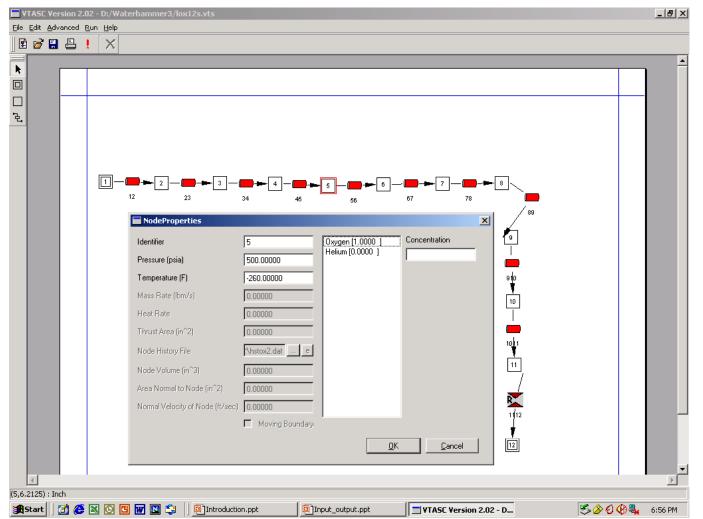






GRAPHICAL USER INTERFACE - 1

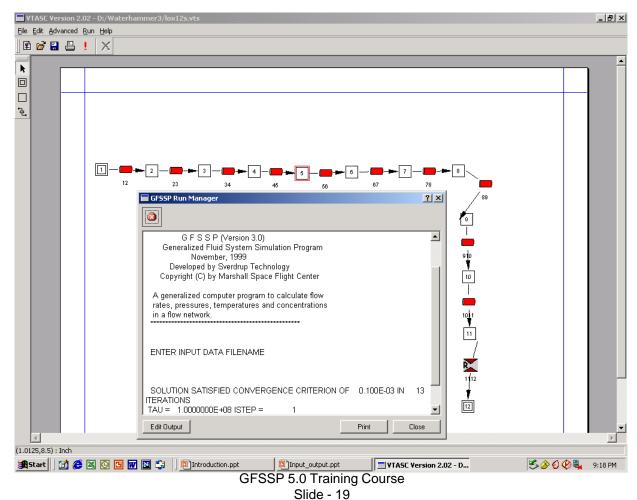








GRAPHICAL USER INTERFACE - 2 MODEL RUNNING

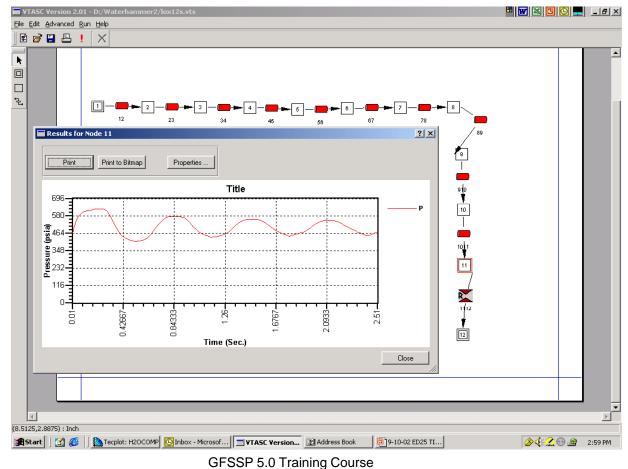




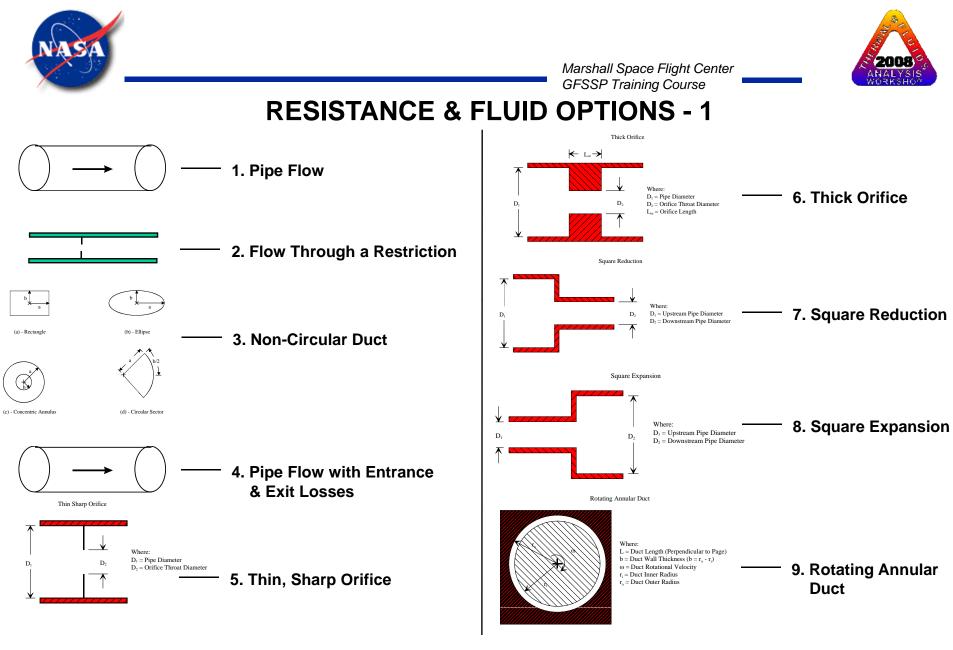


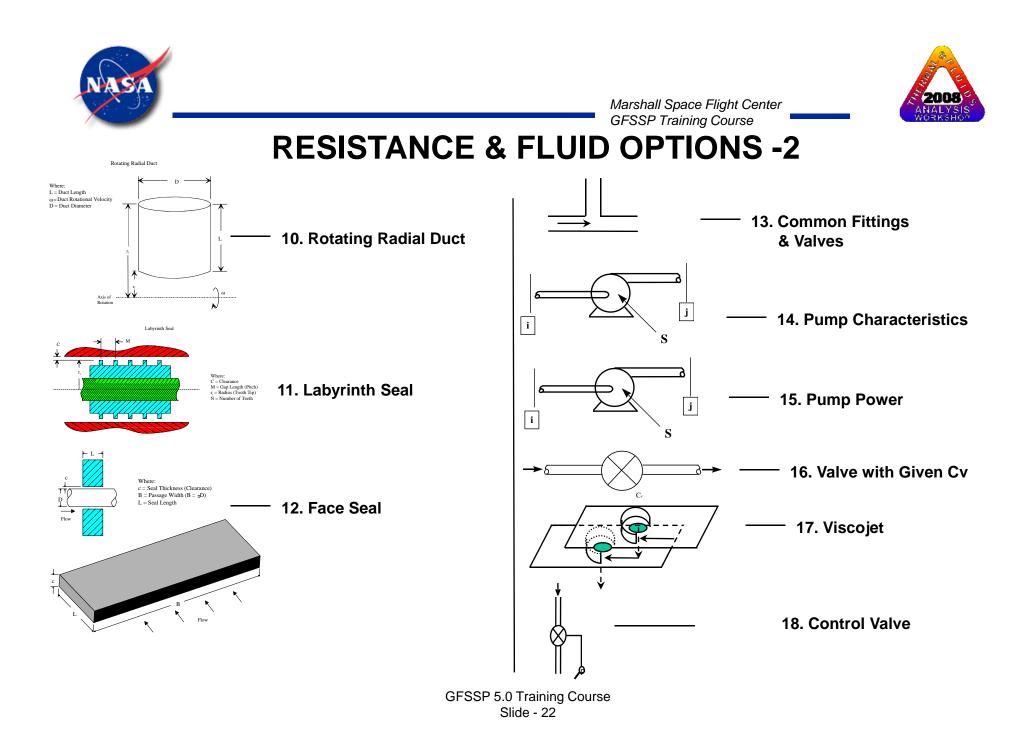
GRAPHICAL USER INTERFACE - 3

MODEL RESULTS



Slide - 20









RESISTANCE & FLUID OPTIONS - 3

GASP & WASP

Index	Fluid	Index	Fluid	
1	HELIUM	7	ARGON	
2	METHANE	8	CARBON DIOXIDE	
3	NEON	9	FLUORINE	
4	NITROGEN	10	HYDROGEN	
5	CARBON MONOXIDE	11	WATER	
6	OXYGEN	12	RP-1	
GFSSP 5.0 Training Course				





RESISTANCE & FLUID OPTIONS - 4

GASPAK

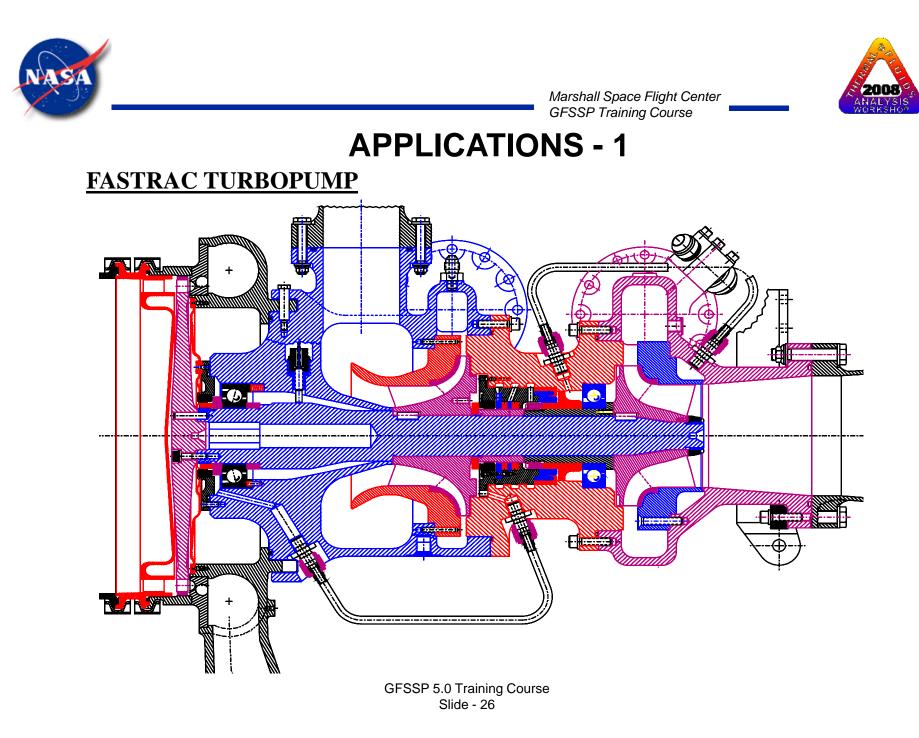
Index	Fluid	Index	Fluid
1	HELIUM	18	HYDROGEN SULFIDE
2	METHANE	19	KRYPTON
3	NEON	20	PROPANE
4	NITROGEN	21	XENON
5	CO	22	R-11
6	OXYGEN	23	R12
7	ARGON	24	R22
8	CO ₂	25	R32
9	PARAHYDROGEN	26	R123
10	HYDROGEN	27	R124
11	WATER	28	R125
12	RP-1	29	R134A
13	ISOBUTANE	30	R152A
14	BUTANE	31	NITROGEN TRIFLUORIDE
15	DEUTERIUM	32	AMMONIA
16	ETHANE	33	IDEAL GAS
17	ETHYLENE	34	AIR
		35	HYDROGEN PEROXIDE





ADDITIONAL OPTIONS

- Variable Geometry Option
- Variable Rotation Option
- Variable Heat Addition Option
- Turbopump Option
- Heat Exchanger
- Tank Pressurization
- Control Valve

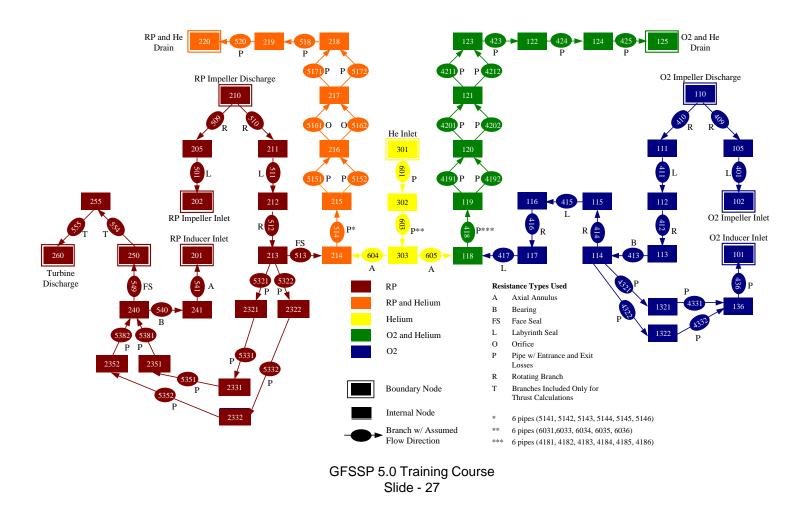








GFSSP Model of the Fastrac Turbopump









Turbopump Test to 20000 RPM with Gas Generator



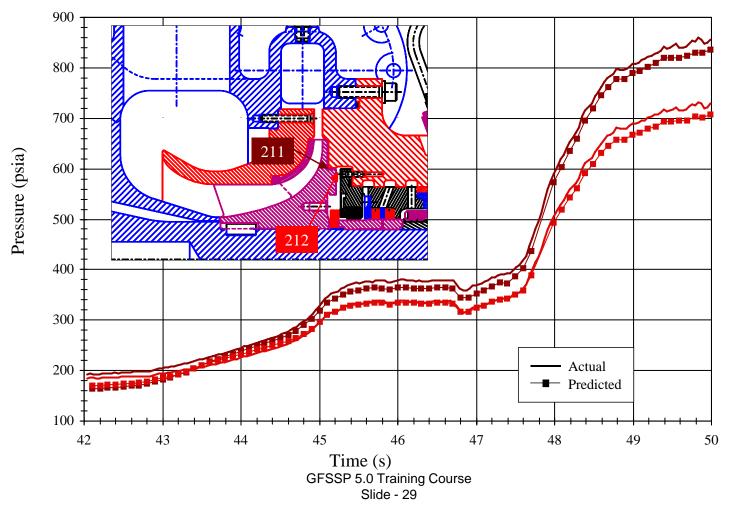




APPLICATIONS - 4

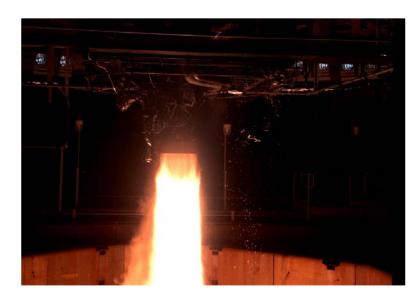
Fastrac Turbopump Model Results

Pressure history comparison at RP-1 Impeller back face [Labyrinth seal inlet (211) and outlet (212)]











LOX Tank

2008

RP-1 Tank

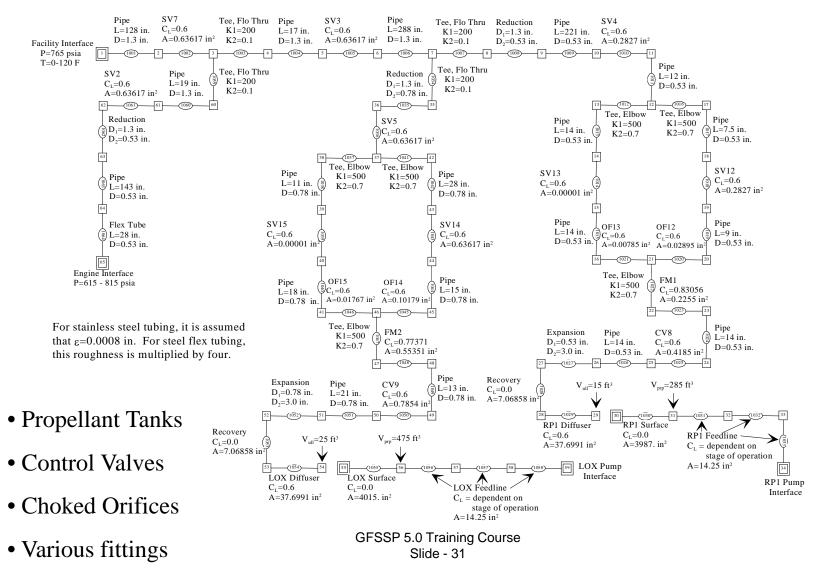
Engine Interface



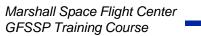


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GFSSP Model of PTA Helium Pressurization System

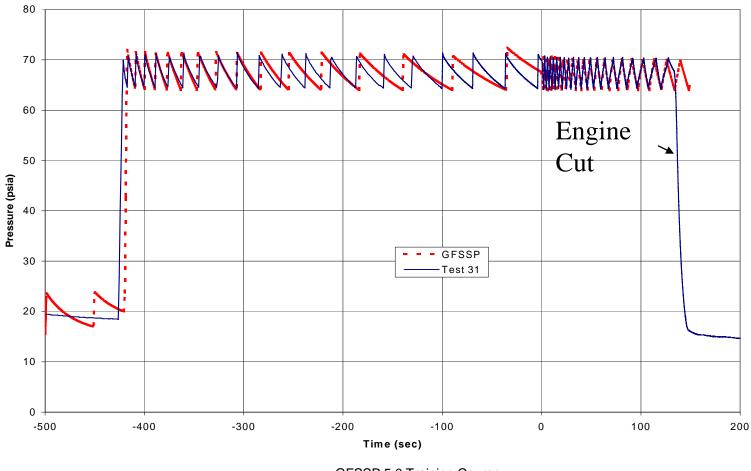




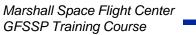




Comparison of LOX Ullage Pressure with Test Data

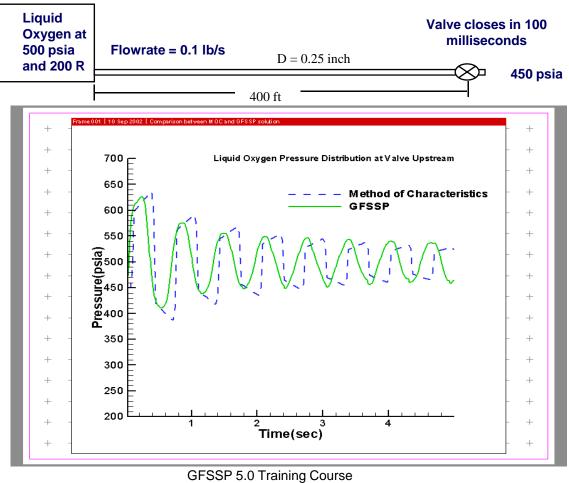








Verification of Fluid Transient Computation

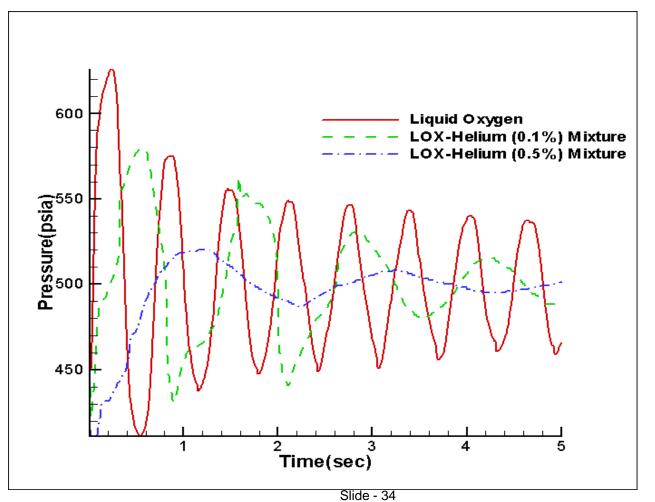








Fluid Transient in Two phase flow

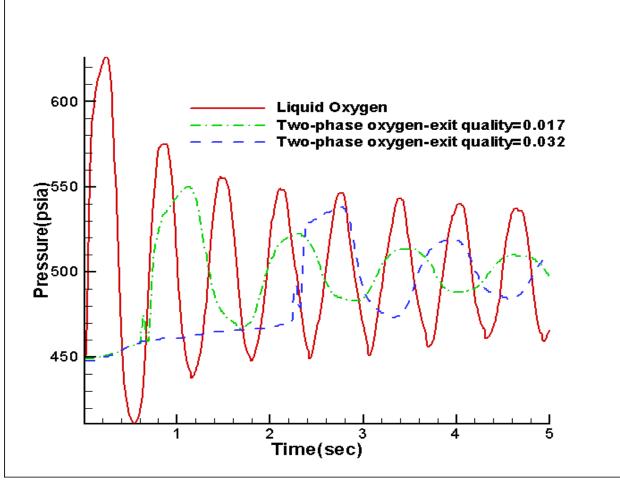






APPLICATIONS - 10

Predicted Fluid Transient Due to Condensation



GFSSP 5.0 Training Course Slide - 35







SUMMARY - 1

- GFSSP is a finite volume based Network Flow Analyzer
- Flow circuit is resolved into a network consisting of nodes and branches
- Mass, energy and specie conservation are solved at internal nodes. Momentum conservation is solved at branch
- Generalized data structure allows generation of all types of flow network
- Modular code structure allows to add new capabilities with ease





SUMMARY – 2

- Unique mathematical formulation allows effective coupling of thermodynamics and fluid mechanics
- Numerical scheme is robust; adjustment of numerical control parameters is seldom necessary
- Intuitive Graphical User Interface makes it easy to build, run and evaluate numerical models
- GFSSP has been successfully applied in various applications that included
 - Incompressible & Compressible flows
 - Phase change (Boiling & Condensation)
 - Fluid Mixture
 - Thermodynamic transient (Pressurization & Blowdown)
 - Fluid Transient (Waterhammer)
 - Conjugate Heat Transfer

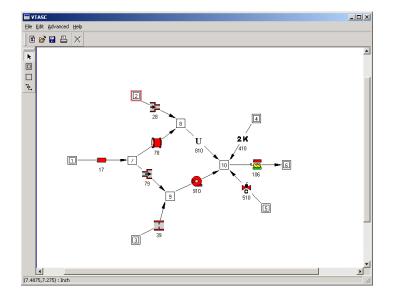




SUMMARY – 3

- GFSSP is available from NASA/MSFC's Technology Transfer Office for US Government agencies and contractors
- An Audio-Video Training Course is also available
- More information about the code and its methodology is available at http://mi.msfc.nasa.gov/GFSSP/index.shtml









BACKGROUND -1

Visual Thermo-fluid dynamic Analyzer for Systems and Components (VTASC) is a program designed to efficiently build flow network models for use in the GFSSP program.

- Visually Interactive
 - Eliminates pre-design of models
 - Immediate feedback on model
- Self-Documenting
 - Hard copy of flow network
 - Bitmap image of flow network for inclusion into papers and presentations





BACKGROUND -2

- Eliminates errors during model building process
 - Automatic node and branch numbering
 - Save and restore models at any point in the model building process
 - Robust
- Pushbutton generation of GFSSP input file
 - Steady and Transient cases
 - Advanced features such as Turbopump, Tank Pressurization and Heat Exchangers
- Run GFSSP directly from VTASC window
 - GFSSP Run Manager acts as VTASC/GFSSP interface





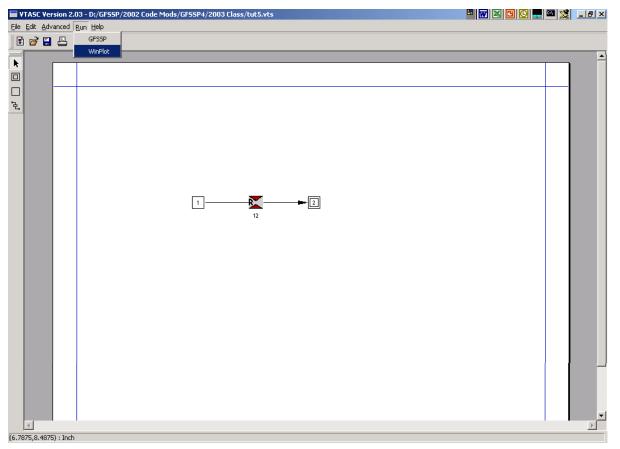
BACKGROUND -3

- Post-processing capability allows quick study of results
 - Pushbutton access to GFSSP output file
 - Point and click access to output at each node and branch
 - Built-in plotting capability for transient cases
 - Capable of plotting through Winplot
- Cross platform operation
 - Program written in C++
 - Uses cross platform C++ GUI toolkit





CREATING A CHART IN WINPLOT -1

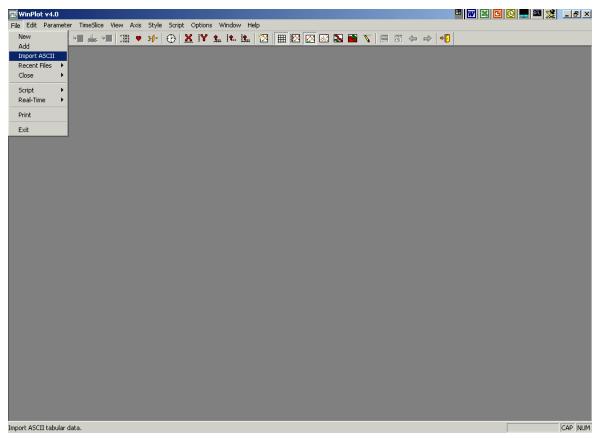


•After completing a model run, select Winplot from the VTASC Run Menu





CREATING A CHART IN WINPLOT -2



•From Winplot's File Menu, select "Import ASCII"





CREATING A CHART IN WINPLOT -3

Import ASCII Tabular File	Importing - winpltb.csv
Look jn: 🔁 2003 Class 💽 🗭 🗈 📸 🎫 Viewinpltb.csv	TIME,F12 .F45 .F56 .F23 .V12 .V45 .V56 .V23 SECONDS,LBM/S,LBM/S,LBM/S,LBM/S,LBM/S,FT/S,FT/S,FT/S,FT/S,LBF/In2,LE 0.100000E+00,0.100000E+01,0.100000E+01,0.100000E+01,0.100000E+01,0. 0.200000E+00,0.670817E+00,0.128146E+03,0.128070E+03,0.665000E+00,0. 0.200000E+00,0.745686E+06,0.128068E+03,0.128070E+03,0.174455E+01,0. 0.400000E+00,137799E+04,0.128133E+03,0.128070E+03,174455E+01,0. 0.400000E+00,137799E+04,0.128132E+03,0.128070E+03,103532E+01, 0.500000E+00,138688E+04,0.128081E+03,0.128070E+03,1288712E+02,11 0.600000E+00,139634E+04,0.128081E+03,0.128070E+03,308912E+02,11 0.600000E+00,431785E+04,0.128081E+03,0.128070E+03,375357E+08,1 . 0.800000E+00,434583E+04,0.128081E+03,0.128070E+03,375357E+08,1 . . .
File name: winpltb.csv Files of type: Comma Delimited (*.csv) ✓ Cancel	0 Skipped rows 1 File index column 0 File title row Import

Use the Browse window to select the files you wish to import
The default GFSSP Winplot files are "winpltb.csv" & "winpltn.csv"
Selecting a file opens the Importing window. Click Import.





CREATING A CHART IN WINPLOT -4

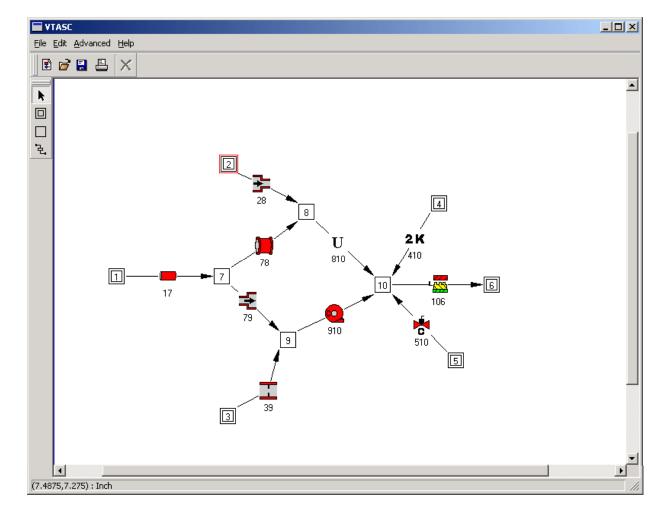
	Options Window Help X IY 🗽 🖎 🖄 🌐 1 🛛 🕢 🖉 🖓 🖓 🖓 🖉 🖓 🖓 🖓 🖓 🖓 🖓 🥵 🥵	
	rameter Selection	
	File: All Files OK (Axis: [default] V Plot Cancel	
Y	'Axis: F12,P1,T1	
	Filter: Click desired column heading to apply filter. Restore Filter duplicates	
	Name Name (all) Units Description TIME TIME SECONDS Imported F12 IMPORT001 LBM/S Imported DP12 IMPORT002 F1/S Imported DP12 IMPORT003 LBF/In2 Imported DE112 IMPORT004 BTU/R-Se Imported TIME TIME SECONDS Imported TIME TIME SECONDS Imported P1 IMPORT001 PSIA Imported P2 IMPORT002 PSIA Imported T1 IMPORT003 DEG_R Imported T2 IMPORT004 DEG_R Imported	
	Retain Sort Retain Filter Save Print	
Ready		NUM

•From the Parameter Selection window, select the data you wish to plot





DEMONSTRATION

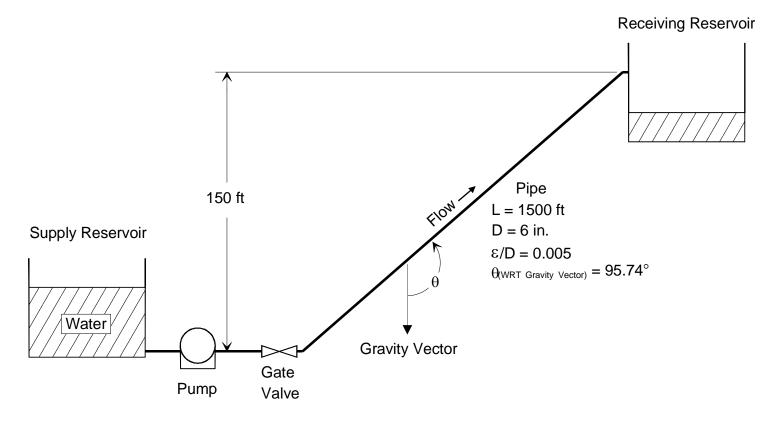








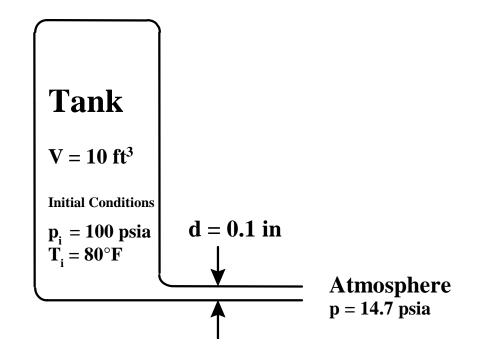
VTASC DEMONSTRATION PROBLEMS -1







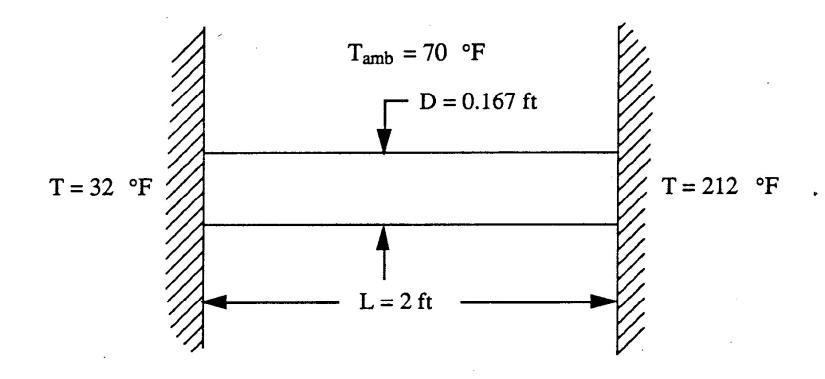
VTASC DEMONSTRATION PROBLEMS -2







VTASC DEMONSTRATION PROBLEMS -3







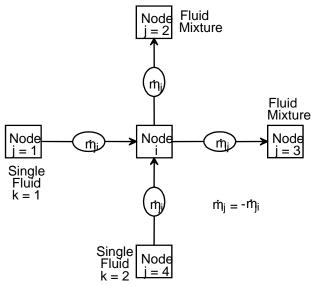
SUMMARY

- VTASC is a flow network model builder for use with GFSSP
- Flow networks can be designed and modified interactively using a "Point and Click" paradigm
- Generates GFSSP Version 4.0 compatible input files





MATHEMATICAL FORMULATION



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Propulsion System Department Marshall Space Flight Center

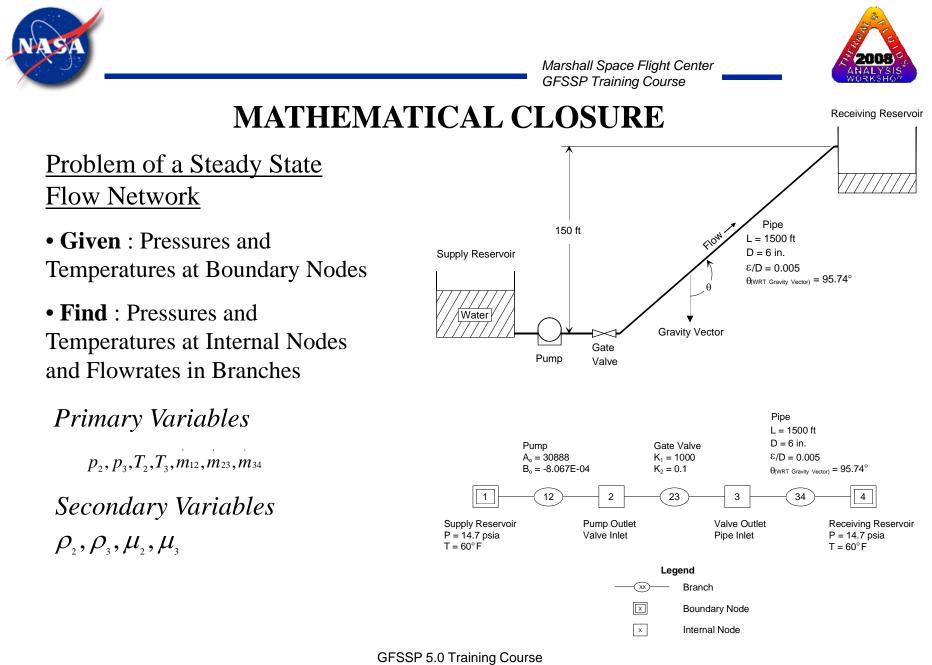
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Content

- Mathematical Closure
- Governing Equations
- Solution Procedure



Slide - 54





MATHEMATICAL CLOSURE

Problem of an Unsteady Flow Network

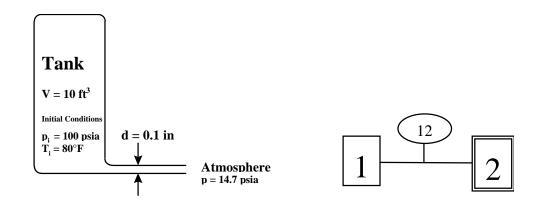
- **Given** : Pressures and Temperatures at Boundary Nodes and Initial Values at Internal Nodes
- **Find** : Pressures and Temperatures at Internal Nodes and Flowrates in Branches with Time.

Primary Variables

 $p_1(\tau), T_1(\tau), m_1(\tau), \dot{m}(\tau)$

Secondary Variables

 $ho_{\scriptscriptstyle 1}(au), \ \mu_{\scriptscriptstyle 1}(au)$







MATHEMATICAL CLOSURE

Principal Variables:

Unknown Variable	Available Equations to Solve
1. Pressure	1. Mass Conservation Equation
2. Flowrate	2. Momentum Conservation Equation
3. Temperature	3. Energy Conservation Equation
4. Specie Concentrations (Mixture)	4. Conservation Equations for Mass Fraction of Species

5. Mass (Unsteady) 5. Thermodynamic Equation of State







MATHEMATICAL CLOSURE

Secondary Variables:

Thermodynamic & Thermophysical Properties

Unknown Variable

Available Equations to Solve

- Density
- Specific Heats Viscosity Thermal Conductivity

Equilibrium Thermodynamic Relations [GASP, WASP & GASPAK Property Programs]

Flow Resistance

Unknown Variable

- 1. Friction Factor
- 2. Loss Coefficient

Available Equations to Solve

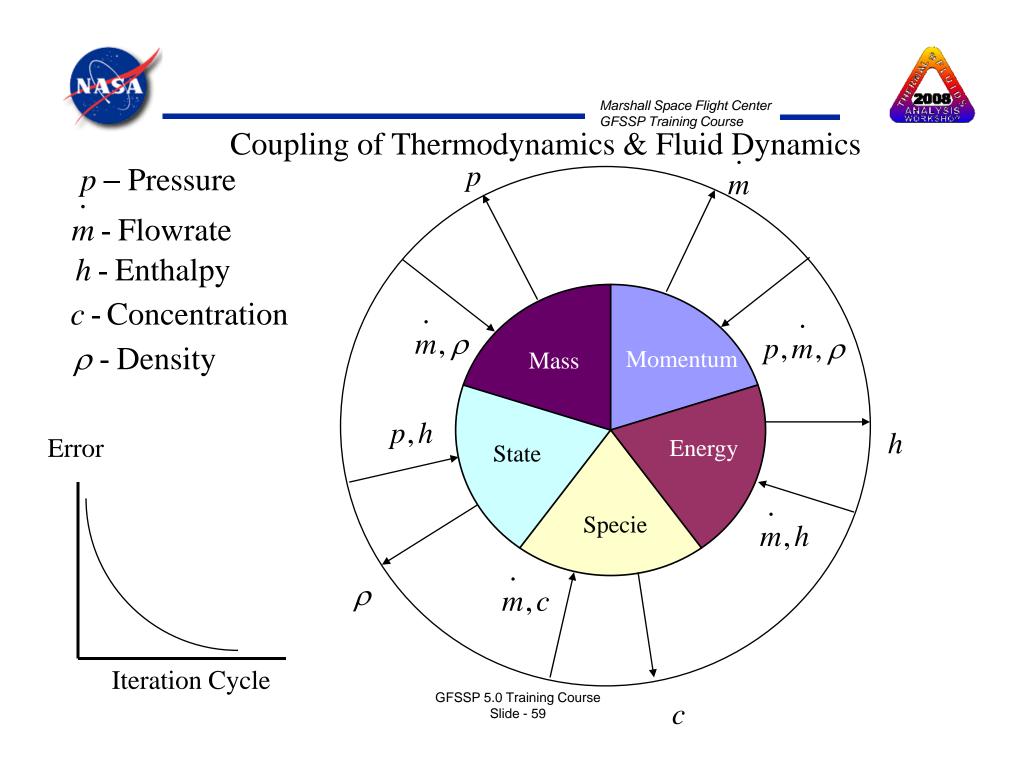
- 1. Empirical Relations
- 2. User Specified

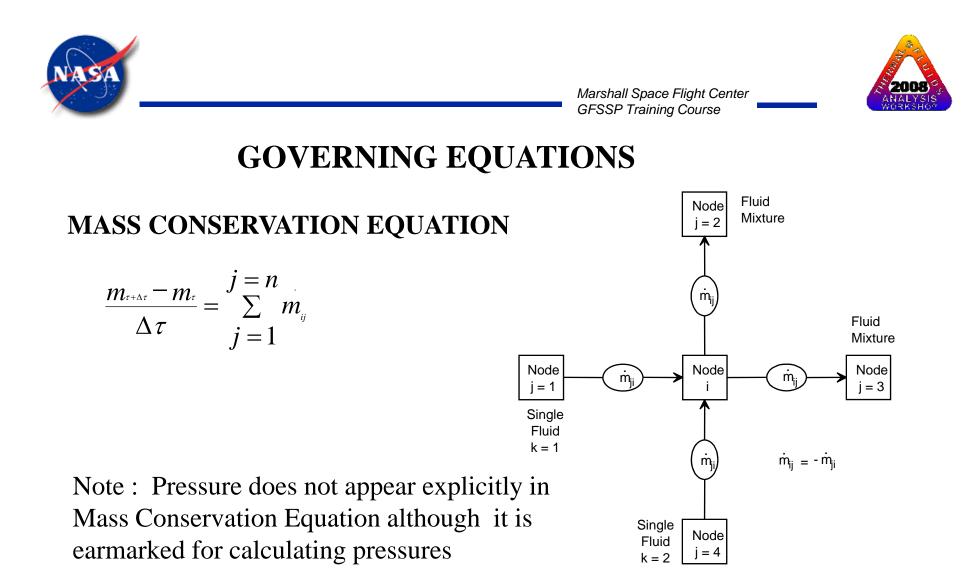


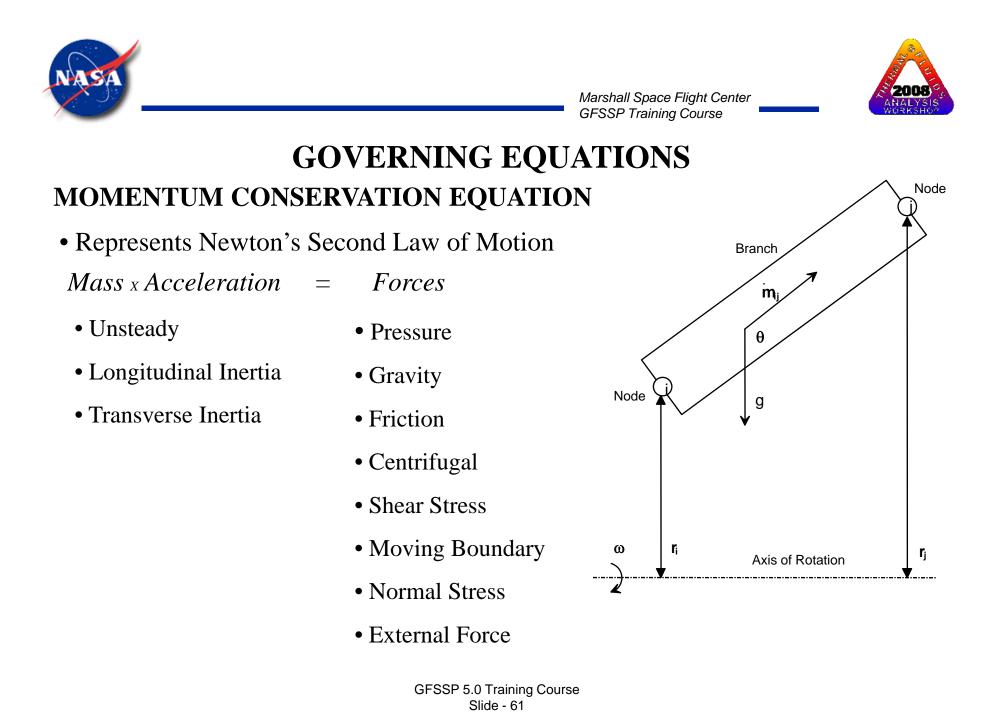


GOVERNING EQUATIONS

- Mass Conservation
- Momentum Conservation
- Energy Conservation
- Fluid Species Conservation
- Equation of State
- Mixture Property





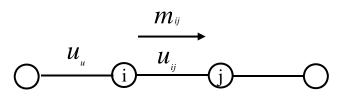






MOMENTUM CONSERVATION EQUATION

Mass x Acceleration Terms in GFSSP



<u>Unsteady</u>

$$\frac{\left(mu_{ij}\right)_{\tau+\Delta\tau}-\left(mu_{ij}\right)_{\tau}}{g_{c}\Delta\tau}$$

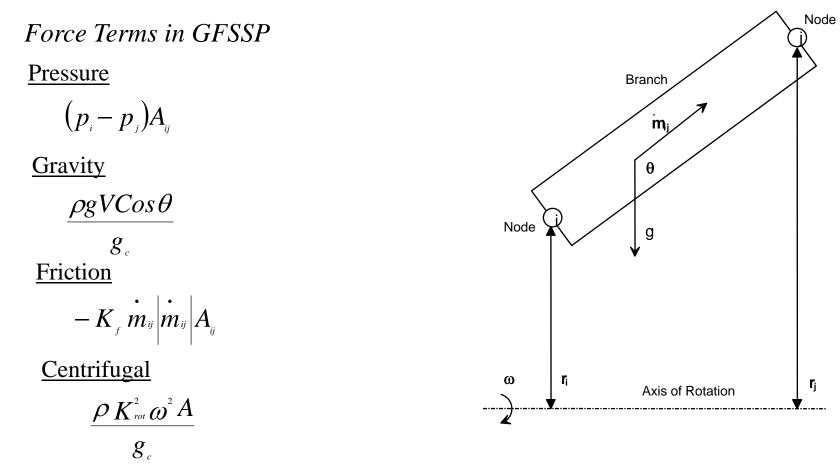
Longitudinal Inertia

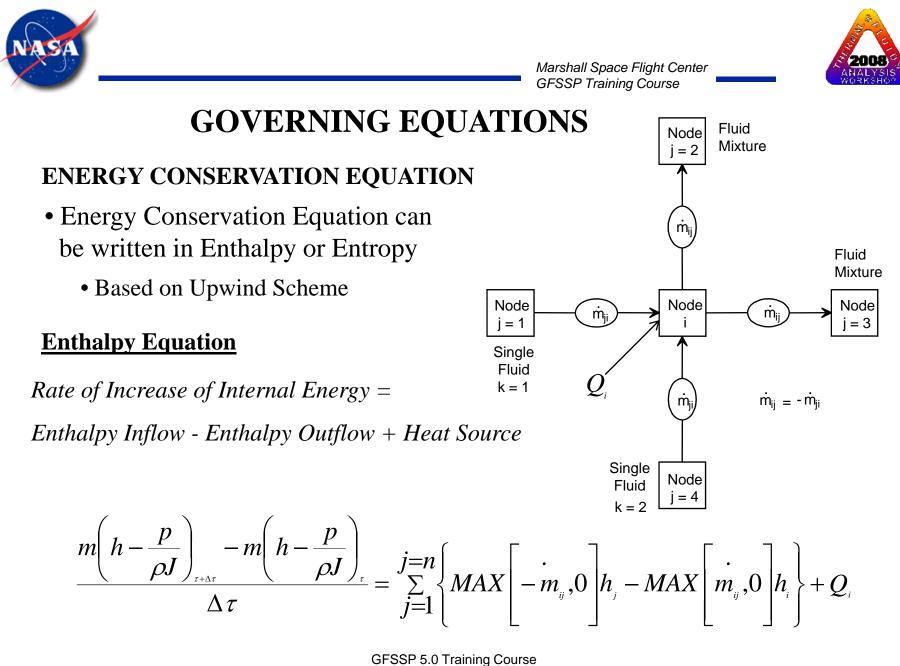
$$MAX \left| m_{ij}, 0 \right| (u_{ij} - u_{ij}) - MAX \left| -m_{ij}, 0 \right| (u_{ij} - u_{ij})$$



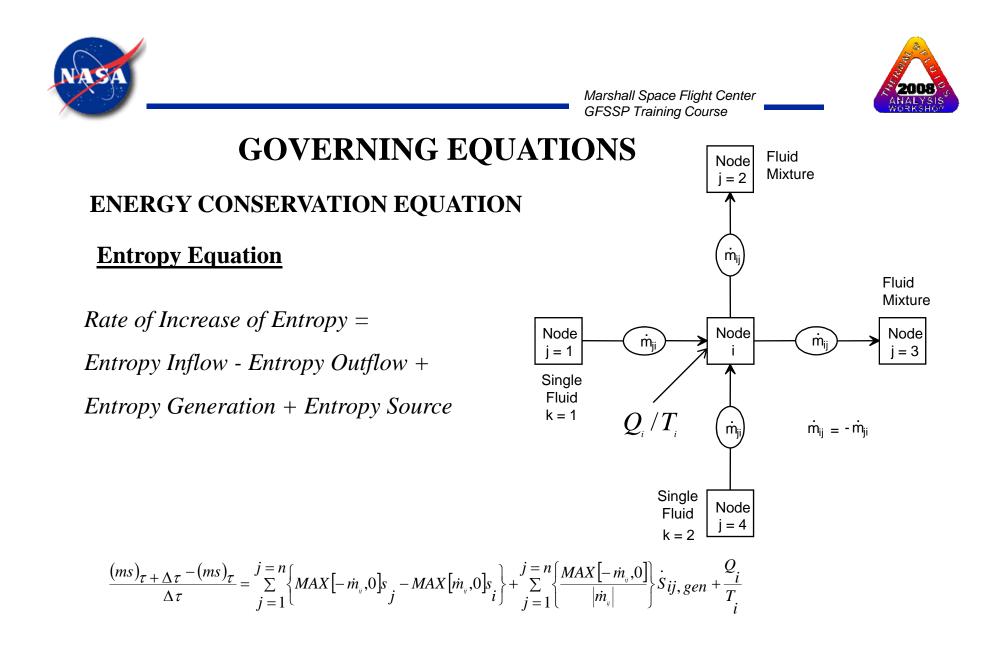


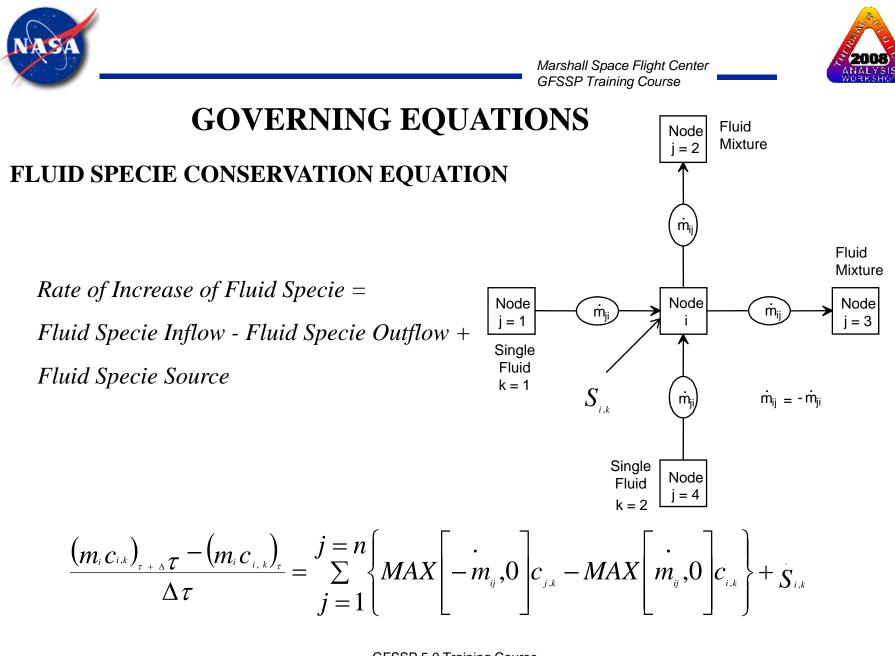
MOMENTUM CONSERVATION EQUATION





Slide - 64











EQUATION OF STATE

For unsteady flow, resident mass in a control volume is calculated from the equation of state for a real fluid

$$m = \frac{pV}{RTz}$$

Z is the compressibility factor determined from

higher order equation of state





GOVERNING EQUATIONS

EQUATION OF STATE

- GFSSP uses two separate Thermodynamic Property Packages GASP/WASP and GASPAK
- GASP/WASP uses modified Benedict, Webb & Rubin (BWR) Equation of State
- GASPAK uses "standard reference" equation from
 - National Institute of Standards and Technology (NIST)
 - International Union of Pure & Applied Chemistry (IUPAC)
 - National Standard Reference Data Service of the USSR







Mixture Property Relation

Density

• Calculated from Equation of State of Mixture with Compressibility Factor

• Compressibility Factor of Mixture is Mole average of Individual Components

$$z_i = \sum_{k=1}^{k=n} x_k z_k z_k \qquad z_k = \frac{p_i}{\rho_k R_k T_k}$$







Mixture Property Relation

Thermophysical Properties

• Viscosity, Specific Heat and Specific Heat Ratios are calculated

by taking Molar Average

$$\mu_{i} = \sum_{k=1}^{k=n} x_{k} \mu_{k} \qquad \qquad \gamma_{i} = \sum_{k=1}^{k=n} x_{k} \gamma_{k} \\ k = 1$$

$$C_{p,i} = \sum_{k=1}^{k=n} \frac{C_{p,k} x_k M_k}{x_k M_k}$$







Mixture Property Relation

Temperature

• Mixture Temperature is calculated from Energy Conservation Equation

$$(T_{i})_{\tau+\Delta\tau} = \frac{\sum_{j=1}^{j=n} \sum_{k=1}^{k=n_{f}} Cp_{k} x_{k} T_{j} MAX \left[-m_{ij}, 0\right] + (C_{p,i}m_{i}T_{i})_{\tau} / \Delta\tau + Q_{i}}{\sum_{j=1}^{j=n} \sum_{k=1}^{k=n_{f}} Cp_{k} x_{k} MAX \left[m_{ij}, 0\right] + (C_{p,i}m)_{\tau} / \Delta\tau$$

Limitation

• Cannot handle phase change of mixture





GOVERNING EQUATIONS Summary

- Familiarity with GFSSP's Governing Equations is not absolutely necessary to use the code
- However, working knowledge about Governing Equations is helpful to implement various options in a complex flow network
- A good understanding of Governing Equations is necessary to introduce new physics in the code





SOLUTION PROCEDURE

- Successive Substitution
- Newton-Raphson
- Simultaneous Adjustment with Successive Substitution (SASS)
- Convergence





SOLUTION PROCEDURE

- Non linear Algebraic Equations are solved by
 - Successive Substitution
 - Newton-Raphson
- GFSSP uses a Hybrid Method
 - SASS (Simultaneous Adjustment with Successive Substitution)
 - This method is a combination of Successive Substitution and Newton-Raphson





SOLUTION PROCEDURE

SUCCESSIVE SUBSTITUTION METHOD

STEPS:

- **1.** Guess a solution for each variable in the system of equations
- 2. Express each equation such that each variable is expressed in terms of other variables: e. g. X = f (Y,Z) and Y = f (X,Z) etc
- 3. Solve for each variable
- 4. Under-relax the variable, if necessary
- 5. Repeat steps 1 through 4 until convergence

ADVANTAGES:

Simple to program; takes less computer memory

DISADVANTAGES:

It is difficult to make a decision in which order the equations must be solved to ensure convergence





SOLUTION PROCEDURE

NEWTON-RAPHSON METHOD

STEPS:

- 1. Guess a solution for each variable in the system of equations
- 2. Calculate the residuals of each equation
- **3.** Develop a set of correction equations for all variables
- 4. Solve for the correction equations by Gaussian Elimination method
- **5.** Apply correction to each variable
- 6. Iterate until the corrections become very small

ADVANTAGES:

No decision making process is involved to determine the order in which equations must be solved

DISADVANTAGES:

Requires more computer memory; difficult to program.





SOLUTION PROCEDURE

SASS (Simultaneous Adjustment with Successive Substitution) Scheme

- SASS is a combination of successive substitution and Newton-Raphson method
- Mass conservation and flowrate equations are solved by Newton-Raphson method
- Energy Conservation and concentration equations are solved by successive substitution method
- Underlying principle for making such division:
 - Equations which have strong influences to other equations are solved by the Newton-Raphson method
 - Equations which have less influence to other are solved by the successive substitution method
- This practice reduces code overhead while maintains superior convergence characteristics



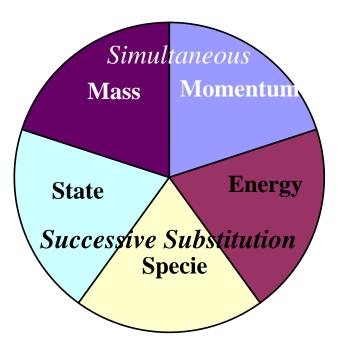


GFSSP Solution Scheme

SASS : Simultaneous Adjustment with Successive Substitution

Approach : Solve simultaneously when equations are strongly coupled and non-linear

Advantage : Superior convergence characteristics with affordable computer memory









CONVERGENCE

- Numerical solution can only be trusted when fully converged
- GFSSP's convergence criterion is based on difference in variable values between successive iterations. Normalized Residual Error is also monitored
- GFSSP's solution scheme has two options to control the iteration process
 - Simultaneous (SIMUL = TRUE)
 - Non-Simultaneous (SIMUL = FALSE)







CONVERGENCE

Simultaneous Option

- Single Iteration Loop
 - First solve mass, momentum and equation of state by the Newton-Raphson (NR) scheme
 - Next solve energy and specie conservation equation by Successive Substitution (SS) scheme
 - Solution is converged when the normalized maximum correction, Δ_{max} is less than the convergence criterion

$$\Delta_{\max} = MAX \left| \sum_{i=1}^{N_E} \frac{\Phi'_i}{\Phi_i} \right| \qquad N_E \text{ is the total number of equations solved by the Newton-Raphson scheme}$$







CONVERGENCE

Non-Simultaneous Option

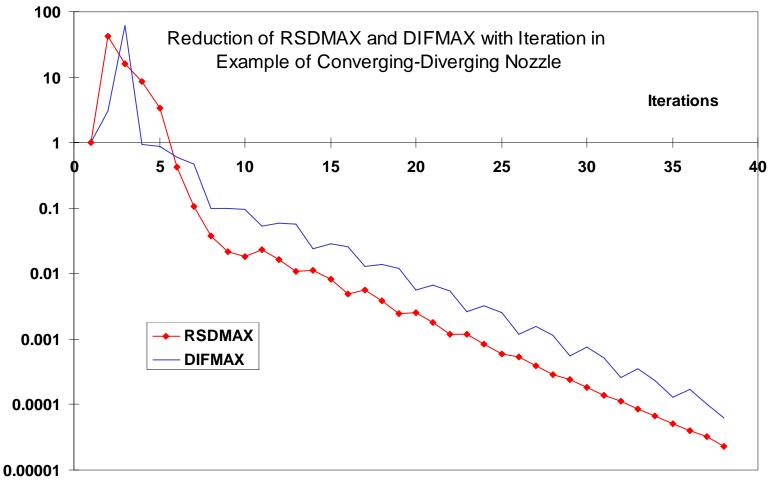
- Inner & Outer Iteration Loop
 - Mass, Momentum and Equation of state is solved in inner iteration loop by NR scheme
 - Energy and Specie conservation equations are solved in outer iteration loop by SS scheme
 - Convergence of NR scheme is determined
 - Convergence of SS scheme is determined by

$$\Delta_{\max}^{\circ} = MAX \left| \Delta_{K_f}, \Delta_{\rho}, \Delta_h \text{ or } \Delta_s \right| \qquad \Delta_{K_f} = MAX \left| \sum_{i=1}^{N_B} \frac{K_f'}{K_f} \right| \quad \text{etc.}$$



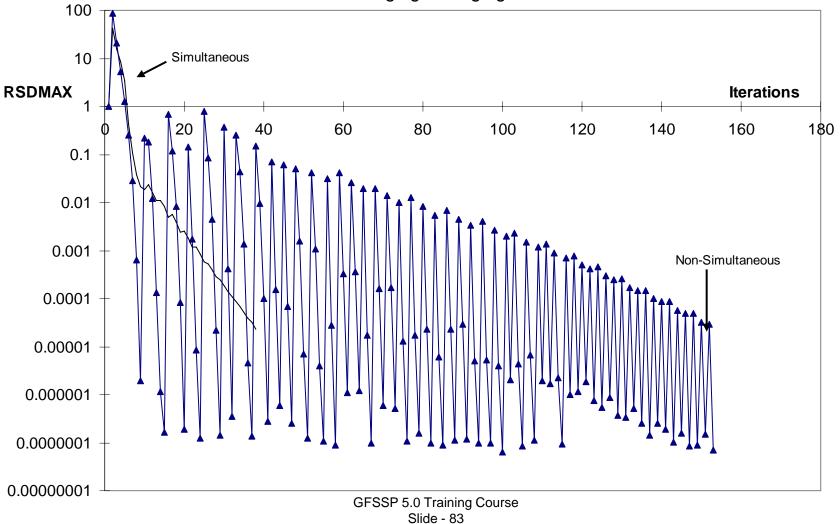


Convergence Characteristics For Simultaneous Option





Comparison of Convergence Characteristics between Simultaneous and Non-Simultaneous Option in Converging-Diverging Nozzle





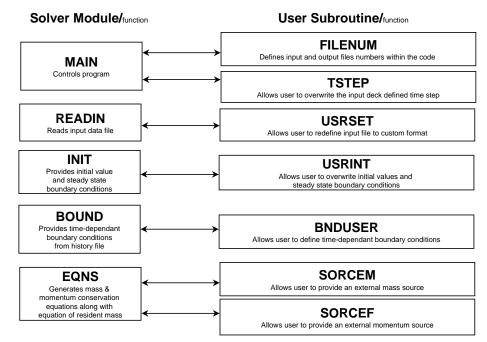


Solution PROCEDURE Summary

- Simultaneous option is more efficient than Non-Simultaneous option
- Non-Simultaneous option is recommended when Simultaneous option experiences numerical instability
- Under-relaxation and good initial guess also help to overcome convergence problem
- A lack of realism in problem specification can lead to convergence problem
- Lack of realism includes:
 - Unrealistic geometry and/or boundary conditions
 - Attempt to calculate properties beyond operating range



USER SUBROUTINES



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CONTENT

- Motivation and Benefit
- How they work



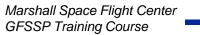




MOTIVATION AND BENEFIT

- <u>Motivation</u>: To allow users to access GFSSP solver module to develop additional modeling capability
- <u>Benefit</u>: GFSSP users can work independently without Developer's active involvement







How do they work?

- A series of subroutines are called from various locations of solver module
- The subroutines do not have any code but includes the common block
- The users can write FORTRAN code to develop any new physical model in any particular node or branch

What users need to do?

 Users need to compile a new file containing all user routines and link that with GFSSP to create a new executable

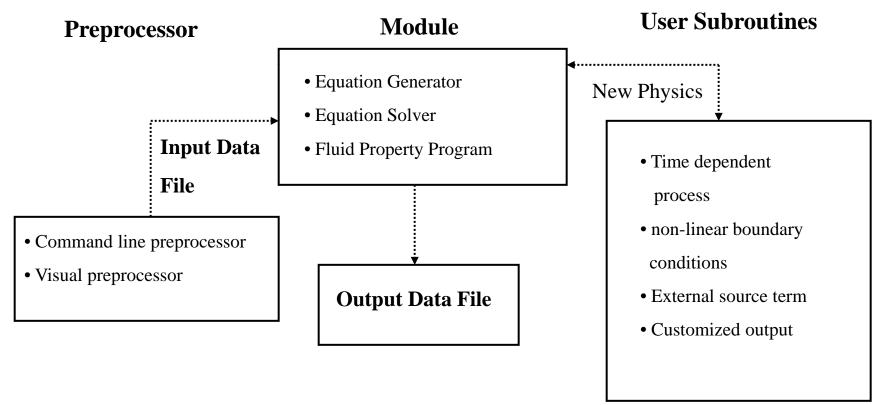






GFSSP PROCESS FLOW DIAGRAM









DESCRIPTION OF USER SUBROUTINES

Twelve User Subroutines were provided:

- SORCEM: External Mass Source
- SORCEF: External Force
- SORCEQ: External Heat source
- SORCEC: External Concentration source
- KFUSER: New resistance option
- PRPUSER: New fluid property
- TSTEP: Variable time step during a transient run

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DESCRIPTION OF USER SUBROUTINES

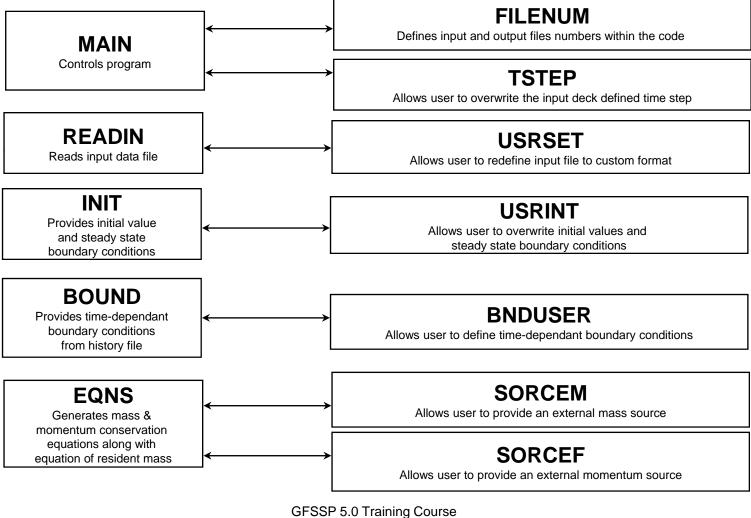
- BNDUSER: Variable boundary condition during transient run (Alternative to history file)
- USRINT: Provide initial values and steady state boundary conditions
- PRNUSER: Additional print out or creation of additional file for post processing
- FILNUM: Assign file numbers; users can define new file numbers
- USRSET: User can supply all the necessary information by writing their own

code





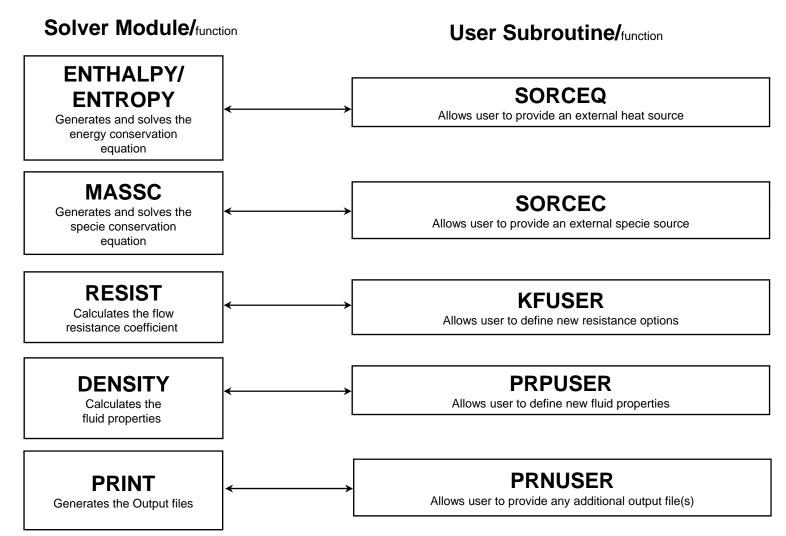
Solver Module/function



User Subroutine/function







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GFSSP INDEXING SYSTEM

- Node and Branch Variables are stored in onedimensional array
- Node variables include:
 - Name
 - Pressure, Temperature, Concentration, Thermodynamic properties
- Branch variables include:
 - Name
 - Flowrate, Velocity, Resistance coefficients, Reynolds number
- Three subroutines are made available to Users for finding location and indices for a given node or branch





NODE & BRANCH INDEX

- User defined node names are stored in NODE-array.
- NODE-array includes both internal and boundary nodes.
- Total number of elements in NODE-array is NNODES
- The internal nodes are stored in INODE-array.
- There are NINT elements in INODE-array.
- Branch names are stored in IBRANCH-array
- There are NBR elements in IBRANCH-array

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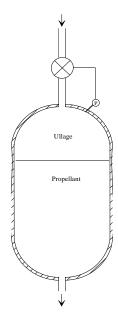
SUMMARY

- User Subroutines can be used to add new capabilities that are not available to Users through Logical Options
- New capabilities may include:
 - Introducing new type of resistance
 - Incorporating heat or mass transfer in any given node
 - Variable time step for a transient problem
 - Customized output
- Checklist for User Subroutines
 - Identify subroutines that require modifications
 - Select GFSSP variables that require to be modified
 - Make use of GFSSP provided User variables in your coding





TANK PRESSURIZATION



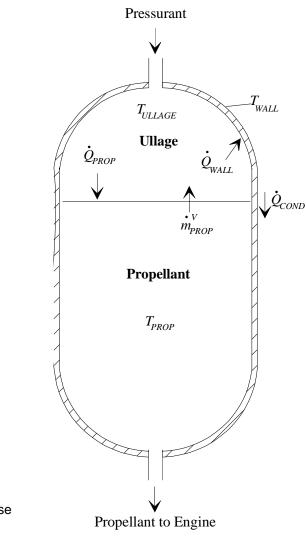
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TANK PRESSURIZATION

- Predict the ullage conditions considering heat and mass transfer between the propellant and the tank wall
- Predict the propellant conditions leaving the tank



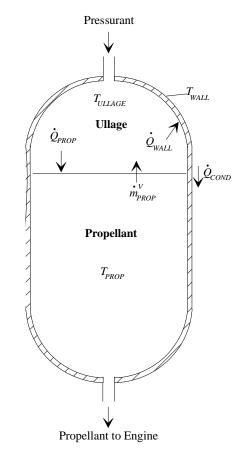
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TANK PRESSURIZATION ADDITIONAL PHYSICAL PROCESSES

- Change in ullage and propellant volume.
- Change in gravitational head in the tank.
- Heat transfer from pressurant to propellant.
- Heat transfer from pressurant to the tank wall.
- Heat conduction between the pressurant exposed tank surface and the propellant exposed tank surface.
- Mass transfer between the pressurant and propellant.



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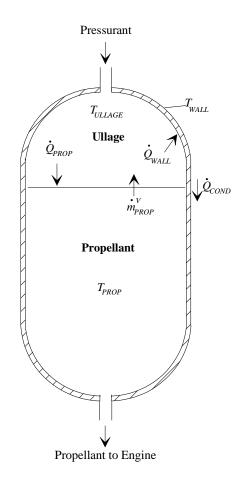




TANK PRESSURIZATION CALCULATION STEPS

For each time step calculate

- Ullage and Propellant Volumes
- Tank Bottom Pressure
- Heat Transfer between pressurant and propellant and pressurant and wall
- Wall Temperature
- Mass Transfer from propellant to ullage









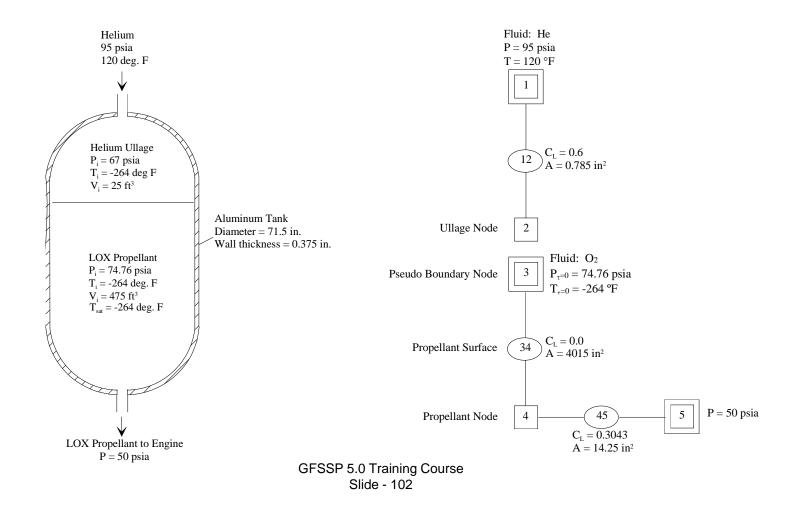
TANK PRESSURIZATION ADDITIONAL INPUT DATA FOR PRESSURIZATION

		Pressurant
PRESS	Logical Variable to Activate the Option	\checkmark
NTANK	Number of Tanks in the Circuit	
NODUL	Ullage Node	T _{ULLAGE} T _{WALL}
NODULB	Pseudo Boundary Node at interface	
NODPRP	Propellant Node	
IBRPRP	Branch number connecting NODULB & NODPRF	$\mathbf{D} \begin{bmatrix} \mathbf{v} & \mathbf{v} \\ \vdots \\ \mathbf{w}_{PROP} \end{bmatrix} \begin{bmatrix} \mathbf{v}^{\mathbf{Q}_{COND}} \\ \vdots \\ \mathbf{w}_{PROP} \end{bmatrix}$
TNKAR	Tank Surface Area in Ullage at Start, in ²	PROP
TNKTH	Tank Thickness, in	Propellant
TNKRHO	Tank Density, lbm/ft ³	T _{PROP}
TNKCP	Tank Specific Heat, Btu/lbm - R	
TNKCON	Tank Thermal Conductivity, Btu/ft-sec-R	
ARHC	Propellant Surface Area, in ²	
FCTHC	Multiplying Factor in Heat Transfer Coefficient	
TNKTM	Initial Tank Temperature, ° F	\downarrow
		Propellant to Engine





TANK PRESSURIZATION EXAMPLE 10 TANK SCHEMATIC AND GFSSP MODEL







TNKTM, deg. F

TANK PRESSURIZATION EXAMPLE 10 PRESSURIZATION INPUT

 NODE
 PRES (PSI)
 TEMP(DEGF)
 MASS SOURC
 HEAT SOURC
 THRST AREA
 VOLUME
 CONCENTRATION

 2
 0.6700E+02
 -0.2640E+03
 0.0000E+00
 0.0000E+00
 0.0000E+00
 0.4320E+05
 1.0000
 0.0000

 4
 0.7476E+02
 -0.2640E+03
 0.0000E+00
 0.0000E+00
 0.0000E+00
 0.8208E+06
 0.0000
 1.0000

 ex10h1.dat
 ex10h3.dat
 ex10h5.dat
 0.0000E+00
 0.000E+00
 0.000E+00
 0.000E+00
 <t

NUMBER OF TANKS IN THE CIRCUIT 1 NODUL NODULB NODPRP IBRPRP TNKAR TNKTH TNKRHOTNKCP TNKCON ARHC FCTHC TNKTM 2 3 4 34 6431.91 0.375 170.00 0.20 0.0362 4015.00 1.00 -264.00 NODE DATA FILE **Tank Input Units** FNODE.DAT BRANCH DATA FILE VOLUME. in³ TNKAR, in^2 FBRANCH.DAT TNKTH, in TNKRHO, lbm/ft³ TNKCP, Btu/lbm-R TNKCON, Btu/ft-s-R ARHC, in²

> GFSSP 5.0 Training Course Slide - 103





TANK PRESSURIZATION EXAMPLE 10 PRESSURIZATION OUTPUT

SOLUTION

INTERNAL NODES

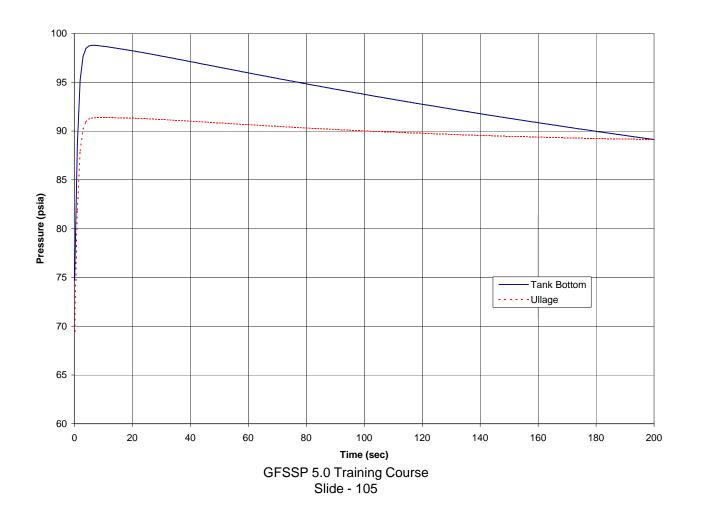
NODE	P(PSI)	TF(F)	Z	RHO (LBM/FT ³)	EM(LBM)	CONC			
						HE	02		
2	0.9138E+02	-0.1347E+03	0.1006E+01	0.1047E+00	0.5144E+01	0.9690E+0	0.0310		
4	0.9869E+02	-0.2640E+03	0.2310E-01	0.6514E+02	0.2937E+05	0.0000E+00	0 1.0000		
BRANCHES BRANCH KFACTOR DELP FLOW RATE VELOCITY REYN. NO. MACH NO. ENTROPY GEN. LOST WORK									
	2/(LBM-FT)^2)		/SEC) (FT/S			BTU/(R-			
					6E+06 0.12	•	lE-02 0.127E+04		
							DE+00 0.000E+00		
							5E+00 0.176E+05		
2	IODPRP QULPR 4 1.964	8.5069	QCOND 1	L96.4447 450		JLG L359 QC TN VC	ank Output Units JLPROP, Btu/s JLWAL, Btu/s COND, Btu/s IKTM, deg. R DLPROP, ft ³ DLULG, ft ³		
GFSSP 5.0 Training Course									



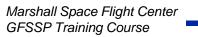


TANK PRESSURIZATION

EXAMPLE 10 ULLAGE AND TANK BOTTOM PRESSURE HISTORY



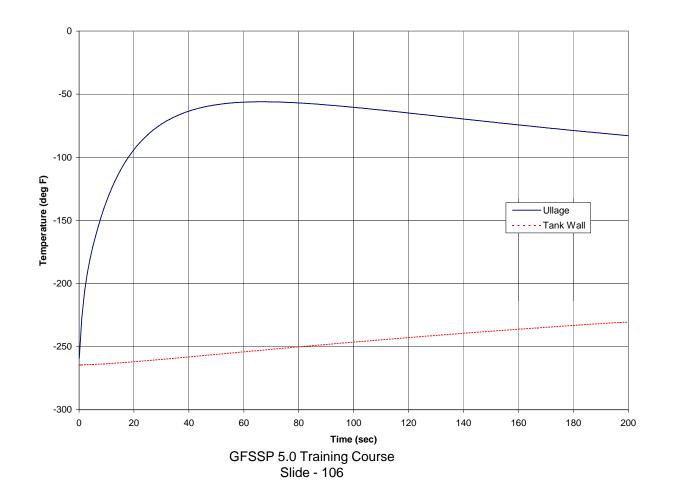






TANK PRESSURIZATION

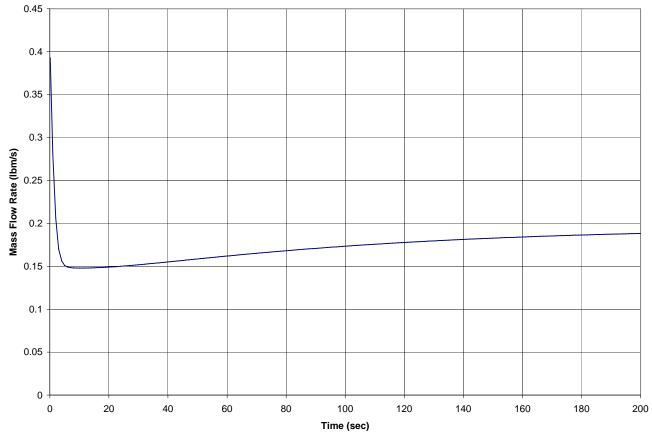
EXAMPLE 10 ULLAGE AND TANK WALL TEMPERATURE HISTORY







TANK PRESSURIZATION EXAMPLE 10 HELIUM FLOW RATE HISTORY

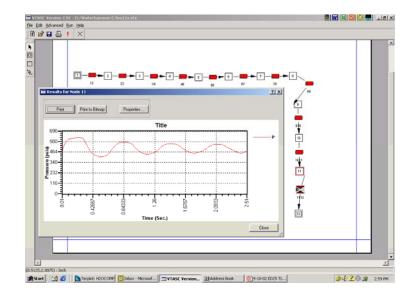


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FLUID TRANSIENT



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CONTENT

- Classification of Unsteady Flow
- Causes of Transient
- Valve Closing
 - Comparison with Method of Characteristics
- Valve Opening
- Conclusions





CLASSIFICATION OF UNSTEADY FLOW

- Quasi-steady flow is a type of unsteady flow when flow changes from one steady-state situation to another steady-state situation
 - Time dependant terms in conservation equation is not activated
 - Solution is time dependent because boundary condition is time dependent
- Unsteady flow formulation has time dependant terms in all conservation equations
 - Time dependant term is a function of density, volume and variables at previous time step





CAUSES OF TRANSIENT

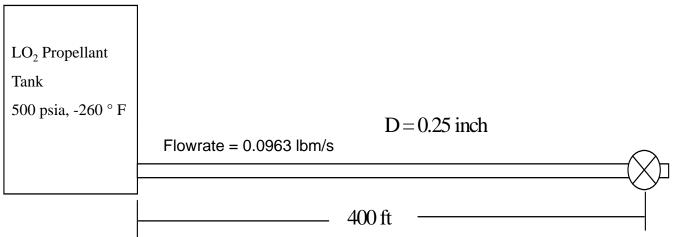
- Changes in valve settings, accidental or planned
- Starting or stopping of pumps
- Changes in power demand of turbines
- Action of reciprocating pumps
- Changing elevation of reservoir
- Waves in reservoir
- Vibration of impellers or guide vanes in pumps or turbines
- Unstable pump characteristics
- Condensation





PROBLEM DESCRIPTION

Rapid valve closing

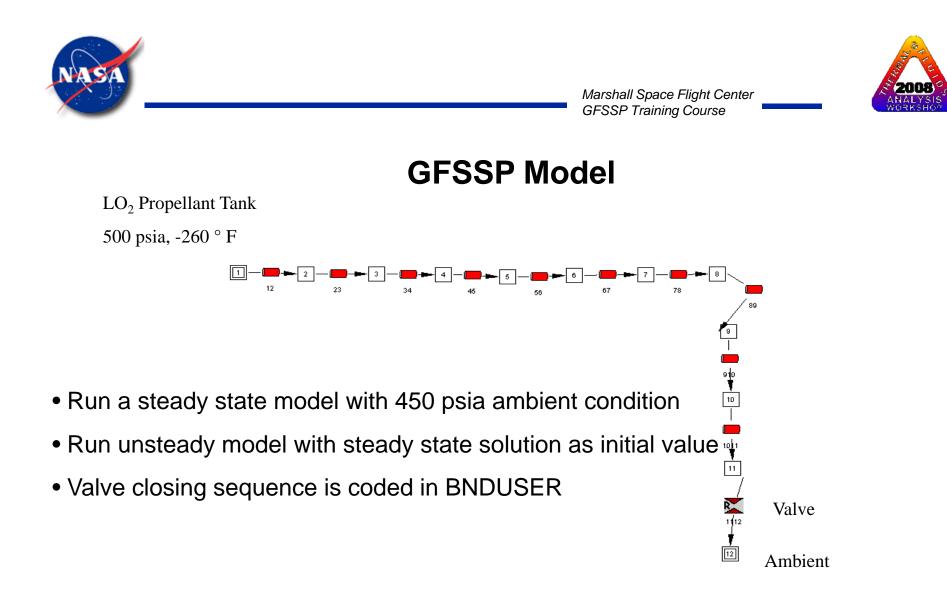


Objectives of Analysis:

- Maximum Pressure
- Frequency of Oscillation

Time (sec)	Area (in ²)
0.00	0.0491
0.02	0.0164
0.04	0.0055
0.06	0.0018
0.08	0.0006
0.10	0.00

Valve Closure History







Description of Test cases

 $P_{tank} = 500 \text{ psia}$ $T_{tank} = -260 \degree F \text{ (Oxygen)} = 70 \degree F \text{ (Water)} = -414 \degree F \text{ (Hydrogen)}$

Case	Fluid	Number of	Time Step	Sound	Flowrate	p _{max}	Period of
No.		Branches	(sec)	Speed	(lb/sec)	(psia)	Oscillation
				(ft/sec)			(sec)
1	LO_2	10	0.01	2462	0.0963	626	0.65
2	LO_2	20	0.005	2462	0.0963	632	0.65
3	LO ₂	5	0.02	2462	0.0966	620	0.65
4	H ₂ O	10	0.005	4874	0.071	704	0.33
5	LH_2	10	0.02	3577	0.0278	545	0.43
6	LO ₂ & GHe	10	0.01	1290**	0.0963	580	1.24
	(0.1%)						
7	LO ₂ & GHe	10	0.01	769**	0.0963	520	2.08
	(0.5%)						
8^*	LO ₂ (2 Phase)	10	0.01		0.0963	550	1.17
	$x_{exit} = 0.017$						
9 [*]	LO ₂ (2 Phase)	10	0.01		0.0963	538	1.22
	$x_{exit} = 0.032$						
10	LO_2		0.01	2462	0.0963	611	0.65

Pressure oscillations are due to condensation

** Estimated from period of oscillation $[a=4L/\lambda]$

• Time step for each test case is so chosen that Courant number is less than unity

• Courant Number = Length of Branch/(Sound Speed X Time Step)





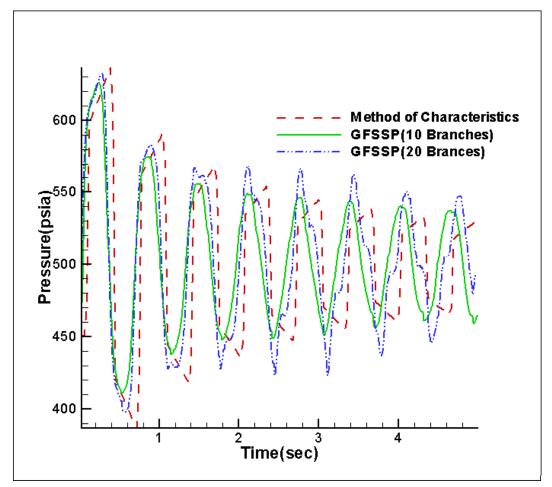
COMPARISON BETWEEN GFSSP & MOC SOLUTION FOR THREE FLUIDS

Fluid	Flowrate (lb/s)	Velocity (ft/s)	Friction Factor (Used in MOC	Sound Speed (ft/s)	Max. Pressure rise above supply pressure (psi)		Period of Oscillation (sec)	
			solution)		MOC	GFSSP	MOC	GFSSP
Water	0.071	3.34	0.0347	4892	214	204	0.33	0.33
Oxygen	0.0963	4.35	0.0196	2455	136	126	0.65	0.65
Hydrogen	0.0278	19.01	0.0157	3725	61	45	0.43	0.43





COMPARISON BETWEEN GFSSP & MOC SOLUTION



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PROBLEM DESCRIPTION Rapid Valve Opening



Objectives of Analysis:

- Maximum Pressure
- Time to reach steady-state

Time (sec)	Area (in ²)
0.00	0.0
0.01	0.0088
0.02	0.1767
0.03	0.2651
0.04	0.3534
0.05	0.4418



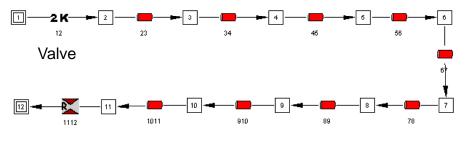




GFSSP Model

LH₂ Propellant Tank

112 psia, -425 ° F

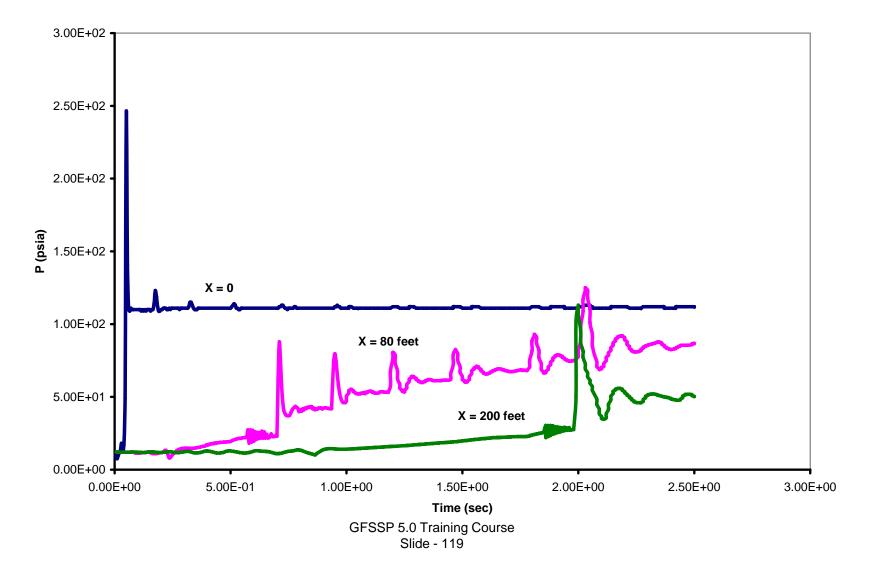


Orifice



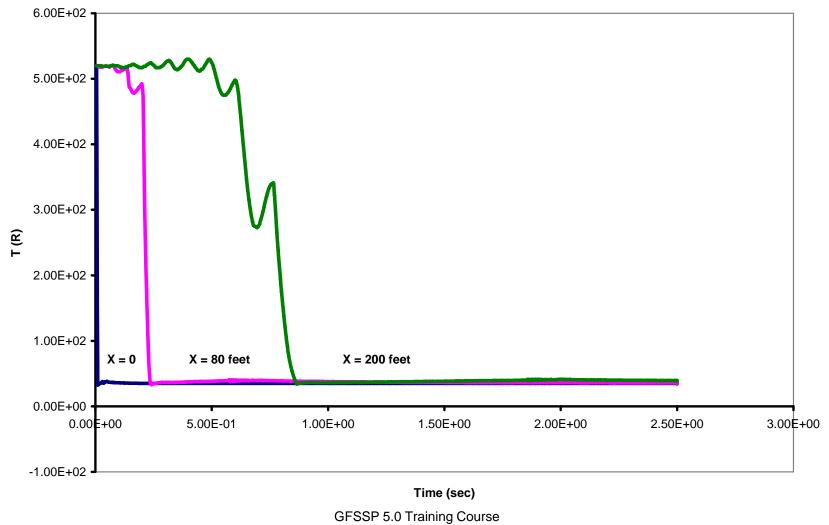


Pressure





Temperature

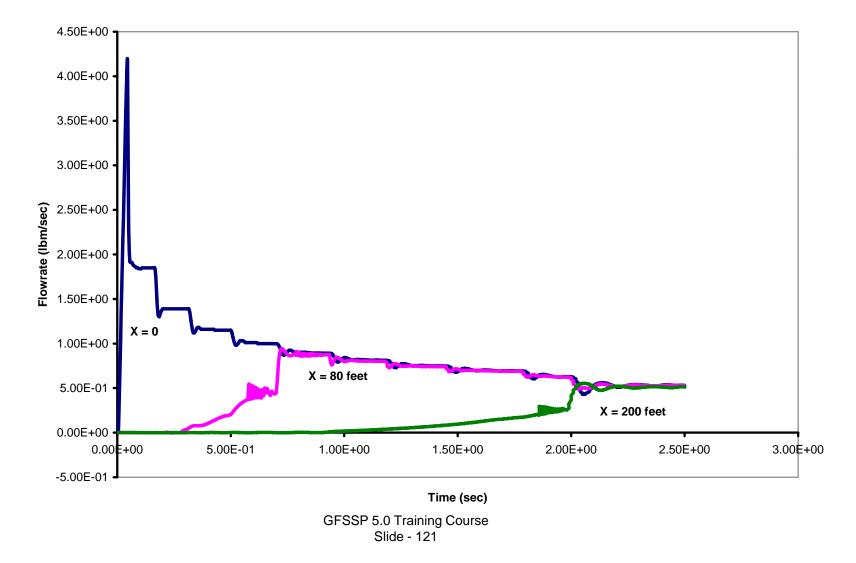


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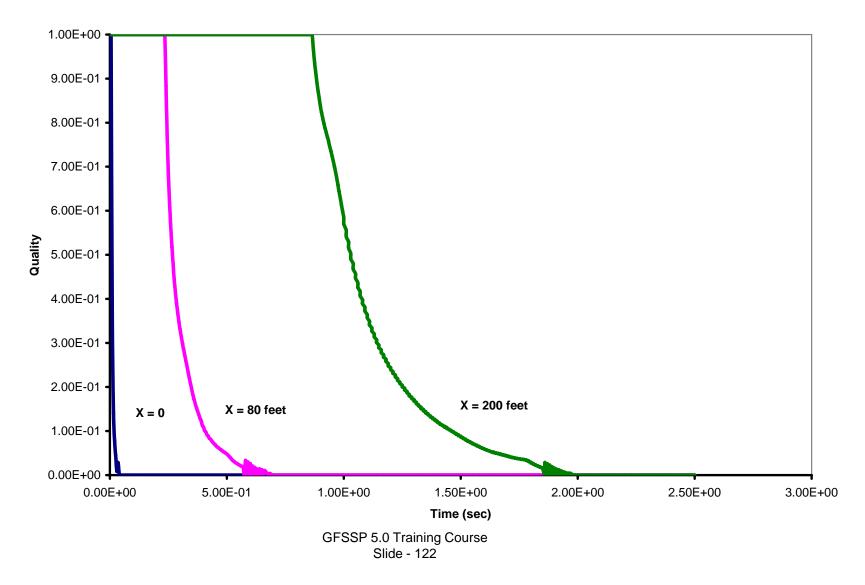


Flowrate





Quality







CONCLUSIONS

- GFSSP has been used to compute fluid transient following rapid valve closure and opening
- GFSSP predictions have been compared with MOC solution:
 - Maximum pressure and frequency compares well
 - Discrepancies exist in damping rate and shape of the pressure curve
- Demonstrations have been made for
 - Sudden opening of cryogenic propellant in long pipeline
- Time step must satisfy Courant condition
- Predictions in all demonstration calculations show physical realism





Conjugate Heat Transfer

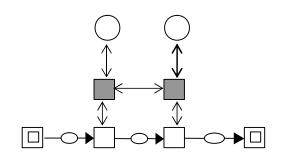
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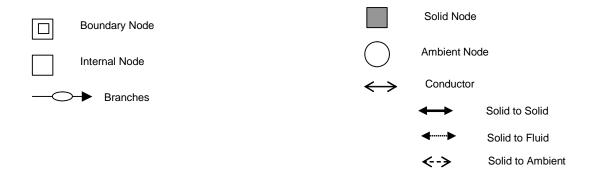


Conjugate Heat Transfer



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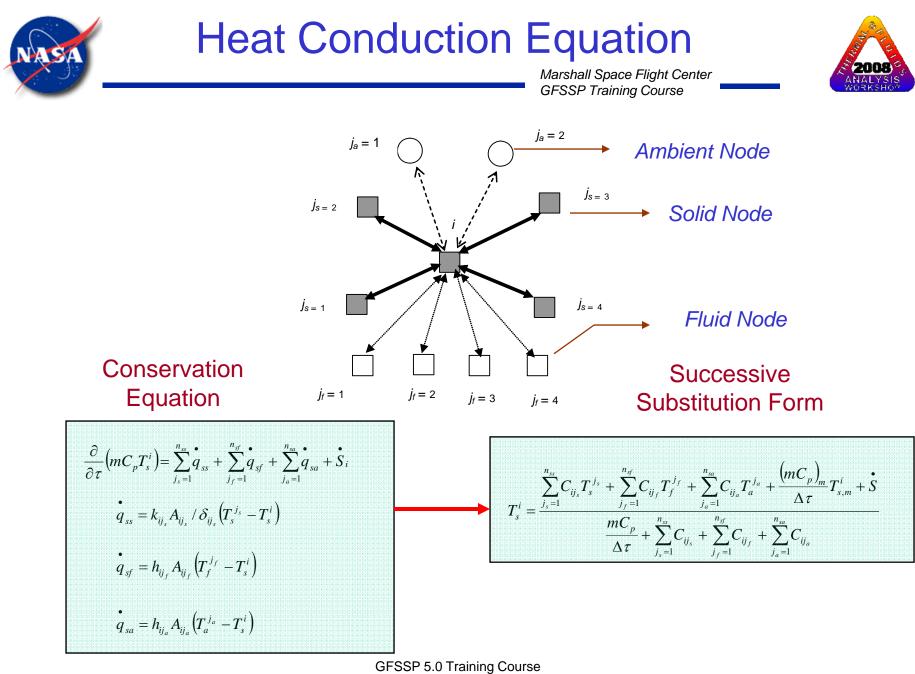
Mathematical Closure

Unknown Variables

- 1. Pressure
- 2. Flowrate
- 3. Fluid Temperature
- 4. Solid Temperature
- 5. Specie Concentrations
- 6. Mass

Available Equations to Solve

- 1. Mass Conservation Equation
- 2. Momentum Conservation Equation
- 3. Energy Conservation Equation of Fluid
- 4. Energy Conservation Equation of Solid
- 5. Conservation Equations for Mass Fraction of Species
- 6. Thermodynamic Equation of State

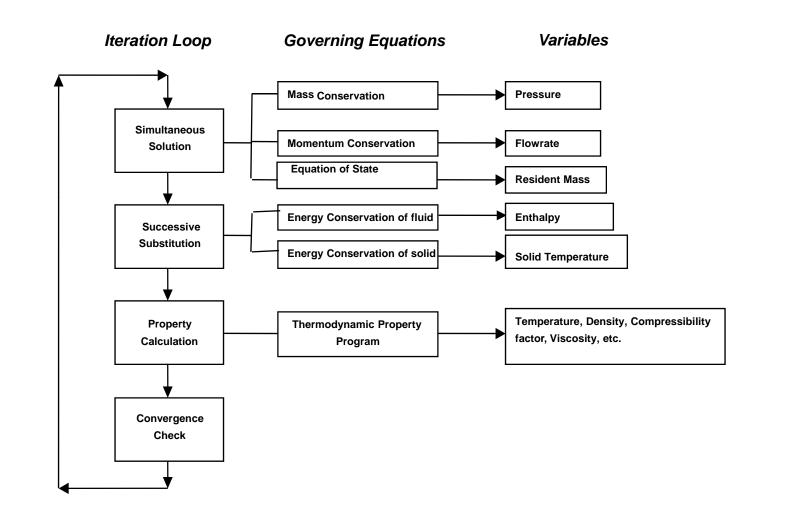


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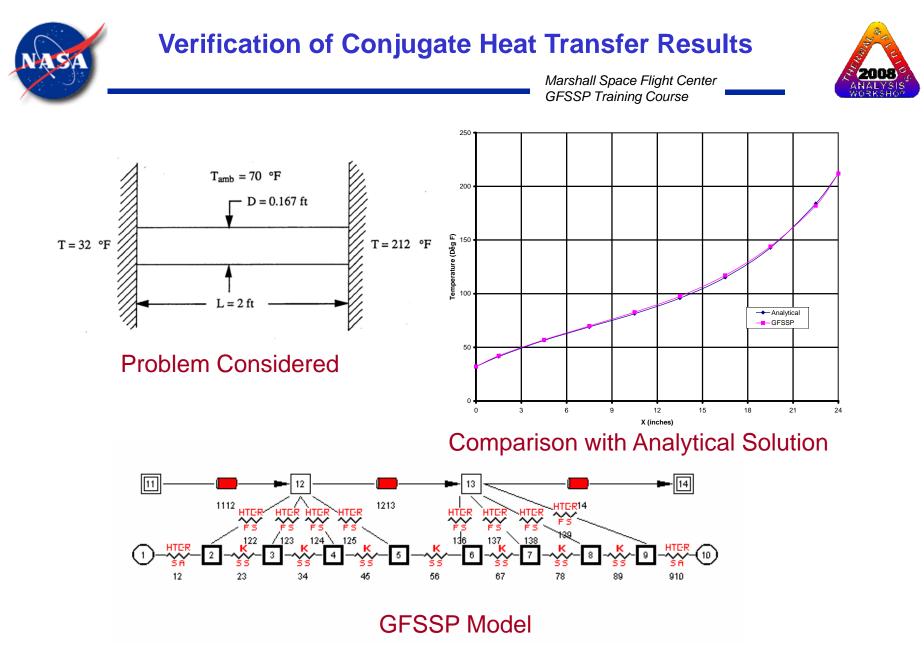
SASS Solution Scheme



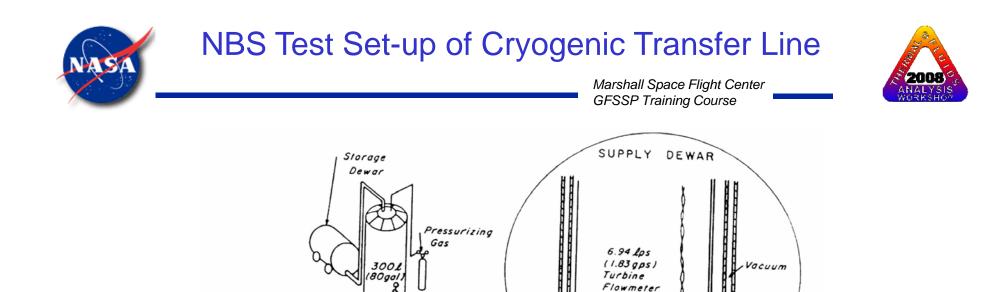
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GFSSP 5.0 Training Course Slide - 129



#2

43.0m (141 ft) 0

Globe and Gate

Valve Location

Inner Tube 61.0 m (200 ft) x

1.90 cm (3/4 in) O.D. x 1.59 cm (5/8 in) 1.D., COPPER

#₄

Ball Valve

Location

Pressure Transducers, Thermocouple Reference

Bath.

60.4 m (198 ft)

> 61.0 m (20011)

#3

Vapor Pressure

Thermometer

6.1 m (20 ft)

INSTRUMENT STATION

Static Pressure

Ταρ

Kovar Seal

FLOW-

Stream / Thermocouple

Wall

Thermocouple

24.4 m (8011)

- Vacuum -

Pitot Tubes

Sealing

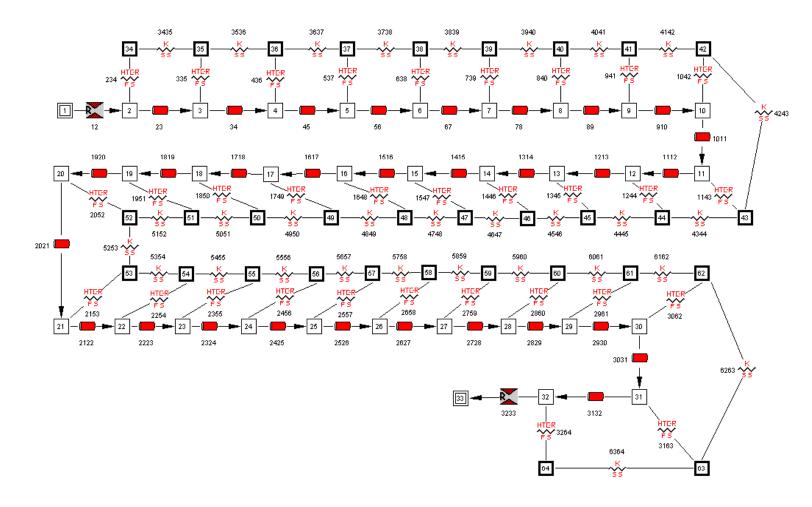
Gland

Slide - 130

GFSSP Model of Cryogenic Transfer Line



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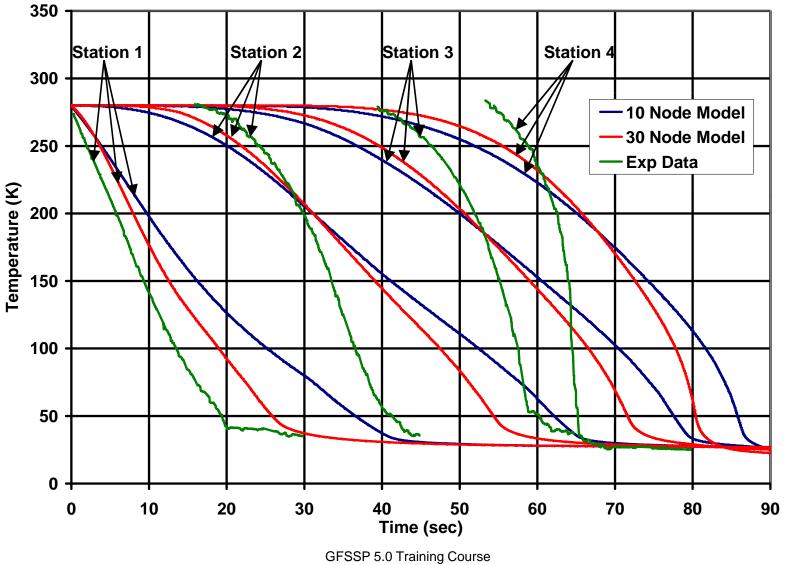
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Comparison with Test Data



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Summary

- **GFSSP** has been extended to model conjugate heat transfer
- Fluid Solid Network Elements include:
 - Fluid nodes and Flow Branches
 - Solid Nodes and Ambient Nodes
 - Conductors connecting Fluid-Solid, Solid-Solid and Solid-Ambient Nodes
- Heat Conduction Equations are solved simultaneously with Fluid Conservation Equations for Mass, Momentum, Energy and Equation of State
- The extended code was verified by comparing with analytical solution for simple conduction-convection problem
- The code was applied to model
 - Pressurization of Cryogenic Tank
 - Freezing and Thawing of Metal
 - Chilldown of Cryogenic Transfer Line
 - Boil-off from Cryogenic Tank