

# **A SELECTION OF COMPOSITES SIMULATION PRACTICES AT NASA LANGLEY RESEARCH CENTER**

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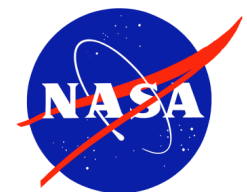
**MSC Software**

**Composites Consortium Meeting**

**May 3 – May 4, 2007**

**Santa Ana, CA**

**NATIONAL  
INSTITUTE OF  
AEROSPACE**





# OUTLINE

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- **National Institute of Aerospace (NIA) overview**
- **NASA Langley (LaRC) overview**
- **Examples of composites simulation:**
  - Thermo-mechanical material model
  - Damage analyses of composites
    - Progressive damage material model
    - Virtual crack closure technique (VCCT)
    - Decohesion element
  - Flight 587 structures investigation
  - Rotorhub flexbeam analysis
  - Mixed-mode delamination failure criterion
  - Delamination in z-pin reinforced laminates
- **Concluding remarks**



# NATIONAL INSTITUTE OF AEROSPACE

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- An Independent Non-profit Research and Graduate Education Institute formed in 2002 by a Consortium of Six Universities and the AIAA Foundation
- Conceived by NASA Langley Research Center and established to serve as LaRC's Collaborative Partner
- Conducts Collaborative **Research** in Engineering and Science relevant to Aerospace
  - Georgia Tech
  - Virginia Tech
  - University of Virginia
  - University of Maryland
  - North Carolina A&T State University
  - Old Dominion University
  - College of William & Mary
  - Hampton University



# COMPOSITE RESEARCH ACTIVITIES AT NASA LANGLEY

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- Computational materials
- Crash worthiness of composite structures
- Structural tailoring with composites
- Manufacturing and fabrication technology
- Health monitoring using embedded sensors
- Residual strength and damage propagation
- Influence of generalized imperfections on composite shell response
- Delamination and crack growth
- Thermo-mechanical material response
- Multidisciplinary design environments
- Uncertainty quantification for composite designs
- Impact response and strain rate sensitivity



# SIMULATION ISSUES FOR COMPOSITES

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- Variabilities in composite design (fiber placement, fiber angle, thickness, volume fraction, failure modes, etc)
- Visualization of composite simulation results
- Micro-mechanics through macro-mechanics - Problem of scale (global local analysis requirements)
- Computational models for new and evolving materials
- Computational models for incorporating mechanical-based failure models
- Failure initiation and damage propagation of different composite architectures (sandwich construction, integrally-stiffened sections, etc)
- Corroborating experimental program for validation of analysis

At NASA Langley, these issues are addressed by researchers using:

1. User-defined material models
2. User-defined element routines
3. User-developed pre and post-processing software



# NASA LANGLEY RESEARCH CENTER

Research Technology Directorate (RTD) consists of 21 branches:

Configuration Aerodynamics Branch	<b>Advanced materials and Processing Branch</b>	Aeroacoustics Branch	Safety-Critical Avionics Systems Branch
<b>Computational Aerosciences Branch</b>	<b>Aeroelasticity Branch</b>	Applied Technologies and Testing Branch	<b>Structural Acoustics Branch</b>
Flow Physics and Controls Branch	<b>Durability, Damage Tolerance and Reliability Branch</b>	Dynamic Systems and Controls Branch	<b>Structural Dynamics Branch</b>
Advanced Sensing and Optical Measurement Branch	<b>Gas, Fluid and Acoustics Research Support Branch</b>	Flight Dynamics Branch	
Aerothermodynamics Branch	<b>Structural Mechanics and Concepts Branch</b>	Crew Systems and Aviation Operations Branch	
Hypersonic Airbreathing Propulsion Branch	<b>Nondestructive Evaluation Sciences Branch</b>	Electromagnetics and Sensors Branch	



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# **THERMO-MECHANICAL MATERIAL MODEL**

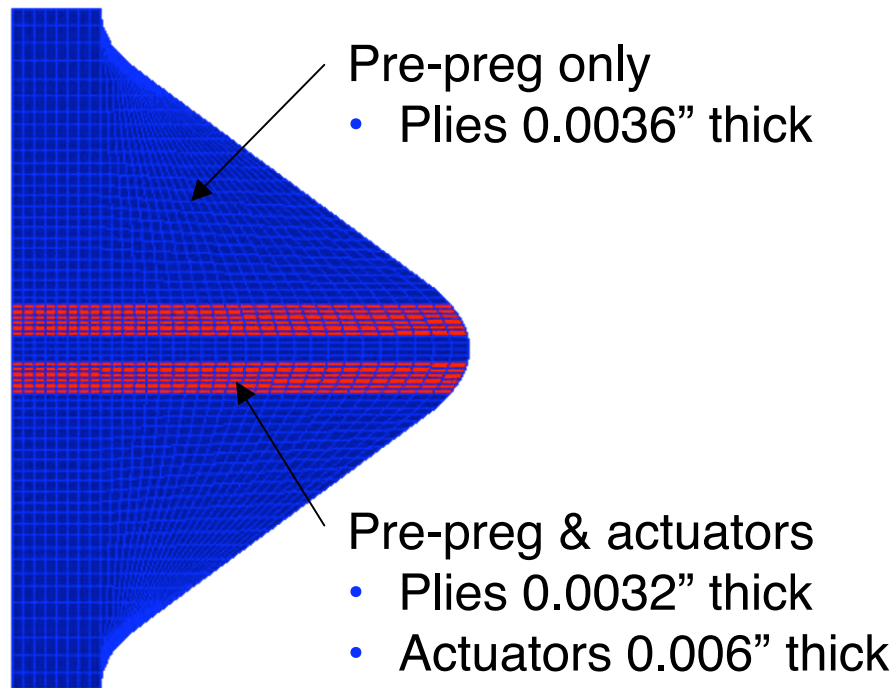
**TRAVIS TURNER**

**STRUCTURAL ACOUSTICS BRANCH  
NASA LANGLEY RESEARCH CENTER  
HAMPTON, VA**

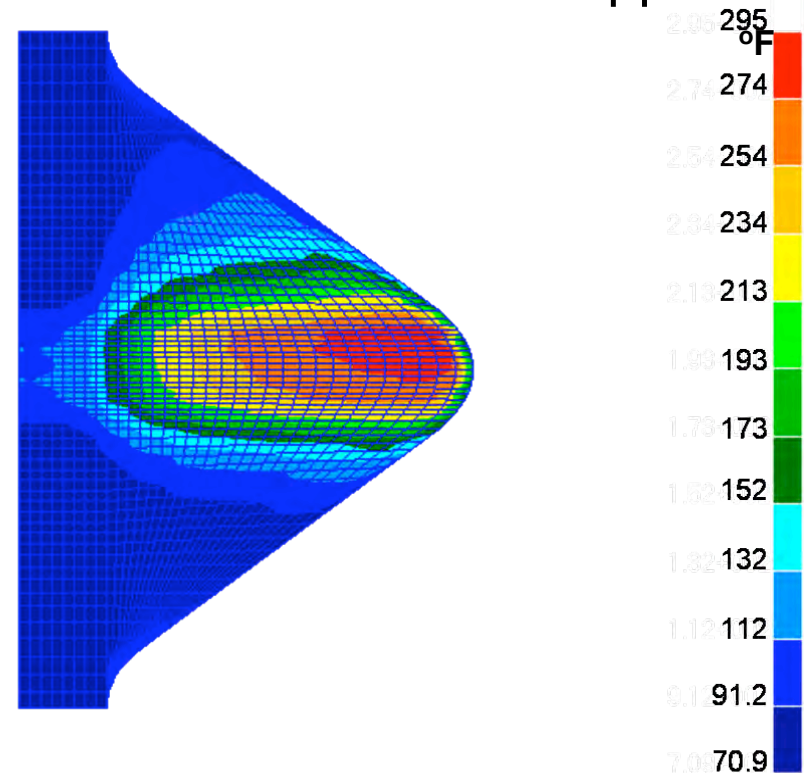


# NUMERICAL MODEL

## Shell Element Mesh



## Meas. Thermal Load Applied



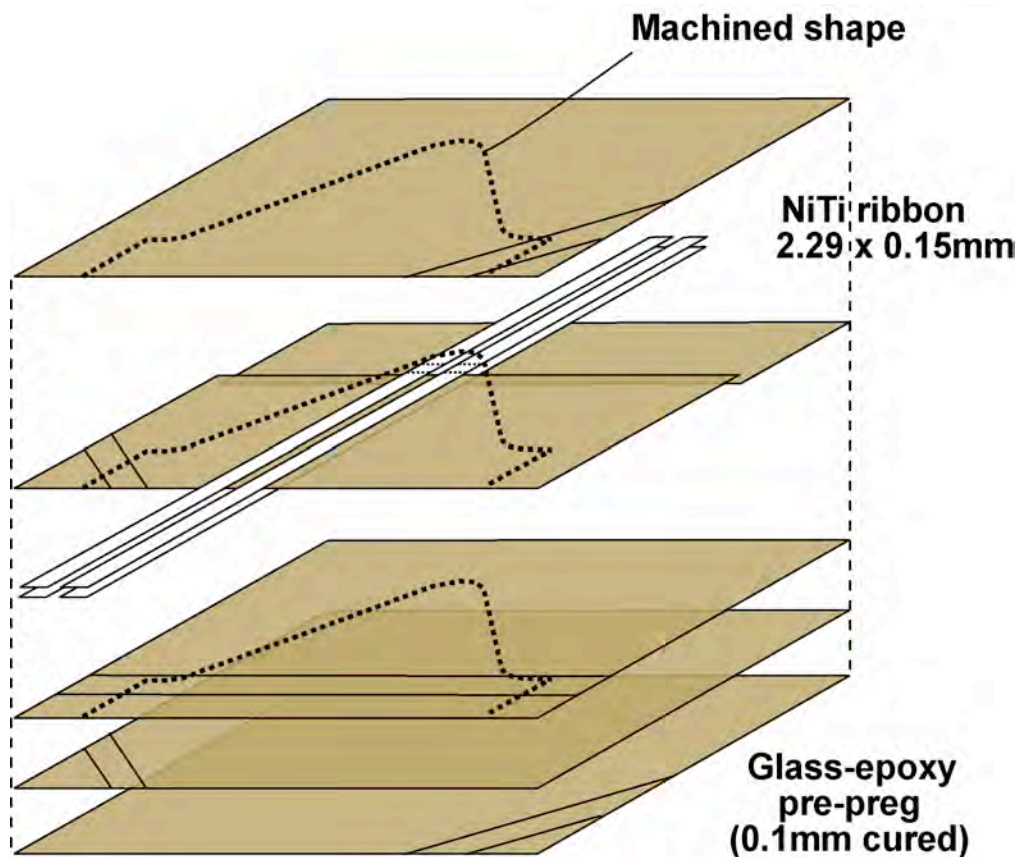
- Developed thermo-mechanical FE model based upon LaRC-developed constitutive model implemented in MSC.Nastran and ABAQUS
- Shell element mesh separates glass-epoxy-only and SMAHC element types
- Nonlinear static solution performed with imposed temperature load specified by experimental measurements at critical temperatures



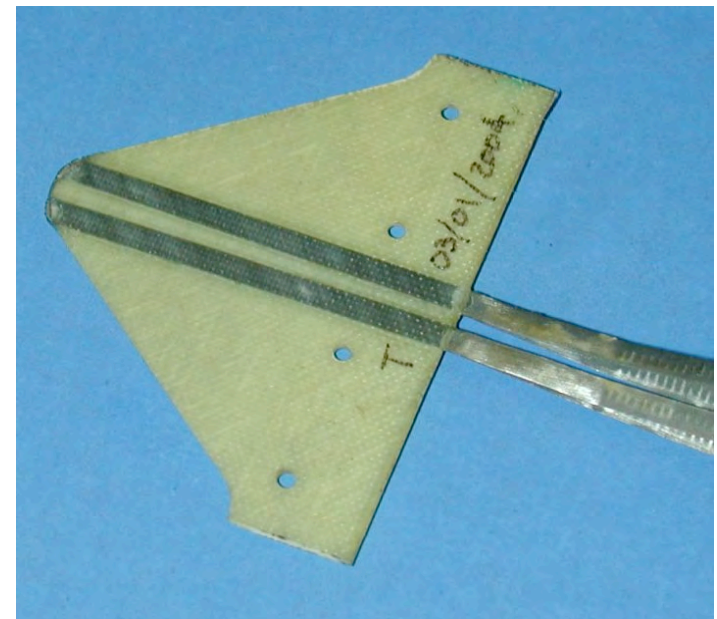


# STRUCTURAL DEFLECTION CONTROL

Actuators embedded within layers of a laminated composite structure



Completed Flow Effector

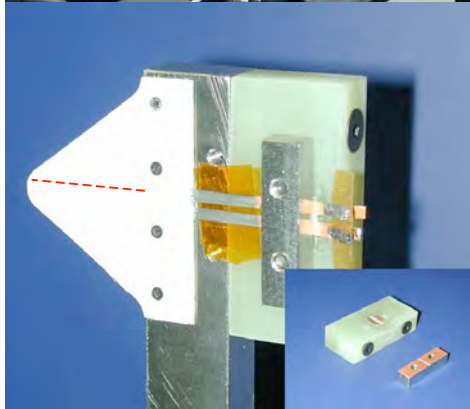
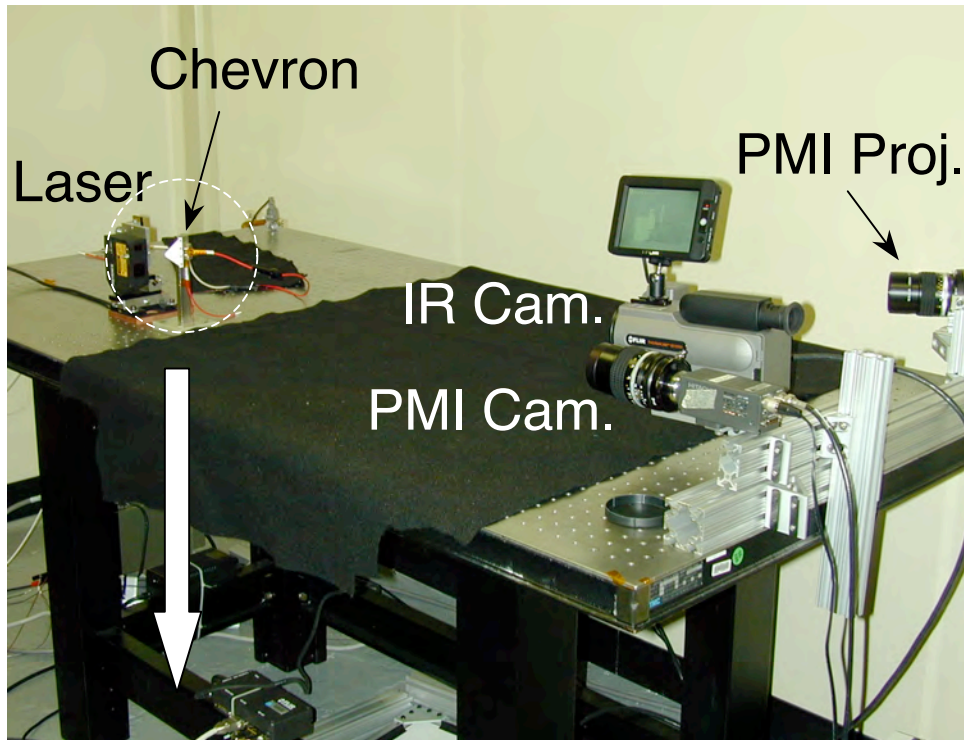


- Discrete actuator “inclusion”
- Non-uniform consolidated pre-preg ply thickness
- Non-uniform temperature distribution in service

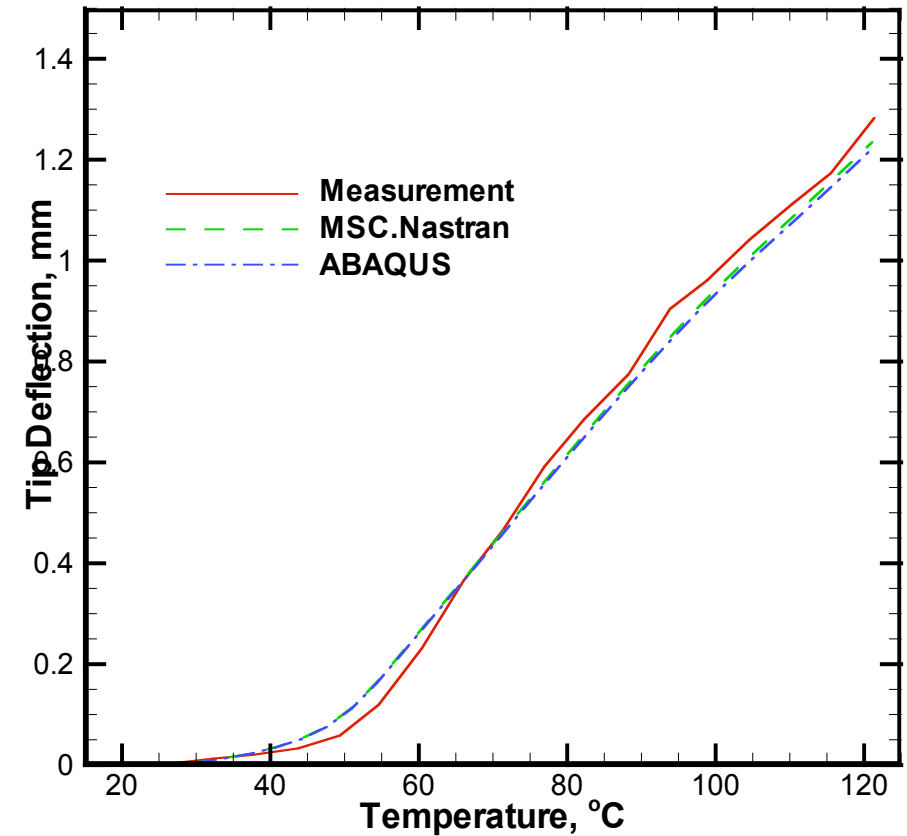
# Flow Effector Deflection Control



## Bench Top Test System



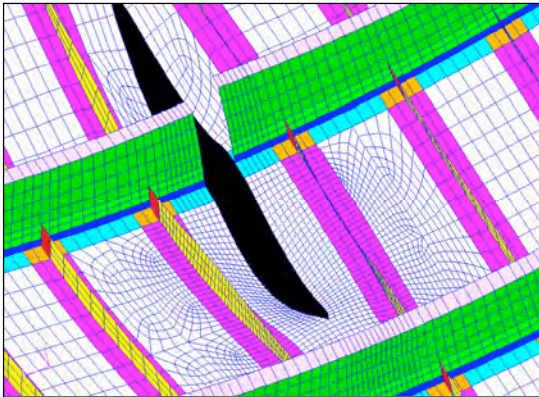
## Tip Deflection Comparison



- Excellent numerical-experimental agreement
- Numerical design tool validated

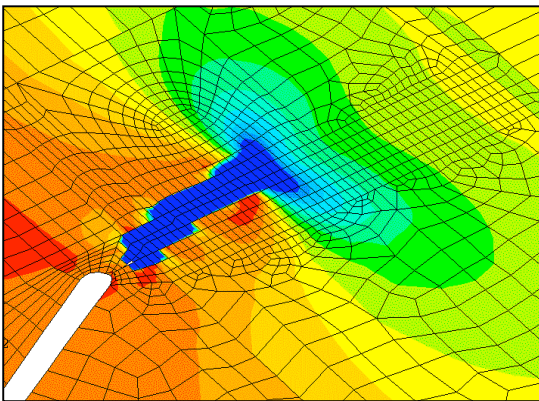


# DAMAGE ANALYSES OF COMPOSITES



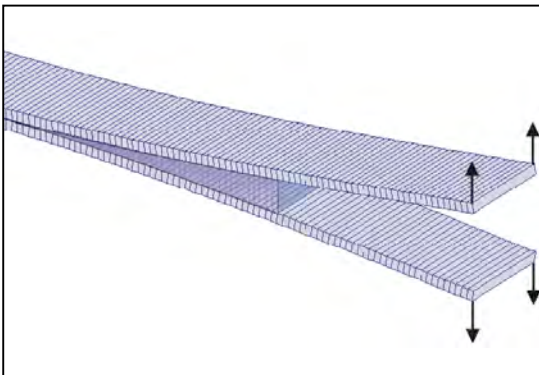
## Through-the-thickness crack

- fracture mechanics and modifications
- strain softening



## Ply Damage

- continuum damage modeling (CDM)
- strength-based methods (criteria)
- micromechanics approach



## Delamination/Debonding

- fracture mechanics approaches (VCCT)
- decohesion elements



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# **PROGRESSIVE FAILURE MATERIAL MODEL**

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# PFA/PDA SIMULATIONS

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- Develop user-defined material subroutine UMAT for PFA and user-defined element subroutine UEL for PDA using ABAQUS/Standard
- UMAT features linear elastic, bimodulus, orthotropic material model for a composite laminate
- Failure initiation based on material allowable values using:
  - Maximum stress criteria
  - Maximum strain criteria
  - Hashin criteria
  - Tsai-Wu polynomial failure criterion
- Material degradation based on degrading elastic material stiffness coefficients for a particular failure direction resulting in near zero stress for that component - rather than degrading engineering properties
- Material degradation can be instantaneous or recursive over several solution steps
- Delamination and crack growth modeling using Boeing fracture interface element (VCCT approach) using user-defined element subroutine UEL



# TYPICAL FAILURE INITIATION CRITERIA

- **Maximum stress criteria**

$$\frac{\sigma_{11}}{X_T} \leq 1 \text{ for } \sigma_{11} \geq 0; \quad \frac{|\sigma_{11}|}{X_C} \leq 1 \text{ for } \sigma_{11} \leq 0$$

$$\frac{\sigma_{22}}{Y_T} \leq 1 \text{ for } \sigma_{22} \geq 0; \quad \frac{|\sigma_{22}|}{Y_C} \leq 1 \text{ for } \sigma_{22} \leq 0$$

$$\frac{\sigma_{33}}{Z_T} \leq 1 \text{ for } \sigma_{33} \geq 0; \quad \frac{|\sigma_{33}|}{Z_C} \leq 1 \text{ for } \sigma_{33} \leq 0$$

$$\frac{|\tau_{12}|}{S_{XY}} \leq 1; \quad \frac{|\tau_{23}|}{S_{YZ}} \leq 1; \quad \frac{|\tau_{13}|}{S_{XZ}} \leq 1$$

- **Tsai-Wu polynomial failure criterion**

$$\begin{aligned} \phi = & F_1\sigma_{11} + F_2\sigma_{22} + F_3\sigma_{33} + F_{11}(\sigma_{11})^2 + F_{22}(\sigma_{22})^2 + F_{33}(\sigma_{33})^2 \\ & + 2F_{12}\sigma_{11}\sigma_{22} + 2F_{23}\sigma_{22}\sigma_{33} + 2F_{13}\sigma_{11}\sigma_{33} \\ & + F_{44}(\sigma_{13})^2 + F_{55}(\sigma_{23})^2 + F_{66}(\sigma_{12})^2 \geq 1 \end{aligned}$$



# TYPICAL MATERIAL DEGRADATION

- 3D stress-strain relations

$$\begin{Bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \\ \sigma_{13} \\ \sigma_{23} \end{Bmatrix} = \begin{bmatrix} C_{11} & C_{12} & C_{13} & 0 & 0 & 0 \\ C_{12} & C_{22} & C_{23} & 0 & 0 & 0 \\ C_{13} & C_{23} & C_{33} & 0 & 0 & 0 \\ 0 & 0 & 0 & C_{44} & 0 & 0 \\ 0 & 0 & 0 & 0 & C_{55} & 0 \\ 0 & 0 & 0 & 0 & 0 & C_{66} \end{bmatrix} \begin{Bmatrix} \epsilon_{11} \\ \epsilon_{22} \\ \epsilon_{33} \\ \gamma_{12} \\ \gamma_{13} \\ \gamma_{23} \end{Bmatrix}$$

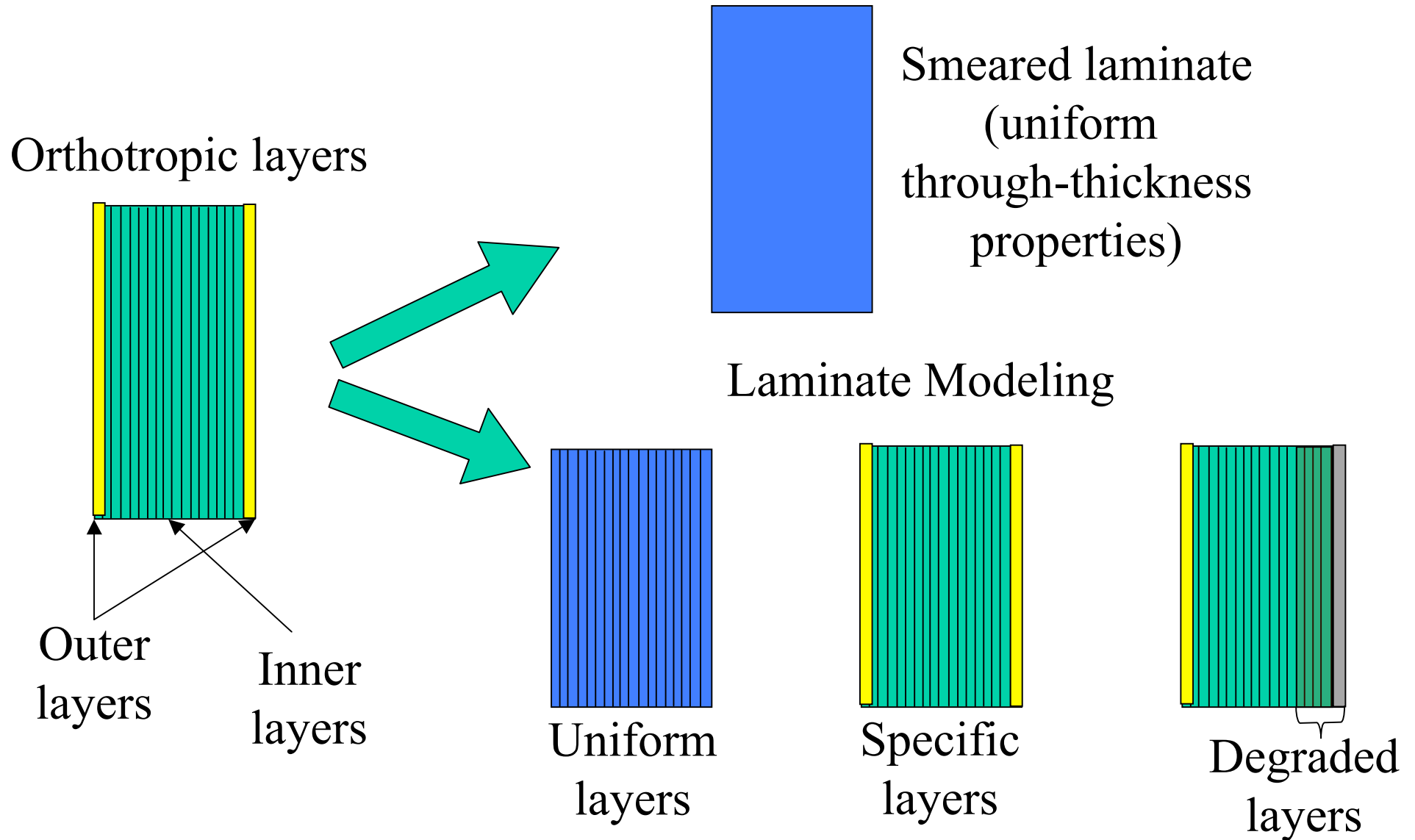
- Material degradation of the  $i^{th}$  row and column of the constitutive matrix [C] when the  $i^{th}$  stress component indicates failure
- Off-diagonal terms set to zero; diagonal term degraded by factor  $b_i$

$$C_{ij}^{\text{degraded}} = C_{ji}^{\text{degraded}} = 0 \text{ for } i \neq j$$

$$C_{ii}^{\text{degraded}} = \beta_i C_{ii}$$



# MATERIAL MODELING OPTIONS







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# **THE VIRTUAL CRACK CLOSURE TECHNIQUE**

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HAMPTON, VA**

**Resident at Durability, Damage Tolerance and  
Reliability Branch, NASA Langley Research Center**



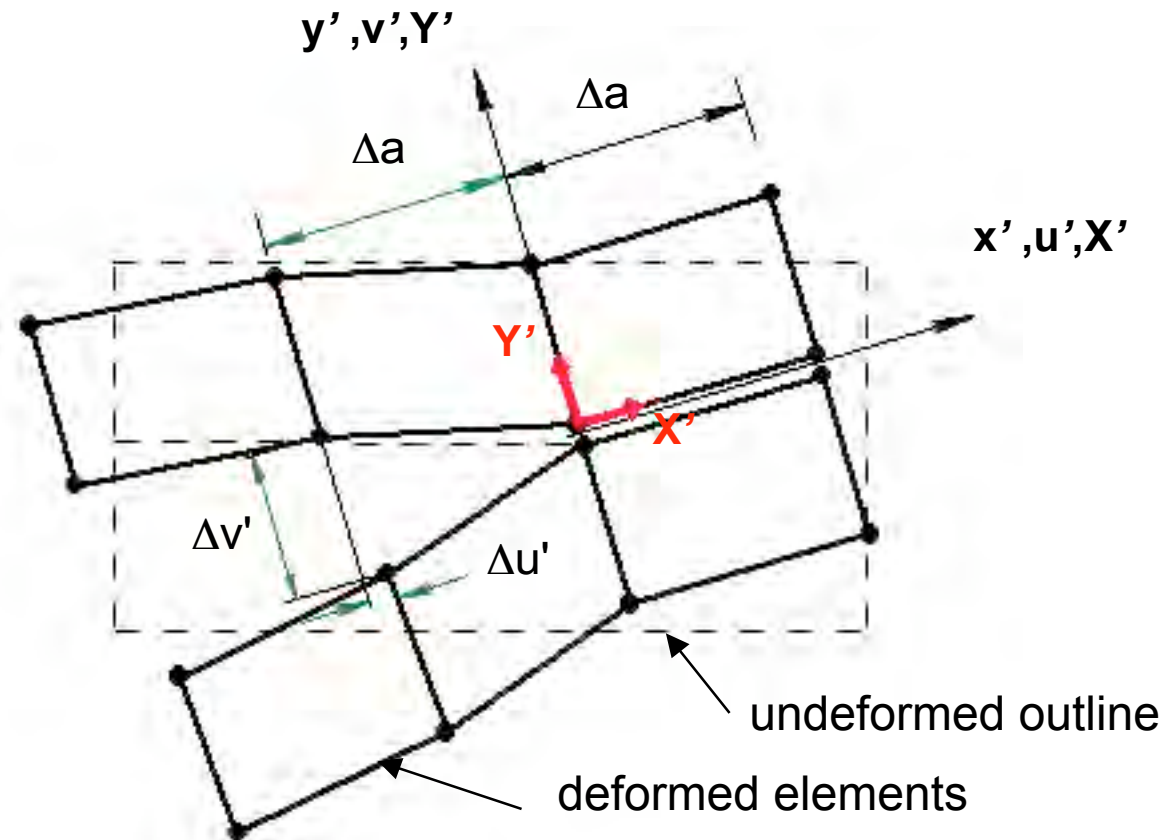
# VIRTUAL CRACK CLOSURE TECHNIQUE (VCCT)\*

- Two and three-dimensional analysis
- Nonlinear analysis
- Arbitrarily shaped delamination front
- 2D Finite Element Analysis

$$G_I = \frac{1}{2\Delta a} \cdot Y' \cdot \Delta v'$$

$$G_{II} = \frac{1}{2\Delta a} \cdot X' \cdot \Delta u'$$

$$G_T = G_I + G_{II}$$

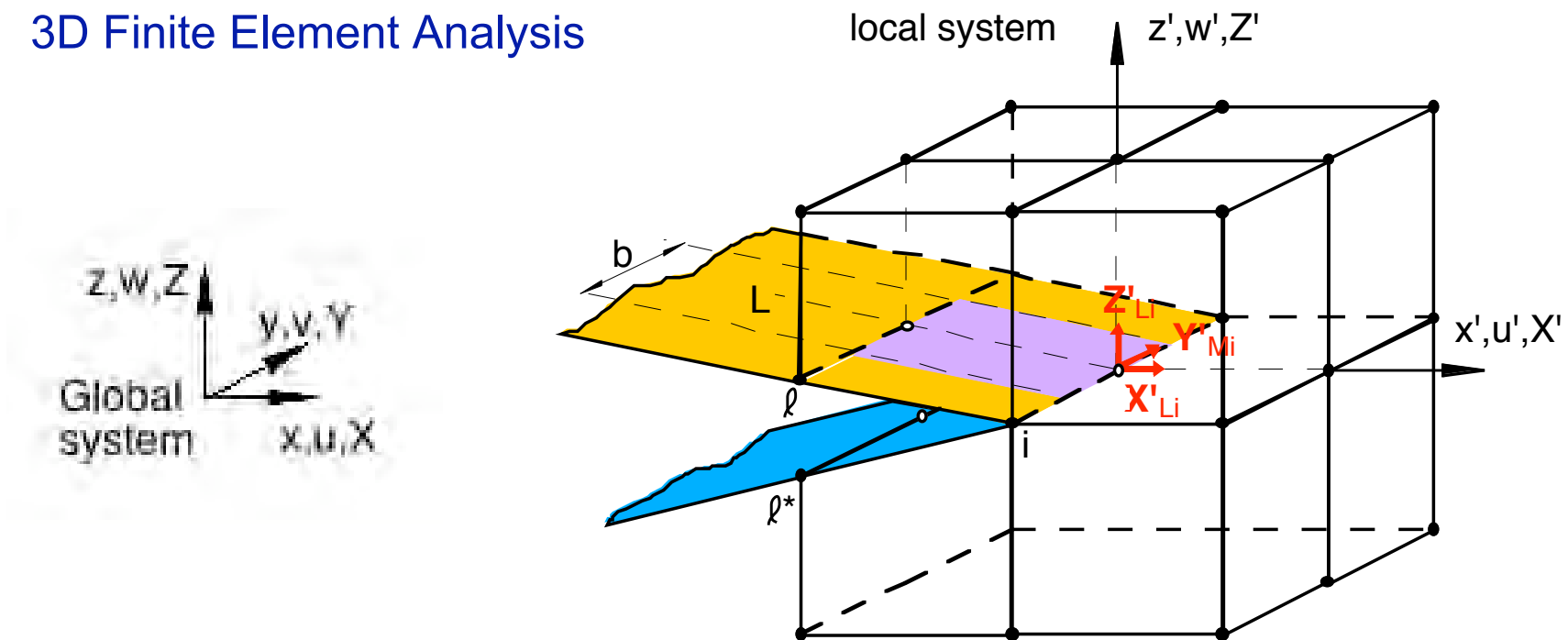


\*Rybicki and Kanninen, Engineering Fracture Mechanics, 1977

# VIRTUAL CRACK CLOSURE TECHNIQUE - CONTINUED



- 3D Finite Element Analysis



$$G_I = \frac{1}{2\Delta ab} \cdot Z'_{Li} \cdot (w'_{Ll} - w'_{Ll^*})$$

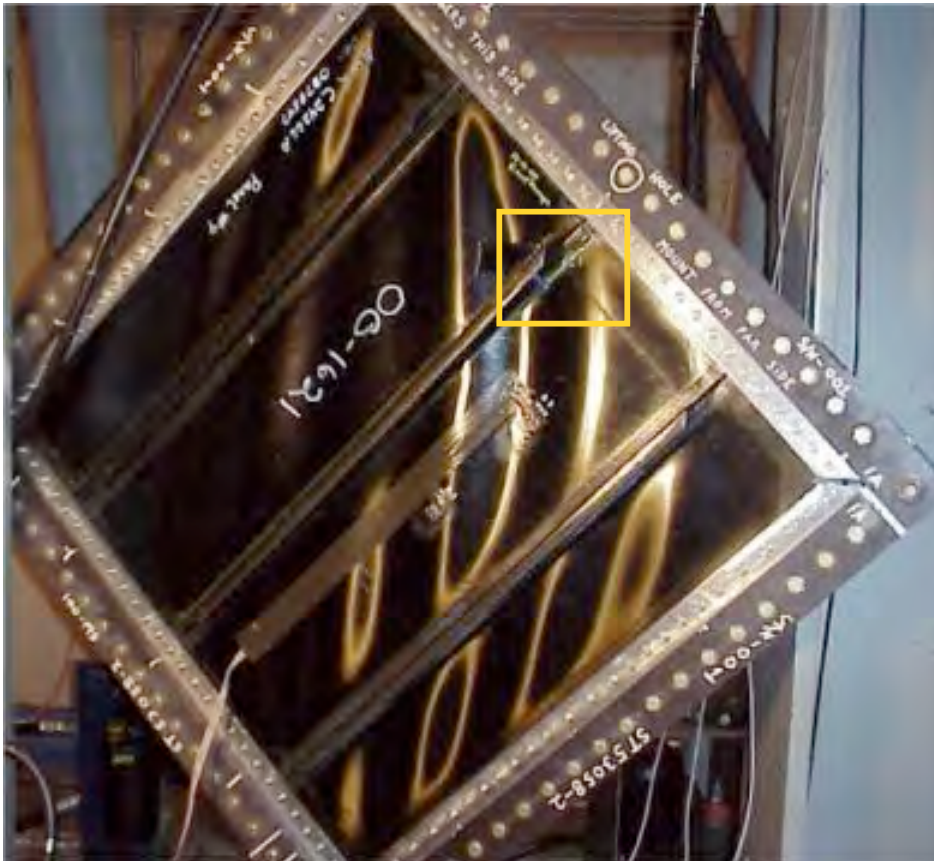
$$G_{II} = \frac{1}{2\Delta ab} \cdot X'_{Li} \cdot (u'_{Ll} - u'_{Ll^*})$$

$$G_{III} = \frac{1}{2\Delta ab} \cdot Y'_{Li} \cdot (v'_{Ll} - v'_{Ll^*})$$

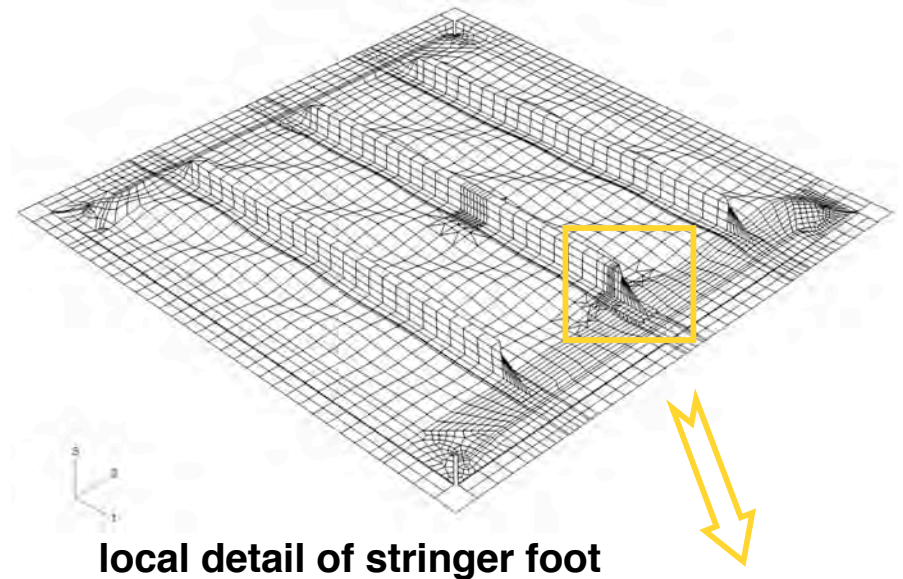
# STRINGER STIFFENED PANEL SUBJECTED TO SHEAR LOADING



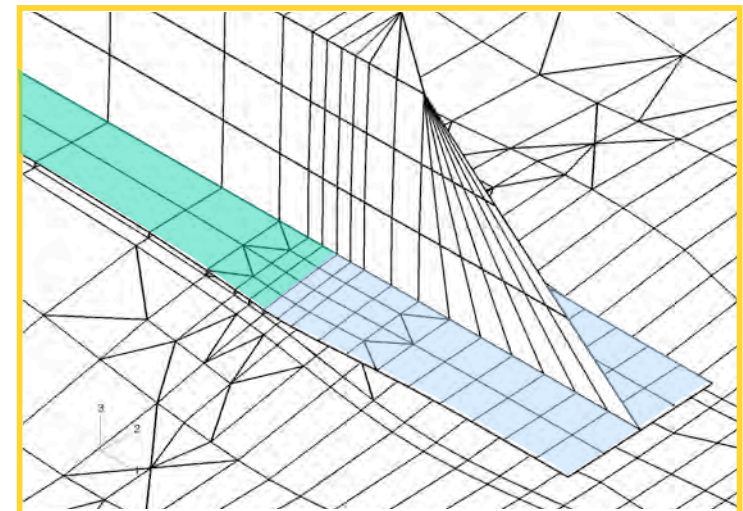
- Testing of Stiffened Shear Panel Boeing, Philadelphia\*



- Original Boeing ABAQUS Shell Model\*



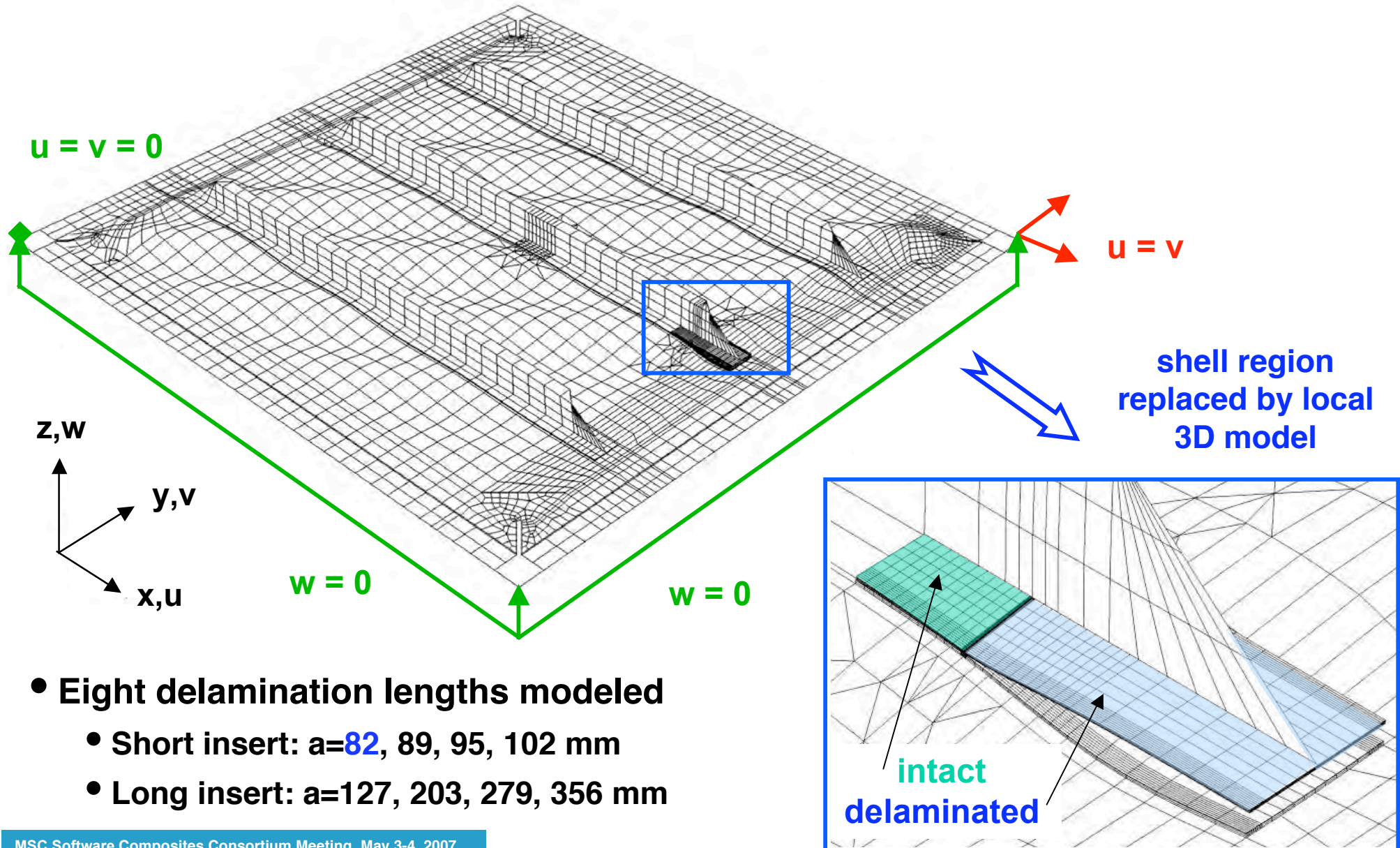
local detail of stringer foot



\*Pierre Minguet, Boeing



# SHELL FE-MODEL WITH LOCAL 3D MODEL

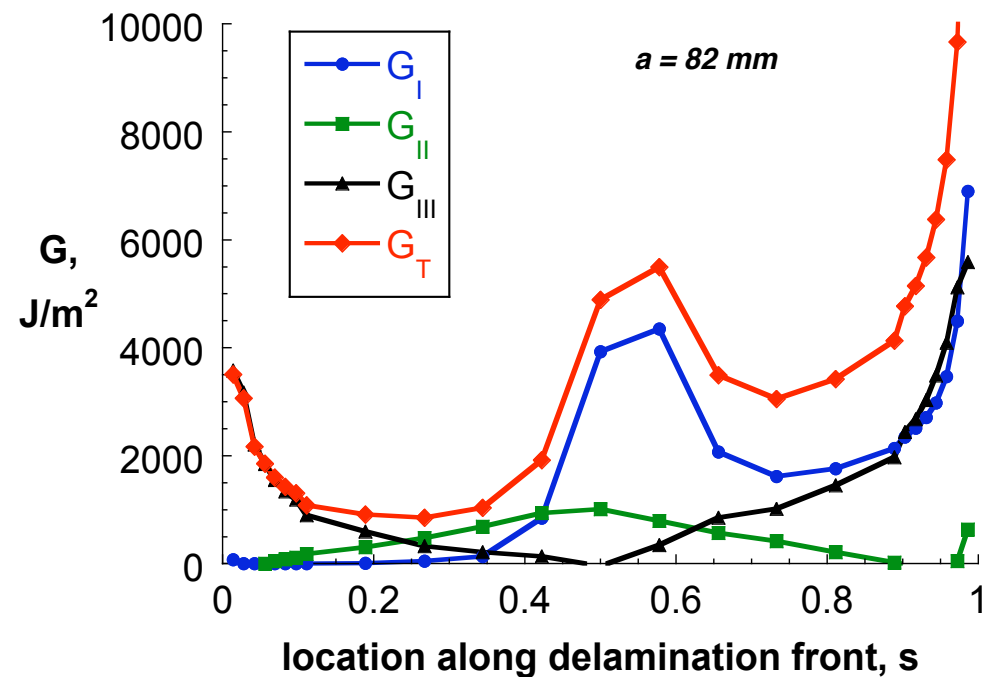
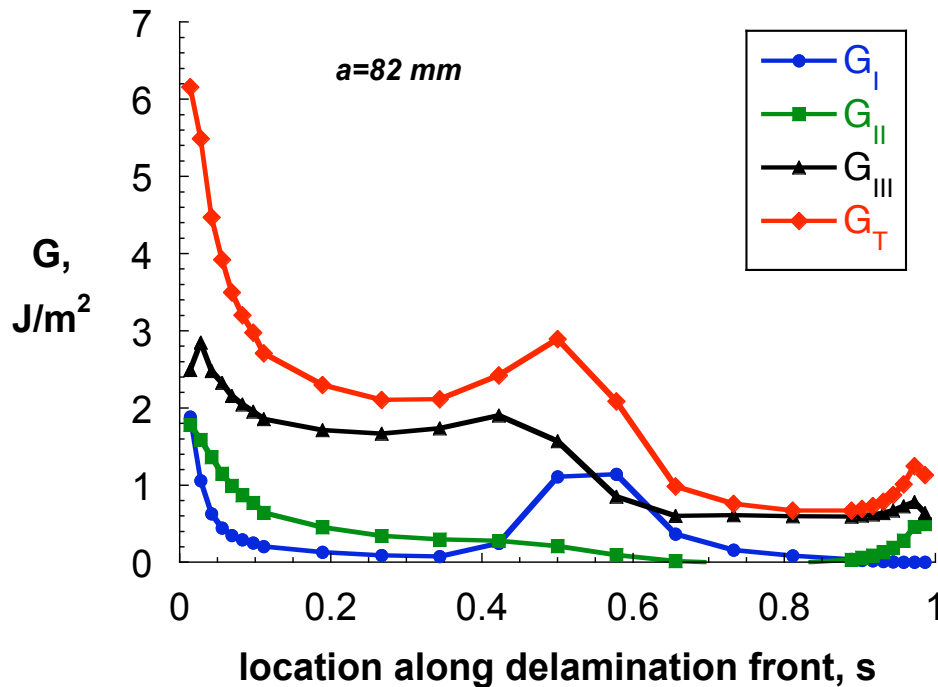
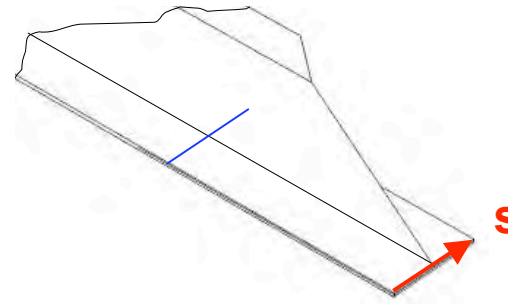




# COMPUTED ENERGY RELEASE RATES

- Increment 5,  $u = v = 0.2$  mm, 3.3 %

- Increment 41,  $u = v = 6.35$  mm, 100%





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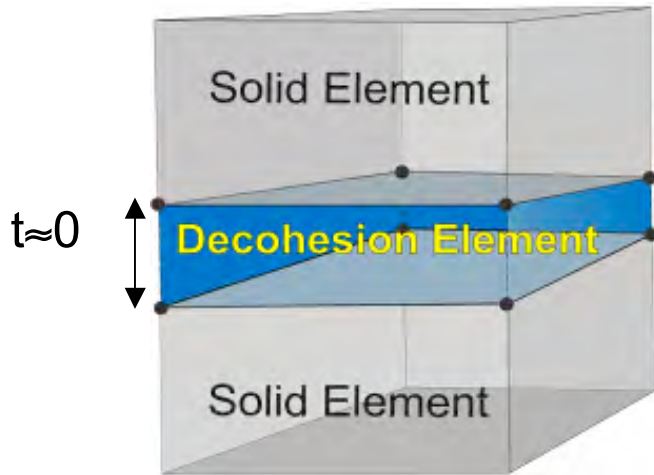
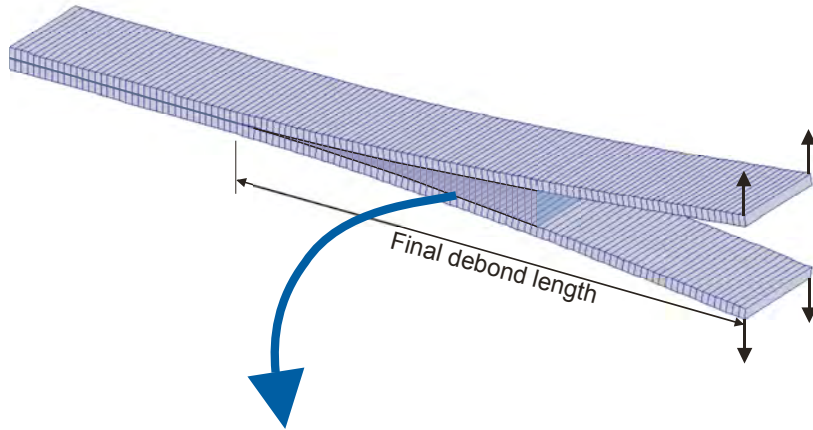
# **DECOHESION ELEMENTS FOR SIMULATING DELAMINATION**

**CARLOS DAVILA**

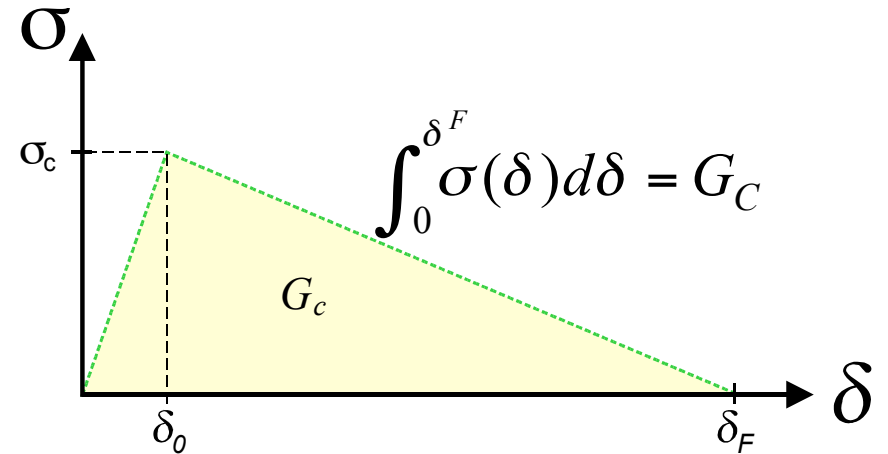
**DURABILITY, DAMAGE TOLERANCE AND  
RELIABILITY BRANCH  
NASA LANGLEY RESEARCH CENTER  
HAMPTON, VA**



# DECOHESION FINITE ELEMENT

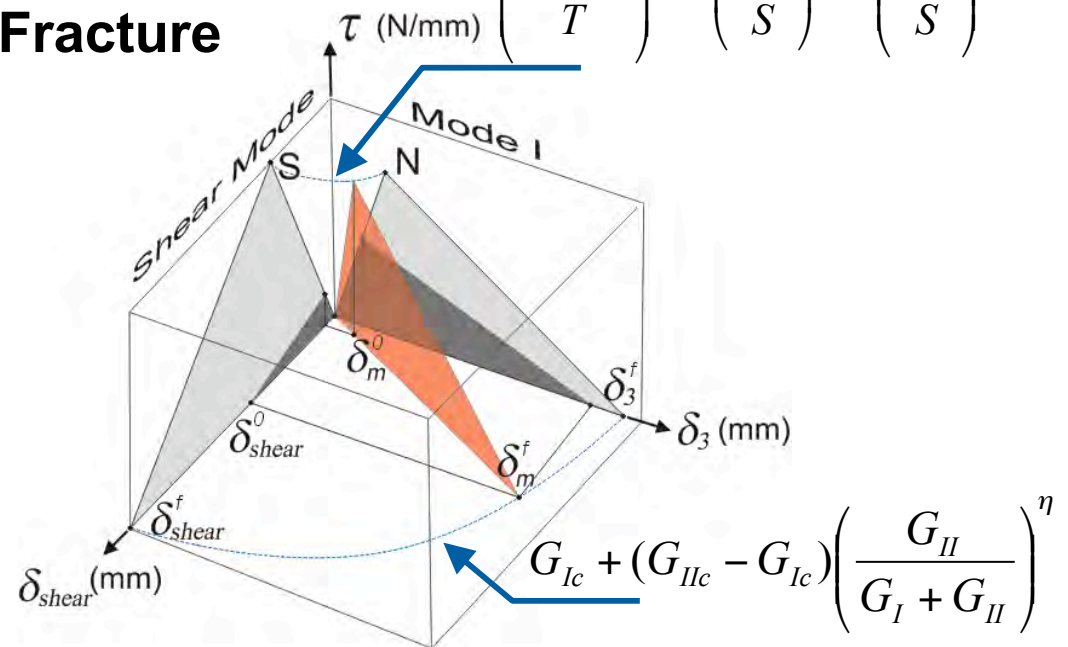


## Bilinear Traction-Displacement Law



## Mixed-Mode Fracture

$$\left( \frac{\langle \sigma_z \rangle_+}{T} \right)^2 + \left( \frac{\tau_{xz}}{S} \right)^2 + \left( \frac{\tau_{yz}}{S} \right)^2 = 1$$



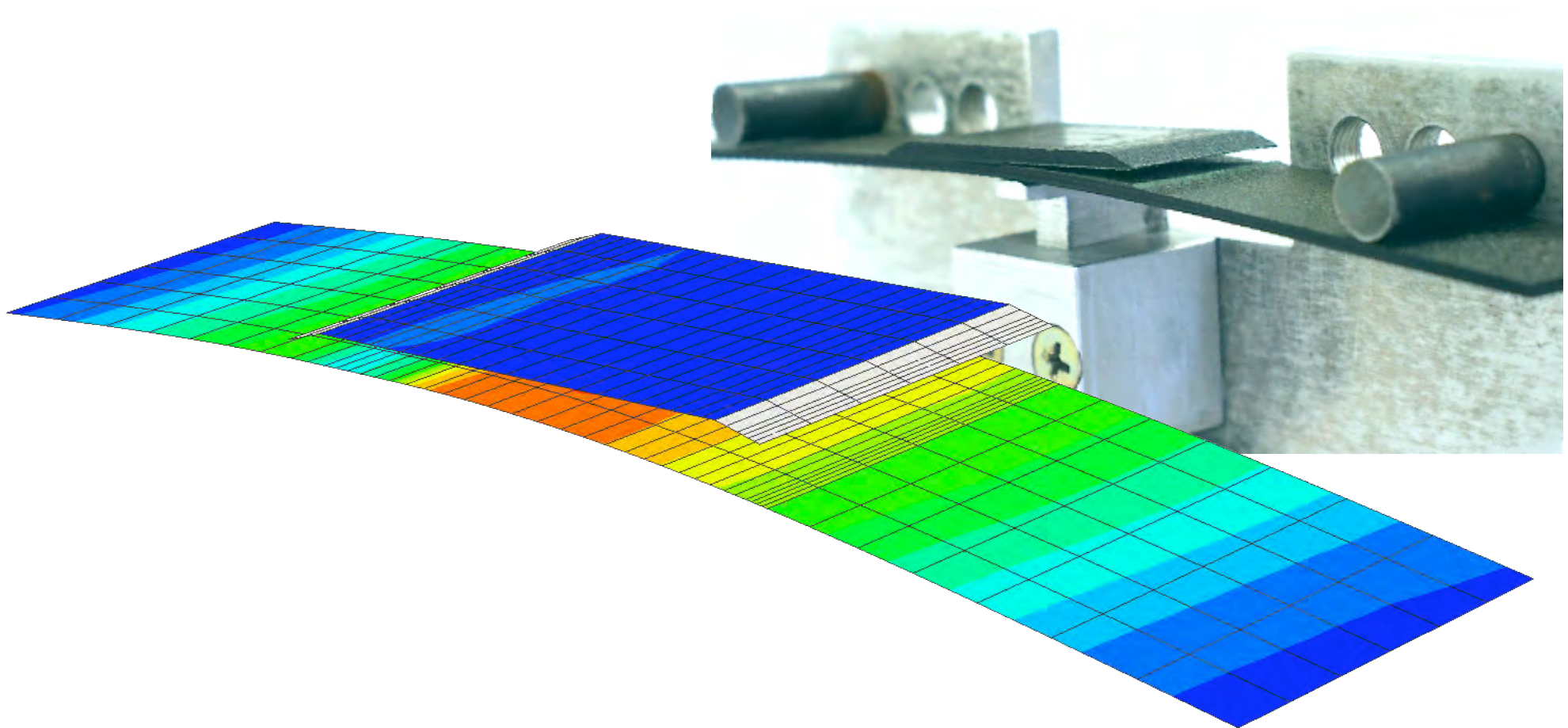




# SKIN / STRINGER SEPERATION SPECIMEN

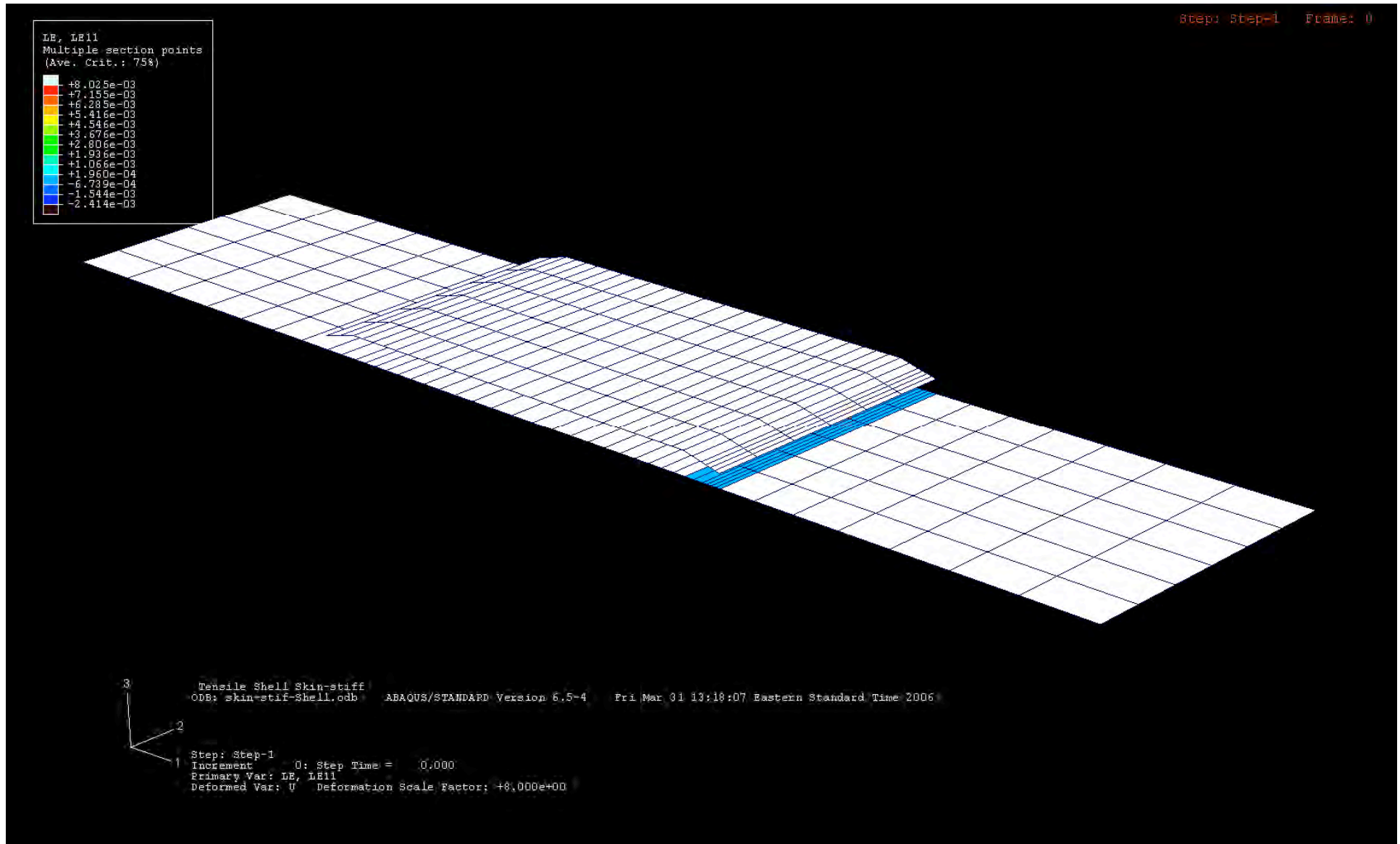
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**Decohesion elements used to predict delamination in skin / stringer specimen**





# SKIN / STRINGER SEPERATION SPECIMEN



# NTSB Board Meeting AA Flight 587



## Structures Investigation

Brian K. Murphy - NTSB

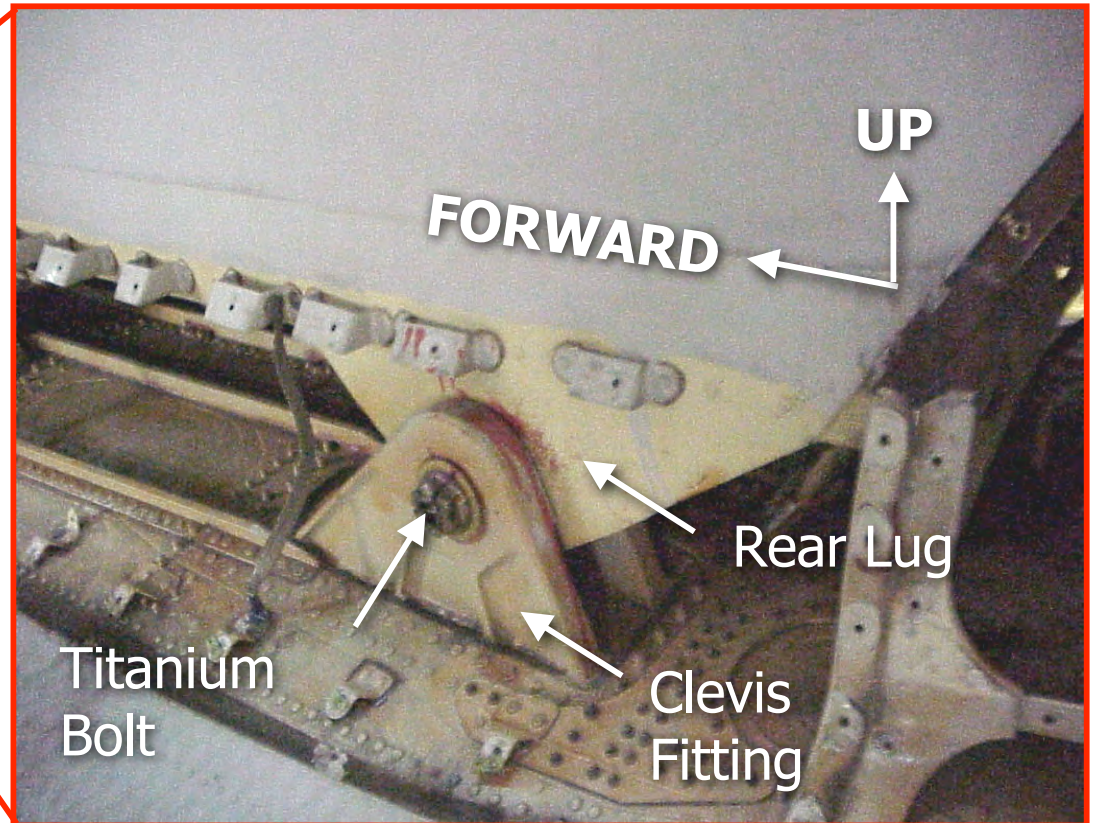
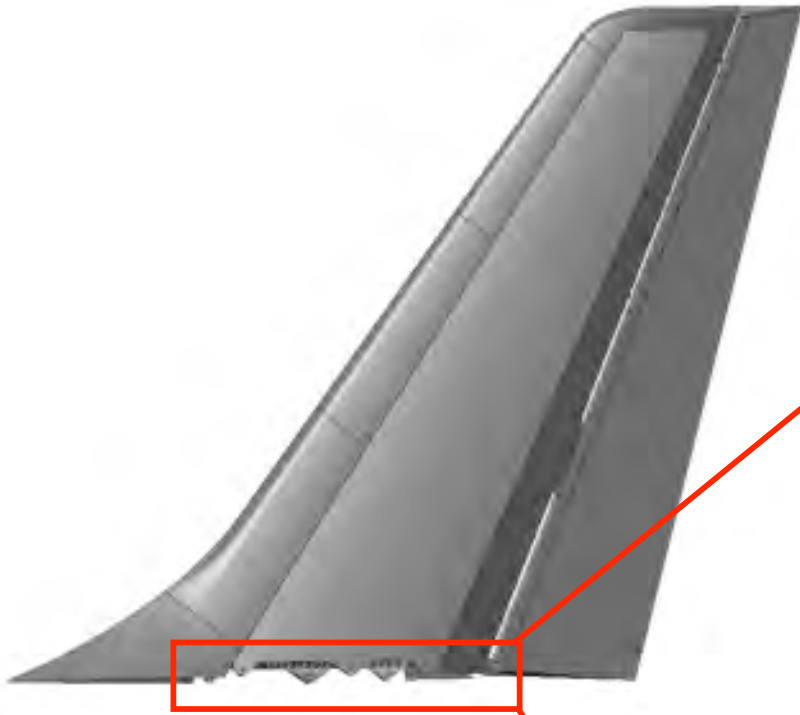
Detailed Lug Analysis Team -  
NASA LaRC







# MAIN ATTACHMENT FITTINGS





# LUG STRENGTH DETERMINATION

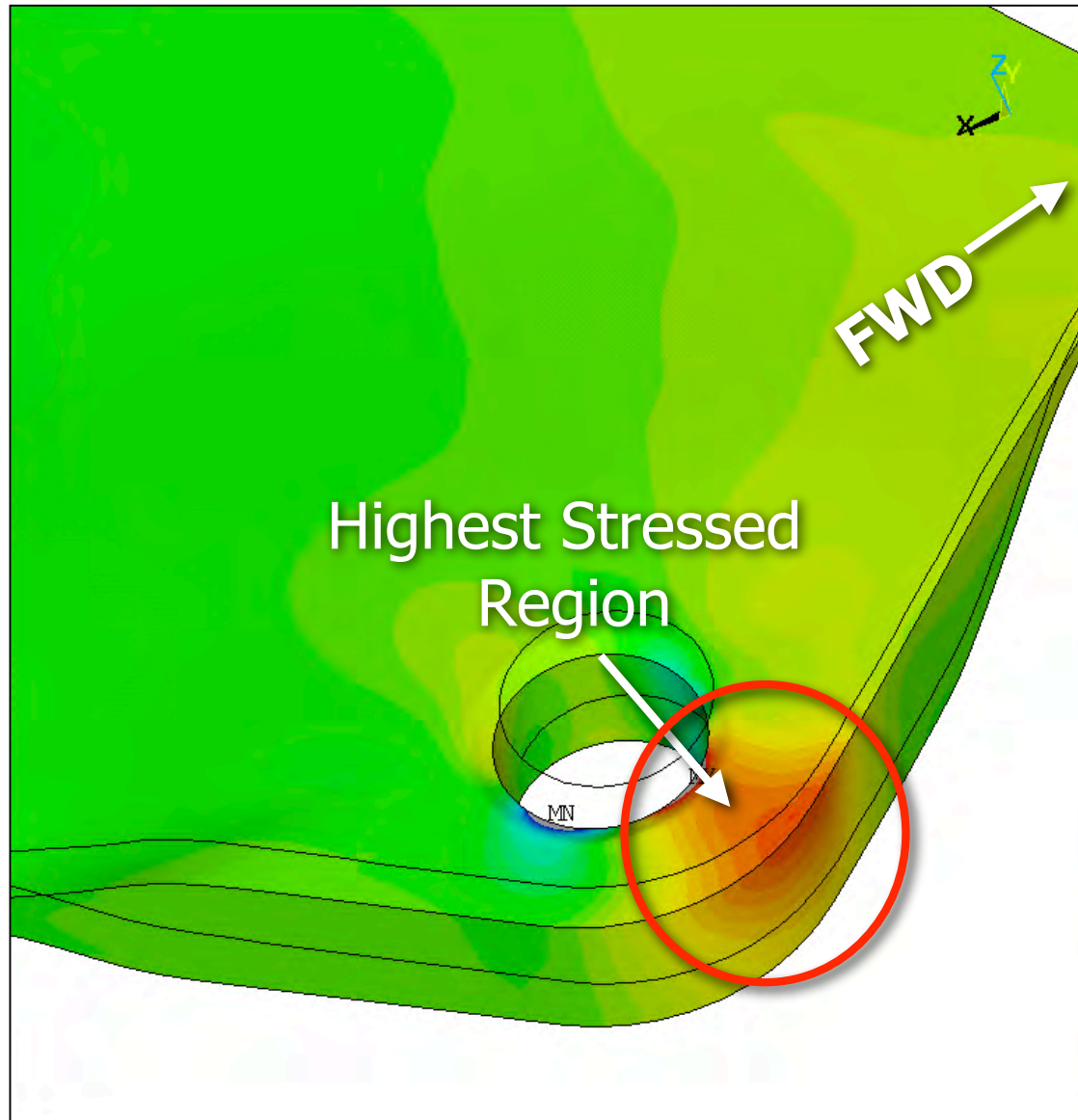
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**The strength of the lug was determined by:**

- Finite element analysis
- Progressive failure analysis
- Post accident lug tests

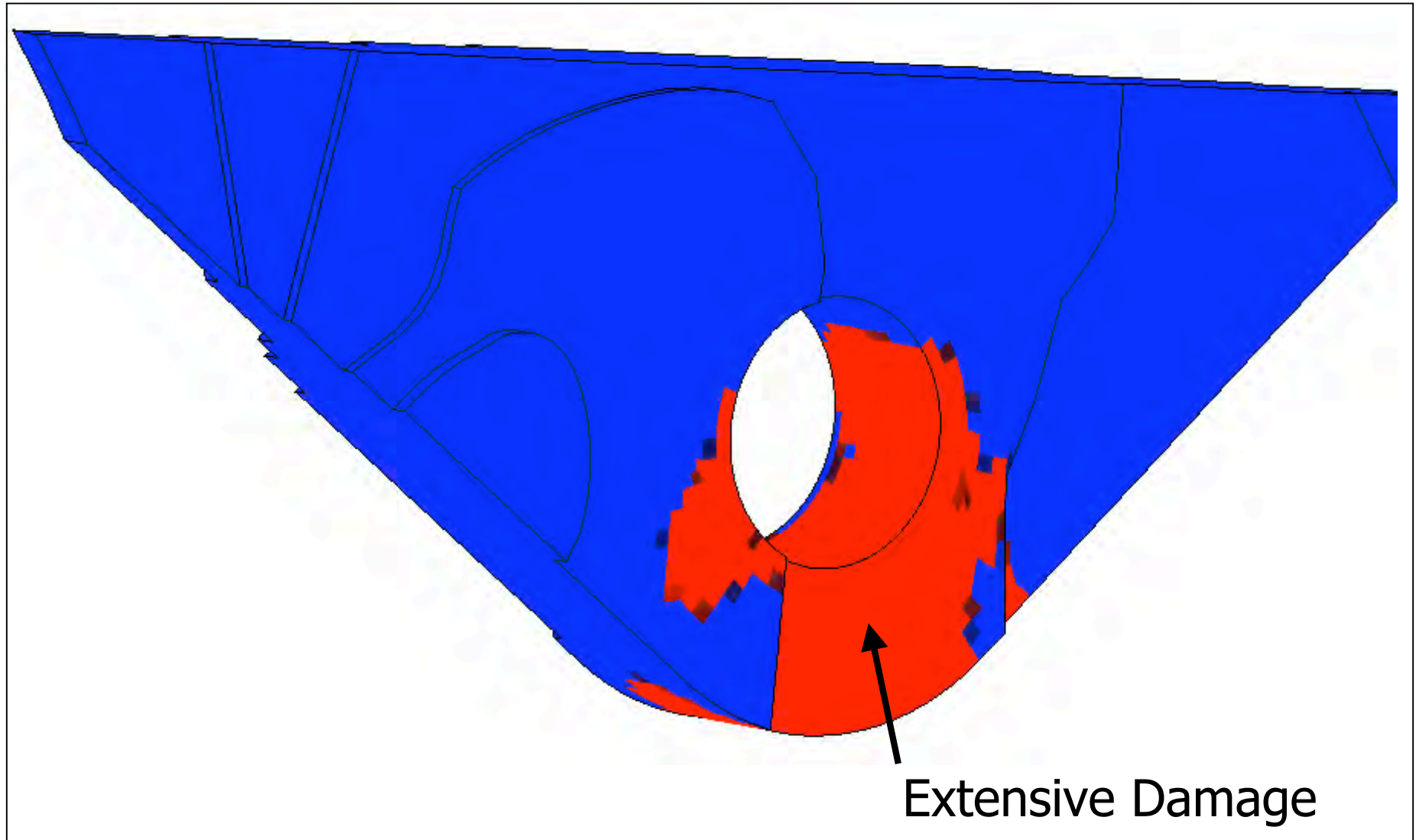


# FINITE ELEMENT ANALYSIS OF THE LUG





# PROGRESSIVE FAILURE ANALYSIS





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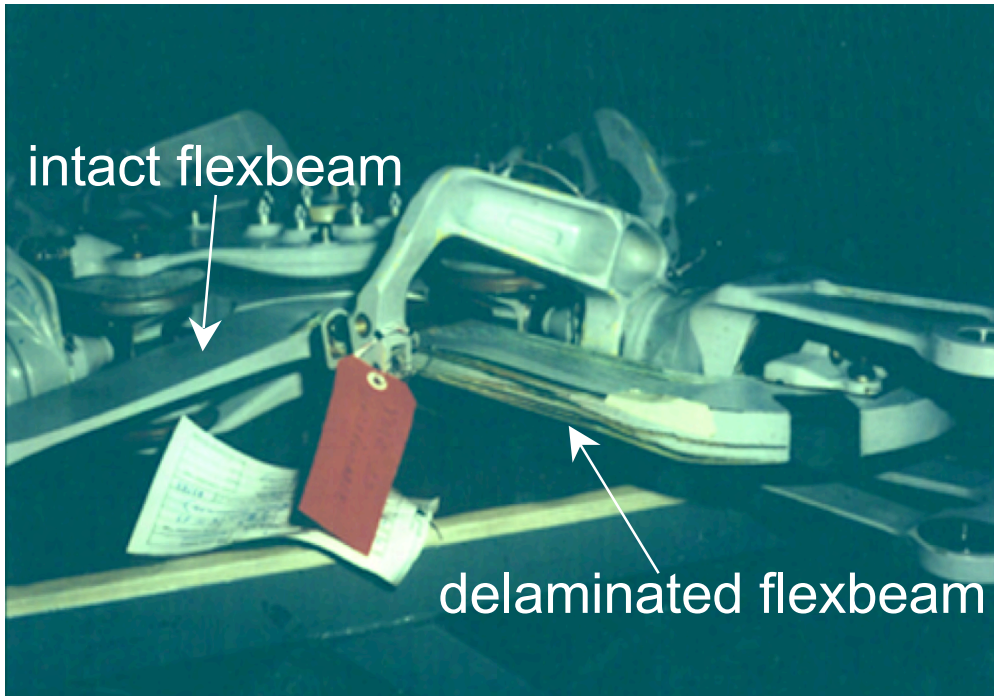
# **FINITE ELEMENT MODEL OF DELAMINATION IN A ROTORHUB FLEXBEAM**

**GRETCHEN MURRI  
U.S. ARMY RESEARCH LABORATORY, VEHICLE  
TECHNOLOGY DIRECTORATE**

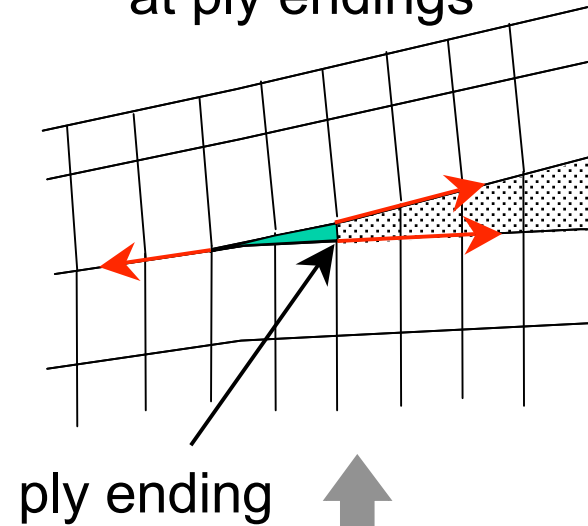
**Resident at Durability, Damage Tolerance and Reliability  
Branch, NASA Langley Research Center**



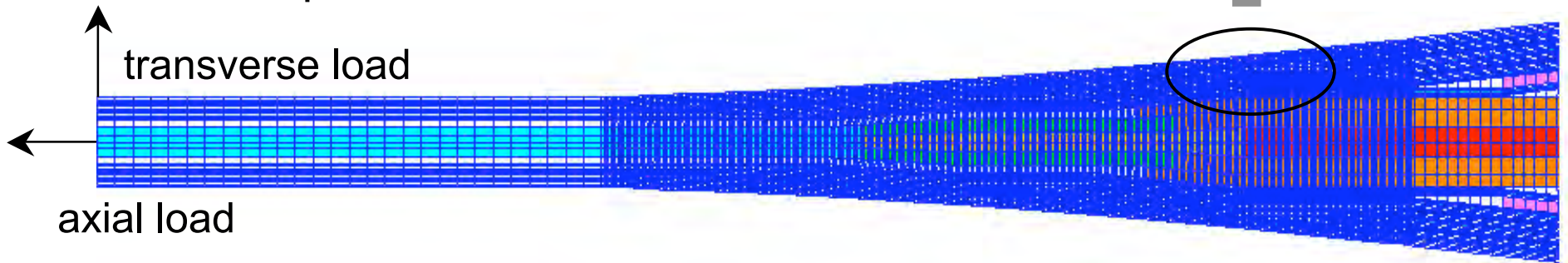
# FINITE ELEMENT MODEL OF DELAMINATION IN A ROTORHUB FLEXBEAM



Delaminations initiate at ply endings



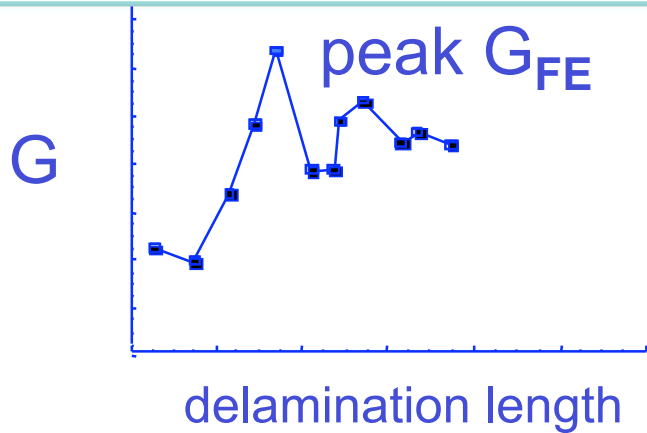
Helicopter Rotorhub



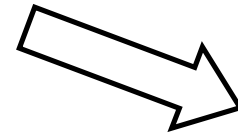
Finite element model of flexbeam with internal ply-drops



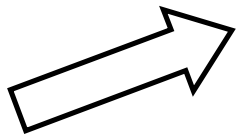
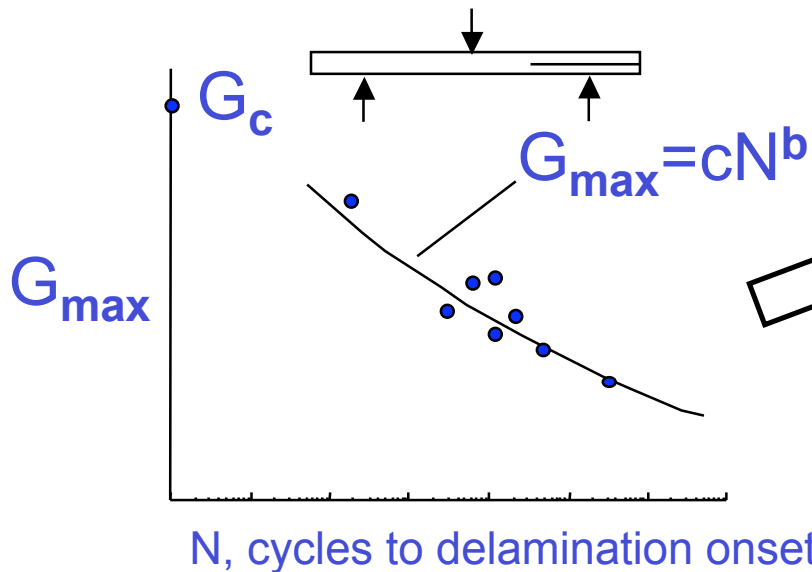
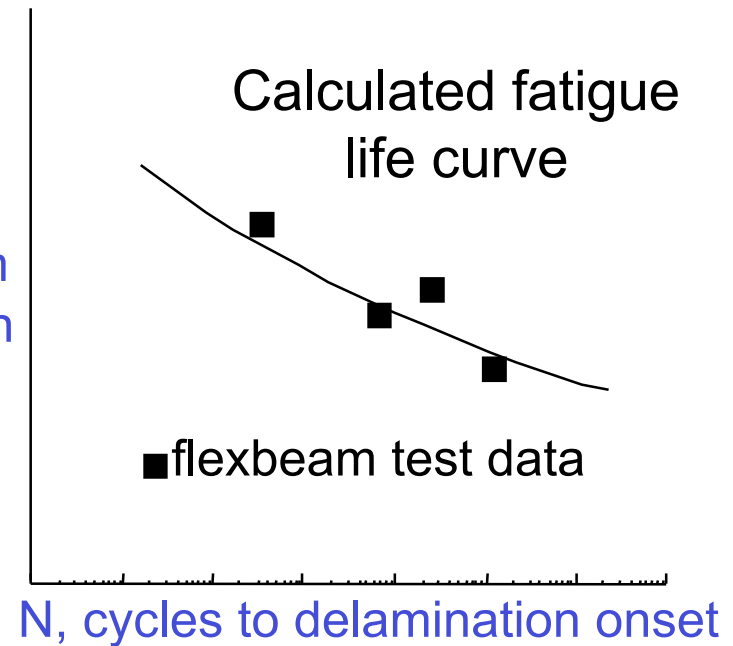
# FLEXBEAM FATIGUE LIFE METHODOLOGY



VCCT used to calculate  $G$  as delamination grows



flex-beam strain



Fatigue toughness data for modeled material



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# **MIXED-MODE FAILURE CRITERIA FOR DELAMINATION IN COMPOSITE LAMINATES**

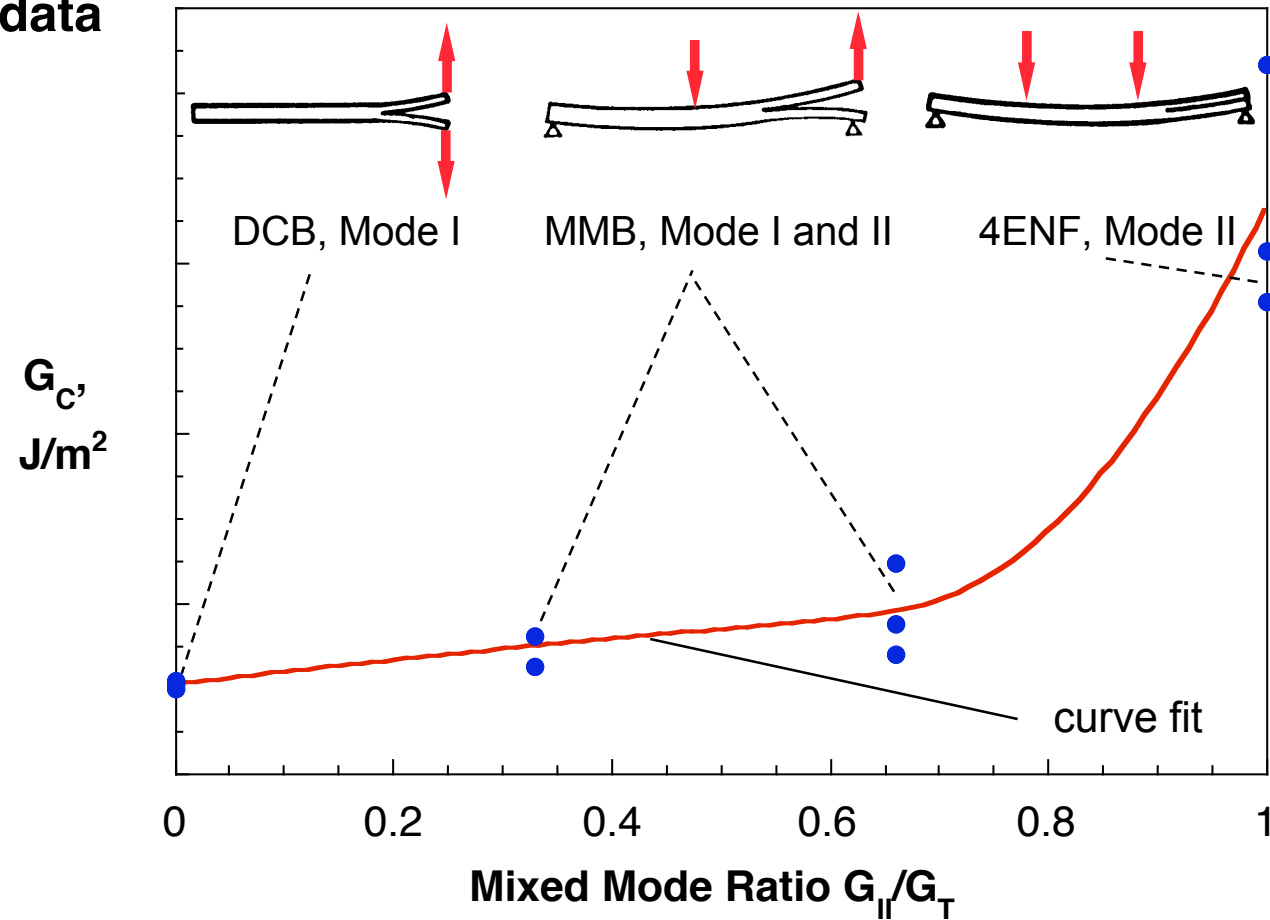
**JAMES REEDER**

**NASA LANGLEY RESEARCH CENTER  
HAMPTON, VA**



# 2D MIXED MODE FRACTURE CRITERION

- Experimental data



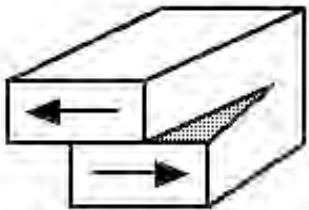
- Curve fit equation by Benzeggagh and Kenane, 1996

$$G_c = \left( G_{Ic} + (G_{IIc} - G_{Ic}) \cdot \left( \frac{G_{II}}{G_T} \right)^\eta \right)$$

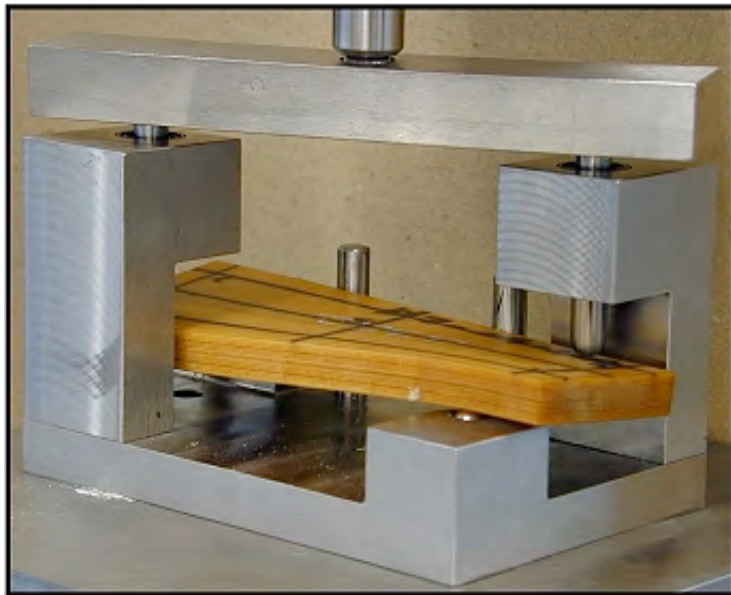


# PROPOSED 3D MIXED MODE FRACTURE CRITERION

- Mode III - ECT Specimen



tearing  
mode III

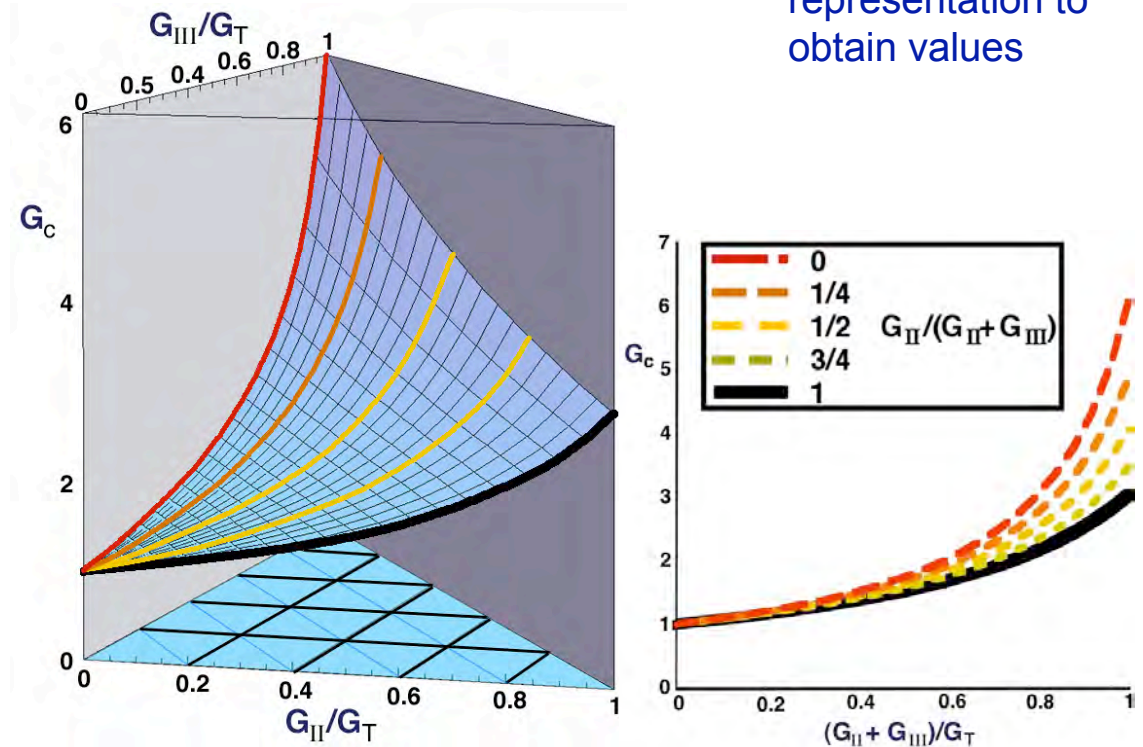


- Proposed 3D failure criterion\*\*

$$\frac{G_{Ic} + (G_{IIc} - G_{Ic}) \left( \frac{G_{II} + G_{III}}{G_T} \right)^\eta + (G_{IIIc} - G_{IIc}) \frac{G_{III}}{G_{II} + G_{III}} \left( \frac{G_{II} + G_{III}}{G_T} \right)^\eta}{G_T} \geq 1$$

- Surface representation

- 2D plot representation to obtain values



\*\*James Reeder, NASA Langley Research Center



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# **ANALYSIS TO PREDICT DELAMINATION IN Z-PIN REINFORCED LAMINATES**

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**Resident at Durability, Damage Tolerance and  
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# Z-PIN TECHNOLOGY

## Definition

- Pultruded graphite rods positioned through-thickness (z-direction) of a composite laminate
- Pins are 0.2-0.5mm diameter rods
- Typical range of areal density between 0.5% and 4%
- Inserted into uncured laminate using ultrasonic hammer

## Purposes

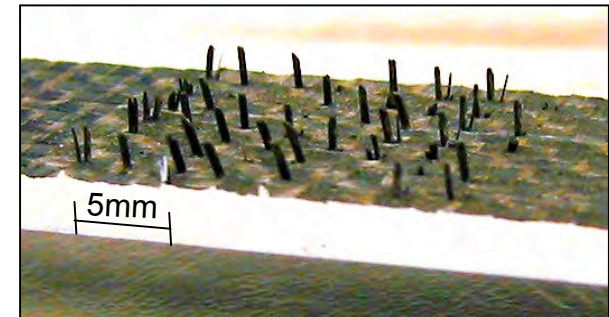
- Improve composite laminate transverse strength
- Prohibit delamination

## Drawbacks

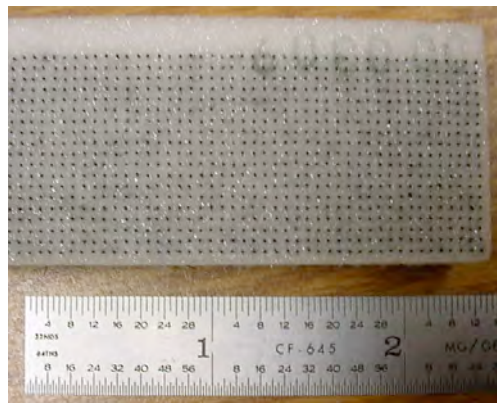
- Degrade laminate (in-plane) properties

## Applications

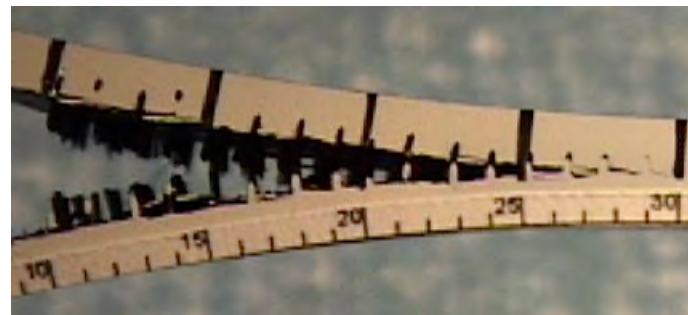
- F/A 18 inlet ducts, X-cor™, Formula 1 auto racing



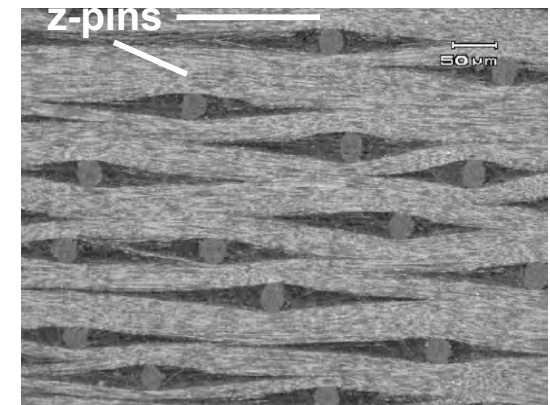
Z-Pins protruding from laminate



Z-Pin preform: Insertion side\*



Z-pin bridging mode I delamination

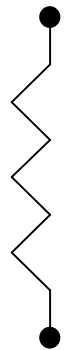


Fiber misalignment from z-pins\*\*

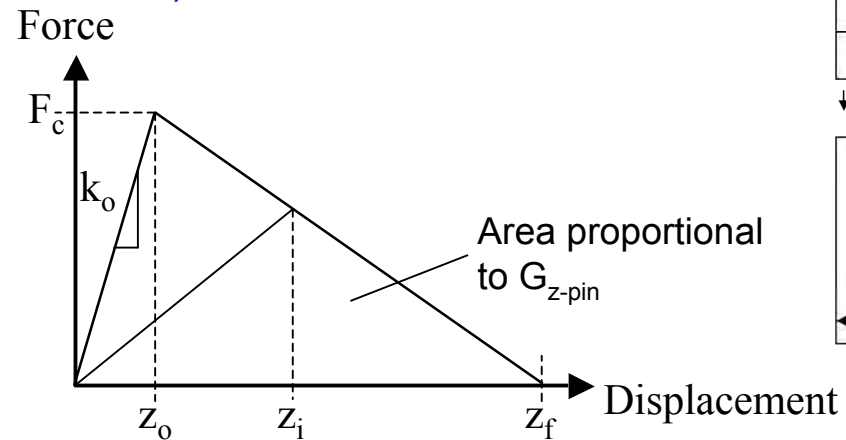


# FINITE ELEMENT ANALYSIS

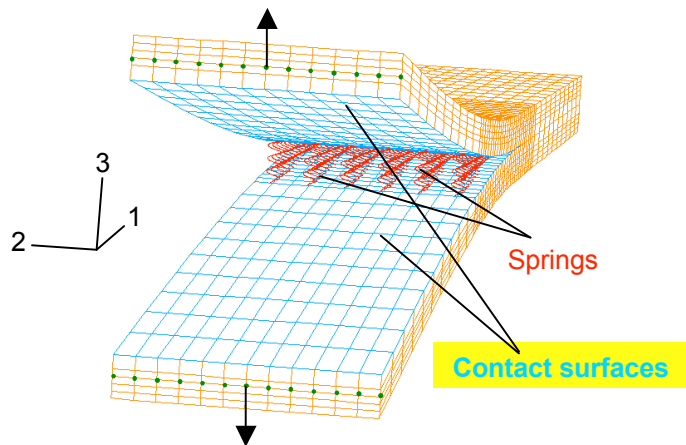
## 1 Discrete spring used to represent individual z-pins (Traction law assigned for representing z-pin failure)



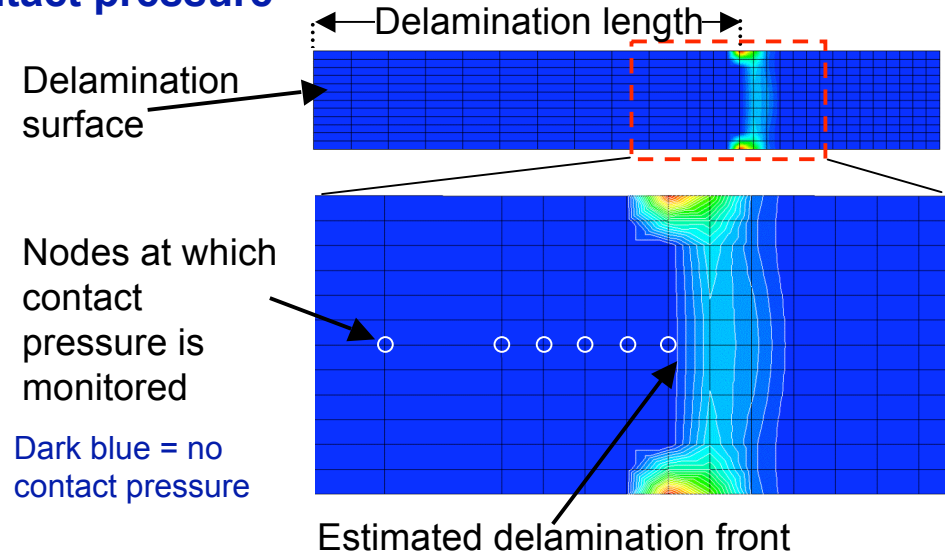
$$k_i = \begin{cases} k_o & \Leftarrow z_i \leq z_o \\ (1-d)k_o & \Leftarrow z_o \leq z_i \leq z_f \\ 0 & \Leftarrow z_i \geq z_f \end{cases}$$



## 2 Springs inserted into finite element model



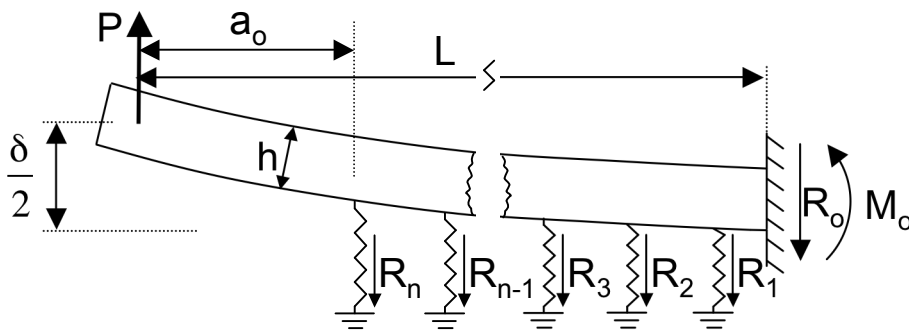
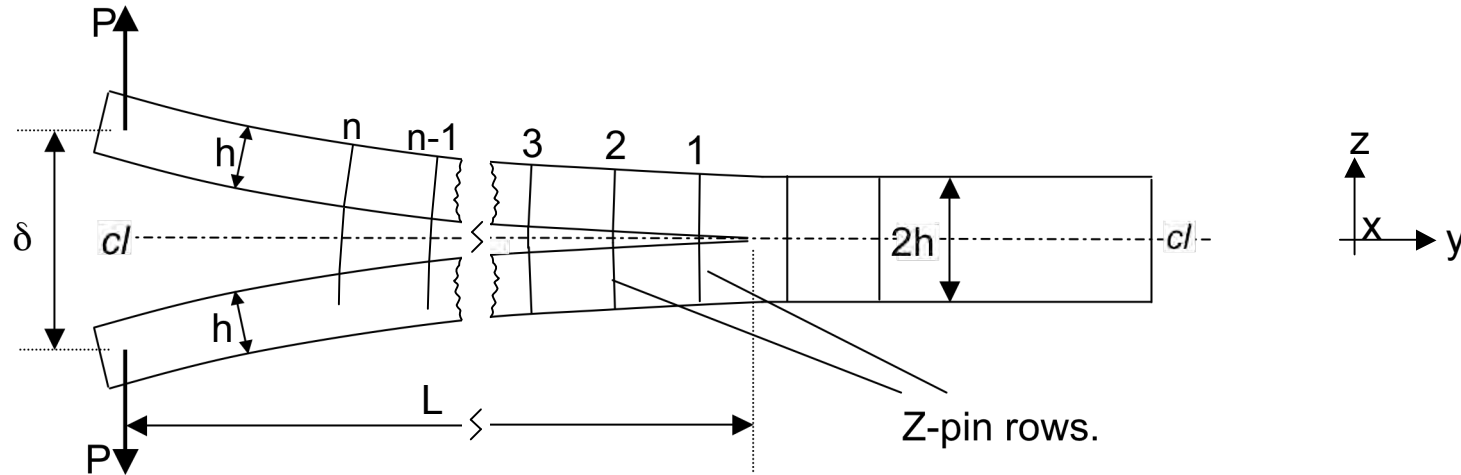
## 3 Delamination growth tracked using contact pressure







# BEAM THEORY ANALYSIS



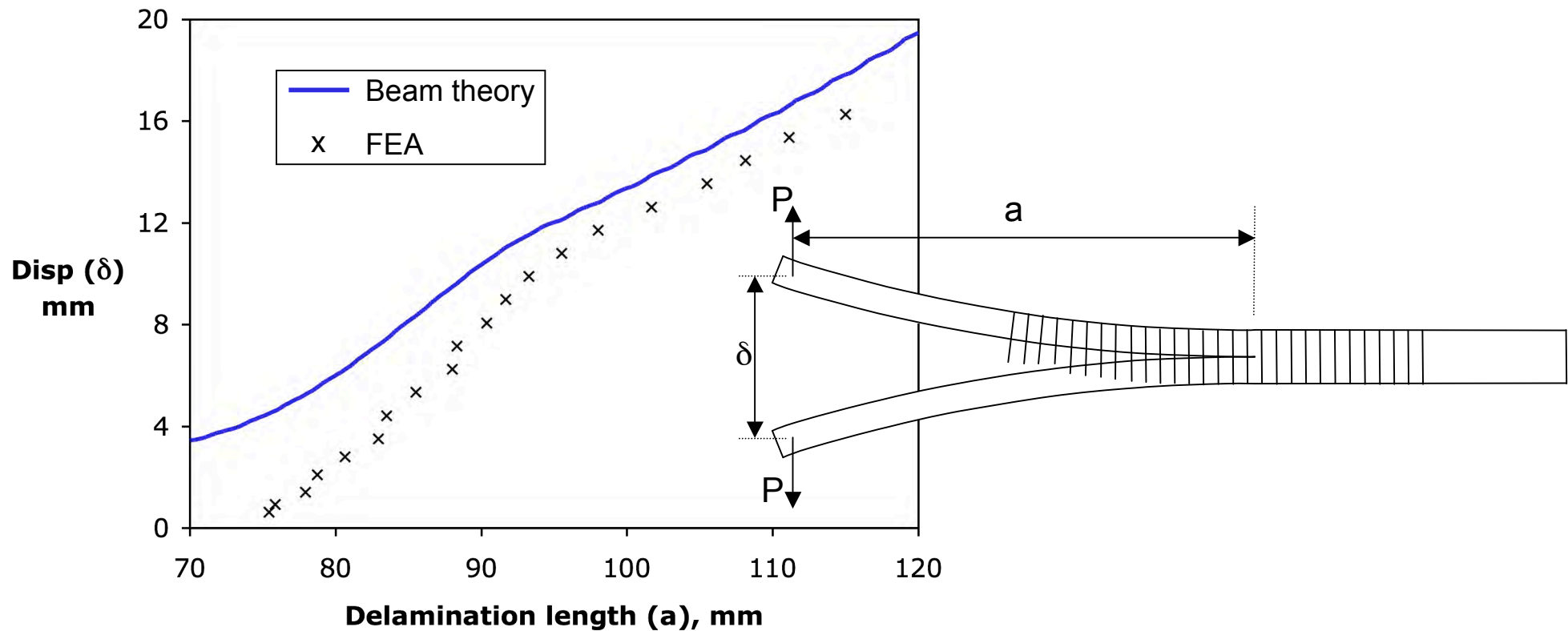
- Half specimen modeled
- Specimen arms represented as cantilever beams
- Spring represents z-pin row
- Traction law to represent z-pin pull out
- Closed-form solutions for specimen compliance
- Algorithm to predict delamination growth

$$C_i = \frac{\delta_i}{P} = 2 \left[ \frac{a_0^3}{3EI} + \frac{L^3 - a_0^3}{3E_{zp}I} \right] + \frac{1}{3PE_{zp}I} \left[ \sum_{i=1}^n k_i z_i a_i^2 (a_i - 3L) \right]$$



# COMPARISON WITH BEAM THEORY

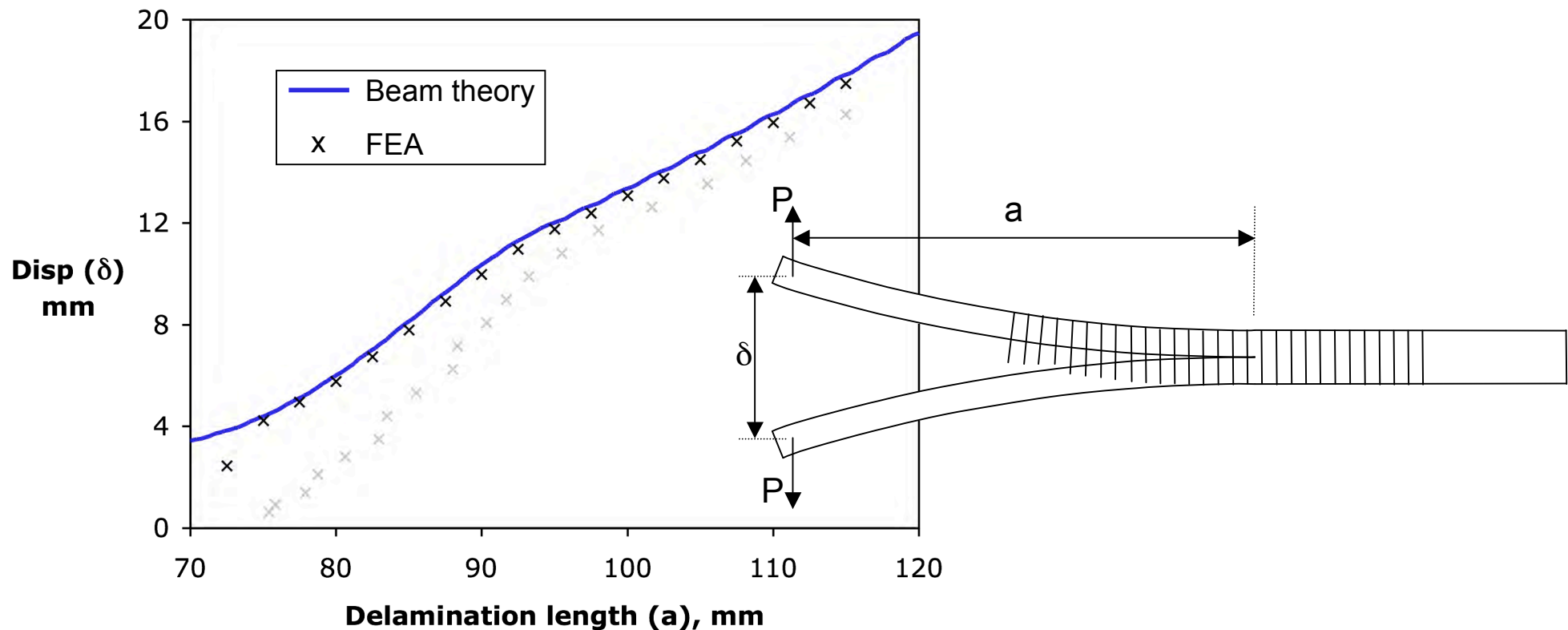
- Finite element analysis overestimates delamination length for a given displacement





# COMPARISON WITH BEAM THEORY

- Finite element analysis results in better agreement with beam theory when decohesion elements used for delamination





## CONCLUDING REMARKS

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- Many analysis studies involve a low Technology Readiness Level (TRL). Therefore, specialized tools are required which are not always commercially available
- In many cases the finite element analysis software has to provide input to specialized user subroutines. An adequate interface is required to enable appropriate communication with the user subroutines.
- The specialized analysis tools are often computationally expensive