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WIND-TUNNEL INVESTIGATION OF A REVISED HORIZONTAL

TAIL SURFACE FOR THE GRUMMAN TBF-1 AIRPLANE

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NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS

MEMORANDUM REPORT

for the

Bureau of Aeronautics, Navy Department WIND-TUNNEL INVESTIGATION OF A REVISED HORIZONTAL

TAIL SURFACE FOR THE GRUMMAN TBF-1 AIRPLANE

By John W. McKee and Robert B. Liddell

INTRODUCTION

At the request of the Bureau of Aeronautics, Navy Department, an investigation was made in the LMAL 7- by 10-foot tunnel of the aerodynamic characteristics of a revised 0.5scale model of the Grumman TBF-1 left horizontal tail surface. The investigation was undertaken to determine if a horizontal tail surface with a large overhang would reduce the high stick forces in maneuvers that the airplane had with the original horn-balanced elevator, without appreciably affecting the longitudinal stability characteristics of the airplane.

Preliminary flight tests of the XTBF-1 airplane and wind-tunnel tests of a 0.5-scale model of the left horizontal tail surface with various amounts of horn balance (reference 1) had previously been made. For the present investigation the model of reference 1 was modified by moving the elevatorhinge axis rearward, by increasing the percentage of aerodynamic nose balance, by eliminating the horn balance, and by adding a full-span leading tab. The effects of tab-elevator deflection ratio, tab-elevator nose seal, elevator hinge cut-out seals, and elevator rudder cut-out were determined. The results of the wind-tunnel tests, parameters estimated from section data, and estimated control forces for the various arrangements are presented in this report.

METHODS AND APPARATUS

The test setup is shown schematically in figure 1 and by the photographs of figure 2. The semispan model was mounted vertically in the LMAL 7- by 10-foot tunnel (reference 2) with the inboard end adjacent to the floor of the tunnel, which thereby acted as a reflection plane. The model was supported entirely by the balance frame with a small clearance at the tunnel floor so that all the forces and moments acting on the model could be measured. The flow over the model simulated the flow over the left semispan of a complete horizontal tail consisting of the test panel joined to its reflection and mounted in a 10- by 14-foot tunnel.

Provisions were made for changing the angle of attack of the model and the deflection of the elevator while the tunnel was in operation. The elevator hinge moments were measured by means of an electrical strain gage mounted within the elevator.

The 0.5-scale model was a revision of the model of the TBF-1 left horizontal tail surface described in reference 1. The revised model had the same root and tip airfoil section and chord and the same tip shape as the model of reference 1. The model represented the portion of the airplane cross-hatched

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in figure 3. The model was tested with modifications 2a and 2b as shown in figure 4 and had the geometric characteristics of table I. The inboard end of the elevator of modification 2a (fig. 4(a)) was cut out to allow for rudder deflection and was made similar to that of the original model (reference 1). The elevator of modification 2b (fig. 4(b)) extended the full span of the model with no cut-out to allow for rudder deflection,

The elevator of modification 2a was the type of control surface suggested in reference 3, having a large aerodynamic balance and a leading tab. The elevator of modification 2a had a blunt-nose balance of approximately 50 percent of the elevator area. The balance was designed to have the center of the nose reach the stabilizer surface (unport) along its full length at an elevator deflection of approximately 12°. The blunt-nose balance shape was used because section data (references 3, 4, and 5) indicated that a blunt nose added less drag than other nose shapes. The elevator was designed, as suggested in reference 3, to have enough balance or overhang to give modification 2a a positive value of Cha in order that the airplane longitudinal stability with controls free would exceed that with controls fixed. A full-span leading tab of approximately 10 percent of the total tail area was provided on modification 2a to overcome the overbalance of the elevator when deflected. The linkage of the tab is shown schematically in figure 5 and the calibrations for the

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various tab-elevator deflection ratios are shown in figure 6. The elevator hinge-moment coefficients include the effect of the tab and linkage loads on the elevator. A reduction in elevator area was permissable due to the increase in elevator effectiveness caused by the leading tab, so the elevatorhinge axis was 5.10 inches (model dimensions) nearer the elevator trailing edge than the hinge axis of the original model (reference 1).

The model was tested with various elevator and tab gap conditions. The dimensions "a" and "b" (fig. 4) of the gap at the elevator nose were varied. For some of the tests the gap was sealed with a sheet rubber seal that allowed an elevator deflection of only ±12°. The tab was tested with a small gap at the nose and with a grease nose seal. Both elevator modifications had four cut-outs in the nose balance for the elevator hinges and the elevator-deflecting link (fig. 4). Each cut-out was 1/2+inch wide and extended back to the hinge axis. Most tests were run with these cut-outs unsealed. For some tests they were sealed with sheet rubber. It is believed that these cut-out seals had some small leaks at large negative elevator deflections but the cut-outs may be considered completely sealed for all practical purposes.

All tests were made at a dynamic pressure of 16.37 pounds per square foot which corresponds to a velocity of approximately 80 miles per hour. The test Reynolds number based on the

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RESULTS

Coefficients and Corrections

The coefficients used in this report are defined as follows:

CL	lift coefficient (L/qS)
CD	drag coefficient (D/qS)
C _m	pitching-moment coefficient (m/qSc)
Che	elevator hinge-moment coefficient $(H_e/qb_e\overline{c_e}^2)$
where	
L	twice the lift of the semispan model
D	twice the drag of the semispan model
m	twice the pitching moment about the mounting axis
	of the semispan model
He	twice the elevator moment of the semispan model
	about the elevator hinge axis, positive when it
	tends to depress the elevator trailing edge
q	dynamic pressure $\left(\frac{1}{2}\rho V^2\right)$
S	twice the area of the semispan model .
b	twice the span of the semispan model
с	mean chord of horizontal tail (S/b)
be	twice the elevator span of the semispan model
ce	root-mean-square chord of the elevator
α	angle of attack, degrees

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- e angle of downwash, degrees
- A aspect ratio of complete tail (b^2/S)
- δe elevator deflection relative to the stabilizer, degrees; positive when the trailing edge is deflected downward

 $\delta_t tab deflection relative to the elevator, degrees; positive when trailing edge is deflected downward article of tab deflection to elevator deflection stick deflection, degrees fractions stick force, pounds, pull is positive force article of the temperature to maneuver, fractions fractions stick force stick stick$

g acceleration of gravity, feet per second per second and

 $C_{L_{\alpha}} = \left(\frac{\partial C_{L}}{\partial \alpha}\right)_{\delta_{e}}, \ \delta_{t}$ $C_{L_{\delta}} = \left(\frac{\partial C_{L}}{\partial \delta_{e}}\right)_{\alpha}$ $C_{h_{\alpha}} = \left(\frac{\partial C_{h}}{\partial \alpha}\right)_{\delta_{e}}, \ \delta_{t}$ $(at \ \alpha = 0^{\circ})$ $C_{h_{\delta}} = \left(\frac{\partial C_{h}}{\partial \delta_{e}}\right)_{\alpha}$ $(at \ \delta_{e} = 0^{\circ})$ $a_{\delta_{e}} = \left(\frac{\partial \alpha}{\partial \delta_{e}}\right)_{C_{L}}$

The results have been corrected for jet-boundary effects. The corrections which were applied (by addition) to the angle of attack and the lift, drag, pitching-moment, and hinge-moment

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coefficients were:

 $\Delta \alpha = 1.48 \times C_{L} \quad (in degrees)$ $\Delta C_{L} = -0.016 \times C_{L}$ $\Delta C_{Di} = 0.00235 \times C_{L}^{2}$ $\Delta C_{m} = 0.0069 C_{L}$ $\Delta C_{h} = 0.0046 \times C_{L}$

The method of determining the corrections is presented in reference 6. No corrections have been made for the effect of the gap between the root section and the floor or leakage around the support strut.

For convenience in locating the results a resume of the tests is given in the following table:

Test no.	aŋ, deg	δ_e , deg	$\frac{\delta_t}{\delta_e}$	Elevator gap	Tab gap	Modifi- cation	Figure no.
109 110 111 112 113 114	-4 -2 0 2 4 8	20 to -20	No tab	a = 0.22 b = 0.67 No seal	No tab	27	17
116	16		\downarrow		1		V
117 118 119 120 121 122 123 124	-4 -2 0 2 4 8 12 16		0		Unsealed	2a	7
117a 119a 121a 122a	-4 0 4 8				Sealed		12
125 126 127 128 129 130 131 132	-4 -2 0 2 4 8 12 16				Unsealed		→ °
133 134 135 136 137 138 139 140	-4 -2 0 2 4 8 12 16		2				
141 142 143 144 145 146 147 148	-4 -2 0 2 4 8 12 16	12 to -12	0.5	a = 0.06 b = 0.06 Nose sealed	Sealed		13

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1

Test no.	đr, deg	δ _e , deg	δt E	levator gap	Tab gap	Modifi- cation	Figure no.
141a 142a 143a 144a 145a 146a 147a 148a	-4 -2 0 2 4 8 2 16	12 to -12		= 0.06 = 0.06 Nose sealed ut-outs sealed	Sealed	2a	15
149 150 151 152 153 154 155 156	-4 -2 -2 -2 -2 -2 -2 -2 -2 -2 -2 -2 -2 -2		1				16
157 158 159 160 161 162 163 164	-42024 2024 120 16		0				
173 174 175 176 177 178 179 180	-4 -2 0 2 4 8 2 6	20 to -20	0.5 (a b N	= 0.22 = 0.67 o seal	Unsealed		8
181 182 183 184 185 186 187 188	42024826			= 0.06 = 0.67 o seal			

DISCUSSION

Modification 2a, unsealed. - The results of the tests of modification 2a with the elevator and tab nose gaps unsealed and with several values of δ_t/δ_e are shown in figures 7 to 11. With $\delta_t/\delta_e = 0$ (fig. 7) the elevator had a positive value of Cha and was overbalanced over most of its deflection range. Table II shows that for $\delta_t/\delta_e = 0.5$ the elevator was no longer overbalanced and as δ_t/δ_e was increased Ch_{δ} became more negative. As δ_t/δ_e was increased GL_R progressively increased and $C_{h_{\alpha}}$ decreased, becoming 0 for $\delta_t/\delta_e = 2$. The values of $C_{h\sigma}$ and $C_{h\delta}$ ($\delta = 0$) of table II are in general valid for only small changes near zero angle of attack and zero elevator deflection. Comparison of figures 8 and 11 shows that reducing the elevator nose gap "a" from 0.22 inch to 0.06 inch gave some increase in $C_{L_{\alpha}}$ but did not increase $C_{\rm LS}$. This modification also reduced $C_{\rm h_{CI}}$ and did not change Cho.

<u>Modification 2a, tab sealed.</u> - Sealing the tab gap $(\delta_t/\delta_e = 0, \text{ fig. 12})$ slightly increased C_{L_0} but did not change $C_{L_{\alpha}}$. The hinge-moment curves were about the same except that $C_{h_{\alpha}}$ was less positive when the tab gap was sealed.

Modification 2a, tab and elevator nose sealed. - Comparison of figure 13 with figure 11 shows that sealing the tab and elevator nose gap slightly increased $C_{L_{\alpha}}$ but did not increase $C_{L\delta}$ when $\delta_t/\delta_e = 0.5$. The seals added negative increments to both $C_{h_{\alpha}}$ and $C_{h_{\delta}}$. The sheet seal used at the elevator nose restricted the elevator deflection to the unporting angle, 12° .

<u>Modification 2a, complete seal</u>. - The characteristics of the model with the tab and elevator nose and elevator balance cut-outs sealed are shown in figures 14 to 16 for several values of δ_t/δ_e . Sealing the elevator balance cut-outs had little effect on $C_{h\delta}$ at small elevator deflections as shown by comparison of figures 13 and 15. Beyond 4° deflection the hinge cut-out seals added balance to the elevator. The hinge cut-out seals increased $C_{L\delta}$, made $C_{h\alpha}$ more positive, and did not change $C_{L\alpha}$. Comparison of figures 14 to 16 with figures 7 to 9 shows that the complete seal increased $C_{L\alpha}$ and $C_{L\delta}$ and in general added balance to the elevator.

<u>Modification 2b, unsealed</u>. - The addition of the rudder cut-out area to the elevator area (modification 2b) with the elevator nose unsealed (fig. 17) increased $C_{L_{\alpha}}$ and greatly increased $C_{L_{\delta}}$. For small elevator deflections, $C_{h_{\delta}}$ was negative, but the elevator was overbalanced at large deflections. $C_{h_{\alpha}}$ was reduced nearly to zero.

<u>Computed tail surface parameters</u>. - Table III lists the parameters calculated for modifications 2a and 2b. The section data from which these values were calculated were taken from references 3, 4, 5, 7, and 8. Considerable extrapolation of the data was necessary. No corrections were made for the hinge cut-outs and only approximate corrections were made for the elevator nose gap.

The formula,

$$C_{L_{\alpha}} = \frac{p c_{l_{\alpha}}}{1 + \frac{57.3 p c_{l_{\alpha}}}{\pi \Delta}}$$
(1)

(reference 8) was used to find the lift-curve slopes where p is an aspect ratio correction and r is an end plate correction. A constant value of $c_{l_{\alpha}}$ (section lift-curve slope) across the span of 0.098 with unsealed gaps and 0.102 with sealed gaps was used. There is good agreement between the calculated and measured values of $C_{L_{\alpha}}$ for modification 2b but there appears to be a loss due to the rudder cut-out of modification 2a that the formula does not take into account.

The values of α_{δ} were obtained by the strip method (assuming no induction) of integrating the section α_{δ} across the span.

$$\alpha_{\delta} = \frac{2}{5} \int_{0}^{b/2} a_{\delta} \times c \, db \tag{2}$$

For a given percent-chord flap, section α_{δ} has an only partially determined variation with overhang, gap, and elevator nose shape. This may explain most of the discrepancy between measured and calculated values of α_{δ} for the model. The section values of α_{δ} for the sealed tab were taken from reference 8. The unsealed tab was assumed to be 10 percent less effective. The expression used to find C_{LS} was:

$$C_{L_{\delta}} = -\alpha_{\delta} \times C_{L_{\alpha}}$$
(3)

The span load distribution should affect $C_{h\alpha}$ and $C_{h\delta}$. In the following equation L_a is the span load factor:

$$C_{h_{\alpha}} = \frac{C_{L_{\alpha}} \times 2 \times S}{b_{e} \times b \times \bar{c}_{e}^{2}} \int_{0}^{b/2} \frac{c_{h_{\alpha}}}{c_{l_{\alpha}}} c_{e}^{2} \frac{L_{a}}{c} db \qquad (4)$$

For modification 2b, $C_{h_{\alpha}}$ was determined using values of L_{a} obtained from reference 9 and for the case of $L_{a} = 1.0$. In both cases $C_{h_{\alpha}}$ was computed to be 0.0004. In the estimation of all other hinge-moment parameters, the span load factor was assumed to be unity. $C_{h_{\delta}}$ was determined from the equation:

 $c_{h\delta} = \frac{2}{\overline{c_e}^2 b} \int_0^{b/2} (c_{h\delta})_{c_l} c_e^2 db + \frac{2c_{L\delta}}{\overline{c_e}^2 b} \int_0^{b/2} (c_{hc_l})_{\delta} c_e^2 db (5)$

A more convenient form is:

$$c_{h\delta} = \frac{2}{\bar{c}_e^2 b} \int_0^{b/2} \left[(c_{h\delta})_a + (c_{h\alpha})_{\delta} a_{\delta} \right] c_e^2 db$$

+
$$\frac{2C_{L_{\delta}}}{\overline{c}_{e}^{2}C_{L_{\alpha}b}} \times \int_{0}^{b/2} (c_{h_{\alpha}})_{\delta} c_{e}^{2} db$$
 (6)

Computed elevator control forces for the airplane.-Several control characteristics of the airplane were estimated for each of the configurations tested and are tabulated in table II. The control characteristics were estimated from the airplane characteristics shown in table I and the controlsurface deflection determined from flight tests of the airplane, corrected to the elevator effectiveness $\begin{pmatrix} C_{L_{Oe}} \end{pmatrix}$ of each modification. A constant value of maximum stick movement of 55° was used. The stick forces were calculated by the method of reference 1 for a center-of-gravity location of 25.5 percent of the mean aerodynamic chord point, approximately the normal center-of-gravity position. The values of $dF_s/d\frac{a}{g}$, change in stick force per unit change in normal acceleration or load factor, are the values at a load factor of 3.5 at 217 miles per hour indicated airspeed. The stick forces required to land with power off were computed with the airplane trimmed at an indicated airspeed of 120 miles per hour with the flaps down.

From the requirements of reference 10 for this type of airplane it is believed that the stick force change per unit change in acceleration should be about 20 pounds and the forces to trim the change due to flaps or to land should be less than 55 pounds. It may be seen from table II that modification 2a with a = 0.22, b = 0.67, $\delta_t/\delta_e = 0.5$, and no seals gives a value of $dF_s/d\frac{a}{g}$ of approximately 18 pounds, a force to trim the change due to flap deflection of -14 pounds, and a force to land of 7 pounds. Figure 18 shows the effect of tab-elevator deflection ratio on the forces for various flight conditions for modification 2a with no seals and with a complete seal. The forces were approximately the same with the gaps sealed or unsealed. The model of the original tail surface (reference 1) had a large positive value of Ch_{α} which would give the airplane greater stability with controls free than with controls fixed. The revised model had smaller values of Ch_{α} but in no case was Ch_{α} negative at small angles of attack. The airplane with the revised tail would therefore also have as great or greater stability with controls free as with controls fixed. Stick forces against speed for two power conditions and two trim conditions were estimated (fig. 19) from the model data for modification 2a with no seals, with gap "a" = 0.22 inch, and with $\delta_t/\delta_e = 0.5$. The forces are low over the speed ranges investigated and in general have stable slopes.

CONCLUDING REMARKS

The results of the tests show that a satisfactory horizontal tail surface for the Grumman TBF-1 airplane could be built without the use of a horn balance. Such a tail surface should also be satisfactory on a high-performance high-speed airplane if the balance nose does not cause compressibility troubles when the elevator is deflected. The Grumman TBF-1 airplane with a tail similar to modification 2a with $\delta_t/\delta_e = 0.5$ with no seals would have satisfactory stick forces for turns, to land, and to trim the change due to flaps. The longitudinal stability characteristics of the airplane would not be seriously affected. Changing the elevator gap dimensions and sealing the tab and elevator gaps and balance cut-outs had only minor effects on the aerodynamic characteristics of the tail surface and on the estimated flight characteristics of the airplane. The tab-elevator deflection ratio had a large effect on the hinge moment due to elevator deflection and a small effect on the hinge moment due to angle of attack. More complete section data of flaps with large overhangs and the effect of balance and flap cutouts are needed to make accurate estimations of the characteristics of tail surfaces with large amounts of balance.

Langley Memorial Aeronautical Laboratory, National Advisory Committee for Aeronautics, Langley Field, Va., February 24, 1943.

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TABLE I

	XTBF-1 airplane	0.5-scale semi- span model of modified hori- zontal tail surface modification 2a	0.5-scale semi- span model of modified hori- zontal tail surface modification 2b
Gross weight, lbs Wing area, sq ft Stick length, ft Stick movement, deg Elevator movement, deg, (relative to stabilizer)	12,910 490 1.50 55 17.7 up, 11.0 down	variable	17.0 up, 10.6 down
Horizontal tail area, sq ft Horizontal tail	111.50	14.12	14.88
span, ft Elevator span, ft Elevator area	20.83	5.20 4.79	5.20 4.96
behind hinge line, sq ft Elevator root	48.00	4.21	4.96
mean square chord, ft Slope of lift curve δε/δα	2.536 .078 .5	.935	1.043

TABLE II

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Fig- ure	Modifi- cation	Elevator gap	Tab gap	δ _t /δ _e	. C ^{La}	CLS	að	c _{ha}	$C_{h_{\delta}}$ ($\delta = 0$)	$C_{h_{\delta}}$ ($\delta = \pm 10$)	δ _e required to land (deg)	Fs to land (lb)	$\frac{dFs}{d\frac{a'}{g}}$ (1b)	F_s to trim flaps at $V_1=120 m_1$ (1b)
7 8 9 10	2a	a = 0.22 b = 0.67 No seal	Unsealed	0 1.0 2.0	0.057 .057 .057 .057	0.034 .042 .047 .055	-0.60 74 82 96	0.0012 .0010 .0008 .0000	0.0021 0042 0107 0217	0.0040 	-20 -17 -15 -13	-32 7 28 53	-9 18 38 58	-9 -14 -18 -27
11	2 a	a = 0.06 b = 0.67 No seal	Unsealed	•5	.058	.042	72	.0006	0042		-17	8	17	-12
12	2a	a = 0.22 b = 0.67 No seal	Sealed	0	.057	•035	61	.0009	0020	.0040	-19	-34	-7	-6
13	2a	a = 0.06 b = 0.06 Nose sealed	Sealed	•5	.059	.042	71	.0003	00747		-17 ^ª	12	16	-9
14 15 16	2a	a = 0.06 b = 0.06 Nose sealed Cut-outs sealed	Sealed	0 •5 1.0	•059 •059 •060	.035 .043 .050	59 73 83	.0013 .0009 .0011	.0043 -,0110	.0057	-20 ^a -17 ^a -15 ^a	-38 2 27	0 17 39	-1 -10 -15
17	2ъ	a = 0.22 b = 0.67 No seal	No tab	No tab	•058	.042	72	•0002	0013	.0009	-17	-18	-4	2

SUMMARY OF TBF-1 REVISED HORIZONTAL TAIL CHARACTERISTICS

^aHinge moments for elevator deflections greater than 12° are from extrapolated curves.

 \oplus Indefinite at $\delta = 0$.

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TABLE III

CALCULATED VALUES OF TBF-1 REVISED

HORIZONTAL TAIL PARAMETERS

Figure	CLa	CLS	αδ	Cha	C _{hō} (8=±10)
7 8 9 10 11 12 13 14 15 16 17	0.060 .060 .060 .060 .060 .062 .062 .062	0.034 .049 .064 .041 .034 .034 .035 .044 .035 .044 .052 .037	-0.57 692 -1.069 571 571 571 83	0.0007 .0007 .0028 .0004	0.0038

m Junt Tunnel wall Model -Tunnel floor Model support-Balance frame NATIONAL ADVISORY COMMITTEE FOR AERONAUTICS Figure 1 - Schematic diagram of test installation.

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(a) Modification 2a, $\delta_e = 8.0^\circ$, $\delta_t / \delta_e = 1.0$.

Figure 2.- Revised 0.5-scale model of TBF-1 left horizontal tail surface.

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(b) Modification 2b, $\delta_e = 0$. Figure 2.- Concluded.







St/Se	0.5	1.0	2.0		
X	20.96	13.50	7.34		
Y	20.36	5.24	1.34		



Figure 5 - Schematic diagram of tab linkage.

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