1	Detection of low frequency tones and whale predator sounds by the American sand lance
2	Ammodytes americanus
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13	Hearing of A. americanus
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21 Auditory evoked potentials (AEPs) were used to measure the hearing range and auditory 22 sensitivity of the American sand lance Ammodytes americanus. Responses to amplitude-23 modulated tone pips indicated that the hearing range extended from 50 to 400 Hz. Sound 24 pressure thresholds were lowest between 200 and 400 Hz. Particle acceleration thresholds 25 showed an improved sensitivity notch at 200 Hz but not substantial differences between 26 frequencies and only a slight improvement in hearing abilities at lower frequencies. The hearing 27 range was similar to Pacific sand lance A. personatus and variations between species may be due 28 to differences in threshold evaluation methods. AEPs were also recorded in response to pulsed 29 sounds simulating humpback whale Megaptera novaeangliae foraging vocalizations termed 'megapclicks'. Responses were generated with pulses containing significant energy below 400 30 31 Hz. No responses were recorded using pulses with peak energy above 400 Hz. These results 32 show that A. americanus can detect the particle motion component of low frequency tones and 33 pulse sounds, including those similar to the low frequency components of megapclicks. 34 *Ammodytes americanus* hearing may be used to detect environmental cues and the pulsed signals 35 of mysticete predators. 36

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38 Key Words: auditory brainstem response ABR; communication; feeding; noise; sand eel;
39 sensory ecology.

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INTRODUCTION

43 Low frequency sounds are generated by biotic and abiotic sources and can be propagated 44 relatively efficiently underwater (Urick, 1983). These acoustic cues and signals are often 45 available for marine organisms (Webster et al., 1992) and many fishes use sound as part of 46 important biological activities, including attracting mates, defending territories and spawning 47 activities (Myrberg, 1986; Lobel, 1992; Myrberg, 1997; Mann & Lobel, 1998). Depending on 48 the associated anatomical structures, fishes detect sound with or without auditory specializations 49 (Popper & Fay, 2011). While both sound pressure and particle motion components of sound are 50 often available to fish (Kalmijn, 1988), species without swim bladders are considered to detect particle motion as the primary stimulus (Enger & Andersen, 1967; Chapman & Sand, 1974). 51 52 Responses to sound stimuli have been measured in a variety of ways including natural 53 behavioural reactions (Nelson & Gruber, 1963), classical conditioning (Fay, 1969) and 54 physiological measures (Corwin et al., 1982; Kenyon et al., 1998). 55 56

57 While fishes are clearly adapted to detect and avoid predators, specific responses to 58 predator sounds are far less documented. Yet, evaluating an auditory scene, including detecting 59 predators, has been suggested as a primary adaptive force for developing hearing abilities in 60 fishes (Bregman, 1990; Fay, 1992; Fay & Popper, 2000). Presumed predator escape responses 61 have been elicited by exposing Atlantic salmon Salmo salar L. 1758 to 10 Hz tones (Knudsen et 62 al., 1992). Alewives Alosa pseudoharengus Wilson 1811 and shad Alosa sapidissima Wilson,

63	1811 also avoid ultrasonic sounds suggesting responses to odontocete echolocation clicks
64	(Dunning et al., 1992; Mann et al., 1997). Pacific herring Clupea pallasii Valenciennes 1847
65	display a context-dependent startle and avoidance response to simulated odontocete clicks, both
66	in tank and free-field tests (Wilson & Dill, 2002). Gulf toadfish Opsanus beta Goode & Bean
67	1880 reduce calling rates in the presence of certain marine mammal sounds (Remage-Healey et
68	al., 2006). However, the adaptation for marine predator detection can lead to disadvantages for
69	fish species. Nowacek (2005) suggested that bottlenose dolphin Tursiops truncatus Montagu
70	1821 may take advantage of their prey's hearing range, emitting broadband, low frequency
71	signals called 'pops' to startle prey from seagrass beds into the water column.
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74	Two species of Ammodytidae are abundant in the north-western Atlantic: A. americanus
75	DeKay 1842 and A. dubius Reinhardt 1837. Both species range from West Greenland to as far
76	south as North Carolina, with A. americanus as the slender-bodied inshore species and A. dubius
77	as the deep-bodied offshore species (Robards et al., 1999). Due to overlapping meristic
78	characteristics, the two species have been considered both a consolidated population (Robards et
79	al., 1999) and reproductively isolated sympatric populations (Winters & Dalley, 1988).
80	Population distribution varies seasonally, with winter as a dormant period and spring to late
81	summer as a period of high abundance in the water column (O'Connell & Fives, 1995). During
82	seasonal dormancy and periods of low light, A. americanus has a tendency to bury into the
83	substrate, even when food is available in the water column (Winslade, 1974a, b). Ammodytes
84	americanus is a visual, water-column predator, which feeds primarily on copepods and other
85	invertebrates, and also fish larvae (Robards et al., 1999). When not concealed in the substrate, A.

americanus shows a strong tendency to school and respond collectively to perceived threats
(Pitcher & Wyche, 1983).

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90 Ammodytes spp. serve as essential prey to over 100 consumer species, including birds, 91 marine mammals, fishes, and invertebrates (Robards et al., 1999; Willson et al., 1999). They are 92 one of the most important forage fishes in north Atlantic ecosystems because the population's 93 overall health can be closely linked to the reproductive fitness of its seabird predators (Martin, 94 1989; Monaghan, 1992) as well as the distribution and abundance of cetacean predators (Payne 95 et al., 1986; Weinrich et al., 1997). Stimpert et al. (2007) recorded one of these predator species, 96 the humpback whale Megaptera novaeangliae Borowski 1781, emitting broadband, low-97 frequency, short-pulsed signals while foraging at night in Jeffreys Ledge, in an area and during a 98 season in the Gulf of Maine in which A. americanus are abundant (Fiedler, 2002). Ammodytes 99 *americanus*, along with the related species A. *dubius*, are large components of the M. 100 novaeangliae diet in the northwest M. novaeangliae Atlantic population (Kenney et al., 1985). 101 The recorded sounds, termed 'megapclicks', were associated with sharp body rolls 102 corresponding to underwater lunge feeding that concluded with 'buzzes' of short inter-pulse 103 intervals, similar to those emitted by odontocetes or bats immediately prior to prey capture (Griffin et al., 1960; Johnson et al., 2004). The authors suggested that these signals may either 104 105 serve a biosonar purpose or to manipulate the movements of prey.

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108	Only one audiogram exists for the family Ammodytidae: the Pacific sand lance A.
109	personatus Girard 1856, found in the western Pacific along the Japanese coast (Suga et al.,
110	2005). The study focused only on juveniles and did not address the particle velocity component
111	of sound stimuli. The hearing abilities of adult sand lance or any Atlantic Ammodytes species are
112	unknown. Hearing sensitivities have been shown to differ between cross-oceanic species, such as
113	C. pallasii and Atlantic herring C. harengus L. 1758 (Mann et al., 2005). This study investigated
114	the hearing of A. americanus with the goal of determining the audiogram of a north Atlantic
115	Ammodytes (sand lance) species and their potential detection of pulsed sounds similar to
116	megapclicks. Results are provided in both sound pressure and acceleration. The implications of
117	these data are discussed in reference to the behaviour of both predators and prey of A.
118	americanus.
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121	MATERIALS AND METHODS
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124	Ammodytes americanus were captured using a seine net in the sand flats of Cape Cod
125	Bay (East Dennis, MA, 41°45' N, 70°07' W) from June to August 2010. Ammodytes americanus
126	were immediately transported in aerated coolers with sand and local seawater to the Woods Hole
127	Oceanographic Institution, Woods Hole, MA. There they were held in an aerated fibreglass
128	holding tank (61.6 x 43.8 x 92.1 cm) filled with constantly flowing ambient seawater $23.5 \pm 0.2^{\circ}$
129	C and fed live Artemia spp. daily. The tank bottom contained a layer of sand to provide burying
130	opportunities. Ammodytes americanus appeared to exhibit normal swimming and burrowing

131	behaviours (Robards et al., 1999). Hearing was measured using auditory evoked potential (AEP)
132	methods. The AEP technique involves measuring neurophysiological activity in response to short
133	acoustic stimuli (Hall, 2007). The technique has been used for hearing tests in both invertebrates
134	(Lovell et al., 2005; Mooney et al., 2010) and vertebrates (Jewett, 1970), including a wide range
135	of fish species (Corwin et al., 1982; Kenyon et al., 1998; Yan et al., 2000; Wilson et al., 2009).
136	Twenty-one Ammodytes americanus were examined using short tone pips to establish an AEP
137	audiogram [10.82 cm mean total length (L_T), S.D. 1.84 cm, 3.24 ± 0.40 g mean mass]. Not every
138	frequency was tested with ever subject; respective sample sizes are listed in Table 1. Twelve
139	animals were tested for megapclick responses [9.84 cm (L_T), S.D. 1.41 cm, 2.38 ± 1.20 g mean
140	mass].
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143	EVOKED POTENTIAL RECORDINGS
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146	Ammodytes americanus were transferred to a rectangular plastic experimental tank (49.5
147	x 45.7 x 35.6 cm) containing gently flowing, unfiltered seawater ($23.2 \pm 0.1^{\circ}$ C). To reduce the
148	influence of outside vibrations, the plastic tank was placed in a foam-lined wooden box (58.7 x
149	57.8 x 86.4 cm) elevated 22.3 cm above the concrete floor on cinderblocks and rubber gaskets.
150	Each A. americanus was wrapped in acoustically transparent mesh fabric, held closed with
151	plastic paper clips, and completely submerged in the water [Fig. 1(b)]. The fabric, suspended
152	with nylon monofilament between two pieces of PVC pipe, created a tight hammock-like
153	arrangement to keep the A. americanus immobile [Fig. 1(c)]. Each A. americanus was positioned

154 in the centre of the tank, directly above the speaker presenting the stimuli. A wooden desk next 155 to the tank held the experimental equipment. Overall, the AEP procedures follow standard 156 techniques used for fish evoked potentials (e.g., Corwin et al., 1982; Kenyon et al., 1998; Yan et 157 al., 2000; Wilson et al., 2009) and followed approved Institute for Animal Care and Use 158 protocols. The subjects fully recovered from these procedures, swimming and borrowing 159 normally when returned to their holding tank. 160 161 162 Stimuli were digitally generated using custom Labview software (National Instruments, 163 Austin, TX, http://www.ni.com/) implemented on a personal laptop computer (Panasonic CF-52 164 Toughbook, Secaucus, NJ, http://www.panasonic.com/business/toughbook/laptop-165 computers.asp). Signal polarity was alternated by this program and sounds were then converted 166 from digital to analog using a 6062E PCMCIA data acquisition card (National Instruments) in 167 the laptop. This card connected to a BNC connector box (National Instruments) and then to a 168 Hewlett-Packard 350D attenuator that controlled the sound pressure levels in 1 dB steps. Signals 169 were relayed to a battery-powered amplifier (PLA-2210, PYLE Chopper Series, Pyle Audio, 170 Brooklyn N.Y., http://www.pyleaudio.com/sku/PLA2210) and then to an underwater speaker 171 (UW-30, Lubell Labs Inc., Columbus, OH, http://www.lubell.com) to play the outgoing sounds. 172 All sounds were concurrently monitored on a digital oscilloscope (Tektronix TPS 2014, 173 Beaverton, OR, http://www.tek.com). 174

176	The response of each A. americanus was recorded using the same laptop, program, and
177	data acquisition card. A recording (non-inverting) electrode was superficially inserted above the
178	medulla at the skull's midline [Fig. 1(a)]. A reference (inverting) electrode was inserted into the
179	left posterior-lateral trunk musculature about 2 cm from the tip of the caudal fin. The electrodes
180	were reusable, stainless steel, 27 Ga, 12 mm length (Rochester Electro-Medical, Inc., Lutz, FL,
181	http://rochestermed.com), and were coated with Por-15 (Morristown, NJ, http://www.por15.com)
182	except at the tips to reduce non-response related electrical noise. Wire connections were coated
183	with insulating epoxy to prevent corrosion. Both electrodes and a carbon-rod ground were
184	connected to a Grass CP-511 bio-amplifier (Astro-Med Inc., West Warwick, RI,
185	http://www.astro-med.com), which amplified (10 000 fold) and filtered (10-3000 Hz) the
186	response of the A. americanus. An additional copper wire grounded the stimulus amplifier. The
187	responses were filtered again (30-3000 Hz; Krohn-Hite 3362, Brockton, MA, http://www.krohn-
188	hite.com) and connected simultaneously to the oscilloscope and the laptop in order to observe the
189	recordings in real-time. All equipment ran on battery to reduce electrical noise and was fully
190	charged every day.
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193	Stimuli consisted of amplitude modulated tone pips from 50–2000 Hz (50, 100, 150, 200,
194	300, 400, 500, 1000 and 2000) and pulsed sounds of simulated megapclicks. The 50 Hz tone
195	could drift in frequency by ± 5 Hz. The update rate for all stimuli was 16 kHz. Tone signals were
196	at least six cycles in duration, thus signal length varied relative to frequency but was never more
197	than 120 ms (50 Hz) and was as short as 20 ms (for stimuli \ge 350 Hz). Sound presentations
108	digitally triggered AEP recordings: thus, stimuli and evoked potential records were

199 synchronized. For an individual response record, the test tone was presented 1000 times, with 200 1000 concurrent averaged AEP records. Measurements typically started at maximum sound 201 pressure levels (SPLs) for each frequency (133–167 dB re. 1 µPa depending on the frequency). 202 Within each frequency presentation, the SPL was decreased in 10-dB steps until the production 203 of recognizable and repeatable AEP waveforms weakened [Fig. 2(a)]. The SPL was then 204 decreased in 5-dB steps until the waveform disappeared. Two-to-three more measurements were 205 made at 10 to 15 dB below this apparent 'threshold' in order to ensure weak responses were not 206 overlooked. Each test began and concluded with a frequency known to produce a strong 207 response, usually 150 Hz. 208 209 210 Stimuli were calibrated for both sound pressure and particle motion components. Sound 211 pressure was calibrated four times during the experiment using a Reson 4014 hydrophone placed 212 directly above the speaker in the same position as the head of the A. *americanus* (± 2 cm). The 213 same test stimuli presented in the tank hearing experiments were presented via the UW-30. The 214 received peak-to-peak voltage (Vp-p) at each location was measured on the oscilloscope and 215 converted to peak-equivalent root-mean square voltage (peRMS) by subtracting 9 dB. Stimuli 216 were also digitally recorded for reference to an Olympus LS-10 recorder (96 kHz sample rate) 217 and assessed later to ensure UW-30 stimuli were the proper frequency. 218 219 220 Particle acceleration values at the position of the auditory pathway of the A. americanus 221 were obtained by measuring the pressure gradient over two closely spaced sound receivers

(Gade, 1982). Two Brüel and Kjær 8103 hydrophones, vertically spaced 2 cm apart, were fixed
directly above and below the location of the head of the *A. americanus* (3 cm depth). Thus, the
hydrophones were at 2 and 4 cm depth (Fig 1(d,e)). Each hydrophone was connected to a charge
amplifier (Brüel and Kjær 2635) that was connected to an analog-to-digital preamplifier
(RA8GA; TDT, http://www.tdt.com) and a digital signal processor (RM2; TDT). As a stimulus
was played, particle acceleration was computed from the pressure gradient across the two
hydrophones:

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 $\alpha = -\Delta sig/(\rho \Delta r)$

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232 where Δsig is the magnitude of the difference between the waveforms of the two hydrophones 233 (in Pa), ρ is the density of the medium and r is the distance between the hydrophones (Wahlberg 234 et al., 2008). The particle motion was measured in three dimensions by positioning the two 235 hydrophones along three orthogonal axes (Kalmijn, 1988; Wahlberg et al., 2008). Subsequently, 236 particle acceleration values for the pressure-derived AEP thresholds were determined by relating 237 the measured pressure at threshold with the corresponding particle acceleration at the head of the 238 fish. Although a fish acts as a rigid body in the acoustic near field (Denton & Gray, 1982; 239 Coombs *et al.*, 1992), measurements at the head were compared with additional measurements \pm 240 5 cm along the anterior–posterior axis to confirm the sound acceleration field. These 241 measurements were similar $(\pm 2 \text{ dB})$ to those at the head. 242

Responses were also measured using the pulsed, broadband sounds of simulated 244 245 megapelicks. These pulses were created using the Labview program to initiate a short-duration 246 waveform and frequency spectrum reflective of megapclicks recorded by Stimpert et al. (2007). 247 Low frequency pulses were varied by duration and centre frequency, and in-water recordings 248 were made of each potential stimulus at the location of the A. americanus. The spectrum of each 249 recorded sound was then viewed using Cool Edit software to compare the pulse spectrum and 250 duration to that of published megapclicks. Stimpert et al. (2007) high-pass filtered original 251 megapclick data at 400 Hz during analysis, eliminating the low-frequency energy in the 252 published recordings. However, the harmonic structure (peaks at ~ 800 and 1600 Hz) suggests 253 substantial lower frequency energy with peaks likely near 200 and 400 Hz. Because of this 254 uncertainty of the actual megapclick spectrum, multiple pulses were examined based on their 255 peak frequency, which suggested the prevalence of the dominant frequency. An arbitrary label 256 of simulated megaplick 1-8 (e.g. MC1, MC2...) was given to each pulse. These pulses were 257 calibrated in the manner as described above, however pulses are presented in dB peak-to-peak. 258 Each AEP session using pulsed sounds began and concluded by collecting thresholds to 150 Hz 259 tone pips. This was to determine baseline auditory capabilities of each A. americanus and to 260 ensure that no temporary threshold shifts occurred.

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Control experiments included recordings with naturally deceased *A. americanus*,
electrodes in the water without a subject and from subjects with the recording electrode placed in
the posterior muscle [Fig. 2(b)] (Ramcharitar & Popper, 2004; Ramcharitar *et al.*, 2004; Mooney *et al.*, 2010). In this case the recording electrode was inserted into the left posterior-lateral trunk

267 musculature, ~ 2 cm from the tip of the caudal fin, and the reference electrode in the left 268 mediolateral muscle, ~ 5 cm from the tip of the caudal fin.

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271 DATA ANALYSIS

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274 Both visual determination and a custom Matlab program were used to assess the auditory 275 threshold of each subject for each tested frequency. For the visual method, the threshold was 276 determined as the last SPL producing a clear, repeatable waveform (Kenyon *et al.*, 1998). The 277 Matlab program graphs the amplitude of an evoked response for its respective attenuation 278 records against the SPL at the peaks of the fast Fourier transformed waveform. The script then 279 performs a best-fit linear regression. The threshold was considered the point at which the 280 regression line crosses the horizontal axis, *i.e.* the SPL at which the amplitude of the response 281 equals 0 µV (Nachtigall et al., 2007; Mooney et al., 2010). Five to 10 attenuation records were used per frequency (mean = 6.13), and the points producing the highest r^2 value were used to plot 282 283 the regression line (Fig. 3). Threshold values procured from all A. americanus were averaged to 284 produce an audiogram for the species based on each method (Kenyon et al., 1998). Megapclick 285 detection was determined using a similar method of examining the fast Fourier transformed 286 waveform to determine if high peak activity occurred at twice the frequency around which each 287 megapelick was centred. The waveforms were also visually scanned for potential responses (e.g. 288 Kenyon et al., 1998; Mooney et al., 2010). Statistical tests were performed using JMP 9.0.0. All 289 measurements are reported as mean \pm standard error unless otherwise specified.

RESULTS

- 295 TONAL AUDIOGRAMS

Responses were found from 50-400 Hz. At higher amplitudes, response waveforms were clearly visible [Figs 2(a), 3]. Tone pip stimuli generated response waves that oscillated at twice the stimulus frequency, consistent with previous studies of fish evoked potentials (Fay & Popper, 1974; Egner & Mann, 2005; Casper & Mann, 2007). A typical response consisted of a clear, repeatable waveform slightly delayed (10-15 ms) from the stimulus onset. Responses were clear and consistent at 350 Hz and below. Response amplitudes decreased with stimulus attenuation [Figs 2(a),3]. Only three of 10 A. americanus showed responses at 400 Hz and responses were not elicited at higher frequencies. No responses were found in the controls, including when electrodes were placed in the water without the A. americanus, in locations posterior and away from the otoliths or when electrodes were placed properly but the A. americanus was deceased [Fig. 2(b)]. Thresholds were at least 40 dB above the background noise present in the tank, which remained under 90 dB for all frequencies.

312	The sound pressure audiograms were somewhat irregular in shape. Thresholds were
313	lowest at 300 Hz and increased slightly at 200 and 400 Hz. Responses were not detected above
314	400 Hz. A substantial audiogram notch was found at 150 Hz, at which sensitivity decreased
315	sharply in relation to other frequencies (Fig. 4). Thresholds then decreased and sensitivities
316	improved at 100 Hz and below. While most thresholds did not vary widely among individuals,
317	some frequencies showed greater variation. This seemed partially, but not always, due to
318	differences in the number of samples per frequency (Table I). For example, 200 Hz had the
319	greatest S.D. values despite a relatively high ($n=18$) sample size. While the sound pressure
320	audiogram shape did not differ substantially between the visual method and the FFT methods,
321	visual thresholds were elevated about 20-30 dB (Fig. 4).
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324	In contrast to the audiogram of A. personatus obtained by Suga et al. (2005), the
325	audiogram of A. americanus showed no responses at 500 Hz. Sensitivities of A. americanus were
326	within the same general range as those of <i>A. personatus</i> , although the audiogram of <i>A</i> .
327	personatus did not display an audiogram notch. Visual thresholds for A. americanus were
328	elevated relative to A. personatus, but A. americanus generated FFT thresholds that were below
329	those of A. personatus.
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332	Particle velocity sensitivities were lowest at 200 Hz (Fig. 5). While 400 Hz was the
333	highest overall threshold, there were not always substantial differences between the frequencies.

334 The visual thresholds showed a general trend of improved sensitivity from high to lower

335	frequencies. This trend was not apparent in the FFT measurements. For example, while the
336	highest FFT thresholds were at 400 Hz, they were only significantly greater than thresholds at
337	200 and 300 Hz (one-way ANOVA, $F_{7,93}$ =19.12, $P \le 0.001$; subsequent Tukey's pairwise
338	comparison). FFT thresholds at 50 Hz were only significantly different from 200 Hz. Thus, the
339	FFT-determined particle velocity thresholds were essentially flat.
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342	PULSED STIMULI
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345	Responses were generated using pulsed sounds that contained high spectral energy from
346	75 to 350 Hz and peak frequencies at or below 178 Hz [Table II; Fig. 6(a)]. Evoked potential
347	waveforms were similar to those for tone pips, consisting of a repeatable sinusoid-like
348	waveform. This was likely due to a ringing of the speaker, which is expected with impulse
349	sounds. Response delays were detectable but less than those of the tonal stimuli (~ 5 ms).
350	Response amplitudes decreased correspondingly with SPL attenuation. Again, controls
351	(deceased A. americanus, no A. americanus and electrodes in the posterior musculature) did not
352	generate responses. At very high SPLs (> 160 dB), the short-duration stimulus waveform was
353	visible in the AEP record, potentially masking the first few ms of recording. Also notably, while
354	responses were consistently generated using pulses with lower frequency peaks, these responses
355	were not generated in every A. americanus. There appeared to be some variation with these brief
356	signals and successful AEP recordings compared to the longer duration tonal stimuli.
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359	Ammodytes americanus did not respond to pulses containing peak energy above 178 Hz
360	[Fig. 6(b)]. Unfortunately, the irregularities and inefficiencies of the UW-30 made it difficult to
361	produce pulsed stimuli with peak energy between about 200-700 Hz.
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364	DISCUSSION
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367	At regions of best sensitivity, 50-350 Hz, responses were clear and easily distinguishable
368	from the background noise. All responses showed a standard physiological time delay before
369	they were observed. This delay was shorter for the pulsed sounds likely because their onset was
370	rapid (e.g. Wysocki & Ladich, 2002). Tone pip stimuli were ramped up to reduce frequency
371	spreading but this increased the latency until a response was observable, likely due to an
372	increased time until sufficient stimulus amplitudes were received by the A. americanus. Thus,
373	lower frequencies, with longer ramp-up times (due to larger wavelengths), had slightly longer
374	physiological delays (Wysocki & Ladich, 2001). The AEP waveforms measured also had
375	significant energy at twice the stimulus frequency, making them easily identifiable using FFTs
376	(Casper & Mann, 2007). This suggests that otolith hair cells of A. americanus are arranged in
377	opposite directions and are alternately stimulated via the sound stimuli (Fay & Edds-Walton,
378	1997). Finally, and as expected, responses decreased with stimulus level [Figs 2(a),3] and
379	comparatively, no responses were generated during various control experiments. These A.
380	americanus tone-generated AEP characteristics of a delayed response, decreases with stimulus

381 level and doubling for frequency general were similar to other fishes (e.g. Kenvon et al., 1998; 382 Egner & Mann, 2005) and some invertebrates (Mooney et al., 2010). Overall, thresholds levels 383 shown here are also similar to those in other studies of fishes without auditory specializations 384 (Wysocki et al., 2009; Anderson & Mann, 2011) showing A. americanus are not hypersensitive, 385 nor insensitive, to sound. Pulsed stimuli with significant low frequency energy generated 386 responses that were much shorter in delay but overall still exemplified the doubling-of-frequency 387 following response [Fig. 6(a)]. These reflected novel fish AEP responses to a predator-like 388 sound.

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391 The shape of the audiograms differed when plotted in sound pressure and particle 392 velocity. The sound pressure thresholds of A. americanus were irregular, with peaks and valleys 393 and displayed greatest sensitivity from 300 Hz to 400 Hz. Acceleration thresholds were lowest at 394 200 Hz. Even excluding this 200 Hz point, the acceleration thresholds slightly improved in 395 sensitivity as frequency decreased. Thresholds plotted in sound pressure were much more 396 uneven in shape. These shape differences are a little surprising because in many instances, fish 397 sound pressure and particle velocity hearing curves have similar curves (Horodysky et al., 2008; 398 Wysocki et al., 2009). Yet, this is not always the case (Anderson & Mann, 2011). The 399 differences between the two audiograms' shapes seen here and elsewhere may be partially due to 400 the complex interaction of acoustic stimuli in small experimental tanks. While free-field 401 calculations between sound pressure and particle motion are a direct theoretical relationship, this 402 is not true in a small tank with reflections and reverberation. Thus, sound pressure and 403 acceleration may not follow the same trends in certain situations.

406	Particle velocities are often the relevant stimuli for many fishes, but fish hearing with
407	respect to pressure and acceleration is now seen as a continuum between species (Popper & Fay,
408	2011). Unfortunately, it can be difficult to predict the details of audiograms and it is suggested
409	that morphological variations do not always coincide with hearing estimations (Wysocki et al.,
410	2009; Anderson & Mann, 2011). The sensory mechanism of fishes (Popper & Fay, 2011) and
411	the differences between pressure and acceleration audiograms, as seen here, support substantial
412	consideration of acceleration values, not simply sound pressure (Suga et al., 2005). Conversion
413	metrics and laboratory settings used here provide an estimate of natural setting data. In situ
414	acceleration measurement devices are now more readily available (McConnell, 2003; Wysocki et
415	al., 2009) and increase the scope of potential understandings of fish pressure and particle motion
416	detection. Additional tests using isolated pressure and particle motion stimuli (Packard et al.,
417	1990; Mooney et al., 2010) will improve understanding of the relative importance of particular
418	stimuli. Notably, in these experiments A. americanus essentially rested directly above the
419	speaker and responses were likely dominated by the acceleration component of the sound wave
420	(Kalmijn, 1988). Both the ear and lateral line may have been highly stimulated (Coombs et al.,
421	1992; Wilson et al., 2009). Given that the AEP is a whole brain response, responses were
422	potentially recorded from both auditory and lateral line inputs. The relative contributions of these
423	two systems may have also influenced the acceleration (but not the pressure) audiogram shape,
424	reflecting in differences between the two stimulus types.
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427 The range and shape of the acceleration audiogram reflect hearing abilities of some other 428 fishes (Casper & Mann, 2006; Horodysky et al., 2008; Wysocki et al., 2009; Belanger et al., 429 2010; Anderson & Mann, 2011). Acceleration audiograms typically have a flattened 'J' shape, 430 with most sensitive thresholds at lower frequencies (often below 200 Hz) and thresholds 431 substantially increasing at higher frequencies (e.g. Karlsen, 1992). This is quite different than 432 the 'U' shape of sound pressure mammalian curves (e.g. Johnson, 1967). The acceleration 433 thresholds here somewhat reflect the 'J' shape, but only start the expected increase at the upper 434 limit of hearing, perhaps suggesting that these results were near, but not reaching the true hearing 435 limit of A. americanus. Fish thresholds are most sensitive at lower frequencies in the optimal 436 range of otolith hair cells and as frequencies increase, hair cell response efficiency can decrease 437 (Sand et al., 2001). This appears to limit the frequency range of responses (Sand & Karlsen, 438 2000) and consequently many particle motion audiograms are limited to low frequencies 439 (Karlsen, 1992; Casper & Mann, 2006; these data). Particle velocity also appears to be the most 440 relevant stimulus for fish without swim bladders (Enger & Andersen, 1967; Chapman & Sand, 441 1974). The lack of a swim bladder (Robards *et al.*, 1999) and the presence of dense otolith 442 structures suggest that A. americanus are without auditory specializations (Popper & Fay, 2011), 443 and particle velocity is the likely acoustic stimulus. This further suggests that acceleration 444 thresholds, which are increasingly becoming standard in current studies (see references above), 445 are experimentally necessary because they are biologically relevant to these and other fishes. 446

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Relatively few responses were generated at 350 Hz and 400 Hz. The starting stimulus
levels at these frequencies were limited by the transmission response curve of the underwater

450 speaker. It is likely that the starting sound levels at 350 Hz and 400 Hz were not sufficiently high 451 to induce reliable responses. Further, at least four reliable response records were required for the 452 FFT threshold determinations. These were difficult to obtain if stimuli started near threshold. In 453 any case, comparing these data to Suga *et al.*'s work (2005) and audiograms of similar fishes 454 without gas bladders or auditory specializations (Karlsen, 1992; Sand & Karlsen, 2000; Sand et 455 al., 2001; Wysocki et al., 2009; Popper & Fay, 2011), similar results are found – that 400 Hz is 456 probably close to the upper limit of A. americanus hearing range. Predominant sources of ocean 457 sounds are also in this low frequency range (Urick, 1983; Au & Hastings, 2009). In these 458 respects, the 'auditory scene' (Bregman, 1990) of A. americanus is likely in the frequencies 459 measured and thus these data provide sensitivities in the primary sensory range of A. americanus. 460

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462 Ammodytes americanus and A. personatus had somewhat different thresholds, although 463 frequency response ranges were similar (Suga *et al.*, 2005). The lack of responses at 500 Hz in 464 this study may be a result of the 140 dB starting SPL, which is very close to the threshold 465 observed in A. personatus by Suga et al. (2005) at 512 Hz (~133 dB). Levels of 140 dB are 466 significantly above threshold for many, but not all fishes without hearing specializations 467 (Wysocki et al., 2009; Belanger et al., 2010). The differences could be an artefact of the maturity 468 of A. americanus compared to the juveniles used in Suga et al. (2005), although threshold 469 differences were not detected across this study's size spectrum or in similar studies (Belanger et 470 al., 2010). Population, and thus genetic or subtle morphological differences, have also been 471 suggested to impact thresholds (Ladich & Wysocki, 2009; Wysocki et al., 2009). The observed 472 differences may also be a remnant of different methods used. Suga *et al.* (2005) placed the

473	speaker out of the water and kept the heads of A. personatus at the water surface. While animal
474	placement and speaker alone may not impact the sound pressure thresholds of otophysans
475	(Ladich & Wysocki, 2009), calibration errors, among other possibilities, may impact threshold
476	levels (Ladich & Wysocki, 2009). Sound measurements are particularly difficult at the air-water
477	boundary due to reflective and refractive effects (Urick, 1983; Au & Hastings, 2009). Thus
478	placing the animal at the surface may lead to unquantified particle velocities to which A.
479	personatus actually responded.
480	
481	
482	The absence of low frequency energy in field-recorded megapclicks is an important
483	factor to consider in interpreting responses to pulses and simulated megapclicks. The methods
484	used by Stimpert et al. (2007) involved applying a high-pass filter to the acoustic tag recordings
485	that effectively removed the majority of energy below 400 Hz. Although used as an analysis
486	method to reduce water-flow noise on the recordings, this most likely removed the low-
487	frequency energy that falls within the auditory range of A. americanus. Recorded megapclicks
488	had a source level at the tag on the animal's back of 143 ± 5 dB and 154 ± 5 dB re 1 µPa pp.
489	These levels are probably higher in front of the A. americanus and are also above A. americanus
490	hearing thresholds for all tested frequencies. Unfortunately, only sound pressure values are
491	available for the megaplicks. As noted above, acceleration is likely to be the primary stimulus for
492	A. americanus. However, given that both pressure and particle motion are generated with all
493	sounds (Urick, 1983; Kalmijn, 1988), these megapelicks probably have significant particle
494	motion components that would be available to A. americanus. By modelling the available

495 pressure stimuli and calibrating both components, this study assumed that natural megapclicks

would have similar acceleration components to which *A. americanus* may respond. The results
also show pulses with a variety of low frequency spectra can generate responses. Detection
ranges are not predicted without the actual source levels. Based on the published source levels
and assuming similar energy below 400 Hz, it seems likely that megapclicks are detectable by *A. americanus*.

- 501
- 502

503 A prey's ability to hear approaching predators is not a new strategy for predator 504 avoidance, and predator detection is considered one of the primary drivers of hearing evolution 505 (Gans, 1992; Fay & Popper, 2000). Ammodytes spp. often show a tightly compacted schooling 506 response when a threat is perceived (Girsa & Danilov, 1976; Pitcher & Wyche, 1983). This 507 'selfish herd' response (Hamilton, 1971) may reduce fish and bird predation for many 508 individuals. Fishes constitute the majority of Ammodytes spp. predators and much of their 509 avoidance behaviour is considered to be adapted to reduce fish predation (Girsa & Danilov, 510 1976; Willson et al., 1999). For M. novaeangliae, this behaviour may result in a higher density 511 prey patch. The acoustic signals produced by *M. novaeangliae* may serve to exploit *A*. 512 *americanus* behavioural responses and manipulate the fish into a denser school. Similar 513 Ammodytes spp. 'balling up' has been observed as a reaction to nets (Girsa & Danilov, 1976). 514 Perhaps less likely, the sounds could serve to startle A. americanus out of the substrate (e.g. 515 Nowacek, 2005). Behavioural tests with A. americanus in the water column would help evaluate 516 this hypothesis. A. americanus might also use this sensory modality to navigate or to 'eavesdrop' 517 on sounds produced by predators (Fay & Popper, 2000). The acoustic detection of predators may

518	also facilitate prey escape, whether or not the detected sounds correlate with predators' foraging
519	strategies.
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521	
522	The results of this study demonstrate that A. americanus detect low frequency sound and
523	potentially the low frequency components of megapclicks. Particle velocity is likely to be the
524	stimulus for A. americanus. Their hearing range encompasses the frequencies of many potential
525	predators, including cetaceans and soniferous fishes but also many more general ambient sounds
526	such as reef, rain, wave and anthropogenic noise (Urick 1983; Robards et al., 1999). The
527	functional uses of sound in the species, as well as their behavioural reactions and directional
528	responses to sound have yet to be determined.
529	
530	
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Table I. Thresholds (dB re 1 uPa and dB re m s²), standard deviations, and sample sizes
for the tone-pip stimuli.

	SPL			Accel	eration				
Freq (Hz)	FFT	S.D.	Visual	S.D.	FFT	S.D.	Visual	S.D.	п
2000				no r	esponse				4
1000				no r	esponse				9
500			no response						11
400	100.1	2.9	130.6	6.3	-8.1	2.9	22.4	6.3	10
350	96.3	2.8	130.0	5.0	-17.7	2.8	16.0	5.0	4
300	90.6	4.2	124.7	3.4	-33.1	4.2	8.8	3.4	19
250	96.8		128.0		-19.7		11.6		2
200	100.3	7.6	130.7	7.8	-42.8	7.6	-12.1	7.8	18
150	124.3	3.3	141.9	2.9	-9.3	3.3	8.7	2.9	21
100	114.9	2.8	132.4	3.2	-28.3	2.8	-0.3	3.2	21
50	99.2	3.1	121.9	5.1	-13.9	3.1	6.7	5.1	12

589 Table II. Simulated megapclick (MC) sound settings.

Simulated megapclick pulse no.	Peak Freq. (Hz)	Duration (ms)	Starting SPL (dB re 1 µPa)	Responses/fish tested
MC1	123	43	159.5	3/3
MC2	136	50	169.4	4/6
MC3	137	51	169.9	3/7
MC4	139	44	160.0	2/3
MC5	178	52	169.6	6/6
MC6	763	3	157.7	0/4
MC7	1323	2	154.1	0/4
MC8	2153	4	152.5	0/5



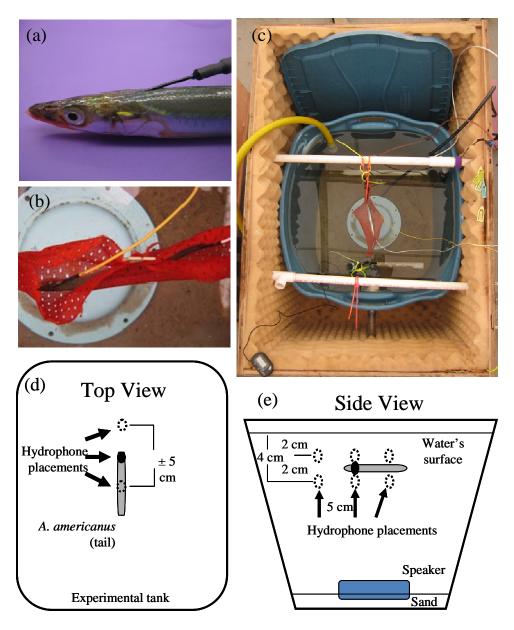
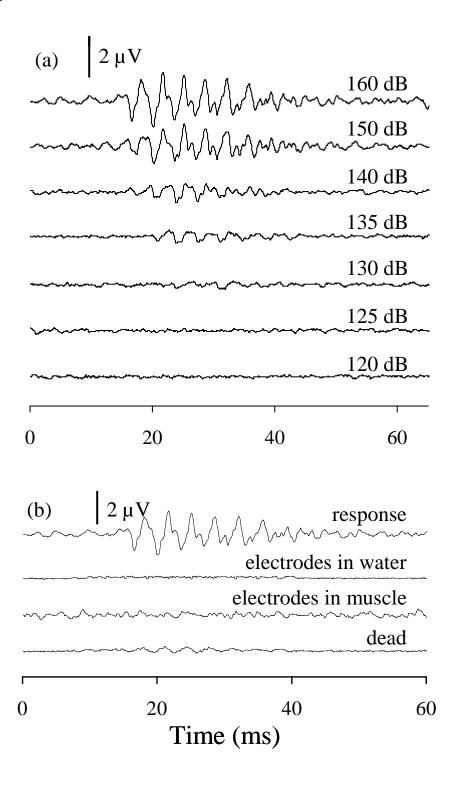
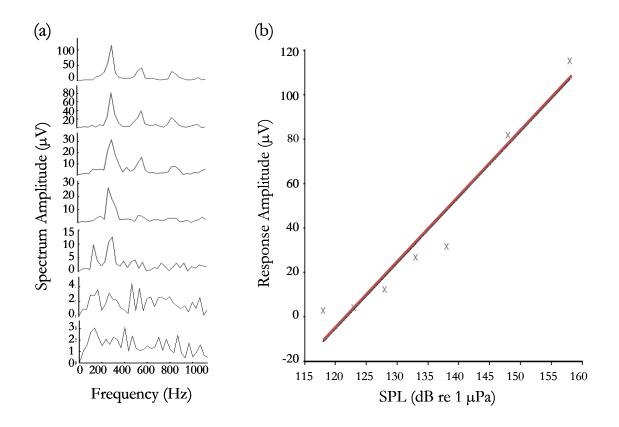
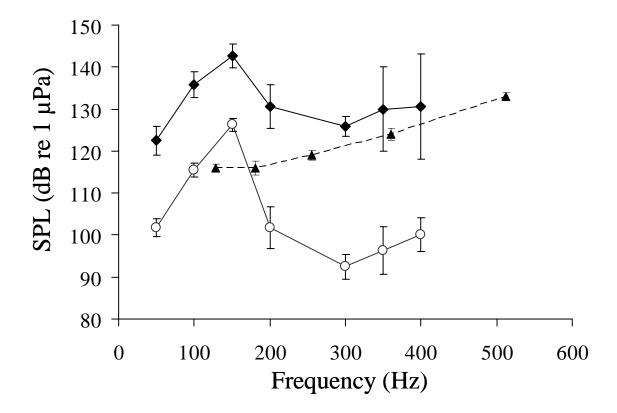


Figure 2.











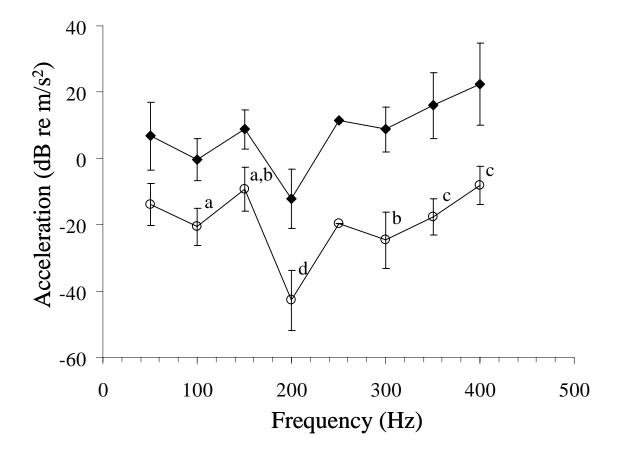


Figure 6.

