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Stable Local Bases for Multivariate Spline Spaces

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Abstract. We present an algorithm for constructing stable local bases for the spaces $\mathcal{S}_d^r(\Delta)$ of multivariate polynomial splines of smoothness $r \geq 1$ and degree $d \geq r2^n + 1$ on an arbitrary triangulation Δ of a bounded polyhedral domain $\Omega \subset \mathbb{R}^n$, $n \geq 2$.

§1. Introduction

Let Δ be a triangulation of a bounded polyhedral domain $\Omega \subset \mathbb{R}^n$, *i.e.*, Δ is a finite set of non-degenerate n -simplices such that

- 1) $\Omega = \bigcup_{T \in \Delta} T$;
- 2) the interiors of the simplices in Δ are pairwise disjoint; and
- 3) each facet of a simplex $T \in \Delta$ either lies on the boundary of Ω or is a common face of exactly two simplices in Δ .

Given $1 \leq r \leq d$, we consider the spline space

$$\mathcal{S}_d^r(\Delta) := \{s \in C^r(\Omega) : s|_T \in \Pi_d^n \text{ for all } n\text{-simplices } T \in \Delta\},$$

where Π_d^n is the linear space of all n -variate polynomials of total degree at most d . It is well-known that $\dim \Pi_d^n = \binom{n+d}{n}$.

The application of splines in numerical computations requires efficient algorithms for constructing locally supported bases for the space $\mathcal{S}_d^r(\Delta)$ or its subspaces (such as finite element spaces). Moreover, if a *local* basis $\{s_1, \dots, s_m\}$ for $\mathcal{S}_d^r(\Delta)$ is in addition *stable*, *i.e.*, for all $\alpha = (\alpha_1, \dots, \alpha_m) \in \mathbb{R}^m$,

$$K_1 \|\alpha\|_{\ell_p} \leq \left\| \sum_{k=1}^m \alpha_k s_k \right\|_{L_p(\Omega)} \leq K_2 \|\alpha\|_{\ell_p},$$

then a *nested* sequence of spaces

$$S_d^r(\Delta_1) \subset S_d^r(\Delta_2) \subset \dots \subset S_d^r(\Delta_q) \subset \dots, \quad (1.1)$$

may be used for designing multilevel methods of approximation on a bounded domain $\Omega \subset \mathbb{R}^n$, see *e.g.* [27] and references therein. In particular, the sequence (1.1)

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constitutes a *multiresolution analysis* on Ω if the maximal diameter of the triangles in Δ_q tends to zero as $q \rightarrow \infty$, and if the constants $0 < K_1, K_2 < \infty$ are independent of q . Note that the bases for the *full space* $\mathcal{S}_d^r(\Delta)$ are particularly interesting since $\mathcal{S}_d^r(\Delta_q) \subset \mathcal{S}_d^r(\Delta_{q+1})$ if Δ_{q+1} is a *refinement* of Δ_q . (This is not the case for the finite element subspaces of $\mathcal{S}_d^r(\Delta)$ when $r \geq 1$; see [14,25,27].)

The famous *B-splines* constitute a stable locally supported basis for the space $\mathcal{S}_d^r(\Delta)$ in the one-dimensional case $n = 1$ for all $d \geq r + 1$. Moreover, the dual basis is also local and therefore provides a quasi-interpolant possessing optimal approximation order. There are well known constructions of local bases for $\mathcal{S}_d^r(\Delta)$ in the bivariate case $n = 2$ for all $d \geq 3r + 2$, see [1,21,22,26]. Stable local bases were constructed in [7,23] for some superspline subspaces, and in [17,19] for the full bivariate spline spaces $\mathcal{S}_d^r(\Delta)$, $d \geq 3r + 2$. In the trivariate case $n = 3$ local bases are known for all $d \geq 8r + 1$ [2]. It was conjectured in [2] that in general locally supported bases for $\mathcal{S}_d^r(\Delta)$ exist if $d \geq r(2^n - 1) + n$.

The main objective of this paper is to construct stable locally supported bases for $\mathcal{S}_d^r(\Delta)$ and its superspline subspaces for all $n \geq 2$ and $r \geq 1$ provided $d \geq r2^n + 1$.

We make use of the *nodal approach* originated in the finite element method, see *e.g.* [12], and extended to the problems of spline spaces on general triangulations in [26] and more recently in [8–11,15,16,17]. We show that in the multivariate case the *nodal smoothness conditions* can be better localized than usual Bernstein-Bézier smoothness conditions [5,20]. The key point for our analysis is that certain matrices associated with the smoothness conditions have a block diagonal structure, which in the same time makes it possible to handle them efficiently in numerical computations, see Sections 5 and 6. In particular, the dimension of any given spline space $\mathcal{S}_d^r(\Delta)$, $d \geq r2^n + 1$ can be efficiently computed by a formula obtained in Section 5.

The paper is organized as follows. In Section 2 we give some definitions and preliminary lemmas. The nodal functionals that we use are described in Section 3. Section 4 is devoted to a detailed analysis of nodal smoothness conditions. In Section 5 we construct local bases for $\mathcal{S}_d^r(\Delta)$, $d \geq r2^n + 1$. In Section 6 we show how to achieve stability of these bases. Finally, in Section 7 we extend the results to the superspline subspaces of $\mathcal{S}_d^r(\Delta)$.

§2. Preliminaries

2.1. Bases and minimal determining sets

It is obvious that the linear space $\mathcal{S}_d^r(\Delta)$ has finite dimension. In this subsection we consider an abstract finite-dimensional linear space \mathcal{S} , although in all our applications we have $\mathcal{S} \subset \mathcal{S}_d^r(\Delta)$.

Let \mathcal{S}^* denote, as usual, the dual space of linear functionals on \mathcal{S} . Given a basis $\{s_j\}_{j \in J}$ for \mathcal{S} , its dual basis is a basis $\{\lambda_j\}_{j \in J}$ for \mathcal{S}^* such that

$$\lambda_i s_j = \delta_{i,j}, \quad \text{all } i, j \in J. \quad (2.1)$$

It is easy to see that the dual basis $\{\lambda_j\}_{j \in J}$ is uniquely determined by $\{s_j\}_{j \in J}$, and vice versa, a basis $\{\lambda_j\}_{j \in J}$ for \mathcal{S}^* uniquely determines a basis $\{s_j\}_{j \in J}$ for \mathcal{S} satisfying (2.1).

In order to construct a basis $\{s_j\}_{j \in J}$ for a spline space \mathcal{S} it is often useful to find first a basis $\{\lambda_j\}_{j \in J}$ for \mathcal{S}^* and then determine $\{s_j\}_{j \in J}$ from the duality condition (2.1). Usually, the required basis for \mathcal{S}^* can be selected by an algorithm from a larger set $\Lambda \subset \mathcal{S}^*$ that spans \mathcal{S}^* . A common example of such a set Λ is the set of linear functionals picking off a coefficient of the Bernstein-Bézier representation of splines $s \in \mathcal{S}$, see *e.g.* [2]. Keeping in mind the tradition upheld in the literature on bivariate and multivariate splines, we will use the following terminology.

Definition 2.1. Any finite spanning set for \mathcal{S}^* is called a **determining set** for \mathcal{S} . Any basis for \mathcal{S}^* is called a **minimal determining set** for \mathcal{S} .

A standard argument in linear algebra shows that a set $\Lambda \subset \mathcal{S}^*$ is a determining set for \mathcal{S} if and only if $\lambda s = 0$ for all $\lambda \in \Lambda$ implies $s = 0$ whenever $s \in \mathcal{S}$. Moreover, a determining set Λ is a minimal determining set for \mathcal{S} if and only if no proper subset of Λ is a determining set. Since every linear functional on \mathcal{S} is well-defined on any subspace $\tilde{\mathcal{S}}$ of \mathcal{S} , it is easy to see that a determining set for \mathcal{S} is also a determining set for $\tilde{\mathcal{S}}$.

Suppose Λ is a determining set for \mathcal{S} . If Λ is not a minimal determining set for \mathcal{S} , then Λ is linearly dependent. It is particularly useful to know a complete system of linear relations for Λ .

Definition 2.2. Let $\Lambda = \{\lambda_j\}_{j \in J} \subset \mathcal{S}^*$ be a determining set for \mathcal{S} . Suppose that the functionals λ_j satisfy linear conditions

$$\sum_{j \in J} c_{i,j} \lambda_j = 0, \quad i \in I, \quad (2.2)$$

where $c_{i,j}$ are some real coefficients. We say that (2.2) is a **complete system of linear relations** for Λ over \mathcal{S} if for any $a = (a_j)_{j \in J}$, with $a_j \in \mathbb{R}$, $j \in J$, such that

$$\sum_{j \in J} c_{i,j} a_j = 0, \quad i \in I, \quad (2.3)$$

there exists an element $s \in \mathcal{S}$ such that $\lambda_j s = a_j$ for all $j \in J$.

Note that the element $s \in \mathcal{S}$ as above is necessarily *unique*. Indeed, if there are $s_1, s_2 \in \mathcal{S}$ such that $\lambda_j s_1 = \lambda_j s_2 = a_j$ for all $j \in J$, then $\lambda_j (s_1 - s_2) = 0$, $j \in J$, which implies $s_1 = s_2$ since Λ is a determining set for \mathcal{S} .

Let $C := (c_{i,j})_{i \in I, j \in J}$. Then (2.3) means that the vector a lies in the null space $N(C) := \{a : C a^T = 0\}$ of the matrix C . Thus, there is a 1-1 correspondence between elements $s \in \mathcal{S}$ and vectors $a \in N(C)$, where $a = (a_j)_{j \in J}$, $a_j = \lambda_j s$. In particular, the dimension of \mathcal{S} can be computed as follows.

Lemma 2.3. *We have*

$$\dim \mathcal{S} = \dim N(C) = \#\Lambda - \text{rank } C. \quad (2.4)$$

Moreover, given a determining set Λ for \mathcal{S} and a complete system of linear relations for Λ over \mathcal{S} with matrix C , it is straightforward to construct a basis for \mathcal{S} ; see also [6].

Algorithm 2.4. *Suppose $\Lambda = \{\lambda_j\}_{j \in J} \subset \mathcal{S}^*$ is a determining set for \mathcal{S} , and (2.2) is a complete system of linear relations for Λ over \mathcal{S} . Let $a^{[k]} = (a_j^{[k]})_{j \in J}$, $k = 1, \dots, m$, form a basis for the null space $N(C)$ of C . For each $k = 1, \dots, m$, construct the unique element $\tilde{s}_k \in \mathcal{S}$ satisfying $\lambda_j \tilde{s}_k = a_j^{[k]}$ for all $j \in J$. Then $\{\tilde{s}_1, \dots, \tilde{s}_m\}$ is a basis for \mathcal{S} .*

It is not difficult to determine corresponding minimal determining set, *i.e.*, the basis $\{\tilde{\lambda}_1, \dots, \tilde{\lambda}_m\}$ for \mathcal{S}^* dual to $\{\tilde{s}_1, \dots, \tilde{s}_m\}$. Let

$$A := [a_j^{[k]}]_{j \in J, k=1, \dots, m}.$$

Since the columns $a^{[k]}$ of this matrix are linearly independent, A has full column rank. Hence, there exists a left inverse of A , *i.e.*, a matrix

$$B = [b_{k,j}]_{k=1, \dots, m, j \in J}$$

satisfying $BA = I_m$, where I_m is the $m \times m$ identity matrix. Note that B is not unique in general.

Lemma 2.5. *The dual basis $\{\tilde{\lambda}_1, \dots, \tilde{\lambda}_m\}$ can be computed by*

$$\tilde{\lambda}_k = \sum_{j \in J} b_{k,j} \lambda_j, \quad k = 1, \dots, m.$$

Proof: It is straightforward to check that the duality condition (2.1) is satisfied. \square

2.2. Geometry of a triangulation in \mathbb{R}^n

Recall that an ℓ -simplex τ ($0 \leq \ell \leq n$) is the convex hull $\langle v_0, \dots, v_\ell \rangle$ of $\ell + 1$ points $v_0, \dots, v_\ell \in \mathbb{R}^n$ called **vertices** of τ . The simplex τ is **non-degenerate** if its ℓ -dimensional volume is non-zero and **degenerate** otherwise. The dimension of a non-degenerate ℓ -simplex is ℓ . By the **interior** of an ℓ -simplex we mean its ℓ -dimensional interior. The convex hull of a subset of $\{v_0, \dots, v_\ell\}$ containing $m + 1 \leq \ell + 1$ elements is an m -**face** of τ . Thus, an m -face is itself an m -simplex. An $(\ell - 1)$ -face of τ is also called a **facet** of τ , and any 1-face of τ is also called an **edge** of τ . Note that the only ℓ -face of τ is τ itself, and the vertices of τ are its 0-faces. (We identify a vertex v and its convex hull $\{v\}$.)

Denote by \mathcal{T}_ℓ the set of all ℓ -faces of the simplices in Δ ($\ell = 0, \dots, n-1$) and set

$$\mathcal{T} := \bigcup_{\ell=0}^n \mathcal{T}_\ell,$$

where $\mathcal{T}_n := \Delta$. We will also use notation $\mathcal{V} := \mathcal{T}_0$, $\mathcal{E} := \mathcal{T}_1$ and $\mathcal{F} := \mathcal{T}_{n-1}$ for the sets of all vertices, edges and facets of Δ , respectively. The star of a simplex $\tau \in \mathcal{T}$, denoted by $\text{star}(\tau)$, is the union of all n -simplices $T \in \Delta$ containing τ , *i.e.*,

$$\text{star}(\tau) = \bigcup_{\substack{T \in \Delta \\ \tau \subset T}} T.$$

In particular, $\text{star}(T) = T$ for each $T \in \Delta$.

Furthermore, given $\tau \in \mathcal{T}_\ell$, $\ell \leq n-1$, we denote by (τ) the linear manifold in \mathbb{R}^n parallel to the affine span $\text{aff}(\tau)$ of τ and by $(\tau)^\perp$ the orthogonal complement of (τ) in \mathbb{R}^n . Note that $\dim(\tau)^\perp = n - \ell$. In particular, $(v)^\perp = \mathbb{R}^n$ for all $v \in \mathcal{V}$.

Let $\tau = \langle v_0, \dots, v_\ell \rangle \in \mathcal{T}_\ell$, $\ell \leq n-1$, and let $w \in \mathcal{V}$ be such that $\tau' = \langle \tau, w \rangle := \langle v_0, \dots, v_\ell, w \rangle$ is in $\mathcal{T}_{\ell+1}$. Since $\dim(\tau)^\perp = n - \ell$ and $\dim(\tau') = \ell + 1$, the linear manifold $(\tau)^\perp \cap (\tau')$ has dimension 1. Moreover, since $\text{aff}(\tau)$ has codimension 1 as an affine subspace of $\text{aff}(\tau')$, it defines two half-spaces of $\text{aff}(\tau')$, and there is a unique unit vector in $(\tau)^\perp \cap (\tau')$ pointing into the half-space of $\text{aff}(\tau')$ containing w . We denote this unit vector by

$$\sigma_{\tau, w}.$$

If v is a vertex in \mathcal{V} , then $\sigma_{v, w}$ is obviously the unit vector in the direction of the edge $\langle v, w \rangle$. If $w_1, \dots, w_m \in \mathcal{V}$ and $\tilde{\tau} = \langle \tau, w_1, \dots, w_m \rangle$ is in $\mathcal{T}_{\ell+m}$, $\ell + m \leq n$, then we set

$$\sigma(\tau, \tilde{\tau}) := (\sigma_{\tau, w_1}, \dots, \sigma_{\tau, w_m}).$$

2.3. Nodal functionals

Given $\sigma = (\sigma_1, \dots, \sigma_m)$ a linearly independent sequence of *unit* vectors in \mathbb{R}^n , and $\alpha = (\alpha_1, \dots, \alpha_m) \in \mathbb{Z}_+^m$, let D_σ^α denote the partial derivative

$$D_\sigma^\alpha := D_{\sigma_1}^{\alpha_1} \cdots D_{\sigma_m}^{\alpha_m},$$

where D_{σ_i} is the derivative in the direction σ_i ,

$$D_{\sigma_i} f(x) := \lim_{t \rightarrow +0} t^{-1} \{f(x + \sigma_i t) - f(x)\},$$

for a differentiable f . By a nodal functional we mean any linear functional on $\mathcal{S}_d^r(\Delta)$ of the form $\eta = \delta_x D_\sigma^\alpha$, where x is a point in Ω , and δ_x is the point-evaluation functional,

$$\delta_x f := f(x).$$

We denote by

$$q(\eta) = |\alpha| := \sum_{i=1}^m \alpha_i \leq r \quad (2.5)$$

the order of η . Given $s \in \mathcal{S}_d^r(\Delta)$, the partial derivative $D_\sigma^\alpha s$ is continuous everywhere in Ω if $|\alpha| \leq r$, and piecewise continuous if $|\alpha| > r$. In this last case we have to choose an n -simplex $T \in \Delta$, with $x \in T$, and apply our functional to $s|_T$. The following situation is of special interest since, for it, a *natural* choice for T exists. Assume that for some $\tau \in \mathcal{T}$ we have $x \in \tau$ and $x + \varepsilon\sigma_i \in \tau$, $i = 1, \dots, m$, if $\varepsilon > 0$ is small enough. Then $\delta_x D_\sigma^\alpha s|_T$ is the same for all $T \in \Delta$ such that $\tau \subset T$. We will choose T in this way whenever the above situation occurs.

We will often use the following simple lemma.

Lemma 2.6. *Let L be a linear manifold in \mathbb{R}^n , $\dim L = m \leq n$, and let $\sigma = (\sigma_1, \dots, \sigma_m)$ be a basis of L , where $\sigma_1, \dots, \sigma_m \in L$ are unit vectors. Suppose that all components of $\tilde{\sigma} = (\tilde{\sigma}_1, \dots, \tilde{\sigma}_m)$ are also some unit vectors in L . Then for any $\alpha \in \mathbb{Z}^m$ there exist real coefficients c_β such that*

$$D_{\tilde{\sigma}}^\alpha = \sum_{\substack{\beta \in \mathbb{Z}^m \\ |\beta| = |\alpha|}} c_\beta D_\sigma^\beta.$$

Proof: Since σ is a basis for L , there are real coefficients a_{ij} such that

$$\tilde{\sigma}_i = \sum_{j=1}^m a_{ij} \sigma_j \quad i = 1, \dots, m.$$

Therefore,

$$D_{\tilde{\sigma}_i} = \sum_{j=1}^m a_{ij} D_{\sigma_j} \quad i = 1, \dots, m,$$

and

$$D_{\tilde{\sigma}}^\alpha = \left(\sum_{j=1}^m a_{1j} D_{\sigma_j} \right)^{\alpha_1} \cdots \left(\sum_{j=1}^m a_{mj} D_{\sigma_j} \right)^{\alpha_m},$$

where $\alpha = (\alpha_1, \dots, \alpha_m)$. \square

2.4. Polynomial unisolvent sets

Let τ be a non-degenerate ℓ -simplex in \mathbb{R}^n . We set

$$\Pi_m^\ell(\tau) := \{p|_\tau : p \in \Pi_m^n\}, \quad m = -1, 0, 1, 2, \dots,$$

where Π_m^n is the space of all n -variate polynomials of total degree at most m , $m = 0, 1, 2, \dots$, and $\Pi_{-1}^n := \{0\}$. By a change of variables, the elements of $\Pi_m^\ell(\tau)$

may be considered as ℓ -variate polynomials of total degree at most m defined on τ . In particular, $\dim \Pi_m^\ell(\tau) = \dim \Pi_m^\ell = \binom{\ell+m}{\ell}$, $m = 0, 1, 2, \dots$, $\dim \Pi_{-1}^\ell(\tau) = 0$. A finite set $\Xi \subset \tau$ is said to be Π_m^ℓ -unisolvent if for any real a_ξ , $\xi \in \Xi$, there exists a unique $p \in \Pi_m^\ell(\tau)$ such that $p(\xi) = a_\xi$ for all $\xi \in \Xi$. Obviously, the number of elements in any Π_m^ℓ -unisolvent set is equal to the dimension of Π_m^ℓ .

As a well known example of a Π_m^ℓ -unisolvent set we mention the set of $\binom{\ell+m}{\ell}$ uniformly distributed points in the ℓ -simplex $\tau = \langle v_0, \dots, v_\ell \rangle$,

$$\tilde{\Xi}_m(\tau) := \left\{ \xi : \xi = \frac{i_0 v_0 + \dots + i_\ell v_\ell}{m}, \text{ where } i_0 + \dots + i_\ell = m \right\}. \quad (2.6)$$

Moreover, its subsets

$$\tilde{\Xi}_m^k(\tau) := \left\{ \xi \in \tilde{\Xi}_m(\tau) : i_j > k, j = 0, \dots, \ell \right\}, \quad 0 \leq k \leq \frac{m-\ell}{\ell+1}, \quad (2.7)$$

are examples of $\Pi_{m-(k+1)(\ell+1)}^\ell$ -unisolvent sets in the *interior* of τ .

The following technical lemma will be very useful later.

Lemma 2.7. *Let $p \in \Pi_m^\ell(\tau)$ and $0 \leq k \leq \frac{m-\ell}{\ell+1}$. Suppose that*

1) *for each facet τ' of τ ,*

$$\delta_x D_{\sigma(\tau', \tau)}^{k'} p = 0, \quad \text{all } x \in \tau', \quad k' = 0, \dots, k,$$

2) *for some $\Pi_{m-(k+1)(\ell+1)}^\ell$ -unisolvent set Ξ in the interior of τ ,*

$$\delta_\xi p = 0, \quad \text{all } \xi \in \Xi.$$

Then $p = 0$.

Proof: Let $\tau_1, \dots, \tau_{\ell+1}$ be all facets of τ . For each τ_i , let p_i be a linear n -variate polynomial such that $p_i|_{\tau_i} = 0$ and $p_i|_\tau \neq 0$. It follows from 1) that

$$p = \tilde{p} \prod_{i=1}^{\ell+1} (p_i|_\tau)^{k+1},$$

where \tilde{p} is a polynomial in $\Pi_{m-(k+1)(\ell+1)}^\ell(\tau)$. Since p_i , $i = 1, \dots, \ell + 1$, do not vanish in the interior of τ , 2) implies that $\tilde{p}(\xi) = 0$ for all $\xi \in \Xi$. Therefore, $\tilde{p} = 0$, and hence $p = 0$. \square

§3. A nodal determining set for $\mathcal{S}_d^r(\Delta)$

Suppose $r \geq 1$ and $d \geq r2^n + 1$. We now associate with each $\tau \in \mathcal{T}$ a set \mathcal{N}_τ of nodal functionals on $\mathcal{S}_d^r(\Delta)$. First, let v be a vertex in $\mathcal{V} = \mathcal{T}_0$. For each n -simplex $T \in \Delta$ containing v we define

$$\begin{aligned} \mathcal{N}_{v,q}(T) &:= \{\delta_v D_{\sigma(v,T)}^\alpha : \alpha \in \mathbb{Z}_+^n, |\alpha| = q\}, & 0 \leq q \leq r2^{n-1}, \\ \mathcal{N}_v(T) &:= \bigcup_{q=0}^{r2^{n-1}} \mathcal{N}_{v,q}(T). \end{aligned}$$

Moreover, we set

$$\mathcal{N}_{v,q} := \bigcup_{\substack{T \in \Delta \\ v \in T}} \mathcal{N}_{v,q}(T), \quad \mathcal{N}_v := \bigcup_{q=0}^{r2^{n-1}} \mathcal{N}_{v,q} = \bigcup_{\substack{T \in \Delta \\ v \in T}} \mathcal{N}_v(T).$$

Suppose now $\tau \in \mathcal{T}_\ell$ for some $\ell \in \{1, \dots, n-1\}$. For each $0 \leq q \leq r2^{n-\ell-1}$, let $\Xi_{\tau,q}$ be a $\Pi_{\mu_{\ell,q}}^\ell$ -unisolvent set in the *interior* of τ , where

$$\mu_{\ell,q} := d - q - (r2^{n-\ell} - q + 1)(\ell + 1). \quad (3.1)$$

Given any n -simplex $T \in \Delta$ containing τ , we define for each $\xi \in \Xi_{\tau,q}$,

$$\mathcal{N}_{\tau,q,\xi}(T) := \{\delta_\xi D_{\sigma(\tau,T)}^\alpha : \alpha \in \mathbb{Z}_+^{n-\ell}, |\alpha| = q\}.$$

Moreover, we set

$$\begin{aligned} \mathcal{N}_\tau(T) &:= \bigcup_{q=0}^{r2^{n-\ell-1}} \bigcup_{\xi \in \Xi_{\tau,q}} \mathcal{N}_{\tau,q,\xi}(T), & \mathcal{N}_{\tau,q,\xi} &:= \bigcup_{\substack{T \in \Delta \\ \tau \subset T}} \mathcal{N}_{\tau,q,\xi}(T), \\ \mathcal{N}_{\tau,q} &:= \bigcup_{\xi \in \Xi_{\tau,q}} \mathcal{N}_{\tau,q,\xi}, & \mathcal{N}_\tau &:= \bigcup_{q=0}^{r2^{n-\ell-1}} \mathcal{N}_{\tau,q} = \bigcup_{\substack{T \in \Delta \\ \tau \subset T}} \mathcal{N}_\tau(T). \end{aligned}$$

Finally, for each $T \in \Delta = \mathcal{T}_n$ we define

$$\mathcal{N}_T := \{\delta_\xi : \xi \in \Xi_T\},$$

where Ξ_T is a $\Pi_{d-(r+1)(n+1)}^n$ -unisolvent set in the interior of T .

Note that in general the sets $\mathcal{N}_{\tau,q,\xi}(T)$ are not mutually disjoint for different T containing τ . For example, let $\tau = \langle v_0, \dots, v_{n-2} \rangle \in \mathcal{T}_{n-2}$, and suppose that both $T = \langle \tau, u, w \rangle$ and $\tilde{T} = \langle \tau, u, \tilde{w} \rangle$ are in Δ . Then the nodal functional $\delta_\xi D_{\sigma_{\tau,u}}^{r+1}$ belongs to $\mathcal{N}_{\tau,r+1,\xi}(T) \cap \mathcal{N}_{\tau,r+1,\xi}(\tilde{T})$. On the other hand, if an n -simplex $T \in \Delta$ is fixed, then the sets $\mathcal{N}_{\tau,q,\xi}(T)$ are mutually disjoint for all τ, q, ξ .

Theorem 3.1. *The set*

$$\mathcal{N} := \bigcup_{\tau \in \mathcal{T}} \mathcal{N}_\tau$$

is a determining set for $\mathcal{S}_d^r(\Delta)$.

Proof: Let $s \in \mathcal{S}_d^r(\Delta)$ satisfy $\eta s = 0$ for all $\eta \in \mathcal{N}$. We have to show that $s = 0$. To this end we choose an arbitrary $T \in \Delta$ and show that $s|_T = 0$. For each vertex v of T , the set

$$\mathcal{N}_v(T) = \{\delta_v D_{\sigma(v,T)}^\alpha : \alpha \in \mathbb{Z}_+^n, |\alpha| \leq r2^{n-1}\}$$

is included in \mathcal{N} . Since $\sigma(v,T)$ is a basis of \mathbb{R}^n , we have by Lemma 2.6,

$$\delta_v D_\sigma^\alpha s|_T = 0, \quad \text{all } \alpha \in \mathbb{Z}_+^n, |\alpha| \leq r2^{n-1},$$

for any sequence σ of unit vectors.

For $\ell = 0, \dots, n-1$, we now show by induction that for each ℓ -face τ of T , if the components of σ are some unit vectors in $(\tau)^\perp$, then

$$\delta_x D_\sigma^\alpha s|_T = 0, \quad \text{all } x \in \tau, \alpha \in \mathbb{Z}_+^{n-\ell}, |\alpha| \leq r2^{n-\ell-1}. \quad (3.2)$$

The validity of (3.2) for $\ell = 0$ is shown above. Suppose $1 \leq \ell \leq n-1$. Let $\alpha \in \mathbb{Z}_+^{n-\ell}$, $|\alpha| = q$, with $1 \leq q \leq r2^{n-\ell-1}$. In view of Lemma 2.6, it suffices to prove (3.2) for $\sigma = \sigma(\tau, T)$. We have $p := D_{\sigma(\tau, T)}^\alpha s|_T \in \Pi_{d-q}^n$ and $p|_\tau \in \Pi_{d-q}^\ell(\tau)$. By the induction hypothesis, for each facet τ' of τ ,

$$\delta_x D_{\sigma(\tau', \tau)}^{q'} p|_\tau = 0, \quad \text{all } x \in \tau', q' = 0, \dots, r2^{n-\ell} - q.$$

Since the nodal functionals $\delta_\xi D_{\sigma(\tau, T)}^\alpha$, $\xi \in \Xi_{\tau, q}$, are included in $\mathcal{N}_\tau(T) \subset \mathcal{N}$, we have in addition

$$\delta_\xi p|_\tau = 0, \quad \text{all } \xi \in \Xi_{\tau, q}.$$

Since $\Xi_{\tau, q}$ is $\Pi_{\mu_{\ell, q}}^\ell$ -unisolvent, Lemma 2.7 implies that $p|_\tau = 0$, which confirms (3.2).

In particular, (3.2) holds for each facet F of T , *i.e.*,

$$\delta_x D_{\sigma(F, T)}^q s|_T = 0, \quad \text{all } x \in F, q = 0, \dots, r.$$

Since \mathcal{N}_T is included in \mathcal{N} , we have in addition

$$\delta_\xi s|_T = 0, \quad \text{all } \xi \in \Xi_T.$$

Since Ξ_T is $\Pi_{d-(r+1)(n+1)}^n$ -unisolvent, Lemma 2.7 implies that $s|_T = 0$, which completes the proof. \square

Theorem 3.2. For each $T \in \Delta$, let

$$\mathcal{N}(T) := \mathcal{N}_T \cup \bigcup_{\ell=0}^{n-1} \bigcup_{\tau \in \mathcal{T}_\ell(T)} \mathcal{N}_\tau(T),$$

where $\mathcal{T}_\ell(T)$ denotes the set of all ℓ -faces of T . Then $\mathcal{N}(T)$ is a minimal determining set for Π_d^n .

Proof: It is easy to see that the set of nodal functionals $\mathcal{N}(T)$ is the same, whatever the triangulation Δ containing T may be. If we take $\Delta = \{T\}$, then obviously $\mathcal{S}_d^r(\Delta) = \Pi_d^n$ and $\mathcal{N} = \mathcal{N}(T)$. Therefore, $\mathcal{N}(T)$ is a determining set for Π_d^n by Theorem 3.1. It thus remains to show that $\#\mathcal{N}(T) = \dim \Pi_d^n = \binom{n+d}{n}$. We have

$$\#\mathcal{N}(T) = \#\mathcal{N}_T + \sum_{v \in \mathcal{T}_0(T)} \#\mathcal{N}_v(T) + \sum_{\ell=1}^{n-1} \sum_{\tau \in \mathcal{T}_\ell(T)} \#\mathcal{N}_\tau(T).$$

It is easy to see that

$$\begin{aligned} \#\mathcal{N}_T &= \binom{n+d-(r+1)(n+1)}{n}, \\ \#\mathcal{N}_v(T) &= \sum_{q=0}^{r2^{n-1}} \binom{n-1+q}{n-1} = \binom{n+r2^{n-1}}{n}, \quad v \in \mathcal{T}_0(T), \\ \#\mathcal{N}_\tau(T) &= \sum_{q=0}^{r2^{n-\ell-1}} \binom{\ell+\mu_{\ell,q}}{\ell} \binom{n-\ell-1+q}{n-\ell-1}, \quad \tau \in \mathcal{T}_\ell(T), \quad 1 \leq \ell \leq n-1, \end{aligned}$$

where $\mu_{\ell,q}$ is defined in (3.1).

We now consider the set

$$Z := \{\alpha \in \mathbb{Z}_+^{n+1} : |\alpha| = d\}.$$

Obviously, $\#Z = \binom{n+d}{n}$. Therefore, the theorem will be established if we show that

$$\#Z = \#\mathcal{N}(T). \quad (3.3)$$

For any nonempty subset I of $\{1, \dots, n+1\}$, let

$$Z_I := \{\alpha \in Z : \sum_{i \in I} \alpha_i \geq d - r2^{n-\ell-1}\}, \quad \text{if } \ell := \#I - 1 < n,$$

$$Z_{\{1, \dots, n+1\}} := Z,$$

and

$$\begin{aligned} \tilde{Z}_{\{i\}} &:= Z_{\{i\}}, \quad i = 1, \dots, n+1, \\ \tilde{Z}_I &:= Z_I \setminus \bigcup_{i \in I} Z_{I \setminus \{i\}}, \quad \#I \geq 2. \end{aligned}$$

Taking into account the assumption $d \geq r2^n + 1$, it is not difficult to see that Z is a disjoint union of the sets \tilde{Z}_I . Hence,

$$\#Z = \sum_{\ell=0}^n \sum_{\#I=\ell+1} \#\tilde{Z}_I.$$

We have

$$\begin{aligned} \tilde{Z}_{\{1, \dots, n+1\}} &= \{\alpha \in Z : \sum_{\substack{i=1 \\ i \neq j}}^{n+1} \alpha_i < d - r, \quad j = 1, \dots, n+1\} \\ &= \{\alpha \in \mathbb{Z}_+^{n+1} : |\alpha| = d, \quad \alpha_j \geq r+1, \quad j = 1, \dots, n+1\}, \end{aligned}$$

and it follows that

$$\#\tilde{Z}_{\{1, \dots, n+1\}} = \binom{n+d-(r+1)(n+1)}{n} = \#\mathcal{N}_T.$$

Furthermore, for each $i = 1, \dots, n+1$, we have

$$\tilde{Z}_{\{i\}} = \{\alpha \in \mathbb{Z}_+^{n+1} : |\alpha| = d, \quad \alpha_i \geq d - r2^{n-1}\},$$

so that $\#\tilde{Z}_{\{i\}} = \binom{n+r2^{n-1}}{n}$, and hence

$$\sum_{i=1}^{n+1} \#\tilde{Z}_{\{i\}} = (n+1) \binom{n+r2^{n-1}}{n} = \sum_{v \in \mathcal{T}_0(T)} \#\mathcal{N}_v(T).$$

Let now $I \subset \{1, \dots, n+1\}$, $\ell := \#I - 1 < n$. Then

$$\begin{aligned} \tilde{Z}_I &= \{\alpha \in Z : \sum_{i \in I} \alpha_i \geq d - r2^{n-\ell-1}, \quad \sum_{i \in I \setminus \{j\}} \alpha_i < d - r2^{n-\ell}, \quad j \in I\} \\ &= \bigcup_{q=0}^{r2^{n-\ell-1}} \{\alpha \in Z : \sum_{i \in I} \alpha_i = d - q, \quad \alpha_j \geq r2^{n-\ell} - q + 1, \quad j \in I\}. \end{aligned}$$

A standard combinatorial argument shows that the cardinality of the set

$$\{\alpha \in Z : \sum_{i \in I} \alpha_i = d - q, \quad \alpha_j \geq r2^{n-\ell} - q + 1, \quad j \in I\}$$

is $\binom{\ell + \mu_{\ell, q}}{\ell} \binom{n-\ell-1+q}{n-\ell-1}$. Since the number of subsets I of $\{1, \dots, n+1\}$ consisting of $\ell + 1$ elements is equal to $\binom{n+1}{\ell+1} = \#\mathcal{T}_\ell(T)$, we conclude that

$$\sum_{\#I=\ell+1} \#\tilde{Z}_I = \sum_{\tau \in \mathcal{T}_\ell(T)} \#\mathcal{N}_\tau(T), \quad \ell = 1, \dots, n-1.$$

Thus, (3.3) holds, and the proof is complete. \square

Theorem 3.2 shows that the set $\mathcal{N}(T)$ defines a *Hermite interpolation operator* $\mathcal{H}_T : C^{r2^{n-1}}(T) \rightarrow \Pi_d^n$ as follows. Given $f \in C^{r2^{n-1}}(T)$, let $\mathcal{H}_T f$ be the unique polynomial in Π_d^n satisfying

$$\eta \mathcal{H}_T f = \eta f, \quad \text{all } \eta \in \mathcal{N}(T). \quad (3.4)$$

Obviously, this is a standard finite-element interpolation scheme, see *e.g.* [24,30].

The following estimation of the norm of $\mathcal{H}_T f$ in the case of uniformly distributed points easily follows from the general results given in [13]; see also the proof of Lemma 3.9 in [16].

Lemma 3.3. *Choose*

$$\begin{aligned} \Xi_{\tau,q} &= \tilde{\Xi}_{d-q}^{r2^{n-\ell}-q}, & \text{all } \tau \in \mathcal{T}_\ell, 1 \leq \ell \leq n-1, 0 \leq q \leq r2^{n-\ell-1}, \\ \Xi_T &= \tilde{\Xi}_d^r, & \text{all } T \in \mathcal{T}_n, \end{aligned} \quad (3.5)$$

where $\tilde{\Xi}_m^k$ are defined in (2.7). Then

$$\|\mathcal{H}_T f\|_{L_\infty(T)} \leq K \max_{\eta \in \mathcal{N}(T)} h_T^{q(\eta)} |\eta f|, \quad (3.6)$$

where h_T is the diameter of T , $q(\eta)$ is the order of the nodal functional η , and K is a constant depending only on n, r and d .

§4. Smoothness conditions

As shown in the previous section, $\mathcal{N} \subset \mathcal{S}_d^r(\Delta)^*$ is a determining set for $\mathcal{S}_d^r(\Delta)$. Therefore, \mathcal{N} is a spanning set for $\mathcal{S}_d^r(\Delta)^*$. However, as we will see, there are some linear dependencies between the elements of \mathcal{N} , called *nodal smoothness conditions*. Our next task is to describe these conditions.

Let $\tau \in \mathcal{T}_\ell$ for some $0 \leq \ell \leq n-1$, and let $F = \langle \tau, u_1, \dots, u_{n-\ell-1} \rangle \in \mathcal{T}_{n-1}$ be an *interior* facet of Δ attached to τ . Then there are exactly two n -simplices $T_1, T_2 \in \Delta$ sharing the facet F . Let $T_1 = \langle F, u_{n-\ell} \rangle$, $T_2 = \langle F, w \rangle$. Since the components of

$$\sigma(\tau, T_1) = (\sigma_{\tau, u_1}, \dots, \sigma_{\tau, u_{n-\ell}})$$

form a basis for $(\tau)^\perp$, and since $\sigma_{\tau, w}$ also lies in $(\tau)^\perp$, there exists $\mu \in \mathbb{R}^{n-\ell}$, $\mu = (\mu_1, \dots, \mu_{n-\ell})$, such that

$$\sigma_{\tau, w} = \sum_{i=1}^{n-\ell} \mu_i \sigma_{\tau, u_i}.$$

Lemma 4.1. *If $s \in \mathcal{S}_d^r(\Delta)$, then for all $\xi \in \tau$, $\alpha \in \mathbb{Z}_+^{n-\ell-1}$ and $0 \leq r' \leq r$,*

$$\delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} s = \sum_{\substack{\beta \in \mathbb{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma(\tau,T_1)}^\beta s, \quad (4.1)$$

where $\binom{|\beta|}{\beta} := \frac{|\beta|!}{\beta_1! \cdots \beta_{n-\ell}!}$, $\mu^\beta := \mu_1^{\beta_1} \cdots \mu_{n-\ell}^{\beta_{n-\ell}}$.

Proof: Let $p_1 := s|_{T_1}$, $p_2 := s|_{T_2}$ and $\sigma_i := \sigma_{\tau,u_i}$, $i = 1, \dots, n-\ell$. We have

$$\begin{aligned} \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} p_1 &= \delta_\xi D_{\sigma(\tau,F)}^\alpha \left(\sum_{i=1}^{n-\ell} \mu_i D_{\sigma_i} \right)^{r'} p_1 \\ &= \delta_\xi D_{\sigma(\tau,F)}^\alpha \left(\sum_{\substack{\beta \in \mathbb{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta D_{\sigma_1}^{\beta_1} \cdots D_{\sigma_{n-\ell}}^{\beta_{n-\ell}} \right) p_1 \\ &= \sum_{\substack{\beta \in \mathbb{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma(\tau,T_1)}^\beta p_1. \end{aligned}$$

Since $s \in C^r(T_1 \cup T_2)$ and $r' \leq r$,

$$D_{\sigma_{\tau,w}}^{r'} p_1(x) = D_{\sigma_{\tau,w}}^{r'} p_2(x), \quad \text{all } x \in F = T_1 \cap T_2.$$

Therefore,

$$\delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} p_1 = \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} p_2,$$

for all $\xi \in F$, in particular for $\xi \in \tau$. Thus,

$$\delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} p_2 = \sum_{\substack{\beta \in \mathbb{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma(\tau,T_1)}^\beta p_1. \quad (4.2)$$

Finally, we note that

$$D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} = D_{\sigma(\tau,T_2)}^\gamma, \quad D_{\sigma(\tau,F)}^\alpha D_{\sigma(\tau,T_1)}^\beta = D_{\sigma(\tau,T_1)}^{\tilde{\gamma}}, \quad (4.3)$$

where $\gamma = (\alpha_1, \dots, \alpha_{n-\ell-1}, r')$, $\tilde{\gamma} = (\alpha_1 + \beta_1, \dots, \alpha_{n-\ell-1} + \beta_{n-\ell-1}, \beta_{n-\ell})$, and the observation that by definition

$$\delta_\xi D_{\sigma(\tau,T_2)}^\gamma s = \delta_\xi D_{\sigma(\tau,T_2)}^\gamma p_2, \quad \delta_\xi D_{\sigma(\tau,T_1)}^{\tilde{\gamma}} s = \delta_\xi D_{\sigma(\tau,T_1)}^{\tilde{\gamma}} p_1$$

(see Section 2.3) completes the proof. \square

Remark 4.2. Lemma 4.1 shows that the condition (4.2) holds for all $\xi \in \tau$, $\alpha \in \mathbb{Z}_+^{n-\ell}$ and $0 \leq r' \leq r$ if the two polynomials p_1 and p_2 defined on T_1 and T_2 , respectively, join together with C^r -smoothness across $F = T_1 \cap T_2$. It is not difficult to see that the converse is also true. Note that for $\tau \in \mathcal{T}_0$, Lemma 4.1 as well as its converse were given (in a slightly different form) in Theorem 4.1.2 of [11], and (in the bivariate case) in [16].

We now concentrate on the conditions (4.1) that involve the nodal functionals in the set \mathcal{N} defined in Section 3. Namely, Lemma 4.1 implies that the following linear relations between the elements of \mathcal{N} hold:

1) given $v \in \mathcal{T}_0$ and $0 \leq q \leq r2^{n-1}$, the system $\mathcal{R}_{v,q}$ of linear conditions

$$\delta_v D_{\sigma(v,F)}^\alpha D_{\sigma_{v,w}}^{r'} = \sum_{\substack{\beta \in \mathbb{Z}_+^n \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \delta_v D_{\sigma(v,F)}^\alpha D_{\sigma(v,T_1)}^\beta, \quad (4.4)$$

for all $0 \leq r' \leq \min\{r, q\}$, all $\alpha \in \mathbb{Z}_+^{n-1}$, with $|\alpha| = q - r'$, and all interior facets $F \in \mathcal{T}_{n-1}$ such that $v \in F$,

2) given $\tau \in \mathcal{T}_\ell$ (where $1 \leq \ell \leq n-2$), $0 \leq q \leq r2^{n-\ell-1}$, and $\xi \in \Xi_{\tau,q}$, the system $\mathcal{R}_{\tau,q,\xi}$ of linear conditions

$$\delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} = \sum_{\substack{\beta \in \mathbb{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma(\tau,T_1)}^\beta, \quad (4.5)$$

for all $0 \leq r' \leq \min\{r, q\}$, all $\alpha \in \mathbb{Z}_+^{n-\ell-1}$, with $|\alpha| = q - r'$, and all interior facets $F \in \mathcal{T}_{n-1}$ such that $\tau \subset F$, and

3) given an interior facet $F \in \mathcal{T}_{n-1}$, $0 \leq q \leq r$, and $\xi \in \Xi_{F,q}$, the linear condition $\mathcal{R}_{F,q,\xi}$,

$$\delta_\xi D_{\sigma_{F,w}}^q = (-1)^q \delta_\xi D_{\sigma(F,T_1)}^q. \quad (4.6)$$

(Here and above w , T_1 and μ_i correspond to a particular F and are defined as in Lemma 4.1.)

Remark 4.3. In view of (4.3) it is easy to see that the smoothness conditions in $\mathcal{R}_{v,q}$, $\mathcal{R}_{\tau,q,\xi}$ or $\mathcal{R}_{F,q,\xi}$ involve only the nodal functionals in $\mathcal{N}_{v,q}$, $\mathcal{N}_{\tau,q,\xi}$ or $\mathcal{N}_{F,q,\xi}$, respectively. (See the definition of the sets of nodal functionals $\mathcal{N}_{v,q}$ and $\mathcal{N}_{\tau,q,\xi}$ in Section 3.)

Let

$$\begin{aligned} \mathcal{R}_v &:= \bigcup_{q=0}^{r2^{n-1}} \mathcal{R}_{v,q}, & v \in \mathcal{T}_0, \\ \mathcal{R}_\tau &:= \bigcup_{q=0}^{r2^{n-\ell-1}} \mathcal{R}_{\tau,q}, & \mathcal{R}_{\tau,q} &:= \bigcup_{\xi \in \Xi_{\tau,q}} \mathcal{R}_{\tau,q,\xi}, & \tau \in \mathcal{T}_\ell, & 1 \leq \ell \leq n-1. \end{aligned} \quad (4.7)$$

Theorem 4.4. *The set*

$$\mathcal{R} := \bigcup_{\tau \in \mathcal{T} \setminus \mathcal{T}_n} \mathcal{R}_\tau \quad (4.8)$$

is a complete system of linear relations for \mathcal{N} over $\mathcal{S}_d^r(\Delta)$.

Proof: By Theorem 3.1, \mathcal{N} is a determining set for $\mathcal{S}_d^r(\Delta)$. Suppose the system \mathcal{R} is written as

$$\sum_{j \in J} c_{i,j} \eta_j = 0, \quad i \in I,$$

where I, J are some index sets, $\{\eta_j\}_{j \in J} = \mathcal{N}$, and $c_{i,j}$ real coefficients. Let a_j , $j \in J$, be any real numbers satisfying

$$\sum_{j \in J} c_{i,j} a_j = 0, \quad i \in I.$$

According to Definition 2.2, we have to show that there exists a spline $s \in \mathcal{S}_d^r(\Delta)$ such that $\eta_j s = a_j$ for all $j \in J$. We first construct the polynomial pieces of s , $p_T = s|_T$, $T \in \Delta$, as follows. By Theorem 3.2, $\mathcal{N}(T)$ is a minimal determining set for Π_d^n . We define p_T to be the unique polynomial in Π_d^n such that

$$\eta_j p_T = a_j, \quad \text{all } \eta_j \in \mathcal{N}(T).$$

We thus have to prove that p_T , $T \in \Delta$, join together with C^r -smoothness. To this end it suffices to consider two n -simplices $T_1, T_2 \in \Delta$ sharing a facet $F \in \mathcal{T}_{n-1}$ and show that the two polynomials $p_1 := p_{T_1}$ and $p_2 := p_{T_2}$ join with C^r -smoothness across F . This, in turn, will follow if we show that

$$\delta_x D_{\sigma_{F,w}}^{r'} (p_2 - p_1) = 0, \quad \text{all } x \in F, \quad r' = 0, \dots, r. \quad (4.9)$$

where w is the vertex of T_2 not lying in F . (That is, $T_2 = \langle F, w \rangle$.)

We first prove by induction on ℓ that for each ℓ -face τ of F , $\ell = 0, \dots, n-2$, and for all $r' = 0, \dots, r$, and $\alpha \in \mathbb{Z}^{n-\ell-1}$, with $|\alpha| \leq r2^{n-\ell-1} - r'$,

$$\delta_x D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'} (p_2 - p_1) = 0, \quad \text{all } x \in \tau. \quad (4.10)$$

Let $\ell = 0$, and let v be a vertex of F . Given $r' = 0, \dots, r$ and $\alpha \in \mathbb{Z}^{n-1}$, with $|\alpha| \leq r2^{n-1} - r'$, the functional $\eta_{j_0} := \delta_v D_{\sigma(v,F)}^\alpha D_{\sigma_{v,w}}^{r'}$ is in $\mathcal{N}(T_2)$. Hence, $\eta_{j_0} p_2 = a_{j_0}$. Let us compute $\eta_{j_0} p_1$. We set $\eta_{j_\beta} := \delta_v D_{\sigma(v,F)}^\alpha D_{\sigma(v,T_1)}^\beta \in \mathcal{N}(T_1)$, $|\beta| = r'$. By (4.4), the equation

$$\eta_{j_0} - \sum_{\substack{\beta \in \mathbb{Z}_+^{n-1} \\ |\beta| = r'}} \binom{|\beta|}{\beta} \mu^\beta \eta_{j_\beta} = 0$$

belongs to \mathcal{R} . Therefore,

$$a_{j_0} - \sum_{\substack{\beta \in \mathbb{Z}_+^n \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta a_{j_\beta} = 0.$$

On the other hand, since $\eta_{j_\beta} \in \mathcal{N}(T_1)$, we have $\eta_{j_\beta} p_1 = a_{j_\beta}$, and it follows that

$$\eta_{j_0} p_1 = \sum_{\substack{\beta \in \mathbb{Z}_+^n \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \eta_{j_\beta} p_1 = \sum_{\substack{\beta \in \mathbb{Z}_+^n \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta a_{j_\beta} = a_{j_0}.$$

Thus, $\eta_{j_0}(p_2 - p_1) = 0$, which confirms (4.10) for $\ell = 0$.

Suppose $1 \leq \ell \leq n - 2$, and let τ be an ℓ -face of F . Given $r' = 0, \dots, r$ and $\alpha \in \mathbb{Z}^{n-\ell-1}$, with $|\alpha| \leq r2^{n-\ell-1} - r'$, consider

$$p := D_{\sigma(\tau, F)}^\alpha D_{\sigma_{\tau, w}}^{r'}(p_2 - p_1)|_\tau \in \Pi_{d-q}^\ell(\tau),$$

where $q := |\alpha| + r'$. Let us show that for each facet τ' of τ ,

$$\delta_x D_{\sigma(\tau', \tau)}^{q'} p = 0, \quad \text{all } x \in \tau', \quad q' = 0, \dots, r2^{n-\ell} - q. \quad (4.11)$$

Since the components of $\sigma(\tau', \tau)$ and $\sigma(\tau, F)$ form a basis for $(\tau')^\perp \cap (F)$, we have by Lemma 2.6, that

$$D_{\sigma(\tau', \tau)}^{q'} D_{\sigma(\tau, F)}^\alpha = \sum_{\substack{\gamma \in \mathbb{Z}^{n-\ell} \\ |\gamma|=|\alpha|+q'}} c_\gamma D_{\sigma(\tau', F)}^\gamma.$$

Moreover, since $\sigma_{\tau, w} \in (\tau)^\perp \subset (\tau')^\perp$,

$$D_{\sigma_{\tau, w}}^{r'} = \sum_{\tilde{r}=0}^{r'} \sum_{\substack{\gamma \in \mathbb{Z}^{n-\ell} \\ |\gamma|=r'-\tilde{r}}} \tilde{c}_{\gamma, \tilde{r}} D_{\sigma(\tau', F)}^\gamma D_{\sigma_{\tau', w}}^{\tilde{r}}.$$

Therefore, we have for $x \in \tau'$,

$$\begin{aligned} \delta_x D_{\sigma(\tau', \tau)}^{q'} p &= \delta_x D_{\sigma(\tau', \tau)}^{q'} D_{\sigma(\tau, F)}^\alpha D_{\sigma_{\tau, w}}^{r'}(p_2 - p_1) \\ &= \sum_{\tilde{r}=0}^{r'} \sum_{\substack{\gamma \in \mathbb{Z}^{n-\ell} \\ |\gamma|=|\alpha|+q'}} \sum_{\substack{\tilde{\gamma} \in \mathbb{Z}^{n-\ell} \\ |\tilde{\gamma}|=r'-\tilde{r}}} c_\gamma \tilde{c}_{\tilde{\gamma}, \tilde{r}} \delta_x D_{\sigma(\tau', F)}^{\gamma+\tilde{\gamma}} D_{\sigma_{\tau', w}}^{\tilde{r}}(p_2 - p_1). \end{aligned}$$

By the induction hypothesis, every term in this last sum is zero (since $\tilde{r} \leq r$ and $|\gamma| + |\tilde{\gamma}| + \tilde{r} = |\alpha| + q' + r' = q + q' \leq r2^{n-\ell}$), and (4.11) follows. We show now that

$$\delta_\xi p = 0, \quad \text{all } \xi \in \Xi_{\tau, q}, \quad (4.12)$$

where $\Xi_{\tau,q}$ is a $\Pi_{\mu_{\ell,q}}^\ell$ -unisolvent set in the interior of τ as defined in Section 3. Let $\xi \in \Xi_{\tau,q}$ be given. Similar to the proof in case $\ell = 0$, we set $\eta_{j_0} := \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma_{\tau,w}}^{r'}$ $\in \mathcal{N}(T_2)$, $\eta_{j_\beta} := \delta_\xi D_{\sigma(\tau,F)}^\alpha D_{\sigma(\tau,T_1)}^\beta \in \mathcal{N}(T_1)$, $|\beta| = r'$. By (4.5), the equation

$$\eta_{j_0} - \sum_{\substack{\beta \in \mathbf{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \eta_{j_\beta} = 0$$

belongs to \mathcal{R} . Hence, we get

$$\begin{aligned} \eta_{j_0} p_1 &= \sum_{\substack{\beta \in \mathbf{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta \eta_{j_\beta} p_1 = \sum_{\substack{\beta \in \mathbf{Z}_+^{n-\ell} \\ |\beta|=r'}} \binom{|\beta|}{\beta} \mu^\beta a_{j_\beta} \\ &= a_{j_0} = \eta_{j_0} p_2, \end{aligned}$$

and (4.12) is proved. In view of (4.11) and (4.12), we conclude by Lemma 2.7 that $p = 0$, which establishes (4.10).

To prove (4.9) for any given $r' = 0, \dots, r$, we set

$$p := D_{\sigma_{F,w}}^{r'}(p_2 - p_1)|_F \in \Pi_{d-r'}^{n-1}.$$

Analysis similar to the above shows that by (4.10) it follows that for each facet τ of F ,

$$\delta_x D_{\sigma(\tau,F)}^q p = 0, \quad \text{all } x \in \tau, q = 0, \dots, 2r - r'.$$

Furthermore, given $\xi \in \Xi_{F,r'}$, the nodal functionals $\eta_{j_1} := \delta_\xi D_{\sigma(F,T_1)}^{r'}$ and $\eta_{j_2} := \delta_\xi D_{\sigma_{F,w}}^{r'}$ are in $\mathcal{N}(T_1)$ and $\mathcal{N}(T_2)$, respectively. By (4.6),

$$\delta_\xi D_{\sigma_{F,w}}^{r'} = (-1)^{r'} \delta_\xi D_{\sigma(F,T_1)}^{r'},$$

and hence

$$\delta_\xi p = \eta_{j_2} p_2 - (-1)^{r'} \eta_{j_1} p_1 = a_{j_2} - (-1)^{r'} a_{j_1} = 0.$$

Thus, Lemma 2.7 implies that $p = 0$, which establishes (4.9) and completes the proof of the theorem. \square

§5. Construction of a local basis for $\mathcal{S}_d^r(\Delta)$

Let $d \geq r2^n + 1$. Since \mathcal{N} is a determining set for $\mathcal{S}_d^r(\Delta)$ by Theorem 3.1, and \mathcal{R} is a complete system of linear relations for \mathcal{N} over $\mathcal{S}_d^r(\Delta)$ by Theorem 4.4, Algorithm 2.4 can be applied to construct a basis $\{\tilde{s}_1, \dots, \tilde{s}_m\}$ for $\mathcal{S}_d^r(\Delta)$. To this end we only need to choose a basis $\{a^{[1]}, \dots, a^{[m]}\}$ for the null space $N(C)$ of the corresponding matrix C . In this section we will show how to choose the basis for $N(C)$ so that the resulting basis for $\mathcal{S}_d^r(\Delta)$ is *local* as defined below.

Let v be a vertex of Δ . We set $\text{star}^1(v) := \text{star}(v)$, and define $\text{star}^\gamma(v)$, $\gamma \geq 2$, recursively as the union of the stars of the vertices in $\mathcal{T}_0 \cap \text{star}^{\gamma-1}(v)$.

Definition 5.1. Let \mathcal{S} be a linear subspace of $\mathcal{S}_d^r(\Delta)$. A basis $\{s_1, \dots, s_m\}$ for \mathcal{S} is called local (or γ -local) if there is an integer γ such that for each $k = 1, \dots, m$, $\text{supp } s_k \subset \text{star}^\gamma(v_k)$, for some vertex v_k of Δ , and the dual functionals $\lambda_1, \dots, \lambda_m$, defined by (2.1), can be localized in the same sets $\text{star}^\gamma(v_1), \dots, \text{star}^\gamma(v_m)$, *i.e.*, for each $k = 1, \dots, m$, $\lambda_k s = 0$ for all $s \in \mathcal{S}$ satisfying $s|_{\text{star}^\gamma(v_k)} = 0$.

We say that an *algorithm produces local bases* if there exists an absolute (integer) constant γ such that any basis constructed by that algorithm is at most γ -local.

The key observation for our construction is that the matrix C of the system \mathcal{R} has a *block diagonal structure*. More precisely, by Remark 4.3 we have

$$\begin{aligned} C &= [\tilde{C} \ O], \\ \tilde{C} &= \text{diag}(C_\tau)_{\tau \in \mathcal{T} \setminus \mathcal{T}_n}, \end{aligned} \quad (5.1)$$

where C_τ is the matrix of the system \mathcal{R}_τ defined in (4.7), and O is the zero matrix corresponding to the nodal functionals in \mathcal{N}_T , $T \in \mathcal{T}_n$, not involved in any smoothness conditions. Moreover, each matrix C_τ itself is block diagonal. Namely,

$$C_\tau = \text{diag}(C_{\tau,q})_{q=0, \dots, r2^{n-\ell-1}}, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n-1, \quad (5.2)$$

where $C_{\tau,q}$ is the matrix of the system $\mathcal{R}_{\tau,q}$ defined in (4.4)–(4.7). If $1 \leq \ell \leq n-1$, then the matrix $C_{\tau,q}$ is again block diagonal,

$$C_{\tau,q} = \text{diag}(C_{\tau,q,\xi})_{\xi \in \Xi_{\tau,q}},$$

with $C_{\tau,q,\xi}$ being the matrix of the system $\mathcal{R}_{\tau,q,\xi}$. By Lemma 2.3, we have

$$\begin{aligned} \dim \mathcal{S}_d^r(\Delta) &= \#\mathcal{N} - \sum_{\tau \in \mathcal{T} \setminus \mathcal{T}_n} \text{rank } C_\tau \\ &= \#\mathcal{N} - \sum_{v \in \mathcal{T}_0} \sum_{q=0}^{r2^{n-1}} \text{rank } C_{v,q} - \sum_{\ell=1}^{n-1} \sum_{\tau \in \mathcal{T}_\ell} \sum_{q=0}^{r2^{n-\ell-1}} \sum_{\xi \in \Xi_{\tau,q}} \text{rank } C_{\tau,q,\xi} \end{aligned} \quad (5.3)$$

Remark 5.2. The formula (5.3) leads to an efficient computation of the dimension of the space $\mathcal{S}_d^r(\Delta)$ by applying to the *small* matrices $C_{v,q}$ and $C_{\tau,q,\xi}$ the standard numerical algorithms of rank determination (see *e.g.* [29]).

In view of (5.1) and (5.2), $N(\tilde{C})$ is an (outer) direct sum of $N(C_{\tau,q})$, $q = 0, \dots, r2^{n-\ell-1}$, $\tau \in \mathcal{T}_\ell$, $0 \leq \ell \leq n-1$. Hence, if we know bases for all $N(C_{\tau,q})$, then we can combine them into a basis for $N(\tilde{C})$ that trivially extends to a basis for $N(C)$. Let $\mathcal{N}_{\tau,q} = \{\eta_j^{[\tau,q]}\}_{j \in J_{\tau,q}}$ and $C_{\tau,q} = (c_{i,j}^{[\tau,q]})_{i \in I_{\tau,q}, j \in J_{\tau,q}}$, so that $\mathcal{R}_{\tau,q}$ has the form

$$\sum_{j \in J_{\tau,q}} c_{i,j}^{[\tau,q]} \eta_j^{[\tau,q]} = 0, \quad i \in I_{\tau,q}.$$

For each $\tau \in \mathcal{T}_\ell$, $0 \leq \ell \leq n-1$, and $q = 0, \dots, r2^{n-\ell-1}$, suppose

$$a^{[\tau, q, k]} = (a_j^{[\tau, q, k]})_{j \in J_{\tau, q}}, \quad k = 1, \dots, m_{\tau, q}, \quad (5.4)$$

form a basis for $N(C_{\tau, q})$. In addition, for each $T \in \mathcal{T}_n$, let $a^{[T, 0, k]} = (a_j^{[T, 0, k]})_{j \in J_{T, 0}}$, $k = 1, \dots, m_T$, be any basis of \mathbb{R}^{m_T} , where $m_T = \#J_{T, 0} = \#\mathcal{N}_T = \#\Xi_T$. We define $\tilde{a}^{[\tau, q, k]} = (\tilde{a}_j^{[\tau, q, k]})_{j \in J}$, with $J = \cup_{\tau, q} J_{\tau, q}$, by

$$\tilde{a}_j^{[\tau, q, k]} := \begin{cases} a_j^{[\tau, q, k]}, & \text{if } j \in J_{\tau, q}, \\ 0, & \text{otherwise.} \end{cases}$$

Then the vectors $\tilde{a}^{[\tau, q, k]}$, $k = 1, \dots, m_{\tau, q}$, $q = 0, \dots, q_\ell$, $\tau \in \mathcal{T}_\ell$, $0 \leq \ell \leq n$, where

$$q_\ell = \begin{cases} r2^{n-\ell-1}, & \text{if } 0 \leq \ell \leq n-1, \\ 0, & \text{if } \ell = n, \end{cases} \quad (5.5)$$

obviously form a basis for $N(C)$. The corresponding basis

$$\tilde{s}^{[\tau, q, k]}, \quad k = 1, \dots, m_{\tau, q}, \quad q = 0, \dots, q_\ell, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n, \quad (5.6)$$

for $\mathcal{S}_d^r(\Delta)$ produced by Algorithm 2.4 satisfies

$$\begin{aligned} \eta_j^{[\tau, q]} \tilde{s}^{[\tau, q, k]} &= a_j^{[\tau, q, k]}, \quad j \in J_{\tau, q}, \\ \eta \tilde{s}^{[\tau, q, k]} &= 0, \quad \text{all } \eta \in \mathcal{N} \setminus \mathcal{N}_{\tau, q}. \end{aligned} \quad (5.7)$$

Denote by

$$\tilde{\lambda}^{[\tau, q, k]}, \quad k = 1, \dots, m_{\tau, q}, \quad q = 0, \dots, q_\ell, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n, \quad (5.8)$$

the dual basis for $\mathcal{S}_d^r(\Delta)^*$ determined by the duality condition

$$\tilde{\lambda}^{[\tau, q, k]} \tilde{s}^{[\tau', q', k']} = \begin{cases} 1, & \text{if } \tau = \tau', q = q' \text{ and } k = k', \\ 0, & \text{otherwise.} \end{cases}$$

Theorem 5.3. *The basis (5.6) for $\mathcal{S}_d^r(\Delta)$, where $d \geq r2^n + 1$, is local. Moreover,*

$$\text{supp } \tilde{s}^{[\tau, q, k]} \subset \text{star}(\tau), \quad (5.9)$$

and the dual basis (5.8) satisfies

$$\tilde{\lambda}^{[\tau, q, k]} s = 0 \quad \text{for all } s \in \mathcal{S}_d^r(\Delta) \text{ such that } s|_{\text{star}(\tau)} = 0. \quad (5.10)$$

Proof: By (5.7) we have $\eta \tilde{s}^{[\tau, q, k]} = 0$ for all $\eta \in \mathcal{N} \setminus \mathcal{N}_{\tau, q}$. Since $\mathcal{N}_{\tau, q} \cap \mathcal{N}(T) \neq \emptyset$ only if $\tau \subset T$, (5.9) follows from the fact that $\mathcal{N}(T)$ is a determining set for Π_d^n , see Theorem 3.2. To show (5.10), we consider the matrix A with columns

$$\tilde{a}^{[\tau, q, k]}, \quad k = 1, \dots, m_{\tau, q}, \quad q = 0, \dots, q_\ell, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n.$$

This matrix is block diagonal,

$$\begin{aligned} A &= \text{diag}(A_\tau)_{\tau \in \mathcal{T}}, \\ A_\tau &= \text{diag}(A_{\tau, q})_{q=0, \dots, q_\ell}, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n, \end{aligned}$$

where $A_{\tau, q} := (a_j^{[\tau, q, k]})_{j \in J_{\tau, q}, k=1, \dots, m_{\tau, q}}$. Let $B_{\tau, q}$ be a left inverse of $A_{\tau, q}$. Then $B := \text{diag}(B_\tau)_{\tau \in \mathcal{T}}$, with $B_\tau = \text{diag}(B_{\tau, q})_{q=0, \dots, q_\ell}$, $\tau \in \mathcal{T}_\ell$, $0 \leq \ell \leq n$, is a left inverse of A . Hence, by Lemma 2.5, $\tilde{\lambda}^{[\tau, q, k]}$ is a linear combination of $\eta_j^{[\tau, q]}$, $j \in J_{\tau, q}$. This implies (5.10) since for every $\eta \in \mathcal{N}_{\tau, q}$ we obviously have $\eta s = 0$ if $s|_{\text{star}(\tau)} = 0$. \square

Remark 5.4. A similar analysis of the space $\mathcal{S}_d^r(\Delta)$, $d \geq r2^n + 1$, was done in [2] by using Bernstein-Bézier smoothness conditions [5]. However, the existence of a local basis for $\mathcal{S}_d^r(\Delta)$ was shown in [2] only for $n \leq 3$. The main advantage of the nodal techniques used here is that the matrix \tilde{C} in (5.1) is block diagonal, while the matrix of Bernstein-Bézier smoothness conditions is block triangular (see [6]).

§6. A stable local basis for $\mathcal{S}_d^r(\Delta)$

In this section we show that if the sets $\Xi_{\tau,q}$ and Ξ_T as well as the bases (5.4) for $N(C_{\tau,q})$ are properly chosen, then an appropriately renormalized version of the local basis for $\mathcal{S}_d^r(\Delta)$ constructed above is in addition stable.

Let us denote by ω_Δ the shape regularity constant of the triangulation Δ ,

$$\omega_\Delta := \max_{T \in \Delta} \frac{h_T}{\rho_T},$$

where h_T and ρ_T are the diameter of T and the diameter of its inscribed sphere, respectively. Given $M = \bigcup_{T \in \tilde{\Delta}} T$, where $\tilde{\Delta} \subset \Delta$, we denote by $|M|$ the n -dimensional volume of M .

Definition 6.1. Let \mathcal{S} be a linear subspace of $\mathcal{S}_d^r(\Delta)$. We say that a basis $\{\tilde{s}_1, \dots, \tilde{s}_m\}$ for \mathcal{S} is L_p -stable if there exist constants K_1, K_2 depending only on n, r, d and ω_Δ , such that for any $\alpha = (\alpha_1, \dots, \alpha_m) \in \mathbb{R}^m$,

$$K_1 \|\alpha\|_{\ell_p} \leq \left\| \sum_{k=1}^m \alpha_k \tilde{s}_k \right\|_{L_p(\Omega)} \leq K_2 \|\alpha\|_{\ell_p}.$$

To establish stability of a local basis it seems most convenient to use the following general lemma; see also [23].

Lemma 6.2. Let $\{s_1, \dots, s_m\}$ be a γ -local basis for \mathcal{S} , and let $\{\lambda_1, \dots, \lambda_m\} \subset \mathcal{S}^*$ be its dual basis. Suppose that

$$\|s_k\|_{L_\infty(\Omega)} \leq C_1, \quad k = 1, \dots, m, \quad (6.1)$$

and

$$|\lambda_k s| \leq C_2 \|s\|_{L_\infty(\text{star}^\gamma(v_k))}, \quad \text{all } s \in \mathcal{S}, \quad k = 1, \dots, m, \quad (6.2)$$

where $\text{supp } s_k \subset \text{star}^\gamma(v_k)$ as in Definition 5.1. Then for any $\alpha = (\alpha_1, \dots, \alpha_m) \in \mathbb{R}^m$,

$$K_1 C_2^{-1} \|\alpha\|_{\ell_p} \leq \left\| \sum_{k=1}^m \alpha_k \frac{s_k}{|\text{supp } s_k|^{1/p}} \right\|_{L_p(\Omega)} \leq K_2 C_1 \|\alpha\|_{\ell_p}, \quad 1 \leq p \leq \infty, \quad (6.3)$$

where K_1, K_2 are some constants depending only on n, r, d, γ and ω_Δ .

Proof: Let $s = \sum_{k=1}^m \alpha_k \frac{s_k}{|\text{supp } s_k|^{1/p}}$. We first prove the upper bound in (6.3). Given an n -simplex $T \in \Delta$, we have by (6.1)

$$\|s|_T\|_{L_p(T)} \leq C_1 (\#\Sigma_T)^{1-1/p} \begin{cases} \left(\sum_{k \in \Sigma_T} |\alpha_k|^p \right)^{1/p}, & \text{if } 1 \leq p < \infty, \\ \max_{k \in \Sigma_T} |\alpha_k|, & \text{if } p = \infty, \end{cases}$$

where

$$\Sigma_T := \{k : T \subset \text{supp } s_k\}. \quad (6.4)$$

As in the bivariate case (see Lemmas 3.1 and 3.2 in [23]), it is not difficult to show that

$$\#\{T \in \Delta : T \subset \text{star}^\gamma(v_k)\} \leq \tilde{K}_1, \quad (6.5)$$

and

$$\max \left\{ \frac{|\text{star}^\gamma(v_k)|}{|T|} : T \subset \text{star}^\gamma(v_k) \right\} \leq \tilde{K}_2, \quad (6.6)$$

where \tilde{K}_1, \tilde{K}_2 are some constants depending only on n, γ and ω_Δ . Hence, for $1 \leq p < \infty$ we have

$$\|s\|_{L_p(\Omega)}^p = \sum_{T \in \Delta} \|s|_T\|_{L_p(T)}^p \leq \tilde{K}_1 C_1^p (\#\Sigma_T)^{p-1} \|\alpha\|_{\ell_p}^p,$$

which shows that the upper bound will be established for all $1 \leq p \leq \infty$ if we prove that $\#\Sigma_T$ is bounded by a constant depending only on n, r, d, γ and ω_Δ . To this end we note that since the basis $\{s_1, \dots, s_m\}$ is γ -local, $\text{supp } s_k \subset \text{star}^{2\gamma}(v)$, for all $k \in \Sigma_T$, where v is any vertex of T . Therefore, the set $\{s_k : k \in \Sigma_T\}$ is linearly independent on $\text{star}^{2\gamma}(v)$, and its cardinality $\#\Sigma_T$ does not exceed the dimension of the space of all piecewise polynomials of degree d on $\text{star}^{2\gamma}(v)$, *i.e.*, $\#\Sigma_T \leq N \binom{n+d}{n}$, where N is the number of n -simplices of Δ lying in $\text{star}^{2\gamma}(v)$. By (6.5), N is bounded by a constant depending only on n, γ and ω_Δ , and the assertion follows.

To establish the lower bound in (6.3), we obtain by (6.2),

$$|\alpha_k| = |\text{supp } s_k|^{1/p} |\lambda_k s| \leq C_2 |\text{supp } s_k|^{1/p} \|s\|_{L_\infty(\text{star}^\gamma(v_k))}, \quad k = 1, \dots, m.$$

Since $\|s\|_{L_\infty(\text{star}^\gamma(v_k))} \leq \|s\|_{L_\infty(\Omega)}$, this completes the proof in the case $p = \infty$. Suppose $1 \leq p < \infty$. By a Nikolskii-type inequality, see *e.g.* [27, p. 56], for some n -simplex $T_k \subset \text{star}^\gamma(v_k)$,

$$\|s\|_{L_\infty(\text{star}^\gamma(v_k))} = \|s|_{T_k}\|_{L_\infty(T_k)} \leq \tilde{K}_3 |T_k|^{-1/p} \|s|_{T_k}\|_{L_p(T_k)},$$

where \tilde{K}_3 is a constant depending only on n and d . Since $\text{supp } s_k \subset \text{star}^\gamma(v_k)$, we have by (6.6),

$$\frac{|\text{supp } s_k|}{|T_k|} \leq \tilde{K}_2.$$

Therefore,

$$\sum_{k=1}^m |\alpha_k|^p \leq \tilde{K}_2 (\tilde{K}_3 C_2)^p \sum_{k=1}^m \int_{T_k} |s|^p.$$

We now have to bound the number of appearances of a given n -simplex T_k on the right-hand side of the above inequality. If $T_{k_1} = T_{k_2}$, then $\text{star}^\gamma(v_{k_1}) \cap \text{star}^\gamma(v_{k_2}) \neq \emptyset$. Hence, $\text{supp } s_{k_2} \subset \text{star}^{3\gamma}(v_{k_1})$. Thus, for all k such that $T_k = T_{k_1}$,

$$\text{supp } s_k \subset \text{star}^{3\gamma}(v_{k_1}).$$

The set $\{s_k : T_k = T_{k_1}\}$ is linearly independent on $\text{star}^{3\gamma}(v_{k_1})$, and it can be shown as above that its cardinality is bounded by a constant \tilde{K}_4 depending only on n, γ and ω_Δ . Therefore,

$$\sum_{k=1}^m \int_{T_k} |s|^p \leq \tilde{K}_4 \int_{\Omega} |s|^p,$$

which completes the proof. \square

We are ready to formulate our main result about stability of the local basis constructed in Section 5. For each $\tau \in \mathcal{T}$, denote by h_τ the *diameter* of the set $\text{star}(\tau)$. (This is compatible with the above notation h_T for $T \in \mathcal{T}_n = \Delta$ since $\text{star}(T) = T$.)

Theorem 6.3. *Suppose that*

- 1) every $\Xi_{\tau,q}$, $q = 0, \dots, q_\ell$, $\tau \in \mathcal{T}_\ell$, $1 \leq \ell \leq n$ (where $\Xi_{T,0} := \Xi_T$ if $T \in \mathcal{T}_n$), is chosen to be the set of uniformly distributed points in the interior of τ , as defined in (3.5); and
- 2) for each $q = 0, \dots, q_\ell$ and $\tau \in \mathcal{T}_\ell$, $0 \leq \ell \leq n$, the vectors

$$a^{[\tau,q,k]} = (a_j^{[\tau,q,k]})_{j \in J_{\tau,q}}, \quad k = 1, \dots, m_{\tau,q}, \quad (6.7)$$

form an orthonormal basis for $N(C_{\tau,q})$.

Let $\tilde{s}^{[\tau,q,k]}$ be the local basis functions for $\mathcal{S}_d^r(\Delta)$, $d \geq r2^n + 1$, constructed as in Section 5. Then for every $1 \leq p \leq \infty$, the splines

$$h_\tau^{-q} |\text{star}(\tau)|^{-\frac{1}{p}} \tilde{s}^{[\tau,q,k]}, \quad k = 1, \dots, m_{\tau,q}, \quad q = 0, \dots, q_\ell, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n,$$

form an L_p -stable local basis for $\mathcal{S}_d^r(\Delta)$.

Proof: As shown in Section 5, the splines $\tilde{s}^{[\tau,q,k]}$ are 1-local, and $\text{supp } \tilde{s}^{[\tau,q,k]} \subset \text{star}(\tau)$. By (6.6),

$$|\text{supp } \tilde{s}^{[\tau,q,k]}| \leq |\text{star}(\tau)| \leq \tilde{K}_2 |\text{supp } \tilde{s}^{[\tau,q,k]}|,$$

where \tilde{K}_2 depends only on n and ω_Δ . Hence, in view of Lemma 6.2, the theorem will be established once we prove that

$$\|\tilde{s}^{[\tau,q,k]}\|_{L_\infty(\Omega)} \leq C_1 h_\tau^q, \quad (6.8)$$

and

$$|\tilde{\lambda}^{[\tau,q,k]}_s| \leq C_2 h_\tau^{-q} \|s\|_{L_\infty(\text{star}(\tau))}, \quad \text{all } s \in \mathcal{S}_d^r(\Delta), \quad (6.9)$$

where the constants C_1, C_2 depend only on n, r, d and ω_Δ .

We first show (6.8). Since $\text{supp } \tilde{s}^{[\tau,q,k]} \subset \text{star}(\tau)$, we have $\|\tilde{s}^{[\tau,q,k]}\|_{L_\infty(\Omega)} = \|\tilde{s}^{[\tau,q,k]}\|_{L_\infty(\text{star}(\tau))}$. Let T be an n -simplex in $\text{star}(\tau)$, and let \mathcal{H}_T be the Hermite interpolation operator defined in (3.4). Since $\tilde{s}^{[\tau,q,k]}|_T = \mathcal{H}_T \tilde{s}^{[\tau,q,k]}|_T$, we have by Lemma 3.3,

$$\|\tilde{s}^{[\tau,q,k]}|_T\|_{L_\infty(T)} \leq \tilde{K}_5 \max_{\eta \in \mathcal{N}(T)} h_T^{q(\eta)} |\eta \tilde{s}^{[\tau,q,k]}|,$$

where \tilde{K}_5 depends only on n, r and d . Now, by (5.7), $\eta \tilde{s}^{[\tau,q,k]} = 0$ for all $\eta \in \mathcal{N}(T) \setminus \mathcal{N}_{\tau,q}$, and

$$\eta_j^{[\tau,q]} \tilde{s}^{[\tau,q,k]} = a_j^{[\tau,q,k]}, \quad j \in J_{\tau,q}.$$

Since the vectors $a^{[\tau,q,k]}$, $k = 1, \dots, m_{\tau,q}$, are orthonormal, we have $|a_j^{[\tau,q,k]}| \leq 1$. Taking into account that $q(\eta) = q$ for all $\eta \in \mathcal{N}_{\tau,q}$, we arrive at the estimate

$$\|\tilde{s}^{[\tau,q,k]}|_T\|_{L_\infty(T)} \leq \tilde{K}_5 h_T^q \leq \tilde{K}_5 h_\tau^q,$$

and (6.8) is proved.

By our hypotheses, the columns of the matrix

$$A_{\tau,q} = [a_j^{[\tau,q,k]}]_{j \in J_{\tau,q}, k=1, \dots, m_{\tau,q}} \quad (6.10)$$

are orthonormal. Hence, $A_{\tau,q}^T$ is a left inverse of $A_{\tau,q}$. By Lemma 2.5 and the proof of Theorem 5.3, it follows that the dual functional $\tilde{\lambda}^{[\tau,q,k]}$ can be computed as

$$\tilde{\lambda}^{[\tau,q,k]} = \sum_{j \in J_{\tau,q}} a_j^{[\tau,q,k]} \eta_j^{[\tau,q]}.$$

Therefore, for any $s \in \mathcal{S}_d^r(\Delta)$,

$$|\tilde{\lambda}^{[\tau,q,k]}_s| = \left| \sum_{j \in J_{\tau,q}} a_j^{[\tau,q,k]} \eta_j^{[\tau,q]} s \right| \leq \#J_{\tau,q} \max_{j \in J_{\tau,q}} |\eta_j^{[\tau,q]} s|.$$

Given $j \in J_{\tau,q}$, let T be an n -simplex such that $\tau \subset T$ and $\eta_j^{[\tau,q]} \in \mathcal{N}(T)$. Since $\eta_j^{[\tau,q]}$ is a nodal functional of order q , we have by Markov inequality (see, e.g. [13]),

$$|\eta_j^{[\tau,q]} s| = |\eta_j^{[\tau,q]} s|_T \leq \tilde{K}_6 \rho_T^{-q} \|s|_T\|_{L_\infty(T)} \leq \tilde{K}_6 \omega_\Delta^q h_T^{-q} \|s\|_{L_\infty(\text{star}(\tau))},$$

where \tilde{K}_6 is a constant depending only on n and d . Since $\#J_{\tau,q} = \#\mathcal{N}_{\tau,q}$ is bounded above by a constant depending only on n, r, d and ω_Δ , the estimate (6.9) follows, and the proof is complete. \square

It is easy to see that Theorem 6.3 remains valid for any $\Xi_{\tau,q}$ such that the Hermite interpolation operator defined by (3.4) satisfies (3.6), and for any choice of the bases (6.7) for $N(C_{\tau,q})$ such that the *condition number* of the matrix (6.10) is bounded by a constant K depending only on n, r, d and ω_Δ ; compare [6]. However, there is a good reason to prefer, at least in practice, an *orthonormal basis* for $N(C_{\tau,q})$, as explained in the following remark.

Remark 6.4. There is a numerically efficient way to compute an orthonormal basis $a^{[\tau,q,k]} = (a_j^{[\tau,q,k]})_{j \in J_{\tau,q}}$, $k = 1, \dots, m_{\tau,q}$, for each $N(C_{\tau,q})$, as required in the above theorem. Namely, construct by an appropriate algorithm a *singular value decomposition* $C_{\tau,q} = Q_L X Q_R^T$ of the matrix $C_{\tau,q}$, where Q_L, Q_R are orthogonal matrices, and $X = [D \ O]$, $D = \text{diag}(\sigma_1, \dots, \sigma_p)$, with $\sigma_1 \geq \dots \geq \sigma_p \geq 0$ being the singular values of $C_{\tau,q}$, see *e.g.* [29]. Obviously, $m_{\tau,q}$ is equal to the number of zero columns in X (including the columns corresponding to zero singular values). Hence, the columns of the matrix $[O \ I_{m_{\tau,q}}]^T$ constitute an orthonormal basis for $N(X)$. Since $C_{\tau,q} Q_R = Q_L X$, the columns of $A_{\tau,q} = Q_R [O \ I_{m_{\tau,q}}]^T$ form the desired orthonormal basis for $N(C_{\tau,q})$. Thus, the matrix $A_{\tau,q}$ consists of the last $m_{\tau,q}$ columns of Q_R .

§7. Superspline spaces

In this section we construct stable local bases for the superspline subspaces of $\mathcal{S}_d^r(\Delta)$.

Definition 7.1. Let $\rho = (\rho_\tau)_{\tau \in \mathcal{T} \setminus (\mathcal{T}_{n-1} \cup \mathcal{T}_n)}$ be a sequence of integers satisfying

$$r \leq \rho_\tau \leq 2^{n-\ell-1}, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n-2. \quad (7.1)$$

The linear space of splines

$$\mathcal{S}_d^{r,\rho}(\Delta) := \{s \in \mathcal{S}_d^r(\Delta) : s \text{ is } \rho_\tau\text{-times differentiable across } \tau, \\ \text{for all } \tau \in \mathcal{T} \setminus (\mathcal{T}_{n-1} \cup \mathcal{T}_n)\} \quad (7.2)$$

is called a superspline space.

In the limiting case $\rho_\tau = 2^{n-\ell-1}$, $\tau \in \mathcal{T} \setminus (\mathcal{T}_{n-1} \cup \mathcal{T}_n)$, the superspline spaces were introduced and studied in [8–11], see also [3,4]. In particular, local bases for $\mathcal{S}_d^{r,\rho}(\Delta)$, where $\rho_\tau = 2^{n-\ell-1}$, were constructed in [11] and [4]. For general ρ_τ , but only in the bivariate case $n = 2$, the superspline spaces were explored in [22,28] and, more recently, in [18,19].

As we will see, our method of construction of a stable local basis can be applied to the spaces (7.2). We first have to extend the system \mathcal{R} of smoothness conditions defined in (4.4)–(4.8) to a larger system $\hat{\mathcal{R}}$, by allowing a larger range of r' in (4.4) and (4.5). Namely, we include in the extended systems $\hat{\mathcal{R}}_{v,q}$ and $\hat{\mathcal{R}}_{\tau,q,\xi}$ all conditions (4.4) and (4.5), respectively, where $0 \leq r' \leq \min\{\rho_\tau, q\}$. The systems $\mathcal{R}_{F,q,\xi}$ are not enlarged, *i.e.*, we set $\hat{\mathcal{R}}_{F,q,\xi} = \mathcal{R}_{F,q,\xi}$.

By the method of proof of Theorem 4.4 it is not difficult to establish the following analogue of it.

Theorem 7.2. *The set $\hat{\mathcal{R}}$ is a complete system of linear relations for \mathcal{N} over $\mathcal{S}_d^{r,\rho}(\Delta)$.*

It is easy to see that the matrix \hat{C} of the system $\hat{\mathcal{R}}$ possesses a block diagonal structure similar to the structure of the matrix C considered in Section 5. Therefore,

all results about the dimension and the local bases carry over to the superspline spaces. Thus, we have

$$\begin{aligned} \dim \mathcal{S}_d^{r,\rho}(\Delta) &= \#\mathcal{N} - \sum_{\tau \in \mathcal{T} \setminus \mathcal{T}_n} \text{rank } \hat{C}_\tau \\ &= \#\mathcal{N} - \sum_{v \in \mathcal{T}_0} \sum_{q=0}^{r2^{n-1}} \text{rank } \hat{C}_{v,q} - \sum_{\ell=1}^{n-1} \sum_{\tau \in \mathcal{T}_\ell} \sum_{q=0}^{r2^{n-\ell-1}} \sum_{\xi \in \Xi_{\tau,q}} \text{rank } \hat{C}_{\tau,q,\xi}, \end{aligned} \quad (7.3)$$

where \hat{C}_τ , $\hat{C}_{v,q}$ and $\hat{C}_{\tau,q,\xi}$ are the appropriate blocks of \hat{C} . Define the splines

$$\hat{s}^{[\tau,q,k]}, \quad k = 1, \dots, \hat{m}_{\tau,q}, \quad q = 0, \dots, q_\ell, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n, \quad (7.4)$$

by the condition

$$\begin{aligned} \eta_j^{[\tau,q]} \hat{s}^{[\tau,q,k]} &= \hat{a}_j^{[\tau,q,k]}, \quad j \in J_{\tau,q}, \\ \eta \hat{s}^{[\tau,q,k]} &= 0, \quad \text{all } \eta \in \mathcal{N} \setminus \mathcal{N}_{\tau,q}, \end{aligned} \quad (7.5)$$

where

$$\hat{a}^{[\tau,q,k]} = (\hat{a}_j^{[\tau,q,k]})_{j \in J_{\tau,q}}, \quad k = 1, \dots, \hat{m}_{\tau,q}, \quad (7.6)$$

is a basis for $N(\hat{C}_{\tau,q})$.

Theorem 7.3. *The splines (7.4) form a local basis for $\mathcal{S}_d^{r,\rho}(\Delta)$, where ρ satisfies (7.1), and $d \geq r2^n + 1$. Moreover,*

$$\text{supp } \hat{s}^{[\tau,q,k]} \subset \text{star}(\tau), \quad (7.7)$$

and the dual basis (5.8) satisfies

$$\hat{\lambda}^{[\tau,q,k]} s = 0 \quad \text{for all } s \in \mathcal{S}_d^r(\Delta) \text{ such that } s|_{\text{star}(\tau)} = 0. \quad (7.8)$$

Since (7.4) is a local basis for $\mathcal{S}_d^{r,\rho}(\Delta)$, Lemma 6.2 can be applied, and the same argument as in the proof of Theorem 6.3 shows that the following result holds.

Theorem 7.4. *Suppose that*

- 1) every $\Xi_{\tau,q}$, $q = 0, \dots, q_\ell$, $\tau \in \mathcal{T}_\ell$, $1 \leq \ell \leq n$ (where $\Xi_{T,0} := \Xi_T$ if $T \in \mathcal{T}_n$), is chosen to be the set of uniformly distributed points in the interior of τ , as defined in (3.5), and
- 2) for each $q = 0, \dots, q_\ell$ and $\tau \in \mathcal{T}_\ell$, $0 \leq \ell \leq n$, vectors $\hat{a}^{[\tau,q,k]} = (\hat{a}_j^{[\tau,q,k]})_{j \in J_{\tau,q}}$, $k = 1, \dots, m_{\tau,q}$, form an orthonormal basis for $N(\hat{C}_{\tau,q})$.

Let $\hat{s}^{[\tau,q,k]}$ be the local basis functions (7.4) for $\mathcal{S}_d^{r,\rho}(\Delta)$, where ρ satisfies (7.1), and $d \geq r2^n + 1$. Then for every $1 \leq p \leq \infty$, the splines

$$h_\tau^{-q} |\text{star}(\tau)|^{-\frac{1}{p}} \hat{s}^{[\tau,q,k]}, \quad k = 1, \dots, m_{\tau,q}, \quad q = 0, \dots, q_\ell, \quad \tau \in \mathcal{T}_\ell, \quad 0 \leq \ell \leq n,$$

form an L_p -stable local basis for $\mathcal{S}_d^{r,\rho}(\Delta)$.

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