



An innovative natural air-cooling system technique for temperature-rise suppression on the permanent magnet synchronous machines

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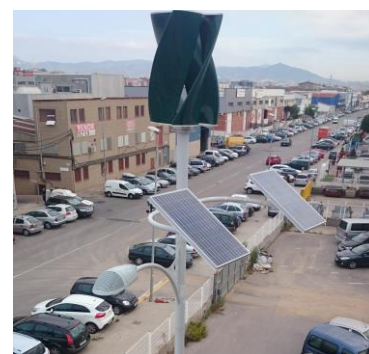
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ABSTRACT

A segmented stator core due to closed-slot topology and type of used winding is subjected to a high temperature-rise. The application-oriented study is aimed to reduce temperature-rise of the conventional model at the stator core via radial and circumferential airflow ducts. This paper investigates a natural air-cooling system which decreases the temperature-rise in the stator core with no additional cost for very first time. The objective is reached without use of any external sources to pushes the air into the ducts. A three-dimensional finite-element (3D-FEA) thermal analysis based on an embedded cooling system with various number of ducts for a permanent magnet synchronous machines (PMSMs) with two-layer fractional slot-concentrated stator winding is proposed, in which the coolant's path is a part of the research's innovation. A temperature distribution, and heat transfer comparison among all FE models such as conventional, two and four ducts in-core natural cooling systems will be comprehensively presented through freezing the electromagnetic performance. The alternative models using FEA, and computational fluid dynamic (CFD) are experimentally verified the innovative technique, in which the generator is operated by a vertical axis twisted savonius type wind turbine (VAWT).



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1. Introduction

1.1. Motivation

The PMSMs are subject to a high thermal stresses during their operation, if these stresses are observed, then that is possible to adapt the machine's control parameters such as current depending on the load and the supplying technique, in order to avoid overheating and a significant heat transfer problems. The conventional model observes with a considerable temperature-rise and related critical heat transfer at the stator core due to segmentation, in which closed-slot configuration is addressed for electromagnetic improvement. In fact, there are many type of

cooling systems [1] to overcome this challenge. Although, they can be costly for a number of applications. We studied an innovative airflow coolant for an application-oriented case, in which the cooling system is exempt of employing any external resources to remove the heat in the stator core.

1.2. Literature review

The outer-rotor surface mounted PM synchronous machines (PMSMs), where two-layer fractional slot-concentrated stator winding is employed. The outer-rotor machines can reach a high torque at low speed, in which for the direct-drive small power generation applications with low-speed operation as [1].

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R. Wrobel, *et al.* [2] studied a thermal analysis of a segmented stator winding design. While the thermal performance played one of the major factors limiting a machine's output capability, a thermal test on a complete prototype machine is an essential part of the design process. The method was allowed for a rapid and inexpensive assessment of the thermal performance of the complete machine and early identification of design modifications needed. The research has been applied to the design of a highly efficient and compact permanent-magnet traction motor. A thermal model for a single-tooth was developed and supported by tests to identify key heat transfer coefficients.

Reference [3], discussed the problem of temperature-rise that influencing the operation performance and also the life time of the PMSM. Based on double Fourier series decomposition, the research established a 3-D analytical model of PM eddy-current loss in the PMSM that considers the effect of time and space harmonics. By applying the thermal network model, the influence of different speed and load on temperature-rise has been analyzed, and a steady-state thermal analysis of the motor has been performed using finite element analysis. The paper caters the theoretical basis for the design of ventilation and cooling system of the PMSM.

M. Polikarpova, *et al.* [4] presented a direct liquid cooling system design for an 8 (MW) outer-rotor direct-drive permanent magnet synchronous motor (PMSG). The approach was novel for wind turbine generators, so its impact on the thermal behavior and reliability for the total electrical machine has been evaluated and reported. In addition, the article focused on a dramatic cost savings that can be realized with the development of a more effective stator windings cooling systems.

In reference [6], the authors discussed a thermal analysis and cooling system design of a dual mechanical port (DMP) using inner wound rotor is surrounded by the stator and the permanent magnet (PM) outer-rotor prototype machine are investigated. To predict the heat sources in actual operation, a transient co-simulation method has been presented. Thermal parameters and the flow distribution at the cooling ducts are calculated in detail. Finite-element analysis of the thermal field is carried out to obtain the temperature distribution and two typical thermal contacts are considered. A robust fully forced-air cooling system with inner rotor teeth ducts is proposed for the DMP machine and a 10-kW DMP machine is prototyped.

Marco Tosetti, *et al.* described a complete conjugate heat transfer analysis of a scaled-sized prototype of an integrated air-cooled surface-mounted permanent-magnet generator for the "more-electric engine" application. Additionally, to predict and prevent the critical working conditions of the prototype, the adopted cooling system has been investigated using a complete fluid-thermal analysis. Due to the capabilities of computational fluid dynamic software, it has been possible to analyze the temperature and flow fields inside the machine, giving an idea about the distribution of the thermal quantities both inside the solid materials and above the surfaces [21].

The finite-element analysis (FEA), CFD, and lumped-parameter-based methodologies are employed for the entire study [7–12], [14–20], [24–28].

1.3. Our contribution

In this paper, a speed-functional model with radial and circumferential airflow ducts under 3-D thermal transient analysis of three FE models with two innovative structures are studied using an in-core circular natural air cooling system, regardless of any external sources (liquid and/ or air) at the stator yoke of an outer-rotor surface-mounted PM synchronous generator with closed-slot topology. Additionally, the proposed model is verified through its heat transfer calculation at each heat flux sensors, and along with experimental investigation. The CFD analysis is evaluated the heat transfer at a number of specific positions of heat flux sensors on the rotor and stator cores. Heat transfer coefficients are measured at 9 key positions in the stator and rotor cores, and accordingly a good performance of thermal analysis is also predicted. The natural airflow is assumed to vary over the range from 0 to 0.6 (m³/s), and temperature between 18 to 35 (°C). Moreover, the rotor speed limited to 500 rpm due to malfunctioning in higher speeds of the data-loggers recording data from sensors on the machine. At last, the temperature-rise is suppressed by 11 °C without fail in the efficiency. Whereas, the electromagnetic performance of the FE models is also examined numerically and experimentally.

2. Design and problem statement

During the operation time, a high temperature-rise is experimentally measured in the stator core of the conventional FE model due to a high mechanical and thermal stresses. Under test bench, the temperature-rise of 83.8 (°C), in which the direction of heat transfer is from inner surface of the stator (with a higher temperature) to outer surface of rotor (with lower temperature), that is governed by the second law of thermodynamics. Natural air cooling system based on the robustness of the FE results depends on the fitness of the generated mesh at the pre-calculation stage. Thermal FE modelling should be taken into account free of any following errors at this stage (1) improper geometric description (if an axial

Nomenclature

c	The specific heat (J/ kg.K)
T	The temperature (°C)
$\{v\}$	The velocity vector for mass transport of heat
D_{sh}	Shaft diameter (mm)
D_r	Rotor diameter (mm)
S_d	Effective slot-depth (mm)
α_p	Ratio of pole-arc to pole-pitch
n_m	Minimum speed (rpm)
P_r	Rated power (W)
S_w	Slot-width (mm)
$\{L\}$	The vector operator
t	The time (s)
Q	The heat source rate per unit volume (W/m ³)
ρ	The mass density (kg/m ³)
J_c	Current density (A/mm ²)
l_s	Active stack stator length
m	Stator number of phases
N	Number of turns per phase
$2p$	Number of poles
Q_s	Total number of the stator slots
δ_g	Air-gap length (mm)
$\% \eta$	Percentage of the efficiency

Table 1 Initial design of the machine geometry

Variable	Linear current density fixed	
l_s	100	mm
D_{sh}	50	mm
D_{se}	410	mm
δ_g	0.6	mm
S_w	15	mm
S_d	50	mm
n_m	150	rpm
P_r	6	kW
Q_s	36	
α_p	0.55	
2P	40	
m	3	

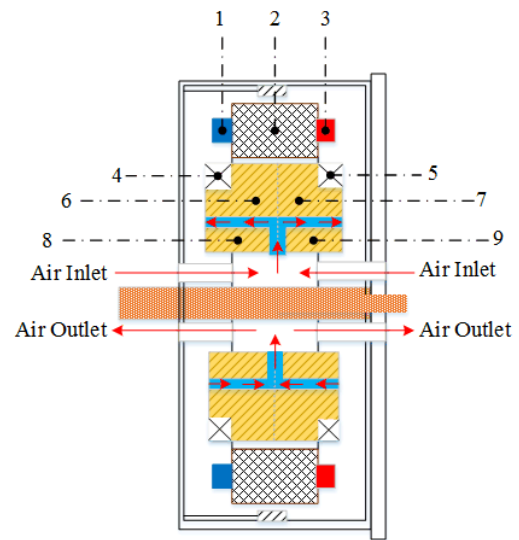
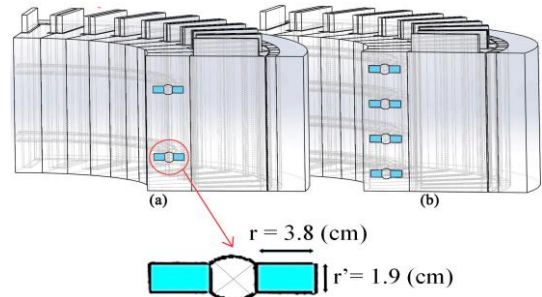
symmetry and/ or rotational symmetry has been accounted without considering that an anti-symmetric load), (2) a poor definition of the used materials, for instance the limit of Poisson's ratio at isotropic materials, (3) improper definition of the load that is not recommended to simplify a complex load states or a number of loads with one load, (4) a wrong boundary expresses, (5) choosing a wrong kind of analysis (depends on the case), (6) singularity concept existing in the model which leads the points in the model where values tend toward an infinite value; FE model, where the infinite density and gravity are equivalent to an infinite stress in a sharp corner [22]. Therefore, a good mesh can be successfully generated for all three FE models.

The design solution alternatively resolves the problem using an innovative airflow path, in which the radial ducts are perpendicular to the shaft and pushes the air into the ducts due to rotation of the shaft and its path to out of housing, where we expect the natural airflow to vary over the range from 0 to 0.6 (m^3/s). Fig. 2 illustrates the main air-flow path, in which the innovative models consist of circumferentially (circular at the stator yoke) and axially (from the circular path to the inner face of the ducts). In continue, the heated air-flow goes out through the gap between the stator core and the shaft. Moreover, position of heat flux sensors is shown, in which positions 1, and 3 are on a pole-pair. Position 2, in the center of rotor yoke. Positions 4, and 5 on the stator centerlines of the coil front/ and bottom faces. Positions 6, 7, 8, and 9 at the different points of the stator core.

Fig. 3 shows that ducts are introduced to separate the machine axial segments for enhance the thermal dissipation capability with relevant ($r = 3.8mm$) dimensions. Table. 2 represents the used materials for different parts of the models with their thermal specifications such as thermal conductivity and specific heat which greatly affect the accuracy of thermal analysis. The problem of the conventional model is determined after a careful steady-state thermal analysis using lumped-circuit (LC) and FE methods that Fig.3 carries the results under condition of 35 ($^{\circ}C$) ambient temperature and 150 (rpm) rated speed of the shaft. The LC method which modeled similar to an electrical circuit solves the steady-state temperatures at each node via solving a set of non-linear equations [23]

$$\Delta T = P \times R \quad (1)$$

where ΔT indicates the temperature-rise that corresponds to the voltage of electrical circuit, P stands for power source that corresponds to current of electrical circuit, as well as R shows thermal resistance that corresponds to electrical resistances of electrical circuit. The FEA based on a 3-D model solves partial differential equations (PDEs) using ANSYS multi-physics

**Fig. 2.** The main heat transfer paths and position of heat flux sensors on the rotor and stator cores**Fig. 3.** 3-D sketch of the innovative coolant models with, a) 2-ducts, and b) 4-ducts

engineering, where the heat transfer at the body of the model is controlled using below heat equation [24]

$$Q = \rho C \left(\frac{\partial T}{\partial t} \right) - \nabla \cdot (k \nabla T) \quad (2)$$

where Q is the heat source, ρ is the density, C is the heat capacitance, and k shows the thermal conductivity. Additionally, extra transverse heat flux terms of the convection and with regarding to Fig. 3, the stator core of the conventional model is the major challenge to cool up. However, the cost of this design process is highlighted, thus, the innovative FE models are accounted to adjust the temperature-rise of stator core cooling system.

Table 2 Materials and thermal specification

Name	Materials	Thermal Conductivity ($W/m^{\circ}C$)	Specific Heat ($kJ/kg^{\circ}C$)
Stator core	M350-50A	38	0.45
Rotor core	M350-50A	38	0.45
Magnets	Nd-Fe-B	10	0.45
Winding	Copper	401	0.38
insulation	Kapton	0.2	1.7
Coil dividers	Nomex	0.14	1.3

This coolant technique can be complex and time consuming but considering thermal behavior of the PMSMs is very significant. Therefore, the increase of temperature may deteriorates the mechanical and electrical strength of the coil insulations and stator core, raises the stator coil resistance, and strongly decreases the lifetime of involved parts (stator core including windings) which tends to a terrible traffic accident. In order to determine the temperate distribution at the electrical machines, following states are considered, (1) accurate calculation of the losses, (2) properties of the cooling fluid and thermal characteristic of the magnetic (in this case, the properties of ambient temperature is measured at the sea level due to location of the generator), (3) proper definition of conductive and insulating parts (in this study, class A insulation per IEEE 177 and 101 standards is selected), (4) accurate analysis of heat conduction and Internal heat generation since the core-loss distribution is completely different in various positions of the stator core, 3-D transient thermal FEA should be used to analyze the temperature distribution for the most accurate simulation. The heat transferred by radiation is ignored. The partial differential equation of the heat conduction and convection is expressed [8] as

$$\rho.c \left(\frac{\partial T}{\partial t} + \{V\}^T \cdot \{L\} T \right) = \{L\}^T \cdot (|D| \cdot \{L\} T) + Q \quad (3)$$

where ρ is the mass density, c is the specific heat, T (K) shows mass transport of heat; $\{L\}$ is the vector operator, $|D|$ is the temperature, t stands for time, $\{V\}$ is the velocity vector for conductivity matrix, and Q is the heat source rate per unit volume. It should be mentioned that for steady-state thermal analysis, the first term on the left-hand side of Eq. 3 should be zero.

At this stage, the iron losses as function of temperature is calculated using Bertotti's iron loss separation models [29-30], in which skin effect has been accounted through following equation. The calculation results have been reported in Table 1.

$$P_{fe} = k_h(f, B) f B^{h(B)} + k_e \left(\frac{\sinh(d\sqrt{f}) - \sin(d\sqrt{f})}{\cosh(d\sqrt{f}) - \cos(d\sqrt{f})} \right) f^{1.5} B^\beta \quad (4)$$

where $khf, B, h(B)$ and keB are polynomials in f and B .

Fig. 4, presents how the temperature distribution using steady-state analysis in the machine's parts using the lumped-circuit and FEA.

In the CFD modelling, 1.543 million volume cells are used, in which the typical cell edge size is 3 (mm), and the axial length of the model is 100 (mm). The symmetry, and 90° periodic boundary conditions are applied. In addition, the commercial CFD code ANSYS is used for the related analysis.

Table 3. Losses calculation results at rated speed of 150rpm

Losses/ model	Iron losses (W)	Joule losses (W)
FE-Conv.	220	40
Exp.-Conv.	219	44
FE-2-ducts	198	43
Exp.-2-ducts	201	42
FE-4-ducts	171	44
Exp.-4-ducts	170	43

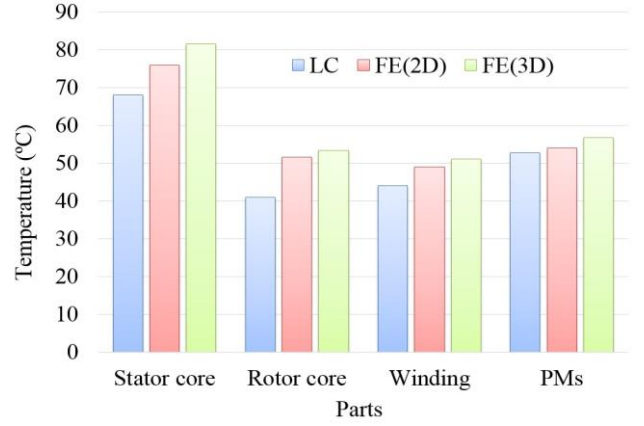


Fig. 4 Comparison of steady-state temperature distribution in the machine's parts of the initial model using LC and FE methods

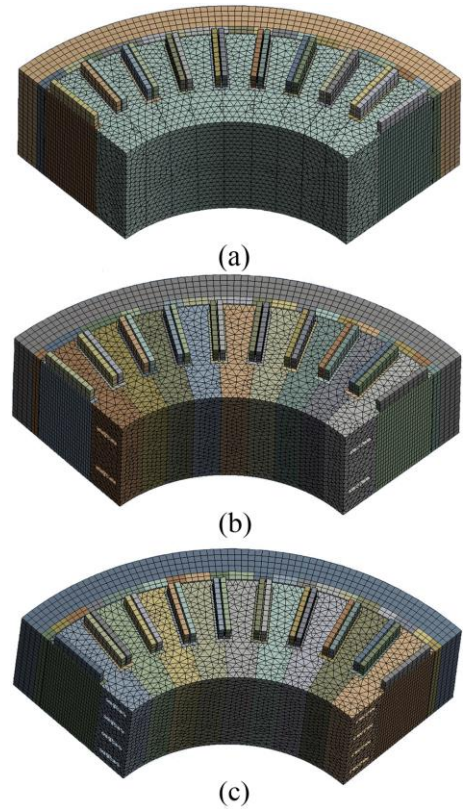


Fig. 5 3-D generated mesh for a) conventional, b) 2-ducts, and c) 4-ducts FE models

3. Results and discussion

The mesh generation is successfully generated (Fig. 5) for the conventional, two-ducts, and 4-ducts models with 367691 nodes and 146213 elements, 382517 nodes and 153400 elements, and 389945 nodes and 158988 elements, respectively.

This section is classified into two parts, one the results of the transient thermal analysis using 3-D FEA for all introduced FE models, and next it will be a general comparison and discussion on the other aspects. Thereupon, a thermal modelling of the conventional, 2-ducts, and 4ducts FE models using lumped-circuit can be addressed in Fig. 6. A steady-state temperature distribution and improvement trend throughout the models is shown, where convection, power sources, delta temperatures (trapezius blocks), and thermal resistance blocks are presented. It should be noted that the blocks with temperature and power tags are for steady-state temperature (or power) of conventional, 2-

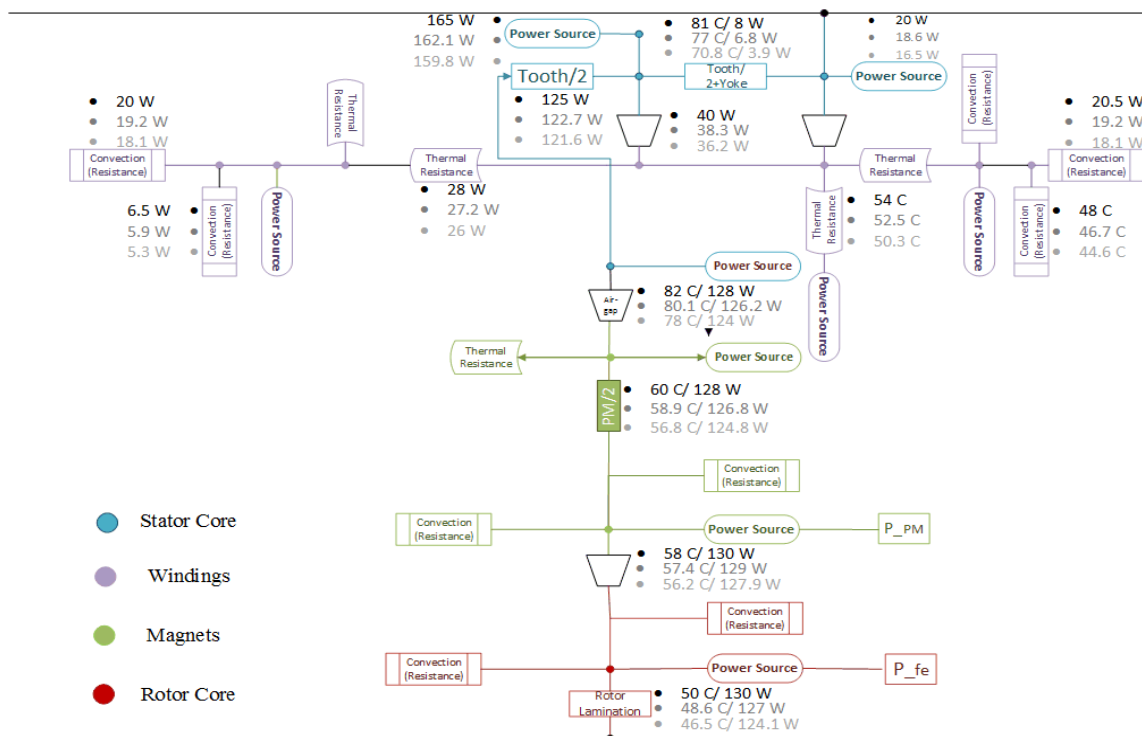


Fig. 6 Lumped-circuit modeling of the FE models ducts, and 4-ducts models, respectively. For example, in thermal resistance block of stator core that named by “Tooth/2 +Yoke”, 81 (°C)/ 8 (W) is reported for initial model, and 73.8 (°C)/ 3.9 (W) stands for 4-ducts model

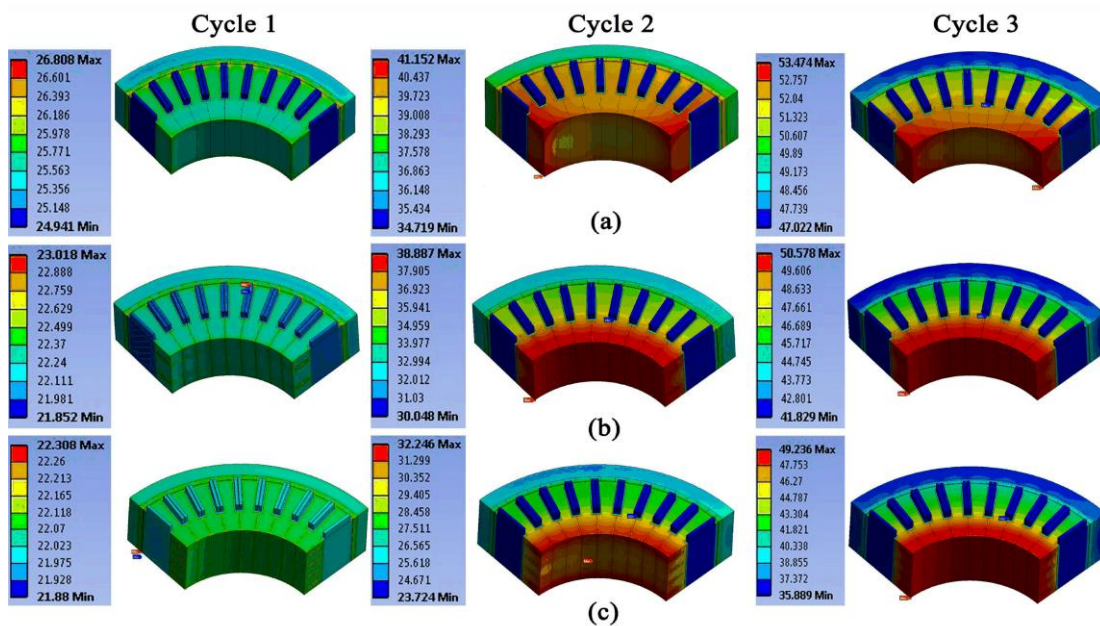


Fig. 7 3D transient thermal FEA by 3 cycles, a) conventional model, b) 2-ducts model, and c) 4-ducts model at 1st, 2nd , and 3rd

The aim of natural air cooling is removing the heat in the stator core through the innovative models, in which electromagnetic performance of the generator is included as a constraint of the technique’s improvement. Fig. 4(a) presents the temperature-rise performance of the innovative models. This figure illustrates the results enclosed by less than 3% from 2-D FEA in compare to 3-D FEA, also a very good prediction among the models can be seen in where the temperature difference between the conventional model and 4-ducts model is approximately for 11.0 (°C). In addition to, the influence of duct-width on other design highlights as back-EMF, and

electromagnetic torque are described via Fig. 8(b). The graph illustrated that through increasing the volume of the ducts, the back-EMF and EM torque decreases strongly. The back-EMF and EM torque for two-ducts, and four- ducts models are 305 (v), 350 (N.m), and 260 (v), 338 (N.m), respectively.

In Fig. 7(a), the temperature distribution of the first-cycle is shown, in which the conventional model varies between 24.941 up to 26.808 (°C). Although, the two-ducts FE model with segmented stator core (model Fig.7-b) resulted in a better temperature distribution performance that varies between 21.852 up to 23.018 (°C). At last, the best achieved performance is

clearly seen through four-ducts innovative model with segmented stator core, shown as model (c) with temperature distribution performance from 21.88 up to 22.308 (°C). Additionally, in this cycle all the models are pointed the same parts by minimum and maximum probes in blue and red labels, respectively.

In the second cycle, models (Fig. 7(a), (b), and (c)) are shown a temperature-rise in comparison with the corresponding models in the first-cycle of analysis. The conventional model (Fig. 7-a) is illustrated temperature distribution variation of 34.7 to 41.15 (°C). The two-ducts model (Fig. 7-b) resulted in a maximum temperature distribution at the stator yoke. In this model, the temperature varies from 30 to 38.8 (°C). The four-ducts model (Fig. 7-c) with a better thermal performance, in which the temperature varies between 23.724 up to 32.246 (°C), and the same parts for maximum and minimum temperature labels with other models in this cycle.

In the third-cycle, all models are carried out the maximum temperature label at the stator core due to segmentation. The conventional model (Fig. 7-a) is illustrated the peak temperature in comparison to the two-ducts model (Fig. 7-b) varies from 47.822 up to 53.474 (°C), and the four-ducts model (Fig. 6-c) with a better performance varies between 41.829 to 50.578 (°C). At last, the four-ducts model has presented the best cooling performance to remove the heat.

In Fig. 8, the influence of the duct-width on the electromagnetic key parameters such as back-EMF and torque is shown in Fig. 8-a. Also, the temperature-rise and power can be seen in Fig. 8-b, in which the duct width $r = 3.8$ (mm) was chosen for the innovative models.

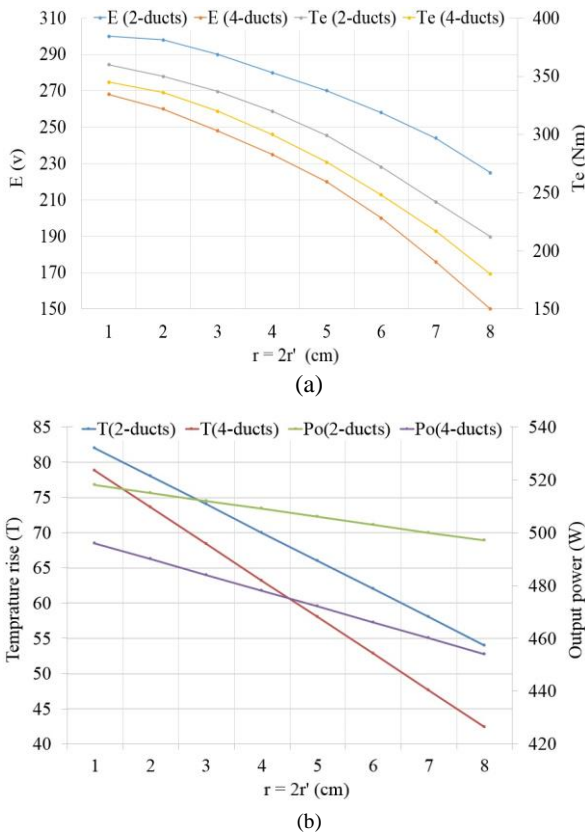


Fig. 8 Influence of duct-width on a) the back-EMF and torque, as well as b) temperature-rise and output power

4. Experimental investigation

Essentially, the heat transfer is known as one the most critical parameters in the thermal design of the PMSMs, thus, the most sensitive heat transfer coefficients are calculated and also experimentally reported in Fig 9 under following conditions

- The axial inlet velocity of the cooling air was defined between 0.5 to 3 (m/s)
- The rotor tip velocity is varied between 2 to 8 (m/s)
- The air approach angle is defined between 0 to 30°

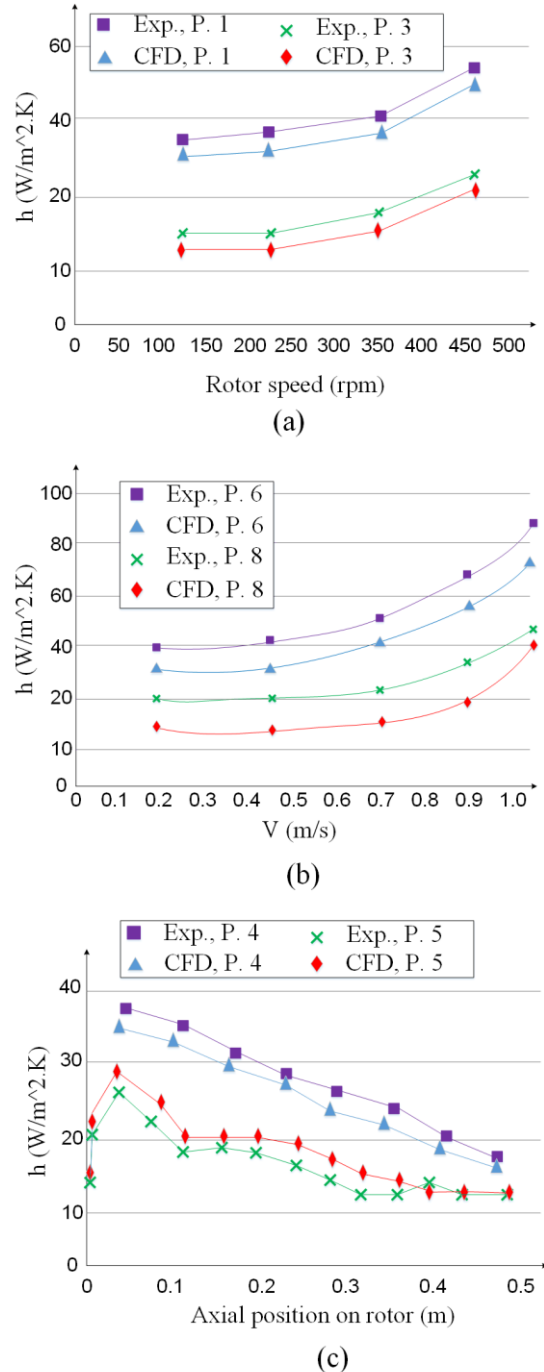


Fig. 9 Heat transfer coefficients verification for the FE models, a) at points 1 and 3 variable airflow rate, b) at points 6 and 8 for variable rotor speed, and c) at points 4 and 5 for variable rotor speed

it should be mentioned that not significant different is seen for the change of the air approach angle from 0 to 60°. Fig. 9(a)

illustrates the change of heat transfer coefficients at the poles (points 1 and 3) at a variable speed condition. In Fig. 9(b), the heat transfer coefficients are at the stator core (points 6 and 8), in which the low velocity ratio (axial inlet velocity/ rotor tip velocity) is variable. Fig. 9(c), presents the surface heat transfer coefficients around the bottom face of the field coil at the leading side of magnet (points 4), and bottom face of the field coil at trailing side of pole (point 5).

The optimized SPMSG under test is fed through a variable speed frequency converter known as ABB ACS600 and loaded by a DC machine. The electrical output power is measured by a power analyzer known as Yokogawa PZ4000 by accuracy of 1%, and the temperature is registered in twenty points by Pt-100 temperature sensors. The manufactured prototype is employed for the small power generation using wind energy along the coast of Barcelona city in Spain.

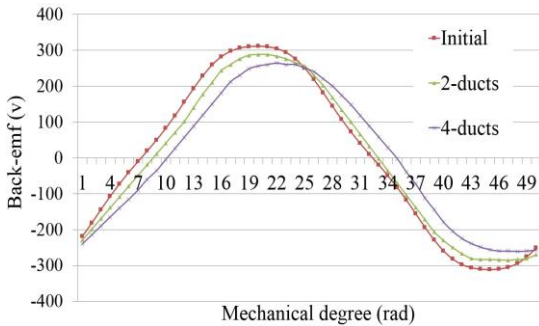


Fig. 10 Back-EMF trend for the FE models

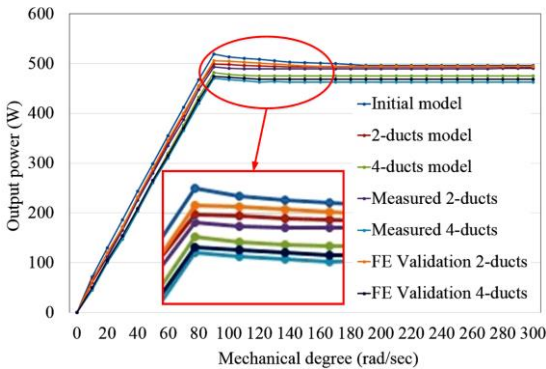


Fig. 11 Predicted output power in comparison with experimental

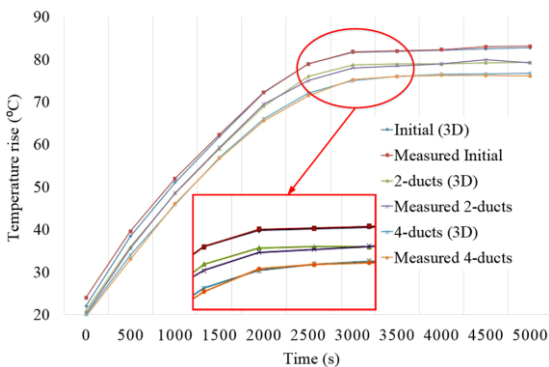


Fig. 12 Predicted temperature-rise in comparison with experimental

The main objective is the temperature-rise, in addition, the performance aspects have to be reliable such as the measured output power in comparison with the conventional, and the innovative FE-models which can be seen in Fig. 11, where temperature-rise improvement can be seen in Fig. 12. A considerable accuracy between FE models and measured values

presents a great fitness of the shape optimization design. The manufactured PMSG can be seen in Fig. 13(a) through segmented stator core for improving slot fill factor, simpler winding, and providing closed-slot topology. In Fig. 13(b), the rotor included the skewed magnets. Additionally, the prototype is used for the wind energy application, the installed vertical axis twisted savonius type wind turbine (VAWT) at the top of PMSG as shown in Fig. 13-c.

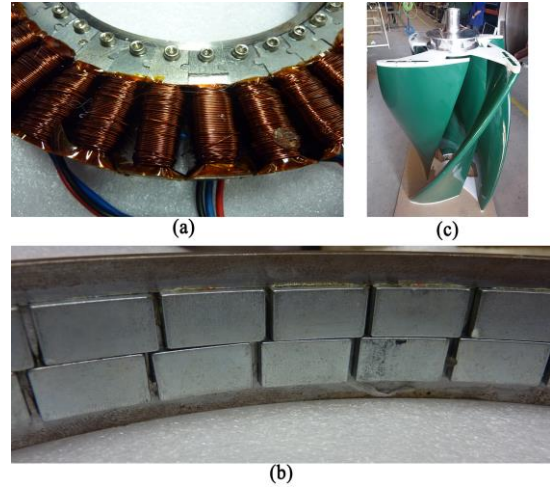


Fig. 13 Manufactured 4-ducts model, a) The PMSG with segmented stator core, b) The rotor core with skewed PMs, and c) The assembled SPMSG and the VAWT at the top of PMSG

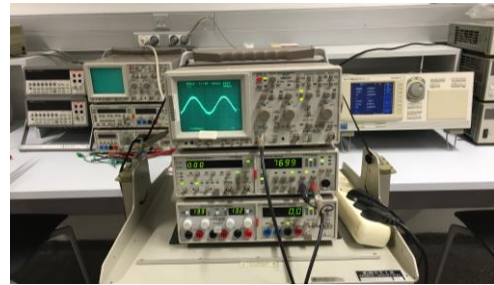


Fig. 14 Measurement setup

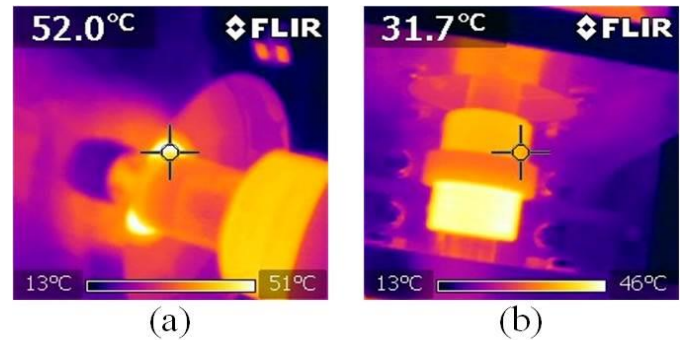


Fig. 15 Use of thermal imaging measurement on the test bench at rated speed of 150 (rpm), a) the inner surface of stator core, and b) the housing

A good electromagnetic performance is reported for the innovative models. Although, a trade-off can be thinkable due to output power changing among the models. One the other hand, the measurement setup for iron losses calculation is presented in Fig. 14, and correspondingly the results are reported in the Table. 3, where there is a considerable iron losses reduction via innovative models as the shape optimization is done in the stator yoke.

Fig. 15 illustrates that the set of boundary and related thermal 3-D analysis is successfully performed, in which the proposed four-ducts innovative FE model (in Fig. 7-c) is recorded 49.23 (°C) and experimentally verified by 52.0 (°C). Of course, a very small error always exist between numerical and experimental calculations.

The coolant solution of the proposed model (in terms of manufacturing process), where the stator core is divided into a number of substacks which can be seen in Fig. 13-a. Cooling air flows into axial ducts due to rotation of the shaft and its way to out of housing. Thus, the stator via circumferential cooling channels formed between the adjacent stator substacks. The use of the stator substacks has an effect on the equivalent length of the generator, and therefore, if ignored, leads to an incorrect no-load voltage and synchronous inductance calculation.

5. Conclusion

The problem of high temperature-rise is investigated due to the segmentation in the stator core with 81 (°C) at 150 (rpm) which becomes the main objective for further post-action design study. Thus, the achievement is to decrease the temperature-rise at the stator core using an innovative coolant.

In this paper, an innovative cooling system with natural airflow technique in order to reduce temperature-rise at the stator core is presented through two innovative FE models with circumferential and axial ducts. The main objective under following constraints have been successfully achieved, in which the efficiency of $\eta_i \geq \%96$, and $P_{oi} \geq 465$ (W) are defined. Consequently, the innovative 2-ducts and 4-ducts FE models are studied, where a significant temperature reduction up to 11 (°C) with freezing the electromagnetic capability is reported by the proposed four-ducts model. Also, its heat transfer path is emphasized. Additionally, the outcome of the cooling system is highlighted under the influence of the duct-width on the key EM parameters such as the back-EMF, torque, output power, and also temperature-rise (constraints). The achievements of the study is perfectly reached, in which the results of all 3-D FEA models have obviously compared through the constraints and experimentally. At last, measured experimental results greatly support the design technique by a very small error of $\epsilon < 2.5\%$.

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