Diagnosing and Correcting a Damaging Below-Ground Column Natural Frequency in a Vertical Pump Using Field Testing and FEA

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By:

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- Two single-stage Circulation Pumps (VTP) installed in 2001 in a 480 MW coal-fired plant in OK, USA.
- The pumps were driven by 1,500 HP induction motors (23,550 lbm) at 510 rpm (8.50 Hz).
- The rated capacity: 66,000 GPM and 70 ft of TDH.







Shaft Failure

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- In 2008, acceptable vibration (0.10 in/s pk) in two orthogonal directions was measured at the top of the motor. The amplitude increased gradually over the next 2.5 years. Within this period, the pump shaft failed in December 2009 (5.5 inch diameter at the upper end of the pump shaft coupling). Before the failure, the vibration was approximately 0.20 in/s pk. In addition, there were only a few of the upper column flange bolts remaining in place, and there was minor rubbing detected at the tip of the impeller vanes. During this period, when the pump was sent out for repair, the soleplate was replaced.
- After the pump was re-installed in March 2010, the vibration was around 0.20 in/s pk, then it started to increase quickly reaching the alarm level of 0.40 in/s pk in the mid-2010.

- In order to achieve an adequate level at the mounting flange of the motor (April 2011), variable thickness shims were required between the discharge head and the soleplate to reduce the vibration.
- Vibration was also susceptible to the discharge pressure. By throttling the valve, the response in vibration amplitude was favorable (lower).





Vibration Testing, Analysis, and Solution Methods

- Experimental Modal Analysis (EMA) test to determine the natural frequencies of the pump structure.
- Operating Deflection Shape (ODS) testing during steady operation.

• Finite Element Analysis (FEA) calibrated to the installed field data to test practical fixes.

Running speed (8.50 Hz)

Running speed (8.50 Hz)



Motor Top Perpendicular



Motor Top Parallel

Pump A While Operating (Loose Pump)

Running speed (8.50 Hz)

Running speed (8.50 Hz)



Motor Top Perpendicular



Motor Top Parallel

Pump A While Shut-down (Tight Pump)

Structural Natural Frequency Summary Table

CWP Pump A	S					
Condition	Perpendicular Direction	Separation Margin (%)	Parallel Direction	Separation Margin (%)	Mode Shape	
Discharge Head Loose During Operation	8.19	-3.7%	7.75	-8.8%	Trunion Mode	
	13.38	57.4%	13.06	53.6%	"C" Shape Mode	
Discharge Head Loose During Shut-down	8.13	-4.4%	8.13	-4.4%	Trunion Mode	
	13.44	58.1%	13.31	<mark>56.6%</mark>	"C" Shape Mode	
Discharge Head Tightened During Shut-down	8.44	-0.7%	8.44	-0.7%	Trunion Mode	
	13.75	61.8%	13.50	58.8%	"C" Shape Mode	



Trunion mode at 8.44 Hz in the perpendicular direction



Global "C" shape mode at 13.50 Hz in the parallel direction

Vibration Test Results





Motor Top Perpendicular Overall: 1.13 in/s pk

Motor Top Parallel Overall: 1.04 in/s pk

Pump A While Pump was Tightened to the Soleplate

Vibration Amplitude Summary Table

	Condition	Location / Direction	Vibration Amplitude (in/s pk)				
Unit			Perpendicular		Parallel		
			1x rpm	Overall	1x rpm	Overall	
CWP Pump A	Discharge Head Loose	Top of the Motor	0.766	0.767	0.470	0.471	
		Top of the Discharge Head	0.337	0.338	0.326	0.327	
	Discharge Head Tightened	Top of the Motor	1.131	1.134	1.032	1.035	
		Top of the Discharge Head	0.488	0.525	0.448	0.451	

Operating Deflection Shape (**ODS**) **Testing**



Discharge head mounting flange loosened to reduced the vibration amplitude at the top of the motor.

Orbiting motion at the top of the motor mostly in the perpendicular direction to the discharge nozzle.

Soft-foot all the way around the discharge head mounting flange due to shimming and looseness between parts.

Preliminary Recommendations

- Increase the stiffness of the discharge head
- Eliminate the looseness of the soleplate with respect to the concrete floor



Existing ribs

Weld 6 ribs 10" tall, 10.5" wide, and 1.0" thick between existing ribs

1" thick plate

1" thick donutsshape plate

Follow Up Testing

- 50% reduction in vibration amplitude at the top of the motor, but still high (0.50 in/s pk).
- The increase in the above-ground stiffness did not shift the offending mode of the system as expected.



Follow Up Testing

 Two months later, during the next outage the pump column was lifted from the sump, and a crack was identified in one of the lower gusset welds



Follow Up Testing

• Below-ground accelerometers were installed at the suction bell flange in two orthogonal directions.





Detailed solids model of the pump

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Calibrated FEA model for original pump

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Proposed modification of the suction bell

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Predicted modified structural natural frequency

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Follow-Up Testing with Weight

Spectrum MCA Gree Wir Prep \ MCA GWP MOBEW LPV 4/11/2012 9 30:29 AM. Channel J. Trand Overall: 0.05521 in/s

Vep D.02477, Freq. 514, Running Speed, 514 9914



Spectrum MCA Gas: Wit Prop \ MCA CWP POBEW LPV, 4/11/2012 1 46-44 AM. Channel 1. Trend Overall 0.2521 in/m

Amp: 0.1312, Pres: 514, Running Speed: 514 RPM



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Conclusions

- The root cause of the high vibration at the top of the motor was due to a below-ground dominated mode (trunion mode) rather than the typical motor cantilever rocking mode. This is why the additional ribbing of the above ground structure did not significantly shift the offending natural frequency.
- The looseness between the discharge head mounting flange and the soleplate shifted the offending mode away from the 1x running speed frequency.
- The addition of weight to the bottom of the suction bell in conjunction with the increased added mass effect of the surrounding water lowered the offending below-ground natural frequency to have sufficient separation margin (~15%) from the running speed.

Recommendations

- Testing combined with FEA analysis are excellent tools when good engineering judgment and experience have not been successful in diagnosing and fixing vibration problems in vertical pumps.
- The use of below-ground accelerometers can greatly help identify below-ground modes on VTPs.
- Closer examination of the spectrum modal plots may be able to distinguish between whether a frequency is an above-ground or below-ground dominated mode based on the relative size of the peaks.
- Shifting below-ground modes by attaching mass to the bell must also consider the added mass effects of the surrounding water to achieve the desired results.

Thank you

Any Questions?

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