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Development and validation of a detailed TRNSYS-Matlab model for large solar collector fields for district heating applications

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Abstract

This study describes the development of a detailed TRNSYS-Matlab model to simulate the behavior of a large solar collector field for district heating application. The model includes and investigates aspects which are not always considered by simpler models, such as flow distribution in the different rows, effect of the flow regime on the collector efficiency, thermal capacity of the components and effect of shadows from row to row. The model was compared with measurements from a solar collector field and the impact of each aspect was evaluated. A good agreement between model and measurements was found. The results showed that a better agreement was achieved, when a flow regime-dependent efficiency of the collector was used. Also the precise flow distribution in the collector field improved the model accuracy, but it must be assessed if the aimed level of accuracy justifies the much longer programming and computing time. Thermal capacity was worth being considered only for the bulkier components, such as the longer distribution and transmission pipes. The actual control strategy, which regulates the flow rates in the solar heating plant, was accurately reproduced in the model, as proved by the good agreement with the measurements.

Keywords: solar collector field; TRNSYS; simulation; flow regime; flow distribution.

Nomenclature

A_{field}	collector area of the collector field	[m ²]
a_1	heat loss coefficient of collector at $T_m - T_{amb} = 0$ K	[W m ⁻² K ⁻¹]
a_2	temperature dependence of the heat loss coefficient of collector	[W m ⁻² K ⁻²]
c_p	specific heat	[J kg ⁻¹ K ⁻¹]
DH	district heating	
F_f	correction factor for heat exchanger fouling	[-]
G_{tot}	hemispherical solar irradiance	[W m ⁻²]
\dot{m}	mass flow rate	[kg s ⁻¹]
<i>nom</i>	subscript referring to nominal conditions	
Q_{sol}	theoretical solar energy output from the collector field	[W]
Re	Reynolds number	[-]
RMSD	root-mean-square deviation	
s_i	uncertainty of the function/variable i	
T_m	mean fluid temperature in the collector field	[°C]
T_{amb}	ambient temperature	[°C]
UA	overall heat transfer coefficient of the heat exchanger	[W K ⁻¹]
η_0	peak collector efficiency	[-]

1. Introduction

1.1. Background

To reach the CO₂-reduction goals agreed at the COP21 conference in Paris, reduce energy imports and cut costs for households and businesses, the European Union will act on several fronts. Among these, a key role should be played by the spread of district heating (DH) and the integration of renewable energy sources into DH networks (European Commission, 2016).

Approximately 80 % of the energy demand of European residential buildings is used for space heating and domestic hot water preparation (Lapillonne et al., 2015). Because solar thermal collector can efficiently and

47 economically provide energy at the temperature levels required by these applications, they seem a perfect
48 candidate to cover this demand. Although solar heating systems are fairly common in the single-family house
49 sector, large solar thermal plants for DH are still rare, except for a few countries, and represented less than
50 1 % of the total installed water collector capacity at the end of 2016 (Weiss et al., 2017). Approximately
51 5000 DH networks are currently in operation in Europe, supplying 10 % of the total heat demand (AEBIOM,
52 2012). Of these, about 300 are solar assisted DH systems at the end of 2016 (Weiss et al., 2017). However,
53 the contribution of solar energy to DH in Europe is expected to increase. According to the SDHtake-off
54 project, supported EC-Programme IEE Intelligent Energy Europe, a solar fraction of 1 % by 2020 and of 5 %
55 by 2050 is realistic (Schubert et al., 2010; SDHtake-off, 2012).

56 Although several large solar plants for DH have been installed in Germany, Austria and Sweden (Schubert et
57 al., 2010), Denmark is still the main market for this technology, with 79 % of the total collector area installed
58 in Europe at the end of 2016 (Weiss et al., 2017). In the Scandinavian country some specific factors, such as
59 high taxation on fossil fuels and widespread use of DH, has lead this development (Furbo et al., 2015). At the
60 end of 2016, Denmark had more than 1,300,000 m² of solar collector fields (Trier, 2016). Additionally, the
61 size of the collector fields has been constantly increasing and at the end of 2016 a 156,000 m² collector field
62 was completed in Silkeborg (Rasmussen, 2016). An even larger installation may come about in the next
63 years, if the project for a 450,000 m² collector field is realized in Graz, Austria (Reiter et al., 2016).

64 In a scenario where solar collector fields become increasingly larger and supply increasingly higher solar
65 fractions, even small performance improvements in relative terms can lead to a large increase in the overall
66 energy production in absolute terms. Hence, it is important to be able to predict the behavior and
67 performance of these plants in the most accurate way. If correct sizing, control strategy and design
68 improvements can be accurately evaluated in advance and implemented already in the planning phase, later
69 and more expensive interventions can be avoided. Additionally, detailed simulation models can be used for
70 on-line simulations, which use real-time measured data as input (Perers and Furbo, 2014), to continuously
71 monitor the plant and verify whether this meets the expected performance.

72 So, the aim of this study was to develop a detailed simulation model of a large solar collector field for DH
73 application. The model was developed in TRNSYS-Matlab. The model treated aspects which are usually
74 neglected in simpler models, such as flow distribution, collector efficiency dependence on the flow regime,
75 etc., in order to evaluate their impact on the overall model accuracy. The reliability of the model was verified
76 by comparing its results against experimental measurements.

77 The paper is structured as follows. Section 1.2 presents a literature review on modeling of solar heating
78 systems and the challenges that were addressed in this study. Section 2 describes the collector field used for
79 the model validation and the developed TRNSYS model. Section 3 presents and analyzes the results of the
80 TRNSYS subsystems used to calibrate single model components, as well as the comparison between the
81 results of the model of the solar heating plant and the measurements. The titles of the subsections of Sections
82 2 and 3 are almost identical, so that for each component the reader can easily move from the methodology
83 subsection to the corresponding result and discussion subsection. Section 4 summarizes the main
84 conclusions.

85 1.2. Literature review

86 Le Denn (2014) distinguishes the available simulation tools for large solar collector fields for DH
87 applications in two categories. The first category includes dedicated solar DH tools, such as F-Easy (Nielsen
88 and Battisti, 2012), Fjernsol-II (PlanEnergi, 2013), SDH Online-Calculator (Deschaintre, 2014) and Sunstore
89 4 Tool (CIT Energy Management, 2013). The second category includes generic software, such as TRNSYS
90 (Klein et al., 2012), energyPRO (EMD International A/S, 2016), Polysun (Vela Solaris, 2016) and
91 RETScreen (Natural Resources Canada, 2016).

92 The programs of the first category are mainly feasibility tools, suitable for rough estimation of the system
93 performance on yearly or monthly basis. They are simple to use, but offer limited detail and few possibilities
94 of customization, so they were discarded for this study. Of the second category, TRNSYS was identified as
95 the most suitable simulation program, as it offered different advantages compared to the other tools. First of
96 all, TRNSYS comes with a wide library of validated component models. Besides the original TRNSYS
97 component library, other libraries (Schwarzbözl, 2007; TESS, 2012) or single components have been

98 developed by different institutions or programmers. Additionally, TRNSYS users can write and compile their
99 own components, or customize existing ones by editing their source code. Finally, TRNSYS can interact
100 with other software, such as Matlab, while a simulation is running. All these possibilities give a high
101 flexibility in the use of the software, which was hence chosen for this study.

102 TRNSYS has been widely used for simulation of solar thermal systems. Numerous articles report on studies
103 where TRNSYS was successfully used to simulate domestic or small case solar thermal systems. A selection
104 of these is presented in the review by Saleem et al. (2015). Larger parabolic trough collector fields connected
105 to power plants have been modeled in TRNSYS (Abdel Dayem et al., 2014; Biencinto et al., 2016, 2014). In
106 the field of solar DH, Raab et al. (2005) developed and validated a TRNSYS model to simulate the solar
107 assisted DH system in Hannover. Sibbitt et al. (2012) used TRNSYS in the design phase of the solar DH
108 system of Drake Landing Solar Community in Canada. The monitored data of the installed system were in
109 satisfactory agreement with the model. Bava et al. (2015) modeled a single collector row in the collector
110 field by Brødstrup II, Denmark. The comparison between simulation results and measurements shows that
111 inaccurate solar radiation measurements and decreased collector efficiency (caused for example by dirty
112 glass cover) may compromise the agreement between model and monitored data.

113 In most of the mentioned studies, the collector field was only a part of the entire system and hence was
114 treated with little detail, usually by a single collector component. Consequently, aspects such as flow
115 distribution across the collector field are not considered, although they may have an impact on the collector
116 field performance (Dorantes et al., 2014). This is especially valid nowadays, when the collector fields have
117 become increasingly larger. Additionally, modeling the entire collector field as a single component entails
118 that also the distribution pipes in the model do not have the actual layout or fluid content. This can easily
119 lead to an advance or delay of the model response compared to reality. To address this problem, the
120 TRNSYS model developed in this study was made interact with a previously validated Matlab model (Bava
121 et al., 2017), so to accurately take into account the exact flow distribution across the collector field (see
122 Section 2.2.2.2).

123 Another simplification consists of assuming the collector efficiency expression constant. Among the
124 different operating conditions which can affect the collector efficiency, the flow regime in the absorber pipes
125 has great importance (Bava and Furbo, 2014; Hausner and Fechner, 1998). Most collectors are tested using
126 water as heat transfer fluid and in condition of turbulent flow. If the collector is supplied with propylene
127 glycol/water mixtures, laminar regime may take place, reducing its efficiency. Therefore, using the
128 certificate collector efficiency as input to the model is likely to cause an overestimation of the collector
129 performance compared to real-world operation. To reproduce the behavior of the collectors in a more
130 realistic way, the collector efficiency from the collector test report was corrected to take into account the
131 different heat transfer fluid through a collector simulation program. Additionally, a new TRNSYS collector
132 component was developed, to account for the effect of the flow regime on the collector efficiency.

133 Other aspects which are often neglected for sake of simplicity, but which were considered in this study, are
134 thermal capacity of pipes, distinction between beam and diffuse radiation and shadow effect from one row to
135 another.

136 **2. Material and method**

137 This section describes the solar collector field used for the model validation and the TRNSYS model itself.
138 The collector field is described in terms of hydraulic layout, system components, measuring equipment and
139 control strategy. Regarding the TRNSYS model, the list of utilized components as well as the reasons and
140 considerations behind their choice are presented.

141 *2.1. Description of the solar collector field*

142 *2.1.1. Collector field design*

143 The TRNSYS model presented in this paper was developed based on the solar collector field near Høje
144 Taastrup, Denmark (Figure 1). As can be seen from the layout in Figure 2, the collector field consisted of
145 two subfields, having 12 collector rows each. Each row was composed of 10 HTHEATStore 35/08 collectors
146 (SP, 2016) from the company Arcon-Sunmark A/S. The collectors were harp flat plate collectors with 18

147 horizontal absorber pipes and a gross area of 13.57 m². The collector field gross area was 3257 m². The
148 declared collector efficiency is reported in Table 1. The row distance was 5.5 m. The collector tilt angle was
149 43° and the orientation 2.5° W. The solar collector fluid was a 35 % propylene glycol/water mixture (Bava et
150 al., 2017). Normal operating temperatures for the collector field were of 50-55 °C in inlet and 90-95 °C in
151 outlet. The flow rate ranged from 8 to 50 m³ h⁻¹ (0.04-0.26 liter min⁻¹ m⁻²) depending on the solar irradiance.



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153 *Figure 1: Aerial picture of Høje Taastrup solar collector field (source: Arcon-Sunmark A/S).*

154 Both supply and return pipes of the primary loop (or solar collector loop) were made of preinsulated steel
155 pipes (Logstor, 2005) with progressively decreasing diameter, as part of the flow was diverted to the
156 collector rows. As seen in Figure 2, supply pipes (in blue) supplied the collector rows from the outer sides of
157 the collector field, while a single return pipe (in red) collected the heated fluid in the middle of the field.
158 Balancing valves were installed and regulated at the inlet of each collector row, to guarantee a uniform flow
159 distribution across the collector field (Bava et al., 2017).

160 The technical building (top-right corner in Figure 2) hosted pumps, expansion vessels, control system,
161 measuring equipment and the plate heat exchanger, which connected primary and secondary side.

162 The secondary side was connected to the DH main network through 550 m long transmission pipes. To avoid
163 supplying too cold fluid to the network in the start-up phase, a bypass is installed at the end of the
164 transmission pipes and it is used to recirculate the fluid until a temperature of at least 65 °C, compatible with
165 the DH network, is reached.



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Figure 2: Layout of Høje Taastrup solar collector field: blue and red lines represent supply and return pipes respectively (adapted from Arcon-Sunmark A/S).

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2.1.2. Measuring equipment

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Electromagnetic flow meters with an accuracy of $\pm 0.5\%$ measured the volume flow rate in both primary and secondary side. The temperature of the heat transfer fluids was measured by resistance thermometers with an accuracy of 0.25 K. The temperature was monitored at the beginning of the supply pipe, at the end of the return pipe, at the inlet and outlet of collector rows 1, 11, 13 and 23 (Figure 2), at each inlet and outlet of the heat exchanger, and at the end of the transmission pipes. The ambient temperature in the field was measured too.

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The solar irradiance on the collector field was measured by pyranometers in different parts of the collector field. Three photovoltaic cell pyranometers (SolData, 2016) were installed next to one another in the collector field and used in the control strategy. However, this kind of sensors is known to degrade over time, underestimating the actual solar irradiance. For this reason, four Kipp & Zonen thermopile pyranometers were added. A secondary standard CMP11 pyranometer and a first class CM5 pyranometer equipped with shadow ring were placed in the middle of the collector field on top of a collector, to measure the total and diffuse irradiance on the collector plane. The diffuse irradiance was corrected to account for the shadow ring using Drummond's (1956) model. From the total and the diffuse irradiance, the beam component was determined. Other two secondary standard CM11 pyranometers were placed at the north-east and north-west corner of the collector field to measure possible differences between morning and afternoon incident radiation due to reflection from the collectors.

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The instantaneous values of the monitored data were recorded once per minute. The sampling time used for control purposes was on the other hand much shorter (< 1 s).

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2.2. Description of the TRNSYS model

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TRNSYS is a transient system simulation tool having a modular structure. A TRNSYS project is set up by interconnecting different modules, which build up the system which is to be simulated. The following sections explain which components built up the model, why they were chosen and how they were connected. A detail of the overall TRNSYS model of Høje Taastrup collector field is shown in Figure 3. Simpler models were developed to calibrate single components, as described in the following sections.

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Perers and Furbo (2014) identify several aspects which should be taken into account, to develop accurate simulation models for large solar collector fields. These range from accurate weather data to choice of the component models, from flow distribution across the collector field to thermal capacity of the components. So the following sections also describe how these different aspects were addressed in this study.

199 *2.2.1. Weather data and time resolution*

200 Accurate weather data, including the distinction between beam and diffuse irradiance on the collector plane,
201 should be used as input (Perers and Furbo, 2014). Both solar irradiance and ambient temperature were
202 measured in the collector field by high class thermopile pyranometers (see Section 2.1.2). The measured
203 weather data, as well as all other relevant monitored data from Høje Taastrup collector field, were loaded
204 into the TRNSYS model by the data reader Type 9c (Klein et al., 2012).

205 To simulate the collector array shading, Type 30 (Klein et al., 2012) was used. The so corrected diffuse and
206 beam irradiances were input to all collector rows except the front ones, which were not shaded.

207 According to Perers and Furbo (2014), the time resolution is also very important. Usually hourly mean
208 values are available, but higher time resolution is desirable to test control algorithms. Hence, all recorded
209 data (one minute time step) were used without averaging.

210 *2.2.2. Model components*

211 Regarding the components models, Perers and Furbo (2014) suggest using already validated models instead
212 of detailed theoretical components, to save both programming and computing time. Hence, almost all
213 components used in the simulation model were taken from existing and well-established TRNSYS libraries
214 (Klein et al., 2012; Schwarzbözl, 2007; TESS, 2012).

215 *2.2.2.1. Collector type components*

216 A collector model which is compatible with the collector test standard ISO 9806 (ISO, 2014) should be used
217 (Perers and Furbo, 2014). To be able to consider aspects which are usually neglected when simulating solar
218 collector fields, Type 330 was used. This is an in-house model developed by editing Type 539 (TESS, 2012)
219 with some desired features added. First of all, Type 330 makes use of a different efficiency expression
220 depending on the flow regime in each node in which the collector is divided. Consequently, this collector
221 type requires two efficiency expressions, one for laminar and one for turbulent regime. This may be a
222 problem, as collector certificates provide only one efficiency expression, usually for turbulent conditions. In
223 this study, a simulation model of the investigated collector HTHEATStore 35/08 (SP, 2016) was developed
224 with the software Soleff (Rasmussen and Svendsen, 1996), based on the collector design and the operating
225 conditions used during the efficiency test. The good agreement between the certificate efficiency and the
226 simulated efficiency (RMSD=0.12 %) proved the reliability of the Soleff model. The model was then used to
227 calculate the collector efficiency in laminar and turbulent conditions for a 35 % glycol/water mixture. The
228 coefficients of the declared and simulated efficiencies are listed in Table 1.

229 *Table 1: Declared and simulated efficiencies of HTHEATStore 35/08 collector based on the gross area of 13.57 m².*

	Fluid	η_0 [-]	a_1 [W m ⁻² K ⁻¹]	a_2 [W m ⁻² K ⁻²]
Declared efficiency (SP, 2016)	water	0.757	2.199	0.007
Soleff efficiency (test conditions)	water	0.757	2.260	0.006
Soleff efficiency (turbulent)	35 % glycol	0.756	2.318	0.006
Soleff efficiency (laminar)	35 % glycol	0.727	2.357	0.005

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231 Considering the operating conditions in Høje Taastrup collector field (see Section 2.1.1) and assuming
232 $Re=2300$ as threshold between laminar and turbulent flow, about one third of the collectors experienced
233 laminar flow. For this reason, it was relevant to have a different efficiency expression in case of laminar
234 flow.

235 A second feature of Type 330 is the possibility for the user to specify an incidence angle modifier (IAM) for
236 diffuse radiation, instead of having it internally calculated as in Type 539. Another feature consists of the
237 wider range of incidence angle where the IAM-expression for beam radiation is used. The range is chosen
238 depending on the data available in the technical datasheet of the collector which is to be simulated. The
239 original Type 539 linearizes the IAM for angles between 60° and 90°.

240 To evaluate whether the improvements introduced in Type 330 had an effect, three different collector type
241 variants were analyzed. The first used Type 539 and the declared collector efficiency (Table 1). The second

242 made use of Type 330 and the Soleff efficiency equation for turbulent conditions (Table 1), regardless of the
243 actual flow regime in the absorber pipes of the collectors. In the third variant, all features of Type 330 were
244 enabled. For sake of simplicity, the first and second variants of Type 330 are referred to as Type330a and
245 Type330b in the rest of the paper. To focus on the behavior of the different collector variants and avoid the
246 influence of external factors, such as control strategy and secondary side temperatures, only the primary side
247 of the collector field was modeled, and the measured flow rate, collector field supply temperature and
248 weather data were given as input. The modeled return temperatures from the collector field in the three
249 scenarios were compared to the measurements. Different types of weather conditions were considered: clear
250 sky, cloudy sky with fluctuating solar radiation and overcast sky.

251 2.2.2.2. *Flow distribution*

252 To take into account the flow distribution in the collector field, each single collector row was modeled. As
253 TRNSYS cannot solve problems of flow distribution in hydraulic networks, Type 155 (Klein and et al.,
254 2012) passed the necessary inputs to a Matlab program (Bava et al., 2017). Matlab evaluated the flow
255 distribution in the different collector rows and returned the result to TRNSYS, where the total flow was then
256 distributed to the different rows accordingly.

257 To evaluate the impact of modeling the exact flow distribution, the detailed model using Type 330b (Section
258 2.2.2.1) was compared to a simpler model. The simpler model differed from the detailed one, as the entire
259 collector array was simulated through a single Type330b. Additionally, the supply and return pipes were
260 modeled by a pipe component each (see Section 2.2.2.3). The pipe length used as input in the pipe
261 components was the average distance between the technical building and each collector row. The thermal
262 capacity of the pipes was proportionally scaled (see Section 2.2.2.3).

263 2.2.2.3. *Pipes and heat exchanger*

264 Type 709 (TESS, 2012) was chosen to model the distribution pipes, as it had a better agreement with the
265 measurements, compared to Type 31 (Klein et al., 2012) and Type 604 (TESS, 2012). However, unlike Type
266 604, Type 709 does not consider the thermal mass of the pipe material, which may be relevant, especially in
267 case of long transmission pipes. To take this aspect into account and evaluate its impact on the accuracy of
268 the model, the thermal capacity Type 306 (Schwarzbözl, 2007) was added to the longest distribution and
269 transmission pipes. Specific TRNSYS projects were built, simulating only the investigated pipes. In this way,
270 all the other simplifications of the model, which could have an effect on the simulation results, were
271 excluded. The pipes investigated in detail were the supply pipe to the western subfield (see Figure 2 and
272 Figure 3) and the transmission pipe from the heat exchanger to the DH network (see Section 2.1.1 and Figure
273 3). These were chosen because their inlet and outlet temperatures were monitored. Additionally, the flow rate
274 in the transmission pipe was directly measured, while the flow rate in the western supply pipe could be
275 estimated based on the measured primary flow rate and the flow distribution model (Section 2.2.2.2). Pipe
276 dimensions and material properties were also known. Finally, these pipes had the largest thermal mass, so
277 they were the most relevant to investigate with respect to thermal inertia effect. The model used the
278 measured inlet temperature and flow rate as input, and the resulting outlet temperatures were compared with
279 the measured.

280 To accurately model the plug flow along the pipes, all distribution pipes segments were simulated, as well as
281 connection hoses between consecutive collectors (Type 31 in Figure 3). This also allowed taking into
282 account the heat losses from the connection hoses. The soil temperature to calculate the heat losses from the
283 buried pipes was evaluated through Type 77 (Klein and et al., 2012).

284 The plate heat exchanger between the solar collector loop (primary side) and the DH network (secondary
285 side) was modeled through Type 5b (Klein et al., 2012). This type offers the possibility of inserting a
286 variable heat transfer coefficient. A specific TRNSYS project, simulating only the heat was developed to
287 calibrate Type 5b against measurements. Measured flow rates and inlet temperatures were given as input to
288 Type 5b and the heat transfer coefficient was varied so to obtain the best agreement between measured and
289 modeled outlet temperatures.

290 2.2.3. *Control strategy*

291 The control strategy implemented in the model was based on the information received by the plant designer

292 Arcon-Sunmark A/S. The control strategy aimed at reaching a constant outlet temperature, by continuously
293 regulating the total flow rate based on the solar irradiance. The desired outlet temperature is the DH supply
294 temperature, increased by the temperature drop across the heat exchanger. As the collector field was not
295 located near an auxiliary energy source, the collector field outlet temperature must meet the DH
296 requirements, if the energy is to be delivered to the DH network.

297 The main principles of the control strategy in Høje Taastrup solar heating plant can be summarized as
298 follows. The relation (Eq. 1) gives the theoretical solar energy output Q_{sol} , which is then used to regulate the
299 primary pump flow rate (Eq. 2). The primary pump is denoted as *Pump 1* in Figure 3.

$$300 \quad Q_{sol} = A_{field}(G_{tot} \eta_0 - a_1 \cdot (T_m - T_{amb}) - a_2 \cdot (T_m - T_{amb})^2) \quad (\text{Eq. 1})$$

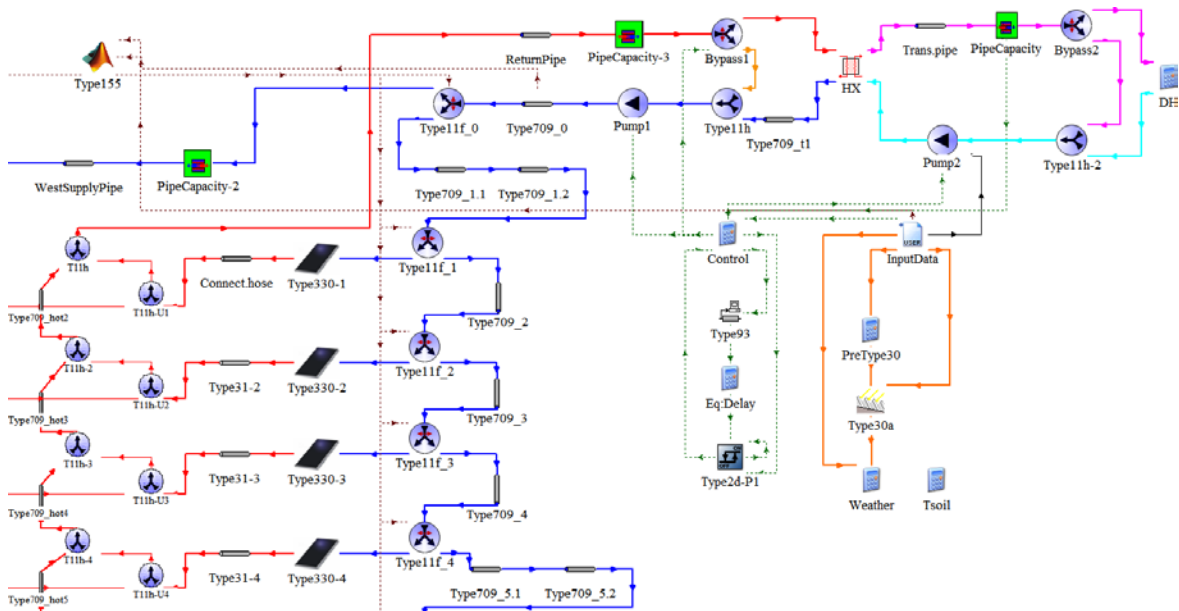
$$301 \quad \dot{m} = \max\left[\dot{m}_{min}, Q_{sol}/\left(c_p \cdot (T_{out, setpoint} - T_{in})\right)\right] \quad (\text{Eq. 2})$$

302 T_m is the mean temperature between the measured collector field inlet temperature T_{in} and the desired outlet
303 temperature $T_{out, setpoint}$. The solar irradiance G_{tot} is measured by the photovoltaic cell pyranometers (see
304 Section 2.1.2).

305 The condition for the primary pump to turn on is that either Q_{sol} is higher than a certain threshold, or one of
306 the monitored fluid temperatures in the collector field is higher than a preset value. The turn-off condition is
307 the negation of the turn-on condition, delayed by the time needed to discharge the energy content of the hot
308 return pipes. Because at the start-up of the primary pump in the morning the primary loop is still relatively
309 cold, the flow bypasses the heat exchanger and is recirculated across the collector field (*Bypass1* in Figure
310 3). When the field outlet temperature is sufficiently high, the primary bypass is closed and the secondary
311 pump is turned on. The secondary pump is regulated so that the heat capacity rate on both sides of the heat
312 exchanger is the same. At the start-up of the secondary pump, the bypass installed at the end of the
313 transmission pipes (*Bypass2* in Figure 3) recirculates the fluid until a temperature of 65 °C, compatible with
314 the DH network, is reached.

315 In the TRNSYS model, most of the control strategy is implemented in an Equation block, while the turn-
316 on/off conditions and the time delay are set by a differential controller Type 2d and Type 93 respectively
317 (Klein and et al., 2012).

318 A detail of the overall TRNSYS model, which implemented also the control strategy of the solar heating
319 plant, is shown in Figure 3. The only measured values used as input were the weather conditions (irradiance
320 and ambient temperature) and the return temperature from the DH network. The accuracy of the model was
321 tested, by comparing simulated and measured temperatures, energy outputs and flow rates under different
322 weather conditions.



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Figure 3: Detail of the TRNSYS model of Høje Taastrup solar heating plant. For sake of clarity, only the first four collector rows of the eastern subfield are shown. Blue and red connections represent the supply and return pipes of the solar collector glycol loop; purple and pale blue connections represent the supply and the return pipes with water to/from the DH network.

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3. Results and discussion

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This section presents and analyzes the results from the validation of the single components or subsystems, such as solar radiation sensors, solar collector, heat exchanger and pipes. Based on these results, the parameters of the single components could be accurately determined and used in the model of the solar heating plant. Secondly, the validation of the model of the plant is presented.

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3.1. Solar radiation measurements

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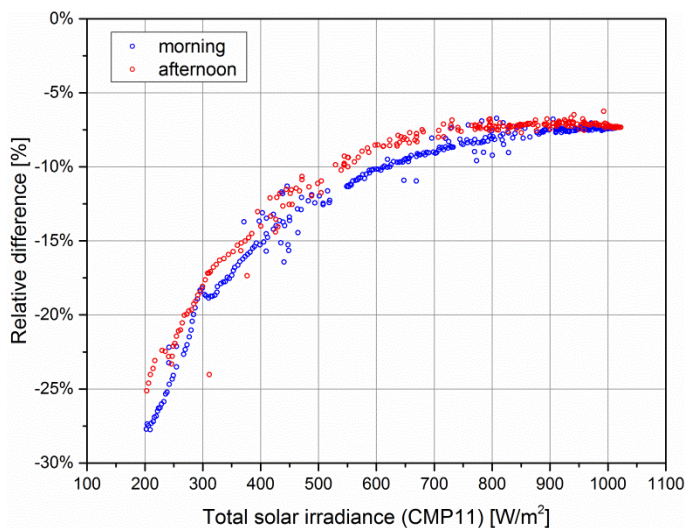
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Figure 4 shows the relative difference between the total solar irradiance measured by the photovoltaic cell pyranometers and that from the thermopile CMP11 pyranometer in a clear sky day. It can be seen that for high irradiances ($G_{tot} > 800 \text{ W m}^{-2}$), the photovoltaic pyranometers underestimated the solar irradiance by 7-8%. At lower irradiances (and larger incidence angles) the difference increased, up to 27% for $G_{tot} = 200 \text{ W m}^{-2}$. The non-perfect overlap of morning and afternoon data must have been caused by a small difference in the orientation of the pyranometers, with the CMP11 sensor oriented slightly more eastward than the photovoltaic sensors.

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342

Figure 4: Relative difference in the hemispherical solar irradiance between photovoltaic cell and thermopile CMP11 pyranometer.

343 As all sensors had been recently cleaned, the difference in the reading cannot be attributed to soiling, but was
 344 likely caused by degradation of the photovoltaic cell. Repeated measurements in similar sky conditions gave
 345 similar results. Conversely, lower differences ($\leq 5\%$) were found in case of overcast sky. This led to the
 346 conclusion that the large deviations between photovoltaic and thermopile pyranometer in the early morning
 347 and late afternoon were caused by larger incidence angles rather than low solar radiations.

348 The significant decrease in sensitivity of the photovoltaic pyranometer over time is a problem which is often
 349 observed with this type of sensors. However, photovoltaic cell sensors have the advantage of much lower
 350 price and much shorter response time (some milliseconds (SolData, 2016)), compared to a thermopile sensor
 351 (5-20 seconds (Kipp & Zonen, 2006)). If the instantaneous measured solar irradiance is used for control
 352 purposes, a fast response time of the sensor is of key importance and photovoltaic cell sensors could be
 353 preferred. However, they should be regularly checked and their sensitivity corrected, if needed. Additionally,
 354 the strong directional response (i.e., dependence of the measured radiation on the incidence angle) of the
 355 photovoltaic pyranometer suggests introducing a second correction to account for this effect.

356 Given the significant difference between the solar irradiance measured by the photovoltaic cell pyranometers
 357 and that from the thermopile pyranometers, it was important to use the two of them properly. Hence, the
 358 irradiance measured by the photovoltaic cell was used in the control strategy of the model, as it was used in
 359 the actual solar heating plant. The irradiance measured by the thermopile pyranometers provided the weather
 360 data input to the collector TRNSYS types.

361 3.2. Collector type components

362 With all three collector type variants, the collector field return temperature calculated by the model was
 363 always higher than the measured, if the efficiencies listed in Table 1 were used. To have a good agreement
 364 between the two, the peak collector efficiency η_0 had to be reduced by 7.3 % for Type 330b and Type 539,
 365 and by 7.8 % for Type 330a. For each type variant, the exact reduction was chosen so that the modeled daily
 366 energy output from the collector field differed from the measured one less than $\pm 1\%$.

367 The good accuracy of the measurement equipment (Section 2.1.2) excluded the presence of faults in the
 368 measured data used as input for the model. Additionally, these data were also carefully checked to spot
 369 possible outliers. Secondly, the presence of temperature sensors at the inlet and outlet of some collector rows
 370 allowed having a clear focus on the behavior of the single rows. This excluded the influence of possible
 371 biased heat losses and plug flow in the pipes. In each modeled collector row, the only components were the
 372 collector (Type 539 or 330) and the pipe Type 31, to take into account plug flow and heat losses in the
 373 connection hoses. Hence, it was concluded that the disagreement between modeled and measured outlet
 374 temperature was most likely due to a difference between the actual collector efficiency and the efficiency
 375 from Soleff, based on the test report. As the variation of the heat loss coefficients (for example, due to moist
 376 insulation) could not be evaluated, the reduction in performance was entirely attributed to the decreased
 377 transmittance of the glass cover, which can be caused by soiling, dirt and moisture on the glass cover. The
 378 pollution from the motorway running just 150 m away might have a more negative effect than less traffic-
 379 congested areas.

380 Table 2 shows the RMSD between measured and modeled temperatures at the end of the return pipe from the
 381 solar collector field. If ranked in order of better agreement with the measurements, the three collector types
 382 were Type 330b, Type 539 and Type 330a.

383 *Table 2: RMSD (in Kelvin) between measured and modeled return temperatures from the collector field with different collector type*
 384 *models.*

Date	Weather	Type 539	Type 330a	Type 330b
12/07/2015	overcast	2.05	1.99	1.74
13/07/2015	cloudy	2.26	2.07	2.05
14/07/2015	sunny	1.43	1.48	1.30
16/07/2015	sunny	1.13	1.42	1.05
17/07/2015	cloudy	1.71	1.95	1.72
24/07/2015	overcast	1.99	2.24	1.75
Mean		1.81	1.97	1.69

386 So, the enhancements introduced in Type 330b improved the agreement between model and measurements,
 387 compared to the original Type 539. However, Type 539 performed better than Type 330a. This can be
 388 explained by the fact that the flow regime in the collector was laminar at low flow rates, which, according to
 389 (Eq. 2), occurred in case of low solar irradiance. Low irradiance was measured either in the early morning
 390 and late afternoon of clear sky days or in cloudy days. In these conditions, the overall IAM used by Type 539
 391 was lower than that used by Type 330. In fact, in the early morning and late afternoon, at incidence angles
 392 larger than 60° , Type 539 linearizes the IAM, which is hence lower than that calculated by Type 330
 393 (Section 2.2.2.1). In cloudy conditions, when the fraction of diffuse radiation is significant, the IAM for
 394 diffuse radiation calculated by Type 539 was lower than that used by Type 330. Type 330 used a value of
 395 0.94, as stated by the collector test report (SP, 2016). These two different effects (use of turbulent efficiency
 396 also at low flow, and lower IAM at low radiation) almost canceled each other out in Type 539.
 397 Consequently, this type was slightly less accurate than Type 330b. Conversely, Type 330a overestimated the
 398 collector efficiency in case of low flow and low irradiance, and hence had the least accurate agreement.

399 3.3. Flow distribution

400 According to the Matlab model, the flow distribution in the collector field was fairly uniform in all the tested
 401 conditions. The maximum relative difference between the modeled flow rate in a collector row and that in
 402 case of a perfectly uniform flow distribution was lower than 6 %. The maximum difference between highest
 403 and lowest row flow rates was lower than 10 %, which is the maximum deviation in flow distribution in solar
 404 collector arrays recommended by the German standard VDI (2004).

405 Because of the fairly uniform flow distribution, it could be expected that neglecting this aspect would not
 406 affect the agreement between model and measurements. To verify this hypothesis, a simpler model where the
 407 entire collector array was simulated by only one collector type was developed.

408 Table 3 lists the RMSDs between measured and modeled field return temperatures, both for the model taking
 409 into account the flow distribution and for the simpler model. As expected, the simpler model had higher
 410 deviations (by about 1 K) compared to the more detailed model. Also in terms of energy output from the
 411 collector field, the simpler model differed more significantly from the measurements. Assuming the same
 412 decrease in the peak collector efficiency for both models (-7.3 %), the simpler model differed between
 413 +0.5 % and +2.6 %, compared to ± 1 % of the detailed model (Section 3.2).

414 *Table 3: RMSD (in Kelvin) between measured and modeled return temperatures from the collector field in case flow distribution is*
 415 *modeled (Detailed model) or not (Simpler model).*

Date	Detailed model	Simpler model
12/07/2015	1.74	2.94
13/07/2015	2.05	2.77
14/07/2015	1.30	2.06
16/07/2015	1.05	2.10
17/07/2015	1.72	2.65
24/07/2015	1.75	1.97
Mean	1.69	2.44

416

417 So taking into account the flow distribution improved the accuracy of the model compared to a perfectly
 418 uniform flow distribution scenario. There are different reasons why the more detailed scenario gave a better
 419 agreement. Firstly, modeling each segment of the distribution pipes, instead of using an average pipe length,
 420 allowed reproducing accurately the plug flow along the pipes and hence the time delay that the fluid takes to
 421 reach the single collector rows. Considering this aspect improves the accuracy of the model mainly in terms
 422 of RMSD of the outlet temperature, as temperature fluctuations are in phase when comparing model and
 423 measurements. Secondly, if the flow distribution in the collector field is not uniform, this reduces slightly the
 424 energy output of the field, which the model is able to reproduce. Finally, if all pipe segments are modeled,
 425 the heat losses can be calculated more accurately. This aspect had however a limited impact, because being
 426 the pipes well insulated, the impact of the heat losses was negligible in both models.

427 However, modeling the flow distribution was the most demanding and time consuming part, both in terms of
 428 programming and computing time. When TRNSYS used a time step of 1 minute, and convergence and
 429 integration relative tolerances of 0.001, a simulation of 2 days of normal operation was performed in
 430 approximately 2.5 minutes by a computer with quad-core CPU, 2.4 GHz CPU frequency and 8 GB memory.
 431 The computing time was about 4 times shorter, when Matlab was not called to calculate the flow distribution,
 432 and 50 times shorter for the simpler model, which used only one collector component to model the entire
 433 array. Therefore, the trade-off between increased accuracy and longer programming and computing time
 434 should be considered case by case. For example, a slower but more precise model could be desirable in case
 435 of on-line simulations. Conversely, a simpler but faster model is a better solution for preliminary evaluations
 436 or feasibility studies.

437 3.4. Pipes and thermal capacity

438 The effect of thermal capacity was investigated adding Type 306 to the supply pipe to the western subfield
 439 and the transmission pipe from the heat exchanger to the DH network. Measured inlet temperature and flow
 440 rate were given as input to the model, and the model outlet temperatures were compared with the measured.
 441 Two different types of days were analyzed: July 14 and 16, mainly clear sky days; July 13 and 17,
 442 characterized by fast fluctuation in solar irradiance due to continuously moving clouds.

443 Table 4 lists the RMSDs between measured and modeled pipe outlet temperature of the investigated pipes. It
 444 should be noted that the listed values were obtained taking into account the thermal mass of the steel pipe
 445 only and neglecting that of the pipe insulation. This choice was motivated by the fact that this simplification
 446 had no or negative effect on the RMSDs. In fact, the thermal capacity of the insulation accounted only for
 447 20 % of that of the steel pipe. Additionally, because of its low thermal conductivity, only a portion of the
 448 insulation thermal mass would actually be involved in the dynamic response of the pipe. Finally, Type 306
 449 models the thermal mass as a lumped capacity, characterized by one temperature and one heat transfer
 450 coefficient between fluid and solid part of the pipe. This simplification can be regarded as accurate for the
 451 steel pipe, due to its high thermal conductivity and small thickness, but not for the insulation.

452 *Table 4: RMSD (in Kelvin) between measured and modeled pipe outlet temperatures with and without taking into account the thermal*
 453 *capacity (Cap.) of the steel pipe.*

	13/07/2015	14/07/2015	16/07/2015	17/07/2015
West supply pipe (no Cap.)	1.87	1.67	1.93	3.12
West supply pipe (with Cap.)	1.15	1.20	1.45	1.91
Transmission pipe (no Cap.)	3.03	1.14	2.38	3.49
Transmission pipe (with Cap.)	2.19	1.05	0.71	1.48

454

455 The remaining deviation between measured and modeled pipe outlet temperature could be caused by several
 456 factors, such as measurement accuracy and limitations of the model to reproduce the exact pipe conditions.
 457 Additionally, the measured data available, which were used as input for the model, were instantaneous values
 458 with recording time of one minute (Section 2.1.2). Hence, the pipe model assumed constant inlet temperature
 459 and flow rate over one minute, although this might not be necessarily the case, especially in conditions of
 460 fluctuating solar radiation and consequent fast variation of the pump speed (see also Section 3.6).

461 Because considering the thermal capacity of the pipes improved the agreement between model and
 462 measurements, Type 306 was added to the longest pipes in the model, i.e. the western supply pipe, the
 463 common return pipe from the collector field and the transmission pipes to the DH.

464 3.5. Heat exchanger

465 A good agreement between modeled and measured outlet temperatures from the heat exchanger was found, if
 466 the overall heat transfer coefficient of Type 5b was given by (Eq. 3).

$$467 \quad UA = F_f(UA)_{nom} \left(\frac{\dot{m}}{\dot{m}_{nom}} \right)^{0.6} \quad (\text{Eq. 3})$$

468 According to the technical specifications of the heat exchanger, the heat transfer coefficient in nominal
 469 conditions is $UA_{nom}=440 \text{ kW K}^{-1}$. However, to fit the model with the measured temperatures, it was

470 necessary to introduce a correction factor for fouling $F_f = 0.77$. A second correction was added to take into
 471 account the reduced convective heat transfer coefficient at flow rates lower than the nominal one, $\dot{m}_{nom} = 58$
 472 $\text{m}^3 \text{h}^{-1}$.

473 As the difference in heat transfer coefficient UA between the technical specifications of the heat exchanger
 474 and real-world operation was significant, it was important to correct the model accordingly. Because flow
 475 rates and inlet/outlet temperatures across a heat exchanger are usually monitored, it is convenient to calibrate
 476 the heat exchanger model against measurements. For this purpose, one day of data with variable flow rate
 477 can be sufficient and improves the accuracy considerably.

478 *Table 5: RMSD (in Kelvin) between measured and modeled outlet temperatures from the heat exchanger, with and without taking into*
 479 *account its thermal capacity (Cap.).*

	13/07/2015	14/07/2015	16/07/2015	17/07/2015
Outlet on primary side (no Cap.)	1.39	0.64	0.53	1.24
Outlet on primary side (with Cap.)	1.38	0.63	0.53	1.23
Outlet on secondary side (no Cap.)	1.30	0.72	0.44	1.54
Outlet on secondary side (with Cap.)	1.15	0.69	0.47	1.52

480

481 The heat exchanger outlet temperatures obtained by using (Eq. 3) were compared with the measurements
 482 from days with different sky conditions. The results are summarized in Table 5. The days July 14 and 16
 483 were characterized by clear sky conditions and hence smooth variations of the flow rates, while July 13 and
 484 17 had fast fluctuations of the flow rate due to passing clouds (see Figure 5). On the clear sky days, the
 485 RMSD between model and measured outlet temperatures was about 0.4-0.7 K on both primary and
 486 secondary side. On the cloudy days, characterized by rapidly varying flow rate, the RMSD was slightly
 487 higher (1.2-1.5 K). These larger deviations can be explained by the recording time of the measured data used
 488 as model input, as in Section 3.4. Adding the thermal capacity of both fluid content and metal plates to the
 489 heat exchanger through Type 306 had negligible effect on the RMSD in most cases, so this aspect was
 490 neglected in all other simulations.

491 3.6. Control strategy and overall TRNSYS model

492 The overall TRNSYS model reproduced in detail the solar heating plant in Høje Taastrup, both in terms of
 493 components and control strategy. The only external boundary conditions required by the model were the
 494 return temperature from the DH and weather conditions.

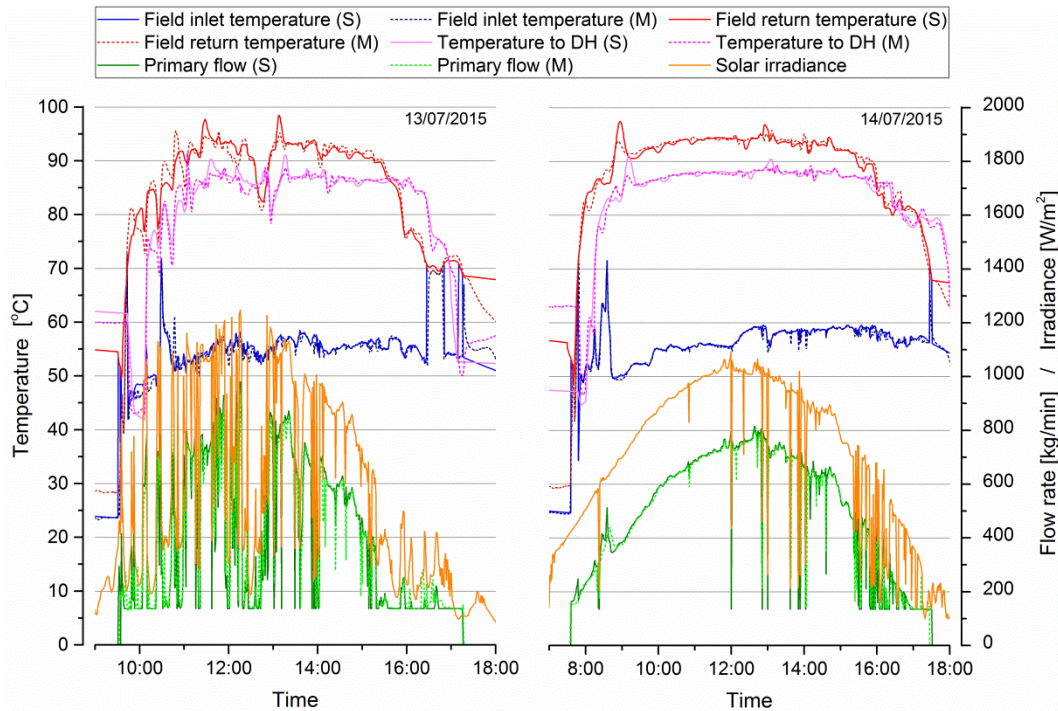
495 The good agreement between measurements and model can be appreciated in Figure 5. Figure 5 shows some
 496 of the measured and modeled data for two different types of weather conditions. As can be seen, July 13 was
 497 characterized by moving clouds and so fast fluctuations of the solar radiation, which caused higher
 498 deviations between measurements and model.

499 Table 6 presents an overview of the comparison between model and measurements in terms of fluid
 500 temperatures in different parts of the system, gross and net produced energy and flow rate in the primary
 501 side. The gross energy output from the collector field was calculated whenever the primary pump was in
 502 operation. So it also includes the energy collected during pre-heating of the primary loop, when the primary
 503 bypass was open. The energy delivered to the DH network was calculated at the end of the transmission line,
 504 when the supply temperature was higher than 65 °C (Section 2.2.3). The cumulated flow is the time integral
 505 of the flow rate. The RMSD of the different temperatures is the deviation between measured and modeled
 506 values. Taking into account the accuracy of the measuring equipment (see Section 2.1.2) and the density and
 507 specific heat of the heat transfer fluids, the uncertainty of the measured energy outputs and cumulated flow
 508 rates was calculated through the formula for propagation of error (Eq. 4):

$$509 \quad s_f = \sqrt{\left(\frac{\partial f}{\partial x}\right)^2 s_x^2 + \left(\frac{\partial f}{\partial y}\right)^2 s_y^2 + \dots + \left(\frac{\partial f}{\partial z}\right)^2 s_z^2} \quad (\text{Eq. 4})$$

510 where s_f is uncertainty of the function f (e.g., the energy output from the collector field) and s_i is the
 511 uncertainty of the function variable i , (e.g., volume flow rate, density and specific heat of the fluid, inlet and
 512 outlet temperature).

513 Based on (Eq. 4), the uncertainty on the measured energy outputs was 1.5 % for the days in the period July
 514 13-17, and 1.7 % for July 12. The uncertainty on the measured mass flow rate was 0.8 %.



516
 517 *Figure 5: Comparison between measurements (M) and simulation results (S) based on the data from 13-14 July 2015.*

518 The tabled values show the good agreement between model and measurements. In terms of energy and
 519 cumulated primary flow, the model differed from the measurements no more than 1 %, with the only
 520 exception being the overcast day July 12.

521 *Table 6: Comparison between measurements (M) and simulation results (S) of the overall TRNSYS model.*

		12/07/2015	13/07/2015	14/07/2015	16/07/2015	17/07/2015
Gross energy output from field (M)	MWh	2.42	6.63	11.4	11.7	8.63
Gross energy output from field (S)	MWh	2.34	6.58	11.4	11.8	8.62
Deviation in gross energy output	%	-3.3 %	-0.8 %	0 %	0.9 %	-0.1 %
Energy supplied to DH (M)	MWh	2.31	6.48	11.4	11.6	8.44
Energy supplied to DH (S)	MWh	2.27	6.47	11.3	11.7	8.45
Deviation in energy to DH	%	-1.7 %	-0.2 %	-0.9 %	0.9 %	0.1 %
Cumulated primary flow (M)	kg	$8.24 \cdot 10^4$	$1.79 \cdot 10^5$	$2.92 \cdot 10^5$	$2.99 \cdot 10^5$	$2.29 \cdot 10^5$
Cumulated primary flow (S)	kg	$8.03 \cdot 10^4$	$1.78 \cdot 10^5$	$2.95 \cdot 10^5$	$3.02 \cdot 10^5$	$2.29 \cdot 10^5$
Deviation in primary flow	%	-2.5 %	-0.6 %	1.0 %	1.0 %	0 %
RMSD($T_{\text{supply to field}}$)	K	1.37	1.20	1.33	1.10	1.28
RMSD($T_{\text{return from field}}$)	K	2.82	2.37	1.48	1.76	2.59
RMSD($T_{\text{supply to DH}}$)	K	3.77	2.20	1.43	1.89	2.29

522
 523 As expected, the temperature deviations were higher in the days characterized by fluctuating solar radiation
 524 (July 13 and 17), compared to clear sky days. The main reason for this is that, although both measured and
 525 simulated data were available once per minute, this one minute time step had a different meaning in the two
 526 cases. In the measured data, one minute is the recording time step, after which the instantaneous measured
 527 value of all monitored parameters was recorded. No information of what happened between one recording
 528 and the next was stored. In the simulation, one minute was the time step used by the model to calculate the
 529 output parameters. Inputs, such as solar radiation and return DH temperature, and calculated parameters,

530 such as flow rates, were assumed constant during the time step. This simplification is reasonable, when the
531 input parameters change slowly, such as in clear or overcast sky conditions. Higher deviations can be
532 expected, in case of higher frequency changes, for example in a cloudy day.

533 A second reason may be the different response time of the real pump and the pump model. The latter reacted
534 instantly to a change in Q_{sol} (Eq. 2), while the former had certain inertia. This effect was more evident in case
535 of rapidly moving clouds and consequent fast variation of the pump speed.

536 Deviations in field return temperature were observed in the early morning, especially in presence of
537 fluctuating solar radiation (Figure 5). On the other hand, July 14 (clear sky day) had a better agreement
538 between measured and modeled temperature profiles, although some misalignment is still visible in the first
539 hours of operation. This might be caused by the simplified modeling of the collector heat capacity. The
540 current standard ISO 9806 (ISO, 2014) accounts for the collector heat capacity through a single value (the
541 *effective thermal capacity*), which may not be sufficient to reproduce completely the dynamic response of the
542 collector. Firstly, among the collector characteristic parameters determined by the quasi-dynamic test method
543 (ISO, 2014), the effective thermal capacity may not always accurately be identified, due to the constant inlet
544 temperature constraint, which limits the dynamic response of the collector (Kong et al., 2015). Secondly,
545 because of how the test is performed, the calculated effective thermal capacity is affected by the residence
546 time of the fluid in the collector, and hence may change at different flow rates. Additionally, the test method
547 assumes a lumped heat capacity, without distinction between fluid and solid parts of the collector. However,
548 it is reasonable to expect that the different components, such as fluid, metal parts and insulation, have a
549 different dynamic response. Consequently, a value of effective thermal capacity, which may give a realistic
550 response during normal operation, may not be as accurate in other phases, such as start-up and/or cooling
551 down of the collector. However, the different effect of the collector thermal capacity between model and
552 actual plant affected mainly the dynamic response of the collector field, and not its energy output. In fact the
553 deviations between model and measured gross energy output in the morning only were not higher than 1 %.

554 The simulation results for July 12, day characterized by overcast sky conditions, had a lower agreement with
555 the measurements compared to the other days. Both the simulated gross energy output from collector field
556 and the simulated energy delivered to the DH network were lower than the measured ones (-3.5 % and -
557 1.7 % respectively). The main reason for this was found in the lower cumulated flow rate in the simulation
558 compared to the measurements. The simulated and measured flow rates had extremely similar profiles,
559 proving the good ability of the model control strategy to reproduce the actual one. However, the measured
560 data showed some sudden and very brief peaks of the flow rates, which could not be reproduced by the
561 model control strategy, because not justified by the recorded weather data. As mentioned above, the fact that
562 the measured data are the instantaneous (and not average) values of the monitored data may explain part of
563 the discrepancy. This explained also the higher RMSD of the investigated temperatures, as even temporary
564 differences in flow rates immediately affect the plug flow, causing a shift and mismatch of the temperature
565 profiles. Secondly, the gross energy production on this day was fairly low (2.42 MWh), between 2.7 and 4.8
566 times lower than the other investigated days. So, even modest absolute differences between model and
567 measurements caused stronger relative differences, compared to days with higher energy output.

568 In Table 6 the data from July 24 are not shown. In fact, taking advantage of the overcast sky conditions,
569 some manual calibration of the plant was performed in this occasion. Hence, the control strategy did not
570 follow the equations described in Section 2.2.3, so it was pointless to compare the measured and modeled
571 flow rate, and consequently all the other quantities.

572 **4. Conclusions and future perspective**

573 The developed TRNSYS-Matlab model showed a good agreement with the measurements in different
574 weather conditions. Although the exact results presented in this study refer to the specific case of Høje
575 Taastrup solar heating plant, they can be used to draw some general considerations and conclusions which
576 should be taken into account when analyzing measurements from other solar heating plants or when
577 modeling this kind of installations. The following conclusions can be drawn:

- 578 • Accuracy of the input data is of key importance for precise modeling. Special attention should be
579 paid to solar radiation sensors, which should be recalibrated, if their sensitivity is suspected of

- 580 varying.
- 581 • If the collectors experience laminar flow for a relevant fraction of their normal operating conditions,
582 a collector model, such as Type 330, with efficiency equations defined differently depending on the
583 flow regime, can improve the accuracy.
- 584 • Considering the exact flow distribution in the collector field improves the accuracy, but it requires
585 much longer programming and computing time. Depending on the aimed level of accuracy, this
586 aspect may be considered or not.
- 587 • The thermal capacity of pipes may be considered for longer pipes only, otherwise its role is
588 negligible.
- 589 • The heat transfer coefficient of a heat exchanger should be estimated through measurements rather
590 than from technical specifications, so to include aspects, such as fouling and flow rate dependence.
- 591 • It was possible to reproduce the actual control strategy of the solar heating plant, maintaining a
592 good agreement between model results and measurements.
- 593 The presented model is meant to be used to investigate different improvements measures in terms of
594 operating conditions and control strategies, which may enhance the performance of the plant and provide a
595 more constant return temperature from the collector field. The improvements measured which are planned to
596 be investigated are improvements of the control strategy (such as more detailed input and closed-loop
597 control), different heat transfer fluids in the primary loop and different temperature levels. Additionally, one
598 year simulations in the above mentioned conditions will elucidate their impact on the yearly performance.

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