

Thermal behavior of radiation damage cascades via the binary collision approximation: Comparison with molecular dynamics results

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Based on the profile of the energy deposition obtained using the binary collision model, we follow the diffusion of energy by solving a simplified version of the heat equation. An estimation of the molten zone compares very well with the molecular dynamics prediction for the same event. We discuss the reasons for this agreement and the relevance of such simplified procedure in terms of present-day computer limitations to simulate high energy cascades using molecular dynamics.

I. INTRODUCTION

One of the problems involved in the design of a fusion reactor and in predicting the lifetime of conventional fission reactors is the degradation of the engineering properties of structural components under irradiation.¹ The understanding of the microscopic mechanisms of damage is also relevant in the field of ion implantation.² The starting point of the damage, the displacement cascade, cannot be treated analytically because it drives the material into a highly nonequilibrium state, where many-body interactions, electron-phonon coupling, thermodynamic and kinetics effects simultaneously contribute and compete. Thus, a complete theoretical model is not yet available; computer simulations are the main method for the analysis of the initial stages of radiation damage, over a time scale that is inaccessible to experimentation.

Some of the most relevant parameters for the prediction of the material's behavior under irradiation are the number of freely migrating defects (FMD); their tendency to cluster, forming voids, dislocation loops, or stacking faults; the rate of atomic mixing; and the interaction with the impurities created by nuclear transmutations. All of them depend on the interaction between ions within the crystalline lattice, and therefore a full many-body ion-ion interaction calculation in the computer simulation is strictly necessary.

This is satisfactorily achieved in the molecular dynamics simulations (MD),³ where the space-time trajectories of a large ensemble of atoms is constructed by solving the classical equations of motion generated by a model interaction potential. However, present-day computational restrictions impose severe limitations in the number of ions that can be followed, typically a hundred thousand, and therefore only low-energy cascades, up to 5 KeV, can be simulated.⁴⁻⁷

MD simulations have been very successful in giving a clear representation of the different stages occurring in a cascade: the collisional phase, the thermal spike, the cascade quenching, and collapse. Quantitative information related to the above-mentioned parameters has also been obtained.

One of the most important results of MD simulations is the prediction of the cascade core melting in Cu and Ni.⁴⁻⁷ This result is obtained by comparison between (a) pair correlation functions calculated in the liquid and in the cascade, (b) the diffusion coefficient calculated in the core of the cascade and experimental values for the liquid, and (c) atomic densities in the cascade core and experimental value for the liquid.

This result came from MD simulations on Cu and Ni; therefore it cannot be concluded that cascade cores melt in all materials, and also that there is not direct experimental verification of melting. In this work we assume that the melting picture for Cu and Ni is correct and apply simple thermodynamics to predict the behavior of cascades.

Interpretation of the damage mechanisms in terms of the cascade core melting gives a satisfactory explanation to the experimental behavior observed in Cu and Ni under irradiation.⁸ In fact, the differences in the melting temperature between these two metals would explain the smaller and shorter core melt in Ni compared to Cu, with implications regarding the extent of mixing and cascade collapse.

This picture of cascades still lacks an ingredient whose importance is difficult to assess, namely, the contributions of the electronic thermal conductivity and heat capacity. In fact, the electron-phonon coupling could quench the thermal spike by heating the electrons and by transporting this energy away from the cascade zone. Qualitative arguments^{9,10} show that these effects are not important in the low energy cascades simulated by molecular dynamics because the time scale, i.e., a few picoseconds, is short compared to the

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phonon-electron relaxation time. However, cascades in the energy range relevant to the fusion environment certainly will last longer, and the electronic coupling determines the duration of the thermal spike.

Previous attempts to solve the cascade evolution using continuum heat equations gave only qualitative information because both the energy deposition profile and the thermodynamic factors entering the equation are, in fact, unknown.^{11,12}

The aim of this paper is to show that by coupling the binary collision approximation, which gives the profile of the energy deposition, to a simplified heat equation, a description of the melt in complete agreement with the results of molecular dynamics in the range of 5 KeV can be obtained. Although this description does not provide the time scale of the processes, it could be very useful in the evaluation of subcascade interactions, in an energy range inaccessible to MD with present-day computational performances.

The reasons for this agreement are not evident *a priori*. In fact, the MD simulations have shown that several effects that could have been considered as important, should not be considered as such. In particular, the amount of energy transported by the pressure wave and focousons, the variation of the melting temperature with pressure, and finally the variations of the latent heat of melting with pressure, are some of these effects which proved to be unimportant. Almost all of the energy deposited into the lattice is transformed into heat, and so the heat equation correctly gives the cooling. The contribution of replacement collision sequences to the energy transport is included in both the MD and the lattice version of the binary collision model we have used.

The paper is organized as follows: Sec. II describes the output of the binary collision model, used as an initial energy density profile; Sec. III shows the simplifications of the heat equation that allow us to obtain solutions regardless of the values of the thermodynamic input; Sec. IV compares our results to those of MD; finally, Sec. V justifies the reasons for the good agreement between the binary collision model and MD and stresses the relevance of this type of simplified approach for high energy events.

II. BINARY COLLISIONS

In this approximation, the cascade develops inside the crystalline solid as a sequence of two-body collisions.¹³ The crystalline structure is given by the locations of the target atoms. An atom is set into motion if, as a consequence of a collision, it receives an energy larger than some cut-off, E_c . Similarly, an atom no longer moves if its energy falls below E_c . A cascade ends when all atoms have an energy lower than E_c . Additional parameters are a binding energy, E_b , which is

lost every time an atom is displaced from its perfect lattice position, and the parameters controlling the inelastic electronic losses. For the energies considered here, up to 5 KeV, inelastic electronic losses are negligible. We have only two parameters, namely, E_b and E_c . The first one determines the threshold energy for the formation of Frenkel pairs. Although there is some freedom in the choice of E_c , which essentially determines the total number of atoms set into motion, it will be shown in Sec. IV that this has a negligible influence on the energy density profile.

The energy balance in this type of approach is as follows: The total initial energy, i.e., the kinetic energy of the primary knock-on atom, E_{PKA} , is distributed between the inelastic collisions with electrons, E_i , the kinetic energy, E_k , mentioned above, and the binding energy lost at each collision, E_b (which represents the potential energy of the distorted lattice and the excitations of vibrations), plus the energy transferred to those atoms below the cut-off. This last contribution is called damage energy, E_d . Therefore,

$$E_{PKA} = E_i + E_d + E_k \quad (1)$$

The dependence of these values with E_{PKA} is such that E_i increases, E_d decreases, and E_k remains constant as E_{PKA} increases.¹⁴ E_k is between 20% and 30% of E_{PKA} , regardless of E_{PKA} .

To perform these calculations we have used the Marlowe-12 code.¹³ The output configuration contains the position and the kinetic energy of all atoms that have been set into motion. It represents the end of the collisional phase of the cascade.

For the cases we have studied, with $E_{PKA} = 5$ KeV in Cu, we obtain E_k in the neighborhood of 1.8 KeV. The key problem now is how to relate the spatial distribution of this amount of energy to the real location of the total energy deposited. The volume of the melt strongly depends on this profile of energy deposition. Since the only available information in the binary collision code is the last location of the atoms, a simple way to solve this problem is to apply a multiplicative factor, E_{PKA}/E_k , to the energy of each of these atoms. In this way the correct total amount of energy is deposited in the crystal but at the last location of the moving atoms, instead of being along their trajectories. As we show in Sec. IV, this assumption does not significantly affect the energy density profile.

We start with the energy density at the end of the collisional phase. This energy will be transformed into heat by thermal equilibration. MD results show that this is achieved after 0.25 psec for 5 KeV cascades⁵; from this time on, a temperature can be defined. However, the concept of temperature has to be used with care, at least at the earliest times of the heat spike, since the number of degrees of freedom with a given

energy is too small, due to a very large energy gradient. One of the basic assumptions of thermodynamics of the nonequilibrium process is thus violated. Temperature profiles for several times also show⁵ that the maximum volume of the molten zone is attained at the earliest time, i.e., 0.25 psec. It is important to stress that it should not necessarily be so; it depends on the starting energy density profile.

Since we shall apply the heat equation at the end of the collisional phase, before equipartition is reached, a justification is needed. Considering the energy flow as diffusive does not imply equipartition but the absence of net crystalline momentum. This was shown to be so in Fig. 3 in Ref. 5, where the dilatation portion of the shock wave carries only a negligible portion of the total energy. As evaluated in Sec. V below, it can therefore be neglected. We proceed then to propagate this energy as heat.

III. HEAT PROPAGATION

The equation of heat conduction in an isotropic, uniform medium with thermal conductivity κ and density ρ is,

$$\frac{\partial Q}{\partial t} = \nabla \cdot \{(\kappa/\rho)\nabla Q\} \quad (2)$$

Discretization on a cubic lattice of lattice constant a gives,

$$\begin{aligned} Q(\mathbf{r}, t + \Delta t) = & (\kappa\Delta t/\rho a^2) \{Q(x + a, y, z, t) \\ & + Q(x - a, y, z, t) \\ & + Q(x, y + a, z, t) \\ & + Q(x, y - a, z, t) \\ & + Q(x, y, z + a, t) \\ & + Q(x, y, z - a, t) \\ & + [(\rho a^2/\kappa\Delta t) - 6]Q(\mathbf{r}, t)\} \end{aligned} \quad (3)$$

In this expression ρ and κ are functions of T , and therefore of \mathbf{r} and t . Taking spatial averages of these quantities, $\langle \rangle$, and choosing Δt such that,

$$\Delta t = \langle \rho a^2 / 7\kappa \rangle, \quad (4)$$

Eq. (3) then takes the form of a simple average over nearest neighbor cells, namely,

$$\begin{aligned} Q(\mathbf{r}, t + \Delta t) = & (1/7) \{Q(x + a, y, z, t) \\ & + Q(x - a, y, z, t) \\ & + Q(x, y + a, z, t) \\ & + Q(x, y - a, z, t) \\ & + Q(x, y, z + a, t) \\ & + Q(x, y, z - a, t) \\ & + Q(\mathbf{r}, t)\}; \end{aligned} \quad (5)$$

where t is now measured in unknown units that we call hereafter steps. It should be noted, in addition, that these units are not linearly related to time. This approximation is reasonable provided the temperature variation of the parameters in Eq. (4) is small in order to justify the average. Also, the number of steps to be integrated must be small, as this Δt is the largest possible and the integrated function may accumulate errors due to the linearization of the differential operators. Finally, the adequacy of the approximation will be evaluated by the nature of its predictions, as compared to MD results. If we let κ be the metallic thermal conductivity of Cu and a its lattice parameter, then $\Delta t = 1.7 \cdot 10^{-4}$ psec. On the other hand, conductivities corresponding to insulators give Δt in the range of 0.1–0.01 psec. These figures clearly show why the effective thermal conductivity cannot be the metallic one: the time scale becomes too short, compared with the electron-phonon relaxation time, for the electrons to equilibrate with ions.

In order to determine the volume of the melt we follow two procedures. First, we evaluate the energy necessary to heat the unit of volume up to the melting temperature, plus the latent heat of melting. In the second procedure, we just estimate the energy necessary to heat a classical degree of freedom up to a temperature T_m , namely, $3 k_B T_m$. The differences between these two methods are, once again, the unknown contribution of electrons and the differences in the potential energy on going from the solid to the liquid. Both strongly depend on the material. We interpret these two values as giving the lower and upper limits of the true molten region.

For Cu, the specific heat, C_p , at 300 K is $2.53 \cdot 10^{-4}$ eV/(K atom); the classical value is $3 k_B = 2.58 \cdot 10^{-4}$ eV/(K atom). At 2000 K it becomes $3.2 \cdot 10^{-4}$ eV/(K atom). The melting temperature is 1357 K and the latent heat of melting, L , is 0.135 eV/atom. In this case, a reasonable approximation for the energy necessary to heat an atom from 0 K up to the melting point, Q_1 , is given by the classical law,

$$Q_1(\text{Cu}) = 3 k_B T_m = 0.35 \text{ eV/atom}, \quad (6a)$$

and the energy to go from 0 K to the liquid phase, Q_2 , is,

$$Q_2(\text{Cu}) = Q_1 + L = 0.485 \text{ eV/atom}. \quad (6b)$$

Quantum effects at low temperature do not significantly change these values, and we neglect them. In Ni the specific heat at 300 K is also close to the classical value, $2.65 \cdot 10^{-4}$ eV/(K atom), but at 2000 K it becomes $4.75 \cdot 10^{-4}$ eV/(K atom), 85% larger due to electronic contributions. The melting temperature being 1746 K, a reasonable approximation is to assume a linear depen-

dence of C_p between 300 K and 2000 K, giving,

$$Q_1(\text{Ni}) \sim 0.6 \text{ eV/atom}. \quad (7a)$$

The latent heat of melting is $L = 0.191 \text{ eV/atom}$; therefore,

$$Q_2(\text{Ni}) = Q_1 + L \sim 0.79 \text{ eV/atom}. \quad (7b)$$

The electronic contributions to the specific heat and to the heat of melting are not included in the MD simulations; to compare with them, the following values of Q_1 and Q_2 are also used,

$$Q_1(\text{Ni})^* = 3 k_b T_m = 0.450 \text{ eV/atom}, \quad (8a)$$

$$Q_2(\text{Ni})^* = Q_1^* + L^* \sim 0.64 \text{ eV/atom}, \quad (8b)$$

L^* being the lattice contribution to the latent heat of melting.

From the output of Marlowe, the matrix $Q(\mathbf{r}, t = 0)$ is filled, with a lattice spacing equal to the lattice parameter of the corresponding metal. Heat propagation is applied, Eq. (5), and profiles of spherically averaged energy densities at several times are calculated. The number of cells with energy above Q_1 and above Q_2 is evaluated.

IV. RESULTS

We present results of 5 KeV cascades in Cu and Ni, with *PKA* directions close to $\langle 110 \rangle$ and $\langle 111 \rangle$. The crystal temperature is zero in all cases. The input parameters in Marlowe are as follows: no electronic losses, $E_b = 0.5 \text{ eV}$ and $E_c = 4.5 \text{ eV}$. This value of E_c gives a thousand moving atoms.

Table I shows the relevant parameters characterizing the output of Marlowe. The kinetic energy is remarkably constant in all cases, as is the number of displaced atoms. σ_i are the eigenvalues of the inertial tensor of the energy distribution, indicating an asymmetry between the largest and the shortest principal axis of a factor of 0.3 to 0.4 for all events.

Figures 1 and 2 show the energy profiles for Cu $\langle 110 \rangle$ and Ni $\langle 110 \rangle$ cascades, respectively, at four different times. At step 0, both profiles are very similar since the masses and lattice parameters are similar. The implication is that the time evolution in terms of steps is

TABLE I. Description of the 5 KeV cascades analyzed in this work. In all cases, input parameters for Marlowe are $E_b = 0.5 \text{ eV}$ and $E_c = 0.5 \text{ eV}$. E_d and E_k are damage and kinetic energies, respectively, N_p is the number of atoms set into motion, and σ_i is the principal axis of inertia of the energy tensor.

<i>PKA</i>	E_d (eV)	E_k (eV)	N_p	σ_1 (Å)	σ_2 (Å)	σ_3 (Å)
Cu $\langle 110 \rangle$	3661	1339	783	17.3	15.9	11.3
Cu $\langle 111 \rangle$	3721	1279	762	16.8	15.1	12.6
Ni $\langle 110 \rangle$	3670	1330	754	18.0	17.1	12.3
Ni $\langle 111 \rangle$	3730	1270	721	16.4	14.7	12.7

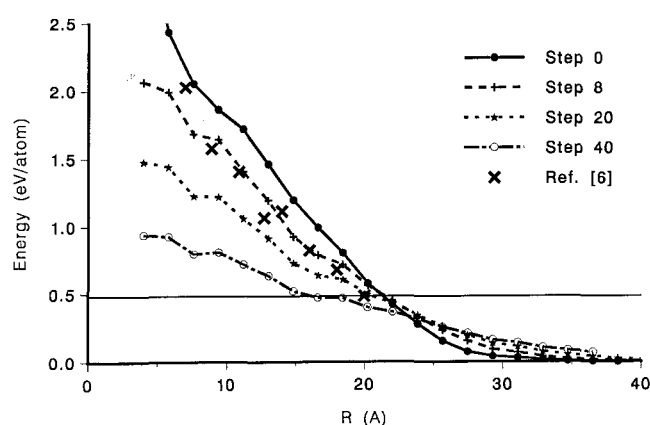


FIG. 1. Spherical averaged energy density for Cu $\langle 110 \rangle$ 5 KeV cascade at different time steps. Step 0 corresponds to the initial configuration as obtained from Marlowe. Step 8 corresponds to the maximum volume of the melt. Horizontal line at $E = 0.485 \text{ eV/atom}$ indicates the criterion for melting, Eq. (6a). Also shown is the profile at $t = 0.26 \text{ psec}$ obtained by MD simulations.⁶

similar too. Figure 1 also shows the data of an MD simulation using the Embedded Atom Model, EAM, for a similar event, at $t = 0.26 \text{ psec}$.⁶ The similarity in the radial distribution of the energy is striking, and it constitutes one of the main results of this work. In addition, it provides us with a first estimation of a time scale, since our step 8 corresponds to 0.26 psec, or $\Delta t = 0.03 \text{ psec}$. It is important to point out that we found that this similarity in the radial distribution is quite general, being independent of the cascade direction, $\langle 110 \rangle$ or $\langle 111 \rangle$, and also of the MD reference used to compare with, EAM,⁶ or pair-potentials.⁵

After eight steps in Cu, the melt reaches its maximum volume. This volume is $4.16 \cdot 10^4 \text{ Å}^3$; it corresponds to a sphere of radius 21.5 Å, which compares perfectly well with the MD result.

An interesting conclusion from this point is that in MD simulations, the earliest time when a temperature

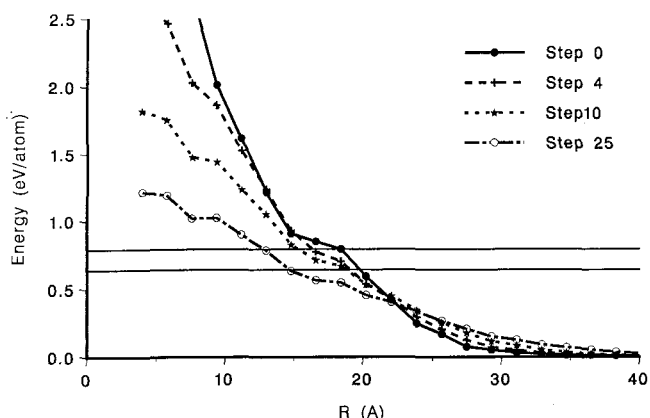


FIG. 2. Same as Fig. 1, for Ni $\langle 110 \rangle$ 5 KeV cascade. Horizontal lines, at $E = 0.64$ and 0.791 eV/atom , correspond to both melting criteria discussed in the text, Eqs. (7b) and (8b).

evaluation is meaningful is after equipartition. In 5 KeV it occurs at about 0.25 psec; from there on, the volume of the melt decreases. In our simulations, we observe that the maximum volume of the melt occurs at step 8, where the distributions coincide. It is therefore justified to consider this volume as in a liquid phase.

Complete resolidification is achieved after step 75, as shown in Fig. 3. Using the corresponding MD results,⁴⁻⁷ this time is around 3.5 psec, thus providing us with a second and more precise estimation of our time scale, namely, $\Delta t = 0.046$ psec.

Comparison between our results and MD for Ni is also in very good agreement when the lattice value $Q_2(\text{Ni})^*$, Eq. (8b), is used for the melting criterion. The corresponding time evolution is shown in Fig. 3. Estimation of the time scale in this case gives $\Delta t = 0.05$ psec, which is, of course, compatible with the estimation in Cu because in MD simulations only lattice thermal conductivity is included and those of both metals should be very similar. If electrons achieve thermal equilibrium with the lattice, and Eq. (7b) is used for $Q_2(\text{Ni})$, the volume of the melt is significantly reduced, as shown in Fig. 3, and the time scale cannot be estimated. The real situation is located between these two extreme limits. The important differences in volume and lifetime of the melt in Cu and Ni were considered in Refs. 4-7 as the reason for the different experimental behavior observed under irradiation.

In order to analyze whether the results reported here are due to a fortuitous coincidence, we have studied the influence of the only free parameter in this approach, namely, the energy cut-off in Marlowe. Table II shows the results of four 5 KeV $\langle 111 \rangle$ cascades in Cu at different values of E_c , between 2.25 and 18 eV. The

TABLE II. Influence of the cut-off energy, E_c , on the maximum volume of the melt. Four values of E_c are analyzed. Number of atoms set into motion, N_p , maximum volume of the melt, V_m , and corresponding time step are reported.

E_c (eV)	N_p	V_m (\AA^3)	Step
2.25	1068	$4.17 \cdot 10^4$	8
4.5	783	$4.16 \cdot 10^4$	8
9.0	537	$4.11 \cdot 10^4$	8
18.0	340	$4.12 \cdot 10^4$	8

number of atoms set into motion is strongly dependent on E_c but the energy deposition is insensitive to it, as shown by the maximum volume of the melt reported in the table. This gives strong support to our analysis.

V. DISCUSSION

The results presented in this paper are very simple and qualitative. Similar approaches were proposed several years ago.^{11,12} However, the present interest resides in the fact that it is only at present that this type of formalism can be compared with MD simulations. Let us discuss two points that show why the MD simulations are essential to support this simplified picture.

First, a cascade can be viewed as an explosion generating a radial compression wave. In that case, part of the energy is transported in the elastic field of this wave, traveling at the speed of sound (typically $40 \text{ \AA}/\text{psec}$), and leaving the cascade core in less than half a psec. The energy available to be transformed into heat is then reduced. The formation of this wave depends on the dynamics of the collisional phase, requiring a high degree of coherence in the motion in order to create a net radial momentum. As far as we know, there is no attempt in the literature to analyze this type of behavior except, naturally, the MD simulations where the presence of this wave is demonstrated through the radial density fluctuations reported in Ref. 5. These fluctuations decrease the density inside a sphere of 20 \AA and increase it outside, reaching values as high as 10% at $t = 0.26$ psec. However, assuming a linear response to evaluate the elastic energy stored in this strain field, we obtain a value of $0.006 \text{ eV}/\text{atom}$ and a total energy of 100 eV , indicating that the energy leaving the system as a shock wave is negligible compared to the amount transformed into heat.

The second point to be made is that under a density fluctuation of 10%, the pressure is, once again assuming linear response, extremely high, $\sim 10^5$ bars. This pressure may have a large influence on the melting temperature of the material.¹⁵ However, MD simulations show that the melting occurs at temperatures comparable to those under normal conditions. At this point it seems important to point out that the melting

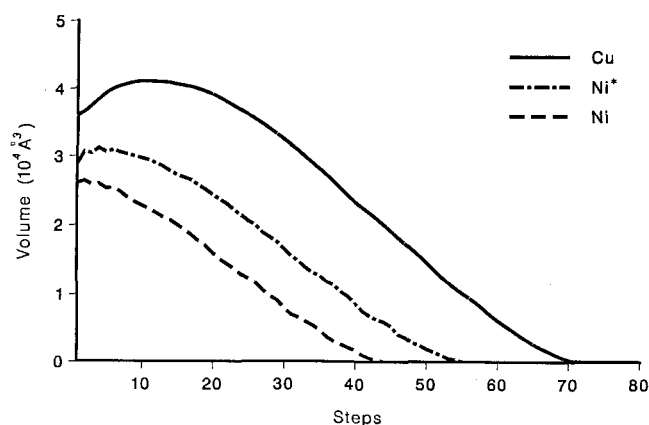


FIG. 3. Time evolution of the molten volume for 5 KeV cascades in Cu and Ni. The two curves for Ni, labeled Ni and Ni*, correspond to different melting criteria, Eqs. (7b) and (8b), respectively. The lowest curve corresponds to the case where electrons give their maximum contribution to the heat capacity. Time scale is unknown and is different for each one of the three curves. See text.

appears inside the sphere of radius 20 \AA , where the pressure is extremely high and negative, and melting is never seen in the region where the pressure is high and positive. If the limit where the pressure changes sign is what determines the boundary of the melt, then all the thermodynamic arguments presented in this paper could be wrong and the agreements found to be the result of an unfortunate coincidence.

To conclude, we should say that this type of analysis would become important when applied to high energy cascades, which are inaccessible to MD at the present time and where nonlinear effects appear due to subcascade formation. An analysis in terms of the volume of the melt could give a qualitative interpretation for the subcascades interactions. In addition, coupling of this type of energy profiles to rate equations could be useful to estimate the amount of ion mixing.

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