# **The existence of infinitely many bifurcating branches**

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#### **Synopsis**

We consider the non-linear problem  $-\Delta u(x) - f(x, u(x)) = \lambda u(x)$  for  $x \in \mathbb{R}^N$  and  $u \in W^{1,2}(\mathbb{R}^N)$ . We show that, under suitable conditions on f, there exist infinitely many branches all bifurcating from the lowest point of the continuous spectrum  $\lambda = 0$ . The method used in the proof is based on a theorem of Ljusternik-Schnirelman type for the free case.

#### **1. Introduction**

We consider the following non-linear problem:

$$
-\Delta u(x)-f(x, u(x))=\lambda u(x) \text{ for } x\in\mathbb{R}^N.
$$

This problem has been treated by many authors including Berger, Strauss, Berestycki and Lions. In this paper we follow Stuart [4, 5].

We prove the following theorem.

THEOREM 1.1. Suppose  $f(x, u(x)) = q(x) |u(x)|^{\sigma} u(x)$  where  $q \in L^{p}(\mathbb{R}^{N})$  with  $\max$  {N/2, 2}  $\leq$  p  $\leq \infty$ ,  $0 < \sigma <$  2(2 - N/p)/(N-2), and  $q(x)$  > 0 for almost all  $x \in \mathbb{R}^N$ .

*Suppose further that there exist constants A,*  $t > 0$  *such that*  $q(x) \ge A/(1+|x|)^t$  *for almost all*  $x \in \mathbb{R}^N$  *and that*  $0 < t < 2 - N\sigma/2$ .

*Then,*

(i) for  $\lambda < 0$ , the equation

$$
-\Delta u(x) - q(x) |u(x)|^{\sigma} u(x) = \lambda u(x) \quad \text{for } x \in \mathbb{R}^{N}
$$

*has infinitely many distinct pairs of (generalised) solutions*  $\{(\lambda, \pm u_k^{\lambda})\}_{k\in\mathbb{N}}$ ;

(ii) *the lowest point of the continuous spectrum is a bifurcation point; in fact all solutions*  $(\lambda, \pm u_k^{\lambda})$  *bifurcate from*  $\lambda = 0$ :

 $||u_k^{\lambda}||_T \rightarrow 0$  *as*  $\lambda \rightarrow 0^-$ .

We prove this theorem even for more generalised non-linearities  $f(x, u(x))$  such as used by Stuart [4]. (See Conditions  $(A1^*)$ ,  $(A2^*)$ ,  $(A3^*)$  and  $(A4^*)$  below.)

The existence of an infinite number of solutions for each negative value of  $\lambda$ has been established by Berestycki and Lions [2], at least when  $f(x, u(x)) =$  $g(u(x))$ . Stuart has shown that  $\lambda = 0$  is a bifurcation point and that there exists a branch of solutions bifurcating from  $\lambda = 0$  [4, 5]. What we show is that in fact there exist infinitely many branches *all* bifurcating from the lowest point of continuous spectrum  $\lambda = 0$ .

The main tool is a generalised result of Ambrosetti and Rabinowitz  $[1,3]$ concerning the existence of an infinite number of critical points of a functional. It involves the investigation of the functional on sets of arbitrary genus and we construct such sets using functions of the following type:

$$
u(x) = p(|x|^2)e^{-|x|^2} \text{ for } x \in \mathbb{R}^N
$$
 (1.1)

where p is a polynomial. This construction seems simpler than that used previously for problems of this kind [2].

An alternative approach is discussed in Section 6.

#### **2.** The equation  $T'Tu - F(u) = \lambda u$

We consider the equation

$$
-\Delta u(x) - f(x, u(x)) = \lambda u(x), \quad x \in \mathbb{R}^N, \quad N \ge 2
$$
 (2.1)

and the corresponding bifurcation problem, but first we give a precise meaning to this equation. (This section follows Stuart [4].)

Let us begin with the operator  $-\Delta$ .

We put

$$
H: = L^{2}(\mathbb{R}^{N}) = L^{2}, \quad ||u|| := \left\{ \int u(x)^{2} dx \right\}^{\frac{1}{2}},
$$

$$
\mathcal{D}(S) := \left\{ u \in H: \sum_{i=1}^{N} D_{i}^{2} u \in H \right\}, \qquad Su := -\sum_{i=1}^{N} D_{i}^{2} u,
$$

i.e. *S* is the self-adjoint extension of the negative Laplacian in *H.* When no domain of integration is indicated, it is understood that the integration is over all of  $\mathbb{R}^N$ . Let  $(H_2, \|\|_2)$  be the Hilbert space obtained by equipping  $\mathscr{D}(S)$  with the graph norm

$$
||u||_2 := {||u||^2 + ||Su||^2}^{\frac{1}{2}}, \quad \forall \ u \in \mathcal{D}(S).
$$

Then, up to equivalence of norms,  $H_2 = W^{2,2}(\mathbb{R}^N)$ .

We now take  $T = S^{\frac{1}{2}}$ , the positive self-adjoint square root of S. Let  $(H_T, ||.||_T)$  be the Hilbert space obtained by equipping  $\mathcal{D}(T)$  with the graph norm

$$
||u||_T = {||u||^2 + ||Tu||^2}^{\frac{1}{2}}, \quad \forall \ u \in \mathcal{D}(T).
$$

Then  $H_T = W^{2,1}(\mathbb{R}^N)$  and  $||Tu|| = |||Vu||$ ,  $\forall u \in H_T$  where  $\nabla u = (D_1u, \ldots, D_Nu)$ .

By identifying *H* with  $H^*$ , we can write  $H_T \subset H = H^* \subset (H_T)^*$  and use  $\langle ., . \rangle$  for the duality between  $(H_T)^*$  and  $H_T$ . Since  $T: H_T \rightarrow H$  is bounded, it has a conjugate  $T' : H^* = H \rightarrow (H_T)^*$  which is also bounded. Then  $T'T : H_T \rightarrow (H_T)^*$  is a bounded linear operator such that  $T'Tu = Su$ ,  $\forall u \in \mathcal{D}(S)$  and  $\mathcal{D}(S) =$  $\{u \in H_T: T'Tu \in H\}.$ 

These results are discussed in more detail in [4].

We now turn to  $f$  in  $(2.1)$  and make the following basic assumption.

(A1) The function f can be written as a sum,  $f = \sum_{i=1}^{m} f_i$ , of a finite number of *functions f<sub>i</sub>* where, for  $1 \leq i \leq m$ ,  $f_i : \mathbb{R}^N \times \mathbb{R} \to \mathbb{R}$  is of Carathéodory type such

*that*

$$
|f_i(x, s)| \leq A_i(x) |s|^{1+\sigma_i}
$$

for all  $s \in \mathbb{R}$  and almost all  $x \in \mathbb{R}^N$ , where  $A_i \in L^{p_i}(\mathbb{R}^N)$  for some  $p_i$  such *that* max  $\{N/2, 2\} \leq p_i \leq \infty$  *and*  $0 < \sigma_i < 2(2 - N/p_i)/(N-2)$ .

(When  $p = \infty$ ,  $1/p$  is understood to be 0 and when  $N = 2$ ,  $1/(N-2)$  is understood to be  $+\infty$ .)

This assumption guarantees a well-posed problem (2.1) in the sense that

$$
f(x, u(x)) \in (H_T)^*
$$
 whenever  $u \in H_T$ .

In fact, if  $(A1)$  is satisfied, we set

$$
\mathscr{F}_i(x, s) := \int_0^s f_i(x, r) dr \text{ and } \mathscr{F} := \sum_{i=1}^m \mathscr{F}_i.
$$

*For u: I*<sup>N</sup>, let

$$
F_i(u)(x) := f_i(x, u(x)) \text{ and } F := \sum_{i=1}^m F_i,
$$
  

$$
\varphi_i(u) := \int \mathcal{F}_i(x, u(x)) dx \text{ and } \varphi := \sum_{i=1}^m \varphi_i.
$$

The problem (2.1) is then equivalent to

$$
Su - F(u) = \lambda u, \quad u \in H_2. \tag{2.2}
$$

The following result is also given by Stuart [4].

- PROPOSITION 2.1. Let Condition (A1) hold.
- (i) For  $1 \leq i \leq m$ ,  $F_i$  maps  $L^{\tau_i}$  boundedly and continuously to  $L^{q_i}$  where

$$
\tau_i
$$
: =  $(2 + \sigma_i)/(1 - 1/p_i)$  and  $q_i$ : =  $\tau_i/(\tau_i - 1)$ ,

and F maps  $H_T$  boundedly and continuously to  $(H_T)^*$ . Further,

$$
|\langle F_i(u),u\rangle|\leq K_i ||Tu||^{\alpha_i}||u||^{\beta_i}, \quad \forall \ u \in H_T,
$$

where  $\alpha_i$ : =  $N(\sigma_i/2+1/p_i)$ ,  $\beta_i$ : =  $2+\sigma_i-\alpha_i$  and  $K_i>0$  and so

$$
|\langle F(u), u \rangle| \leq \max_{1 \leq i \leq m} \{ mK_i ||Tu||^{\alpha_i} ||u||^{\beta_i} \}, \quad \forall u \in H_T.
$$

(ii) 1/ *in addition to Assumption* (Al) *we have*

$$
0 < \sigma_i < 2(1 - N/p_i)/(N-2) \quad \text{for} \quad 1 \leq i \leq m,
$$

then  $F_i$  maps  $L^{\tau_i}$  boundedly and continuously into H.

(iii) For  $1 \le i \le m$ ,  $\varphi : H_T \to \mathbb{R}$  is continuously Fréchet differentiable and  $\varphi'(u)v =$  $\langle F(u), v \rangle$  for all  $u, v \in H_T$ .

*Remark.* We note that  $2 < \tau_i < 2N/(N-2)$  and so  $H_T$  is continuously embedded in  $L^{\tau_i}$  for  $1 \leq i \leq m$  by the Sobolev embedding. It follows that  $L^{q_i}$  is continuously embedded in  $(H_T)^*$ .

*A* pair  $(\lambda, u)$  is now called a (generalised) solution of  $(2.2)$  if

(i)  $(\lambda, u) \in \mathbb{R} \times H_T$ 

and

(ii)  $T'Tu-F(u) = \lambda u$  holds in  $(H_T)^*$ , i.e.

 $\langle T'Tu, v \rangle - \langle F(u), v \rangle = \lambda \langle u, v \rangle$ 

for all  $v \in H_T$ .  $\lambda$  is called a  $(L^2-)$  *bifurcation point* for  $(2.2)$  if there exists a sequence  $\{(\lambda_n, u_n)\}\$  of (generalised) solutions to (2.2) such that

(i)  $u_n \neq 0$ ,  $\forall n \in \mathbb{N}$ ,

(ii)  $\lambda_n \to \lambda$  and  $||u_n||_T \to 0$  for  $n \to \infty$ .

We want to show that  $\lambda = 0$  is a bifurcation point for (2.2) and that there exist infinitely many bifurcating branches; to do this we need  $\varphi$  to be weakly sequentially continuous. This is guaranteed by the following assumption.

 $(A1^*)$  *f satisfies Condition*  $(A1)$  *and*  $A_i(x) \rightarrow 0$  *for*  $|x| \rightarrow \infty$  *whenever*  $p_i = \infty$  *and*  $f(x, s)$  *is odd with respect to s.* 

Then the following result holds.

PROPOSITION 2.2. *Let Condition* (Al\*) *hold. Then F is completely continuous and compact; more precisely*

$$
u_n \rightharpoonup u \text{ in } H_T \Rightarrow F(u_n) \to F(u) \text{ in } (H_T)^* \quad \text{for } n \to \infty.
$$

COROLLARY 2.3. Let Condition  $(A1^*)$  hold. Then  $\varphi: H_T \to \mathbb{R}$  is weakly sequen*tially continuous.*

*Proof.* This follows from the compactness of  $\varphi' = F$ . See [6, Satz 39.22].

#### **3.** The functional  $J_{\lambda}$

For  $\lambda < 0$ , we put

$$
||u||_{\lambda} = {||Tu||^2 - \lambda ||u||^2}^{\frac{1}{2}}, \quad \forall \ u \in H_T.
$$

Note that  $||\cdot||_x$  and  $||\cdot||_T$  are equivalent norms in  $H_T$ . We now define a functional  $J_{\lambda}$  whose critical points are (generalised) solutions to (2.1); critical points in turn will be found via a theorem of Ljusternik-Schnirelman type for the free case.

We put

$$
J_{\lambda}: H_{\mathcal{T}} \to \mathbb{R}, \quad u \mapsto J_{\lambda}(u) := \frac{1}{2} ||u||_{\lambda}^2 - \varphi(u).
$$

In order to control the radial behaviour of  $J_{\lambda}$ , we make the following assumption on  $f$ .

 $(A2^*)$  There exist constants  $\bar{\sigma} \geq \sigma > 0$  such that for every  $s \in \mathbb{R}$ 

$$
\mathcal{F}(x, ts) \geq t^{2+\sigma} \mathcal{F}(x, s) \geq 0 \quad \text{whenever } t \geq 1
$$

*and*

$$
\mathcal{F}(x, ts) \geq t^{2+\bar{\sigma}} \mathcal{F}(x, s) \geq 0 \quad \text{whenever } 0 \leq t \leq 1.
$$

*Further,*

$$
\varphi(u) > 0 \quad \text{for all} \quad u \in H_T \backslash \{0\}.
$$

Note that Condition  $(A2^*)$  will be satisfied if the function f is of the form

$$
f(x, s) = \sum_{i=1}^{m} q_i(x) |s|^{\sigma_i} s
$$
 (3.1)

with  $q_i(x) > 0$  for almost all  $x \in \mathbb{R}^N$  and  $\sigma_i > 0$ . (Simply take  $\sigma := \min \{\sigma_i : 1 \le i \le m\}$ ,  $\bar{\sigma}$ : = max { $\sigma_i$ : 1  $\leq i \leq m$  }.)

In order to have a quantitative control on the radial behaviour of  $J_{\lambda}$ , we introduce a second functional on  $H_T$ :

$$
I_{\lambda}: H_{T} \to \mathbb{R}, u \mapsto I_{\lambda}(u) = \begin{cases} 0 & (u = 0), \\ \frac{1}{2} || ||u||_{\lambda}^{2} - ||u||_{\lambda}^{2+\sigma} \psi(u) & (u \in H_{T}, || ||u||_{\lambda} \geq 1), \\ \frac{1}{2} || ||u||_{\lambda}^{2} - ||u||_{\lambda}^{2+\sigma} \psi(u) & (u \in H_{T}, 0 < || ||u||_{\lambda} \leq 1), \end{cases}
$$

where

$$
\psi(u):=\varphi(u/\|u\|_{\lambda}) \quad \text{for} \quad u\in H_T\backslash\{0\}.
$$

Then  $I_{\lambda}$  is a majorant functional for  $J_{\lambda}$  whose radial behaviour can be completely controlled. In fact, the following lemma follows immediately from the definition of  $I_{\lambda}$  and Condition (A2\*).

LEMMA 3.1. *Let Condition* (A2\*) *be satisfied. Then*

(i) 
$$
J_{\lambda}(u) = I_{\lambda}(u)
$$
 whenever  $|||u||_{\lambda} = 1$ .

(ii) 
$$
J_{\lambda}(u) \leq I_{\lambda}(u)
$$
 for all  $u \in H_T$ .

Let us now have a look at the radial behaviour of  $I_{\lambda}$ . For any fixed  $u \in H_T \setminus \{0\}$ , we put

$$
a:[0,\infty)\to\mathbb{R},\qquad t\mapsto a(t):=I_{\lambda}(tu),
$$

i.e.

$$
a(t) = \begin{cases} 0 & (t = 0), \\ \frac{1}{2}t^2 \|\|u\|_{\lambda}^2 - t^{2+\bar{\sigma}} \|\|u\|_{\lambda}^{2+\bar{\sigma}} \psi(u) & (0 < t \le 1/\|u\|_{\lambda}), \\ \frac{1}{2}t^2 \|\|u\|_{\lambda}^2 - t^{2+\underline{\sigma}} \|\|u\|_{\lambda}^{2+\underline{\sigma}} \psi(u) & (t \ge 1/\|u\|_{\lambda}). \end{cases}
$$

Then

$$
a'(t) = \begin{cases} 0 & (t = 0), \\ t \|\|u\|_{\lambda}^2 \{1 - (2 + \bar{\sigma})t^{\bar{\sigma}}\|\|u\|_{\lambda}^{\bar{\sigma}} \psi(u)\} & (0 < t < 1/\|u\|_{\lambda}), \\ t \|\|u\|_{\lambda}^2 \{1 - (2 + \sigma)t^{\sigma}\|\|u\|_{\lambda}^{\sigma} \psi(u)\} & (t > 1/\|u\|_{\lambda}), \end{cases}
$$

and

$$
a'_{-}(1/\|u\|_{\lambda}) = \|u\|_{\lambda} \{1 - (2 + \bar{\sigma})\psi(u)\}\
$$

$$
a'_{+}(1/\|u\|_{\lambda}) = \|u\|_{\lambda} \{1 - (2 + \sigma)\psi(u)\}\
$$

where  $a'$  and  $a'$  are the left and right derivatives. Hence a can be extremal for  $t = 1$  only if

or  
\n
$$
\|u\|_{\lambda} = \{(2+\sigma)\psi(u)\}^{-1/\sigma} > 1
$$
\n
$$
\|u\|_{\lambda} = \{(2+\sigma)\psi(u)\}^{-1/\sigma} < 1.
$$

of use, available at<https:/www.cambridge.org/core/terms>. <https://doi.org/10.1017/S0308210500020850> Downloaded from <https:/www.cambridge.org/core>. University of Basel Library, on 11 Jul 2017 at 11:54:39, subject to the Cambridge Core terms In the case where  $\sigma = \bar{\sigma} =: \sigma$ , both conditions reduce to

 $1 = (2 + \sigma) \psi(u)$  |||u|||?.

We put

$$
M_{\lambda} := M_{\lambda}^{(i)} \cup M_{\lambda}^{(ii)}
$$

where

$$
M_{\lambda}^{(i)} := \{u \in H_{\mathrm{T}} \setminus \{0\} : ||u||_{\lambda} = \{(2 + \sigma)\psi(u)\}^{-1/\sigma} > 1\},
$$
  

$$
M^{(ii)} := \{u \in H_{\mathrm{T}} \setminus \{0\} : ||u||_{\lambda} = \{(2 + \bar{\sigma})\psi(u)\}^{-1/\bar{\sigma}} < 1\}.
$$

(In the case where  $\sigma = \bar{\sigma} = \sigma$ , simply set

$$
M_{\lambda} := \{u \in H_T \setminus \{0\} : 1 = (2 + \sigma)\psi(u) ||u||_{\lambda}^{\sigma}.
$$

The two following lemmas give the central properties of these sets.

LEMMA 3.2. Let  $u \in H_T \setminus \{0\}$  be fixed. If  $I_{\lambda}(tu)$  is maximal for  $t = 1$  then  $u \in M_{\lambda}$ .

LEMMA 3.3.

- (i) If  $u \in M_{\lambda}^{(1)}$ ,
- (ii) If  $u \in M_{\lambda}^{(ii)}$ , then  $I_{\lambda}(u) = \bar{\sigma}/(4 + 2\bar{\sigma})\|\|u\|^2_{\lambda} < \bar{\sigma}/(4 + 2\bar{\sigma}).$
- (iii) If  $\bar{\sigma} = \sigma = \sigma$  and  $u \in M_{\lambda}$ , then  $I_{\lambda}(u) = \sigma/(4 + 2\sigma) \|u\|_{\lambda}^2$ .

As mentioned above, we investigate the critical points of  $J_{\lambda}$  via a theorem of Ljusternik-Schirelman type given by Ambrosetti and Rabinowitz;  $(I_1)$ - $(I_5)$  will therefore refer to conditions on  $J_{\lambda}$  given by these authors in [1]. We now show that  $J_{\lambda}$  in fact satisfies these conditions if the following assumption is made on f.

 $(A3^*)$  There exists  $q > 2$  such that for all  $s \in \mathbb{R}$  and almost all  $x \in \mathbb{R}^N$ 

$$
f(x, s)s \geq q\mathcal{F}(x, s) \geq 0.
$$

Note that f satisfies this condition if f is of the form given in  $(3.1)$ ; simply set  $q = 2 + q$ . Assumption (A3<sup>\*</sup>) means that

$$
\langle F(u), u \rangle \geq q\varphi(u) \geq 0 \quad \text{for all} \quad u \in H_T;
$$

Assumptions  $(A2^*)$  and  $(A3^*)$  together give that

$$
\langle F(u), u \rangle \ge 2\varphi(u) > 0 \quad \text{for all} \quad u \in H_T \setminus \{0\}. \tag{3.2}
$$

We now suppose that f satisfies Conditions  $(A1^*)$ ,  $(A2^*)$  and  $(A3^*)$  and show that  $J_{\lambda}$  satisfies Conditions  $(I_1)$ – $(I_5)$  in [1].

 $(I_1)$  There exists  $\rho, \alpha > 0$  such that  $J_\lambda > 0$  on  $B_\rho \setminus \{0\}$  and  $J_\lambda \ge \alpha > 0$  on  $S_\rho$  where  $B_{0}$ : = { $u \in H_{T}$ : |||u|||<sub> $\lambda$ </sub> <  $\rho$ } and  $S_{0}$ : =  $\partial B_{0}$ .

*Proof.* The proof can be found in [5]. For completeness, we just recall that, for  $u \in H_T$ ,

$$
J_{\lambda}(u) \geq \frac{1}{2} |||u|||_{\lambda}^{2} - \frac{1}{2} \sum_{i=1}^{m} K_{i} ||Tu||^{\alpha_{i}} ||u||^{\beta_{i}}
$$

by (3.2) and Proposition 2.1. Hence,

$$
J_{\lambda}(u) \geq \frac{1}{2} |||u||_{\lambda}^{2} [1 - \max_{1 \leq i \leq m} \{ mK_{i} |||u||_{\lambda}^{\alpha_{i} + \beta_{i} - 2} |\lambda|^{-\beta_{i}/2} \}]
$$

and, since  $\alpha_i + \beta_i > 2$ , the proof is complete.  $\Box$ 

 $(I_2)$  There exists  $e \in H_T \setminus \{0\}$  such that  $J_\lambda(e) = 0$ .

*Proof.* This follows immediately from  $(I_1)$  and  $(I_5)$  (see below). In fact there *Proof.* This follows immediately from  $\mathcal{L}_1$  and  $\mathcal{L}_5$  (see below). In fact there is infinitely many such elements exist infinitely many such elements. •

 $(I_3)$  *If*  $\{u_n\}$  is a sequence in  $H_T$  such that

$$
0 < J_{\lambda}(u_n) \leq \sup J_{\lambda}(u_n) < \infty
$$

*and*

$$
||J'(u_n)||_{(H_T)^*} \to 0 \quad \text{for} \quad n \to \infty,
$$

*then there exists a subsequence*  $\{u_n\}$  *such that*  $u_n$  *converges in H<sub>T</sub> to some*  $\bar{u}$ *.* 

*Proof.* For a proof see [5].

*Remark.* Condition  $(I_3)$  is the Palais–Smale condition  $(PS)^+$ .

 $(I_4)$  *J<sub>A</sub>* is even:  $J_\lambda(u) = J_\lambda(-u)$  for all  $u \in H_T$ .

*Proof.* By (A1<sup>\*</sup>),  $\varphi$  is an even functional. Therefore  $J_{\lambda}$  is also even.  $\Box$ 

 $(I<sub>5</sub>)$  *For any finite dimensional subspace Z of H<sub>T</sub>, the set*  $Z \cap \{u \in H_T: J_{\lambda}(u) \geq 0\}$  *is bounded.*

*Proof.* For a proof see [5].

#### **4. The existence of infinitely many solutions**

According to [1], we set

$$
\Gamma := \{ g \in C([0, 1], H_T) : g(0) = 0 \text{ and } g(e) = 1 \}
$$

where *e* is the element whose existence is given by  $(I_2)$ ;

 $\Gamma_* := \{ h \in C(H_T, H_T) : h(0) = 0,$ 

*h* is a homeomorphism from  $H_T$  to  $H_T$  and  $h(B) \subset \hat{A}_0$ 

where

$$
B := \{ u \in H_T : |||u||_{\lambda} < 1 \} \text{ and } \hat{A}_0 := \{ u \in H_T : J_{\lambda}(u) \ge 0 \};
$$
  

$$
\Gamma^* := \{ h \in \Gamma_* : h \text{ is odd} \};
$$

$$
\Gamma_k := \{ K \subset H_T : K \text{ is compact in } H_T, K \text{ is a symmetric set i.e. } -K = K, \gamma(K \cap h(\partial B)) \ge k, \quad \forall \ h \in \Gamma^* \quad (k \in \mathbb{N}) \}
$$

where  $\gamma$  is the genus of a set

If Conditions  $(A1^*)$ ,  $(A2^*)$  and  $(A3^*)$  are satisfied, equation  $(2.1)$  has for each  $\lambda$  < 0 infinitely many (generalised) solutions corresponding to the critical values  $b^{\lambda}$  and  $b_k^{\lambda}(k \in \mathbb{N})$ , where

(i) 
$$
b^{\lambda} := \inf_{g \in \Gamma} \max_{u \in g(0,1)} J_{\lambda}(u),
$$

(ii) 
$$
b_k^{\lambda} := \inf_{\mathbf{K} \in \Gamma_k} \max_{u \in \mathbf{K}} J_{\lambda}(u).
$$

# **5. Behaviour of the solutions as**  $\lambda \rightarrow 0^-$

We discuss the behaviour of the solutions  $u_k^{\lambda}$  to equation (2.1) which correspond to the critical values  $b_k^{\lambda}$  when  $\lambda \rightarrow 0$ . Accordingly, we make the following assumption on  $f$ :

 $(A4^*)$  There exist constants A,  $\delta$ ,  $t > 0$  such that

 $\mathcal{F}(x, s) \geq A(1+|x|)^{-t} |s|^{2+\bar{\sigma}}$ 

for all  $|s|\!<\! \delta$  and for almost all  $x\!\in\!\mathbb{R}^N$  where  $\delta$  and t satisfy the inequalities

 $0 < \delta < 1$  and  $0 < t < 2 + \sigma - \bar{\sigma} - N\bar{\sigma}/2$ .

where  $\bar{\sigma}$  and  $\sigma$  are the constants of Condition (A2<sup>\*</sup>).

Note that Condition  $(A4^*)$  is satisfied by a function f of the form  $(3.1)$  if

 $|x|$ <sup>-t</sup> for almost all  $x \in \mathbb{R}^N$   $(i = 1 \ldots m)$ .

What we want to show is that under Assumptions  $(A1^*)$ – $(A4^*)$  bifurcation will occur at the point  $\lambda = 0$ .

Let  $p(t) := \sum_{i=0}^{k-1} a_i t^i$  be a polynomial of degree  $\leq k-1$ . We often identify  $p(t)$ and  $p := (a_0, a_1, \dots, a_{k-1}) \in \mathbb{R}^k$ . The space  $\mathbb{R}^k$  will be considered to be equipped with the norm

$$
||p||_k
$$
: = max { $|a_i|$ :  $i = 0, ..., k-1$ },  $\forall p = (a_0, ..., a_{k-1}) \in \mathbb{R}^k$ ;

this norm is equivalent to the usual one

$$
\|p\| := \left\{\sum_{i=0}^{k-1} a_i^2\right\}^{\frac{1}{2}}, \qquad \forall \ p = (a_0, \ldots, a_{k-1}) \in \mathbb{R}^k.
$$

For  $p \in \mathbb{R}^k$ , we set

$$
d_p := \left\{ \int p^2 (|y|^2) e^{-2|y|^2} dy \right\}^{\frac{1}{2}},
$$
  
\n
$$
L_p := 4 \int |y|^2 [p'(|y|^2) - p(|y|^2)]^2 e^{-2|y|^2} dy,
$$
  
\n
$$
K_p := 2^{-t} A \int_{|y| \ge 1} |y|^{-t} |p(|y|^2)|^{2+\tilde{\sigma}} e^{-(2+\tilde{\sigma})|y|^2} dy.
$$

We first give some properties of  $d_p$ ,  $L_p$  and  $K_p$ .

LEMMA 5.1.  $d_p$  depends continuously on p, for all  $p \in \mathbb{R}^k$ .

*Proof.* Let

$$
p := (a_0, \dots, a_{k-1}) \in \mathbb{R}^k,
$$
  
\n
$$
\varepsilon := (\varepsilon_0, \dots, \varepsilon_{k-1}) \in \mathbb{R}^k,
$$
  
\n
$$
p + \varepsilon := (a_0 + \varepsilon_0, \dots, a_{k-1} + \varepsilon_{k-1}) \in \mathbb{R}^k.
$$

Then

$$
d_{p+\epsilon}^2 - d_p^2 = 2 \int \mathcal{E}(|y|^2) p(|y|^2) e^{-2|y|^2} dy + \int \mathcal{E}^2(|y|^2) e^{-2|y|^2} dy
$$
  

$$
= \sum_{i=0}^{2k-2} \sum_{j=0}^i \left\{ 2 \int \mathcal{E}_i a_{i-j} |y|^{2i} e^{-2|y|^2} dy \right\}
$$
  

$$
+ \int \mathcal{E}_j \mathcal{E}_{i-j} |y|^{2i} e^{-2|y|^2} dy \right\}
$$
  

$$
= \sum_{i=0}^{2k-2} \sum_{j=0}^i \mathcal{E}_j (2a_{i-j} + \mathcal{E}_{i-j}) \int |y|^{2i} e^{-2|y|^2} dy,
$$

where  $a_s = \varepsilon_s = 0$  for  $s \ge k$ . Therefore,

$$
d_{p+\epsilon}^2 - d_p^2 \to 0 \quad \text{as} \quad ||\epsilon||_k \to 0.
$$

This proves the continuity of  $d_p$ .  $\Box$ 

LEMMA 5.2. There exists a constant  $\mathcal{L} > 0$  such that

$$
0 \leq L_p \leq \mathcal{L} \|p\|_{k}^2, \quad \forall \ p \in \mathbb{R}^k.
$$

*Proof.* Let  $p = (a_0, \ldots, a_{k-1}) \in \mathbb{R}^k$ . Then

$$
0 \le L_p = 4 \int |y|^2 [p'(|y|^2) - p(|y|^2)]^2 e^{-2|y|^2} dy
$$
  
= 4 \int |y|^2 \left\{ \sum\_{i=0}^{k-1} [(i+1)a\_{i+1} - a\_i] |y|^{2i} \right\}^2 e^{-2|y|^2} dy,

where  $a_k$  is taken to be zero. Since

$$
|(i+1)a_{i+1} - a_i| \le (k+1) \max \{|a_i|: i = 0, ..., k-1\}
$$
  
=  $(k+1) ||p||_k$ ,

we have

$$
0 \le L_p \le 4(k+1)^2 \int |y|^2 \left\{ \sum_{i=0}^{k-1} |y|^{2i} \right\}^2 e^{-2|y|^2} dy \, . \, \|p\|_k^2.
$$

If we put

$$
\mathcal{L} = 4(k+1)^2 \int |y|^2 \left\{ \sum_{i=0}^{k-1} |y|^{2i} \right\}^2 e^{-2|y|^2} dy,
$$

the lemma is proved.  $\square$ 

LEMMA 5.3. (i)  $K_p$  depends continuously on p, for all  $p \in \mathbb{R}^k$ . (ii)  $K_p = 0$  if and *only if*  $p = 0$ .

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*Proof.* (i) Let  $p:=(a_0, \ldots, a_{k-1}) \in \mathbb{R}^k$ ,

$$
\varepsilon:=(\varepsilon_0,\ldots,\varepsilon_{k-1})\in\mathbb{R}^k\quad\text{with}\quad\|\varepsilon\|_k<1.
$$

Then

$$
K_{p+\varepsilon}=2^{-t}A\int_{|y|\geq 1}|y|^{-t}|(p+\varepsilon)(|y|^2)|^{2+\tilde{\sigma}}e^{-(2+\tilde{\sigma})|y|^2}dy.
$$

If one takes as dominating function

$$
y\mapsto |y|^{-t}\,|\tilde{p}(|y|^2)|^{2+\tilde{\sigma}}e^{-(2+\tilde{\sigma})|y|^2},\qquad y\in\mathbb{R}^N,
$$

where

$$
\tilde{p}(t) := \sum_{i=0}^{k-1} (|a_i|+1)t^i,
$$

the Lebesgue dominated convergence theorem gives

 $K_{p+\varepsilon}\to K_p$  as  $||\varepsilon||_k\to 0.$ 

(ii) This follows from the definition of  $K_p$ . For  $p \in \mathbb{R}^k$  and  $\lambda < 0$ , we put

 $u_{p,\lambda}(x) := p(-\lambda |x|^2) e^{\lambda |x|^2}, \qquad x$ 

and we consider the following subspace

$$
Z(k,\lambda):=\{u_{p,\lambda}(x)\colon p\in\mathbb{R}^k\}\subset H_T.
$$

By Condition  $(I_5)$ , the set

$$
Z(k,\lambda)_+:=Z(k,\lambda)\cap\{u\in H_T\colon J_\lambda(u)\geq 0\}
$$

is bounded in  $H_T$  and hence in  $Z(k, \lambda)$ . The following proposition shows that this boundedness is uniform if  $|\lambda|$  is small enough.

PROPOSITION 5.4. *Let Conditions* (A1\*)-(A4\*) *hold and put*

 $\tilde{Z}(k,\lambda) := \{u_{n,\lambda}(x) \in Z(k,\lambda): ||p||_k \leq 1\}.$ 

*Then there exists a constant*  $\lambda_0 \in [-1,0)$  *such that* 

 $Z(k, \lambda)_+ \subset \tilde{Z}(k, \lambda)$  whenever  $\lambda \in (\lambda_0, 0)$ .

*Proof.* Let  $Z := \{u_{p,\lambda}(x) \in Z(k,\lambda): ||p||_k = 1\}$ . For the majorant functional  $I_\lambda$  we show that

 $I_\lambda|_Z(u)$  < 0 whenever  $\lambda \in (\lambda_0, 0)$ .

The conclusion of the proof follows from the radial behaviour of  $I_{\lambda}$  and the connection between  $J_{\lambda}$  and  $I_{\lambda}$ .

We first remark that

$$
||u_{p,\lambda}||^2 = |\lambda|^{-N/2} d_p^2,
$$
  

$$
||Tu_{p,\lambda}||^2 = |\lambda|^{1-N/2} L_p,
$$

and

$$
||u_{p,\lambda}||_{\lambda}^{2} = |\lambda|^{1-N/2} (L_p + d_p^2)
$$
 for all  $u_{p,\lambda}(x) \in Z(k, \lambda)$ .

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These equalities can easily be verified by a direct computation. We now put

$$
y(p) := 2 \max_{x \in \mathbb{R}^N} |u_{p,\lambda}(x)|, \quad \forall \ p \in \mathbb{R}^k
$$

and

$$
y_0
$$
 := min {y(p):  $p \in \mathbb{R}^k$  with  $||p||_k = 1$  }.

Note that  $y(p)$  is always finite and depends continuously on p. Since  $y(p) > 0$ whenever  $p \neq 0$ , we thus have  $y_0>0$ . If  $\delta$  is the constant in Condition (A4\*), we have, by  $(A2^*)$ ,

$$
\varphi(u_{p,\lambda}) = \varphi\left(\frac{y(p)}{\delta} \cdot \frac{\delta}{y(p)} u_{p,\lambda}\right)
$$

$$
\geq [y(p)/\delta]^{2+\sigma} \varphi\left(\frac{\delta}{y(p)} u_{p,\lambda}\right)
$$

where

$$
\sigma = \begin{cases} \bar{\sigma} & \text{if } y(p)/\delta < 1 \\ \sigma & \text{otherwise.} \end{cases}
$$

Therefore, by  $(A4^*),$ 

$$
\varphi(u_{p,\lambda}) \ge [y(p)/\delta]^{(2+\sigma)/2+\bar{\sigma}} 2^{-t} A \int_{|x|\ge 1} |x|^{-t} |p(\lambda|x|^2)|^{2+\bar{\sigma}} e^{\lambda(2+\bar{\sigma})|x|^2} dx
$$
  

$$
\ge [y(p)/\delta]^{(2+\sigma)/(2+\bar{\sigma})} 2^{-t} A |\lambda|^{(t-N)/2} \int_{|y|\ge 1} |y|^{-t} |p(-|y|^2)^{2+\bar{\sigma}} e^{-(2+\bar{\sigma})} |y|^2 dy
$$

if  $|\lambda| \leq 1$ . Hence, for  $|\lambda| \leq 1$ ,

$$
\varphi(u_{p,\lambda}) \geq C \cdot K_p \cdot |\lambda|^{(t-N)/2}
$$

where

$$
C:=\min\{[y_0/\delta]^{(2+\sigma)/(2+\tilde{\sigma})}, y_0/\delta\}>0.
$$

If we set

$$
D := \max \{ L_p + d_p^2 : p \in \mathbb{R}^k \text{ with } ||p||_k = 1 \},
$$
  

$$
K := \min \{ K_p : p \in \mathbb{R}^k \text{ with } ||p||_k = 1 \},
$$

we have, by Lemmas 5.1, 5.2 and 5.3, that *D* and *K* are finite and positive. Hence, for  $\lambda \in [-1,0)$ ,

$$
I_{\lambda}(u_{p,\lambda}) \leq \frac{1}{2} |\lambda|^{1-N/2} (L_p + d_p^2) - C K_p |\lambda|^{(t-N)/2}
$$
  
 
$$
\leq |\lambda|^{(t-N)/2} (\frac{1}{2} |\lambda|^{1-t/2} D - C \cdot K).
$$

Therefore, there exists some  $\lambda_0 \in [-1,0)$  such that

$$
I_{\lambda}(u_{p,\lambda})<0 \quad \text{for all} \quad u_{p,\lambda}(x)\in Z
$$

where  $\lambda \in (\lambda_0, 0)$ .  $\Box$ 

*Remark.* By the proof of Lemma 2.7 in [1],

$$
\tilde{Z}(k, \lambda) \in \Gamma_k \ (k \in \mathbb{N})
$$
 for  $\lambda \in (\lambda_0, 0)$ .

of use, available at<https:/www.cambridge.org/core/terms>. <https://doi.org/10.1017/S0308210500020850> Downloaded from <https:/www.cambridge.org/core>. University of Basel Library, on 11 Jul 2017 at 11:54:39, subject to the Cambridge Core terms

PROPOSITION 5.5. Let Conditions  $(A1^*)$ - $(A4^*)$  hold and let  $\lambda_0$  be given by *Proposition* 5.4. *Then there exists a constant*  $\lambda_1 \in [\lambda_0, 0)$  *such that* 

$$
\psi(u_{p,\lambda}) \geq 2 \quad \text{for all} \quad u_{p,\lambda} \in \bar{Z}(k,\lambda) \setminus \{0\}
$$

*where*  $\lambda \in (\lambda_1, 0)$ .

*Proof.* For  $u_{n\lambda} \in \tilde{Z}(k, \lambda) \setminus \{0\}$ , we have

$$
\psi(u_{p,\lambda}) = \varphi(u_{p,\lambda}/\|u_{p,\lambda}\|_{\lambda}) \ge \|\|u_{p,\lambda}\|_{\lambda}^{-(2+\sigma)}\varphi(u_{p,\lambda})
$$

where

$$
\sigma = \begin{cases} \bar{\sigma} & \text{if } \|u_{p,\lambda}\|_{\lambda} \geq 1, \\ \sigma & \text{otherwise} \end{cases}
$$

Hence,

$$
\psi(u_{p,\lambda}) \geq {\{|\lambda|^{1-N/2}(L_p + d_p^2)\}}^{-1-\sigma/2} \cdot C_p \cdot K_p \cdot |\lambda|^{(t-N)/2}
$$

where

$$
C_p := \min \{ [y(p)/\delta]^{(2+\sigma)/(2+\tilde{\sigma})}, \qquad y(p)/\delta \}.
$$

But since

 $\psi(tu_{p,\lambda}) = \psi(u_{p,\lambda})$  for all  $t > 0$ ,

we get

$$
\psi(u_{p,\lambda}) \geq D^{-1-\sigma/2} C K |\lambda|^{n}
$$

where *C*, *D* and *K* are the same as in the proof of Proposition 5.4 and where  $\kappa$  is given by

$$
\kappa = (N/2 - 1)(1 + \sigma/2) + (t - N)/2 < -1 + N\bar{\sigma}/4 - \sigma/2 + t/2 < -\bar{\sigma}/2 < 0.
$$

So

 $\rightarrow \infty$  for  $\lambda \rightarrow 0^-$  uniformly on  $Z(k, \lambda) \setminus \{0\}$ .  $\square$ 

PROPOSITION 5.6. Let Conditions  $(A1^*)$ – $(A4^*)$  hold. Let  $u_k^{\lambda}$  be the (generalised) *solution to* (2.1) *corresponding to the critical value*  $b_k^{\lambda}(\lambda < 0, k \in \mathbb{N})$ *. Then* 

 $b^{\lambda}_{\mu} \rightarrow 0$  as  $\lambda \rightarrow 0^-$ .

*More precisely,*

$$
b_k^{\lambda} = o(\lambda) \quad \text{for} \quad \lambda \to 0^-.
$$

*Proof.* Suppose that  $q < \bar{\sigma}$ . For  $q = \bar{\sigma}$ , the proof remains the same except that  $M_{\lambda}^{(ii)}$  is replaced by  $M_{\lambda}$ . Suppose  $\lambda \in (\lambda_1, 0)$ . Then

$$
0 < b_k^{\lambda} = \inf_{K \in \Gamma_k} \max_{u \in K} J_{\lambda}(u)
$$
\n
$$
\leq \max_{u \in \tilde{Z}(k,\lambda)} I_{\lambda}(u)
$$
\n
$$
\leq \max_{u \in \tilde{Z}(k,\lambda) \cap M^{(i)}_n} I_{\lambda}(u)
$$

since  $\tilde{Z}(k, \lambda) \cap M_{\lambda}^{(i)} = \emptyset$  by Proposition 5.5. If we put

$$
t(u) := [(2+\bar{\sigma})\psi(u)]^{-1/\bar{\sigma}}(L_{p} + d_{p}^{2})^{-\frac{1}{2}}|\lambda|^{-\frac{1}{2}+N/4}
$$

of use, available at<https:/www.cambridge.org/core/terms>. <https://doi.org/10.1017/S0308210500020850> Downloaded from <https:/www.cambridge.org/core>. University of Basel Library, on 11 Jul 2017 at 11:54:39, subject to the Cambridge Core terms and

$$
Z_{\lambda} := \{u_{p,\lambda} \in Z(k,\lambda): ||p||_{k} = 1\},\
$$

then

$$
t(u_{p,\lambda})u_{p,\lambda} \in M_{\lambda}^{(ii)}
$$
 whenever  $u_{p,\lambda} \in Z_{\lambda}$ 

and so

$$
0 < b_k^{\lambda} \leq \max_{u \in Z_{\lambda}} I_{\lambda}(t(u)u)
$$
  
=  $\bar{\sigma}/(4 + 2\bar{\sigma}) \max_{u \in Z_{\lambda}} ||t(u)u||_{\lambda}^2$   
=  $\bar{\sigma}/(4 + 2\bar{\sigma}) \max_{u \in Z_{\lambda}} [(2 + \bar{\sigma})\psi(u)]^{-2/\bar{\sigma}}$   
 $\leq \text{const} |\lambda|^{-2\kappa/\bar{\sigma}}$ 

by the proof of Proposition 5.5. Since  $-2\kappa/\bar{\sigma} > 1$ , we have

 $b_k^{\lambda} = o(\lambda)$  for  $\lambda \rightarrow 0^-$ .  $\Box$ 

We are now ready to prove the main theorem.

THEOREM 5.7. Let Conditions  $(A1^*)-(A4^*)$  hold. Then (i) for  $\lambda < 0$ , equation (2.1) has infinitely many distinct pairs of (generalised) solutions  $\{(\lambda, \pm u_k^{\lambda})\}_{k\in\mathbb{N}}$ ; (ii)  $\lambda = 0$  is a bifurcation point for equation (2.1), *i.e.* 

 $\|\mu_k^{\lambda}\|_{\mathcal{T}} \to 0$  *as*  $\lambda \to 0^-$ .

*Proof,* (i) This is a result of Section 4.

(ii) Let  $u_k^{\lambda}$  be a critical point of  $J_{\lambda}$ :

$$
J_{\lambda}(u_{k}^{\lambda})=b_{k}^{\lambda}, \qquad J_{\lambda}'(u_{k}^{\lambda})=0.
$$

Therefore,

$$
\frac{d}{dt}J_{\lambda}(tu_{k}^{\lambda})|_{t=1}=0, \quad \text{i.e.} \quad ||u_{k}^{\lambda}||_{\lambda}^{2}=\langle F(u_{k}^{\lambda}), u_{k}^{\lambda}\rangle.
$$

But

$$
b_k^{\lambda} = \frac{1}{2} ||u_k^{\lambda}||_{\lambda}^2 - \varphi(u_k^{\lambda})
$$
  
=  $\frac{1}{2} \langle F(u_k^{\lambda}), u_k^{\lambda} \rangle - \varphi(u_k^{\lambda}) = o(\lambda)$  for  $\lambda \to 0$ 

and thus by  $(A3^*)$ 

$$
b_k^{\lambda} \geq (\frac{1}{2}q - 1)\varphi(u_k^{\lambda}) \geq 0 \to \varphi(u_k^{\lambda}) = o(\lambda) \quad \text{for} \quad \lambda \to 0^-.
$$

Therefore,

$$
\langle F(u_k^{\lambda}), u_k^{\lambda} \rangle = o(\lambda)
$$
 for  $\lambda \to 0^-$ ,

i.e.

$$
\|u_{k}^{\lambda}\|_{\lambda}^{2} = o(\lambda) \quad \text{for} \quad \lambda \to 0^{-}.
$$

Since  $||u||_{\lambda} \ge ||Tu||$  and  $||u||_{\lambda} \ge \sqrt{|\lambda|} ||u||$  for all  $u \in H_T$ , we have

$$
||Tu_k||^2 = o(\lambda),
$$
  
\n
$$
||u_k||^2 = o(1),
$$
  
\n
$$
||u_k||_T^2 = o(1) \text{ for } \lambda \to 0^-.
$$

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### **6. An alternative approach**

There is another approach to the problem  $(2.1)$  given by Stuart [4]. We put

$$
J(u) := \frac{1}{2} ||Tu||^2 - \varphi(u) \quad \text{for} \quad u \in H_T
$$

and

$$
M_r
$$
: = { $u \in H_T$ :  $||u|| = r$ } for  $r > 0$ .

Then critical points of  $J|_M$  are (generalised) solutions to (2.1) and it is sufficient to verify the hypotheses of Theorem 4 of [5]. The main point is to show that Assumption (S4) is satisfied for all  $i \in \mathbb{N}$  and this can be done (under the assumptions on  $f$  given below) using functions of type  $(1.1)$  and calculations similar to those of Section 5. The details will appear in [7].

Let us make the following (weaker) assumptions on  $f$ :

- $(A2)$   $\mathscr{F}(x, ts) \geq t^2 \mathscr{F}(x, s) \geq 0$  for all  $s \in \mathbb{R}$  all  $t \geq 1$  and almost all  $x \in \mathbb{R}^N$ .
- $(A3)$   $f(x, s)s \geq 2\mathcal{F}(x, s) \geq 0$  for all  $s \in \mathbb{R}$  and almost all  $x \in \mathbb{R}^N$ .
- (A4) There exist positive constants  $\sigma$ ,  $\delta$ ,  $A$  and  $t$  such that  $0 < \sigma < 2(2-t)/N$  and  $\mathscr{F}(x, s) \ge A(1 + |x|)^{-t} |s|^{2+\sigma}$  for all  $0 \le s \le \delta$  and almost all  $x \in \mathbb{R}^N$ .

THEOREM 6.1. *Let Conditions* (Al\*), (A2)-(A4) *hold. Then, for r>0 small enough, there exist infinitely many distinct pairs of (generalised) solutions*  $(\lambda_n^r, \lambda_n^r)$  $\pm u_n^r$ ) $\in \mathbb{R} \times H_T$  for equation (2.1) such that

$$
||u_n'|| = r, \qquad \lambda_n^r < 0 \qquad \text{for all } n \in \mathbb{N}.
$$
  

$$
||u_n||_{T} \to 0, \qquad \lambda_n^r \to 0^- \quad \text{as } r \to 0^+.
$$

Let us remark that the question as to whether Condition  $(A1^*)$  can be weakened remains open.

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