

The Solution of Initial-value Wave-like Models via Perturbation Iteration Transform Method

Grace O. Akinlabi, Sunday O. Edeki, *Member, IAENG*

Abstract— This work is based on the application of the new **Perturbation Iteration Transform Method (PITM)**, which is a combined form of the **Perturbation Iteration Algorithm (PIA)** and the **Laplace Transform (LT)** method on some wave-like models with constant and variable coefficients. The method provides the solution in closed form, is efficient and it involves less computational work.

Index Terms— Laplace transform method, perturbation iteration algorithm, wave-like equations

I. INTRODUCTION

Many real life problems can be mathematically modeled into Differential Equations (DEs), which comprise the Ordinary DEs (ODEs) and the Partial DEs (PDEs). A variety of methods to obtain both exact and approximate solutions of various forms of DEs have been proposed in literature. They include: Homotopy Perturbation Method (HPM), Differential Transform Method (DTM), Adomian Decomposition Method (ADM), Variational Iteration Method (VIM), modified HPM and so on [1-7].

The wave-like equation is a second-order PDE whose purpose is the description of waves. This equation has great relevance in applied Mathematics, Engineering and Physics. A lot of methods for the solution of wave-like equations have been proposed by different authors. Among them, we mention the DTM used in [8] to solve both wave-like and heat-like equations. Akinlabi and Edeki in [9] also solved some wave-like equations using the modified DTM. In [10], Keskin and Oturanc applied the reduced DTM in the solution of nonlinear wave equations.

The aim of this study is to approximate the wave-like equations using the Perturbation Iteration Transform Method (PITM), which was proposed in [11]. The PITM is the union of the Perturbation Iteration Algorithm (PIA) and the Laplace Transform (LT) method. The PIA has been studied extensively studied by several authors [12-16]. Some authors

have combined the LTM with variety of other methods and this has proven to be very effective. Examples of such approach include but not limited to: [11], [17].

The remaining parts of this study are arranged thus: in section II, we review the PIA. Section III involves the description of the PITM. In section IV, the PITM is applied to some wave-like equations to show its efficiency. Section V involves the discussion of results with the aid of graphs. The concluding remark is given in section VI.

II. PERTURBATION ITERATION ALGORITHM [11], [13]

In this section, we illustrate how the PIA works. If we derive a perturbation algorithm by taking the Taylor series of the correction terms of the first derivatives and also taking a correction term in the perturbed expansion. The perturbation algorithm will be referred to as: PIA (1, 1).

Now, considering a 2nd -order DE:

$$G(u, u', u'', \dot{u}, \ddot{u}, \varepsilon) = 0 \quad (2.1)$$

$$\text{where } u = u(x, t), \quad \ddot{u}(x, t) = \frac{\partial^2 u(x, t)}{\partial t^2}, \quad \dot{u}(x, t) = \frac{\partial u(x, t)}{\partial t},$$

$$u''(x, t) = \frac{\partial^2 u(x, t)}{\partial x^2}, \quad u'(x, t) = \frac{\partial u(x, t)}{\partial x} \text{ and } \varepsilon \text{ is the introduced}$$

perturbed parameter.

Using only a correction term in the perturbed expansion yield:

$$u_{n+1} = u_n + \varepsilon(u_c)_n. \quad (2.2)$$

Putting (2.2) into (2.1) and taking the Taylor series expansion with first derivatives gives.

$$\begin{cases} G(u', u'', \dot{u}, \ddot{u}, u, 0) + G_u(u', u'', \dot{u}, \ddot{u}, u, 0)\varepsilon(u_c)_n + \\ G_{u'}(u', u'', \dot{u}, \ddot{u}, u, 0)\varepsilon(u_c)_n + G_{u''}(u', u'', \dot{u}, \ddot{u}, u, 0)\varepsilon(u_c)_n + \\ G_{\dot{u}}(u', u'', \dot{u}, \ddot{u}, u, 0)\varepsilon(\dot{u}_c)_n + G_{\ddot{u}}(u', u'', \dot{u}, \ddot{u}, u, 0)\varepsilon(\ddot{u}_c)_n + \\ G_\varepsilon(u', u'', \dot{u}, \ddot{u}, u, 0)\varepsilon = 0 \end{cases} \quad (2.3)$$

$$\text{where } u = u(x, t), \quad G_u = \frac{\partial G}{\partial u}, \quad G_{\dot{u}} = \frac{\partial G}{\partial \dot{u}}, \quad G_{u'} = \frac{\partial G}{\partial u'}, \quad G_{u''} = \frac{\partial G}{\partial u''}$$

$$G_{\ddot{u}} = \frac{\partial G}{\partial \ddot{u}}, \quad G_\varepsilon = \frac{\partial G}{\partial \varepsilon} \text{ and } \varepsilon \text{ the perturbation parameter to be}$$

evaluated at $\varepsilon = 0$.

Reorganizing (2.3), we have

$$(\ddot{u}_c)_n + \frac{G_{u''}}{G_{\ddot{u}}}(u_c)_n + \frac{G_u}{G_{\ddot{u}}}(u_c)_n = -\frac{G_\varepsilon}{G_{\ddot{u}}}\varepsilon - \frac{G_{u'}}{G_{\ddot{u}}}(u_c)_n. \quad (2.4)$$

This is a variable coefficient linear 2nd-order DE.

The term, $(u_c)_0$ is calculated from (2.4) starting with an initial guess, u_0 and then substituted into (2.2) to evaluate u_1 . We continue the iterative process using (2.2) and (2.4)

Manuscript received December 22, 2016; revised February 01, 2017.

This work was supported in part by CUCRID: Covenant University Centre for Research, Innovation and Development.

S. O. Edeki[†] is with the Department of Mathematics, Covenant University, Ota, Nigeria. Corresponding author's E-mail Address: soedeki@yahoo.com.

G. O. Alao is with the Department of Mathematics, Covenant University, Ota, Nigeria. E-mail: grace.akinlabi@covenantuniversity.edu.ng.

until we get a satisfactory result.

III. PERTURBATION ITERATION TRANSFORM METHOD [11]

To demonstrate the basic idea of the PITM, we consider a PDE with boundary conditions of the form:

$$Au(x,t) + Bu(x,t) = c(x,t) \tag{3.1}$$

subject to the conditions:

$$u(x,0) = g(x) \text{ and } u_t(x,0) = h(x) \tag{3.2}$$

where $A = \frac{\partial^2}{\partial t^2}$, $B = \frac{\partial^2}{\partial x^2}$ are the second order linear differential operators with $c(x,t)$ as the source term.

Taking the LT of both sides of (3.1), we get

$$L[Au(x,t)] + L[Bu(x,t)] = L[c(x,t)] \tag{3.3}$$

which on using the differential property of LT, yield

$$L[Au(x,t)] = \frac{g(x)}{s} + \frac{h(x)}{s^2} + \frac{1}{s^2}L[c(x,t)] - \frac{1}{s^2}L[Bu(x,t)]. \tag{3.4}$$

Applying the inverse LT to both sides of (3.4) yield

$$u(x,t) = D(x,t) - L^{-1}\left[\frac{1}{s^2}L[Bu(x,t)]\right] \tag{3.5}$$

where $D(x,t)$ is the term obtained from the imposed initial conditions and the source term.

Now, by using the PITM (3.5) becomes:

$$u(x,t) - G(x,t) + u_c(x,t)\varepsilon + L^{-1}\left[\frac{1}{s^2}L[Bu(x,t)]\right]\varepsilon = 0 \tag{3.6}$$

Thus,

$$u_c(x,t) = \frac{G(x,t) - u(x,t)}{\varepsilon} - L^{-1}\left[\frac{1}{s^2}L[Bu(x,t)]\right]. \tag{3.7}$$

This is the combined form of the LTM and the PIA. The term, $(u_c)_0$ is then obtained from (3.7) and substituted into (2.2) for u_1 . The iterative process is repeated for u_2, u_3, \dots . The solution is thus obtained by:

$$u(x,t) = u_0(x,t) + u_1(x,t) + u_2(x,t) + u_3(x,t) + \dots \tag{3.8}$$

IV. NUMERICAL EXAMPLES

In this section, the method discussed above is applied to the following wave-like equations with both constant and variable coefficients.

First Case:

Consider the variable coefficient wave-like model:

$$u_{tt}(x,t) = \frac{x^2}{2}u_{xx}(x,t) \tag{4.1}$$

subject to:

$$u(x,0) = 1 \text{ and } u_t(x,0) = x^2 \tag{4.2}$$

Solution to First Case:

Taking the LT of both sides of (4.1) yields

$$L[u(x,t)] = \frac{1}{s} + \frac{x^2}{s^2} + \frac{1}{s^2}L\left[\frac{x^2}{2}u_{xx}(x,t)\right]. \tag{4.3}$$

Applying the Inverse LT to both sides of (4.3) gives

$$u(x,t) = 1 + x^2t + L^{-1}\left[\frac{1}{s^2}L\left[\frac{x^2}{2}u_{xx}(x,t)\right]\right]. \tag{4.4}$$

Now, by the PITM, (3.4) becomes:

$$u(x,t) - 1 - x^2t + u_c(x,t)\varepsilon - L^{-1}\left[\frac{1}{s^2}L\left[\frac{x^2}{2}u_{xx}(x,t)\right]\right]\varepsilon = 0 \tag{4.5}$$

Thus,

$$u_c(x,t) = \frac{-u(x,t) + 1 + x^2t}{\varepsilon} + L^{-1}\left[\frac{1}{s^2}L\left[\frac{x^2}{2}u_{xx}(x,t)\right]\right]. \tag{4.6}$$

This implies that:

$$u_0(x,t) = 1 + x^2t,$$

$$u_1(x,t) = \frac{x^2t^3}{3!},$$

$$u_2(x,t) = \frac{x^2t^5}{5!},$$

$$u_3(x,t) = \frac{x^2t^7}{7!},$$

⋮

Hence, the closed-form solution is:

$$\begin{aligned} u(x,t) &= u_0(x,t) + u_1(x,t) + u_2(x,t) + u_3(x,t) + \dots \\ &= 1 + x^2t + \frac{x^2t^3}{3!} + \frac{x^2t^5}{5!} + \frac{x^2t^7}{7!} + \dots \\ &= 1 + x^2 \left\{ t + \frac{t^3}{3!} + \frac{t^5}{5!} + \frac{t^7}{7!} + \dots \right\} \\ &= 1 + x^2 \sum_{\eta=0}^{\infty} \frac{t^{2\eta+1}}{(2\eta+1)!} \\ &= 1 + x^2 \text{Sinh } t. \end{aligned} \tag{4.7}$$

Second Case:

Consider the constant coefficient wave-like model:

$$u_{tt}(x,t) = u_{xx}(x,t) - 3u(x,t) \tag{4.8}$$

subject to:

$$u(x,0) = 0 \text{ and } u_t(x,0) = 2\sin x. \tag{4.9}$$

Solution to Second Case:

Taking the LT of both sides of (4.8) yields

$$L[u(x,t)] = \frac{0}{s} + \frac{2\sin x}{s^2} + \frac{1}{s^2}L[u_{xx}(x,t) - 3u(x,t)]. \tag{4.10}$$

Applying the Inverse LT to both sides of (4.10) gives

$$u(x,t) = 2t \sin x + L^{-1}\left[\frac{1}{s^2}L[u_{xx}(x,t) - 3u(x,t)]\right]. \tag{4.11}$$

Now, by the PITM (4.11) becomes:

$$\begin{aligned} u(x,t) - 2t \sin x + u_c(x,t)\varepsilon \\ - L^{-1}\left[\frac{1}{s^2}L[u_{xx}(x,t) - 3u(x,t)]\right]\varepsilon = 0. \end{aligned} \tag{4.12}$$

Thus,

$$u_c(x,t) = \frac{-u(x,t) + 2t \sin x}{\varepsilon} + L^{-1}\left[\frac{1}{s^2}L[u_{xx}(x,t) - 3u(x,t)]\right]. \tag{4.13}$$

This implies that:

$$u_0(x,t) = 2t \sin x,$$

$$u_1(x,t) = -\frac{(2t)^3 \sin x}{3!},$$

$$u_2(x,t) = \frac{(2t)^5 \sin x}{5!},$$

$$u_3(x,t) = -\frac{(2t)^7 \sin x}{7!},$$

⋮

Hence, the closed-form solution is:

$$u(x,t) = u_0(x,t) + u_1(x,t) + u_2(x,t) + u_3(x,t) + \dots$$

$$\begin{aligned}
 &= 2t \sin x - \frac{(2t)^3 \sin x}{3!} + \frac{(2t)^5 \sin x}{5!} - \frac{(2t)^7 \sin x}{7!} + \dots \\
 &= \sin x \left[2t - \frac{(2t)^3}{3!} + \frac{(2t)^5}{5!} - \frac{(2t)^7}{7!} + \dots \right] \\
 &= \left(\sum_{j=0}^{\infty} (-1)^j \frac{(x)^{2j+1}}{(2j+1)!} \right) \left(\sum_{\eta=0}^{\infty} (-1)^\eta \frac{(2t)^{2\eta+1}}{(2\eta+1)!} \right) \\
 &= \sin 2t \sin x.
 \end{aligned} \tag{4.14}$$

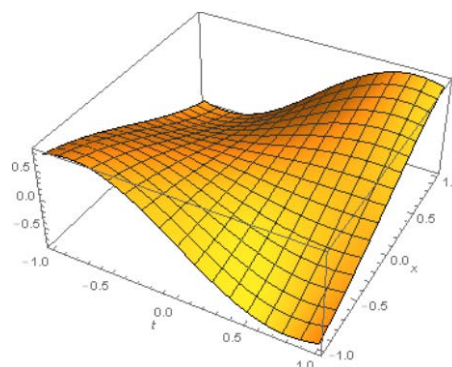


Fig. 2b: Approximate solution of second case

V. DISCUSSION OF RESULTS

In this section, graphs for the approximate and exact solutions to the problems discussed above are presented. The approximate solutions contain terms up to the seventh power.

Fig. 1a and Fig. 1b are solution graphs for first case:

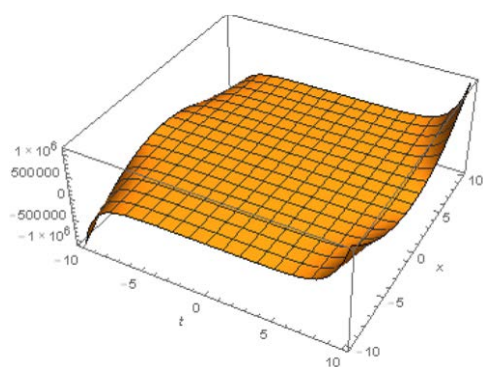


Fig. 1a: Exact solution of first case

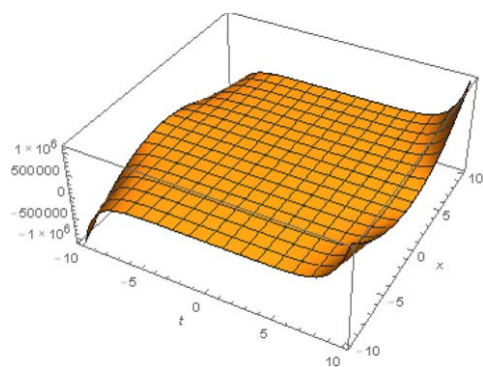


Fig. 1b: Approximate solution of first case

Fig. 2a and Fig. 2b are solution graphs for second case:

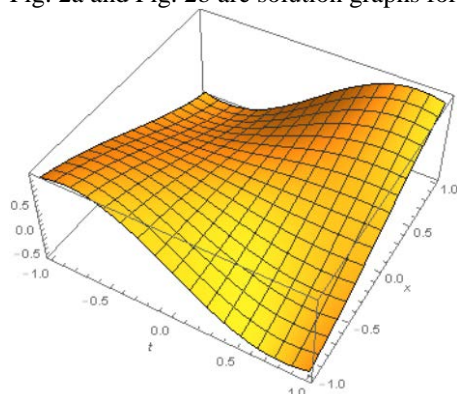


Fig. 2a: Exact solution of second case

VI. CONCLUSION

In this study, the new Perturbation Iteration Transform Method (PITM) is applied to some wave-like models with constant and variable coefficients for closed-form solutions. The results obtained when compared with their exact solutions, showed that the proposed method is efficient and simple. We therefore, propose this method for solving both linear and non-linear PDEs.

ACKNOWLEDGMENT

The authors: GOA and SOE wish to thank Covenant University (CUCRID) for the provision of good working environment and most importantly for the financial support towards this study. They also wish to appreciate the anonymous reviewers for their helpful and constructive contributions.

REFERENCES

- [1] S. O. Edeki, G. O. Akinlabi and S. A. Adeosun, "Analytic and Numerical Solutions of Time-Fractional Linear Schrödinger Equation" *Comm Math Appl*, vol. 7, no. 1, pp. 1–10, 2016.
- [2] S. Abbasbandy, "Numerical method for non-linear wave and diffusion equations by the variational iteration method", *Int. J. Numer. Meth. Engng*, vol. 73, pp. 1836-1843, 2008.
- [3] J. H. He, "Variational iteration method-a kind of non-linear analytical technique: Some examples", *International Journal of Non-Linear Mechanics*, vol. 34, no. 4, pp. 699-708, 1999.
- [4] S.O. Edeki, G.O. Akinlabi, and M.E. Adeosun, "Analytical Solutions of the Navier-Stokes Model by He's Polynomials" *Lecture Notes in Engineering and Computer Science: Proceedings of the World Congress on Engineering 2016, WCE 2016, June 29 - July 1, 2016, London, U.K.*, pp16-19.
- [5] S.O. Edeki, G.O. Akinlabi, A.O. Akeju, "A Handy Approximation Technique for Closed-form and Approximate Solutions of Time-Fractional Heat and Heat-Like Equations with Variable Coefficients", *Proceedings of the World Congress on Engineering, 2016, Vol II, WCE 2016, June 29 - July 1, London, UK*.
- [6] S. O. Edeki, G.O. Akinlabi and K. Onyenike, "Local Fractional Operator for the Solution of Quadratic Riccati Differential Equation with Constant Coefficients" *International MultiConference of Engineers and Computer Scientists, Hong Kong, 15-17 March 2017*, (Accepted-2017).
- [7] S.O. Edeki, G.O. Akinlabi, S.A. Adeosun, "On a modified transformation method for exact and approximate solutions of linear Schrödinger equations", *2015 Progress in Applied Mathematics in Science and Engineering (PIAMSE), Conference proceedings, September 29-October 1, 2015, AIP Conference Proceedings 1705, Bali, Indonesia*.

- [8] K. Tabatabaei, E. Celik and R. Tabatabaei, "The differential transform method for solving heat-like and wave-like equations with variable coefficients", *Turk. J. Phys*, vol.36, pp. 87-98, 2012
- [9] G. O. Akinlabi and S. O. Edeki, "On Approximate and Closed-form Solution Method for Initial-value Wave-like Models", *International Journal of Pure and Applied Mathematics*, vol. 107, no. 2, pp. 449–456, 2016.
- [10] Y. Keskin and G. Oturanc, "Reduced Differential Transform Method For Solving Linear And Nonlinear Wave Equations", *Iranian Journal of Science & Technology, Transaction A*, vol. 34, pp. 114-122, 2010.
- [11] M. Khalid, M. Sultana, F. Zaidi, and A. Uroosa, "Solving Linear and Nonlinear Klein-Gordon Equations by New Perturbation Iteration Transform Method", *TWMS J. App. Eng. Math*, vol. 6, no. 1, pp. 115–125, 2016.
- [12] A. H. Nayfeh, "Introduction to Perturbation Techniques", John Wiley and Sons, New York, 1981.
- [13] Y. Aksoy and M. Pakdemirli, "New Perturbation-Iteration Solutions for Bratu-type Equations", *Computers and Mathematics with Applications*, vol. 59, no. 8, pp. 2802-2808, 2010
- [14] H. Hu, "A Classical Perturbation Technique which is Valid for Large Parameters", *Journal of Sound and Vibration*, vol. 269, pp. 409–412, 2004.
- [15] M. Pakdemirli, M. M. F. Karahan and H. Boyacı, "A New Perturbation Algorithm with Better Convergence Properties: Multiple Scales Lindstedt Poincaré Method", *Mathematical and Computational Applications*, vol. 14, pp. 31–44, 2009.
- [16] V. Marinca and N. Herisanu, "A Modified Iteration Perturbation Method for some Nonlinear Oscillation Problems", *Acta Mechanica*, vol. 184, pp. 231–242, 2006.
- [17] M. Alquran, K. Al-khaled, M. Ali and A. Ta'any, "The Combined Laplace Transform-Differential Transform Method for Solving Linear Non-Homogeneous PDEs" *Journal of Mathematical and Computational Science*, vol. 2, no. 3, pp. 690-701, 2012.