ANALYSIS OF THE RELAXATION PERIOD OF A MULTIVIBRATOR

By D. C. SARKAR AND RAIS AHMED DEPARTMENT OF PHYSICS, MUSLIM UNIVERSITY, ALIGARH

(Received for publication, July 25, 1952, received after revision October 20, 1954)

ABSTRACT. An improved mathematical analysis of the relaxation periods of a free running symmetrical multivibrator has been made showing expressions for different electrode potentials and time periods. The theoretical values obtained have been compared with experimental data, part of which is also presented here.

INTRODUCTION

As a result of the many common as well as specialized applications of the multivibrator circuits and their derivatives, a large number of papers have appeared on the subject in recent years. The analyses made generally pertain either to the relaxation periods (e.g. Kiebert and Inglish, 1945) or to the switching periods between two states of passive relaxation (e.g. However, it is noticed that Williams et al, 1950; Rais Ahmed, 1950). although the voltages obtained in the relaxation period are used as boundary conditions in the switching period, it is not always possible to carry over the assumptions implicit in one analysis into the other. For example, with reference to the waveforms shown in figure 2, the maximum negative grid voltage appearing at the gril has to be computed without ignoring the positive drive of the other grid, and the voltage division between the shunting and coupling capacitances. A common relaxation analysis assuming no positive grid swing and negligible shunting capacitance will lead not only to erronecus values of the relaxation period but also to unreliable boundary conditions for the switching period, especially for high frequency multivibrators.

In the present analysis both these shortcomings of the older discussions have been removed so that the results can be safely applied to the more minute observations of the switching period.

THE ANALYSIS

 e_{σ} = positive swing of the grid voltage,

 E_{oo} = static cut-off grid voltage for supply potential E_b ,

 E_b = the plate supply potential.

 E_0 = voltage drop across the load resistance R_L when the grid voltage of the same tube is zero with coupling condenser removed,

 E_1 = voltage drop across R_L when the grid, voltage of the same tube is e_{e_1}

 C_1 and C_2 are shunting capacitances from plate to cathode and grid to cathode respectively of each tube,

 e_{gm} = maximum negative grid voltage,

 r_p = plate resistance of the tube, and

k = non-linearity factor of the tube characteristic.

With the notations indicated in figures 1 and 2, E_0 and the current through the load resistance R_L , namely i_{bo} will be :

$$i_{bo} = \frac{E_b - K}{r_p + R_L}; \quad E_o = \left(\frac{E_b - K}{r_p + R_L}\right) R_L \tag{1}$$

The voltage E_1 is greater than E_0 because of the fact that a greater current ib_1 flows through R_L when the grid of the tube is positive. The current in the tube is then

$$i_{b_1} = \frac{\mu e_c + E_b - K}{r_p + R_L}$$

$$E_1 = \left(\frac{\mu e_c + K_b - K}{r_p + R_L} - R_L\right) \qquad (2)$$

and

where μ stands for $g_m r_p$, both the latter factors having a value different from the normal value of the tube transconductance and plate resistance when taken in the region of positive grid drive. Since the difference in the value of μ is usually not more than 15% of the normal mean value, this difference may be ignored (when e_c is large μ decreases sharply). The grid voltage e_c can be found from the equivalent circuit of figure 3 which represents the conditions just at the instant when the grid voltage jumps from $-E_{co}$ to e_c , the positive value.

At the instant τ_1 (figure 2), the tube V2 begins to conduct and VI is suddenly cut off. Just before τ_1 , VI was conducting and its plate voltage was $E_b - E_o$, so that the condenser was charged to $E_b - E_o$ at the plate side of the tube VI, and to $-E_{oo}$ at the grid side of V2, because V2 just reaches cut-off at that instant, so that the condenser was charged to $(E_b - E_o + E_{oo})$ volts.

From a consideration of the total driving voltage and the potential drop in the parallel combination of r_g and R_g of figure 3, we get

$$e_{o} = \frac{\left[E_{b} - (E_{b} - E_{o} + E_{oo})\right]\tau'_{g}}{R_{L} + \tau'_{g}}$$

where τ_{ρ} = grid cathode resistance of V₂ when it is conducting

and
$$= \frac{r_g R_g}{r_g + R_g} \text{ or } e_s = \frac{(E_s - E_{so})r'_g}{R_L + r'_g} \qquad \dots \quad (3)$$

534



FIG. 2. The voltage waveform of a symmetrical multivibrator



FIG. 3. Equivalent circuit for the calculation of the positive grid drive

If E_0 is substituted in (3) from (1), we obtain

$$e_{c} = \left[\frac{\frac{R_{L}(E_{b}-K)}{r_{p}+R_{L}} - E_{c_{\theta}}}{R_{L}+r'_{g}}\right] r'_{\theta}$$

or

$$e_{\sigma} = \frac{\left[R_{L}(E_{b}-K)-(R_{L}+\tau_{P})E_{co}\right]\tau'_{\sigma}}{(R_{L}+\tau'_{\sigma})(R_{L}+\tau_{p})} \qquad \dots \qquad (4)$$

On substitution of (4) in (2), we find

$$E_{1} = \frac{R_{L} \left[\mu \left\{ \frac{R_{L} (E_{b} - K) - (R_{L} + \tau_{p}) E_{e_{1}}}{(R_{L} + \tau_{g}) R_{L} + \tau_{p}} \right\} r'_{g} + E_{b} - K \right]}{R_{L} + \tau_{p}}$$

or
$$E_{1} = \frac{R_{L} \left[\mu \tau' g \left\{ (E_{b} - K) R_{L} - (R_{I} + \tau_{p}) E_{co} \right\} + (E_{b} - K) (\tau_{p} + R_{L}) (R_{L} + \tau' g) \right]}{(R_{L} + \tau_{p})^{2} (R_{L} + \tau' g)} \dots \quad (5)$$

It is obvious that when the shunting capacitance C_2 is small compared to the coupling capacitance C_c , the voltage E_1 is also equal to e_{gm} . At higher frequencies, where C_2 is not negligible, the maximum negative grid voltage is given by

$$e_{gm} = \frac{C_c}{C_c + C_2} E_1 \qquad \dots \tag{6}$$

The above equation will give an idea of the maximum possible frequency attainable by the multivibrator. So long as $e_{gm} = \frac{C_e}{C_e + C_2} E_1 > E_{ee}$ the multivibrator will oscillate. When C_2 is so large compared with C_e that e_{gm} is less than E_{ee} , the multivibrator will stop oscillating.

Once the maximum negative grid voltage is known accurately, the period of relaxation can be calculated from the equivalent circuit of figure 4.



FTG. 4. Equivalent circuit for the calculation of relaxation time.

The equations for the circuit are :

536

$$R_{Lp} = \frac{r_p R_L}{r_p + R_L} = \frac{1}{G_1}$$
; $R_g = \frac{1}{G_2}$

at the junction Λ_{i}

$$C_{e} \frac{d(e_{1} - e_{y})}{dt} = -C_{1} \frac{de_{1}}{dt} - \frac{e_{1}}{R_{Ly}} = -C_{1} \frac{de_{1}}{dt} + \frac{e_{1}}{R_{Ly}}$$

$$C_{e} \frac{de_{1}}{dt} + C_{1} \frac{de_{1}}{dt} + \frac{e_{1}}{e_{1}} = C_{1} \frac{de_{y}}{dt}$$

or

$$C_{e} \frac{de_{1}}{dt} + C_{1} \frac{de_{1}}{dt} + \frac{e_{1}}{Re_{p}} = C_{e} \frac{de_{y}}{dt} \qquad \dots \qquad (7)$$

$$C_{e} \frac{d(e_{1} - e_{y})}{dt} = C_{2} \frac{de_{y}}{dt} + \frac{e_{y}}{R_{y}}$$

and at the junction B,

or

$$C_{e} \frac{de_{1}}{dt} = C_{e} \frac{de_{\mu}}{dt} + C_{2} \frac{dc_{g}}{dt} + \frac{c_{g}}{R_{\mu}} \qquad \dots \qquad (8)$$

Denoting d/dt by p, (7) and (8) become

or

$$C_{c}pe_{1} + C_{1}pe_{1} + c_{1}G_{1} = C_{c}pe_{y}$$

$$C_{c}pe_{1} = C_{c}pe_{y} + C_{2}pe_{y} + c_{g}G_{2}$$

$$(pC_{e} + pC_{1} + G_{1})e_{1} - pC_{c}e_{y} = 0 \qquad \dots \quad (g)$$

$$C_{c}pe_{1} - (pC_{e} + pC_{2} + G_{2})e_{g} = 0 \qquad \dots \quad (10)$$

From (9) and (10) we get
$$(pC_{e_1} + G_1)(pC_{e_2} + G_2) - p^2 C_e^2 = 0$$

where $C_{e_1} = C_e + C_1$ and $C_{e_2} = C_e + C_2$

or
$$p^2 (C_{e_1} C_{e_2} - C_e^2) + p (C_{e_1} G_2 + C_{e_1} G_1) + G_1 G_2 = 0$$
 ... (11)

so
$$p = \frac{-(C_{e_1}G_2 + C_{e_2}G_1) \pm [(C_{e_1}G_2 + C_{e_2}G_1)^2 - 4(C_{e_1}C_{e_2} - C_e^2)G_1G_2]^{1/2}}{2(C_{e_1}C_{e_2} - C_e^2)}$$

The above two values of p may be denoted by $-\alpha$ and $-\beta$. The grid voltage during the relaxation period may now be written as :

$$e_g = A e^{-\alpha t} + B e^{-\beta t} \qquad \dots \qquad (12)$$

where A and B are the constants which are to be determined by the boundary conditions that :

(i)
$$e_g = e_{gm}$$
 at $t = 0$,

and

(ii)
$$\frac{deg}{dt} = 0$$
 at $t = 0$.

Thus at t = 0

$$e_{gm} = A + B$$
$$\frac{de_g}{dt} = 0 = A\alpha + B\beta$$

The above equations give $A = \frac{-\beta e_{gm}}{\alpha - \beta}$, $B = \frac{\alpha e_{gm}}{\alpha - \beta}$ After substituting the values A and B in (12), we obtain

$$e_g = \frac{e_{gm}}{\alpha - \beta} \left[\alpha e^{-\beta t} - \beta e^{-\alpha t} \right] \qquad \dots \qquad (13)$$

By putting $e_g = E_{co}$ in this expression, the time required by the grid voltage to go from its most negative value to the tube current cut-off voltage E_{co} can be found. In this way the relaxation time is found with positive grid drive as well as shunting capacitances taken into account.

 $e_g = A_e - t / (R_{Lp} + R_s)C_s$

There are two special cases of interest.

Case 1. When
$$C_1 = C_2 = 0$$
 and $C_{o_1} = C_o = C_{o_2}$, Eqn. (11) becomes
 $pC_0(G_1 + G_2) + G_1G_2 = 0$

$$p = \frac{-G_1 G_2}{(G_1 + G_2)C_e} = \frac{-1}{(R_{Lp} + R_p)C_e}$$

or

ot

538

In this case from (6), $e_{gm} = E_o$; and at t = 0, $e_g = e_{gm} = E_o$, so that $e_g = E_o e^{-t/(RL_P + R_n)C}$.

and relaxation time =
$$\left(\frac{R_L r_p}{R_L + r_p} + R_g\right) C_e \ln \frac{E_e}{E_{eq}}$$

This is the conventional formula.

Case II. When $C_1 = 0$, $R_{Lp} = 0$; Eqn. (11) becomes

$$p(C_{e} + C_{2})R_{g} + 1 = 0$$
, or $p = \frac{-1}{(C_{e} + C_{2})R_{g}}$
 $e_{g} = Ae^{-t/(C_{e} + C_{2})R_{g}}$

when

$$t=0, \ e_g = ge_m = A = \frac{C_e}{C_r + C_2} E_1$$

or

$$e_g = \frac{C_o}{C_o + C_2} E_1 e^{-t/(C_o + C_2)R_g}$$

In this case the relaxation time = $(C_c + C_2)R_g \ln \frac{C_o}{C_c + C_2}$. $\frac{E_1}{E_{oo}}$

This is the formula given by Puckles (1951).

The practical method of calculating the relaxation time is given below.

Suppose in a particular case $C_c = 200 \text{ mmf}$, $C_1 = 50 \text{ mmf}$. $C_2 = 50 \text{ mmf}$.; $C_{o1} = C_{o2} = 250 \text{ mmf}$.; $R_L = 100 \text{ K}\Omega$; $R_g = 1 \text{ M}\Omega$; $r_P = 8 \text{ K}\Omega$; $R_{LP} = 7 \times 10^{-1}$ $= 1/G_1$; $e_{gm} = 96v$. (measured); $E_{o0} = 9.5v$.

$$C_{e_1}C_{e_2} - C_e^2 = 22.5 \times 10^{-21}$$
; $C_{e_1}G_2 + C_{e_2}G_1 = 35.96 \times 10^{-15}$;
and $G_1G_2 = 1.43 \times 10^{-10}$

Equation (11) becomes $22.5 \times 10^{-21} p^2 + 35.96 \times 10^{-13} p + 1.43 \times 10^{-10} = 0$

$$p = \frac{-35.96 \pm 35.78}{45 \times 10^{-9}}$$

or

Analysis of the Relaxation Period of a Multivibrator 539

which gives $\alpha = -4 \times 10^3$ and $\beta = -1.594 \times 10^6$

 $|\alpha| \ll |\beta|; \frac{\beta}{\alpha - \beta} e^{-\alpha t} \gg \frac{\alpha}{\alpha - \beta} e^{-\beta t} \text{ and } \frac{-\beta}{\alpha - \beta} = 1$ $= e_{\rho m}^{-\alpha t} = 96e^{-4 \times 10^{4}t};$

so

Since

Relaxation time =
$$\frac{1}{4 \times 10^3} \ln \frac{96}{9.5} = 575$$
 microseconds

The time period will be twice the relaxation time and so is 1150 microseconds. An experimental value in this case was found to be 1020 microseconds.

EXPERIMENTAL RESULTS

A double beam Cossor oscillograph was used to measure the different electrode potentials and time periods. The measurement of time was checked by means of a standard oscillator.

TABLE I $E_b = 110V$, $R_L = 100K\Omega$; $R_g = 1$ M Ω ; tube 6C5; $C_1 = 0$; $C_2 = 46$ mmf.

C, in mmf	E ₀ in volts	E_1 in volts	c _{ym} in volts	e _{gm} in volts (cal)
1000	84	94	90	90.0
500	86	.94	87	86. r
250	85	94	80	79.3
100	84	94	68	64.3
50	86	94	44	.18.9
25	86	94	30	33."

By applying formula (6) in the first observation the value of C_2 was found to be 46 mmf. This value of C_2 was used in the calculation of e_{gm} for different values of the coupling condenser.

Equation (6) was further verified by taking a fixed value of C_o and observing the variation of c_{gam} with C_2 .

TABLE II

C ₂ in mmf.	E ₁ in volts	E_0 in volts	c _{gm} in volts	e _{ym} calc
55 0	120	111	33	. 32,0
350	120	111	45	43.6
250	120	111	57	53-4
150	120	111	<u>7</u> 0	68.5
50	120	111	96 .	96.0

7-1852P-11

540 D. C. Sarkar and Rais Ahmed

The constants for this set of observations were $E_b = 150$ v., tube 6C5; $R_g = 1$ megohin., $R_L = 100$ K Ω and $C_e = 200$ mmf. The value of C_2 inherent in the circuit was estimated from the last reading when no external shunting capacitance was used, and e_{gm} was calculated on the basis of equation (6).

TABLE III	
$E_b = 150$ v., tube 6C5; $R_L = 100$ K Ω ; $R_g = 1$ megohm., $r_p = 8$ K Ω ; $C_g = 200$	mmf.
$C_1 = 50$ mmf. (assumed); τ stands for time period in microseconds.	

C ₂ in mmf.	c _{ym} in volts	<i>E</i> in volts	au obs.	τ cal
550	33	95	1750	1880
350	45	9.5	1500	1620
250	57	95	1450	1508
150	70	9.5	1200	1,280
50	96	9-5	1020	1150

TABLE	IV
-------	----

 $E_b = 1_{30}$ v.; tube 6SN7; $R_L = 20$ K Ω ; $R_g = 1$ megohun; $r_p = 8$ K Ω ; $C_2 = 80$ mmf; $C_1 = 50$ mmf (assumed); $\tau/2$ measured in microseconds = relaxation period.

C, in mmf.	E ₁ in volts	c _{gm} in volts	E in volts	τ/2 obs.	$\tau/2$ cal.
1000	92	85	8	2500	2510
500	92	8 0	8	1350	1298
250	92	68	8	550	611
100	92	56	8	340	328
50	9 0	37	8	130	137
25	90	21	8	70	86

TABLE V

 $E_b = 125 \text{ v.}$; tube 6C5; $R_g = 1$ megohm; $r'_g = 1000 \text{ ohm}$; $r_p = 10 \text{ K}\Omega$; $E_{oo} = 6 \text{ v.}$; k = 15 v.; $C_c = 500 \text{ mmf.}$; μ nearly 10.

R_L in K Ω	E ₀ obs in volts	E_0 cal. in volts	E ₁ obs, in volts	E ₁ cal in volts	e, obs.	c, cal.
100	83	100	94	109	I 5	1.5
30	70	82	92	300	30	24
10	50	55	78	77	50	4.5
5	30	36	58	54	5.0	5.1
2	18 `	18	38	28	3.0	40

Analysis of the Relaxation Period of a Multivibrator 541

CONCLUSION

It can be concluded from these tables that the set of equations derived here gives a reliable manner of calculating the relaxation period and the various electrode voltages of a multivibrator running at fairly high frequencies. These equations, therefore, can be safely taken to yield the boundary conditions for an accurate determination of the switching periods in a multivibrator.

ACKNOWLEDGMENTS

The authors are very grateful to Dr. H. Rakshit for his going through the manuscript and making valuable suggestions. They are also thankful to Professor P. S. Gill for given facilities for this work in the Department of Physics.

REFERENCES

Ahmed, Rais 1950, Ind. Jour. Phys., 24, 281. Kiebert, M. V., and Inglis A. F., 1945, Proc. I. R. E., 33, 534. M. I. T. Staff 1946, Principles of Radar, McGraw Hill Puckle, O. S., 1951, Time Bases, Chapman and Hall Williams, F. M., Aldrich, D. F., and Woodford, J. B., 1950, Proc. I. \mathcal{J} E., 38, 65.