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12th OpenFOAM<sup>®</sup> Workshop, University of Exeter 24th-27th July 2017

# A new hybrid slurry CFD model compared with experimental results

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### Outline

- Background, context and motivation to the problem
- Development of hybrid model
- PIV experiments/validation work

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# Background

- Weir group produce equipment for the mining and oil and gas industries
- Erosion is a large problem
- CFD modelling is used to predict erosion = better designs
- Longer pump life, better for customer





![](_page_3_Picture_8.jpeg)

### Ball mill video

![](_page_4_Picture_1.jpeg)

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#### Before

#### Impeller

It could be as little as 2 weeks of continuous running for this to happen

![](_page_5_Picture_4.jpeg)

![](_page_5_Picture_5.jpeg)

After

### **Problem/Motivation**

![](_page_6_Picture_1.jpeg)

- Need particle impact data at the wall for erosion modelling
- Fluid/particulate flow simulation is computationally expensive: especially for dense slurries
- Solution to make faster: Combine with two-fluid model

#### Velocity contours of submerged jet impingement test note: old asymmetric geometry pictured

![](_page_6_Picture_6.jpeg)

Dotted region where particles are necessary for impact data

## Geometry and Solvers

![](_page_7_Picture_1.jpeg)

- A simple geometry was chosen for solver development
- reactingTwoPhaseEulerFoam for Euler-Euler
- DPMFoam for Euler-Lagrange
- OpenFOAM 3.0.x was used
- Tutorial available at: <u>http://www.tfd.chalmers.se/~hani/</u> <u>kurser/OS\_CFD\_2016/</u> <u>AlasdairMackenzie/tutorial1.pdf</u>

![](_page_7_Picture_7.jpeg)

Geometry shown with sizes in metres

### **Description of Solvers**

reactingTwoPhaseEulerFoam

Euler-Euler

Two fluid model

Both phases treated as continuum

Incompressible model: setting in dictionary

Fast to solve

Transient solver for coupled transport of kinematic particle clouds

Includes the effect of volume fraction of the particles on the continuous phase

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![](_page_8_Picture_11.jpeg)

![](_page_8_Picture_12.jpeg)

Euler-Lagrange

Fluid/particle model

### Combining the solvers

![](_page_9_Picture_1.jpeg)

- A new solver was made based on the EE model
- To have 2 solvers running, we need 2 regions
- To go from fluid to particles, we need a transition
- An outlet/inlet is needed for particle phase, but shouldn't affect the rest of the flow
- Solution...

### Baffles + Regions

![](_page_10_Picture_1.jpeg)

- createBaffles: makes internal surface into boundary face
- *master* and *slave* patch created
- splitMeshRegions: Splits mesh into 2 separate regions
- BC's can now be applied to baffle patches
- chtMultiRegionFoam: Inspiration for solving regions sequentially

![](_page_10_Figure_7.jpeg)

### Interpolation

![](_page_11_Picture_1.jpeg)

- patchToPatchInterpolation: transfers data between two patches
- All variables were interpolated: U1, U2, p, p\_rgh, alpha1, alpha2, k, epsilon, nut, and theta
- After this was implemented, the domain ran as if it was one region, not two: the surface doesn't affect the flow
- 'back pressures' were taken into account by interpolating upstream

![](_page_11_Figure_6.jpeg)

#### **DPMFoam added**

![](_page_12_Picture_1.jpeg)

- Code from DPMFoam was added to new solver
- Particles injected from slave patch after back interpolation (slave to master)
- Particles are only in region1 (where erosion would take place)
- Injection values based on phase 2 from region0 by using a lookup table: kinematicLookupTableInjection

### **DPMFoam** injection

![](_page_13_Picture_1.jpeg)

```
18 /* (x y z) (u v w) d rho mDot numParcels
       where:
19
     x, y, z = global cartesian co-ordinates [m]
20
     u, v, w = global cartesian velocity components [m/s]
21
22
     d
             = diameter [m]
            = density [kg/m3]
23
     rho
          = mass flow rate [kg/m3]
24
     mDot
25
     numParcels = number of Parcels
     Dictionary for the KinematicLookupTableInjection */
26
27 (
28 (0.0005 0.01 -0.0005) (0.01417 0.01831 -0.001718) 5.5e-05 2750 0.005 -2
29 (0.0015 0.01 -0.0005) (0.06206 -0.1608 -0.001616) 5.5e-05 2750 0.005 10
30 (0.0025 0.01 -0.0005) (0.1088 -0.3422 -0.0005019) 5.5e-05 2750 0.005 19
31 (0.0035 0.01 -0.0005) (0.1497 -0.4695 -0.001312) 5.5e-05 2750 0.005 24
```

- Modified kinematicLookupTableInjection used to inject particles
- Lookup table is updated every time step
- 1 line = 1 cell
- Values for particle injection are based on new updated values so solver can deal with geometry changes etc. See Lopez' presentation for more details:

https://sourceforge.net/projects/openfoam-extend/files/OpenFOAM\_Workshops/OFW10\_2015\_AnnArbor/Presentations/Lopezpresent-OFW10-16.pdf/download

## **DPMFoam injection**

![](_page_14_Picture_1.jpeg)

```
kinematicParcelInjectionDataIOList& injectors =
    const_cast<kinematicParcelInjectionDataIOList&>
    (
        mesh.lookupObject<kinematicParcelInjectionDataIOList>("kinematicLookupTableInjection")
    );
    forAll(injectors, i)
    {
        injectors[i].x() = centres[i]; //forgot to add this when in Croatia
        injectors[i].U() = U1.boundaryField()[slave][i];
        injectors[i].numParticles() = abs((alpha1.boundaryField()[master][i]*(mag(normalSlaveVector[i]))
        *uNormal[i])/(((((pi)*pow3(injectors[i].d()))/6))*nParticle*(-1)*timestepsPerSecond));
    }
    injectors.write();
}
```

- Number of parcels to be injected is calculated from volume flow rate, number of particles/parcel and alpha distribution.
- Number of parcels/cell = (alpha particles \* area of cell \* normal velocity component to cell boundary face) / (volume of particle \* number of particles/parcel \* number of time-steps/second)

### Velocity contours

![](_page_15_Picture_1.jpeg)

![](_page_15_Picture_2.jpeg)

+ 2D slice through Z normal. Particles injected from slave patch

#### Real geometry setup

![](_page_16_Picture_1.jpeg)

![](_page_16_Figure_2.jpeg)

#### 3 sample geometries

![](_page_17_Picture_1.jpeg)

![](_page_17_Figure_2.jpeg)

DIMENSIONS IN MM

17

#### **Experimental setup**

![](_page_18_Picture_1.jpeg)

![](_page_18_Picture_2.jpeg)

![](_page_18_Figure_3.jpeg)

Particle Image Velocimetry Frame straddling used by laser ΔT=67µs DantecDynamics laser system 250 images used, 125 image pairs

Reynolds numbers of experiments and CFD are both around 10<sup>5</sup> (so are comparable)

![](_page_18_Picture_6.jpeg)

### Comparison of data

![](_page_19_Picture_1.jpeg)

![](_page_19_Picture_2.jpeg)

Lines show where data is taken from: top is 5mm from nozzle, bottom is 9.5/10mm from nozzle Interpolator is in between sample lines

![](_page_20_Picture_0.jpeg)

### Cone velocity contours

![](_page_21_Picture_1.jpeg)

![](_page_21_Figure_2.jpeg)

#### Cone

![](_page_22_Picture_1.jpeg)

#### Cone- 5mm below nozzle exit: velocity profile

![](_page_22_Figure_3.jpeg)

#### Cone

![](_page_23_Picture_1.jpeg)

#### Cone-10mm below nozzle exit: velocity profile

![](_page_23_Figure_3.jpeg)

#### Hemisphere velocity contours Glasgow

![](_page_24_Figure_1.jpeg)

#### Error in Hemisphere

![](_page_25_Figure_1.jpeg)

U.water Z is the horizontal velocity component There is almost no UZ in region0

#### Hemisphere

![](_page_26_Picture_1.jpeg)

#### **5mm below nozzle exit: velocity profile**

![](_page_26_Figure_3.jpeg)

#### Hemisphere

![](_page_27_Picture_1.jpeg)

#### 9.5mm below nozzle exit: velocity profile

![](_page_27_Figure_3.jpeg)

### Cylinder velocity contours

![](_page_28_Picture_1.jpeg)

![](_page_28_Figure_2.jpeg)

![](_page_29_Picture_0.jpeg)

![](_page_29_Picture_1.jpeg)

#### Cylinder- 5mm below nozzle exit: velocity profile

![](_page_29_Figure_3.jpeg)

![](_page_30_Picture_0.jpeg)

![](_page_30_Picture_1.jpeg)

#### Cylinder- 5mm above sample surface: velocity profile

![](_page_30_Figure_3.jpeg)

### Future work

- Get particle injections to work properly: couple injection data with injection sites...
- Validate second/particulate phase: particle tracking experiments
- Particles back to fluid?

#### Conclusion

![](_page_32_Picture_1.jpeg)

Work still in progress but...

- Fluid phase shown to work on different geometries
- Solver should dramatically reduce computational time compared to pure EL
- Particle data should still be present near walls, where required
- Enable better design of mining equipment

![](_page_32_Picture_7.jpeg)

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#### Thank you

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![](_page_33_Picture_4.jpeg)

![](_page_33_Picture_5.jpeg)

![](_page_33_Picture_6.jpeg)