



Initial Results from ACCESS: an Autonomous CubeSat Constellation Scheduling System for Earth Observation

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SmallSat Session V - Ground Systems

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Motivation

- Approach
 - EO Constellation Scheduling
 - ACCESS architecture
 - Data Routing
 - Simulation cases
- Results
 - Data Routing latency
 - Urgent Data Routing latency
 - Execution Time
- Conclusion



Earth Observing Constellations







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EO Constellation Scheduling

- STAR Lab
- Existing tools: observation and downlink scheduling
 - Planet Inc. algorithms
 - Multi-Sat Multi-GS scheduling
 - STK Scheduler
- Crosslink usage with tight-knit satellite clusters
 - Task allocation (e.g. market based)
 - Local or mesh networks



NASA Edison Demonstration of Smallsat Networks (EDSN)







- 1. Simulate a "spread-out" satellite constellation
- 2. Schedule with a centralized ground planning system
 - Key: utilize long-distance crosslinks for low-latency bulk data routing
- 3. Distribute plans to sats via ground and crosslink network
- 4. Reactive observation replanning onboard sats
 - Key: distribute updates through network



Data Routing Approach



- Optimize metric: observation latency to downlink
- Implemented a greedy algorithm
 - Downlink observations in temporal order
 - Use earliest downlink possible each time



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Payload and Link Models



High data rate EO payload

- 5 spectral bands, optical and NIR
- 127.5 Mbps compressed data
- 60 s average flyover

- X-band Downlink
 Optical Crosslink
 - -1WTx
 - 0.25U
 - 5.5 m Rx diam.
 - Adaptive data rate
 - 25-45 Mbps

- - 1 W Tx
 - 1U
 - 8.5 cm Rx diam.
 - Adaptive data rate
 - 10 Mbps @ 4,300km range





Simulation Cases



- 24h window for routing
- Set of 33 obs. targets
- 3 orbital geometries
- 3 GS networks











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- Routing Latency results
 - For first 1 Gbit of data from each observation
 - Average of latencies for all obs data packets
- Do not yet consider satellite energy constraints



Routing Latency: 10 Sat SSO

• 10 satellites in single 10:30 LTAN SSO





Better Latency: 30 Sat Walker



• 30 satellites in a 3 plane Walker Delta pattern, 60° inc.







Urgent Latency, Downlink Only

• Plot with downlinks only, 9 GS



Xlinks Reduce Urgent Latency

Plot with downlinks and crosslinks, 9 GS



Data Routing Execution Time



- Measured algorithm execution time
 - Scheduling of obs, dlinks, xlinks; data packet routing
 - Custom Python code
- For increasing constellation size
- For two planning window durations: 12 hours and 24 hours
- Run on a 2013 Macbook Pro laptop (2 GHz, 8 GB RAM)

Number of	Execution Time (mins)			
Satellites	12 Hour Window	24 Hour Window		
30	0.18	0.56		
60	0.94	2.92		
100	4.57	13.23		

Planning execution time appears tractable for scalability.





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Conclusion



- Summary of results
 - Regular latency, Walker Delta with xlnks: 23 and 17 mins
 - Urgent latency, Walker Delta with xlnks: 16 mins
 - Execution time of 13 mins for 24 h window with 100 sats
- Long range crosslinks promising for low latency bulk data delivery
- Future work
 - Algorithm improvements: energy-aware planning, data routing optimization (utilizing e.g. MILP), onboard replanning.
 - Additional metrics, sensitivity studies (particularly: crosslink range and data rate, simplex vs duplex)
 - Incorporation in operations SW stack
 - Open-sourcing



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Backup

23

and more...

The Problem: EO Data Delivery

- To effectively monitor events on Earth, we need "almost instantaneous data availability" ^{3,4}
 - 0.5 to 1 hour $^{\rm 5}$
 - Benchmark: 90min latency, Disaster Monitoring Constellation ³



Gupta, 2007²²

Constellation Crosslinks

- Inter-satellite crosslinks
 - TLM and CMD

- Bulk data routing
- Crosslinks stress operations
 - Energy usage ⁹
 - Satellite scheduling complexity
 - Constellation scheduling complexity

Crosslinks in Iridium Constellation





Imaging Payload Details



- From commercial 6U CubeSat design by Tsitas and Kingston [x21]
 - Designed to be competitive with DMC and RapidEye EO satellites
 - 600 km SSO, GSD of 6.5m and swath width of 26km
- Imager
 - Questar 3.5 telescope (89mm aperture, 20.3cm length, 1.4 kg)
 - Fairchild imaging CCD5061 (4000 pixels, 12 bit digitization)
- 5 spectral bands, 255 Mbps uncompressed
 - 2:1 lossless compression -> 127.5 Mbps

Altitude and orbit	Nadir GSD	Swath	Spectral bands	Optical MTF	Imager MTF	Digitisation	SNR
600km Sun synchronous	6·5m	>25km	440-510nm (Blue) 520-590nm (Green) 630-685nm (Red) 690-730nm (Red edge) 760-850nm (NIR)	@ 1/2 Nyquist @ Nyquist (0∙	t (0·7 field) > 7 field) > 20 @ Nyquist	12 bits - 55% % (0·7 field) ≥ 7%	154 168-4 142 117 174-6

Example Plot of Battery Level





Payload/Comm Energy Usage



Clements et al, 2016

Motivation



- What if there were a low cost way for a CubeSat to downlink 100 Gb/day?
 - Most CubeSats downlink << 10 Gb/day (UHF or S-band systems) ^[1]
- Radio frequency (RF) downlinks challenged by resource constraints
 - E.g., ground station size, transmitter power, or spectrum
- Lasercom is less resource constrained and could scale to Gbps^[3]
 - More power-efficient for given size, weight, and power (SWaP)
 - More bandwidth available
 - Many groups working on it: MIT, Aerospace
 Corporation, Sinclair, UF, DLR, JAXA, ...



Wallops CubeSat Comm. Antennas^[2]



MIT Lasercom Ground Station

NODE Space Terminal Overview



Scope	CubeSat Low-Cost Payload (<\$15k parts)	Beacon				
Architecture	Direct detection MOPA COTS telecom parts (1550 nm)	11 cm				
Downlink data rates	10 Mbps (30 cm amateur telescope) 100 Mbps (1 m OCTL)					
Power	0.2 W (transmit power), 15 W (consumed power)	Fiber Tray				
Beamwidth	1.3 mrad half power (initial demo)	(under tray)				
Modulation	РРМ	PCBs				
Coding	RS(255,239)	Fast steering mirror (FSM) M. <u>Khatsenko</u> , J. <u>Hevns</u>				
Mass, Vol.	1.0 kg, 1 U	2 ~9.6 cm ↑				
Control architecture	 Bus coarse pointing (<0.5°) FSM fine steering (+/- 2.5°) Beacon receiver (976 nm) for pointing knowledge (20 arcsec) 	Beacon receiver				
Current Status	 Pointing control testing Component-level environmental tests Functional testing End-to-end over the air demo 	COTS Collimator				





- Deployment of global planner algorithm on ground software stack (e.g. Ball Aerospace's COSMOS)
- Deployment local (satellite) planner algorithm on flight software stack (e.g. NASA Goddard's cFS)
- Incorporate more versatile observation payload and satellite operations modeling
- Open source release of ACCESS software for use by the wider small sat community.

Earth Observing Constellations

- Advantages ¹:
 - Higher temporal resolution
 - Multi-point instrument coordination
 - Low-latency data availability



TROPICS Mission, MIT LL ²

Large GS Network Deployment

- Ground Stations
 - Expensive to deploy
 - Lots of organizational/legal overhead
 - Very hard to deploy across oceans
 - For lasercomm, clouds can hinder downlink
 - For commercial networks
 - Still have to pay for usage
 - Have to worry about schedule access

Latency: Both Geometries

Combined latency plot of 10 sat SSO, 30 sat Walker











Need an automated operations approach that:



CubeSat platform

- Human-in-the-loop planning scales linearly with number of satellites [x3]
- EO Data rates of 100 MB to TB per orbit [x2,x4,x5]
- Often impossible to fully downlink all data
- Limited comm. availability
- Low energy generation, storage
- Multi-modal measurements



ACCESS Design Goals



- Efficiently manage data collection and routing to ground
 - Schedule observations, downlinks, and crosslink to balance fast downlink of key data with bulk data delivery
 - "efficient" not optimal scheduling, but close enough
 - Key advantage: crosslink routing built directly into algorithms
- Allow scalability to 100s of satellites
 - Scheduling divided based on constellation-level and satellite-level constraints
 - Sacrifices some degree of optimality in scheduling for better tractability
- Enable reactive and federated constellation operations
 - Satellites have some freedom to replan activities
 - Allows reactivity for disaster monitoring, multi-constellation cooperation
 - Key advantage: loose coupling of planning responsibility between ground and satellites

ACCESS CubeSat Ops Model

- 3 activities
 - Observation
 - Crosslink
 - Downlink







ACCESS Architecture







- Algorithms and software exist for small satellite scheduling
 - Manage activity timing and limited onboard resources
 - e.g. Planet Inc. [x8], Multi-Sat Multi-GS scheduling [x9], ASPEN/
 CASPER [x10], STK Scheduler [x6,x7]
- EO constellation management adds difficult logistics
 - Tasking satellites with observation targets [x8]
 - De-conflicting downlinks between satellites [x8,x9]
 - Maintaining schedule synchronization across constellation [x11,x12,x13,x14,x15]
- Using crosslinks as data routes add more complexity
 - At first glance, number of connections between satellites grows as N²