# Equations of Variation for Ordinary Differential Equations on Manifolds 

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## EQUATIONS OF VARIATION FOR ORDINARY DIFFERENTIAL EQUATIONS ON MANIFOLDS

For systems of ordinary differential equations in $\mathrm{R}^{\mathrm{n}}$ (real Euclidean space of dimension n ), it is well known that derivatives of solutions with respect to the initial time, initial position and parameters satisfy certain variational equations. However, for systems of ordinary differential equations on manifolds, only the variational equations for the derivatives of solutions with respect to the initial position seem to have appeared in print (Sternberg, Lectures on Differential Geometry, p. 184, 1964). In this paper, we will derive equations of variation for systems on manifolds. Our methods are different from those employed in the above reference and since no extra effort is involved, all three types will be deduced.

For definitions and properties concerning differentiable manifolds, we refer the reader to (Brickell and Clark, Differentiable Manifolds, 1970).
If $f: E_{1} \rightarrow E_{2}$ and $g: H_{1} \rightarrow H_{2}$ are maps, then $f \times g$ will denote the mapping from $E_{1} \times H_{1}$ into $E_{2} \times H_{2}$ defined by

$$
f \times g(x, y)=(f(x), g(y)) .
$$

Let M and N be $\mathrm{C}^{\infty}$ manifolds of dimensions m and n respective and denote the real numbers by R . We suppose that X is a map with domain (denoted by dom ( X )) an open subset of $\mathrm{R} \times \mathrm{M} \times \mathrm{N}$ and range a subset of the tangent bundle of M . We assume further that X is $\mathrm{C}^{\infty}$ and that if $(t, p, q)$ is in dom $(X)$, then $X(t, p, q)$ is an element of the tangent space to $M$ at $p$. Stated in a different manner, $X$ is a time dependent vector field that also depends on parameters q in N .

We consider the intial value problem
(IV)

$$
\dot{c}(t)=X(t, c(t), q), c\left(t_{0}\right)=p .
$$

For each ( $\mathrm{t}_{\mathrm{o}}, \mathrm{p}, \mathrm{q}$ ) in dom ( X ), it is known (Brickell and Clark, Differentiable Manifolds, p. 136, 1970) that the unique solution of (IV) corresponding to ( $t_{o}, p, q$ ) is defined in an open interval of $R$. We will denote the value of this solution at $t$ by $c\left(t ; t_{o}, p, q\right)$. It follows that a function may be defined with domain an open subset of $R \times R \times M \times N$ by $C\left(t, t_{0}, p, q\right)=c\left(t ; t_{0}, p, q\right)$.

Let $\left(t_{o}, p, q\right)$ be in $\operatorname{dom}(X)$ and suppose $u: U \rightarrow R^{m}$ and $v: V \rightarrow R^{n}$ are charts at $p$ and $q$ respectively. Denote identity maps by id. In each case, the domain of a particular id will be clear from the context in which it is used. We ntoe that id $\times u \times v: R \times U \times V \rightarrow R \times R^{m} \times R^{n}$ is a chart for the product manifold $\mathrm{R} \times \mathrm{M} \times \mathrm{N}$.

Assume that c:1-M is a solution of (IV) defined on an open interval I of R. Let J be the largest open interval such that $\mathrm{t}_{0}$ is in J and J is contained in $\mathrm{I} \quad \mathrm{c}^{-1}(\mathrm{U})$. Then t in J implies $(\mathrm{t}, \mathrm{c}(\mathrm{t}), \mathrm{q})$ is in $\operatorname{dom}(\mathrm{X})(\mathrm{J} \times \mathrm{U} \times \mathrm{V})$.

For each $j=1, \ldots, m$, let $u_{j}$, be the $j$ th coordinate function of $u$ and let $X\left(u_{j}\right)$ be the value of the vector field, $X, a_{j} u_{j}$. Also, define $f_{j}$, by (1) and set $f=\left(f_{1}, \ldots, f_{m}\right)$.

Arguments similar to those given in (Brickell and Clark, Differentiable Manifolds, p. 131, 1970) establish that $\mathrm{c}: \mathrm{I} \rightarrow \mathrm{M}$ is a solution of (IV) if and only if uoc, restricted to J, is a solution of
IV ')
$x^{\prime}(t)=f(t, z(t), v(q)), z\left(t_{0}\right)=u(p)$.
Denote the value of this solution at $t$ by $z\left(t ; t_{0}, u(p), v(q)\right)$. Also, for elements ( $\left.t_{o}, u(p), v(q)\right)$ in dom ( $f$ ), one may define a function $Z$ on an open subset of $R \times R \times u(U) \times v(V) C R \times R \times R^{m} \times R^{n}$ by $Z\left(t, t_{o}, u(p), v(q)\right)=z\left(t ; t_{o}, u(p), v(q)\right)$. It follows from the preceding discussion that
(2)

$$
\begin{aligned}
& \mathrm{Z}\left(\mathrm{t}, \mathrm{t}_{0}, \mathrm{u}(\mathrm{p}), \mathrm{v}(\mathrm{q})\right) \\
& =\mathrm{z}\left(; \mathrm{t}_{0}, \mathrm{u}(\mathrm{p}), \mathrm{v}(\mathrm{q})\right) \\
& \left.\left.=\mathrm{u}(\mathrm{c}) \mathrm{t} ; \mathrm{t}_{o}, \mathrm{p}, \mathrm{q}\right)\right) \\
& \left.=\mathrm{u}(\mathrm{C}), \mathrm{t}_{0}, \mathrm{q}, \mathrm{q}\right) \\
& =\left[\mathrm{uoCo}\left(\mathrm{id} \times \mathrm{id} \times \mathrm{u}^{-1} \times \mathrm{v}^{-1}\right)\right]\left(\mathrm{t}, \mathrm{t}_{\mathrm{o}}, \mathrm{u}(\mathrm{p}), \mathrm{v}(\mathrm{q})\right) .
\end{aligned}
$$

Thus, $\mathrm{Z}=\operatorname{uoCo}_{0}\left(\mathrm{idxidxu} \mathrm{xv}^{-1} \mathrm{xv}^{-1}\right.$ ), and it follows that Z is $\mathrm{C}^{\infty}$. Also, f is $\mathrm{C}^{\infty}$ because we assumed that X is $\mathrm{C}^{\infty}$.
For the purpose of writing partial derivatives, we will denote the arguments of Z by $\left(\mathrm{t}, \mathrm{t}_{0}, \xi_{,}, \eta\right)$ whre $\xi=\left(\xi_{1}, \ldots, \xi_{\mathrm{m}}\right)$ and $\eta=\left(\eta_{1}, \ldots \eta_{\mathrm{m}}\right)$. It is well known (Reid, Ordinary Differential Equations. p. 70, 1971) that the first partial derivatives of $Z$ with respect to $t_{0}, \xi_{1}$ and $\eta$, satisfy certain variational equations. In the equations that follow, it is understood that the arguments of derivatives of the $\mathrm{Z}_{1}$ are $\left(\mathrm{t}, \mathrm{t}_{\mathrm{o}}, \mathrm{u}(\mathrm{p}), \mathrm{v}(\mathrm{q})\right)$ and the arguments of derivatives of the $f_{i}$ are $\left(t, Z\left(t, t_{0}, u(p), v(q)\right), v(q)\right)$. Also, $\delta_{i k}$ denotes the Kronecker delta. The variational equations are
(V1)
(V2)

$$
\begin{aligned}
& \frac{\partial}{\partial t}\left(\frac{\partial Z_{i}}{\partial t_{o}}\right)=\sum_{j=1}^{m} \frac{\partial E_{1}}{\partial \xi_{j}} \frac{\partial z_{i}}{\partial t_{o}}, \quad \frac{\partial z_{i}}{\partial t_{o}}\left(t_{0}, t_{0}, u(p), v(q)\right)=-f_{( }\left(t_{0}, u(p), v(q)\right) ; \\
& \frac{\partial}{\partial t}\left(\frac{\partial Z_{i}}{\partial \xi_{k}}\right)=\sum_{j=1}^{m} \frac{\partial \xi_{i}}{\partial \xi_{j}} \frac{\partial Z_{j}}{\partial \xi_{k}}, \quad \frac{\partial Z_{i}}{\partial \xi_{k}}\left(t_{o}, t_{0}, u(p), v(q)\right)=\delta_{i k} ; \\
& \frac{\partial}{\partial t}\left(\frac{\partial Z_{1}}{\partial n_{k}}\right)=\sum_{j=1}^{m} \frac{\partial f_{i}}{\partial \xi_{j}} \frac{\partial Z_{i}}{\partial n_{k}}+\frac{\partial f_{i}}{\partial n_{k}} \quad, \quad \frac{\partial Z_{i}}{\partial n_{k}}\left(t_{0}, t_{0}, u(p), v(q)\right)=0
\end{aligned}
$$

(V3)

It follows from (1) and (2) that $\frac{\partial Z_{1}}{\partial t_{0}}, \frac{\partial Z_{1}}{\partial \xi_{j}}$ and $\frac{\partial Z_{1}}{\partial \eta_{k}}$ are the respective coordinate expressions for $\frac{\partial C_{1}}{\partial t_{0}}, \frac{\partial C_{i}}{\partial u_{j}}$ and $\frac{\partial C_{i}}{\partial v_{k}}$. The derivatives of the $Z_{i}$ 's are evaluated at $\left(t, t_{o}, u(p), v(q)\right)$ and the derivatives of the $C_{i}$ 's are evaluated at $\left(t, t_{o}, p, q\right)$. Also, $\frac{\partial f_{1}}{\partial \xi_{j}}$ and $\frac{\partial f_{i}}{\partial \eta_{k}}$ are coordinate expressions for $\frac{\partial X\left(u_{i}\right)}{\partial u_{j} \text { and }} \frac{\partial X\left(u_{i}\right)}{\partial v_{k} \text { res }}$ at $\left(\mathrm{t}, \mathrm{C}\left(\mathrm{t}, \mathrm{t}_{\mathrm{o}}, \mathrm{p}, \mathrm{q}\right), \mathrm{q}\right)$. Consequently, the variational equations for C may be found by substituting in ( V 1$),(\mathrm{V} 2)$ and $(\mathrm{V} 3)$. In the equations that follow,

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it is understood that the arguments of derivatives of the $C_{i}$ 's are ( $\left.t, t_{o}, p, q\right)$ and the arguments for the derivatives of the $\mathrm{X}\left(\mathrm{u}_{i}\right)$ 's are $\left(\mathrm{t}, \mathrm{C}\left(\mathrm{t}, \mathrm{t}_{o}, \mathrm{p}, \mathrm{q}\right), \mathrm{q}\right)$. The variational equations for the system on the manifold are
(VM1)
$\frac{\partial}{\partial t}\left(\frac{\partial C_{i}}{\partial t_{0}}\right)=\sum_{j=1}^{m} \frac{\partial X\left(u_{i}\right)}{\partial u_{j}} \frac{\partial C_{1}}{\partial t_{0}}$

$$
\frac{\partial \mathrm{C}_{1}}{\partial \mathrm{t}_{0}}\left(\mathrm{t}_{o}, \mathrm{t}_{0}, \mathrm{p}, \mathrm{q}\right)=\mathrm{X}(\mathrm{u})\left(\mathrm{t}_{\circ}, \mathrm{p}, \mathrm{q}\right) ;
$$

(VM2)

$$
\frac{\partial}{\partial t}\left(\frac{\partial C_{i}}{\partial u_{k}}\right)=\sum_{j=1}^{m} \frac{\partial X\left(u_{i}\right)}{\partial u_{j}} \frac{\partial C_{1}}{\partial u_{k}} .
$$

$$
\frac{\partial C_{1}}{\partial u_{k}}\left(\mathrm{t}_{0}, \mathrm{t}_{0}, \mathrm{p}, \mathrm{q}\right)=\delta_{i}
$$

(VM3)

$$
\frac{\partial}{\partial t}\left(\frac{\partial C_{1}}{\partial v_{k}}\right)=\sum_{j=1}^{m} \frac{\partial X\left(u_{1}\right)}{\partial u_{j}} \frac{\partial C_{1}}{\partial v_{k}}+\frac{\partial X\left(u_{1}\right)}{\partial v_{k}}
$$

$$
\frac{\partial \mathrm{C}_{1}}{\partial \mathrm{v}_{\mathrm{k}}}\left(\mathrm{t}_{\mathrm{o}}, \mathrm{t}_{\mathrm{o}}, \mathrm{p}, \mathrm{q}\right)=0 .
$$

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## NOTES ON THE BIOLOGY OF THYANTA CALCEATA (HEMIPTERA: PENTATOMIDAE) ON TEPHROSIA VIRGINIANA (LEGUMINOSAE), A NEW HOST PLANT

Thyanta calceata (Say) is distributed over the eastern United States from New England to Florida and west to Michigan, Illinois and Missouri (McPherson, The Pentatomoidea [Hemiptera] of northeastern North America with emphasis on the fauna of Illinois. S. Ill. Univ. Pr., Carbondale, 1982). The nymphal instars of this pentatomid have been previously described (Paskewitz and McPherson, Great Lakes Entomol. 15(4):231-255, 1982). Tephrosia virginiana (L.) ranges from Massachusetts south to Georgia, and west to Minnesota, Texas and Oklahoma (Steyermark, Flora of Missouri, Iowa St. Univ. Pr., Ames, 1975). This study presents additional information on the biology of this insect as it relates to T. virginiana, a previously unreported host plant.

McPherson (1982) reported T. calceata having been collected from soybean, red clover, blue-grass, cheat, wheat, timothy, winter cress, milkweed, horse-weed, buckbrush, Lespedeza, bean, pea, tomato, allegheny blackberry, common bromegrass, mullein, wild raspberry, goldenrod, and evening primrose. We have observed T. calceata commonly associated with T. virginiana in northeastern Arkansas on Crowley's Ridge and in northern Arkansas and southern Missouri on the Ozark Plateau.

Table 1. Occurrence of Thyanta calceata on Tephrosia virginiana, 28 April-7 August 1987.

|  | PREBLOOM |  |  | WE |  |  |  |  |  | TB |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | April |  | May |  |  |  |  |  |  | uly |  |  | August |
|  | $28 \quad 1$ | 8 | 15 | 22 | 28 | 19 | 26 | 3 | 10 | 16 | 24 | 31 | 7 |
| Adult ( $\mathrm{N}=23$ ) |  | 1 | 3 |  | 6 |  | 3 | 2 | 1 | 1 | 4 |  | 2 |
| 1st Instar ( $\mathrm{N}=0$ ) |  |  |  |  |  |  |  |  |  |  |  |  |  |
| 2nd Instar ( $\mathrm{N}=7$ ) |  | 1 | 1 |  |  | 1 | 1 |  |  |  | 1 |  | 2 |
| 3rd Instar |  |  |  |  |  |  | 2 | 1 |  |  |  |  |  |
| 4th Instar ( $\mathrm{N}=7$ ) |  |  |  | 1 |  |  | 2 | 1 |  |  | 2 |  | 1 |
| Sth Instar ( $\mathrm{N}=1$ ) |  |  |  |  |  |  | 1 |  |  |  |  |  |  |

