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# AN OMNIBUS LIKELIHOOD RATIO TEST STATISTIC AND ITS FACTORIZATION FOR CHANGE DETECTION IN TIME SERIES OF POLARIMETRIC SAR DATA

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## ABSTRACT

Based on an omnibus likelihood ratio test statistic for the equality of several variance-covariance matrices following the complex Wishart distribution with an associated $p$-value and a factorization of this test statistic, change analysis in a short sequence of multilook, polarimetric SAR data in the covariance matrix representation is carried out. The omnibus test statistic and its factorization detect if and when change(s) occur. The technique is demonstrated on airborne EMISAR L-band data but may be applied to Sentinel-1, Cosmo-SkyMed, TerraSAR-X, ALOS and RadarSat-2 or other dual- and quad/full-pol, and even single-pol data also.

## 1. INTRODUCTION

In earlier publications we have described a test statistic for the equality of two variance-covariance matrices following the complex Wishart distribution with an associated $p$-value [1]. We showed their application to bitemporal change detection and to edge detection [2] in multilook, polarimetric synthetic aperture radar (SAR) data in the covariance matrix representation. The test statistic and the associated $p$-value is described in [3] also. In [4] we focused on the block-diagonal case, we elaborated on some computer implementation issues, and we gave examples on the application to change detection in both full and dual polarization bitemporal, bifrequency, multilook SAR data.

In [5] we described an omnibus test statistic $Q$ for the equality of $k \geq 2$ variance-covariance matrices following the complex Wishart distribution. We also described a factorization of $Q = \prod_{j=2}^{k} R_j$ where $Q$ and $R_j$ determine if and when a difference occurs. Additionally, we gave $p$-values for $Q$ and $R_j$. Finally, we demonstrated the use of $Q$ and $R_j$ and the $p$-values to change detection in truly multitemporal, full polarization SAR data.

For more references to change detection in polarimetric SAR data, see [5].

The methods may be applied to other polarimetric SAR data also such as data from Sentinel-1, COSMO-SkyMed, TerraSAR-X, ALOS, and RadarSat-2 and also to single-pol data.

## 2. TEST STATISTICS AND THEIR DISTRIBUTIONS

This section gives the main results from [5]. The average covariance matrix for multilook polarimetric SAR is defined as [6]

$$\langle \boldsymbol{C} \rangle = \begin{bmatrix} \langle S_{hh}S_{hh}^* \rangle & \langle S_{hh}S_{hv}^* \rangle & \langle S_{hh}S_{vv}^* \rangle \\ \langle S_{hv}S_{hh}^* \rangle & \langle S_{hv}S_{hv}^* \rangle & \langle S_{hv}S_{vv}^* \rangle \\ \langle S_{vv}S_{hh}^* \rangle & \langle S_{vv}S_{hv}^* \rangle & \langle S_{vv}S_{vv}^* \rangle \end{bmatrix}$$

where $\langle \cdot \rangle$ denotes ensemble averaging and $^*$ denotes complex conjugation. $S_{rt}$ denotes the complex scattering amplitude for receive and transmit polarization ($r, t \in \{h, v\}$ for horizontal and vertical polarization).

### 2.1. Test for equality of several complex covariance matrices

To test whether a series of $k \geq 2$ complex variance-covariance matrices $\boldsymbol{\Sigma}_i$ are equal, i.e., to test the null hypothesis

$$H_0 : \boldsymbol{\Sigma}_1 = \boldsymbol{\Sigma}_2 = \cdots = \boldsymbol{\Sigma}_k$$

against all alternatives, we use the following omnibus test statistic (for the real case see [7]; for the case with two complex matrices see [1, 2]; $|\cdot|$ denotes the determinant)

$$Q = \left\{ k^{pk} \frac{\prod_{i=1}^{k} |\boldsymbol{X}_i|}{|\boldsymbol{X}|^k} \right\}^n.$$

Here the $\boldsymbol{\Sigma}_i$ (and the $\boldsymbol{X}_i$) are $p$ by $p$ ($p = 3$ for full pol data, $p = 2$ for dual pol data, and $p = 1$ for single channel power data), and the $\boldsymbol{X}_i = n\hat{\boldsymbol{\Sigma}}_i = n\langle \boldsymbol{C} \rangle_i$ follow the complex Wishart distribution, i.e., $\boldsymbol{X}_i \sim W_C(p, n, \boldsymbol{\Sigma}_i)$. $n$ is the equivalent number of looks. Further, $\boldsymbol{X} = \sum_{i=1}^{k} \boldsymbol{X}_i \sim W_C(p, nk, \boldsymbol{\Sigma})$. If the hypothesis is true ("under $H_0$" in statistical parlance), $\hat{\boldsymbol{\Sigma}} = \boldsymbol{X}/(kn)$. $Q \in [0, 1]$ with $Q = 1$ for equality.

**Fig. 1**. RGB images of diagonal elements of the L-band data March, April, May (top row, left to right), June, July, August (bottom row, left to right).

For the logarithm of the test statistic we get

$$\ln Q = n \left\{ pk \ln k + \sum_{i=1}^{k} \ln |\boldsymbol{X}_i| - k \ln |\boldsymbol{X}| \right\}.$$

A simple expression for the probability of finding a smaller value of $-2 \ln Q$ is ($z = -2 \ln q_{\text{obs}}$)

$$P\{-2 \ln Q \leq z\} \simeq P\{\chi^2((k-1)p^2) \leq z\}.$$

A better a approximation for $P$ can be obtained. Setting

$$f = (k-1)p^2$$

$$\rho = 1 - \frac{(2p^2-1)}{6(k-1)p} \left( \frac{k}{n} - \frac{1}{nk} \right)$$

$$\omega_2 = \frac{p^2(p^2-1)}{24\rho^2} \left( \frac{k}{n^2} - \frac{1}{(nk)^2} \right) - \frac{p^2(k-1)}{4} \left( 1 - \frac{1}{\rho} \right)^2$$

the probability of finding a smaller value of $-2\rho \ln Q$ is ($z = -2\rho \ln q_{\text{obs}}$)

$$P\{-2\rho \ln Q \leq z\} \simeq P\{\chi^2(f) \leq z\} + \omega_2[P\{\chi^2(f+4) \leq z\} - P\{\chi^2(f) \leq z\}].$$

$P\{-2\rho \ln Q \leq -2\rho \ln q_{\text{obs}}\} = P\{Q \geq q_{\text{obs}}\}$ is the change probability, $1 - P\{-2\rho \ln Q \leq -2\rho \ln q_{\text{obs}}\} = P\{Q < q_{\text{obs}}\}$ is the no-change probability.

### 2.2. Test for equality of first $j < k$ complex covariance matrices

If the above test shows that we cannot reject the hypothesis of equality, no change has occurred over the time span covered by the data. If we can reject the hypothesis, change has occurred at some time point. To test whether the first $j$ complex variance-covariance matrices $\boldsymbol{\Sigma}_i$ are equal, i.e., given that

$$\boldsymbol{\Sigma}_1 = \boldsymbol{\Sigma}_2 = \cdots = \boldsymbol{\Sigma}_{j-1}$$

then the likelihood ratio test statistic $R_j$ for testing the hypothesis

$$H_{0,j} : \boldsymbol{\Sigma}_j = \boldsymbol{\Sigma}_1 \text{ against } H_{1,j} : \boldsymbol{\Sigma}_j \neq \boldsymbol{\Sigma}_1$$

is

$$R_j = \left\{ \frac{j^{jp}}{(j-1)^{(j-1)p}} \frac{|\boldsymbol{X}_1 + \cdots + \boldsymbol{X}_{j-1}|^{(j-1)}|\boldsymbol{X}_j|}{|\boldsymbol{X}_1 + \cdots + \boldsymbol{X}_j|^j} \right\}^n$$

**Table 1**. Part of the change analysis structure for an example with data from six time points.

| | $t_1 = \cdots = t_6$ | $t_2 = \cdots = t_6$ | $t_3 = \cdots = t_6$ | $t_4 = \cdots = t_6$ | $t_5 = t_6$ |
|---|---|---|---|---|---|
| Omnibus | $Q^{(1)}$: $P\{Q^{(1)} < q_{\text{obs}}^{(1)}\}$ | $Q^{(2)}$: $P\{Q^{(2)} < q_{\text{obs}}^{(2)}\}$ | $Q^{(3)}$: $P\{Q^{(3)} < q_{\text{obs}}^{(3)}\}$ | $Q^{(4)}$: $P\{Q^{(4)} < q_{\text{obs}}^{(4)}\}$ | $Q^{(5)}$: $P\{Q^{(5)} < q_{\text{obs}}^{(5)}\}$ |
| $t_1 = t_2$ | $R_2^{(1)}$: $P\{R_2^{(1)} < z_{2,\text{obs}}^{(1)}\}$ | | | | |
| $t_2 = t_3$ | $R_3^{(1)}$: $P\{R_3^{(1)} < z_{3,\text{obs}}^{(1)}\}$ | $R_2^{(2)}$: $P\{R_2^{(2)} < z_{2,\text{obs}}^{(2)}\}$ | | | |
| $t_3 = t_4$ | $R_4^{(1)}$: $P\{R_4^{(1)} < z_{4,\text{obs}}^{(1)}\}$ | $R_3^{(2)}$: $P\{R_3^{(2)} < z_{3,\text{obs}}^{(2)}\}$ | $R_2^{(3)}$: $P\{R_2^{(3)} < z_{2,\text{obs}}^{(3)}\}$ | | |
| $t_4 = t_5$ | $R_5^{(1)}$: $P\{R_5^{(1)} < z_{5,\text{obs}}^{(1)}\}$ | $R_4^{(2)}$: $P\{R_4^{(2)} < z_{4,\text{obs}}^{(2)}\}$ | $R_3^{(3)}$: $P\{R_3^{(3)} < z_{3,\text{obs}}^{(3)}\}$ | $R_2^{(4)}$: $P\{R_2^{(4)} < z_{2,\text{obs}}^{(4)}\}$ | |
| $t_5 = t_6$ | $R_6^{(1)}$: $P\{R_6^{(1)} < z_{6,\text{obs}}^{(1)}\}$ | $R_5^{(2)}$: $P\{R_5^{(2)} < z_{5,\text{obs}}^{(2)}\}$ | $R_4^{(3)}$: $P\{R_4^{(3)} < z_{4,\text{obs}}^{(3)}\}$ | $R_3^{(4)}$: $P\{R_3^{(4)} < z_{3,\text{obs}}^{(4)}\}$ | $R_2^{(5)}$: $P\{R_2^{(5)} < z_{2,\text{obs}}^{(5)}\}$ |

**Table 2**. Average no-change probabilities for the grass field.

| | $t_1 = \cdots = t_6$ | $t_2 = \cdots = t_6$ | $t_3 = \cdots = t_6$ | $t_4 = \cdots = t_6$ | $t_5 = t_6$ |
|---|---|---|---|---|---|
| Omnibus | 0.0003 | 0.0010 | 0.0210 | 0.0653 | 0.0791 |
| $t_1 = t_2$ | 0.2753 | | | | |
| $t_2 = t_3$ | 0.0171 | 0.0784 | | | |
| $t_3 = t_4$ | 0.0341 | 0.0895 | 0.2688 | | |
| $t_4 = t_5$ | 0.0015 | 0.0048 | 0.0309 | 0.1287 | |
| $t_5 = t_6$ | 0.3565 | 0.3016 | 0.2184 | 0.1521 | 0.0791 |

or

$$\ln R_j = n\{p(j \ln j - (j-1)\ln(j-1)) + (j-1)\ln|\sum_{i=1}^{j-1} X_i| + \ln|X_j| - j\ln|\sum_{i=1}^{j} X_i|\}.$$

Furthermore, the $R_j$ constitute a factorization of $Q$

$$Q = \prod_{j=2}^{k} R_j$$

or $\ln Q = \sum_{j=2}^{k} \ln R_j$. If $H_0$ is true the $R_j$ are independent. A simple expression for the probability of finding a smaller value of $-2\ln R_j$ is ($z_j = -2\ln r_{j,\text{obs}}$)

$$P\{-2\ln R_j \leq z_j\} \simeq P\{\chi^2(p^2) \leq z_j\}.$$

A better a approximation for $P$ can be obtained. Letting

$$f = p^2$$
$$\rho_j = 1 - \frac{2p^2 - 1}{6pn}\left(1 + \frac{1}{j(j-1)}\right)$$
$$\omega_{2j} = -\frac{p^2}{4}\left(1 - \frac{1}{\rho_j}\right)^2 + \frac{1}{24n^2}p^2(p^2-1)\left(1 + \frac{2j-1}{j^2(j-1)^2}\right)\frac{1}{\rho_j^2}$$

we get ($z_j = -2\rho_j \ln r_{j,\text{obs}}$)

$$P\{-2\rho_j \ln R_j \leq z_j\} \simeq P\{\chi^2(f) \leq z_j\} + \omega_{2j}[P\{\chi^2(f+4) \leq z_j\} - P\{\chi^2(f) \leq z_j\}].$$

## 3. CHANGE VISUALIZATION EXAMPLES

To illustrate the above we use full polarimetry EMISAR [8,9] L-band data acquired in 1998 over a Danish agricultural test site on $t_1 = 21$ March, $t_2 = 17$ April, $t_3 = 20$ May, $t_4 = 16$ June, $t_5 = 15$ July, and $t_6 = 16$ August. Figure 1 shows the diagonal elements of the covariance matrix. $\langle S_{hv}S_{hv}^*\rangle$ (red) is stretched linearly between –36 dB and –6 dB, $\langle S_{hh}S_{hh}^*\rangle$ (green) between –30 dB and 0 dB and $\langle S_{vv}S_{vv}^*\rangle$ (blue) between –24 dB and 0 dB. The darker areas in the March and April images are bare surfaces corresponding to spring crops, and the very bright areas in all images are forest areas, primarily coniferous forest. The development of the crops during the growing season is clearly seen in the series of images from March to August.

Table 1 shows the change structure built (for each pixel) for an example with data from six time points. The first column indicates which tests are performed for the row in question. The second column shows $Q^{(1)}$ and $P\{Q^{(1)} < q_{\text{obs}}\}$ ("Omnibus" row), or $R_j^{(1)}$ and $P\{R_j^{(1)} < r_{j,\text{obs}}\}$, $j = 2, \ldots, 6$ for all time points $t_1$ through $t_6$. The third column shows $Q^{(2)}$ and $P\{Q^{(2)} < q_{\text{obs}}\}$ ("Omnibus" row), or $R_j^{(2)}$ and $P\{R_j^{(2)} < r_{j,\text{obs}}\}$, $j = 2, \ldots, 5$ for time points $t_2$ through $t_6$. The fourth column shows $Q^{(3)}$ and $P\{Q^{(3)} < q_{\text{obs}}\}$ ("Omnibus" row), or $R_j^{(3)}$ and $P\{R_j^{(3)} < r_{j,\text{obs}}\}$, $j = 2, \ldots, 4$ for time points $t_3$ to $t_6$, etc. Remember, that for a test for $R_j^{(\ell)}$ to be valid, all previous tests for $R_i^{(\ell)}$, $i = 2, \ldots, j-1$ must show equality, see hypothesis $H_{0,j}$ in Section 2.2.

Note, that $R_2^{(\ell)}$ are the (marginal, non-omnibus) pairwise tests for equality.

(a) $-2\rho \ln Q$



(b) $p$-value

**Fig. 2**. Test statistic (a) and $p$-value with grass field marked as black (b). Dark areas are no-change. $p$ is approximately 1 in the grass field.

### 3.1. Per pixel change visualization

As examples of per pixel change visualization, Figure 2 shows the quantity $-2\rho \ln Q$ and the corresponding $p$-value, i.e., the change probability. Figure 3 shows changes from $t_1$ to $t_2$ as blue, from $t_3$ to $t_4$ as green, and from $t_5$ to $t_6$ as red after applying a 3 by 3 mode filter. Black areas have not changed.

### 3.2. Per field change visualization

Table 2 shows the average no-change probabilities for the grass field shown in Figure 2. Table 2 shows that the pairwise tests reveal no change over time for the grass field ($p$-values are 0.2753, 0.0784, 0.2688, 0.1287 and 0.0791, respectively). The omnibus test statistic $Q$ indicates change at some time point between March and August ($P\{Q^{(1)} < q^{(1)}_{\text{obs}}\} = 0.0003$), and the $R_j$ show that the first change for this field occurs between April and May
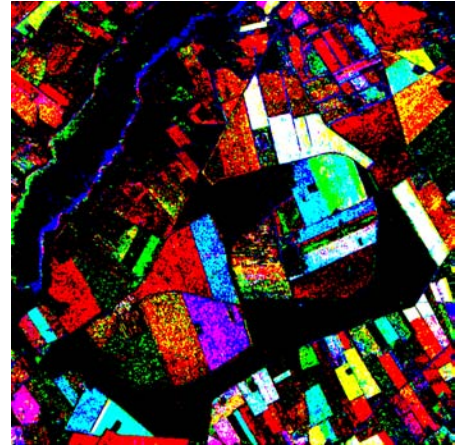


**Fig. 3**. Shows changes from $t_1$ to $t_2$ as blue, from $t_3$ to $t_4$ as green, from $t_5$ to $t_6$ as red (after application of a 3 by 3 mode filter); change probability significance level is 99.99%.

($P\{R^{(1)}_3 \leq r^{(1)}_{3,\text{obs}}\} = 0.0171$). The second and last change for this field occurs between June and July ($P\{Q^{(2)} < q^{(2)}_{\text{obs}}\} = 0.0010$ and $P\{R^{(2)}_4 \leq r^{(2)}_{4,\text{obs}}\} = 0.0048$).

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