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## DTU Compute Department of Applied Mathematics and Computer Science



# **Spectral tensor-train decomposition** for low-rank surrogate models

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#### Introduction

The construction of surrogate models is very important as a mean of acceleration in computational methods for uncertainty quantification (UQ). When the forward model is particularly expensive compared to the accuracy loss due to the use of a surrogate – as for example in computational fluid dynamics (CFD) – the latter can be used for the forward propagation of uncertainty [7] and the solution of inference problems [4].

### 40 30 20 -10<sup>10</sup> 20 30 40 50 **-**10



**Software**: http://www.compute.dtu.dk/~dabi/ **Python PyPi**: TensorToolbox

#### Problem setting

### Functional TT-decomposition Spectral TT-decomposition

We consider  $f \in L^2([a,b]^d)$ , where  $d \gg 1$  and assume f is a computationally expensive function. Let  $\boldsymbol{\xi} \in [a, b]^d$  be random variables entering the formulation of a parametric problem. In the context of UQ, we might want to:

- Compute relevant statistics
- Inquire the sensitivity of f to  $\boldsymbol{\xi}$
- Infer the distribution of  $\boldsymbol{\xi}$

In most real problems, these goals require an high number of evaluations of f. Often the construction of the surrogate and its evaluation in place of the original f provides a good payoff.

### **Tensor-train decomposition**

Let f be evaluated at all points on a tensor grid  $\mathcal{X} = \bigotimes_{j=1}^{d} \mathbf{x}_j$ , where  $\mathbf{x}_j = (x_{i_j})_{i_j=1}^{n_j}$  for  $j \in [1, d]$ . Let  $\mathcal{A} = f(\mathcal{X})$ .

**Discrete tensor-train approximation [5]** For  $r = (1, r_1, ..., r_{d-1}, 1)$ , let  $A_{TT}$  be s.t.  $\mathcal{A}(i_1,\ldots,i_d) = \mathcal{A}_{TT}(i_1,\ldots,i_d) + \mathcal{E}_{TT}(i_1,\ldots,i_d)$ 

Using the spectral theory on (non-symmetric) Hilbert-Schmidt kernels, we can construct a functional counterpart of the discrete TTapproximation.

**Functional tensor-train approximation [1]** For  $r = (1, r_1, ..., r_{d-1}, 1)$ , let  $f_{TT}$  be s.t.  $f(\mathbf{x}) = f_{TT}(\mathbf{x}) + R_{TT}(\mathbf{x})$  $f_{TT}(\mathbf{x}) = \sum \gamma_1(\alpha_0, x_1, \alpha_1) \cdots \gamma_d(\alpha_{d-1}, x_d, \alpha_d)$  $\alpha_0, \dots, \alpha_d = 1$ 

where  $\gamma_i(\alpha_{i-1}, \cdot, \alpha_i)$  are orthogonal (see [1]).

 $f_{TT}$  is constructed through the eigenvalue decomposition of Hermitian integral operators defined in terms of f. It can be proved that [1]:

• for fixed **r**,  $f_{TT}$  is optimal • if  $\frac{\partial^{\beta} f}{\partial x_{1}^{\beta_{1}} \cdots \partial x_{J}^{\beta_{d}}}$  exists and is continuous, then  $\gamma_k(\alpha_{k-1}, \cdot, \alpha_k) \in \mathcal{C}^{\beta_k}(I_k)$  for all k,  $\alpha_{k-1}$  and  $\alpha_k$ . The latter statement can be relaxed:

#### FTT-decomposition and Sobolev spaces [1]

Let  $P_{\mathbf{N}} : L^2_{\omega}(\mathbf{I}) \to \operatorname{span}\left(\{\Phi_{\mathbf{i}}\}_{\mathbf{i}=0}^{\mathbf{N}}\right)$  where  $\{\Phi_{\mathbf{i}}\}_{\mathbf{i}=0}^{\mathbf{N}}$  are orthogonal polynomials:

# **STT-Projection** $P_{\mathbf{N}}f_{TT} = \sum \hat{c}_{\mathbf{i}}\Phi_{\mathbf{i}}$ $c_{\mathbf{i}} = \sum_{i=1}^{\mathbf{i}} \beta_1(\alpha_0, i_1, \alpha_1) \dots \beta_d(\alpha_{d-1}, i_d, \alpha_d)$ $\alpha_0, \dots, \alpha_d = 1$ $\beta_n(\alpha_{n-1}, i_n, \alpha_n) = \int_{I_n} \gamma_n(\alpha_{n-1}, x_n, \alpha_n) \phi_{i_n}(x_n) dx_n$

Let  $\Pi_N : L^2_{\omega}(\mathbf{I}) \to \operatorname{span}\left(\{l_i\}_{i=0}^N\right), \{l_i\}_{i=0}^N$  being the Lagrange polynomials:

#### **STT-Interpolation**

 $\Pi_{\mathbf{N}} f_{TT} = \sum \beta_1(\alpha_0, \hat{x}_1, \alpha_1) \cdots \beta_d(\alpha_{d-1}, \hat{x}_d, \alpha_d)$  $\alpha_0, \ldots, \alpha_d = 1$  $\beta_n(\alpha_{n-1}, \hat{x}_n, \alpha_n) = L^{(n)} \gamma_n(\alpha_{n-1}, x_n, \alpha_n)$ 

where  $L^{(n)}$  is the Lagrange interpolation matrix.

# Conclusions

• Tackles the curse of dimensionality.

$$\boldsymbol{\mathcal{A}}_{TT} = \sum_{lpha_0, \dots, lpha_d = 1}^{\mathbf{r}} G_1(lpha_0, i_1, lpha_1) \dots G_d(lpha_{d-1}, i_d, lpha_d)$$

The construction can be built through the evaluation of f on the most important *fibers* (Fig. 1), detected using the TT-cross algorithm [6]. For example, let  $f(x, y) = \frac{1}{x+y+1} \sin(4\pi(x+y))$ 

Original 10.6 \*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\* 0.0 0.2 0.4 0.6 0.8 1.00.0

Figure 2: TT-cross: selection of fibers.

- Existence of low-rank best approximation
- Memory complexity: linear in d
- Computational complexity: linear in d It tackles the **curse of dimensionality**.

#### References

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Let  $\mathbf{I} \subset \mathbb{R}^d$  be closed and bounded, and  $f \in \mathcal{I}$  $L^2_{\omega}(\mathbf{I})$  be a Hölder continuous function with exponent > 1/2 such that  $f \in \mathcal{H}^k_{\omega}(\mathbf{I})$ . Then  $f_{TT}$  is such that  $\gamma_j(\alpha_{j-1}, \cdot, \alpha_j) \in \mathcal{H}^k_{\omega_j}(I_j)$  for all  $j, \alpha_{j-1}$ and  $\alpha_i$ .

#### Spectral convergence on smooth functions.

### **Ongoing works**

- Anisotropic heterogeneous adaptivity.
- Ordering problem.
- Application in the fields of coastal engineering [2, 3] and geoscience.

### **Numerical Examples**



Genz functions:

$$f_1(\mathbf{x}) = \cos\left(2\pi w_1 + \sum_{i=1}^d c_i x_i\right)$$
$$f_2(\mathbf{x}) = \left(1 + \sum_{i=1}^d c_i x_i\right)^{-(d+1)}$$

The method shows spectral convergence on both the tests, even on  $f_2$ , when there is no analytical low-rank representation.

For d = 5, we compare the non-adaptive STT-Projection

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### **Ordering problem**

TT and STT are negatively affected by the wrong ordering of the dimensions, leading to an increased computational cost and severe loss of accuracy. We propose a strategy to find a good ordering.

with the anisotropically adaptive Smolyak Sparse Grid.



We construct a vicinity matrix based on the 2nd order ranks of the tensor. We then need to solve the Traveling Salesman Problem.