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Evolution of Attacks, Threat Models and Solutions for Virtualized Systems

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Virtualization technology enables Cloud providers to efficiently use their computing services and resources. Even if the benefits in terms of performance, maintenance, and cost are evident, virtualization has also been exploited by attackers to devise new ways to compromise a system. To address these problems, research security solutions have considerably evolved over the years to cope with new attacks and threat models. In this work we review the protection strategies proposed in the literature and show how some of the solutions have been invalidated by new attacks, or threat models, that were previously not considered. The goal is to show the evolution of the threats, and of the related security and trust assumptions, in virtualized systems which have given rise to complex threat models and the corresponding sophistication of protection strategies to deal with such attacks. We also categorize threat models, security and trust assumptions, and attacks against a virtualized system at the different layers, in particular hardware, virtualization, OS, application.

Categories and Subject Descriptors: K.6.5 [Management of Computing and Information Systems]: Security and Protection - Unauthorized access

General Terms: Security, Algorithms, Measurement

Additional Key Words and Phrases: Virtualization, Threat Models, Cloud Computing, Integrity Attacks

1. INTRODUCTION

Virtualization increases the efficient use of computing services and resources in terms of their performance, maintenance, and cost, by enabling multiple environments, such as operating systems (OSes), to share the same physical resources. While its advantages are well documented [Creasy 1981] [Uhlig et al. 2005a] [Rosenblum 2004], virtualization also gives rise to several security concerns [Sahoo et al. 2010] [Garfinkel and Rosenblum 2005] [Pearce et al. 2013]. Some of these concerns are not entirely novel, whereas others, such as multi-tenancy or high-privileges of the hypervisor, are specific to virtualization and require novel solutions [Azab et al. 2010], [Szefer et al. 2011], [Zhang et al. 2011a], [Butt et al. 2012], [Xia et al. 2013], [Wu et al. 2013], [Hofmann et al. 2013].

Addressing security concerns in virtualized system requires a careful consideration of the threats; however, when the virtualized environment is "outsourced to the Cloud", i.e., run by an external provider, the trust placed in that provider (*trust assumptions*) also needs to be examined [Butt et al. 2012] [Szefer et al. 2011] [Li et al. 2013] [Santos et al. 2012]. It is important to realize that such trust assumptions, as well as other

© 2016 ACM 1539-9087/2016/01-ART46 \$15.00 DOI:http://dx.doi.org/10.1145/0000000.0000000

ACM Computing Surveys, Vol. 48, No. 3, Article 46, Publication date: January 2016.

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This work is supported by FP7 EU-funded project Coco Cloud under grant No. 610853 and EPSRC Project CIPART, grant no. EP/L022729/1.

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security assumptions, are not fixed, but change in time owing to changes in the technology, the discovery of new vulnerabilities amongst others. Threat models for virtualized systems have considerably evolved over the years, and, therefore, research solutions have also become increasingly sophisticated to cope with them [Garfinkel and Rosenblum 2003], [Bryan D. Payne and Martim Carbone and Wenke Lee 2007], [Jiang et al. 2007]. For example, early studies assumed the hypervisor of a remote host to be trusted, and used this assumption to build a trusted chain of enforcement [Keller et al. 2010], [Hofmann et al. 2011], [Azab et al. 2009], [Xiong et al. 2011]. More recent studies consider this assumption to be too strong [Wu et al. 2013] [Xia et al. 2013] [Ding et al. 2013a], especially in light of new attacks against the hypervisor that have since been discovered [Wang and Jiang 2010], [Ding et al. 2013a] and the correspondingly updated threat models.

Figure 1 shows the evolution of the threat models and of the security goals as a function of the attacks discovered and the threat assumptions. We can see that over the years threat models have evolved, from considering only attacks on the tenant OS, such as control-flow attacks [Abadi et al. 2005; Petroni and Hicks 2007], to lower-level attacks on the hypervisor, such as virtualization-based rootkits [King and Chen 2006], [Dai Zovi 2006], [Rafal Wojtczuk 2008], or cross virtual machines attacks [Kortchinsky 2009], [Xu et al. 2011]. As a consequence, the trust assumptions have also changed by reducing the size of the trusted computing base (TCB). To address new threats, with weaker assumptions, research solutions have also evolved, by firstly proposing protection models that assume a trusted monitoring application, then a trusted kernel, to solutions adding the enforcement into an administrative virtual machine. They then have further evolved by proposing solutions where only the hypervisor is trusted to, finally, solutions that protect the (untrusted) hypervisor from lower-levels. In parallel, technologies for root-of-trust have evolved to cope with these new protection needs.



Fig. 1. Evolution of Threat Models and Corresponding Solutions Over Time

This survey arises from the observation that many publications in this area have become narrower in focus and often rely on implicit, and different, assumptions. Threat models are often presented in different ways making it difficult to evaluate the efficacy of solutions: which threats do they address? and under which assumptions? Moreover, to the best of our knowledge, the evolution of threat models, attacks and research solutions for virtualized systems is not presented in the existing literature. Hence, in this survey, we categorize threat models, security and trust assumptions, and attacks against a virtualized system at the different layers: hardware, hypervisor, virtualization, OS, and application. We review protection strategies proposed in the literature and show why some of the solutions have been invalidated by new attacks, or by threat models previously not considered. We focus in particular on attacks and security solutions of the *compute* virtualization area, and do not cover all possible attacks against network and storage virtualization, as well as overall virtualization infrastructure security. We also aim to provide a first guide towards presenting in one uniform framework the threat models (security and trust assumptions), the security properties (goals and TCB) and *implementation strategies* (methodology and features) for the proposed solutions, in the hope that future papers can use a standard approach to define their assumptions and goals. Other recent surveys cover related topics and, thus, sometimes refer to the same literature, in particular:

. [Ryan 2013] surveys four generic solutions for Cloud security, i.e., homomorphic encryption, key translation, hardware-anchored security and CryptDB; it also outlines the weaknesses of each approach and discusses their applicability in real scenarios; these solutions are orthogonal to the ones discussed in this paper.

. [Bouchenak et al. 2013] survey existing studies towards verifying that Cloudbased services behave as expected. Their work focuses on verifying the identity of the service and of the nodes the service runs on, on verifying the functional correctness of a service with respect to service level agreements parameters (e.g., performance and dependability) and on the compliance of the service with security requirements as specified by a security policy. In contrast, we focus here on virtualization-based solutions to protect the integrity of software running on Cloud. [Xiao and Xiao 2013] survey studies on Cloud security and privacy, by clustering problems and solutions in five areas: *Cloud confidentiality, Cloud integrity, Cloud*

availability, *Cloud accountability* and *Cloud privacy*. In this survey we also consider the evolution of threat models, the taxonomy of attacks and protection solutions, with more emphasis on integrity and confidentiality rather than availability and accountability.

. [Pearce et al. 2013] focus on threats and solutions in virtualized scenarios. Amongst the related work, this paper is probably closest to ours. However, in contrast with this work, we provide a taxonomy of attacks and solutions by considering the level at which they apply and, furthermore, we discuss the threat models and their evolution, and the different TCB presented in the papers. Finally, we also consider attestation techniques for virtualized environments and provide a first guide towards a uniform framework for presenting threat models and protection solutions.

. [Pék et al. 2013] focus on low-level attacks on the virtualization layers and other issues introduced by such layer. We also consider higher-level issues and we discuss in detail existing solutions to cope with these attacks.

This paper is organized as follows. In Sect. 2 we introduce some key concepts of virtualization and Cloud computing. In Sect. 3 we present a taxonomy of attacks that exploit virtualization. In Sect. 4 we survey and categorize research solutions aimed at protecting virtualized environments. In Sect. 5 we discuss the threat models on virtualization resources at different levels, i.e., hardware, virtualization and Cloud. We also

propose a methodology to define, categorize and evaluate the security solutions under a common framework. In Sect. 6 we analyze the results of this survey by showing the trend of the protection solutions. In particular, we show that usually solutions only consider a specific threat model and, for this reason, they are highly sensitive to variations to that model, e.g. if an assumption is removed, or a new threat is considered, the solution is no longer valid. Finally, in Sect. 7 we conclude the paper.

2. BASICS OF VIRTUALIZATION

We start by recalling some of the key concepts of virtualization. Virtualization enables the software emulation of the physical properties of a physical computer, which is encapsulated in a Virtual Machine (VM) that can be used and managed independently from other VMs. This allows the resources of a physical computer, including processor, memory, storage and I/O channels, to be shared between several concurrent VMs, while preserving isolation. In turn, this allows for a more efficient use of the physical resources and the on-demand allocation of resources to the tenants. For example, in current virtualized environments, a new VM can be created in a matter of seconds. Usually an administrative VM (Admin VM^{1}) takes care of configuring and initializing the VMs. The replacement of a physical system with a VM is, in theory, transparent to the applications and to the OS, which can run unchanged. The tenants' applications can therefore run in a VM, exactly as they do on a physical architecture. A virtual machine monitor (VMM) [Goldberg 1973] [Goldberg 1974] is the software component that creates, manages and monitors VM, and can be of two types: (i) a type I VMM², which is a thin software layer that runs on top of the hardware/firmware layer; (ii) a type II VMM, which runs on top of a *host OS* and implements each tenant VM as a guest OS process that emulates a physical architecture. VMs allow distinct OSes and applications in them to run concurrently. From a security point of view, the VMM must guarantee the isolation of the VMs to ensure that any erroneous or malicious behavior within a VM is confined within it. This isolation is fundamental, and must be ensured even for processes running with administrative permissions within a VM and requires mediating each access from a VM to shared resources.

2.1. Cloud Computing

Virtualization is the key foundation for realising *Cloud computing* – a form of computing similar in several respects to *utility computing* [Rappa 2004] – in which services, including storage, computation and applications, are provided by large pools of remote resources. We recall the major service models of Cloud computing, which are known as [Mell and Grance 2011]: (i) *software-as-a-service* (SaaS), where tenants are provided with the capability to use the provider's applications but do not manage or control the infrastructure; (ii) *platform-as-a-service* (PaaS), where tenants can deploy onto the Cloud infrastructure consumer-created or acquired applications created using programming languages and tools supported by the provider. In PaaS the consumer has control only over the deployed applications and possibly their hosting configurations; and (iii) *infrastructure-as-a-service* (IaaS) where tenants can access virtualized physical resources such as processing, storage, networks, where they can deploy and run arbitrary software. Tenants manage the use of the OS and the resources they have purchased. These Cloud services may be offered in four different deployment models:

¹The VM used by administrators to manage the platform that has a privileged access to the VMM interfaces and the VMs, e.g. to create them, stop them, use the introspection interface. An example is Dom0 in Xen. In literature it is also referred as *Privileged VM*, *Control VM*, *Root VM*, etc.

 $^{^{2}}$ A type I VMM is also called *hypervisor*: we will use the term hypervisor interchangeably with any type of VMM.

- -*private Cloud*: operated solely for an organization and managed by it (although the management may be subcontracted);
- -community Cloud: shared by several organizations and supports a specific community that has shared concerns. It may be managed by the organizations or a contracted third party;
- *public Cloud*: available to the general public or a large industry group and is owned by an organization selling Cloud services;
- -hybrid Cloud: a composition of two or more Clouds (private, community, or public) that remain unique entities but are bound together by standardized or proprietary technology that enables data and application portability.

There is clearly a trade-off for tenants between flexibility and control (and security and trust assumptions) among these service and deployment models. In fact, tenants have more control (and better security) and flexibility (e.g., in terms of configuration options) when moving from SaaS to IaaS and, analogously, when moving from a public Cloud to a private Cloud. The drawback in these cases is that when moving from SaaS to IaaS the user interface to the Cloud, i.e., to allocate services or resources, places an additional burden to the user in terms of ease of use.

3. ATTACKS IN VIRTUALIZED ENVIRONMENTS

While virtualization offers many advantages, as discussed in the previous section, it also introduces new security concerns linked mainly to the loss of control arising from the usage of third-party owned resources, the sharing of resources among VMs and vulnerabilities of the hypervisor itself. In particular, attacks due to vulnerabilities in the hypervisor itself have a high impact, since they allow an attacker to control all the VMs. We therefore start by first describing the categories of attacks possible in a virtualized environment as described in the literature. Firstly, attacks can be categorized by considering their possible *targets*, i.e., at what level an attacker can exploit a vulnerability. The taxonomy we present here span from the higher to the lowest levels:

- *application-level* (guest VM's user-space): these are attacks against user applications, such as through injection of malicious code inside an application to divert its control-flow and execute the attacker's code [Aleph One 1996] [Roemer et al. 2012];
- -*kernel-level* (guest VM's kernel-space): these attacks target the OS, such as kernel rootkits [Sparks and Butler 2005] [Hoglund and Butler 2006][Levine et al. 2006], which allow an attacker to fully control the system;
- -*virtualization layer*: these attacks exploit the virtualization features in many ways, such as to attack VMs residing on the same host [Xu et al. 2011] [Zhang et al. 2012];
- hypervisor: these attacks try to exploit vulnerabilities at the hypervisor level (see also Table I, described later) to gain control of it, and of all the VMs on top of it; other ways require escaping from a VM to attack the hypervisor [Kortchinsky 2009];
- lower levels: in these attacks, an attacker tries to subvert the levels below the hypervisor, such as the hardware or the System Management Mode (SMM), e.g. to directly access the memory to modify/read the hypervisor virtual space [Embleton et al. 2008] [Stewin and Bystrov 2013].

Attacks can also be categorized by taking into account the *source* of attacks [Jamkhedkar et al. 2013], i.e., from where the attack is originated. In particular, they can be initiated by the same VM (e.g., from kernel, other applications, or by the application not respecting its intended behavior), or from the same host (e.g., co-resident VMs, the hypervisor, lower levels), or external hosts. As far as internal or external attack sources are concerned, we consider as possible attackers: (i) the Cloud providers, which can be considered as trusted providers, honest-but-curios providers, malicious providers, or

trusted with insider threats; (ii) tenants of other VMs; (iii) tenants of the same VM (from the point of view of the provider). Any other possible source of external attacks, such as a server in the same Cloud environment or a remote host, is considered as a generic external attacker. The sources of attacks can be further fine-grained if we consider entities such as the manufacturer of the hardware used by the provider, the developers of the software run by the provider, and, in general, any third-party involved with the provider. Such issues are covered well in [Bleikertz et al. 2013]. Finally, we need to consider the *goal* of the attack in virtualized environments, which can be the compromise of the (i) integrity, (ii) confidentiality, (iii) availability. In this work we do not consider attacks against the availability of the services because these are usually regulated by service-level agreements (SLAs) and they are more easy to be checked and accounted for.

3.1. Attack Paths in Virtualized Systems



Fig. 2. Attack Paths

Taking into account the previous taxonomy of attacks, we have enumerated in Fig. 2 the possible attack paths in virtualized environments. The double circled letters indicate the initial existing accesses to the assets according to the considered threat model. In particular, in (A), a honest-but-curios provider has (read-only) access to the Admin VM, whereas in (B) a malicious administrator has a read-and-write access to the Admin VM. The Admin VM may export a management tool, with virtual machine introspection (VMI) capabilities, that enables direct access to the VMM through its management interface (see path (E)) to modify configuration files, start new VMs or halt existing ones, read/modify the memory of the VMs. Having physical access to the premises, a malicious administrator can also directly access the VMM (see (C)) and the layers below (see (D)). Instead, a tenant has usually only access to a guest VM

(see (F)), which may entitle him to either access the entire stack of the VMs (in IaaS model) or only some applications (in SaaS model). Here, we consider the case where the (malicious) tenant has full access to the VM (as in IaaS model).

The second set of paths, highlighted with circled numbers, show possible attack hops. In particular, in (1) we show the path that enables an entity using the management interface to (maliciously) access the state of a VM (e.g., memory, processor's registers etc). As an example, this path may enable an attacker to modify the status of the VM (integrity) or read private files (confidentiality) or stop/start VMs (availability). With path (2) an entity owning a guest VM gains access to the Admin VM, either because of its vulnerabilities or open ports, which may be open only to the internal network or to the virtual private network of the VMM, or because of Cross-VM attacks (described later in Sect. 3.2.1). With (3) a guest VM exploits a vulnerability of the VMM to gain access to the VMM or to attack it. In (4) a guest VM either gains access to another VM (not belonging to the user of the guest VM) or exploits Cross-VM attacks to steal private data from the co-located VM. The difference with (2) is that in (2)usually the attacker wants to elevate his/her privileges, whereas in (4) the target is the VM itself. In (5) we show the path where a (compromised) hypervisor is exploited to attack, or access, a guest VM illegally. In (6), (7) and (8) a remote attacker exploits a vulnerability to illegally attack (or access), respectively, a tenant VM, the VMM, or the Admin VM. The Admin VM can also be used to exploit a vulnerability of the VMM to attack it, or gain access to it, as shown in path (9). Finally, path (10) shows the compromise of the VMM from the layers below.

We want to underline that these paths can be combined together, such as with the combination of (6) and (3), where an attacker that wants to subvert an hypervisor firstly attacks a guest VM ((6)) and then attacks the VMM from the guest VM ((3)), or analogously with paths (8) and (1).

3.2. Existing Attacks

In the following, we briefly survey known attacks against a virtualized environment at different levels. In particular, we focus on the last three targets of the previous taxonomy, namely virtualization layer (*attacks to VMs*), hypervisor (*attacks to and from hypervisor*) and *attacks to lower levels*. Figure 3 pictorially reports some of the attacks discussed in the following by showing at which level they are deployed.

3.2.1. Attacks to VMs. The first layer we consider is the virtualization one; in particular, we describe known attacks against VMs or attacks that are facilitated by the presence of the virtualization layer. We show that the presence of a VMM does not necessarily make a system more secure. In fact, even if virtualization enables strong separation among VMs on the same host, it may happen that one of its interfaces, such as hypercalls [Barham et al. 2003], is vulnerable and exploited by an attacker. Furthermore, we need to consider whether an attacker can detect if the target runs in virtualized environment and if he can exploit this knowledge. We will then discuss existing attacks facilitated by the virtualization layer.

VM Detection. For an attacker, detecting that a target system runs inside a VM might open new avenues to subvert the system. In fact, by detecting the presence of the virtualization layer, the attacker can focus its targeted attacks on this layer

ACM Computing Surveys, Vol. 48, No. 3, Article 46, Publication date: January 2016.



Fig. 3. Summary of Some Attacks at the Various Levels

rather then on the OS or applications so the whole system can be more easily subverted, e.g. by trying to exploit know vulnerabilities of the discovered VMM. Quist and Smith [2006] describe a method for determining the presence of VM emulation in a non-privileged operating environment by using the local descriptor table as a signature for virtualization. In [Garfinkel et al. 2007] the authors discusses the usage of timing benchmarks to detect the presence of VMMs, whereas [Raffetseder et al. 2007] surveys alternative strategies to detect system emulators. Ferrie [2006] and Ferrie [2007] show some possible ways for VMM to hide their presence, such as intercepting non-sensitive instructions (e.g., SIDT), whereas [Carpenter et al. 2007] shows some mitigation techniques against VM detection on VMware by modifying the VM configuration files (VMX files). Franklin et al. [2008a] and Franklin et al. [2008b] show how it is possible for an attacker to detect the presence of a VMM under the OS by measuring the execution time of particular code sequences on the remote system, whose execution time differs from the perspective of an external verifier when a host runs inside a VM.

Virtualization Extension-based Attacks. This class of attacks exploits existing virtualization technologies, such as AMD-V [Advanced Micro Devices 2005], Intel VTx [Uhlig et al. 2005b] or Intel Virtualization Technology for Directed I/O (VT-d)³ by trying to insert a malware (VM-based rootkits, or VMBRs) at a lower level than the hypervisor (this techniques is also called "Hyperjacking"). This class of malware inserts a malicious hypervisor underneath the OS and leverages virtualization to make themselves undetectable. Proof-of-concept VMBRs are SubVirt [King and Chen 2006], Vitriol [Dai Zovi 2006] and Blue Pill [Rafal Wojtczuk 2008]. Wojtczuk and Rutkowska [2011] show some software attacks to escape from a VM with direct access to physical devices to gain full control over the whole system. Further attacks against the VMM which exploit direct device assignment are discussed in [Pék et al. 2014].

VM Escape and VM Hopping. In a *VM escape* attack, an attacker is able to break out from a compromised VM and take control of the underlying hypervisor. Once there, an attacker can invoke any function, such as for creating VMs, or managing I/O devices.

³This technology provides hardware support for I/O Memory Management Units (MMUs), for direct memory access (DMA) and interrupt virtualization.

For example, *Cloudburst* [Kortchinsky 2009] is a memory-corruption exploit that enables a guest VM to execute malicious code on the underlying host, and then tunnels a connection to it. An orthogonal attack is *VM hopping* [Tsai et al. 2012], which allows an attacker to move out from one VM to compromise another VM on the same host.

Cross-VM Attacks. In contrast to the attacks described in the previous paragraph, whose goal is to escape from the VM to control (i.e. getting access to) the hypervisor or another co-resident VM, Cross-VM attacks aim at attacking co-resident VMs. Examples of such attacks are limiting the availability of the VMs or retrieving sensitive information from them. These last attacks are usually implemented by leveraging various side channels, such as cache covert channels, network-based (such as network watermarking and fingerprinting) or memory-based (memory deduplication, memory bus covert channels). In fact, since VMs are sharing the same hardware resource, such CPU (e.g. caches), memory (e.g. buffers) and network (e.g. virtual interfaces), it is possible to extract information from the co-hosted VMs. As an example, Xu et al. [2011] show how to exploit L2 cache covert channels to steal small amount of data from a co-resident VM, and [Zhang et al. 2012] show how a malicious VM can exploit the L1 cache to capture the target VM's private ElGamal decryption key. Wu et al. [2012] exploit the memory bus as a high-bandwidth covert channel medium and demonstrates realistic covert channel attacks on various virtualized x86 systems. HomeAlone [Zhang et al. 2011b] is a tool for detecting the existence of side channels on the same host to launch the attack by examining neighbor VMs L2 cache memory activity. [Irazoqui et al. 2014] demonstrate a Cross-VM Flush+Reload cache attacks to recover the keys of an AES implementation of OpenSSL running inside the victim VM, where the VMs are located on separate cores. A similar attack for commercial PaaS Cloud is proposed in [Zhang et al. 2014], which has been exemplified with three real attacks. The proposed framework exploits the knowledge of the control-flow graph of an executable shared with the victim of the attack. The authors propose to build a so called *attack* non-deterministic finite automaton to determine which memory chunks should be monitored to trace, and characterize, the victim's execution for specific attacks. Last-level cache (LLC, basically L3 cache) attacks are discussed in [Liu et al. 2015], where the authors show how LLC presents a high-bandwidth channel that can be exploited to mount (cross-core) Cross-VM side channel attacks. Since this kind of cache is shared across all cores of the CPU, the impact of such an attack can be much larger. Another L3 attack is discussed in [Irazoqui et al. 2015], which does not rely on the deduplication features required by Cross-VM Flush+Reload, and hence applicable in a larger number of hypervisors. The authors demonstrate the viability of recovering AES keys when attacker and victim are located in different cores in less than three minutes.

One of the issues in this class of attacks, and also for VM Hopping attacks, is the identification of where a desired VM is located. Given this knowledge, an attacker then strives to place the malicious VM on the same host to finally launch the attack using these techniques. Ristenpart et al. [2009] show that it is possible to (i) map the internal Cloud infrastructure, (ii) identify where a particular target VM is likely to reside, (iii) instantiate new VMs until one is placed co-resident with the target. Another attack, called *resource-freeing attacks*, modifies the workload of a victim VM in a way that it frees up resources for the benefit of the attacker's VM [Varadarajan et al. 2012].

3.2.2. Attacks to Hypervisor. Several research solutions enhance the hypervisor to defend the system from attacks to VMs, such as the ones discussed in the previous section. The idea is that, by moving the enforcement and protection mechanism into a lower level, attackers cannot hide their actions. This is also true for attackers, who strive to reach the VMM-level to control all the other VMs. Hence, it is a "race to the bottom" between the attackers and the defenders trying to attack, and protect, the

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Aen	CVE-2015-4104	DoS	7.8	R	Low	None	None	С
Xen	CVE-2015-3456	DoS Exec Code Overflow	7.7	L-N	Low	С	С	С
Xen	CVE-2015-3209	Exec Code Overflow	7.5	R	Low	Р	Р	Р
Xen	CVE-2015-2751	\mathbf{DoS}	7.1	R	Medium	None	None	С
Xen	CVE-2015-2151	DoS Exec Code Mem. Corr. +Info	7.2	\mathbf{L}	Low	С	С	С
Xen	CVE-2015-0361	\mathbf{DoS}	7.8	R	Low	None	None	С
Xen	CVE-2014-9030	\mathbf{DoS}	7.1	R	Medium	None	None	С
Xen	CVE-2014-7188	\mathbf{DoS}	8.3	L-N	Low	С	С	С
Xen	CVE-2014-3969	+Priv	7.4	L-N	Medium	С	С	С
Xen	CVE-2014-1666	DoS +Priv	8.3	L-N	Low	С	С	С
Xen	CVE-2013-6375	DoS +Priv	7.9	L-N	Medium	С	С	С
Xen	CVE-2013-2211	Other	7.4	L-N	Medium	С	С	С
Xen	CVE-2013-2072	DoS Overflow +Priv Mem. Corr.	7.4	L-N	Medium	С	С	С
Xen	CVE-2013-1432	DoS +Priv	7.4	L-N	Medium	С	С	С
Xen	CVE-2012-6030	DoS	7.2	\mathbf{L}	Low	С	С	С
Xen	CVE-2012-3515	+Priv	7.2	\mathbf{L}	Low	С	С	С
Xen	CVE-2012-0217	Overflow +Priv	7.2	\mathbf{L}	Low	С	С	С
Xen	CVE-2011-1763	DoS +Priv	7.7	L-N	Low	С	С	С
Esxi	CVE-2013-5970	DoS	7.1	R	Medium	None	None	С
Esxi	CVE-2013-3658	Dir. Trav.	9.4	R	Low	None	С	С
Esxi	CVE-2013-3657	DoS Exec Code Overflow	7.5	R	Low	Р	Р	Р
Esxi	CVE-2013-3519	+Priv	7.9	L-N	Medium	С	С	С
Esxi	CVE-2013-1659	DoS Exec Code Mem. Corr.	7.6	R	High	С	С	С
Esxi	CVE-2013-1406	+Priv	7.2	\mathbf{L}	Low	С	С	С
Esxi	CVE-2013-1405	DoS Exec Code Mem. Corr.	10	R	Low	С	С	С
Esxi	CVE-2012-3289	\mathbf{DoS}	7.8	R	Low	None	None	С
Esxi	CVE-2012-3288	DoS Exec Code Mem. Corr.	9.3	R	Medium	С	С	С
Esxi	CVE-2012-2450	DoS Exec Code	9	R	Low	С	С	С
Esxi	CVE-2012-2449	DoS Exec Code Overflow	9	R	Low	С	С	С
Esxi	CVE-2012-2448	DoS Exec Code Overflow	7.5	R	Low	Р	Р	Р
Esxi	CVE-2012-1518	+Priv	8.3	L-N	Low	С	\mathbf{C}	С
Esxi	CVE-2012-1517	DoS Exec Code Overflow	9	R	Low	С	С	С
Esxi	CVE-2012-1516	DoS Exec Code Overflow	9	R	Low	С	С	С
Esxi	CVE-2012-1515	+Priv	8.3	L-N	Low	С	С	С
Esxi	CVE-2012-1510	Overflow +Priv	7.2	L	Low	С	С	С
Esxi	CVE-2012-1508	DoS +Priv	7.2	L	Low	С	\mathbf{C}	С
Hyper-V	CVE-2013-3898	DoS Exec Code Mem. Corr.	7.9	L-N	Medium	С	С	С
KVM	CVE-2015-3456	DoS Exec Code Overflow	7.7	L-N	Low	С	С	С
KVM	CVE-2011-2212	DoS Overflow +Priv	7.4	L-N	Medium	С	С	С

Table I. Vulnerabilities in CVE with High Severity for the period January 2012 - June 2015 for Xen, VMWare Esxi, Hyper-V and KVM (C=Complete, P=Partial, L=Local, L-N=Local Network, R=Remote)

lowest possible level. The basic assumption to insert a protection mechanism into hypervisors is that usually they have a code base that is much smaller than conventional OSes⁴ and, should have less bugs (vulnerabilities) and are more difficult to subvert. Unfortunately, despite the advances due to hardware virtualization and the leverage of various functionalities in host OS kernels, contemporary hypervisors, such as Xen and VMware, have a large, and complex, code base⁵ and thus have a potentially wide attack surface. Moreover, within the current code base, several components are rather complex, such as memory virtualization and guest instruction emulation and often offer venues to various exploitable vulnerabilities.

For the period between January 2012 and June 2015, the National Vulnerability Database (NVD) records 39 vulnerabilities for hypervisors with a severity higher than 7, i.e., those classified "high", which means they are very critical from a security point

⁴As a rule of thumb, hypervisors have a code size in the order of 100K lines of code, whereas OSes in the order of 10M lines of code, hence with an approximate ratio of one over one hundred lines.

⁵Xen has more than 200K source lines of code, while KVM kernel module alone contains 33.6K source lines of code of TCB [Wu et al. 2013]

of view (see Table I). From the table, we can see that there have been 18 vulnerabilities reported for Xen, 18 for VMWare Esxi, 1 for Hyper-V and 2 for KVM (one shared with Xen, the CVE-2015-3456, the "VENOM" vulnerability). Some of these vulnerabilities allow an attacker to directly compromise the hypervisor, e.g. by escaping from a VM. Once a hypervisor is compromised, the attacker can further take over all the VMs it hosts, which could lead to not only disrupting hosted services, but also leaking potentially confidential data contained within guest VMs. Concerning hypervisor vulnerabilities, Perez-Botero et al. [2013] characterize them in three dimensions: the trigger source, the attack vector and the attack target. The authors have classified Xen and KVM vulnerabilities into eleven functionalities (attack vectors) that are provided by hypervisor. The study shows that the most common trigger source is guest VM user-space, accounting for 39% of Xen and 34.2% of KVM vulnerabilities. Some of the attacks (and solutions) mainly focus on code or control-flow integrity, without considering the so called *non-control data attacks* [Chen et al. 2005], i.e., attacks that do not tamper with control-data to divert the control-flow of the program. However, [Ding et al. 2013b] show how to construct attacks that target hypervisor non-control data to demonstrate which types of data in the hypervisor's code are critical to system security by showing that privilege, resource utilization and security policy related data are vulnerable to return-oriented programming or DMA attacks.

Attacks from Hypervisor. As previously discussed, once hypervisors have been attacked, they can be exploited to attack other VMs on the same host. Other venues of attacks may stem from high privileged tools available to administrators. These tools, if attacked, my also provide means for malicious users to control the system. For example, the introspection capability (see Sec. 4.1) available to administrators of the VMM, if attacked or misused, might threaten the VMs confidentiality and integrity, as shown by DKSM [Bahram et al. 2010], an attack against kernel structures that evade VM introspection by providing it with false information. In fact, an implicit assumption of VM introspection is that the guest OS uses the kernel data in a predetermined way. But, if the guest OS is compromised, any assumption concerning the kernel respecting data structures may become false. Furthermore, management consoles are at the core of administrating VMs, and are very attractive for attackers. If an adversary manages to get access to the management console of the hypervisor, the entire security of virtual environment is at risk. An example is VM sprawl, which is the excessive creation of VMs to waste resources and create more entry points for attackers [Chen and Noble 2001].

3.2.3. Lower-Level Attacks. If the threat model considers that physical access is not controlled, then high-impact attacks on the host become possible that make it easier for an attacker to subvert the security of the system. Often, in these cases it might not be always possible to find an appropriate security solution. We discuss some attacks that exploit DMA, SMM and BIOS and Trusted Platform Module (TPM).

DMA Attacks. DMA malware is a class of malware that exploits the DMA to launch stealthy attacks on a system by executing on dedicated hardware. An example is DAG-GER [Stewin and Bystrov 2013], which is a keylogger that attacks Linux and Windows platforms and is executed on the Intel's Manageability Engine processor. The authors show that currently a host has no reliable means to protect itself against DMA malware and that even with IOMMU-enabled platforms there exist several issues that are not easily tackled.

SMM and BIOS Attacks. The System Management Mode (SMM) is a separate CPU mode from the protected mode and real mode, which provides a transparent mechanism for implementing system-control functions, such as power management and sys-

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tem security. SMM is implemented by the BIOS and is entered via the system management interrupt (SMI) when the SMM interrupt pin is asserted. The microprocessor automatically saves its entire state in a separate address space known as system management RAM (SMRAM) and enters the SMM to execute an SMI handler. The handler then executes the rsm instruction to exit the SMM. The SMRAM is inaccessible from other CPU modes (while not in SMM) and, hence, it can act as a trusted storage space. Embleton et al. [2008] propose of a proof-of-concept *SMM rootkit* which implements a chipset level keylogger and a network backdoor capable of directly interacting with the network card to send logged keystrokes to a remote machine. Another attack [Wojtczuk and Rutkowska 2009] modifies SMM memory via Intel CPU cache poisoning, where the attacker can make the CPU execute the SMM code from cache instead of DRAM.

On the other hand, the Basic Input-Output System (BIOS) is used to initialize the hardware devices, including the processor, main memory, chipsets, hard disk, and other necessary I/O devices. BIOS code is normally stored on a non-volatile ROM chip on the motherboard. Since the BIOS is charged with the correct initialization of the SMM, it also needs to be protected from malicious tampering. If an attacker is able to attack the BIOS, he/she can control the SMM or invalidate the chain-of-trust procedure of the TPM. As an example, Kauer [2007] modify the BIOS by showing that by rebooting the system the Core Root of Trust for Measurement (CRTM) of the TPM can be changed without being noticed. [Butterworth et al. 2013] also present a vulnerability that allows an attacker to take control of the BIOS update process and re-flash it with an arbitrary image despite the presence of signed enforcement. This class of rootkits has been called "Ring -2 rootkits" (level -1 being hypervisor rootkits). Another, lowerlevel, class of rootkit is called "Ring -3 rootkit" [Tereshkin and Wojtczuk 2009], which are essentially rootkits trying to subvert the chipset functionalities, such as the Intel Active Management Technology (AMT), to install backdoors (see Fig. 3 for the various levels of rootkits deployment). Note that rootkits have been demostrated also for other low-level components, such as UEFI (Unified Extensible Firmware Interface, a lowlevel interface designed to replace BIOS) [Hudson and Rudolph 2015] and hard-disk firmware⁶.

TPM Attacks. This class of attacks tamper with the TPM to dump the content of its internal registers, and retrieve its private data (e.g., private keys), or to disable its functions [Sparks 2007]. *Replay attacks* are also possible, as shown in [Bruschi et al. 2005], i.e., an attacker can capture a message exchanged between the TPM and some authorized user, and then use the same message later in a malicious way. [Sparks and Sparks 2007] discusses time-of-check-to-time-of-use attacks against the TPM, a bus attack on the low pin count bus and also side channel attacks.

4. SOLUTIONS

The protection of the system running inside a VM can be enforced either from the OS itself of the guest VM or from a component that is independent from the system being monitored, i.e., from an Admin VM or from hardware. These two distinct approaches are known in literature as "in-the-box" and "out-of-the-box" [Jiang et al. 2007]. The in-the-box method generally relies on the security hooks provided by the monitored OS, e.g. a Linux kernel patched with Integrity Measurement Architecture (IMA) [Sailer et al. 2004] or PRIMA [Jaeger et al. 2006], which is able to measure the executable files through Linux Security Module (LSM) or Linux Integrity Module (LIM). In general, the disadvantages with these methods are that (i) since modifications must be made to

⁶http://www.malwaretech.com/2015/06/hard-disk-firmware-rootkit-surviving.html

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the monitored OS, they are not always deployable on running systems and may also introduce further vulnerabilities, and (ii) such methods rely on the OS being trusted and are therefore vulnerable to kernel rootkits. To overcome these shortcomings, virtual machine introspection (VMI) [Garfinkel and Rosenblum 2003] has been proposed as an "out-of-the-box" approach that enables an Admin VM to access the memory and virtual CPUs of a monitored VM to check the state of the system, e.g. some critical datastructures, at the kernel or at the user-level. To improve performance and stealthiness, VMI-based approaches have been proposed using additional hardware, such as [Zhang et al. 2002] [Petroni et al. 2004]. In devising protection mechanism with a limited attack surface, other solutions have removed the Admin VM from the TCB by enhancing the hypervisor directly [Litty and Lie 2006]. This requires that only the hypervisor is protected from attacks. To this end, several solutions have proposed the protection of the hypervisor from run-time attacks [Wang and Jiang 2010], or a micro-hypervisor architecture [Murray et al. 2008] [Steinberg and Kauer 2010], or the introduction of a further nested layer of virtualization [Carbone et al. 2008] [Zhang et al. 2011a]. All these approaches will be categorized and detailed in the following.

4.1. Using an Admin VM for Protection

In this category of solutions an Admin VM can analyze the state of the processes and of the kernel hosted on the monitored VMs using an introspection interface exported by the hypervisor. In particular, the TCB includes the Admin VM and the hypervisor, and the lower levels, whereas the attack surface includes the monitored VM, both at the kernel and user level.

4.1.1. Virtual Machine Introspection-based Solutions. Livewire [Garfinkel and Rosenblum 2003] was the first prototype of an intrusion detection system (IDS) that monitors VMs through introspection from an Admin VM. One of the problem with VMI is the semantic gap between the activity of the VM (in terms of processes, files) and the the low-level view of the introspection interface. One of the first libraries to implements VMI is *XenAccess* [Bryan D. Payne and Martim Carbone and Wenke Lee 2007], which is used for monitoring OSes on Xen. XENKimono [Quynh and Takefuji 2007] detects violations of the kernel level through VMI using two distinct strategies: (i) integrity checking of illegal changes to kernel code and system call table. Interrupt Descriptor Table (IDT), page-fault handler; (ii) comparison from data as seen inside and from outside the VM to detect malicious modifications to critical kernel objects. VMwatcher [Jiang et al. 2007] is another out-of-the-box approach that exploits a technique called view casting to reconstruct internal semantic views (e.g., files, processes, and kernel modules) of a VM from the outside. This tool can be used to apply: (i) comparisonbased malware detection, which compares a VM's semantic view obtained from both inside and outside to detect any discrepancy; (ii) out-of-the-box execution of off-theshelf anti-malware software.

Other VMI-based solutions try to detect hidden processes running in the monitored VM, which are usually an indicator of a rootkit being installed in the monitored VM. *Lycosid* [Jones et al. 2008] exploits cross-view validation to detect maliciously hidden OS processes by comparing the lengths of the process lists obtained, respectively, from the Admin VM and from the monitored VM. The *VIX tools* [Hay and Nance 2008] support a forensic analysis of a guest VM from an Admin VM by including a suite of tools which mimic the behavior of common Unix command line utilities. [Christodor-escu et al. 2009] adopts virtualization to monitor and protect the systems running in a Cloud from a centralized Admin VM. The proposed solution does not assume any a-priori semantic knowledge of the guest OS or any trust assumptions into the state of the VM. Another out-of-the-box approach is discussed in [Xing et al. 2014], which

measures the integrity of critical files through system call interception and without any modification of the guest VMs.

Several papers have proposed techniques to reduce the semantic gap. For example, [Srinivasan et al. 2011] present a technique called *process out-grafting*, which relocates a suspect process from inside a VM to run side-by-side with the out-of-box VM. *SYRINGE* [Carbone et al. 2012] protects the monitoring application by moving it in a separate VM where it can invoke guest functions using function-call injection. Another solution is *Virtuoso* [Dolan-Gavitt et al. 2011], which is an approach to automatically creating introspection tools. The solution analyzes dynamic traces of small, in-guest programs that retrieve the desired introspection information, and then produces similar programs that retrieve the same information from outside the guest VM. Similarly, *VMST* [Fu and Lin 2012] automatically generates VMI tools by identifying the introspection related kernel data and redirecting these accesses to the in-guest OS memory. To reduce the huge overhead of the previous solutions, [Saberi et al. 2014] exploit *on-line memoization* to cache the trained meta-data in an online fashion to execute the inspection command (such as ps, netstat, etc).

4.2. Using the Hypervisor for Protection

The second method to protect applications and OS running in a VM is to exploit the presence of the hypervisor, e.g. by enhancing it with mechanisms to protect the VMs that run on top of it. These solutions further reduce the TCB, by removing the Admin VM from it. Some of these solutions perform code authorization at kernel-level. For example, Manitou [Litty and Lie 2006] ensures that a VM only executes authorized code, by enabling the executable bit of the virtual page containing the code only if its hash belongs to a list of authorized hashes. Other solutions periodically check the integrity of the OS kernel from the VMM [Xu et al. 2007]. As an example, HIMA [Azab et al. 2009] is a hypervisor-based solution to measure the integrity of VM by monitoring critical guest events and memory protection. It maintains the measurements of the code segments of all kernel components and user programs running inside the guest VMs. HookSafe [Wang et al. 2009] is a hypervisor-based system that relocates kernel hooks to a dedicated page and then exploits hook indirection to regulate accesses to them through hardware-based page-level protection. KvmSec [Lombardi and Di Pietro 2009] is an extension to Linux KVM with the ability to check the integrity of the guest VMs [Hofmann et al. 2011] presents OSck, a hypervisor-based system that protects the system call table through hardware page protection and a hypervisor call that ensures that, once the table is initialized, the guest OS may not modify it, by setting as read-only the hardware page protections on pages containing kernel text. Finally, AccessMiner [Fattori et al. 2015] is a hypervisor-based detector that models the activities of benign applications to the OS and use the extracted models to detect the presence of malicious applications.

Other VMM-based solutions exploit memory techniques. As an example, *NICKLE* exploits *memory shadowing*, in which the VMM maintains a shadow physical memory of a running VM and performs kernel code authentication so that the shadow memory only stores authenticated kernel code. *Overshadow* [Chen et al. 2008] exploits *multi-shadowing* which leverages the extra level of indirection offered by memory virtualization in a VMM to offer a VM context-dependent mapping. This mechanism presents an application with a clear-text view of its pages, and the OS with an encrypted view to provide confidentiality and integrity. However, *Iago attacks* (where the semantics of system calls is maliciously changed) have been shown to be possible in these scenarios [Checkoway and Shacham 2013].

Finally, other solutions of this category are aimed at protecting the VM from *untrusted components*. For example, *CHAOS* [Chen et al. 2007] uses a VMM to mediate

privileged operations, where the goal is to protect a trusted process from exposing its private data and prevents tampering from a compromised OS kernel and other processes. Yang and Shin [2008] present an approach for using hypervisors to protect application data privacy even when the OS cannot be trusted. The hypervisor encrypts and decrypts each memory page requested depending on the application's access permission to the page. HUKO [Xiong et al. 2011] is a hypervisor-based integrity protection system designed to protect commodity OS kernels from untrusted extensions by confining their behavior through mandatory access control policies and hardwareassisted paging. InkTag [Hofmann et al. 2013] is a hypervisor-based system that protects trusted applications from an untrusted OS, allowing them to securely use the OS services. It does so by introducing *paraverification*, where an untrusted OS is required to verify its own behavior by communicating its intent to the hypervisor. [Wen et al. 2013] propose a solution to protect VMs from VMMs in multi-processor Cloud environments by exploiting hardware mechanisms to enforce access control over the shared resources (e.g., memory spaces). STEALTHMEM [Kim et al. 2012] is a system-level protection mechanism against cache-based side channel attacks in the Cloud. The system manages a set of locked cache lines per core, which are never evicted from the cache, and multiplexes them so that each VM can load its own sensitive data into the locked cache lines. HyperShot [Srivastava et al. 2012] removes the Admin VM from the TCB and implements a protocol for Cloud environments which allows tenants to request and verify the run-time status of VM snapshots even in presence of malicious administrators.

4.3. Protecting the Hypervisor

In the solutions described so far, the threat model assumes that the hypervisor is trusted. However, this assumption is sometime not true, as demonstrated by the attacks discussed in 3.2.2. Hence, several approaches focus on protecting the integrity of the hypervisor itself. We categorize the existing research solutions by proposing the following classes:

- formal verification: formally prove the correctness of the hypervisor (threat model: the hypervisor is considered trusted);
- hypervisor hardening: these solutions aim to protect the integrity of the hypervisor, e.g. by protecting from static attacks, control-flow attacks, and non-control-data attacks (threat model: the hypervisor is untrusted but *sanitizable* [Lacoste 2013]);
- minimize hypervisor TCB: these approaches split functionalities among different components, and remove some of these component from the TCB, using an approach similar to microkernel approaches (threat model: the hypervisor is untrusted but is hardened);
- nested virtualization approaches: these solutions add another layer below the hypervisor (threat model: the hypervisor is untrusted, but the new layer is in the TCB);
- hardware-assisted solutions: exploiting hardware features, such as SMM, to protect the hypervisor (threat model: the hypervisor is untrusted);
- introducing additional hardware: the hypervisor is protected using hardware (threat model: the hypervisor is untrusted);
- using root-of-trust: these solutions allows the trusted loading of the hypervisor (threat model: the hypervisor is untrusted).

Each of these techniques will be detailed in the following.

4.3.1. Formal Verification. One approach to remove the hypervisor from the threat model is to formally verify that it is secure. For example, some approaches can prove the absence of known classes of vulnerabilities, such as buffer overflows and null

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pointer dereferences, on small micro-kernels (e.g., seL4 [Klein et al. 2009]). However, these approaches also impose strict requirements on the micro-kernel design and implementation and, even if attractive, they require significant efforts to the design of hypervisors. We also note that the size of micro-kernel that can be formally verified is around 10K LOC, whereas commodity hypervisors greatly exceed this size (in the order of 100K LOC), so this approach is only applicable in very few cases in practice.

4.3.2. Hypervisor Hardening. If the absence of known bugs cannot be ascertained, other techniques can be used to make it difficult to exploit them. HyperSafe [Wang and Jiang 2010] implements two techniques to protect a Type I VMM: (i) non-bypassable memory lockdown, where once a memory pages is locked down it guarantees that the page needs to be unlocked first before being modified; (ii) restricted pointer indexing, which leverages the memory lockdown to extend the protection coverage from hypervisor code to control data. HyperVerify [Ding et al. 2013a] is an architecture to monitor hypervisor non-control data using a introspection VM. Other approaches advocate a self-protection paradigm [Wailly et al. 2012] by enforcing hypervisor protection using security loops which control different VMM layers. To this end, hooks mediate and control interactions between a device driver and the VMM environment.

4.3.3. Reducing the Hypervisor TCB. Other solutions revisit hypervisor design by proposing new architectures in an attempt to minimize its TCB [Murray et al. 2008] [Steinberg and Kauer 2010]. NOVA [Steinberg and Kauer 2010] is a micro-kernel-based VMM that decouples the VMM into a modular system by introducing a capabilitybased access control for the several components inside a VMM. Another approach that has been advocated is to isolate buggy or untrusted device drivers of the hypervisor, such as [Sharif et al. 2009]. *HyperLock* [Wang et al. 2012] similarly creates a separate address space in host OS kernel so that the execution of the hypervisor as a loadable module can be isolated. However, it still runs in privileged mode and requires additional techniques to avoid possible misuse of privileged code. NoHype [Keller et al. 2010] [Szefer et al. 2011] is a system that implements a microkernel-like hypervisor to only provide pre-allocated memory and processor core to a guest-OS and by sharing only the network interface and disk. To reduce the hypervisor TCB, [Gebhardt et al. 2010] exploit hardware protection mechanism to isolate hypervisor security critical functions, in particular by moving the hypervisor in ring 0 of VMX root mode, whereas the non security TCB are executed in one of the other VMX root modes. *DeHype* [Wu et al. 2013] is a system that deprivileges hypervisor execution to user mode by decoupling the hypervisor code from the host OS, hence by reducing the attack surface. *MyCloud* [Li et al. 2013] is a reduced VMM system hat removes the Admin VM from processor root-mode and only keeps crucial security components in the TCB.

4.3.4. Inserting an Additional (Software) Layer Below the Hypervisor. Other solutions insert another layer below the hypervisor to check the integrity of the hypervisor. *GuardHype* [Carbone et al. 2008] is a hypervisor with a focus on VMBR prevention that allows the execution of legitimate third-party hypervisors but disallow VMBRs. GuardHype mediates the access of third-party hypervisors to the hardware virtualization extensions, effectively acting as a hypervisor for hypervisors. *CloudVisor* [Zhang et al. 2011a] exploits *nested virtualization* [Ben-Yehuda et al. 2010] to introduce a tiny security monitor underneath a commodity hypervisor. CloudVisor is responsible for protecting the confidentiality and integrity of the resources owned by VMs, whereas the hypervisor is still responsible of the (de)allocation of the resources to the VM. In other approaches, such as [Strackx and Piessens 2012], a new (minimal) hypervisor is introduced to protect applications and kernel. The difference with the previous approaches is that this is a thin layer that sits below the OS and applications (it can be seen as a reduced hypervisor) and not a hypervisor below an existing hypervisor.

4.3.5. Hardware-Assisted Solutions to Protect the Hypervisor. Several approaches [Azab et al. 2010] have shown that inserting an additional software layer to protect the integrity of hypervisors may not be sufficient. In fact, the additional layer may introduce new vulnerabilities and could start another race with malicious attackers in obtaining the highest privilege in the system. Hence, some solutions have proposed to exploit hardware-supported schemes to monitor the integrity of hypervisors. For example, some works exploit SMM mode by adding a small (locked) code to protect the integrity of the hypervisor [Rutkowska and Wojtczuk 2008] [Wang et al. 2010] [Azab et al. 2010]. One of the problems with these approaches is that they are not easy to be updated and/or deployed on commodity systems. Bastion [Champagne and Lee 2010] is a hardware-software architecture for protecting critical software modules in an untrusted software stack. It includes a processor and a thin hypervisor, which are both enhanced to provide secure execution and storage to these modules. HyperCheck [Wang et al. 2010] [Zhang et al. 2014] is a hardware-assisted tampering detection framework designed to protect the integrity of hypervisors by leveraging SMM and a PCI device to securely generate and transmit the full state of the protected machine to an external server. HyperSentry [Azab et al. 2010] is a framework for integrity measurement of a hypervisor that introduces a software component that is isolated from the hypervisor. HyperSentry uses an out-of-band channel to trigger stealthy measurements, and adopts the SMM to protect its base code and critical data. SICE [Azab et al. 2011] shows that building strong isolation mechanisms on top of existing SMM requires a very small TCB of about 300 LOC. DataSafe [Chen et al. 2012] is an architecture that uses policies to protect data from attacks from untrusted third-party application, such as untrusted third party applications. To this end, DataSafe provides dynamic instantiations of secure data compartments and continuously tracks and propagates hardware tags to identify sensitive data by enforcing unbypassable output control. HyperWall [Szefer and Lee 2012] exploits hardware to provide VMs protection from hypervisor by allowing it to freely manage the memory, processor cores and other resources of a platform, and by protecting the memory of the guest VMs from accesses by the hypervisor or by DMA. The protections are enabled through modifications to the microprocessor and MMUs. HyperCoffer [Xia et al. 2013] is a hardware-software framework to protect confidentiality and integrity of tenant's VMs that only trusts the processor chip. HyperCoffer requires some changes to the (untrusted) hypervisor by introducing a mechanism called VM-Shim that runs in-between a guest VM and the hypervisor.

4.3.6. Protection Using Additional Hardware Units. This set of solutions does not rely on the hypervisor at all, as an example by exploiting a secure coprocessor [Dyer et al. 2001] [Zhang et al. 2002]. In [Arbaugh et al. 1997] system integrity is verified at boot time, and the root of trust is a small bootloader which computes a hash of the content loaded into memory, and compares this to a signed hash stored in secure ROM. A device is only allowed to boot if the two hashes match. AEGIS [Suh et al. 2003] is a processor to build computing systems secure against physical and software attacks. In the threat model, all the components external to the processor, such as memory, are considered to be untrusted. AEGIS provides a tamper-evident, authenticated environments in which any physical or software tampering by an adversary is guaranteed to be detected. *COPILOT* [Petroni et al. 2004] is a coprocessor-based kernel integrity monitor for commodity systems designed to detect malicious modifications to the host kernel. [Dinaburg et al. 2008] proposes *Ether*, which is a malware analyzer that exploits hardware virtualization to reside completely outside the target OS environment. Finally,

to protect security critical processes and data from Cloud administrators, [Seol et al. 2015] propose a trusted VMM to encrypt confidential data of guest VMs and a hardware security module called Trusted Cloud Module (TCM), implemented as an external PCI device, to store the cryptographic keys.

4.3.7. Protection Using Root-of-Trust. Some solutions ascertain the integrity of the hypervisor through hardware-based technologies, including TPM [Bajikar 2002], Intel Trusted Execution Technology (TXT) [Greene 2012] and AMD SVM [Uhlig et al. 2005b]. These are capable of effectively establishing static, or dynamic, root-of-trust by guaranteeing that the hypervisor has loaded in a trustworthy manner, i.e., that its code has not been tampered and the correct version has been loaded. However, one of the main challenges with these approaches is how to maintain the same level of integrity throughout the lifetime of the loaded hypervisor. Since the absence of software vulnerabilities in the loaded components (e.g., the hypervisor) cannot be proven, we have to consider threats that exploit such vulnerabilities after it has been loaded. The goal of the static root-of-trust (also known as Static Root of Trust Measurement, SRTM) is to guarantee that the system is started in a known good state by booting it from some immutable piece of code. The assumption underlying this approach is that the code used for loading the system is trusted, i.e., it cannot be modified. This code initiates the measurement process, in which each component measures the next one in a chain of trust. In particular, the hardware firmware code first calculates the hash of the BIOS, and extends a TPM's platform configuration register (PCR) with the value of this hash. Then, the BIOS continues this chain measurement with the PCI EEPROMs and the master boot record, before handling execution to them. Finally, the bootloader measures the OS loader before executing the OS or the hypervisor.

With Dynamic Root of Trust (DRTM), which is also referred as secure late launch [Kauer 2007] [McCune et al. 2008], attestation functions can be invoked long after the normal boot sequence has completed. This allows the system to transfer control to known code after hardware specific activities, such as device drivers, have initialized. The first implementation of DRTM on AMD processors was the Open Secure LOader (OSLO) [Kauer 2007]. Using this mechanism, also the BIOS and bootloaders can be removed from the trust chain. Similarly Flicker [McCune et al. 2008] is an infrastructure for executing security-sensitive code in isolation and for providing attestation of code execution to a remote party. The TCB is only 250 lines of code and is meant to execute small sensitive pieces of code. SecVisor [Seshadri et al. 2007] is a tiny hypervisor that ensures code integrity for OS kernels by checking that only previously approved code can execute in kernel mode. SecVisor exploits late launch technologies to boot the system safely. The disadvantages of these approaches is that one processor may interrupt all the other processors on the same machine and it also requires developers to port their applications. Trusted Execution Environment [Dai et al. 2010] is an architecture that can run multiple instance of DRTM in parallel in virtualized environment. TrustVisor [McCune et al. 2010] is a special-purpose hypervisor that provides code integrity as well as data integrity and secrecy for selected portions of an application and is initialized via DRTM. SMART [Eldefrawy et al. 2012] is a primitive based on hardware-software for establishing a dynamic root of trust in a remote embedded device. In [Jayaram Masti et al. 2013] the authors propose an architecture that enables the creation and management of multiple, concurrent, secure executions environments on multi-core systems. The architecture relies on new processor extensions and a hardware-based virtualized TPM to support multiple, concurrent, dynamic root-of-trust requests from different VMs. [Owusu et al. 2013] propose a new a set of CPU instruction set extension for externally verifiable initiation and execution of an isolated execution environment.

Recently, new processor extensions have been devised to provide a form of integrity protection in Cloud environments. In particular, Software Guard Extensions (SGX) [McKeen et al. 2013], [Anati et al. 2013] for Intel Processors allow an application to instantiate a protected container, referred to as an *enclave*, which is a protected area in the application's address space having its own entry table, heap, stack and code. The enclave provides both confidentiality and integrity of the application even in cases where an attacker has gained the most privileged execution level. To this end, accesses to the enclave memory area from any software not resident in the enclave are prevented. Using SGX, the application to be protected can be distributed in clear. When the protected portion is loaded into an enclave, its code and data are measured and protected against external software access⁷. This new set of extensions in a Cloud environment makes it possible to attest single portion of a host memory without interrupting the execution of other software on the machine. As an example, Guardat [Vahldiek et al. 2014] is an architecture that enforces data access policies at the storage layer. The enforcement can be implemented in a trustlet within a VMM (or OS) isolated using a container with SGX. Haven [Baumann et al. 2014] is a system designed to run unmodified legacy applications in the Cloud by exploiting the protection of SGX to provide integrity and confidentiality of tenant's applications. In the considered threat model, the adversary may have full control of the hardware, excluding the processor but including memory and I/O, besides the entire software stack. The system is structured in such a way that also Cloud providers are protected from misbehaving tenants applications. VC3 [Schuster et al. 2015] is a system based on SGX to run distributed MapReduce computations in the Cloud, and that keeps the code and data secret as well as ensuring the correctness and completeness of the result. The user code is loaded into an SGX enclave, and it exploits a key exchange protocol to get the keys needed to decrypt the provided map and reduce functions. The TCB only contains Hadoop, while the OS, and the VMM, are outside the TCB. Hence, in the considered threat model, an attacker can attack OS and hypervisor and can also record, replay, and modify network packets.

5. FRAMEWORK TO CATEGORIZE, DEFINE AND EVALUATE SECURITY SOLUTIONS

To categorize the solutions discussed so far, we propose a framework that takes into account their *threat model*, the *security properties* of the solution (goal and TCB), and how the *solution is implemented* (methodology and features).We believe that such a common framework is needed also to evaluate different solutions under the same taxonomy. Furthermore, such a framework can be used when proposing a new security solution to clearly define the assumptions and the goals. To this end, in the following we propose a categorization of the security solutions based upon the *threat models* (security and trust assumptions), *security properties* (goals and TCB) and the *implementation strategy* (methodology and features).

5.1. Threat Models of the Solutions

We have seen that different threat models may exist in a virtualized system, each of which includes a different set of security and trust assumptions and possible threats against the assets. A *threat model* thus comprises a set of *threats* (and related *attacks*), *security assumptions* and *trust assumption*. The *security assumptions* form the basis from which security control is enforced. For example, if in one model one considers physical access is not possible, attacks trying to subvert the hypervisor from the lower level are not taken into account by the solution, but may still exist. In another example,

 $^{^7 \}rm For$ more details, see the Software Guard Extensions Programming Reference: https://software.intel.com/sites/default/files/managed/48/88/329298-002.pdf

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if the threat model considers the hypervisor to be with no (exploitable) bugs, whereas the OS is vulnerable, then a proposed protection solution can be deployed directly inside the hypervisor itself to consider possible attacks against the kernel. The trust assumptions define the level of trust in the system's components and its principals before security mechanisms are deployed. Trust assumptions in the threat models might be based upon trust in the Cloud providers, in SLAs, on an assessment, on proofs, or on a black box approach. Trust can also be defined as an *accepted dependance* [Avizienis et al. 2004], where dependence of a component A on a component B represents the extents to which the security (dependability) of A depends by that of B. In our case, we are interested in defining the trust of actors (willingness/capacity to operate in a compliant way), which have direct access to these components (i.e., a component B depends on the trust of the actor A). The notion of *dependability*, i.e. the ability to deliver service that can justifiably be trusted, can be related to the security assumptions on the components, in particular in terms of their trustworthiness (i.e., assurance that the component will perform as expected) and *control* (which actor is supposed to be in control of the component). In our model, the threats are generic (e.g., provider and an external attackers) rather than specific as in [Avizienis et al. 2004] (administrators, users, providers, infrastructures, intruders, etc.) and we consider trust assumptions on the Cloud providers only. The same applies to the classes of attacks (or faults) where, when defining their threat model, we are usually referring to the security of the components with respect to generic attacks. This is due to the fact that we are trying to depict the worst-case scenarios.

We start by categorizing the existing security and trust assumptions at the different levels.

5.1.1. Security and Trust Assumptions. Concerning this set of assumptions, the first thing to consider is how well protected is the physical access to the server hosting the tenants' VMs. Obviously, any device that can be easily accessed, and tampered with, cannot be easily protected (even if some form of hardware mechanism and obfuscation can make this task more difficult [Chakraborty and Bhunia 2009], [Chakraborty and Bhunia 2010], [Desai et al. 2013]). Then we need to consider the assumptions at the upper levels.

Security Assumptions at Physical Level. Concerning physical assumptions, those that may impact the integrity and confidentiality of the tenants system are categorized as follows:

- Is physical access possible? When access is restricted to trusted staff, i.e., this includes the case in which physical security systems in the Cloud premises are in place (such as cameras, security personel, etc) [Wang and Jiang 2010] [Azab et al. 2010] [Szefer et al. 2011], versus those in which attackers may have physical access to the system [Owusu et al. 2013].
- Is physical tamper possible? When hardware is protected by physical tampering [Suh et al. 2003]; this caters for cases where, even if physical access in not restricted, some anti-tampering mechanisms exist. If this is the cases, and depending on the quality and protection level of such mechanisms, physical attacks might be removed from the threat model.
- Are BIOS/SMM or DMA malicious? If we consider these threats as possible, such as DMA attacks, then solutions that are based on the protection mechanisms offered by the CPU (e.g., paging) are no longer valid, and they propose alternative mechanisms [McCune et al. 2008]. Other solutions explicitly remove SMM threats from the threat model [Li et al. 2013] [Wang and Jiang 2010].

- Is trusted-boot present? When trusted boot is considered to be present or not, one can assume the loading of the hypervisor to be trustworthy and focus on protecting other functionalities or the system [Butt et al. 2012] [Strackx and Piessens 2012].
- Is the hardware known? When the hardware is known (CPU, memory, etc), i.e., we assume to know the model of the CPU, its frequency, the amount or RAM. For softwarebased attestation solutions [Seshadri et al. 2005] [Perito and Tsudik 2010] this is usually a mandatory requirement since, being based on timing requirements, it is mandatory to exactly know the model of the hardware components.

Note that usually some attacks are not considered at all, such as monitoring the highspeed bus that connects the CPU and memory, because they are very difficult to implement and also the protection mechanisms to resist such attacks are difficult to deploy. Fig. 4 shows some of the possible attacks, discussed in Sect. 3, related to each of these assumptions in case they are not satisfied.



Fig. 4. Security Assumptions at Physical Level

Security Assumptions at Virtualization Level. Next we need to categorize the assumptions concerning the VMs and the hypervisor:

- Is the OS vulnerable? When the OS is benign but may contain vulnerabilities [Criswell et al. 2014]: this caters for cases where the user trusts the initial setup of the OS inside the VM, but attacks are still possible due to the presence of bugs.
- Is the OS untrusted? When the OS is considered to be untrusted and can behave in any malicious way [McCune et al. 2008] [McCune et al. 2010] [Szefer et al. 2011] [Jayaram Masti et al. 2013], i.e., we assume it can be remotely (locally) attacked. In this case, the owner of the VM does not trust the VM OS. A class of attacks due to improper semantics of the OS are the Iago attacks [Checkoway and Shacham 2013], where the results of the system call are manipulated in such a way that the requesting application is tampered with. In this case, the OS is completely untrusted.
- Is introspection enabled? If this condition is met [Garfinkel and Rosenblum 2003] [Bryan D. Payne and Martim Carbone and Wenke Lee 2007] [Jiang et al. 2007], an attacker gaining access to a privileged VM is able to read sensitive data of any guest VM. Furthermore, it might be able to modify the semantics of programs running inside VMs or configuration files.

- Is the Admin VM protected? When the *Admin VM* is considered to be protected [Ding et al. 2013a] or may be vulnerable to attacks or is considered to be malicious [Butt et al. 2012] [Srivastava et al. 2012]; in these cases, the attacks might access the Admin VM from a guest VM, or remotely, and from this privileged VM they may perform denial-of-service attack, such as stopping a tenant VM. An attacker may also read, or write, to any portion of memory of the guest VM in an invisible manner.
- Is the configuration interface protected? When a (remote) attacker can modify, read, restart any other VMs using the hypervisor configuration interface [Santos et al. 2012], [Zhang et al. 2011a]. This might happen because the configuration interface (e.g., the Web interface) is not well protected (e.g., open port to the outside and easy password) or the hypervisor itself is not updated and vulnerabilities may be exploited. Otherwise, it is assumed to be trusted [Szefer et al. 2011]
- Are there any vulnerabilities in the hypervisor? When hypervisor is considered trusted [Szefer et al. 2011] or it may contain vulnerabilities [Zhang et al. 2011a]: for example, solutions can consider that the hypervisor is trustworthy (and possibly loaded with SRTM technologies [Wang and Jiang 2010]) but it may contain vulnerabilities that can be exploited by an attacker [Azab et al. 2010].
- Is the hypervisor protected? When protection is in place against attacks on the hypervisor [Xiong et al. 2011] by guest VMs or remote attacks.

Figure 5 shows some of the possible attacks related to these assumptions in the worst case, i.e., if these assumptions are considered as false in the threat model.



Fig. 5. Security Assumptions at Virtualization Level

Trust Assumptions at Cloud Level. In this context, the trust level is related to the fact that tenants lose part of their control over the hardware and software components, and this loss of control means they have to trust to some extent the provider. The trust assumptions on the Cloud provider are categorized as follows:

- Is the provider trusted? When providers are trusted so no attacks are considered possible on the virtualized system, especially low-level attacks [Szefer et al. 2011] [Li et al. 2013].
- It the provider honest-but-curious? When system administrators of guest VMs are trusted but may have the opportunities to access user's confidential data [Xiong et al. 2012]. In this case, it is assumed that they cannot alter programs or configuration files of VMs or the hypervisor.

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- Do we consider insider threats or malicious administrator? Even if the providers can be trusted, it might be the case that either some untrusted staff or trusted staff, unwillingly, perform operations that might impact the integrity or confidentiality of VMs [Srivastava et al. 2012], such as deleting files, or stopping a VM.
- What is the Cloud service model? When the tenant is using a IaaS/PaaS/SaaS model [Mell and Grance 2011]: this sets the tenants' level of access to the resources, i.e., if the user is in control of the entire stack of the VM, only of the OS, the middleware or of the applications.

Regarding the third point, some papers on protecting tenants VMs in the Cloud [Butt et al. 2012] [Szefer et al. 2011] [Li et al. 2013] [Santos et al. 2012] differentiate between Cloud service providers and Cloud system administrators. Cloud providers, such as Amazon EC2 and Microsoft Azure, have a vested interest in protecting their reputations. On the other hand, Cloud system administrators are individuals entrusted with system tasks and maintaining the Cloud infrastructure and that have access to Admin VM and the privileges that it entails. In these papers, it is assumed that Cloud system administrators are either malicious or they could make mistakes. By extension, the assumption is that the Admin VM is untrusted, i.e., system administrators can perform any operation with high-privileges on the hypervisor and VMs, but they cannot physically access them. Also in this case, we have depicted some of the possible attacks if each assumption is not satisfied (see Figure 6).



Fig. 6. Security Assumptions at Cloud Level

Combining Security and Trust Assumptions. In Table II we summarize the set of possible security and trust assumptions in the threat models. Note that each threat model includes only those assumptions that the designer of the solution believe to be considered. Hence, each protection solution is tailored for that specific threat model. For this reason, before exploiting a protection solution, it is important to understand what are the exact threats that one needs to cover. In fact, it might be the case that no solution exist if one considers the worst-case scenario, i.e., with a very restricted threat model. Note also that once the threat model has been defined, the level of access of the tenants to the Cloud resources, the attacker's capabilities, and the provider's trustworthiness, the classes of attacks on tenants resources vary noticeably.

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Assumptions	Meaning
Hardware-Level	
Physical attacks	When physical access is possible.
BIOS/DMA malicious	When low-level attacks are possible.
SRTM/DRTM	When trusted boot is present.
Virtualization-Level	
OS vulnerable	When the OS can have bugs.
OS untrusted	When OS can be controlled by attackers.
Introspection untrusted	When VMI can be used by attackers to read/modify VMs.
Admin VM untrusted	When admin VM can be used to access VMs and VMM.
Hypervisor vulnerable	When hypervisor can be attacked.
Hypervisor untrusted	When hypervisor can be controlled by attackers.
Cloud-Level	
Trusted but misoperations	When the providers are trusted.
Honest but curious	When the provider can read data.
Malicious admins	When the provider can read and modify data.

Table II. Assumptions in the Threat Model

5.2. Security Properties of the Solutions: Goals and TCB

In our categorization of the security solutions for virtualized environments, we also categorize the solutions based on their *security properties*, in terms of *goals* (covered attacks) and *TCB*. In particular, we consider these goals:

- integrity of the applications: protection from attacks are aimed at modifying the applications running in the VM, usually by exploiting standard techniques [Abadi et al. 2005] but by taking advantage of virtualization technology, e.g., by placing them at a lower level;
- *integrity of the VM* (OS and applications): protection from attacks that are aimed at modifying the VM; another distinction here is between *static protection* (i.e., the correct loading of the VM [Sailer et al. 2004] [Jaeger et al. 2006]) versus *dynamic protection* [Quynh and Takefuji 2007] (e.g., run-time checking of the semantics of the OS [Criswell et al. 2014] or of the applications [Baiardi et al. 2009]);
- *integrity of the VMs by untrusted components* (VM isolation): protecting the integrity of the VMs by isolating them from an untrusted OS [Chen et al. 2008] or other components, such as drivers;
- *integrity of the hypervisor*: protection from attacks against the hypervisor. We further differentiate among solutions that provide *static integrity protection* (Hypeguard [Rutkowska and Wojtczuk 2008], Hypersentry [Azab et al. 2010], HyperCheck [Wang et al. 2010]), or *control-flow protection* (Hypersafe [Wang and Jiang 2010]), or *non-control-data protection* (HyperVerify [Ding et al. 2013a]);
- confidentiality of the data or program in the VM: protection from attacks whose goal is to illegally access (confidential) data of the tenants [Godfrey and Zulkernine 2014], [Priebe et al. 2014], [Kim et al. 2015];
- protection against specific threats: solutions suited for particular problems, such as kernel rootkits [Garfinkel and Rosenblum 2003], VMM detection [Carpenter et al. 2007], VM escape, VM hopping, Cross-VM, or for existing known vulnerabilities (CVE);

Other goals that we do not consider here are, but that can be easily integrated in the framework, are (i) the integrity of the computation: these attacks are aimed at modifying the results of a computation (there is a strong interest in this field in current papers, such as with verifiable computation [Parno et al. 2013] [Vu et al. 2013]; however, we do not consider these classes of attacks); (ii) program or VM availability.

As far as regards the TCB, we have seen (in particular, in Sect. 4) that all the solutions rely on an (implicit) TCB, which is left outside the attacks surface. Usually the TCB is strongly related to the security and trust assumptions, e.g. if one assumes that the hypervisor cannot be attacked then logically it is in the TCB. However, we have shown that some solutions also introduce additional software, or hardware, components that are also included in the TCB. For these reasons, we also explicitly include the TCB in the categorization. In particular, when analyzing the solutions discussed in Sect. 4, we have seen there are many possible TCBs, among which the most common include:

- the Admin VM and the hypervisor (and the layers below): these are solutions based on an additional VM to check the integrity of the VM;
- only the hypervisor (and the layers below): these are solutions based on monitoring the VMs from the hypervisor;
- a reduced TCB hypervisor (and the layers below): these are solutions that remove functionalities from the TCB of the hypervisor;
- a nested micro-hypervisor (and the layers below): these are solutions based on adding an additional software layer below the hypervisor;
- only the hardware: these are solutions based on exploiting hardware-based mechanisms (such as SMM mode or additional hardware).

In other cases, a custom TCB is proposed.

5.3. Implementation Strategy of the Solutions: Methodologies and Features

The next axis to categorize the solutions is their *implementation strategy*, in particular in terms of *methodologies* and proposed *features*. We recall the categorization of the solutions for virtualized environment we have proposed in the previous section:

— using an Admin VM for protection:

— e.g., VMI.

- using the hypervisor for protection;
- protecting the hypervisor:
 - formal verification;
 - hypervisor hardening ;
 - minimize hypervisor TCB;
 - nested virtualization approaches;
 - hardware-assisted solutions;
 - introducing additional hardware;
 - using root-of-trust.

However, also other methodologies are possible (they also depend on the state-of-theart of the technology). We also consider the *features* of the solutions, such as (i) the *transparency* of the solutions, i.e., if the solution requires none or little changes to virtualization stack (OS, VMM) or if it requires modification of the computing platform (and at which level, i.e., libraries, or kernel level), (ii) if it can be used in any OS or hypervisor or only on specific ones (*portability*), and (iii) the *performance overhead* of the solution. Finally, those attacks that are not covered, under the considered threat model, define the *limitations* of the proposed solutions.

In the end, by combining the threat models, the goals, the TCB, the methodology and the features of the protection solutions, we can define of a common methodology to categorize and evaluate them. We have summarized all these features these in Tab. III. This table is by no means exhaustive, i.e., there can be other goals, assumptions, methodologies that one can consider and add to it. By using the same approach, one can clearly understand the attacks that are considered by the protection solutions

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and only under what assumptions they are effective. We think that by using the same taxonomy for defining, among others, the threat model, the security properties and implementation strategy of a protection solution, it is possible to qualitatively and quantitatively evaluate a proposed solution more accurately. To show an instantiation of this categorization, in Tab. IV we have summarized the threat models (security and trust assumptions), security properties (goals and TCB) and implementation strategy methodology and features) of some of the papers previously discussed in Sect 4 (or-dered chronologically).

Table III. Framework to Categorize, Define and Evaluate Security Sc	olutions
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Threat Model: Security Assumptions
Physical Access
BIOS/DMA malicious
SRTM/DRTM available
OS vulnerable
OS untrusted
Introspection untrusted
Admin VM untrusted
Hypervisor vulnerable
Hypervisor untrusted
Threat Model: Trust Assumptions
Trusted
Honest but curious
Malicious admins
Solution: Security Properties - Goals (Attack Covered)
Integrity of the VM (static, dynamic)
VM isolation
Integrity of the hypervisor (static, control-flow attacks, non-control-data)
VM confidentiality
Specific Threats (VMM Detection, VM Escape, VM Hopping, Cross VM, known CVE)
Solution: Security Properties - TCB
Admin VM and hypervisor
Hypervisor
A reduced TCB hypervisor
A nested micro-hypervisor
Only the hardware
Solution: Implementation - Methodology
Using an Admin VM for Protection (e.g., VMI)
Using the Hypervisor for Protection
Protecting Hypervisor (e.g., formal verification, hardening, minimize TCB,)
Solution: Implementation - Features
Transparency
Portability
Performance
Limitations (e.g., attacks not covered)

6. DISCUSSION

We have seen that virtualization technology has been used to prevent existing attacks, e.g. to OS and apps, but in a "clever way", and also to prevent attacks facilitated by virtualization, such as Cross-VM, and to prevent attacks against the virtualization layer itself, e.g. the hypervisor. Most of the proposed solutions address generic threats, such as integrity or confidentiality, instead of specific ones (such as VM Escape or a specific CVE). In general, the solutions we have detailed are mainly targeted against

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Paper	Security Assumptions	Trust Assumptions	Security Properties: Goal	Security Properties: TCB	Implementation: Methodology	Implementation: Features
[McCune et al. 2008]	BIOS, OS, DMA may be malicious Exploit AMD SVM	N.A.	Execute sensitive code in isolation Attestation of code execution	250 Lines of code	DRTM	Applications need to be ported Pause all the processes
[Wang and Jiang 2010]	No physical Attacks No BIOS/SMM attacks Yes DMA attacks Hypervisor vulnerable Trusted-Boot to load hypervisor	N.A.	Integrity of the hypervisor (dynamic and non-control-data)	Loaded Hypervisor	Hypervisor Hardening	Modification required to hypervisors 5% overhead
[Azab et al. 2010]	Out-of-band channel to enable SMI remotely Physical security in place Trusted boot to launch hypervisor SMRAM is protected	N.A.	Hypervisor Integrity and attestation (instantiated in different typologies: code integrity, CFG integrity)	SMM Code	SMM-Based Solution	Do not address periodic attacks in-between checks
[McCune et al. 2010]	Untrusted OS and applications Untrusted DMA-devices No physical attacks Requires/Exploits DRTM	N.A.	Reduced TCB Hypervisor Code and data integrity for selected portion of applications	6K Lines of Code	DRTM	7% overhead Does not support multi-processor Applications need to be ported to include PAL
[Champagne and Lee 2010]	Software and hardware attacks	N.A.	Protection of SW modules in untrusted environments	Microprocessor Chip	Hardware-Assisted Solution	Requires new microprocessor requires ad-hoc hypervisor
[Szefer et al. 2011]	Physical security controls in place Untrusted OS Trusted hypervisor	Trusted provider Trusted mngmt interface	Attacks to VMM by guest VMs Isolation between VMs	New reduced VMM	Reducing TCB	Requires slightly modified OS available to tenants 1% overhead
[Zhang et al. 2011a]	Trusted boot to launch Cloudvisor VMI is possible Management interface vulnerable Hypervisor untrusted No physical attacks	Honest provider misoperations can happen	Confidentiality and integrity of VMs from other VMs and VMM	5K LOC of TCB	Nested virtualization	1 LOC of modification to Xen Needs porting
[Xiong et al. 2011]	Untrusted OS and Extensions Trusted hypervisor	N.A.	OS integrity (static, data integrity and control-flow)	Hypervisor	Protection from Hypervisor	Modification to Xen (3.3K LOC) Modification to Linux (450 LOC)
[Strackx and Piessens 2012]	Attacker can execute arbitrary code at kernel level Trusted boot to load VMM No physical access	N.A.	Protect applications from OS and apps	TCB 7K	Nested Virtualization	New Hypervisors (1K) 3%-14% overhead
[Butt et al. 2012]	Admin VM untrusted Trusted boot to check system-level TCB Physical Security in place	CSP trusted Malicious sysadmins	Tenants VM security and privacy	Hypervisor and Domain builder	Reducing Hypervisor TCB	Modification to VMM
[Santos et al. 2012]	Remote attackers can do anything No physical attacks Remote interface vulnerable Trusted boot to load hypervisor	Malicious administrator Misconfiguration	Data confidentiality (reveal data only to nodes satisfying a policy)	Hypervisor and Trusted Node	Trusted Third Party	Assume a trusted monitor node to certify nodes
[Chen et al. 2012]	Attacker exploit a pps or OS to leak sensitive data OS untrusted Secure boot is present No hardware attacks No analogue hole	N.A.	Data confidentiality (only authorized apps can access data protect against data dissemination)	Only hardware	Hardware-Assisted	Requires new hardware
[Srivastava et al. 2012]	Malicious Admin VM Trusted boot to load hypervisor No hardware attacks	Trusted provider Malicious administrators	Provide attestation of integrity of VMs to tenants	Hypervisor	Protection from Hypervisor	Adds 4K LOC to hypervisor Requires trusted third party
[Hofmann et al. 2013]	Untrusted OS Trusted Hypervisor	N.A.	Protect VM apps from untrusted OS	Hypervisor Trusted library	Protection from Hypervisor	3500 hypervisor LOC (extension to KYM) Add (trusted) user-library 5x - 55x slowdown
[Li et al. 2013]	No physical attacks Trusted-boot Protection to SMM in place (custom BIOS)	Malicious sysadmins Provider trusted	TCB reduction Provide privacy to VMs VM-to-VMM attacks VM-to-VM attacks Insider attacks	TCB 5.8K LOC	Reducing TCB	New hypervisor 2-9% slowdown
[Wu et al. 2013]	No physical Attacks Hypervisor vulnerable Host OS Trusted	N.A.	Reducing Hypervisor TCB	TCB 2.3K LOC	Reducing hypervisor TCB	Added 10 new system calls 6% overhead
[Owusu et al. 2013]	Attacker can have physical access Can tamper with BUSes OS, App, Firmware untrusted	Trusted CSP Malicious administrators	Isolated execution environment	Only CPU	DRTM	Requires a new CPU
[Jayaram Mat et al. 2013]	sti Hypervisor is trusted OS can be malicious	N.A.	Using TXT in multi-core architectures (concurrent execution of secure environments e.g. on Cloud)	Hypervisor	DRTM	Requires changes to x86 platform
[Xia et al. 2013]	Untrusted Hypervisor Physical attacks are possible Require secure processor VM not vulnerable	Malicious administrator	Protection of VMs from untrusted hypervisor	VM-Shim (1,100 LOC)	Hardware-based	380 LOC of changes to hypervisor requires hardware support
[Ding et al. 2013a]	Untrusted hypervisor Assume hypervisor code integrity is ensured Untrusted VMs can attack hypervisor Trusted admin VM DMA enabled	N.A.	Monitor hypervisor non-control data	Admin VM and Loaded Hypervisor	Hardening	VMI can be fooled Attacks in-between periodic checks
[Baumann et al. 2014]	Untrusted hardware (except processor)	Untrusted Cloud provider Untrusted admins	Integrity and Confidentiality	LibOS (209MB) and Shield Module (180KB)	Hardware-based	Around 31%-54% overhead

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integrity attacks, in all their variants, whereas only a limited number of them address confidentiality issues (e.g., Cross-VM), and almost none of them consider availability issues.

In this survey we have provided a thorough review of threats and attacks against a system running in a virtualized environment and the research solutions aimed at addressing a set of threats. We have seen that to devise a protection mechanisms in a virtualized environment, one needs to consider the possible threat models, i.e., attacks, usage scenarios, trust assumptions at each architectural layer, e.g. hardware, hypervisor, VM – the security of the system being linked to a set of threats and trust assumptions. One of the issues with this approach is that solutions only consider a specific threat model and are highly sensitive to variation to that model, e.g. if an assumption is removed, or a new threat is considered, the solution is no longer valid. Such changes occur naturally because new issues and attacks arise as new technologies emerge, as we have described for virtualization technology. We have seen that the hypervisor is a worthy target since if an attacker is able to compromise the hypervisor of a physical host of the provider, he/she is potentially able to access, and modify, any tenants' data or application, possibly without being noticed [Kortchinsky 2009], [Elhage 2011]. Hence, many studies exploit virtualization to provide application integrity but assume that the hypervisor is trusted [Keller et al. 2010], [Hofmann et al. 2011], [Azab et al. 2009], [Xiong et al. 2011]. This is the case of solutions based upon virtual machine introspection [Garfinkel and Rosenblum 2003] [Bryan D. Payne and Martim Carbone and Wenke Lee 2007] [Jiang et al. 2007], which check the memory of a VM for compromise, and rely on the data gathered from a introspection interface exported by the hypervisor itself. However, in these scenarios, should a hypervisor be compromised, either fake data might be returned by the introspection interface or, worst, other VMs resident on the same host might by attacked from the compromised hypervisor. The argument that hypervisor is secure is based on the observation of its restricted codebase, and narrow interface. However, as the hypervisor size is continuously increasing, and taking into account also existing attacks against the hypervisor (e.g., VM escape), the assumption no longer holds and new threat models no longer consider it trusted [Szefer et al. 2011] [Azab et al. 2010]. As we have depicted in Fig. 7, we can see that proposed security solutions are increasingly moving closer to the hardware. Furthermore, we can clearly see a trend towards TCB reduction: this has happened as new attacks made it possible, and likely, to attack firstly the tenant VMs, then the Admin VM, then the hypervisor and so on. In particular, regarding the hypervisor, we have seen that it has been initially assumed to be part of the TCB; then solutions have directly enhanced it to protect it from external attacks; newer solutions have striven to reduce its TCB; finally, some recent solutions consider the hypervisor not part of the TCB anymore.

An interesting aspect that we want to underline is that, in the existing studies, threats are considered either possible or not possible, i.e., threat models only consider worst-case scenarios, e.g. the hypervisor is either fully compromised or trusted, without considering probabilities. Another interesting characteristic is whether solutions can be combined together. We have seen that some can be merged, such as those to provide hypervisor integrity with those that guarantee the VM integrity, to produce a larger protection interface. Furthermore, we can also envision the combination of solutions that provide control-flow integrity with those that provide data-flow, and non-control data integrity. Analogously, we can consider the combination of solutions tackling different goals, such as system integrity and confidentiality. Obviously, some of these combinations may increase the size of the TCB, whereas some other combinations are not directly possible because they need to be integrated (e.g., in the hypervisor) and this might require some effort to make them cooperate.



Fig. 7. Trends of Virtualization-based Solutions

7. CONCLUSION

In this survey we have provided a taxonomy of attacks in virtualized systems, by considering the target at the different levels, the source and goals of the attackers and also shown the possible attack paths. We have then proposed a framework to categorize more clearly the threat models, which can be used to define precisely the security and trust assumptions when proposing a new protection solution. This framework also includes the security properties of the solutions, such as their goal, for which we have proposed a taxonomy that considers the kind of attacks they aim to prevent. We have also categorized the solutions using their implementation strategy, such as with a set of methodologies to protect the virtualized environment. We believe that the use of a common and standardized framework could ease the categorization, description, and evaluation, of the security solutions for virtualized environments. In fact, we have witnessed, across the papers, several different ways to express the threat model and some assumptions are not always evident. Furthermore, by clearly defining the security properties of the solutions, we can compare different solutions with the same security properties using their implementation strategies, and it also becomes easier to evaluate if different solutions can be combined to solve a complex problem.

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