

1 **Abstract**

2 Asymmetry in gymnastics underpins successful performance and may also
3 have implications as an injury mechanism; therefore, understanding of this
4 concept could be useful for coaches and clinicians. The aim of this study
5 was to examine kinematic and external kinetic asymmetry of the arm
6 segments during the contact phase of a fundamental skill, the forward
7 handspring on floor. Using a repeated single subject design six female
8 National elite gymnasts (age: 19 ± 1.5 years, mass: 58.64 ± 3.72 kg, height:
9 1.62 ± 0.41 m) each performed 15 forward handsprings whilst synchronised
10 3D kinematic and kinetic data were collected. Asymmetry between the lead
11 and non-lead side arms was quantified during each trial. Significant kinetic
12 asymmetry was observed for all gymnasts ($p < 0.005$) with the direction of the
13 asymmetry being related to the lead leg. All gymnasts displayed kinetic
14 asymmetry for ground reaction force. Kinematic asymmetry was present for
15 more gymnasts at the shoulder than the distal joints. These findings provide
16 useful information for coaching gymnastics skills, which may subjectively
17 appear to be symmetrical. The observed asymmetry has both performance
18 and injury implications.

19

20 INTRODUCTION

21 In the sport of artistic gymnastics the forward handspring on floor is a fundamental
22 skill (Arkaev & Suchilin, 2009; Readhead, 1997), which represents a foundation
23 for developing gymnasts and an acceleration skill for more established
24 performers who wish to generate the correct take off conditions to perform more
25 complex movements (e.g. multiple somersaults). The assessment of this skill is
26 based on criteria outlined by the International governing body (FIG, 2013).
27 According to these recommendations one would expect the movement patterns
28 undertaken by the gymnast to have little or no asymmetry. Furthermore,
29 excessive amounts of asymmetry are penalised by points deductions in
30 competition (FIG, 2013). The coaching recommendations concur with the belief
31 that the handspring is a symmetrical movement and consequently this forms the
32 guidance for the development of this skill via preparatory activities (Arkaev &
33 Suchilin, 2009; Readhead, 1997).

34

35 Research on upper extremity asymmetry is underdeveloped, particularly within
36 the sporting context. However, research into lower-limb asymmetry during
37 running gait (Vagenas & Hoshizaki, 1992; Exell, Irwin, Gittoes & Kerwin, 2012)
38 has suggested that asymmetry may lead to a predisposition for injury in one limb.
39 From a clinical framework research has examined asymmetry of the arms during
40 wheelchair propulsion (Boninger et al., 2002; Hurd, Morrow, Kaufman & An,
41 2008). Boninger et al. (2002) reported upper limb asymmetries in propulsion
42 patterns which was suggested to have clinical consequences contributing to the
43 development of upper limb injury. Furthermore, Hurd et al. (2008) also reported
44 upper-limb asymmetry but with no consistent pattern in the direction of
45 asymmetry, which is a limiting factor in the prediction of injury and may also have

46 implications for skill development. The presence of asymmetry in joint
47 movements patterns without consistent direction (i.e. a dominant side) may
48 suggest that asymmetry can be viewed as a joint-specific compensatory
49 mechanism that is used to minimise injury risk for the different sides.

50

51 Much of the research in asymmetry has been concentrated upon the lower
52 extremity during impact forces incurred whilst jumping or landing (Fuchs, Bauer
53 & Snow, 2001; Fuchs, Cusimano & Snow, 2002) and during activities such as
54 submaximal running (Hamill, Bates & Knutzen, 1984; Vagenas & Hoshizaki,
55 1992; Zifchock, Davis, & Hamill, 2006), the triple jump (Wilson, Simpson, van
56 Emmerick & Hamill, 2008) and sprint running (Exell, Irwin et al., 2012; Exell,
57 Gittoes, Irwin & Kerwin 2012). Čuk and Marinšek (2013) looked specifically at
58 landing quality in a variety of somersaulting movements in men's gymnastics.
59 The authors found that, in order to avoid asymmetry in landing, gymnasts need
60 to develop enough height, produce high angular momentum around the
61 transverse and longitudinal axes and better control angular velocity in the
62 longitudinal axis. It has been reported that if the frequency of jumping and landing
63 is very high in sporting activities, there is an increased risk of over load injury
64 (Bressel & Cronin, 2005). It has been suggested that a smaller peak of vertical
65 ground reaction force (GRF) exists when landing from movements unilaterally
66 due to the absorption of injury inducing force and this may be an argument for
67 the production of asymmetrical movement in landing (Ortega, Rodriguez Bies, &
68 Berral, 2010). However, the utilisation of functional asymmetry in landing is
69 limited in gymnastic events due to the associated scoring penalty. Asymmetry
70 has been assessed, for the most part, in clinical settings to attempt to quantify

71 inter limb discrepancies and to assess the injury potential of limb imbalances
72 (Exell, Irwin et al., 2012; Schache, Wrigley, Baker & Pandy, 2009).

73

74 The aim of this study was to examine the kinematic and external kinetic
75 asymmetry of the arm segments during the contact phase of the forward
76 handspring on floor. The hypothesis of this research was that there would be
77 gymnast-specific asymmetry profiles influenced by the technique employed. This
78 research contributes to the applied area of gymnastics and the understanding of
79 biological asymmetry, helping coaches, clinicians and biomechanists

80

81

82 **2. METHODS**

83 *2.1. Participants*

84 Ethical approval was gained from the University's Research Ethics Committee
85 prior to commencement of the study. Six female national level gymnasts gave
86 voluntary written informed consent to participate in the study. Gymnasts mean
87 [\pm SD] age, mass and stature were 19 [\pm 1.5] years, 58.64 [\pm 3.72] kg and 1.62
88 [\pm 0.41] m, respectively. Participants were all free from injury at the time of data
89 collection.

90

91 *2.1. Equipment*

92 Three-dimensional kinematic data were collected using an automated motion
93 analysis system (CODAmotion, Charnwood Dynamics, Ltd., UK) operating at 200
94 Hz. Two cx1 scanners were used to provide a field of view of approximately 2.00
95 m, which covered the ground contact phase of the action. Synchronised ground
96 reaction force data were collected using two force plates operating at 1000 Hz

97 (Kistler 9287BA), mounted end-to-end, perpendicular to the direction of the action
98 and separated by a distance of 0.006 m. Kinematic and kinetic data were
99 collected simultaneously using the CODA software so that they were time
100 synchronised. Force plates were mounted in recessed customised housings and
101 covered with a Mondo running track surface (Mondo, USA) and thin gymnastic
102 mat (0.02 m thickness, Baenfer, Germany) similar to the set up reported by
103 Farana, Irwin, Jandacka, Uchytíl and Mullineaux, 2015. The experimental set up
104 is illustrated in Figure 1.

105

106 *2.3. Experimental procedure*

107 Twelve active cx1 CODA markers were connected in pairs to “twin-marker drive
108 boxes” and attached to gymnasts using adhesive tape prior to commencement of
109 data collection. Markers were attached to the proximal inter phalangeal joint, and
110 joint centres of the wrists, elbows, shoulders and hips on both sides of the body.
111 Following a warm up, participants each performed 15 forward handsprings from
112 a two- step approach. Participants were allowed sufficient recovery, lasting
113 approximately 10 min between trials, to avoid the effects of fatigue. Kinematic
114 and kinetic data were collected simultaneously during the performance of each
115 forward handspring.

116

117 ****** FIGURE 1 NEAR HERE ******

118

119 *2.4. Data analysis*

120 Data were processed using custom code (MATLAB R2010a, The Mathworks,
121 USA). Sagittal plane coordinates were extracted from the three dimensional
122 marker coordinates and used for all calculations. Kinematic data were filtered

123 using a 12 Hz Butterworth filter, which was customised through Winter's residual
124 analysis (Winter, 2009).

125

126 Data were analysed using a repeated single subject design. All analyses focused
127 on the ground contact phase of the hands during the handspring. Touch down
128 and take off were defined as the times when the vertical ground reaction force
129 rose above and fell below the mean plus two standard deviation value of the
130 unloaded plate, respectively. The four kinetic variables comprised peak vertical
131 and anteroposterior GRFs and times to these peaks. The six kinematic variables
132 comprised sagittal plane wrist, elbow and shoulder angles at touchdown and take
133 off. Asymmetry (percentage difference) was quantified for kinetic variables
134 (timing and magnitude) using the symmetry angle equations presented by
135 Zifchock, Davis, Higginson and Royer (2008). This method provides a percentage
136 score to quantify the magnitude of asymmetry present for a given variable, with
137 0% indicating perfect symmetry. Asymmetry was calculated with the
138 incorporation of intra-limb variability proposed by Exell, Gittoes et al. (2012):

$$141 \quad \theta_{SYM} = \frac{(45^\circ - \arctan(X_{lead}/X_{non-lead}))}{90^\circ} \times 100\% \quad [1]$$

139 Where θ_{SYM} is the symmetry angle, X_{lead} is the value for lead side and X_{non-}
140 $_{lead}$ is the value for non-lead side. However, if:

$$142 \quad (45^\circ - \arctan(X_{lead}/X_{non-lead})) > 90^\circ$$

143 then [2] was substituted:

$$144 \quad \theta_{SYM} = \frac{(45^\circ - \arctan(X_{lead}/X_{non-lead}) - 180^\circ)}{90^\circ} \times 100\% \quad [2]$$

145

146 Due to the potential influence of angle definitions on asymmetry magnitude, joint

147 kinematic asymmetry was calculated as the difference in joint angles between
148 lead and non-lead sides. All statistical tests were performed using SPSS v.17.0
149 (Chicago, IL.) Using the criteria of Peat and Barton (2005), all variables were
150 accepted as displaying a normal distribution; therefore, parametric statistical tests
151 were subsequently employed. To determine the magnitude of intra limb variability
152 relative to the amount of asymmetry for each gymnast, independent t-tests were
153 used to test for significant differences (Bonferroni adjusted $p < 0.005$) between
154 values for lead and non-lead sides for each variable. Variables that displayed a
155 significant difference between sides were described as displaying “significant
156 asymmetry” (Exell, Gittoes et al., 2012) meaning that the magnitude of the
157 difference that occurred between limbs was significantly greater than the
158 magnitude of intra limb variability.

159

160 **3. RESULTS**

161 Individual gymnast kinetic results for lead and non-lead sides are included in
162 Table 1. Furthermore, asymmetry values relating to these variables are
163 presented in Table 2. All gymnasts except Gymnast 1 demonstrated significant
164 kinetic asymmetry with the largest symmetry angle value being 10.70% for
165 maximum horizontal ground reaction force (F_z) of Gymnast 4. Four gymnasts
166 also exhibited significant asymmetry for timing of maximum force (greatest
167 symmetry angle value Gymnast 4 = 25.11%).

168

169 ****** TABLES 1 & 2 NEAR HERE ******

170

171 Table 3 contains bilateral joint angle values at instants of touch down and take
172 off for all gymnasts. Kinematic asymmetry values relating to these variables are

173 presented in Table 4. The number of kinematic variables displaying significant
174 asymmetry ranged from 2/6 (Gymnasts 2 & 6) to 6/6 (Gymnast 4). Significant
175 asymmetrical kinematic variables were reported for touchdown and take off at the
176 wrist, shoulder and elbow. Kinematic asymmetry did not appear to be related to
177 the lead leg side for wrist and elbow results. For the shoulder, five out of six
178 gymnasts demonstrated significant asymmetry at touchdown and take off, with
179 touchdown values being larger for the non-lead side and take off values being
180 larger for the lead leg side for all of these five gymnasts.

181

182 ****** TABLES 3 & 4 NEAR HERE ******

183

184 Figure 2 includes mean [\pm SD] vertical and antero-posterior ground reaction force
185 profiles for all gymnasts. The profiles highlight the individual nature of kinetic
186 asymmetry, in particular for Fz. For Gymnast 4 the Fz profile was the most
187 asymmetrical, this finding was reflected by the discrete results, where both timing
188 and magnitude were significantly asymmetrical and asymmetry values were
189 larger than the other gymnasts for most variables.

190

191 ****** FIGURE 2 NEAR HERE ******

192

193 **4. DISCUSSION**

194 Asymmetry is a fundamental characteristic of gymnastic performance and
195 assessment and may have implications as an injury mechanism. The aim of the
196 current investigation was to examine the kinematic and external kinetic
197 asymmetry, of the arm segments during the contact phase of the forward

198 handspring on floor. It was also proposed that there would be gymnast-specific
199 asymmetry profiles influenced by the individual techniques employed. Asymmetry
200 for kinetic variables was calculated using the symmetry angle approach as
201 presented by Zifchock et al. (2008) and recently adopted by Exell, Gittoes et al.
202 (2012).

203

204 Three gymnasts (2, 4 & 6) demonstrated significant asymmetry in peak vertical
205 GRF values, with no gymnasts demonstrating significant asymmetry in the
206 horizontal direction. However, asymmetry in the time of maximum force was
207 reported in both horizontal (Gymnasts 3, 4 & 6) and vertical (Gymnasts 4 & 5)
208 directions. The magnitude of asymmetry for significant maximum Fz values was
209 larger for all gymnasts compared to values reported during sprint running (Exell,
210 Gittoes et al., 2012). With gymnasts performing high volumes of these skills within
211 a session and across a season the implications for micro traumas become
212 apparent, the load will affect the nature and severity of injury (Irwin, 2011)
213 particularly at vulnerable joints such as the wrist. Biomechanical asymmetry has
214 been a prominent research area in walking and running gait research and has
215 provided important information relating to injury potential, coaching, and data
216 collection (Exell, Gittoes et al., 2012; Hamill et al., 1984; Schache et al., 2009).
217 To the authors' knowledge, symmetry in the upper extremities has not been
218 investigated during sporting activity; however, results of the current investigation
219 can be associated with those of Hurd et al. (2008), who investigated upper
220 extremity symmetry during wheelchair propulsion. Hurd et al. (2008) found
221 significant asymmetry in propulsion timing, effort and force, however, due to the
222 variability produced by this action it proved difficult for the authors to prescribe
223 specific training and conditioning regimes that could aid in injury prevention. An

224 in-depth knowledge of asymmetry can facilitate the development of a sound
225 understanding of the mechanisms of specific techniques, which in turn can inform
226 strength and conditioning regimes (Arkaev & Suchilin, 2009). The data presented
227 in this study demonstrate the potential importance of considering asymmetry in
228 external loading experienced by gymnasts. Robust methods of quantifying
229 asymmetry, such as the symmetry angle used in this study allow asymmetry to
230 be measured and compared across different skills; however, it is important to
231 consider the magnitude of asymmetry in relation to other factors that may
232 influence injury such as magnitude of force. This is exemplified in the current
233 study by the larger asymmetry magnitude in peak vertical force for Gymnast 4
234 (10.70 %) than Gymnast 6 (-8.18 %), however the peak force applied to one side
235 by Gymnast 6 (2.09 BW) was almost three times larger than the largest mean
236 value recorded for Gymnast 4 (0.70 BW).

237

238 Čuk and Marinšek (2013) suggested that the landing quality in artistic gymnastics
239 is related to landing symmetry. Furthermore, they found that limb angles at the
240 moment of touch down can influence the ability of the muscles to absorb energy,
241 thus reducing injury potential for the corresponding joints. Therefore, asymmetry
242 at the moment of touchdown can lead to one limb being at a greater risk of injury.
243 Indeed, much of this research has concentrated upon the lower extremities of the
244 body during landing and the purpose of the current investigation was to assess
245 the upper extremities. However, comparisons may be drawn between the
246 discrepancies found in the limbs.

247

248 The initial phase of the movement that requires weight bearing at the upper
249 extremities is in fact used for propulsion and does not represent the landing stage

250 of this movement. Thus, the asymmetry found at the upper extremity of the
251 movement in the forward handspring may represent an absorbing and stabilising
252 function (Riccio, 1993; Wilson et al., 2008) to ensure a symmetrical landing is
253 achieved in the lower extremities at landing. This is an interesting concept and
254 although the answer is beyond the scope of this study, it would certainly be
255 interesting to observe the kinetics and kinematics of the landing of these
256 gymnasts from the forward handspring. Despite this, these findings certainly have
257 implications in terms of coaches attempting to replicate the spatio-temporal
258 characteristics of the target skill by developing certain preparatory activities (Irwin
259 & Kerwin, 2007; Wilson et al., 2008).

260

261 In the current investigation, the direction of asymmetry for maximum F_z appears
262 to be related to the gymnasts' lead leg, with larger values observed for the side
263 of the lead leg. This finding suggests an absorbing function of the upper extremity
264 on this side of the body. In their study, Čuk and Marinšek (2013) discovered that
265 the main predictor for asymmetry was the difference in vertical hip velocities in
266 the lowest position, reporting that while the velocity of the leading hip stopped at
267 the lowest position, the velocity of the non- leading hip was still decreasing
268 (difference = $0.1 \text{ m}\cdot\text{s}^{-1}$). This finding may suggest that asymmetries result from
269 the force absorbing properties of the dominant side. Hurd et al. (2008)
270 investigated wheelchair propulsion using the dominant and non-dominant arm,
271 reporting no large differences between the two limbs. As previously noted, the
272 function of the upper extremities in the front handspring is one of weight bearing
273 and force production prior to the final landing stage of the motion. Therefore, the
274 asymmetries represented may suggest that the coordinating limbs are adapting
275 to movement requirements in a force absorbing capacity, thus representing an

276 initial stage of an overall movement system that is privy to change to ensure
277 overall symmetry is established (Turvey & Beek, 1990; Sternard, Turvey &
278 Schmidt, 1992; Wilson et al., 2008). Again, without obtaining results for these
279 gymnasts for the kinetics of the lower extremity at landing, it is impossible to
280 suggest whether the asymmetries exhibited at the upper extremity are
281 compensating for overall symmetry at landing. However, if this were the case it
282 could be suggested that the kinetic asymmetries play an important role in the
283 movement from a dynamical systems perspective (Hamill, Haddad & McDermott,
284 2000; Kurz & Stergiou, 2004). The dynamical systems theory suggests that
285 variations in movement patterns are attributable to the neuromuscular junction's
286 response to global (changes in the environment of task) and local perturbations
287 (joint flexion and proprioception) (Kurz & Stergiou, 2004) and proposes that when
288 the neuromuscular system is globally or locally perturbed, it will spontaneously
289 return to a stable state of equilibrium after the perturbation subsides (Kurz &
290 Stergiou, 2004; Wilson et al., 2008).

291

292 Kinematic asymmetry in the current investigation did not appear to be related to
293 the lead leg side for wrist and elbow angles. For the shoulder, five gymnasts
294 demonstrated significant ($p < 0.005$) asymmetry at touchdown and take off. This
295 result is similar to that of Čuk and Marinšek (2013) who found that the more distal
296 joints of the lower extremity (ankle and knee) were less affected than the hip for
297 landing kinematics. They found that the uneven load of the legs (whole leg chain)
298 was mostly expressed in the hips due to their weight bearing capacity. This fact
299 is also true for the shoulder joint, at this joint the gymnast has the ability to adjust
300 their movement profile and as such, kinematics at this joint provide the greatest
301 asymmetry. Furthermore, the greater asymmetry at the shoulders may represent

302 a compensatory mechanism to allow the increased symmetry at the more distal
303 segments. The kinematic values obtained at touchdown were larger for the
304 opposite side to the lead leg and take off values were larger for the lead leg side.
305 This may represent the unbalanced distribution of force absorption at initial
306 contact and the force required to propel the athlete to a landing position (Čuk &
307 Marinšek, 2013)

308

309 It was hypothesised in the current investigation that gymnast-specific asymmetry
310 profiles would exist, influenced by the individual technique employed. Indeed, the
311 individual nature of asymmetry was highlighted by the fact that no two participants
312 displayed identical asymmetric profiles for the same kinematic or kinetic variables.
313 This led to the hypothesis being accepted. Three gymnasts exhibited significant
314 asymmetry for timing of maximum force (greatest symmetry angle value 25.11%).
315 Furthermore, four gymnasts (1, 3, 4 & 5) displayed significant asymmetry for four
316 or more of the eight kinematic variables. The profiles displayed in Figure 2
317 highlight the individual nature of the kinetic asymmetry, in particular for Fz. The
318 Fz profile produced by Gymnast 4 was the most asymmetrical, this finding was
319 also reflected by the discrete results, where both timing and magnitude were
320 significantly asymmetrical and asymmetry values were larger than for the other
321 gymnasts. Exell, Irwin et al. (2012) also discovered diverse variability between
322 athletes during sprint running. The individual nature of variables displaying
323 significant asymmetry makes profiling of such movements very difficult. This
324 reinforces the recommendation of a single participant design (Dufek, Bates,
325 Stergiou, & James, 1995) when analysing asymmetry data.

326

327 **5. CONCLUSIONS**

328 This study aimed to increase understanding of the kinematic and kinetic
329 asymmetry of the arm segments during the contact phase of the forward
330 handspring on floor. The main findings include significant external kinetic
331 asymmetries during the hand contact from touch down to take off and a possible
332 compensatory mechanisms with decreased asymmetry from proximal to distal
333 segments. Future research in this area could investigate the complex interaction
334 of joint kinetic asymmetries to identify any potential within-limb compensatory
335 mechanisms that may be employed. The results of this study provide new
336 information regarding the understanding of gymnastics skills, which may
337 subjectively appear to be symmetrical but that display significant asymmetry.
338 These findings and their implications could provide useful information to coaches,
339 biomechanists and clinicians.

340

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458

459 **TABLES**

460 **Table 1**

461 Individual gymnast results for maximum vertical (Fz) and antero-posterior (Fy)
 462 ground reaction forces.

Gymnast:	Time of maximum	Maximum	Time of maximum	Maximum
side	Fz (% of ground	Fz (BW)	Fy (% of ground	Fy (BW)
	contact)		contact)	
1: Lead	20.9 (5.1)	0.93 (0.16)	13.8 (8.3)	-0.26 (0.09)
Non-lead	20.7 (4.4)	0.96 (0.22)	16.7 (8.6)	-0.23 (0.10)
2: Lead	16.1 (2.6)	1.22 (0.17)	16.5 (2.4)	-0.36 (0.09)
Non-lead	16.7 (2.4)	0.95 (0.19)	16.9 (2.5)	-0.32 (0.09)
3: Lead	15.9 (2.1)	0.82 (0.14)	16.1 (2.1)	-0.28 (0.05)
Non-lead	20.4 (6.2)	0.66 (0.19)	12.5 (3.2)	-0.25 (0.05)
4: Lead	34.7 (10.3)	0.70 (0.10)	11.0 (3.9)	-0.27 (0.04)
Non-lead	23.3 (11.3)	0.50 (0.07)	4.5 (1.3)	-0.29 (0.03)
5: Lead	13.7 (1.5)	1.30 (0.13)	13.4 (1.6)	-0.44 (0.07)
Non-lead	22.5 (5.6)	1.19 (0.07)	12.4 (2.3)	-0.41 (0.04)
6: Lead	14.6 (2.1)	1.61 (0.23)	15.2 (2.0)	-0.57 (0.14)
Non-lead	13.7 (2.8)	2.09 (0.16)	14.2 (2.6)	-0.70 (0.15)

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465 **Table 2**

466 Individual gymnast symmetry angle (θ_{SYM}) values (%) and p values for magnitude
 467 and timing of maximum vertical (Fz) and antero-posterior (Fy) ground reaction
 468 forces.

Gymnast	Time of maximum Fz	Maximum Fz	Time of maximum Fy	Maximum Fy
1: θ_{SYM}	0.35	-1.05	-5.98	4.43
p	0.886	0.432	0.008	0.007
2: θ_{SYM}	-1.29	7.90	-0.64	3.43
p	0.146	0.000*	0.714	0.103
3: θ_{SYM}	-7.79	6.61	7.83	3.53
p	0.017	0.008	0.001*	0.068
4: θ_{SYM}	12.34	10.70	25.11	-2.18
p	0.004*	0.000*	0.000*	0.085
5: θ_{SYM}	-15.29	2.84	2.47	1.65
p	0.000*	0.011	0.181	0.177
6: θ_{SYM}	1.95	-8.18	-6.31	2.16
p	0.176	0.000*	0.000*	0.078

Positive θ_{SYM} values = lead > non-lead, negative values = non-lead > lead

* = significant asymmetry

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473 **Table 3**

474 Individual gymnast wrist, elbow and shoulder joint angles at instants of
475 touchdown (TD) and take off (TO) for lead and non-lead sides.

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Gymnast	Wrist		Elbow		Shoulder	
	TD	TO	TD	TO	TD	TO
1: Lead	144 (3)	138 (6)	158 (7)	171 (2)	130 (7)	149 (2)
Non-lead	134 (3)	140 (4)	155 (7)	165 (4)	139 (9)	142 (3)
2: Lead	141(4)	130 (3)	157 (2)	156 (3)	123 (4)	143 (2)
Non-lead	142(3)	132 (5)	161 (3)	155 (3)	136 (4)	133 (5)
3: Lead	129 (2)	124 (1)	151 (3)	149 (3)	123 (4)	154 (2)
Non-lead	128 (2)	120 (2)	147 (7)	140 (5)	135 (7)	129 (2)
4: Lead	118 (2)	119 (2)	154 (2)	154 (2)	139 (2)	140 (2)
Non-lead	125 (2)	125 (2)	146 (1)	146 (1)	130 (2)	130 (2)
5: Lead	159 (2)	162 (2)	157 (2)	163 (3)	122 (3)	139 (4)
Non-lead	142 (3)	149 (3)	155 (6)	158 (4)	143 (10)	132 (3)
6: Lead	162 (3)	170 (5)	165 (5)	173 (7)	154 (6)	149 (5)
Non-lead	152 (3)	160 (2)	165 (6)	171 (2)	150 (8)	141 (5)

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Table 4

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Individual gymnast asymmetry magnitude (θ) and p values for wrist, elbow and

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shoulder joint angles at instants of touchdown (TD) and take off (TO).

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Gymnast	Wrist		Elbow		Shoulder	
	TD	TO	TD	TO	TD	TO
1: θ ($^{\circ}$)	10.3	-1.5	3.5	6.2	-9.0	7.0
p	0.000*	0.127	0.143	0.000*	0.000*	0.000*
2: θ ($^{\circ}$)	-1.1	-1.8	-4.1	0.8	-13.6	10.2
p	0.083	0.214	0.011	0.539	0.000*	0.000*
3: θ ($^{\circ}$)	1.2	4.1	3.4	9.17	-11.8	25.0
p	0.068	0.000*	0.029	0.000*	0.000*	0.000*
4: θ ($^{\circ}$)	-7.2	-6.7	8.5	8.4	-9.3	9.5
p	0.000*	0.000*	0.000*	0.000*	0.000*	0.000*
5: θ ($^{\circ}$)	17.8	13.3	2.4	4.6	-21.5	6.8
p	0.000*	0.000*	0.171	0.002*	0.000*	0.000*
6: θ ($^{\circ}$)	9.9	10.2	0.1	2.0	4.1	7.9
p	0.000*	0.000*	0.976	0.256	0.490	0.000*

Positive θ values = lead > non-lead, negative values = non-lead > lead

* = significant asymmetry

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488 **FIGURES**

489 Figure 1. Diagram showing the experimental set up.

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491 Figure 2. Mean [\pm SD] vertical and antero-posterior ground reaction force profiles
492 for all gymnasts. Black = lead side, grey = non-lead side.

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