

GPU-accelerated Immersed Boundary Method for the efficient simulation of biomedical fluid-structure interactions

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Background: the AV-FLOW Project

High-Performance Numerical Simulation of Fluid-Structure Interaction in the aortic heart valve system.

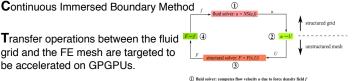
Crucial role in medical device implantation in case of aortic valve disease.

Challenging due to pulsatile turbulent blood flow and elastodynamical behaviour of soft tissue.

Immersed Boundary Method is widely used to avoid expensive mesh-fitting operation of the fluid domain.

Scalable highly accurate incompressible flow solver (IMPACT) simulates the complex blood flow. The elastodynamic deformation of soft tissue is simulated in a dedicated parallel FEM solver (PASSO).

Transfer operations between the fluid grid and the FE mesh are targeted to be accelerated on GPGPUs.



Sharp Interface Immersed Boundary Method

Flow simulation in moving 3D complex geometries on a Eulerian fluid mesh Sharp-Interface Method is extensively used for biomedical FSI simulations Ghost Cell Methodology for Immersed Boundary treatment^a







No need for conforming mesh, but the IB treatment is still expensive! Remedy: Computational Geometry operations can be accelerated on GPUs.

Turbulent incompressible flow through an array of

30 rigid cylinders (Re=10000).

Considerations:

Results

- 1. CPU-GPU data bandwidth is limited
- 2. More operation on staggered grid
- 3. Dynamic allocation is crucial for moving boundaries
- 4. Parallel reduction is restricted by the "shared memory"
- 5. Double percision accuracy not achievable on all threads

IBM on GPU

General Purpose Graphical Processing Units(GPGPU)

Accelerating floating point operations in shared memory paradigm.

 ${f T}$ housands of parallel threads can be executed on GPU.

Maximum GPU capacity should be utilized to hide the memory-latency.

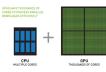
Tesla K20x GPUs on Cray XC30 machine(CSCS-Piz Daint):

14 multiprocessors 5.6GB GDDR5 memory

max 2048 threads per multiprocessor

max 1024 threads per block







Implementation (CUDA FORTRAN by PGI)

CUDA vs. OpenACC

Higher speedup!

Strong scaling (vs. pragma) More programming effort Knowledge of hardware Tuned choice of thread blocks



Extensive IB computations due to:

High-resolution grid for resolving the turbulent flow

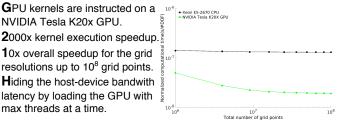
Large and discrete solid-fluid interface

Staggerred grid in the flow solver

Speedup Measurement

NVIDIA Tesla K20x GPU. 2000x kernel execution speedup. 10x overall speedup for the grid resolutions up to 108 grid points.

Hiding the host-device bandwith latency by loading the GPU with max threads at a time.



Acknowledgment

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Multi-beat simulation of of turbulent incompressible flow through a mechanical valve (Re=3000).



