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5 *Technical Note*

## 6 **An alternative method to Niskin sampling for** 7 **molecular analysis of the marine environment.**

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17 **Abstract:** The development of low-cost, open-source Remotely Operated Vehicle (ROV) systems has  
18 provided almost unrestricted access for researchers looking to monitor the marine environment in  
19 ever greater resolution. Sampling microbial communities from the marine environment, however,  
20 still usually relies on Niskin-bottle sampling (ROV or CTD based), a method which introduces an  
21 inaccuracy and variability that is incompatible with metatranscriptomic analysis, for example. Here,  
22 we describe a versatile, easily-replicated platform which achieves *in situ* mRNA preservation, via  
23 the addition of RNAlater to filtered microbial cells, to enhance ROV or CTD functionality.

24 **Keywords:** Remotely Operated Vehicle; Metatranscriptomics; Niskin

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27 Based on the modified Nansen bottle (invented in 1894); the Niskin bottle (1967), invented just  
28 a few years after the discovery and characterisation of mRNA, was developed for the retrieval of  
29 seawater samples to the surface (Hill, 1900; Niskin, 1966; Cobb, 1990) [1-3]. Traditional Niskin  
30 sampling still dominates oceanic analysis, while metatranscriptomic (whole community mRNA  
31 profiling) based techniques have revolutionised our understanding of the function of mixed  
32 community assemblages at the molecular level (Gilbert et al, 2011) [4]. Together, they have provided  
33 a much needed insight on the fundamental workings of global biogeochemical cycling. However,  
34 while metatranscriptomics suffers from a necessity to reduce technical variation as much as possible  
35 to allow meaningful interpretation of results, it is stifled by the inaccuracy and variability that is  
36 irrevocably associated with current Niskin-based sampling methods. Whilst cellular mRNA profiles  
37 can respond to environmental insults within milliseconds, the mandatory transcriptional alterations  
38 induced by Niskin sampling, which subjects samples to unavoidable exposure to differences in  
39 pressure, temperature and light, in addition to the inherent temporal delay, is difficult to circumvent.  
40 This irreconcilable observation has stimulated the development of many *in situ* profiling technologies  
41 for the marine environment (Feike et al, 2012; Taylor et al, 2015; McQuillan and Robidart, 2017) [5-7],  
42 however these solutions have not gained dominance or widespread use as yet, primarily due to cost  
43 restrictions.

44 In tandem to the dawning realisation that the majority of current marine transcriptomic and  
45 metatranscriptomic analyses are inherently inaccurate, the development of low cost open source ROV  
46 systems has provided easy access (to the top 100 metres of the ocean at the very least) for researchers  
47 looking to monitor, and sample, the marine environment in ever greater resolution. Whilst utilising

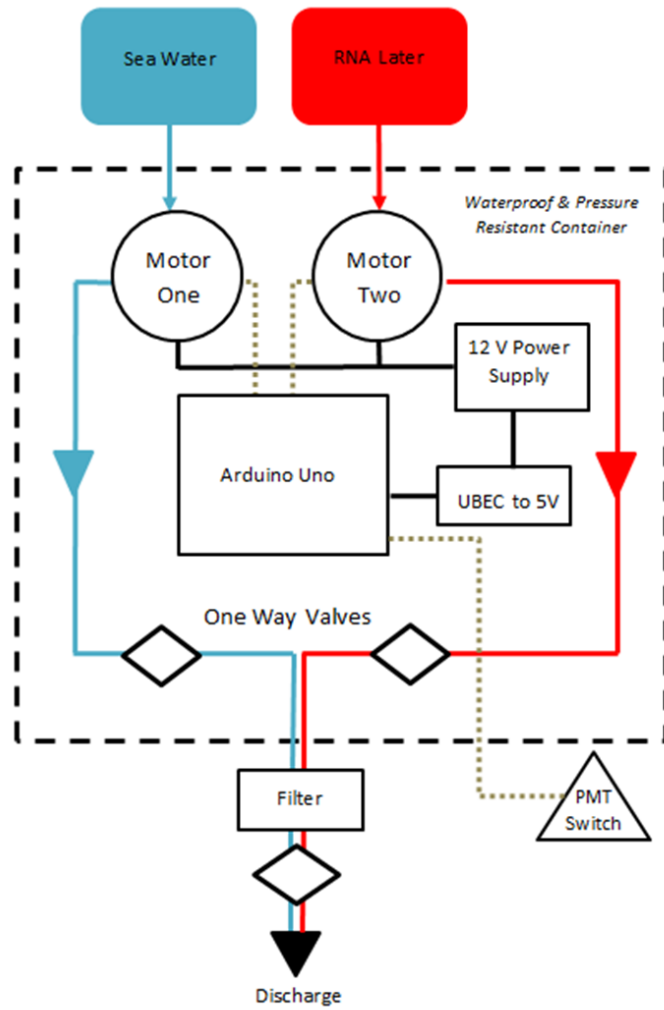
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48 an ROV mounted Niskin system to study metatranscriptomic profiles, we were struck by the contrast  
49 between the antiquated nature of this traditional and inaccurate sampling technique, and the low  
50 cost, high-performance simplicity of the ROV system upon which it was mounted. To this end, we  
51 looked to develop a versatile, easily replicated RNA sampling platform (“RNA Automated  
52 Preservation *in situ* Device, RAPID”) inspired by low-cost, high-performance and simplicity. It is  
53 well established that *in situ* mRNA preservation can be achieved rapidly and simply through the  
54 addition of RNAlater to microbial cells (Ottesen et al, 2011) [8].

55 With this premise in mind, we looked to design a system that could both concentrate and  
56 preserve samples in a rapid, simple and low cost manner. Utilising off the shelf components we  
57 assembled and tested an Arduino (Leonardo) controlled dual pump system [9], capable of pushing  
58 seawater through a suitable filter unit, prior to the delivery of RNAlater (Figure 1). With motors and  
59 electronics encased and powered from 12V supply (4 × AA batteries) within a permanently sealed  
60 waterproof junction box (Model: a16030800ux0347, SourcingMap) (Figure 2), and filtration units and  
61 RNAlater reservoir (saline drip bag [Model: GMEPN-UK-72813179, Amazlabs]) external for easy  
62 replacement and retrieval, our system was mounted on an OpenROV (rated to 100m depth) for  
63 testing. Pumps were mounted alongside each other and tubing joined via a T-junction with one-way  
64 valves (Model: 1024989, Carparts online) attached to the (external) Millipore Swinnex 25 mm filter  
65 assembly. Initial trials with centrifugal pumps (adapted from a NERF Electrostorm water pistol)  
66 revealed rapid degradation of internal components exposed to seawater and RNAlater, so we  
67 favoured a peristaltic pump option (Model: A518, ZJchao). Any filter assembly (and filter type)  
68 capable of withstanding pressure can be used (we have utilised 25 mm and 47 mm filter assemblies,  
69 as well as the Sterivex system). The Arduino was mounted on the lid of the box, so that in the situation  
70 of structural integrity being lost, water damage to the circuit would be minimised (total immersion  
71 in silicon oil is another simple way to reduce pressure effects). Nevertheless, replacement of the  
72 junction box with a more robust structure may be necessary to go beyond 100 m depth. Whilst we  
73 developed here a single filter sample system, the addition of simple controlled distribution valves  
74 will provide the opportunity for numerous samples to be taken and preserved in procession.  
75 Following activation of pump 1, seawater is pushed through the filter assembly at a rate of ~2.5 ml/s  
76 (we achieved filtration of ~500 ml through a 0.22 µm Sterivex Filter in 4 minutes), applying different  
77 filters varies the rate of flow, as does biomass accumulation on the filter, until pump 2 is engaged for  
78 a 10 s flooding with ~27 ml of RNAlater. Although not instantaneous, the sample is not subjected to  
79 any temperature, pressure and/or light variation (unless the ROV is operated to specifically induce  
80 such conditions) and filtration/preservation is performed rapidly *in situ*. This potentially represents  
81 a significant improvement in both accuracy of transcript profiles and rapidity in comparison with  
82 current sampling procedures which usually rely on a delay for filtering on board ship following  
83 sample retrieval.

84 For samples where it is crucial to preserve the transcriptional profile immediately, pumps 1 and  
85 2 can be run simultaneously to bring RNAlater into contact with the seawater immediately prior to  
86 filtration or bag collection. Following retrieval of the ROV to the surface and RNA extraction in the  
87 laboratory, no difference was observed in quality or quantity of total RNA obtained by Niskin or the  
88 on board system (Figure 3), thereby proving the principle that sampling via systems of this type can  
89 provide sufficient and suitable RNA, which is by virtue of its processing more representative of the  
90 natural environment from which it is taken. In addition to costing less than £50 to build and being  
91 small enough to mount on low-cost, entry-level ROV systems (which provide visualisation, easy  
92 maneuverability, and often accurate depth and temperature data, in real time and therefore with the  
93 opportunity for responsive action), such a system can also be utilised in conjunction with more  
94 established CTD instrumentation. In the spirit of the open source ethos, we invite others to join us  
95 and take up the challenge in testing and developing improved versions of this versatile system that  
96 has the potential to revolutionise the molecular analysis of the marine environment [11].

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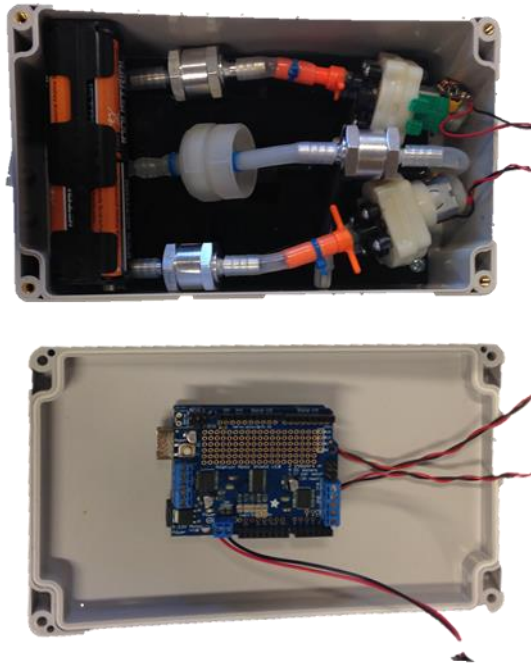


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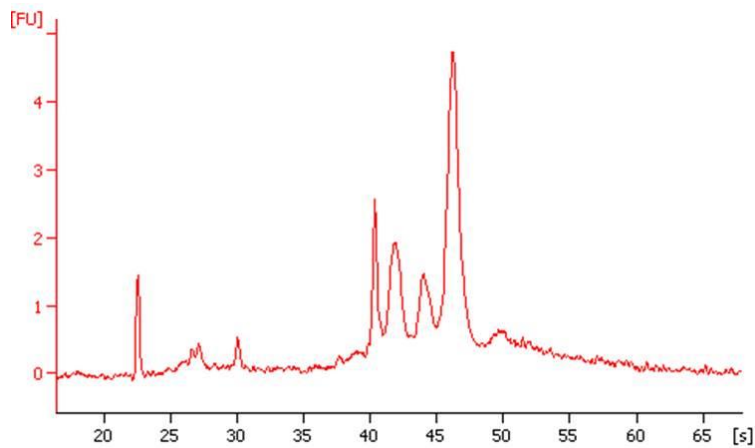
**Figure 1.** Configuration of Nucleic Acid Preservation device. RNALater is stored within a saline drip bag to minimise pressure effects. Proximal and distal one way valves serve to ensure filter remains immersed in RNALater following preservation. Dashed line denotes components contained within pressure and water resistant shell.

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**Figure 2.** Components within the casing and their configuration (Prototype 1, with Electrostorm motors). L200 × W120 × D76 mm



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112 **Figure 3.** RNA (112 ng/μl; RIN 28S:18S score, 8.0) extracted from approximately 500 ml of natural seawater from  
113 Plymouth Sound preserved by RAPID sampling, analysed by Agilent Bioanalyser.

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118 **Author Contributions:** M.J.A and J.T. conceived and designed the experiments; J.T. performed the experiments;  
119 M.J.A, J.T., S.S., G.G. and T.S. analyzed the data; M.J.A, J.T., G.G., S.S. and T.S. contributed  
120 reagents/materials/analysis tools; M.J.A and J.T. wrote the paper.

121 **Conflicts of Interest:** The authors declare no conflict of interest.

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