

CDMA BLIND CHANNEL EQUALIZATION: A WEIGHTED SUBSPACE APPROACH

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Abstract - This paper considers the problem of blind demodulation of multiuser information symbols in a direct-sequence code-division multiple access (DS-CDMA) environment. Channel estimation and symbol detection in presence of both multiple access interference (MAI) and intersymbol interference (ISI) is carried out with second order statistics methods from the received data. This problem is similar to Direction Of Arrival (DOA) estimation, where many solutions like the *MUSIC* algorithm or "weighted" techniques (as *Deterministic Maximum Likelihood* or *Weighted Subspace Fitting* method) have been developed. In this proposal these techniques are extended to blind DS-CDMA channel identification problem in an unified framework known as *Subspace Fitting*. In this framework the estimated and the received data are "fitting" through the subspaces in a least square sense. Then, in order to achieve a better estimation of the channel, a modified Gauss-Newton type algorithm is suggested. Simulations are carried out comparing the proposed solutions with a classical signal subspace-based blind channel identification scheme.

I. INTRODUCTION

There is actually a growing interest in the design of high-rate DS-CDMA networks. This kind of digital communications are subjected to intersymbol interference (ISI) (due to channels with multipath phenomena) and multiple-access interference (MAI) (which is inherent to any nonorthogonal CDMA system). These problems can be so severe that correct reception of the transmitted symbols is not feasible anymore. It is necessary therefore to equalize the channel, suppressing jointly both MAI and ISI.

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Since Tong, Xu and Kailath showed in [1] that it is possible to obtain an estimation of the channel from a second order statistic of the received signal, second order statistics have showed its usefulness in channel estimation. Subspace-based methods are based on the singular value decomposition (SVD) of a matrix constructed from the observed signal, which provides a robust discrimination between desired and disturbing signals in terms of signal and noise subspaces. In particular, several works (see [2] and references therein) have addressed the use of MUSIC-type methods for parameter estimation in CDMA systems.

The general objective is to find a low-rank subspace with a shift structure that has minimal distance to the true signal space, or equivalently, that is as orthogonal to the noise subspace as possible. Viberg and Ottersten formulate in [4] different methods in a common subspace fitting based framework, providing an overview of the DOA estimation problem and clarifying the algebraic relations between the algorithms.

In this contribution we focus on *MUSIC* [3], *WSF* [4] and *MDL* [6] algorithms. These methods are summarized and adapted to blind channel identification in a subspace fitting approach. The paper is organized as follows. In Section II signal model of a DS/SS CDMA system and its subspace approach are formulated. Blind channel identification method for DS-CDMA proposed by [2] is also outlined. In Section III we extend the subspace-fitting framework proposed by Viberg [4] to blind DS-CDMA channel identification. The cost functions whose minimization/maximization will allow estimating the channel are then formulated. After that, the Gauss-Newton algorithm for blind channel identification [8] is outlined. In section IV some simulation results are presented and discussed. Finally, we present some conclusions and outline future work in section V.

II. PROBLEM FORMULATION

Signal Model

Consider a K -user binary communication system through a Gaussian channel. Let $s_k(n)$ denote the k th user transmitted symbol at time nT (where T is the symbol duration) and $\{c_k(j)\}$ be the signature sequence of $M \pm 1$'s assigned to the user. The transmitted signal due to the k th user is:

$$x_k(t) = A_k \cdot \sum_{n=0}^{N_s-1} s_k(n) \sum_{j=1}^M c_k(j) \cdot p(t - nT - jT_c - \tau_k) \quad 0 \leq t \leq T \quad (1)$$

Where N_s is the number of transmitted symbols, M is the processing gain, $p(t)$ is a normalized chip waveform of duration $T_c = T/M$ and A_k and τ_k denote, respectively, the amplitude and delay of k th user. The resulting signal thorough a time-invariant channel $h_k(t)$ is:

$$x_k(t) = A_k \cdot \sum_{n=0}^{N_s-1} s_k(n) \sum_{j=1}^M c_k(j) \cdot \bar{h}_k(t - nT - jT_c) \quad 0 \leq t \leq T \quad (2)$$

With $\bar{h}_k(t) = p(t - \tau_k) * h_k(t)$; $\bar{h}_k(t) \neq 0 \quad \forall t \in [0, L_k \cdot T]$.

The signal is filtered with the chip-matched filter and sampled at the chip rate T_c . The resulting discrete-time signal component due to the k th user at the i th chip period of the n th symbol interval will be:

$$y_{ik}(n) = \sum_{l=0}^{L_k} s_k(n-l) \cdot h_{ik}(l) \quad i = 1..M; k = 1..K; \quad (3)$$

With

$$f_k(m) = \int_0^{T_c} \bar{h}_k(t + mT_c) \cdot p(t) dt \quad 0 \leq m \leq (L_k + 1) \cdot M - 1 \quad (4)$$

$$h_{ik}(l) = h_k(lM + i); \quad h_k(m) = A_k \cdot \sum_{j=1}^M c_k(j) \cdot f_k(m-j) \quad 0 \leq m \leq (L_k + 1) \cdot M \quad (5)$$

The received discrete-time signal at the i th chip period of the n th symbol interval is then:

$$r_i(n) = y_i(n) + \bar{v}_i(n) \quad y_i(n) = \sum_{k=1}^K y_{ik}(n) \quad (6)$$

With $\bar{v}_i(n)$ the filtered AWGN noise. Defining the following matrix and vectors [2]:

$$\mathbf{r}(n) = \begin{bmatrix} r_1(n) \\ \vdots \\ r_M(n) \end{bmatrix}_{M \times 1}; \quad \mathbf{y}(n) = \begin{bmatrix} y_1(n) \\ \vdots \\ y_M(n) \end{bmatrix}_{M \times 1}; \quad \mathbf{v}(n) = \begin{bmatrix} v_1(n) \\ \vdots \\ v_M(n) \end{bmatrix}_{M \times 1}$$

$$\mathbf{H}(n) = \begin{bmatrix} h_{11}(n) & \cdots & h_{1K}(n) \\ \vdots & \ddots & \vdots \\ h_{M1}(n) & \cdots & h_{MK}(n) \end{bmatrix}_{M \times K}; \quad \mathbf{s}(n) = \begin{bmatrix} s_1(n) \\ \vdots \\ s_K(n) \end{bmatrix}_{K \times 1} \quad (7)$$

By stacking W successive samples of the received data we have the $MW \times 1$ vectors:

$$\mathbf{y}_W(n) = \mathbf{H}_W \cdot \mathbf{s}_W(n) \quad \mathbf{r}_W(n) = \mathbf{y}_W(n) + \mathbf{v}_W(n) \quad (8)$$

With:

$$\mathbf{H}_W = \begin{bmatrix} \mathbf{H}(L) & \cdots & \mathbf{H}(0) & \mathbf{0} & \cdots & \mathbf{0} \\ \vdots & & \ddots & & \ddots & \vdots \\ \mathbf{0} & \cdots & \mathbf{0} & \mathbf{H}(L) & \cdots & \mathbf{H}(0) \end{bmatrix}_{MW \times K(W+L)} \quad (9)$$

$$\mathbf{s}_W(n) = \begin{bmatrix} \mathbf{s}(n-L) \\ \vdots \\ \mathbf{s}(n+W-1) \end{bmatrix}_{K(W+L) \times 1}; \quad \mathbf{y}_W(n) = \begin{bmatrix} \mathbf{y}(n) \\ \vdots \\ \mathbf{y}(n+W-1) \end{bmatrix}_{MW \times 1}$$

$$\mathbf{r}_W(n) = \begin{bmatrix} \mathbf{r}(n) \\ \vdots \\ \mathbf{r}(n+W-1) \end{bmatrix}_{MW \times 1}; \quad \mathbf{v}_W(n) = \begin{bmatrix} \mathbf{v}(n) \\ \vdots \\ \mathbf{v}(n+W-1) \end{bmatrix}_{MW \times 1} \quad (10)$$

and L the maximum of $\{L_k\}$.

We will process a block of P received data. We can define the following block Hankel matrices:

$$\mathbf{R}_W = [\mathbf{r}_W(1) \quad \mathbf{r}_W(2) \quad \cdots \quad \mathbf{r}_W(P-W+1)]_{MW \times (P-W+1)}$$

$$\mathbf{Y}_W = [\mathbf{y}_W(1) \quad \mathbf{y}_W(2) \quad \cdots \quad \mathbf{y}_W(P-W+1)]_{MW \times (P-W+1)}$$

$$\mathbf{S}_W = [\mathbf{s}_W(1) \quad \mathbf{s}_W(2) \quad \cdots \quad \mathbf{s}_W(P-W+1)]_{K(W+L) \times (P-W+1)} \quad (11)$$

and then (8) can be rewritten as:

$$\mathbf{Y}_W = \mathbf{H}_W \cdot \mathbf{S}_W \quad \mathbf{R}_W = \mathbf{Y}_W + \mathbf{N}_W \quad (12)$$

Since the received signal is sampled at M times the baud rate, the resulting discrete signal becomes a wide-sense cyclostationary process, which allows to recover the phase of the channel from second order statistics as showed Tong, Xu and Kailath [1]. On the other hand, to assure identifiability, \mathbf{H}_W should have full column rank. Conditions under this occur can be found in [2] **Error! Unknown switch argument.**

Subspace Approach

The additive noise $\bar{v}_i(n)$ is modeled as a Gaussian, stationary, white and zero mean random process. The covariance matrix of the received signal is:

$$\mathbf{C}_{RR} = E[\mathbf{R}_W \cdot \mathbf{R}_W^H] = \mathbf{H}_W \cdot \mathbf{H}_W^H + \sigma^2 \mathbf{I}_{MW} \quad (13)$$

Where the function $E[\cdot]$ denotes mathematical expectation and superscript H is the hermitic operator. We assume that each user's information symbols are independently identically distributed and the symbol streams of different users are independent: $E[\mathbf{S}_w \cdot \mathbf{S}_w^H] = \mathbf{I}_r$, with $r = K(W+L)$.

The signal subspace is defined as the space spanned by columns of \mathbf{H}_w , and the noise subspace is its orthogonal complement. Both subspaces can be obtained from the SVD of covariance matrix:

$$\mathbf{C}_{RR} = \mathbf{U} \Lambda \mathbf{U}^H = [\mathbf{U}_s \quad \mathbf{U}_o] \begin{bmatrix} \Lambda_s & \\ & \Lambda_o \end{bmatrix} [\mathbf{U}_s \quad \mathbf{U}_o]^H \quad (14)$$

With $\Lambda_s = \text{diag}(\lambda_1 \dots \lambda_r)$, $\lambda_i > \sigma^2$ for $i=1, \dots, r$ (signal eigenvalues) and $\Lambda_o = \text{diag}(\lambda_{r+1} \dots \lambda_{MW})$, $\lambda_i = \sigma^2$ for $i=r+1, \dots, MW$ (noise eigenvalues). The $MW \times r$ matrix \mathbf{U}_s and the $MW \times MW-r$ matrix \mathbf{U}_o are:

$$\mathbf{U}_s = [\mathbf{u}_1 \quad \dots \quad \mathbf{u}_r]; \quad \mathbf{U}_o = [\mathbf{u}_{r+1} \quad \dots \quad \mathbf{u}_{MW}] \quad (15)$$

Since columns of \mathbf{U}_s span the signal subspace and columns of \mathbf{U}_o the noise subspace, orthogonality between subspaces provides:

$$\mathbf{u}_{o,i}^H \cdot \mathbf{H}_w = 0 \quad \text{for } i=1, \dots, MW-(W+L) \quad (16)$$

Blind channel estimation in DS-CDMA

The following subspace algorithm is an extension of the method developed in [3] to multiple input signals. Let $\mathbf{U}_o^H = [\mathbf{U}_1^H \quad \dots \quad \mathbf{U}_r^H]$, where \mathbf{U}_i^H is the i th $(MW-r) \times M$ partition of \mathbf{U}_o^H , we define the $M(L+1) \times K$ matrix \mathbf{H} and the $(MW-r)(W+L) \times M(L+1)$ matrix \mathbf{G} as:

$$\mathbf{H} = \begin{bmatrix} \mathbf{H}(0) \\ \vdots \\ \mathbf{H}(L) \end{bmatrix}; \quad \mathbf{G} = \begin{bmatrix} \mathbf{U}_w^H & & & \mathbf{U}_w^H \\ \vdots & \ddots & & \vdots \\ \mathbf{U}_1^H & \dots & \dots & \mathbf{U}_1^H \end{bmatrix} \quad (17)$$

Then (16) can be rewritten as:

$$\mathbf{U}_o^H \cdot \mathbf{H}_w = 0 \Leftrightarrow \mathbf{G} \cdot \mathbf{H} = 0 \quad (18)$$

If \mathbf{G} has more rows than columns, then its right null subspace specifies \mathbf{H} up to a nonsingular ambiguity $K \times K$ matrix factor, i.e.: $\hat{\mathbf{H}} = \mathbf{H} \cdot \mathbf{D}$. To further solve this ambiguity, the finite alphabet property of the input data has to be exploited, which is prohibitively expensive. In order to overcome this problem, Wang incorporated in [2] the spreading signatures.

Let denote the $M(L+1) \times m_f$ matrix of the composite signature of the k th user \mathbf{C}_k as:

$$\mathbf{C}_k = \begin{bmatrix} c_k(1) & & & \\ \vdots & \ddots & & \\ c_k(M) & & c_k(1) & \\ & & \vdots & \\ & & & c_k(M) \end{bmatrix} \quad (19)$$

With m_f the channel response length of $f_k(m)$ in (4); having that $\mathbf{H} = [\mathbf{h}_1 \quad \mathbf{h}_2 \quad \dots \quad \mathbf{h}_K]$, we can rewrite (5) as:

$$\mathbf{h}_k = A_k \mathbf{C}_k \mathbf{f}_k \quad \text{with} \quad \mathbf{f}_k = \begin{bmatrix} f_k(0) \\ \vdots \\ f_k(m_f-1) \end{bmatrix}_{m_f \times 1} \quad (20)$$

Then, from (18) we have that:

$$\mathbf{G} \cdot \mathbf{H} = 0 \Rightarrow \mathbf{G} \cdot \mathbf{h}_k = A_k \cdot \mathbf{G} \cdot \mathbf{C}_k \cdot \mathbf{f}_k = 0 \quad (21)$$

And therefore, the right null vector of $\mathbf{G} \cdot \mathbf{C}_k$ is \mathbf{f}_k up to an ambiguity scalar factor.

III. WEIGHTED SUBSPACE FITTING

Cost functions

Since covariance matrix \mathbf{C}_{RR} is in practice estimated from a limited amount of received data, only an approximation of \mathbf{C}_{RR} is available. Then, (21) has to be solved in a least square sense. Adapting to blind channel identification the basic subspace fitting problem in DOA estimation proposed by Viberg & Ottersen [4], we have that, given some representation of the data \mathbf{M} , we should to find an estimation of \mathbf{H} and \mathbf{T} such that

$$\mathbf{H}, \mathbf{T} = \arg \min_{\mathbf{H}, \mathbf{T}} \|\mathbf{M} - \mathbf{H}_w(\mathbf{H}) \cdot \mathbf{T}\|_F^2 \quad (22)$$

Where $\|\cdot\|_F^2$ is the quadratic Froebius norm. This is a separable problem, and substituting the solution of the first part, $\mathbf{T} = \mathbf{H}_w^+ \cdot \mathbf{M}$ into (22) (the superscript $+$ denotes the pseudoinverse operator), this gives the generic subspace fitting cost function:

$$\hat{\mathbf{H}} = \arg \min_{\mathbf{H}} V(\mathbf{H}) \quad \text{with}$$

$$V(\mathbf{H}) = \|(\mathbf{I} - \mathbf{P}_H) \cdot \mathbf{M}\|_F^2 = \text{Tr} \{ \mathbf{P}_H^\perp \cdot \mathbf{M} \cdot \mathbf{M}^H \} \quad (23)$$

Where $\mathbf{P}_H = \mathbf{H}_w \mathbf{H}_w^+$ is the LS projector onto the column space of \mathbf{H}_w , $\mathbf{P}_H^\perp = \mathbf{I} - \mathbf{P}_H$ is the orthogonal LS projector and $\text{Tr}\{\cdot\}$ denotes the trace operator. As \mathbf{M} is a representation of the data, different choices of \mathbf{M} will provide different cost functions (criteria).

MUSIC criterion.

The MUSIC criterion is based on orthogonality between signal and noise subspaces. The cost function derived from (16) can be written as:

$$\begin{aligned} V_{MUSIC}(\mathbf{H}) &= \sum_{i=1}^{MW-r} \|\hat{\mathbf{u}}_{o,i}^H \cdot \mathbf{H}_w\|^2 = \\ &= \|\hat{\mathbf{U}}_o^H \cdot \mathbf{H}_w\|_F^2 = \text{Tr} \{ \mathbf{H}_w^H \hat{\mathbf{U}}_o \hat{\mathbf{U}}_o^H \mathbf{H}_w \} \end{aligned} \quad (24)$$

This is the MUSIC cost function. Since in DOA problem (24) does not give accurate results when the signals are highly correlated, Schmidt **Error! Unknown switch argument.** introduced a normalization matrix $(\mathbf{H}_w^H \cdot \mathbf{H}_w)^{-1}$ into (24), resulting the *Multi-Dimensional (MD) MUSIC* algorithm:

$$\hat{\mathbf{H}} = \arg \min_{\mathbf{H}} V_1(\mathbf{H})$$

$$V_1(\mathbf{H}) = \text{Tr} \left\{ \left(\mathbf{H}_w^H \cdot \mathbf{H}_w \right)^{-1} \cdot \mathbf{H}_w^H \cdot \hat{\mathbf{U}}_o \cdot \hat{\mathbf{U}}_o^H \cdot \mathbf{H}_w \right\} =$$

$$= \text{Tr} \left\{ \mathbf{P}_H \cdot \hat{\mathbf{U}}_o \cdot \hat{\mathbf{U}}_o^H \right\} = \text{Tr} \left\{ \mathbf{P}_H \cdot (\mathbf{I} - \hat{\mathbf{U}}_s \cdot \hat{\mathbf{U}}_s^H) \right\} \quad (25)$$

As the trace of a projection operator is equal to the dimension of the subspace onto which it projects, minimizing $V_1(\mathbf{h})$ gives the same result that maximizing $V_2(\mathbf{H}) = \text{Tr} \left\{ \mathbf{P}_H \cdot \hat{\mathbf{U}}_s \cdot \hat{\mathbf{U}}_s^H \right\} = \text{Tr} \left\{ (\mathbf{I} - \mathbf{P}_H) \cdot \hat{\mathbf{U}}_s \cdot \hat{\mathbf{U}}_s^H \right\}$, and the cost function of *MD-MUSIC* algorithm will be:

$$\hat{\mathbf{H}} = \arg \min_{\mathbf{H}} V_{MD-MUSIC}(\mathbf{H})$$

$$V_{MD-MUSIC}(\mathbf{H}) = \text{Tr} \left\{ \mathbf{P}_H \cdot \hat{\mathbf{U}}_s \cdot \hat{\mathbf{U}}_s^H \right\} \quad (26)$$

Thus, the *MD-MUSIC* algorithm is a subspace fitting method where the representation of data is directly given by the signal subspace, $\mathbf{M} = \hat{\mathbf{U}}_s$.

Deterministic ML criterion.

Described by Böhme [6], this method try to maximize the log likelihood of the received data \mathbf{Y} with respect to \mathbf{H}_w and \mathbf{S} (the columns of the $MW \times N_e$ matrix \mathbf{Y} are the N_e snapshots $y(n)$ with $n=1..N_e$, and the columns of the $(W+L) \times N_e$ matrix \mathbf{S} are the N_e transmitted symbol vectors $s(n)$). This is equivalent to minimize the cost function $V_{MDL}(\mathbf{H}) = \|\mathbf{Y} - \mathbf{H}_w \cdot \mathbf{S}\|_F^2$. The solution of the first part is $\hat{\mathbf{S}} = \mathbf{H}_w^+ \cdot \mathbf{Y}$ and the cost function becomes:

$$\hat{\mathbf{H}} = \arg \min_{\mathbf{H}} V_{MDL}(\mathbf{H}) \text{ with } V_{MDL}(\mathbf{H}) = \text{Tr} \left\{ \mathbf{P}_H \cdot \mathbf{C}_{RR} \right\} \quad (27)$$

Connection with subspace fitting can be made using asymptotic arguments (see [4]). For large N_e , we have $\Lambda_o \rightarrow \sigma^2 \mathbf{I}$, $\mathbf{C}_{RR} \rightarrow \hat{\mathbf{U}}_s \cdot \tilde{\Lambda} \cdot \hat{\mathbf{U}}_s^H + \sigma^2 \cdot \mathbf{I}$ and $\tilde{\Lambda} = \Lambda_s - \sigma^2 \cdot \mathbf{I}$. As the trace of $\sigma^2 \mathbf{P}_H$ is a constant, the cost function is asymptotically (large N_e) equivalent to:

$$V_{MDL}(\mathbf{H}) = \text{Tr} \left\{ \mathbf{P}_H \cdot \hat{\mathbf{U}}_s \cdot \tilde{\Lambda} \cdot \hat{\mathbf{U}}_s^H \right\} \quad (28)$$

Therefore, the deterministic ML method is a subspace fitting technique where the data are represented by its weighted signal subspace $\mathbf{M} = \hat{\mathbf{U}}_s \cdot \mathbf{W}_{MDL}^{1/2}$; $\mathbf{W}_{MDL} = \tilde{\Lambda}$.

WSF criterion.

The *deterministic ML* method allows to us to introduce the weighted subspace-fitting concept. This is:

$$\hat{\mathbf{H}} = \arg \min_{\mathbf{H}} V_{WSF}(\mathbf{H})$$

$$\text{with } V_{WSF}(\mathbf{H}) = \text{Tr} \left\{ \mathbf{P}_H \cdot \hat{\mathbf{U}}_s \cdot \mathbf{W}_{WSF} \cdot \hat{\mathbf{U}}_s^H \right\} \quad (29)$$

Where \mathbf{W}_{WSF} is a positive definite weighting matrix. The question is to find a weighting matrix \mathbf{W}_{WSF} that makes the estimation statistically (for large N_e) efficient, i. e., that makes the *WSF* estimates asymptotically achieve the Cramer-Rao lower bound on the variance of the estimator error. Viberg and Ottersten [4] have shown that the optimal choice for \mathbf{W}_{WSF} is $\mathbf{W}_{WSF} = \tilde{\Lambda}^2 \Lambda_s^{-1}$. Thus, the *WSF* criterion can be expressed in (23) when the representation of the data is $\mathbf{M} = \hat{\mathbf{U}}_s \cdot \mathbf{W}_{WSF}^{1/2}$.

Modified Variable Projection Algorithm

The proposed technique in [8] is the *Modified Variable Projection (MVP)* method (see [7] and references therein) applied to (one user) blind channel identification. The criterion function in (23) must be minimized over the vector \mathbf{h} (for one emitter, matrix \mathbf{H} is a column vector). Consider the nonlinear least square problem given by (23); in the damped Newton scheme, \mathbf{h} is iteratively estimated with:

$$\mathbf{h}_{k+1} = \mathbf{h}_k - \mu_k \cdot \mathbf{G}^{-1} \cdot \mathbf{v} \quad (30)$$

With μ_k the step length, \mathbf{G} the Hessian matrix of the cost function and \mathbf{v} the gradient. Every iteration the Hessian and the gradient are evaluated in \mathbf{h}_k . If \mathbf{h} is well initialized, the Newton method guarantees an ultimate quadratic convergence to $\hat{\mathbf{h}}$.

Consider first the gradient of the cost function. The i th element of the gradient yields:

$$\mathbf{v}_i = \frac{\partial V}{\partial h_i} = -2 \text{Tr} \left\{ \mathbf{H}_i^H \cdot \mathbf{P}_H \cdot \mathbf{M} \cdot \mathbf{M}^H \cdot (\mathbf{H}_w^+)^H \right\} \quad (31)$$

Consider now the Hessian matrix, the ij th component of the *approximate* (a Kaufmann's modification is applied to the algorithm, see [7]) Hessian matrix is:

$$\mathbf{G}_{ij} = 2 \text{Tr} \left\{ \left[(\mathbf{H}_w^+)^H \cdot \mathbf{H}_i^H \cdot \mathbf{P}_H \cdot \mathbf{H}_j^H \cdot \mathbf{H}_w^+ \right] \cdot \mathbf{M} \cdot \mathbf{M}^H \right\} \quad (32)$$

Then, (30), (31) and (32) give the *MVP* algorithm (derivation of (31) and (32) can be found in [7] and [8]). In order to obtain a good initialization of the estimates, we can use the MUSIC algorithm, which will allow to achieve a global minimum. The step length

factor should be chosen in order to guarantee global convergence. It is known that quadratic convergence of Newton-type algorithms is only achieved if the step length factor converges to unity.

IV. SIMULATION RESULTS

A 50 Monte Carlo simulation is carried out in order to evaluate the performance of the weighted subspace algorithms in a digital DS-CDMA communication system. The $K=5$ users emit a burst of $N_s=128$ BPSK symbols. The Gold signature sequence has $M=15 \pm 1$'s (i.e. $T_c=T/15$). The highest order of the channels (ISI) is set to $L=2$ and the width of the temporal window is $W=4$. Each user has $A_k=1$ (0 dB MAI) and we consider the asynchronous CDMA channel. The performance measure plotted here is the mean of the probability of bit error computed for each user in a given signal-to-noise ratio (SNR) defined as A_k^2/σ^2 .

Preliminary results can be seen in Fig. 1. WSF and MDL methods give virtually the same results, slightly worse than the MUSIC method. Since 50 Monte Carlo simulations do not provide a sufficient statistics, we can expect the same result than in case of one emitter, where the three methods proposed here give the same performance.

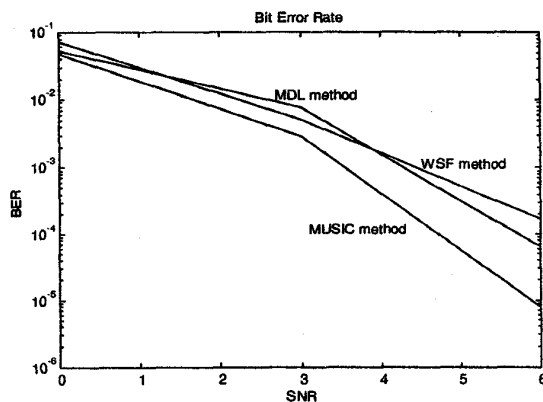


Figure 1. Bit error rate.

V. CONCLUSIONS

A Monte Carlo simulation is carried out in order to evaluate the different weighted subspace algorithms. As it is shown in the figures, weighted subspace methods provide the same accurate results than the MUSIC method developed by Moulines *et al.* in [3] and extended to DS-CDMA by Wang in [2]. As was shown in [8], the Modified Variable Projection algorithm developed and applied in a blind channel identification

context can improve the MUSIC results in a single user context when weighted subspace methods are involved. It can be expected that this algorithm can be applied to DS-CDMA systems with same results. On the other hand, the weighting matrices in MDL and WSF methods were defined for DOA problem; as channel estimation is not the same problem another weighting matrix can be derived for this specific situation. Another simulations have been carried out in order to test the behavior of weighted algorithms with larger bursts. Results have shown that at larger sample size, less difference in Mean Square Error (MSE) exists between MUSIC and the proposed algorithms. Therefore we can conclude that the weighting matrices defined in MDL and WSF criterions are useful in low sample sizes.

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