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Recovering the initial distribution for strongly damped wave equation

Nguyen Huy Tuan^a, Doan Vuong Nguyen^{b,c}, Vo Van Au^{d,e}, Daniel Lesnic^{f,*}

^aApplied Analysis Research Group, Faculty of Mathematics and Statistics, Ton Duc Thang University, Ho Chi Minh City, Viet Nam

^bFaculty of Mathematics and Computer Science, University of Science, Vietnam National University, Ho Chi Minh City, Viet Nam

^cFaculty of Fundamental Science, Industrial University of Ho Chi Minh City, Viet Nam

^dInstitute of Computational Science and Technology, Ho Chi Minh City, Viet Nam

^eFaculty of General Sciences, Can Tho University of Technology, Can Tho City, Viet Nam

^fDepartment of Applied Mathematics, University of Leeds, Leeds LS2 9JT, UK

Abstract

We study for the first time the inverse backward problem for the strongly damped wave equation. First, we show that the problem is severely ill-posed in the sense of Hadamard. Then, under the *a priori* assumption on the exact solution belonging to a Gevrey space, we propose the Fourier truncation method for stabilising the ill-posed problem. A stability estimate of logarithmic type is established.

Keywords and phrases: Fourier regularization method; final value problem; strongly damped wave equation.

Mathematics subject Classification 2000: 35K05, 35K99, 47J06, 47H10

1. Introduction

The strongly damped wave equation (SDWE), see (1.1) below, occurs in a wide range of applications modelling the motion of viscoelastic materials [3, 7, 9, 10]. From both the theoretical and numerical point of view, the initial value problem for this equation has been extensively studied (e.g., [4, 5, 11]). However, to the best of our knowledge, the final value (backward) problem has not been solved yet (though it is worth mentioning that in [6], Lattes and Lions introduced the problem (1.1)-(1.2) but they did not regularize it). Our major objective is to provide a regularization method for solving the ill-posed nonlinear problem (1.1)-(1.2).

Let T be a positive number and Ω be an open, bounded and connected domain in \mathbb{R}^n , $n \geq 1$ with a smooth boundary $\partial\Omega$. We are interested in the following inverse backward problem: Find the initial data $u(x, 0)$ for $x \in \Omega$, where $u(x, t)$ satisfies the following semilinear SDWE:

$$u_{tt} - \alpha \mathcal{A}u_t - \mathcal{A}u = F(x, t, u(x, t)), \quad (x, t) \in \Omega \times (0, T), \quad (1.1)$$

subject to the conditions

$$\begin{cases} u = 0, & (x, t) \in \partial\Omega \times (0, T), \\ u(x, T) = g(x), & (x, t) \in \Omega \times (0, T), \\ u_t(x, T) = h(x), & (x, t) \in \Omega \times (0, T), \end{cases} \quad (1.2)$$

where $\alpha > 0$ is a given damping constant, $g(x)$ and $h(x)$ are given functions, and the source function F will be defined later. **Here, the operator $\mathcal{A} : D(\mathcal{A}) \subset L^2(\Omega) \rightarrow L^2(\Omega)$ is a linear, positive-definite, self-adjoint operator with compact inverse in $L^2(\Omega)$. For instance, $\mathcal{A} := \sum_{i,j=1}^d \frac{\partial}{\partial x_i} (l_{ij}(x) \frac{\partial}{\partial x_j})$, $x \in \Omega$ is a linear second-order elliptic operator with smooth coefficients $\{l_{ij}\}_{i,j=1}^d$ being symmetric and uniformly positive definite. Then, the Dirichlet eigenvalues $(\lambda_j)_{j \in \mathbb{N}^*}$ of $-\mathcal{A}$ satisfy, see Chapter 6.5 in [2], $0 < \lambda_1 \leq \lambda_2 \leq \lambda_3 \leq \dots \leq \lambda_j \leq \dots$ and $\lim_{j \rightarrow \infty} \lambda_j = \infty$.**

In practice, the data (g, h) is obtained by measurement contaminated with noise. Hence, instead of (g, h) , we have the observation data $(g^\epsilon, h^\epsilon) \in L^2(\Omega) \times L^2(\Omega)$ satisfying

$$\|g^\epsilon - g\|_{L^2(\Omega)} + \|h^\epsilon - h\|_{L^2(\Omega)} \leq \epsilon, \quad (1.3)$$

where the constant $\epsilon > 0$ represents a bound on the measurement error. We will show that the inverse backward problem (1.1)-(1.2) is ill-posed in the sense of Hadamard in Section 2. In order to stabilise the solution, in Section 3 we develop a regularization method based on the truncated Fourier method for which a stability estimate of logarithmic type is established.

*Corresponding author

Email addresses: nguyenhuytuan@tdt.edu.vn (Nguyen Huy Tuan), vuongnguyendoan@gmail.com (Doan Vuong Nguyen), vvau8190hg@gmail.com (Vo Van Au), amt51d@maths.leeds.ac.uk (Daniel Lesnic)

2. Ill-posedness of the inverse problem (1.1)-(1.2)

Assume that the problem (1.1)-(1.2) has a unique solution in the series form

$$u(x, t) = \sum_{j=1}^{\infty} u_j(t) \phi_j(x), \quad (2.4)$$

where ϕ_j denotes the eigenfunction corresponding to the eigenvalue λ_j and

$$\begin{cases} u_j''(t) + \alpha \lambda_j u_j'(t) + \lambda_j u_j(t) = F_j(u)(t), & t \in (0, T), \\ u_j(T) = g_j, \quad u_j'(T) = h_j, \end{cases} \quad (2.5)$$

where $F_j(u)(t) = \int_{\Omega} F(x, t, u(x, t)) \phi_j(x) dx$, $g_j = \int_{\Omega} g(x) \phi_j(x) dx$ and $h_j = \int_{\Omega} h(x) \phi_j(x) dx$.

For given fixed damping $\alpha > 0$, consider the decomposition

$$\mathbb{N}^* = \left(\mathbb{D}_1 = \left\{ j \in \mathbb{N}^* \mid \lambda_j > \frac{4}{\alpha^2} \right\} \right) \cup \left(\mathbb{D}_2 = \left\{ j \in \mathbb{N}^* \mid \lambda_j = \frac{4}{\alpha^2} \right\} \right) \cup \left(\mathbb{D}_3 = \left\{ j \in \mathbb{N}^* \mid \lambda_j < \frac{4}{\alpha^2} \right\} \right).$$

Then, the solution of (2.5) is given by:

(i) if $j \in \mathbb{D}_1$ then

$$u_j(t) = \frac{\lambda_j^+ e^{(T-t)\lambda_j^-} - \lambda_j^- e^{(T-t)\lambda_j^+}}{\sqrt{\Lambda_j}} g_j - \frac{e^{(T-t)\lambda_j^+} - e^{(T-t)\lambda_j^-}}{\sqrt{\Lambda_j}} h_j + \int_t^T \frac{e^{(s-t)\lambda_j^+} - e^{(s-t)\lambda_j^-}}{\sqrt{\Lambda_j}} F_j(u)(s) ds, \quad (2.6)$$

(ii) if $j \in \mathbb{D}_2$ then

$$u_j(t) = e^{\frac{2}{\alpha}(T-t)} \left[1 - \frac{2}{\alpha}(T-t) \right] g_j - e^{\frac{2}{\alpha}(T-t)} (T-t) h_j + \int_t^T (s-t) e^{\frac{2}{\alpha}(s-t)} F_j(u)(s) ds,$$

(iii) if $j \in \mathbb{D}_3$ then

$$\begin{aligned} u_j(t) &= \frac{2e^{\frac{\alpha \lambda_j}{2}(T-t)}}{\sqrt{-\Lambda_j}} \left[\frac{\sqrt{-\Lambda_j}}{2} \cos \left(\frac{\sqrt{-\Lambda_j}}{2}(T-t) \right) + \frac{\alpha \lambda_j}{2} \sin \left(\frac{\sqrt{-\Lambda_j}}{2}(T-t) \right) \right] g_j \\ &- \frac{2e^{\frac{\alpha \lambda_j}{2}(T-t)}}{\sqrt{-\Lambda_j}} \sin \left(\frac{\sqrt{-\Lambda_j}}{2}(T-t) \right) h_j + \int_t^T \frac{2e^{\frac{\alpha \lambda_j}{2}(s-t)}}{\sqrt{-\Lambda_j}} \sin \left(\frac{\sqrt{-\Lambda_j}}{2}(s-t) \right) F_j(u)(s) ds, \end{aligned}$$

where

$$\lambda_j^+ = \frac{\alpha \lambda_j + \sqrt{\alpha^2 \lambda_j^2 - 4\lambda_j}}{2}, \quad \lambda_j^- = \frac{\alpha \lambda_j - \sqrt{\alpha^2 \lambda_j^2 - 4\lambda_j}}{2}, \quad \Lambda_j = \alpha^2 \lambda_j^2 - 4\lambda_j. \quad (2.7)$$

Hence, the solution (2.4) can be represented as

$$u(x, t) = \sum_{j \in \mathbb{D}_1} u_j(t) \phi_j + \sum_{j \in \mathbb{D}_2} u_j(t) \phi_j + \sum_{j \in \mathbb{D}_3} u_j(t) \phi_j.$$

From above observations, we can show that the term $\sum_{j \in \mathbb{D}_2} u_j(t) \phi_j + \sum_{j \in \mathbb{D}_3} u_j(t) \phi_j$ containing sin and cos trigonometric functions is bounded and stable, and no regularization is need it for it. We only need to regularize the first term $\sum_{j \in \mathbb{D}_1} u_j(t) \phi_j$ which contains the exponential terms in (2.6). Alternatively, we can take $\mathbb{D}_1 = \mathbb{D}_2 = \emptyset$ by assuming that $\alpha^2 \lambda_1 > 4$, as will adopted in the remanding of the paper. Note that this also implies $\alpha^2 \lambda_j^2 - 4\lambda_j > 0$ for all $j \in \mathbb{N}^*$, and hence the roots in (2.7) are real and distinct.

From now on, we denote by $\langle \cdot, \cdot \rangle$ and $\| \cdot \|$ the inner product and norm in $L^2(\Omega)$, respectively. For $\varphi \in L^2(\Omega)$, defining

$$\mathcal{S}(t)\varphi = \sum_{j=1}^{\infty} \frac{\lambda_j^+ e^{t\lambda_j^-} - \lambda_j^- e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j, \quad \mathcal{P}(t)\varphi = \sum_{j=1}^{\infty} \frac{e^{t\lambda_j^-} - e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j, \quad (2.8)$$

we can recast (2.4) in the form

$$u(x, t) = \mathcal{S}(T-t)g(x) + \mathcal{P}(T-t)h(x) - \int_t^T \mathcal{P}(s-t)F(u(s))ds. \quad (2.9)$$

Next, we give an example which shows that the solution $u_m(x, t)$ (for any $m \in \mathbb{N}^*$) of problem (1.1)-(1.2) (if it exists) is not stable. Let $u_{T,m}$ and $v_{T,m}$ and F_0 be defined as follows:

$$u_m(x, T) = u_{T,m}(x) = 0, \quad \partial_t u_m(x, T) = v_{T,m}(x) = \frac{\phi_m(x)}{\sqrt{\lambda_m}} \quad \text{and} \quad F_0(w) = \sum_{j=1}^{\infty} \frac{e^{-\alpha T \lambda_j}}{2T^2} \langle w(x, t), \phi_j \rangle \phi_j, \quad \forall w \in L^2(\Omega). \quad (2.10)$$

Let u_m satisfy the integral equation

$$u_m(x, t) = \mathcal{P}(T-t)v_{T,m} - \int_t^T \mathcal{P}(s-t)F_0(u_m(s))ds. \quad (2.11)$$

First, we show that (2.11) has a unique solution $u_m \in C([0, T]; L^2(\Omega))$. Indeed, we consider the function

$$\mathcal{H}(w)(t) = \mathcal{P}(T-t)v_{T,m}(x) - \int_t^T \mathcal{P}(s-t)F_0(w(s))ds. \quad (2.12)$$

Then, for any $v_1, v_2 \in C([0, T]; L^2(\Omega))$, we have

$$\begin{aligned} \|\mathcal{H}(v_1)(t) - \mathcal{H}(v_2)(t)\| &\leq \int_t^T \|\mathcal{P}(s-t)(F_0(v_1(s)) - F_0(v_2(s)))\| ds \\ &= \int_t^T \sqrt{\sum_{j=1}^{\infty} \left[\frac{e^{(s-t)\lambda_j^-} - e^{(s-t)\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle F_0(v_1(s)) - F_0(v_2(s)), \phi_j \rangle^2} ds \\ &= \frac{1}{2} \int_t^T \sqrt{\sum_{j=1}^{\infty} \left[\frac{e^{(s-t)\lambda_j^-} - e^{(s-t)\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \frac{e^{-2\alpha T \lambda_j}}{T^4} \langle v_1(s) - v_2(s), \phi_j \rangle^2} ds. \end{aligned} \quad (2.13)$$

Using the the inequality $|e^{-a} - e^{-b}| \leq |a - b|$ for $a, b > 0$, we have

$$\left[\frac{e^{(s-t)\lambda_j^-} - e^{(s-t)\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \frac{e^{-2\alpha T \lambda_j}}{T^4} = e^{2(s-t)(\lambda_j^+ + \lambda_j^-)} \left[\frac{e^{-(s-t)\lambda_j^+} - e^{-(s-t)\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 \frac{e^{-2\alpha T \lambda_j}}{T^4} \leq (s-t)^2 e^{2\alpha(s-t)\lambda_j} \frac{e^{-2\alpha T \lambda_j}}{T^4} \leq \frac{1}{T^2}. \quad (2.14)$$

From (2.13) and (2.14) we deduce that

$$\|\mathcal{H}(v_1)(t) - \mathcal{H}(v_2)(t)\| \leq \frac{1}{2} \int_t^T \frac{1}{T} \|v_1(s) - v_2(s)\| ds \leq \frac{1}{2} \|v_1 - v_2\|_{C([0, T]; L^2(\Omega))}, \quad \forall t \in [0, T]. \quad (2.15)$$

This implies that

$$\|\mathcal{H}(v_1) - \mathcal{H}(v_2)\|_{C([0, T]; L^2(\Omega))} \leq \frac{1}{2} \|v_1 - v_2\|_{C([0, T]; L^2(\Omega))}. \quad (2.16)$$

Hence, \mathcal{H} is a contraction. Using the Banach fixed-point theorem, we conclude that $\mathcal{H}(w) = w$ has a unique solution $u_m \in C([0, T]; L^2(\Omega))$.

It is easy to see that (here, noting that $F_0(0) = 0$)

$$\left\| \int_t^T \mathcal{P}(s-t)F_0(u_m(s))ds \right\| = \|\mathcal{H}(u_m)(t) - \mathcal{H}(0)(t)\| \leq \frac{1}{2} \|u_m\|_{C([0, T]; L^2(\Omega))}. \quad (2.17)$$

Hence,

$$\|u_m(t)\| \geq \left\| \mathcal{P}(T-t)v_{T,m} \right\| - \left\| \int_t^T \mathcal{P}(s-t)F_0(u_m(s))ds \right\| \geq \left\| \mathcal{P}(T-t)v_{T,m} \right\| - \frac{1}{2} \|u_m\|_{C([0, T]; L^2(\Omega))}. \quad (2.18)$$

This leads to

$$\|u_m\|_{C([0, T]; L^2(\Omega))} \geq \frac{2}{3} \sup_{0 \leq t \leq T} \left\| \mathcal{P}(T-t)v_{T,m} \right\|. \quad (2.19)$$

We continue to estimate the right hand side of this inequality. We have

$$\left\| \mathcal{P}(T-t)v_{T,m} \right\|^2 = \left[\frac{e^{(T-t)\lambda_m^-} - e^{(T-t)\lambda_m^+}}{\lambda_m^+ - \lambda_m^-} \right]^2 \frac{1}{\lambda_m} = \frac{e^{2(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2 \lambda_m^2 - 4\lambda_m}} \right)^2}{\lambda_m (\lambda_m^+ - \lambda_m^-)^2} \geq \frac{e^{2(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2 \lambda_1^2 - 4\lambda_1}} \right)^2}{\lambda_m (\alpha^2 \lambda_m^2 - 4\lambda_m)}.$$

Since the function $\Phi(t) = e^{(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)$ is a decreasing function, we deduce that

$$\sup_{0 \leq t \leq T} \|\mathcal{P}(T-t)v_{T,m}\| \geq \sup_{0 \leq t \leq T} \frac{e^{(T-t)\lambda_m^+} \left(1 - e^{-(T-t)\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}} = \frac{e^{T\lambda_m^+} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}} \geq \frac{e^{\alpha T\lambda_m/2} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}}. \quad (2.20)$$

Combining (2.19) and (2.20) yields

$$\|u_m\|_{C([0,T];L^2(\Omega))} \geq \frac{2}{3} \frac{e^{\alpha T\lambda_m/2} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}}. \quad (2.21)$$

As $m \rightarrow +\infty$, we see that

$$\begin{aligned} \lim_{m \rightarrow +\infty} (\|u_{T,m}\| + \|v_{T,m}\|) &= \lim_{m \rightarrow +\infty} \frac{1}{\sqrt{\lambda_m}} = 0, \\ \lim_{m \rightarrow +\infty} \|u_m\|_{C([0,T];L^2(\Omega))} &\geq \lim_{m \rightarrow +\infty} \frac{2}{3} \frac{e^{\alpha T\lambda_m/2} \left(1 - e^{-T\sqrt{\alpha^2\lambda_1^2 - 4\lambda_1}}\right)}{\sqrt{\lambda_m(\alpha^2\lambda_m^2 - 4\lambda_m)}} = +\infty. \end{aligned} \quad (2.22)$$

This shows that problem (1.1)-(1.2) is ill-posed in the sense of Hadamard in the L^2 -norm.

3. Fourier's truncation method

For $\varphi \in L^2(\Omega)$, let us define the truncated version of (2.8) as

$$\mathcal{S}_N(t)\varphi = \sum_{j=1}^N \frac{\lambda_j^+ e^{t\lambda_j^-} - \lambda_j^- e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j, \quad \mathcal{P}_N(t)\varphi = \sum_{j=1}^N \frac{e^{t\lambda_j^-} - e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \langle \varphi, \phi_j \rangle \phi_j. \quad (3.23)$$

Let us define the regularized solution by Fourier's truncation method as follows:

$$u^{N,\epsilon}(x,t) = \mathcal{S}_N(T-t)g^\epsilon(x) + \mathcal{P}_N(T-t)h^\epsilon(x) - \int_t^T \mathcal{P}_N(s-t)F(u^{N,\epsilon})(x,s)ds, \quad (3.24)$$

where N is a parameter regularization to be prescribed.

Lemma 3.1. *The following estimates hold:*

$$\|\mathcal{S}_N(t)\|_{\mathcal{L}(L^2(\Omega))} \leq \sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} e^{\alpha t\lambda_N}, \quad \|\mathcal{P}_N(t)\|_{\mathcal{L}(L^2(\Omega))} \leq T e^{\alpha t\lambda_N}, \quad \forall t \in [0, T]. \quad (3.25)$$

Proof. Let $\varphi \in L^2(\Omega)$. From (3.23) we have

$$\|\mathcal{S}_N(t)\varphi\|^2 = \sum_{j=1}^N \left[\frac{\lambda_j^+ e^{t\lambda_j^-} - \lambda_j^- e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2 = \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \left[\frac{\lambda_j^+ e^{-t\lambda_j^+} - \lambda_j^- e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2. \quad (3.26)$$

Using the inequality $(a+b)^2 \leq 2a^2 + 2b^2$ for $a, b \in \mathbb{R}$ and the inequality $|e^{-a} - e^{-b}| \leq |a-b|$ for $a, b > 0$, we obtain

$$\begin{aligned} \left[\frac{\lambda_j^+ e^{-t\lambda_j^+} - \lambda_j^- e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 &= \left(e^{-t\lambda_j^+} + \lambda_j^- \frac{e^{-t\lambda_j^+} - e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right)^2 \leq 2e^{-2t\lambda_j^+} + 2|\lambda_j^-|^2 t^2 \\ &\leq 2 + \left(\frac{2t\lambda_j}{\alpha\lambda_j + \sqrt{\alpha^2\lambda_j^2 - 4\lambda_j}} \right)^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2}. \end{aligned} \quad (3.27)$$

It follows from (3.26) and (3.27) that

$$\|\mathcal{S}_N(t)\varphi\|^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2} \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \langle \varphi, \phi_j \rangle^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2} \sum_{j=1}^N e^{2\alpha t\lambda_j} \langle \varphi, \phi_j \rangle^2 \leq \frac{2\alpha^2 + 8T^2}{\alpha^2} e^{2\alpha t\lambda_N} \|\varphi\|^2. \quad (3.28)$$

This completes the proof of the first part of (3.25). Also, using $|e^{-a} - e^{-b}| \leq |a-b|$ for $a, b > 0$, we obtain

$$\|\mathcal{P}_N(t)\varphi\|^2 = \sum_{j=1}^N \left[\frac{e^{t\lambda_j^-} - e^{t\lambda_j^+}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2 = \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \left[\frac{e^{-t\lambda_j^+} - e^{-t\lambda_j^-}}{\lambda_j^+ - \lambda_j^-} \right]^2 \langle \varphi, \phi_j \rangle^2 \leq T^2 \sum_{j=1}^N e^{2t(\lambda_j^+ + \lambda_j^-)} \langle \varphi, \phi_j \rangle^2, \quad (3.29)$$

which completes the proof of the second part of (3.25). \square

At this stage, **in order to obtain the convergence rate (3.31) given in the following theorem**, we introduce the abstract Gevrey class of functions of order $\gamma > 0$ and index $\sigma > 0$, e.g., [1], defined by

$$\mathbb{G}_{\gamma,\sigma} = \left\{ v \in L^2(\Omega) : \sum_{j=1}^{\infty} \lambda_j^{2\gamma} e^{2\sigma\lambda_j} \left| \langle v, \phi_j(x) \rangle \right|^2 < \infty \right\},$$

which is a Hilbert space equipped with the inner product

$$\langle v_1, v_2 \rangle_{\mathbb{G}_{\gamma,\sigma}} := \left\langle (-\Delta)^\gamma e^{\sigma\sqrt{-\Delta}} v_1, (-\Delta)^\gamma e^{\sigma\sqrt{-\Delta}} v_2 \right\rangle, \quad \forall v_1, v_2 \in \mathbb{G}_{\gamma,\sigma},$$

and the corresponding norm $\|v\|_{\mathbb{G}_{\gamma,\sigma}} = \sqrt{\sum_{j=1}^{\infty} \lambda_j^{2\gamma} e^{2\sigma\lambda_j} \left| \langle v, \phi_j(x) \rangle \right|^2} < \infty$.

We also assume that F is globally Lipschitz, i.e. there exists a constant $K > 0$ such that

$$\|F(x, t, u) - F(x, t, v)\| \leq K\|u - v\|, \quad \forall u, v \in L^2(\Omega), \quad \forall (x, t) \in \Omega \times (0, T). \quad (3.30)$$

Theorem 3.1. *The nonlinear integral equation (3.24) has a unique solution $u^{N,\epsilon} \in C([0, T]; L^2(\Omega))$. Assuming further that $u \in L^\infty(0, T; \mathbb{G}_{\gamma,\sigma T})$ for some $\gamma > 0$, then we have the following estimate:*

$$\|u^{N,\epsilon}(\cdot, t) - u(\cdot, t)\| \leq e^{-\alpha t \lambda_N} e^{KT^2} \left(\left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha T \lambda_N} \epsilon + \lambda_N^{-\gamma} \|u\|_{L^\infty(0, T; \mathbb{G}_{\gamma,\sigma T})} \right), \quad \forall t \in [0, T]. \quad (3.31)$$

Remark 3.1. *If we choose $N = N(\epsilon)$ such that $\lambda_N \leq \frac{\delta}{\alpha T} \ln\left(\frac{1}{\epsilon}\right)$ for some $\delta \in (0, 1)$, then the error $\|u^{N,\epsilon}(\cdot, t) - u(\cdot, t)\|$ is of logarithmic order $\left[\ln\left(\frac{1}{\epsilon}\right)\right]^{-\gamma}$. Also, if $F(x, t, u) = F(x, t)$ does not depend on u then we do not need to employ the Gevrey space but only require that $u \in L^\infty(0, T; L^2(\Omega))$. To remove the assumption on u belonging to $L^\infty(0, T; \mathbb{G}_{\gamma,\sigma T})$, we can employ a new regularization method described in [8] for the Cauchy problem for semilinear elliptic equations, but its extension to the present damped semilinear wave equation (1.1) is deferred to a future work.*

Proof. Part 1. The existence and uniqueness solution of the nonlinear integral equation (3.24).

For $w \in C([0, T]; L^2(\Omega))$, we define

$$\mathcal{G}(w)(x, t) = \mathcal{S}_N(T-t)g^\epsilon(x) + \mathcal{P}_N(T-t)h^\epsilon(x) - \int_t^T \mathcal{P}_N(s-t)F(w(x, s))ds. \quad (3.32)$$

We shall prove by induction that

$$\left\| \mathcal{G}^m(w_1) - \mathcal{G}^m(w_2) \right\|_{C([0, T]; L^2(\Omega))} \leq \frac{(KT e^{\alpha T \lambda_N} (T-t))^m}{m!} \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))}, \quad \forall w_1, w_2 \in C([0, T]; L^2(\Omega)). \quad (3.33)$$

For $m = 1$, we have

$$\begin{aligned} \|\mathcal{G}(w_1) - \mathcal{G}(w_2)\| &= \left\| \int_t^T \mathcal{P}_N(s-t) (F(w_1(s)) - F(w_2(s))) ds \right\| \\ &\leq \int_t^T T e^{\alpha(s-t)\lambda_N} \|F(w_1(s)) - F(w_2(s))\| ds \leq KT e^{\alpha T \lambda_N} (T-t) \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))}. \end{aligned} \quad (3.34)$$

Assume that (3.33) holds for $m = p$. We show that (3.33) holds for $m = p + 1$. Indeed, we have

$$\begin{aligned} \|\mathcal{G}^{p+1}(w_1) - \mathcal{G}^{p+1}(w_2)\| &= \left\| \int_t^T \mathcal{P}_N(s-t) (F(\mathcal{G}^p(w_1)(s)) - F(\mathcal{G}^p(w_2)(s))) ds \right\| \\ &\leq \int_t^T T e^{\alpha(s-t)\lambda_N} \|F(\mathcal{G}^p(w_1)(s)) - F(\mathcal{G}^p(w_2)(s))\| ds \leq KT e^{\alpha T \lambda_N} \int_t^T \|\mathcal{G}^p(w_1(s)) - \mathcal{G}^p(w_2(s))\| ds \\ &\leq KT e^{\alpha T \lambda_N} \int_t^T \frac{(KT e^{\alpha T \lambda_N} (T-s))^p}{p!} \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))} ds \leq \frac{(KT e^{\alpha T \lambda_N} (T-t))^{p+1}}{(p+1)!} \|w_1 - w_2\|_{C([0, T]; L^2(\Omega))}. \end{aligned} \quad (3.35)$$

Therefore, by the induction principle, we have that (3.33) holds. Since $\lim_{m \rightarrow +\infty} \frac{(KT e^{\alpha T \lambda_N})^m}{m!} = 0$ there exists a positive integer m_0 such that \mathcal{G}^{m_0} is a contraction. It follows that the equation $\mathcal{G}^{m_0} w = w$ has a unique solution $u^{N,\epsilon} \in C([0, T]; L^2(\Omega))$. We claim that $\mathcal{G}(u^{N,\epsilon}) = u^{N,\epsilon}$. Indeed, since $\mathcal{G}^{m_0}(u^{N,\epsilon}) = u^{N,\epsilon}$, we know that $\mathcal{G}(\mathcal{G}^{m_0}(u^{N,\epsilon})) = \mathcal{G}(u^{N,\epsilon})$. This is equivalent to $\mathcal{G}^{m_0}(\mathcal{G}(u^{N,\epsilon})) = \mathcal{G}(u^{N,\epsilon})$. Hence, $\mathcal{G}(u^{N,\epsilon})$ is a fixed point of \mathcal{G}^{m_0} . Moreover, as noted above, $u^{N,\epsilon}$ is a fixed point of \mathcal{G}^{m_0} .

Part 2. Denote

$$U^N(x, t) = \mathcal{S}_N(T-t)g(x) + \mathcal{P}_N(T-t)h(x) - \int_t^T \mathcal{P}_N(s-t)F(u^N(x, s))ds. \quad (3.36)$$

Step 1. Firstly, we estimate $\|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\|$. Using Lemma 3.1, we have

$$\begin{aligned} \|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| &\leq \left\| \mathcal{S}_N(T-t)(g - g^\epsilon) \right\| + \left\| \mathcal{P}_N(T-t)(h - h^\epsilon) \right\| + \left\| \int_t^T \mathcal{P}_N(s-t)(F(u^{N,\epsilon}(\cdot, s)) - F(U^N(\cdot, s)))ds \right\| \\ &\leq \sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} e^{\alpha(T-t)\lambda_N} \|g - g^\epsilon\| + T e^{\alpha(T-t)\lambda_N} \|h - h^\epsilon\| + T \int_t^T e^{\alpha(s-t)\lambda_N} \|F(u^{N,\epsilon}(\cdot, s)) - F(U^N(\cdot, s))\| ds \end{aligned} \quad (3.37)$$

It follows from (1.3) and (3.30) that

$$\|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| \leq \left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha(T-t)\lambda_N} \epsilon + KT \int_t^T e^{\alpha(s-t)\lambda_N} \|u^{N,\epsilon}(\cdot, s) - U^N(\cdot, s)\| ds. \quad (3.38)$$

Multiplying both sides by $e^{\alpha t \lambda_N}$ and applying Gronwall's inequality, we derive that

$$e^{\alpha t \lambda_N} \|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| \leq \left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha T \lambda_N} \epsilon e^{K(T-t)T}.$$

Hence,

$$\|u^{N,\epsilon}(\cdot, t) - U^N(\cdot, t)\| \leq e^{KT(T-t)} \left(\sqrt{\frac{2\alpha^2 + 8T^2}{\alpha^2}} + T \right) e^{\alpha(T-t)\lambda_N} \epsilon. \quad (3.39)$$

Step 2. Secondly, we estimate $\|u(\cdot, t) - U^N(\cdot, t)\|$. First, it is easy to see that

$$\sum_{j=1}^N u_j(t)\phi_j(x) = \mathcal{S}_N(T-t)g(x) + \mathcal{P}_N(T-t)h(x) - \int_t^T \mathcal{P}_N(s-t)F(u(x, s))ds.$$

Using Lemma 3.1, we obtain

$$\begin{aligned} \|u(\cdot, t) - U^N(\cdot, t)\| &\leq \left\| u(\cdot, t) - \sum_{j=1}^N u_j(t)\phi_j(\cdot) \right\| + \left\| \sum_{j=1}^N u_j(t)\phi_j(\cdot) - U^N(\cdot, t) \right\| \\ &\leq \sqrt{\sum_{j=N+1}^{\infty} \lambda_N^{-2\gamma} e^{-2\alpha t \lambda_N} \lambda_j^{2\gamma} e^{2\alpha t \lambda_j} |u_j(t)|^2} + \int_t^T \mathcal{P}_N(s-t) \|F(u(\cdot, s)) - F(U^N(\cdot, s))\| ds \\ &\leq \lambda_N^{-\gamma} e^{-\alpha t \lambda_N} \|u\|_{L^\infty(0, T; \mathbb{G}_{\gamma, \alpha T})} + KT \int_t^T e^{\alpha(s-t)\lambda_N} \|u(\cdot, s) - U^N(\cdot, s)\| ds. \end{aligned} \quad (3.40)$$

Multiplying both sides by $e^{\alpha t \lambda_N}$ and applying Gronwall's inequality, we derive that

$$\|u(\cdot, t) - U^N(\cdot, t)\| \leq e^{KT(T-t)} \|u\|_{L^\infty(0, T; \mathbb{G}_{\gamma, \alpha T})} \lambda_N^{-\gamma} e^{-\alpha t \lambda_N}. \quad (3.41)$$

Combining (3.39) and (3.41) we deduce (3.31). \square

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