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The Moonshine and LHC di-Photon Excess

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Abstract

The spinor-vector duality was discovered in free fermionic constructions of the heterotic-string in four dimensions. It played a key role in the construction of heterotic-string models with an anomaly free extra Z' symmetry that may remain unbroken down to low energy scales. A generic signature of the low scale string derived Z' model is via di-photon excess that may be within reach of the LHC. A fascinating possibility is that the spinor-vector duality symmetry is rooted in the structure of the heterotic-string compactifications to two dimensions. The two dimensional heterotic-string theories are in turn related to the so-called moonshine symmetries that underlie the two dimensional compactifications. In this paper we embark on exploration of this connection by the free fermionic formulation to classify the symmetries of the two dimensional heterotic-string theories. We use two complementary approaches in our classification. The first utilises a construction which is akin to the one used in the spinor-vector duality. Underlying this method is the triality property of SO(8) representations. In the second approach we use the free fermionic tools to classify the twenty four dimensional moonshine lattices.

1 Introduction

The ATLAS and CMS collaborations reported in December 2015 evidence for excess in the di–photon chanel [1, 2]. Absence of evidence for any other deviation from the Standard Model expected signals suggested that the excess could be interpreted as production and decay of a Standard Model singlet state by heavy vector–like states [3], in a process depicted in figure 1. In ref. [4] it was shown that the spectrum required to generate the excess naturally arise in the string derived model of ref. [5], which allows for a light Z' vector boson. Anomaly cancellation mandates that the mass scale of the Standard Model singlet state, which is produced in resonance in figure 1, as well as the mass scale of the heavy vector–like states that are used in the production and decay of the singlet states, is the Z' symmetry breaking scale. Thus, assuming that the Z' remains unbroken down to the multi–TeV scale naturally gives rise to the characteristics required to generate di–photon excess. In ref. [6] it was shown that existence of the light Z' at the multi–TeV scale is compatible with gauge coupling unification at the GUT scale, as well as other phenomenological constraints.

In August 2016 the ATLAS and CMS collaborations reported that accumulation of further data did not substantiate the observation of the di–photon excess [7, 8], suggesting that initial observation was a statistical fluctuation. However, this does not repudiate the di–photon excess as a signal of the string derived Z' model, albeit not as the purported 750GeV resonance. Thus, searching for di–photon excesses in the energy range accessible at the LHC continues to be of immense interest.

Extra Z' vector bosons as possible signatures of heterotic-string vacua have been discussed in the literature since the mid-eighties [9]. The difficulty in constructing heterotic-string models that allow for an extra U(1) symmetry to remain unbroken down to low scales stems from the fact that the aforementioned symmetries tend to be anomalous in the heterotic-string derived models. The reason being that the string models utilise the symmetry breaking pattern $E_6 \to SO(10) \times U(1)_{\zeta}$, with anomalous $U(1)_{\zeta}$. Suppression of left-handed neutrino masses implies that the extra U(1) symmetry, which is embedded in SO(10), has to be broken near the GUT scale. This conundrum motivated the search of extra U(1) symmetries that do not admit the E_6 embedding of their charges [10]. However, these choices result in contradiction between gauge coupling unification and the gauge coupling parameters at the electroweak scale, which works well if the extra U(1) charges admit the E_6 embedding [11, 6].

It is therefore notable that in reference [5] an heterotic-string derived model with

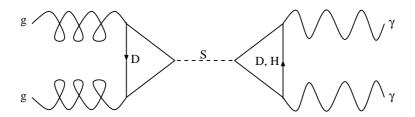


Figure 1: Production and di-photon decay of the Standard Model singlet scalar state.

an anomaly free $U(1)_{\zeta}$ was constructed. What is perhaps more remarkable is that the construction of the model utilises a basic duality symmetry that operates in the space of $Z_2 \times Z_2$ heterotic-string vacua which was dubbed spinor-vector duality. The duality operates under the exchange of the total number of spinorial $16 \oplus \overline{16}$ and vectorial 10 representations of SO(10). For every vacuum with a number of $16 \oplus \overline{16}$ representations, and a number of 10 representations, there exist a dual vacuum in which the two numbers are interchanged. One can further show that the duality arises from the breaking of (2,2) world-sheet supersymmetry to (2,0) and that the duality map is induced by a spectral flow operator that operates in the bosonic sector of the heterotic-string vacuum. In the vacua with (2,2) world-sheet supersymmetry the $SO(10) \times U(1)_{\zeta}$ symmetry is enhanced to E_6 . The chiral 27 and $\overline{27}$ representations of E_6 decompose under $SO(10) \times U(1)_{\zeta}$ as

$$\begin{array}{rclcrcl} 27 & = & 16_{+\frac{1}{2}} & + & 10_{-1} & + 1_{+2}, \\ \overline{27} & = & \overline{16}_{-\frac{1}{2}} & + & 10_{+1} & + 1_{-2}. \end{array}$$

Thus, the (2,2) vacua are self-dual under the exchange of the total number of spinorial $16 \oplus \overline{16}$ and vectorial 10 representations. The spectral flow operator acts as the U(1) generator of the N=2 world-sheet supersymmetry and interchanges between the SO(10) components in the decomposition of E_6 under $SO(10) \times U(1)_{\zeta}$. The breaking of the E_6 to $SO(10) \times U(1)_{\zeta}$, or the breaking of the world-sheet supersymmetry from (2,2) to (2,0) is induced by Wilson lines. One choice of Wilson line breaking results in a vacuum with $\#_1$ of $16 \oplus \overline{16}$ representations, and a $\#_2$ of 10 representations, whereas a second choice interchanges the two numbers. Furthermore, the duality map between the dual cases induced by the spectral flow operator of the parent (2,2) vacuum.

A new twist is that the spinor-vector duality was used to construct the heterotic-string model with anomaly free $U(1)_{\zeta}$ that allows for an extra E_6 Z' to remain unbroken down to low scales. Using the methods developed in refs. [12, 13, 14, 15, 16] for the classification of free fermionic models, a self-dual model under the spinor-vector duality is fished from the landscape of vacua. The unbroken gauge symmetry at the string level is $SO(10) \times U(1)_{\zeta}$, but the spectrum is self-dual under the exchange of the total number of spinorial $16 \oplus \overline{16}$ and vectorial 10 representations. Thus, the spectrum still forms complete E_6 multiplets and consequently $U(1)_{\zeta}$ is anomaly free. This is possible in the $Z_2 \times Z_2$ orbifold if the different spinorial and vectorial components are obtained from different fixed points. Conversely, obtaining both the spinorial and vectorial representations at the same fixed point necessarily implies that the gauge symmetry is enhanced to E_6 . in the model of ref. [5] the SO(10) symmetry is broken at the string level to $SO(6) \times SO(4)$. However, the chiral spectrum of the model still appears in complete E_6 representations, hence maintaining $U(1)_{\zeta}$ as an anomaly free symmetry.

The spinor–vector duality is a fundamental symmetry in the space of (2,0) heterotic–string vacua. It played a central role in the construction of the Z' model in ref. [5]. If the additional U(1) symmetry remains unbroken down to low scales it may be detected via di–photon production as in fig. 1.

Another fascinating direction of investigation is the possibility that the spinorvector duality is a mere reflection of a much larger symmetry structure that underlies this class of vacua. The much larger symmetry structure is obtained in compactifications to two dimensions, and give rise to 24 dimensional lattices. Ref. [17] alluded to possible similarities with the Massive Spectrum boson–fermion Degeneracy Symmetry [MSDS] [18], which arises from a basic Jacobi–like identity in 24 dimensions. The compactifications to two dimensions are connected to 24 dimensional lattices and the symmetries of those are related to the so called moonshine symmetries. In two dimensions the spectral flow operator that induces the spinor–vector duality and the the twist operators that acts on the internal coordinates can be seen to share a common structure in that both have four periodic right–moving fermions. One may further envision that under decompactification back to 4 dimensions the two spinor–vector dual vacua appear on the boundaries of the moduli space. This is reminiscent of the case when spacetime supersymmetry is broken to N=0 by a Scherk–Schwarz mechanism in nine dimensions and the supersymmetric and non–supersymmetric vacua appear on the boundaries of the compactified dimension.

In this paper we embark on a program to explore the connection between the moonshine symmetries and the spinor-vector duality. We foresee that the spinorvector duality is a tip of the iceberg, and that elucidation of this connection may reveal a covering space of large space of string compactifications facilitating a deeper understanding of their symmetries and connections. In this paper we make several modest steps to initiate the enterprise. In section 2 we review a specific realisation of the spinor-vector duality, which is particularly suited for our purpose here. In this realisation the untwisted vector bosons corresponding to the sixteen dimensional vector bundle of the heterotic-string in ten dimensions, generate an $SO(8)^4$ gauge symmetry. This is obtained by including in the construction four basis vectors with four periodic world-sheet fermions, and enhancement to larger gauge symmetries is obtained from twisted sectors. A similar basis vector with four periodic fermions that acts simultaneously on the gauge degrees of freedom and the internal coordinates produces the twisted sectors. The spinor-vector duality can be then seen to arise due to a special choice of the Generalised GSO (GGSO) phases. In section 3 we explore a similar construction in two dimensions and classify the symmetries that arise on the resulting 24 dimensional lattices. In section 4 we derive representations of some of the Niemeier lattices in 24 dimensions in the free fermionic formulation. Section 5 concludes our paper.

2 A novel basis

In this section we review the spinor vector duality in the specific realisation of ref. [19]. Construction of a consistent four dimensional heterotic-string theory in the light-cone gauge requires 20 left-moving and 44 right-moving two dimensional real fermions [20] propagating on the world-sheet torus. The models in this construction are specified in terms of a set of basis vectors v_i , i = 1, ..., n,

$$v_i = \{\alpha_i(f_1), \alpha_i(f_2), \alpha_i(f_3)\} \dots \}$$

describing the transformation properties of each fermion

$$f_A \to -e^{i\pi\alpha_i(f_A)} f_A, , A = 1, \dots, 44,$$
 (1)

when transported along the non-contractible loops of the one loop vacuum to vacuum amplitude. The basis vectors span a space Ξ which consists of 2^N sectors that give rise to the string spectrum. Each sector is given by

$$\xi = \sum N_i v_i, \quad N_i = 0, 1 \tag{2}$$

The spectrum is truncated by a GGSO projection whose action on a string state |S> is

$$e^{i\pi v_i \cdot F_S} |S\rangle = \delta_S \ c \begin{bmatrix} S \\ v_i \end{bmatrix} |S\rangle,$$
 (3)

where F_S is the fermion number operator and $\delta_S=\pm 1$ is the spacetime spin statistics index. Different sets of projection coefficients $c{S \brack v_i}=\pm 1$ consistent with modular invariance give rise to different models. A model is defined by a set of basis vectors $v_i, i=1,\ldots,n$ and a set of $2^{N(N-1)/2}$ independent projections coefficients $c{v_i\brack v_j},i>j$. The 64 world–sheet fermions in the light–cone gauge are denoted by: $\psi^\mu,\chi^i,\psi^i,\omega^i,i=1,\ldots,6$ (real left-moving fermions) and $\bar{y}^i,\bar{\omega}^i,i=1,\ldots,6$ (real right-moving fermions); $\bar{\psi}^j,j=1,\ldots,4$; $\bar{\eta}^k,k=0,1,2,3$; $\bar{\phi}^l,l=1,\ldots,8$ (complex right-moving fermions). The division of the right–moving complex fermions into groups of four is obtained by introducing four basis vectors $z_{\{0,1,2,3\}}$ into the basis. Each of the z_i contains four non–overlapping periodic fermions under the sets $\{\bar{\psi}^1,\ldots,4,\bar{\eta}^{0,1,2,3},\bar{\phi}^1,\ldots,4,\bar{\phi}^5,\ldots,8\}$. We note that our notation here deviates from the conventional one in the free fermion literature by renaming $\bar{\psi}^5\equiv\bar{\eta}^0$. To illustrate the structure of the spinor–vector duality we use a basis V of seven boundary condition basis vectors given by:

$$V = \{v_1, v_2, \dots, v_7\},\$$

where

$$v_{1} = \mathbf{1} = \{\psi^{\mu}, \chi^{1,\dots,6}, y^{1,\dots,6}, \omega^{1,\dots,6} | \\ \bar{y}^{1,\dots,6}, \bar{\omega}^{1,\dots,6}, \bar{\eta}^{1,2,3}, \bar{\psi}^{1,\dots,5}, \bar{\phi}^{1,\dots,8} \},$$

$$v_{2} = S = \{\psi^{\mu}, \chi^{1,\dots,6} \},$$

$$v_{3} = z_{1} = \{\bar{\phi}^{1,\dots,4} \},$$

$$v_{4} = z_{2} = \{\bar{\phi}^{5,\dots,8} \},$$

$$v_{5} = z_{3} = \{\bar{\psi}^{1,\dots,4} \},$$

$$v_{6} = z_{0} = \{\bar{\eta}^{0,1,2,3} \},$$

$$v_{7} = b_{1} = \{\chi^{34}, \chi^{56}, y^{34}, y^{56} | \bar{y}^{34}, \bar{y}^{56}, \bar{\eta}^{0}, \bar{\eta}^{1} \}.$$

$$(4)$$

The partition function of such models is of the form

$$Z(\tau,\bar{\tau}) = \frac{1}{\tau_{2}(\eta\bar{\eta})^{2}} \frac{1}{\eta^{10}\bar{\eta}^{22}} \frac{1}{2^{7}} \sum_{a,b,s,s'} \sum_{h_{1},g_{1}} \sum_{H_{I},G_{I}} C^{[a,s,h_{1},H_{I}]}_{[b,s',g_{1},G_{I}]}$$

$$\theta^{[a+s]}_{[b+s']} \theta^{[a+s]}_{[b+s']} \theta^{[a+s+h_{1}]}_{[b+s']} \theta^{[a+s]}_{[b+s']}$$

$$\theta^{[a]}_{[b]} \theta^{[a+h_{1}]}_{[b+g_{1}]} \theta^{[a]}_{[b+g_{1}]} \theta^{[a+h_{1}]}_{[b+g_{1}]} \theta^{[a+h_{1}]}_{[b+g_{1}]}$$

$$\overline{\theta}^{[a]}_{[b]} \overline{\theta}^{[a+h_{1}]}_{[b+g_{1}]} \overline{\theta}^{[a+h_{1}]}_{[b+g_{1}]} \overline{\theta}^{[a+h_{1}]}_{[b+g_{1}]} \overline{\theta}^{[a+h_{1}]}_{[b+g_{1}]}$$

$$\overline{\theta}^{[a+H_{0}]}_{[b+G_{0}]} \overline{\theta}^{[a+H_{0}]}_{[b+G_{0}]} \overline{\theta}^{[a+H_{0}]}_{[b+G_{0}]} \overline{\theta}^{[a+H_{3}]}_{[b+G_{3}]} \overline{\theta}^{[a+H_{3}]}_{[b+G_{3}]} \overline{\theta}^{[a+H_{3}]}_{[b+G_{3}]} \overline{\theta}^{[a+H_{3}]}_{[b+G_{3}]}$$

$$\overline{\theta}^{[a+H_{1}]}_{[b+G_{1}]} \overline{\theta}^{[a+H_{1}]}_{[b+G_{1}]} \overline{\theta}^{[a+H_{1}]}_{[b+G_{1}]} \overline{\theta}^{[a+H_{2}]}_{[b+G_{2}]} \overline{\theta}^{[a+H_{2}]}_{[b+G_{2}]} \overline{\theta}^{[a+H_{2}]}_{[b+G_{2}]} \overline{\theta}^{[a+H_{2}]}_{[b+G_{2}]} \overline{\theta}^{[a+H_{2}]}_{[b+G_{2}]} .$$
(5)

The phases $C_{[b,s',g_1,G_I]}^{[a,s,h_1,H_I]}$ can be calculated in terms of the phases $C_{[v_j]}^{[v_i]}$ that define the model: If we define the vectors

$$\alpha = a\mathbf{1} + sS + h_1b_1 + \sum_{I} H_I z_I = \sum_{I} n_a v_a ,$$

$$\alpha' = b\mathbf{1} + s'S + g_1b_1 + \sum_{I} G_I z_I = \sum_{I} n'_b v_b ,$$

then

$$C_{[b,s',g_1,G_I]}^{[a,s,h_1,H_I]} = C_{\alpha'}^{[\alpha]} = \left(\delta_{\alpha}\right)^{\sum_a n'_a - 1} \left(\delta_{\alpha'}\right)^{\sum_a n_a - 1} e^{-\pi i \, r(\alpha) \cdot \alpha'} \prod_{a,b} C_{\mathbf{B}_b}^{\mathbf{B}_a}^{\mathbf{B}_a}^{n_a n'_b} , \quad (6)$$

where $\delta_{\alpha} = e^{i\pi\alpha(\psi^{\mu})}$ and $r(\alpha) = \frac{\alpha - [\alpha]}{2}$ is the reduction vector which takes α to $[\alpha]$ with the latter having all its entries in the interval (-1,1].

The models generated by the basis (4) preserve N=2 space—time supersymmetry. Models that break N=2 to N=1 space—time supersymmetry are easily incorporated by introducing a second basis vector b_2 [14]. The second function of the second Z_2 basis vector b_2 is to break the untwisted observable symmetry gauge group from $SO(12) \times SO(4)$ to $SO(10) \times U(1)^3$. Here the spinor-vector duality is therefore seen in terms of SO(12), rather than SO(10), representations. However, since in the N=1 vacua the spinor-vector duality operates separately on each of the N=2 planes [14], the discussion in terms of N=2 representations is sufficient.

In the models generated by the basis in eq. (4) all the geometrical degrees of freedom $\{y^i, \omega^i | \bar{y}^i, \bar{\omega}^i\}$, $i=1,\cdots,3$ are grouped together. The remaining 8 left–moving and 32 right–moving world–sheet fermions are divided into five non–overlapping groups of eight real fermions. In the ten dimensional supersymmetric heterotic–string such a division always produces either SO(32) or $E_8 \times E_8$ gauge groups [21]. Although, naively one may expect that other gauge symmetries, such as $SO(8)^4$, $SO(16)^2$ or $SO(8) \times SO(24)$ may be obtained, the modular properties of the partition function forbid the other possible extensions. In terms of the SO(8) characters this property follows from the equivalence of the 8_v , 8_s and 8_c SO(8) representations, which enables twisted constructions of the SO(32) or $E_8 \times E_8$ gauge groups. This phenomena appear in the models generated by the basis in eq. (4) and will be exploited in section 3 below. The basis vector b_1 generates a Z_2 projection which breaks N=4 to N=2 space–time supersymmetry, and breaks one of the SO(8) groups to $SO(4) \times SO(4) \equiv SU(2)^4$.

The sectors contributing to the gauge group are the 0–sector and the 10 antiholomorphic sets:

$$G = \{ 0, z_0, z_1, z_2, z_3, z_0 + z_1, z_0 + z_2, z_0 + z_3, z_1 + z_2, z_1 + z_3, z_2 + z_3 \}.$$

$$(7)$$

The 0-sector requires two oscillators acting on the vacuum in the right-moving sector to produce a massless state; the z_j -sectors require one oscillator; and the $z_i + z_j$ sectors require no oscillators. We first discuss the N = 4 gauge group arising prior to the inclusion of the basis vector b_1 , which reduces N = 4 to N = 2 spacetime supersymmetry. The basis vector b_1 does not produce additional enhancement sectors, and therefore merely breaks the N = 4 gauge group to a subgroup.

The 0-sector gauge bosons produces the gauge symmetry

$$[SO(12)] \times SO(8)^4 \tag{8}$$

where the SO(12) group factor arises from the 12 right—moving world-sheet fermions $\{\bar{y},\bar{\omega}\}^{1,\cdots,6}$, which correspond to the internal lattice at the free fermionic SO(12) enhanced symmetry point. The $SO(8)_{3,0,1,2}$ group factors arise respectively from: $\bar{\psi}^{1,\cdots,4}$, $\bar{\eta}^{0,1,2,3}$, $\bar{\phi}^{1,\cdots,4}$, $\bar{\phi}^{5,\cdots,8}$. The notation adheres to the conventional notation in the quasi–realistic heterotic–string models in the free fermionic formulation [22].

The additional sectors in eq. (7) may produce space—time vector bosons that enhance the untwisted four dimensional gauge symmetry. The possible enhancements depend on the GGSO projection coefficients $c\begin{bmatrix} z_i \\ z_j \end{bmatrix}$ with $i \neq j$. Excluding the basis vector b_1 all vacua possess N=4 space—times supersymmetry, which fixes the $c\begin{bmatrix} S \\ z_i \end{bmatrix}$ phases. Hence, there may be a priori 2^6 possibilities for the four dimensional gauge group, some of which are repeated. Identical manifestations of the gauge groups arise from twisted realisation of the group generators, due to the triality property of the SO(8) group representations. This is the four dimensional manifestation of the twisted generation of gauge groups already observed in the ten dimensional case. A few of the possibilities that may arise were classified in ref. [19]. The same construction will be exploited in section 3 in the analysis of compactifications to two dimensions.

2.1 A simple example of the spinor-vector duality

The basis vector b_1 reduces $N=4 \rightarrow N=2$ space—times supersymmetry. The N=4 vacuum with $[SO(12)] \times SO(16) \times SO(16)$ gauge group is realised with the GGSO projection coefficient taken to be:

$$c \begin{bmatrix} z_0 \\ z_1 \end{bmatrix} = c \begin{bmatrix} z_0 \\ z_3 \end{bmatrix} = c \begin{bmatrix} z_1 \\ z_2 \end{bmatrix} =$$

$$-c \begin{bmatrix} z_0 \\ z_2 \end{bmatrix} = -c \begin{bmatrix} z_1 \\ z_3 \end{bmatrix} = -c \begin{bmatrix} z_2 \\ z_3 \end{bmatrix} = -1$$

$$(9)$$

With this set of GGSO phases the additional sectors, beyond the 0-sector, that produce additional space-time vector bosons are z_2 and z_3 , whereas those from all

other sectors in eq. (7) are projected out. The additional projection induced by the basis vector b_1 breaks the gauge symmetry arising from the 0-sector to

$$[SO(8) \times SO(4)]_{\mathcal{L}} \times [SO(8)_3 \times SO(4) \times SO(4)]_{\mathcal{Q}} \times [SO(8)_1 \times SO(8)_2]_{\mathcal{H}}$$
 (10)

The SO(12) lattice gauge symmetry in eq. (8) is reduced to $[SO(8) \times SO(4)]_{\mathcal{L}}$. The observable gauge symmetry arising from the 0–sector is $[SO(8)_3 \times SO(4) \times SO(4)]_{O}$, and $[SO(8)_1 \times SO(8)_2]_H$ is the hidden gauge symmetry. Both observable and hidden sector gauge symmetries are enhanced. The hidden gauge symmetry is enhanced to $[SO(16)]_H$ by the additional vector bosons arising from the sector z_2 . At the N=4 level, the additional vector bosons from the sector z_3 enhance the observable $[SO(8)_3 \times SO(8)_0]_O$ gauge symmetry to $[SO(16)]_O$. At the N=2 level the b_1 projection reduces $[SO(16)]_O \to [SO(12) \times SO(4)]_O \equiv [SO(12) \times SU(2)_0 \times SU(2)_1]_O$. The N=2 spinor–vector duality is realised by the exchange of the vectorial 12 representation of SO(12) with the spinorial 32 representation. This duality is illustrated by considering two different models in which these representations are interchanged due to the choices of the GGSO projection coefficients. We remark further that the choice of GGSO projection coefficients in eq. (9) prevent the enhancement of the $SO(12) \times SU(2)$ gauge symmetry to E_7 , which is the N=2 analog of the enhancement of $SO(10) \times U(1)$ to E_6 at the N=1 level.

The first choice of the extra GGSO projection coefficients that we consider is given by:

$$c \begin{bmatrix} b_1 \\ 1, z_0 \end{bmatrix} = -c \begin{bmatrix} b_1 \\ S, z_1, z_2, z_3 \end{bmatrix} = -1.$$
 (11)

This choice defines a model with 2 multiplets in the $(1, 2_L + 2_R, 12, 1, 2, 1)$ and 2 in the $(8, 2_L + 2_R, 1, 2, 1, 1)$ representations of

$$[SO(8) \times SO(4)]_{\mathcal{L}} \times [SO(12) \times SU(2)_0 \times SU(2)_1]_O \times [SO(16)]_H$$
 (12)

The sectors producing the vectorial 12 representation of SO(12) are the sectors b_1 and $b_1 + z_3$, where the sector b_1 produces the (1, 2, 2) representation and the sectors $b_1 + z_3$ produces the $(8_s, 1, 1)$ under the decomposition

$$[SO(12)]_O \to [SO(8) \times SO(4)]_O \equiv [SO(8) \times SU(2) \times SU(2)]_O \ . \eqno(13)$$

All other states are projected out. In this case there are eight multiplets in the vectorial representation of the observable SO(12), which also transform as as doublets of the observable $SU(2)_1$.

We next consider the choice of GGSO phases given by

$$c \begin{bmatrix} b_1 \\ 1, z_0, z_1 \end{bmatrix} = -c \begin{bmatrix} b_1 \\ S, z_2, z_3 \end{bmatrix} = -1 \tag{14}$$

This case defines a model with 2 multiplets in the $(1, 2_L + 2_R, 32, 1, 1, 1)$, and 2 in the $(1, 2_L + 2_R, 1, 1, 2, 16)$, representations of the gauge group in eq. (12). The sectors producing the spinorial 32 representation of $[SO(12)]_O$ are the sectors $b_1 + z_0$ and $b_1 + z_3 + z_0$, where the sector $b_1 + z_0$ produces the $(8_V, 2, 1)$ representation and the sectors $b_1 + z_3 + z_0$ produces the $(8_C, 1, 2)$ under the decomposition given in

eq. (13). The sectors producing the vectorial 16 multiplet of the hidden SO(16) gauge group are the sectors b_1 and $b_1 + z_2$, where the sector b_1 produces the $(8_V, 1)$ multiplet and the sector $b_1 + z_2$ produces the $(1, 8_C)$ multiplet under the decomposition $[SO(16)]_H \rightarrow [SO(8)_1 \times SO(8)_2]_H$. The hidden 16 multiplets transform as doublets of the observable $SU(2)_1$ group. All other states are projected out. In this model there are eight multiplets in the spinorial 32 representation of the observable $[SO(12)]_O$.

We note that in the first model the vectorial 12 representation of the observable $[SO(12)]_O$ is constructed as $12 = (8_s, 1, 1) \oplus (1, 2, 2)$, while in the second model the spinorials are constructed as $32 = (8_v, 2, 1) \oplus (8_c, 1, 2)$ under the decomposition $SO(12) \to SO(8) \times SU(2) \times SU(2)$. At the core of the construction is the triality of the SO(8) representations $8_s \leftrightarrow 8_v \leftrightarrow 8_c$. This property of the SO(8) representations reproduces the standard decomposition of $SO(n+m) \to SO(n) \times SO(m)$ as $V^{n+m} = (V^n, 1) \oplus (1, V^m)$, and $S^{n+m} = (S^n, S^m) \oplus (C^n, C^m)$, for the vectorial and spinorial representations of SO(n+m), respectively. The triality of the SO(8) representations, which is SO(12) in the N=2 models, and SO(10) in N=1 models. This SO(8) triality is the main property in the analysis of section 3.

The transformation between the two models, (11) and (14), is induced by the discrete GGSO phase change

$$c \begin{bmatrix} b_1 \\ z_1 \end{bmatrix} = +1 \quad \to \quad c \begin{bmatrix} b_1 \\ z_1 \end{bmatrix} = -1 \tag{15}$$

In the models utilising the basis of eq. (4) the map from sectors that produce vectorial representations of the observable SO(12) group, to sectors that produce spinorial representations is obtained by adding the basis vector z_0 , which is similar to the x-map of refs. [23, 14]. The basis vector z_0 therefore acts as the spectral flow operator. It is a generator of the right-moving N=2 world-sheet supersymmetry in the models that preserve (2, 2) world–sheet supersymmetry. It is the mirror image of the basis vector S, which is the spectral flow operator on the fermionic side of the heterotic-string. For appropriate choice of the discrete GGSO phases either the vectorial states or the spinorial states are kept in the spectrum. The discrete phase modification in eq. (15) induces the spinor-vector duality map in the N=2model. The role of the basis vectors z_2 and z_3 in the models of (11) and (14) is to generate the twisted realisation of the gauge symmetry enhancement of the SO(8)gauge groups arising from the null sector. We may further represent the spinorvector duality in an orbifold representation [24], and translate the duality map in eq. (15) to distinct choices of the toroidal background fields [25, 17]. Generalisation of the spectral map transformation between heterotic-string vacua was extended to Gepner models in [26].

3 D = 2 model classification

In this section we extend the classification of the symmetry groups to the case of compactifications to two dimensions. We develop the formalism and perform a complete classification in the simpler cases and partial classification in the more complex cases, where complexity here entails increasing number of basis vectors. The primary property which is exploited in our classification is the triality of the SO(8) representations. In section 4 we will employ an alternative method to construct the 24 dimensional Niemeier lattices. In section 5 we will comment on the overlap and differences between our analysis in sections 3 and 4 and that of 2.

We compactify the heterotic–string to two dimensions. The two dimensional free fermions in the light-cone gauge (in the usual notation [20, 22]) are: $\chi^i, y^i, \omega^i, i = 1, \ldots, 8$ (real left-moving fermions) and $\bar{y}^i, \bar{\omega}^i, i = 1, \ldots, 8$ (real right-moving fermions), $\bar{\psi}^A, A = 1, \ldots, 4, \bar{\eta}^B, B = 0, 1, 2, 3, \bar{\phi}^\alpha, \alpha = 1, \ldots, 8$ (complex right-moving fermions). The left– and right–moving real fermions are combined into complex fermions as $\rho_i = 1/\sqrt{2}(y_i + i\omega_i), i = 1, \cdots, 8, \ \bar{\rho}_i = 1/\sqrt{2}(\bar{y}_i + i\bar{\omega}_i), i = 1, \cdots, 4, \ \bar{\rho}_i = 1/\sqrt{2}(\bar{y}_i + i\bar{\omega}_i), i = 5, \cdots, 8.$

The class of models under investigation, is generated by a maximal set V of 7 basis vectors

$$V = \{v_{1}, v_{2}, \dots, v_{7}\},$$

$$v_{1} = \mathbf{1} = \{\chi^{1,\dots,8}, y^{1,\dots,8}, \omega^{1,\dots,8} | \\ \bar{y}^{1,\dots,8}, \bar{\omega}^{1,\dots,8}, \bar{\eta}^{0,1,2,3}, \bar{\psi}^{1,\dots,4}, \bar{\phi}^{1,\dots,8}\},$$

$$v_{2} = H_{L} = \{\chi^{1,\dots,8}, y^{1,\dots,8}, \omega^{1,\dots,8}\},$$

$$v_{3} = z_{1} = \{\bar{\phi}^{1,\dots,4}\},$$

$$v_{4} = z_{2} = \{\bar{\phi}^{5,\dots,8}\},$$

$$v_{5} = z_{3} = \{\bar{\psi}^{1,\dots,4}\},$$

$$v_{6} = z_{4} = \{\bar{\eta}^{0,1,2,3}\},$$

$$v_{7} = z_{5} = \{\bar{y}^{1,\dots,4}, \bar{\omega}^{1,\dots,4}\},$$

$$(16)$$

with the corresponding matrix of one-loop GGSO projection coefficients

The analysis of the models is similar to the analysis in the four dimensional case, where we define the GGSO projections in a similar way to eq. (3), with the δ_S index being +1 in sectors in which the left-moving world-sheet fermions are anti-periodic and -1 sectors in which they are periodic. With this definition of the GGSO projection, consistent with modular invariance, we can proceed to analyse the symmetry configurations.

$c\begin{bmatrix} z_1 \\ H_L \end{bmatrix}$	$c\begin{bmatrix} z_2 \\ H_L \end{bmatrix}$	$c\begin{bmatrix} z_1\\ z_2 \end{bmatrix}$	Gauge group G
+	+	+	$SO(16) \times SO(32)$
+	_	+	$SO(8) \times SO(40)$
_	_	+	SO(48)
_	_	_	$E_8 \times SO(32)$

Table 1: The configuration of the symmetry group with four basis vectors.

3.1 Configurations

We analyse the various configurations that arise with increasingly larger number of basis vectors. The simplest is the set $\{1, H_L\}$. With this set there is only one possible configuration with SO(48) symmetry. Climbing the complexity ladder by adding the z_1 basis vector produces two possible configurations $SO(8) \times SO(40)$ and SO(48). The first is obtained from the the untwisted vector states and the vector states from the sector z_1 are projected out, whereas the second is obtained by retaining the states from z_1 in the massless spectrum. The choice of the phase $c\begin{bmatrix} z_1 \\ H_L \end{bmatrix} = \pm 1$ selects between the two configurations. The next set is obtained by adding the basis vector z_2 yielding the set $\{1, H_L, z_1, z_2\}$. The matrix of GGSO phases is given by:

Only the phases above the diagonal are independent, whereas those on and below the diagonal are fixed by the modular invariance rules. Thus, in the configurations corresponding to eq. (18) we have a total of three independent phases or eight possible configurations. Naturally, there are degeneracies in the space of configurations due to the permutation symmetries among the z_i . With the basis corresponding to eq. (18) we find a total of four independent configurations shown in table 1.

We note that we each subsequent basis set the configurations of the smaller sets are reproduced. This is a recurring feature of string constructions [14] and results from some generic θ -function identities and redistribution of the vector states among the different sectors. We next add the additional basis vector z_3 producing a five basis set $\{1, H_L, z_1, z_2, z_3\}$. The phases matrix is given by

Gauge group G	$c\begin{bmatrix} z_2 \\ z_3 \end{bmatrix}$	$c\begin{bmatrix} z_1 \\ z_3 \end{bmatrix}$	$c\begin{bmatrix} z_1 \\ z_2 \end{bmatrix}$	$c\begin{bmatrix} z_3 \\ H_L \end{bmatrix}$	$c\begin{bmatrix} z_2 \\ H_L \end{bmatrix}$	$c\begin{bmatrix} z_1 \\ H_L \end{bmatrix}$
$SO(24) \times SO(24)$	+	+	+	+	+	+
$SO(8) \times SO(16) \times SO(24)$	_	+	+	+	+	+
$SO(16) \times SO(32)$	+	+	+	_	+	+
$SO(8) \times SO(40)$	+	+	+	+	_	_
$E_8 \times SO(8) \times SO(24)$	+	+	_	+	_	_
SO(48)	+	+	+	_	_	_
$E_8 \times SO(32)$	+	+	_	_	_	_

Table 2: The configuration of the symmetry group with five basis vectors.

The untwisted symmetry is $SO(8)_1 \times SO(8)_2 \times SO(8)_3 \times SO(24)$. In this case there are a total of six independent phases producing 64 distinct possibilities. Out of those we obtain seven distinct configurations shown in table 2. Four of the resulting configurations are reproductions of previous cases and three are new. a complete analysis of all configurations has been performed in the case with five basis vectors.

The next step is to add an additional basis vector to the set. The set of basis vectors is then $\{1, H_L, z_1, z_2, z_3, z_4\}$. The untwisted symmetry is $SO(8)_1 \times SO(8)_2 \times SO(8)_3 \times SO(8)_4 \times SO(16)$. The sectors contributing to the symmetry group are the 0-sector and the 11 purely anti-holomorphic sets:

$$G = \{ 0,$$

$$z_{1}, z_{2}, z_{3}, z_{4},$$

$$z_{1} + z_{2}, z_{1} + z_{3}, z_{1} + z_{4}, z_{2} + z_{3}, z_{2} + z_{4}, z_{3} + z_{4},$$

$$\tilde{z} = \mathbf{1} + H_{L} + z_{1} + z_{2} + z_{3} + z_{4} \}$$

$$(20)$$

where the 0-sector requires two oscillators acting on the vacuum in the gauge sector; the z_j -sectors require one oscillator; and the $z_i + z_j$ and \tilde{z} require no oscillators. The matrix of GGSO phases is given by

There are 10 independent phases in eq. (21) rendering a total of 1024 different possibilities with a complete analysis seemingly prohibitive. For a sample of the choices we reproduce the previous seven configurations and obtain six new ones. The thirteen configurations are displayed in table 3.

The fifth case in table 3 is a new feature of the basis set corresponding to eq. (21) as compared to the earlier cases. In all the previous cases the symmetry was enhanced by one or more of the additional sectors, whereas in the case of the fifth

$c \begin{bmatrix} z_1 \\ H_L \end{bmatrix}$	$c{z_2 \brack H_L}$	$c\begin{bmatrix} z_3 \\ H_L \end{bmatrix}$	$c\begin{bmatrix} z_4 \\ H_L \end{bmatrix}$	$c\begin{bmatrix} z_1 \\ z_2 \end{bmatrix}$	$c\begin{bmatrix} z_1\\ z_3 \end{bmatrix}$	$c\begin{bmatrix} z_1\\ z_4 \end{bmatrix}$	$c\begin{bmatrix} z_2 \\ z_3 \end{bmatrix}$	$c\begin{bmatrix} z_2 \\ z_4 \end{bmatrix}$	$c\begin{bmatrix} z_3\\ z_4 \end{bmatrix}$	Gauge group G
+	+	+	+	+	+	+	+	+	+	$E_8 \times SO(32)$
+	+	+	+	+	+	+	+	+	_	$SO(16) \times SO(16) \times SO(16)$
+	+	+	+	+	+	+	+	_	_	$SO(16) \times SO(8) \times SO(8) \times SO(16)$
+	+	+	+	+	+	+	_	_	_	$E_8 \times SO(24) \times SO(8)$
+	+	+	+	_	+	+	_	+	_	$SO(16) \times SO(8) \times SO(8) \times SO(8) \times SO(8)$
+	+	+	+	_	_	_	+	+	+	$SO(24) \times SO(16) \times SO(8)$
+	+	+	+	+	_	_	_	_	+	$E_8 \times SO(16) \times SO(16)$
_	+	+	+	+	+	+	+	+	+	$SO(24) \times SO(24)$
+	+	+	+	_	_	_	_	_	_	$SO(32) \times SO(16)$
_	_	+	+	_	+	+	+	+	+	$E_8 \times E_8 \times SO(16)$
_	_	_	_	+	+	+	+	+	+	SO(48)
_	_	_	+	+	+	+	+	+	+	$SO(40) \times SO(8)$
_	_	_	_	_	+	+	+	+	_	$E_8 \times E_8 \times E_8$

Table 3: The configuration of the symmetry group with six basis vectors.

row in table 3 all enhancements are projected out. Thus, this set affords a larger set of projectors that facilitate projection of all enhancements. This is a recurring feature, which is frequently used in classification of fermionic string vacua in four dimensions. The last row in table 3 correspond to a model with E_8^3 symmetry, which is identified as one of the Niemeier lattices.

The next and final step is to add an additional basis vector which correspond to the set given in eq. (16) and the GGSO coefficients matrix in eq. (17). The untwisted symmetry is $SO(8)_1 \times SO(8)_2 \times SO(8)_3 \times SO(8)_4 \times SO(8)_5 \times SO(8)_6$, corresponding to the six sets of right—moving worldsheet complex fermions

$$\Big\{ \{\bar{\rho}^{1,2,3,4}\}; \{\bar{\rho}^{5,6,7,8}\}; \{\bar{\psi}^{1,2,3,4}\}; \{\bar{\eta}^{0,1,2,3}\}; \{\bar{\phi}^{1,2,3,4}\}; \{\bar{\phi}^{5,6,7,8}\} \Big\}.$$

The sectors contributing to the symmetry group are the 0–sector and the 21 purely anti–holomorphic sets:

$$G = \left\{ \begin{array}{c} 0, \\ z_1, \ z_2, \ z_3, \ z_4, \ z_5, \ z_6, \\ z_1 + z_2, z_1 + z_3, z_1 + z_4, z_1 + z_5, z_1 + z_6, \\ z_2 + z_3, z_2 + z_4, z_2 + z_5, z_2 + z_6, \\ z_3 + z_4, z_3 + z_5, z_3 + z_6, \\ z_4 + z_5, z_4 + z_6, z_5 + z_6 \end{array} \right\}$$

$$(22)$$

where $z_6 = \mathbf{1} + H_L + z_1 + z_2 + z_3 + z_4 + z_5 = {\bar{\phi}^{5,6,7,8}}$., Similarly, to the previous cases the 0-sector requires two oscillators acting on the vacuum in the right-moving sector to produce a massless state; the z_i sectors require one oscillator; and the $z_i + z_j$ with $i \neq j$ require no oscillators. All these cases require one oscillator acting on the vacuum in the left-moving sector. There are 15 independent phases in eq. (17) rendering a total of 32768 possibilities, which requires a computerised analysis, and is beyond our scope here.

All the sets that we introduced so far involve non-overlapping periodic fermions, i.e. the product between any two non-trivial basis vectors is 0mod4. We can introduce additional basis vectors with two overlapping right—moving periodic fermions, i.e. the product between the new basis vectors and two of those in in eq. (16) is 2. For example, a basis vector with $z_7 = \{\bar{\rho}^{1,2}, \bar{\eta}^{2,3}\} \equiv 1 \text{ has } z_7 \cdot z_1 = z_7 \cdot z_4 = 2.$ We can further envision breaking H_L into three corresponding basis vectors z_0 , z_8 and z_9 with $H_L = z_0 + z_8 + z_9$, and similarly introduce basis vectors with overlapping periodic complex fermions. A single mod 4 left-moving basis vector, with null assignment for the right-moving fermions, produces a Jacobi-like factor, $V_8 - S_8$, in the partition function, which produces N=4 spacetime supersymmetry in the four dimensional models. Such non overlapping left-moving basis vectors produce a product of Jacobi-like identities, whereas basis vectors with overlapping periodic fermions break this identity in a familiar way from the four dimensional models. The action of the basis vectors with overlapping periodic fermions is reminiscent of the orbifold action in section 2 and combining a left-moving action with a rightmoving one will entail precisely that. This will alter the sharp division between the left- and the right-movers and reduce the symmetry structures obtained with the

24 dimensional lattices. This looks similar to the case of toroidal orbifolds. Detailed analysis of these cases is beyond our scope here and will be reported in future work. What may be envisioned is that the symmetry structures of the four dimensional models are rooted in the rich symmetry structures of the 24 dimensional lattices in two dimensions. In turn the free fermionic construction may provide a set of simple tools that can be used to explore the properties of the 24 dimensional lattices. In the next section we derive some of the Niemeier lattices by using the free fermionic tools.

4 The Niemeier lattices

Some of the models we have already presented have the property that the modular invariant partition function factorizes into a left and a right—moving part:

$$Z(\tau,\bar{\tau}) = Z(\tau)Z(\bar{\tau}). \tag{23}$$

For models based on the set $\{H_L, H_R\} = \{\mathbf{1}, H_R\}$, which might also include some of the z_i 's given in (16), this will happen if the phases between H_L and any other vector are chosen appropriately $(c \begin{bmatrix} H_L \\ \text{anything} \end{bmatrix} = -1)$.

Within the class of models with factorized partition functions, there is a subclass of models for which $Z(\tau)$ and $Z(\bar{\tau})$ are modular invariant by themselves. Particular cases of this type are models for which $Z(\tau)$ is a constant. These models display a Massive Spectrum Degeneracy Symmetry (MSDS) and have been studied in [18]. Here, we would like to focus more on the right-moving partition function, which for lattice compactifications is

$$Z(\bar{\tau}) = \frac{Z_{\Lambda}(\bar{\tau})}{\bar{\eta}(\bar{\tau})^{24}} \ . \tag{24}$$

 Λ is the lattice on which the right-moving bosons are compactified.

Since $Z(\bar{\tau})$ is modular invariant, Λ must be an even, self-dual, 24-dimensional lattice (assuming a compactification to two dimensions). There are 24 such lattices classified by Niemeier [27] and they are presented in table 4. With the exception of the Leech lattice that has no vectors of length 2, the vectors of length 2 of the remaining 23 lattices belong to the root lattices of simple Lie groups. However, knowing the components is not enough by itself to fully define a Niemeier lattice. One must also describe how conjugacy classes among different components are coupled with each other. This is given in terms of certain glue vectors. For example, the Niemeier lattice D_{12}^2 needs glue vectors $\{(s,v),(v,s)\}$ where v and s stand for the vector and the spinor conjugacy class of D_{12} . More details about this construction and a list of glue vectors for all the Niemeier lattices can be found in [28, 29].

Note that these lattices have been studied extensively in the past, especially in connection with moonshine. For example, the lattice A_1^{24} carries a natural representation of the monster group M_{24} and the Umbral Moonshine conjecture associates a finite group and a set of vector valued mock modular forms to each of these 23 Niemeier lattices (see [30] and references therein).

Lattice compactifications have an equivalent fermionic description [31, 32]. The main result of this section is table 4 in which we give realizations of the Niemeier lat-

tices in terms of free fermionic basis vectors. Note that even though many glue vectors need to be included for a description in the bosonic language, the free fermionic realizations of many of these lattices are quite succinct. This is a demonstration of the power of the free fermionic formalism for certain tasks and an example where the dictionary between bosons and fermions described in [31] can be used to provide new insights.

For an example, let us look at the D_{12}^2 Niemeier lattice again. The straightforward way one might imagine implementing this in the free fermionic language is through the basis set $\{b_1, b_2, b_3, b_4\}$ where (remembering that the normalization is twice the usual for weight vectors):

$$b_1 = \{1^{12}, 0^{12}\}, (25)$$

$$b_1 = \{1^{12}, 0^{12}\},$$

$$b_2 = \{0^{12}, 1^{12}\},$$

$$b_3 = \{1^{12}, 2, 0^{11}\},$$

$$b_4 = \{2, 0^{11}, 1^{12}\}.$$

$$(25)$$

$$(26)$$

$$(27)$$

$$b_3 = \{1^{12}, 2, 0^{11}\}, (27)$$

$$b_4 = \{2, 0^{11}, 1^{12}\}. (28)$$

 b_1 and b_2 generate the two D_{12} , whereas b_3 and b_4 is what one would naively write down to implement the glue vectors (s, v) and (v, s). On the other hand, the inclusion of b_3 and b_4 appears highly unconventional from a free fermionic model building perspective because they are not independent of b_1 and b_2 when considered mod 2. The resolution to this paradox is to use the formula [31]:

$$c\begin{bmatrix} \alpha + \delta \\ \alpha' + \delta' \end{bmatrix} = e^{\frac{1}{2}\pi i \delta \cdot \alpha'} c\begin{bmatrix} \alpha \\ \alpha' \end{bmatrix}, \qquad (29)$$

where δ and δ' have only even entries and α, α' are arbitrary, to reduce b_3 and b_4 to b_1 and b_2 respectively. This also changes the phase $c\begin{bmatrix}b_1\\b_2\end{bmatrix}$ from 1 to -1, hence verifying the corresponding entry in table 4. The same idea can be applied to fill in the rest of the table.

We tried to give realisations of the lattices using a small number of free fermionic basis vectors. However, for certain lattices we were not able to do so and we had to use the following set of 12 basis vectors $\{g_1, g_2, \cdots, g_{12}\}$, known as the Golay *qenerators*:

Note that we only show the right-moving components of the basis vectors here, with the understanding that the left-moving components are all zero. For a consistent free fermionic model, (at least) the vector H_L should also be added to the set to ensure that the vector $\mathbf{1}$ is generated. The defining phases $c\begin{bmatrix}g_i\\g_j\end{bmatrix}$ for the models that use this set are as follows:

Note that there are some entries in table 4 for which we were unable to provide concrete realisations. We conjecture that these cases can also be given in terms of the Golay basis vectors for certain phases. However, the fact that there are 2^{78} a priori different phases that are allowed by modular invariance makes it computationally difficult to verify (or disprove) this claim.

For all the models presented in table 4, an independent check of correctness can be performed by calculating the partition function (restricted to the right-moving sector) of the proposed free fermionic realization via the formula

$$Z(\bar{\tau}) = \sum_{\text{sectors } \alpha, \beta} c \begin{bmatrix} \alpha \\ \beta \end{bmatrix} \bar{\theta} \begin{bmatrix} \alpha \\ \beta \end{bmatrix}$$
(35)

and check that it matches the partition function of the Niemeier lattices given as [33]

$$Z(\bar{\tau}) = J(\bar{\tau}) + 24(h+1) ,$$
 (36)

where h is the corresponding Coxeter number (given for example in [28]) and $J(\bar{\tau})$ the unique modular invariant with zero constant term (i.e. $J(\bar{\tau}) = j(\bar{\tau}) - 744$). Note in particular that the partition functions of all these lattices (and those of the corresponding free fermionic models) only differ in their constant term. The massive spectra of all the models are identical.

The fact that the modular invariant phases in the partition function can be adjusted to couple conjugacy classes among different factors is quite surprising and, to our knowledge, has not been noticed before. It demonstrates an interesting interplay between gluing lattices and modularity and allows for a deeper understanding of the spinor-vector duality: For lattice compactifications, adjusting the generalized phases couples different conjugacy classes among different factors leading to different lattices. In a similar way, for orbifold compactifications adjusting certain generalized phases leads to spinor-vector dual models.

5 Conclusions

The heterotic–string models in the free fermionic formulation are among the most realistic string models constructed to date [22]. They correspond to $Z_2 \times Z_2$ toroidal orbifold constructions at special points in the moduli space [34, 31]. Their phenomenological properties raise the possibility that the true string vacuum shares some of their underlying properties. It is therefore of immense interest to explore what those underlying properties are. It is of course also plausible that the true string vacuum does not belong to this class, and for that purpose other classes of interesting string vacua (see e.g. [35]) should be investigated and their underlying properties explored.

A particular sub-class of free fermionic models are those that allow for a light extra Z', with its distinct low scale signature via a di-photon excess. The construction of the string model utilised the spinor-vector duality, which is akin to mirror symmetry [36]. A realisation of the spinor-vector duality relies on the triality of the SO(8) representations. In particular, this triality enables a large range of possibilities for the GGSO phases to produce the same symmetry groups. The SO(8)

Niemeier lattice	Free fermionic basis vector realization						
based on							
D_{24}	$\{1^{24}\}$						
$D_{16}E_{8}$	$\{1^{16}, 0^8\}, \{0^{16}, 1^8\}$						
E_8^3	$\{1^8, 0^8, 0^8\}$						
A_{24}	$\{(\frac{1}{3})^{23}, \frac{7}{3}\}, \ c\begin{bmatrix}b_1\\b_1\end{bmatrix} = e^{\frac{4\pi i}{3}}$						
D_{12}^2	$\{1^{12},0^{12}\},\{0^{12},1^{12}\},\ c{b_1\brack b_2}=-1$						
$A_{17}E_{7}$	$\{(\frac{1}{3})^{18}, 1^6\}$						
$D_{10}E_7^2$	$\{1^{24}\}, \{1^{10}, \underline{(0)(1)^6, 0^7}\}$						
$A_{15}D_{9}$	Golay set						
D_8^3	$\{\underline{1^8, 0^8, 0^8}\}, \ c\begin{bmatrix}b_i\\b_j\end{bmatrix} = -1, \ i \neq j$						
	$\{1^8, 0^{16}\}, \{0^4, 1^8, 0^{12}\}, \{1, 0^3, 1, 0^4, 1^4, 0^3, 1, 0^3, 1, 0^3\},$						
A_{12}^2	$\{1, 0^3, 1, 0^3, 1, 0^4, 1^4, 0^3, 1, 0^3\}, \{0^{12}, 1^8, 0^4\}, \{0^{16}, 1^8\},$						
	$c \begin{bmatrix} b_3 \\ b_4 \end{bmatrix} = -1, \ c \begin{bmatrix} b_5 \\ b_6 \end{bmatrix} = -1$						
$A_{11}D_7E_6$?						
E_{6}^{4}	$\{\underline{(0)(1)^5,(1)(0)^5,(1)(0)^5,(1)(0)^5}\},\ c\begin{bmatrix}b_2\\b_4\end{bmatrix}=-1$						
$A_9^2 D_6$?						
D_6^4	$\left \{0^6, 1^6, 0^6, 1^6\}, \{1^6, 0^6, 1^6, 0^6\}, \{0^{12}, 1^{12}\}, \ c{b_i \brack b_j} \right = -1, \ i \neq j$						
A_8^3	Golay set						
$A_7^2 D_5^2$	Golay set						
A_6^4	?						
$A_5^4 D_4$?						
D_4^6	$\{1^{24}\}, \{\underline{1^8, 0^4, 0^4, 0^4}\}, \ c{b_2\brack b_5} = -1, \ c{b_3\brack b_4} = -1$						
A_4^6	Golay set						
A_3^8	?						
A_2^{12}	?						
A_1^{24}	?						
Leech	?						

Table 4: Free fermionic realizations of all inequivalent Neimeier lattices. Underlying means permutations of all blocks separated by comma. For example, the three basis vectors needed for E_8^3 are $\{1^8,0^8,0^8\},\{0^8,1^8,0^8\},\{0^8,0^8,1^8\}$. Only the 24 right-moving components of the basis vectors appear explicitly; the left-moving are understood to be zero. We also state explicitly which generalized phases in the upper triangular part of the phase matrix are not 1. For a consistent free fermionic model, (at least) the vector H_L should also be added to the set to ensure that the vector 1 is generated.

triality property is also at the core of the well known Jacobi identity and the ensuing spacetime supersymmetry.

In this paper we explored the symmetry structures of heterotic-string vacua compactified to two dimensions. Our primary motivation is to seek the origin of the four dimensional spinor-vector duality in the symmetry structure of 24 dimensional lattices that are obtained in the two dimensional compactifications. This is analogous to the MSDS symmetry which is similarly rooted in two dimensional compactifications. We discussed in section 2 how the spinor-vector duality is rooted in the triality property of SO(8) representations and we used this triality property in 3 to classify some of the symmetries of the two dimensional compactifications. Selfduality under the spinor-vector duality played a key role in the construction of the Z' model of ref [5], with its distinctive signature via a di-photon excess [4, 6]. Thus, a basic property underlying the string vacua is tied to a phenomenological model with its distinct experimental signature. In section 4 we derived a representation of some of the Niemeier lattices in the free fermionic formulation. The properties of 24 dimensional lattices and their moonshine symmetries are of growing in the literature [37]. In this context it is not implausible that the free fermionic methods can add to the set of tools that can be used to explore the underlying mathematical structures. How, and whether, these mathematical phenomena manifest themselves in physical observable is the arena we will explore in future publications.

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