

# Current Interruption Using Electromagnetically Convolved Electric Arcs in Gases

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**Abstract**— Measurements are described of current, voltage and local dielectric strength for a current interrupter which utilized a novel form of electromagnetically convolved electric arc in Air. Experiments have been performed with various interrupter structures and operational conditions. Pre current zero voltage extinction peaks and post arc local breakdown voltages have been measured and are compared with values for non convoluted arcs in Nitrogen and SF<sub>6</sub>. An empirical relationship between the extinction peak voltage and various design and operational parameters is presented. Signatures for the various interrupter structures under different operational conditions have been obtained using a chromatic methodology and embodying the extinction peak, and a local breakdown voltage.

**Index Terms**—Arc discharges, magnetic fields, dielectric measurements, plasma arc devices, plasma control, ablation, data processing.

## I. INTRODUCTION

MANY forms of power network current interrupters have been proposed or implemented which involve the use of electromagnetic arc control (e.g. [1], [2]) and appropriate gaseous arcing media. These forms of circuit interrupters have been of interest since they provide the possibility of utilizing the electromagnetic forces available for reducing the external power demands of the interrupter's operating mechanism. There can also be an enhancement of the thermal energy derived from the arc to assist the arc plasma quenching process [3] whilst producing gentle but effective current interruption with good dielectric recovery properties.

This contribution describes some experimental results obtained with a novel form of electromagnetic arc control [4]. The control is based upon tailoring electromagnetic forces to produce a highly convoluted arc in atmospheric pressure air around the outer periphery of a hollow PTFE cylinder onto

whose surface the arc plasma column is tightly wound by the electromagnetic forces. Experimental measurements are presented for the time variation of the voltage across the convoluted arcs as well as the breakdown voltage at a single location close to (but not across the overall) contact gap, using a dielectric voltage probe energized from its own circuit. Comparisons are made with results for some other forms of electromagnetic arc control units [1], [2]. An empirical relationship is considered for describing the dependence of the magnitude of the arc voltage extinction peak upon various operational parameters. Chromatic processing methods [5] are applied for comparing the signatures of the various interrupters under different operating conditions and which incorporate the extinction peak and local breakdown voltages.

It is shown that the convoluted arc unit is capable of interrupting alternating currents, although the full potential of the approach warrants further investigations.

## II. PRINCIPLE OF OPERATION

The principle of operation of the convoluted arc plasma unit is shown on Fig. 1. An electric arc is initially formed vertically between two contacts when they are physically separated. The arc is immediately rotated due to a Lorenz force ( $I_z \times B_x$ ) produced with a suitably orientated B-field (Fig. 1a).  $I_z$  is the current through the arc;  $B_x$  is the radial component of the B-field produced by a current carrying coil, which is concentric with the contacts axis [4]. As the gap between the contacts increases, the arc column extends axially into regions of different magnetic field orientations (Fig. 1b). The spatial B-field distribution is such that it distorts the arc column by the contrary rotation of the anode and cathode regions of the arc ( $I_z \times B_x$ ) so that it assumes the azimuthal form shown on Fig. 1b and which persists and is maintained by an orthogonal Lorenz force ( $I_o \times B_z$ ). If an alternating current sustains the electric arc and the B-field, the B-field coil loses its influence on the arc control (when the current reduces to zero since  $i=0$  and  $B \approx 0$ ). The electromagnetically compressed plasma is then released so that the arc helix repels itself azimuthally [6]. In so doing the arc column self-disrupts (Fig. 1c). The azimuthally formed plasma may be contained within an annular gap formed between the coil containing cylinder and a second cylinder of greater diameter and concentric with the coil containing

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cylinder. Such an arrangement provides a means for the arc plasma column to interact with the material forming both walls of the annular gap.

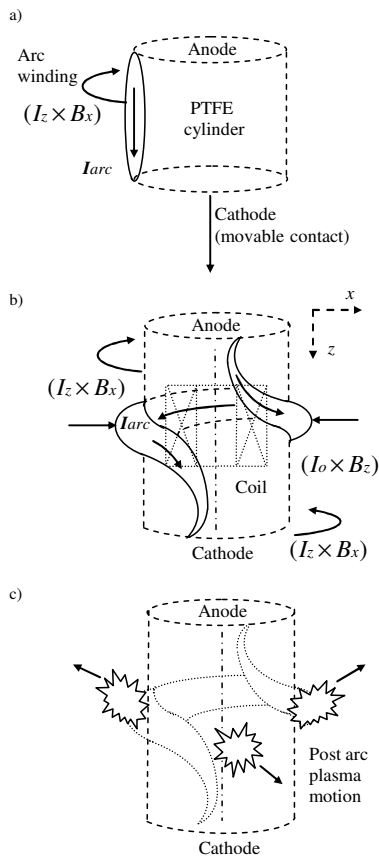


Fig. 1. Arc convolution principle.  
 a) Arc initiation; b) Peak current azimuthal compression; c) Current zero arc rupture.

### III. EXPERIMENTAL TEST HEADS

A versatile interrupter unit which enabled the operation principles described in section II to be implemented is shown on Fig. 2. This consisted of a fixed anode, a movable cathode, outer and inner PTFE cylinders, the latter housing the B-field producing coil. The anode was a copper ring fitting within the cylindrical annular gap between the outer and inner PTFE cylinders. The cathode was a copper tube also fitting within this annular space and which carried fingers to mate with the fixed anode when the contact gap was closed. One end of the B-field producing coil was connected to the anode of the contact gap and the other end to a high voltage test circuit (Fig. 3). Thus a B-field could be produced by a fault current flowing through the coil in series with the anode and cathode. During operation, the copper cathode tube slid along the annular gap between the inner and outer PTFE cylinders so that the opening gap and electric arc were gradually exposed to the B-field produced by the coil. The anode and both the inner and outer PTFE cylinders remained fixed at the same positions

as the cathode was retracted.

Five variants (Units A-E) of the basic test head configuration shown on Fig. 2 were used in the present investigations. These are listed on Tables I and II. Conditions which were varied were the presence /absence of a B-field, an outer PTFE cylinder, moving/stationary cathode and background gas and its pressure.

TABLE I  
 UNITS TESTED AND PURPOSE

Unit	Coil	Outer PTFE	Moving Cathode	Closed Chamber	Purpose
A	No	Yes	Yes	Yes	Gap-Coil optimised
B	Yes	No	No	No	Fixed length arcs, $B > 0$
C	No	No	Yes	No	Moving cathode, $B = 0$
D	Yes	No	Yes	No	Moving cathode, $B > 0$
E	Yes	Yes	Yes	No	Annular arc, $B > 0$

Unit A was used for establishing the rate at which the contact gap was opened so that the length and axial location of the B-field producing coil could be optimized relative to the contact travel. It was also used for some preliminary tests in Nitrogen and SF<sub>6</sub> at above ambient pressures. Unit B was used to check the effect of a B-field with different gap lengths each being kept constant during the entire arcing period (with arc initiation via a fuse wire). Unit C was used to investigate the effect of a time varying contact gap produced by a moving cathode without either a B-field or outer PTFE cylinder to indicate ablation effects from the inner cylinder alone without a B-field. Unit D was used to determine the effect of a moving contact with a B-field and without an outer PTFE cylinder. Unit E was the prototype interrupter with both a B-field and outer PTFE cylinder as shown on Fig. 2. An advantage of

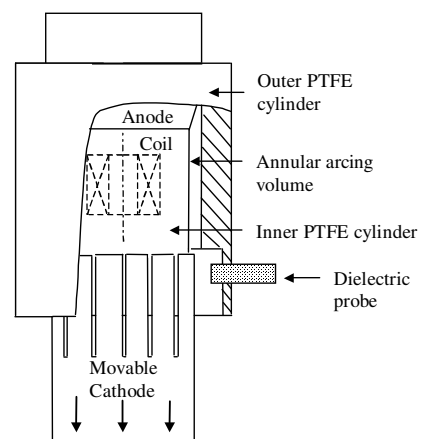


Fig. 2. Interrupter structure.

Units B, C and D was the ease with which photographic images of the convoluted arc could be obtained [4], [7]. Units C and D were also used for comparing contact wear with and

TABLE II  
EXAMPLES OF EXPERIMENTAL UNITS AND CONDITIONS INVESTIGATED

Experiment	I peak AC	B peak field	V peak (gas used)	Gap	V extinction (gas used)	Pressure gauge	V recovery (gas used)
	kA	mT	V	m	V	bar	V
A. Non-rotary arc reference interrupter: (preliminary arc tests).	12.0		580 N2	0.110	490 N2	3	240 N2
	12.2		900 SF6		700 SF6	3	230 SF6
	14.8		420 N2	0.093	400 N2	3	380 N2
	14.0		600 SF6		620 SF6	3	360 SF6
	18.3		560 N2	0.068	250 N2	3	400 N2
	18.0		470 SF6		510 SF6	3	530 SF6
B. Arc control: (with coil).	1.3	33.75	500 Air	0.093	340 Air	Atmosphere	340 Air
C. Current interrupter: (no coil).	12.8		320 Air	0.102	250 Air	Atmosphere	270 Air
D. Current interrupter head: (with the arc-driving coil).	11.8	306.35	480 Air	0.122	420 Air	Atmosphere	230 Air
	13.2	342.70	400 Air	0.106	410 Air	Atmosphere	400 Air
	14.0	363.47	320 Air	0.095	370 Air	Atmosphere	450 Air
	16.2	420.59	250 Air	0.070	190 Air	Atmosphere	390 Air
E. Prototype interrupter: (with the arc-driving coil).	10.5	272.60	352 Air	0.106	500 Air	Atmosphere	240 Air
	11.8	306.35	500 Air	0.122	490 Air	Atmosphere	280 Air
	13.3	345.30	320 Air	0.106	430 Air	Atmosphere	390 Air
	14.0	363.47	320 Air	0.095	360 Air	Atmosphere	480 Air
	15.0	389.43	360 Air	0.106	448 Air	Atmosphere	490 Air
	15.8	410.20	260 Air	0.070	180 Air	Atmosphere	680 Air

(System voltage is 2.3kV for interrupters A, C, D, E and 1.3kV for B; Quasi-steady current: 2 - 9.3kA).

without a B-field. Units D and E allowed comparisons to be made to determine the effect of the annular gap between the PTFE cylinders on the current interrupting arc.

Fig. 2 also shows the position within the test units at which dielectric probes were installed for monitoring changes in the breakdown strength of the arc exposed gases. Three test points equally inclined to each other azimuthally at 120 degrees from each other were used at the axial location shown on Fig. 2. These points corresponded to locations at which high-speed photographs reported by Shpanin *et. al.* [7] suggested that the residence of post arcing hot gases might be extended in time and so form a region of reduced dielectric strength.

#### IV. TEST CIRCUITS AND EXPERIMENTAL CONDITIONS

The main test circuit consisted of an L-C source connected across the terminals of the interrupter unit under test. With the B-field interrupter units (Units B, D, E) one terminal of the B-field coil was connected to the L-C source whilst the other coil terminal was connected to the anode of the arc gap (Fig. 3).

At contact separation, Ignitron 1, connected in series with a resistor, was triggered to conduct a quasi steady dc current through the B-field coil and electrodes (connected in series). At a predetermined time, Ignitron 2 was triggered to short circuit the current limiting resistor R1 and the first ignitron (Fig. 3) to produce a half cycle of sinusoidal current tuned to 50Hz by the circuit inductance. Thus this current not only sustained the electric arc between the cathode and anode but

also produced the B-field by passage through the series connected coil. Ignitron 3 controlled the duration of the electric arcing by being triggered to connect the dump resistor R2 30 ms after the switching of Ignitron 2 in order to dump the remaining energy from the capacitor bank. Examples of the time variation of the initial, quasi steady current followed by the half sinusoid current loop are shown on Fig. 4a and b. For

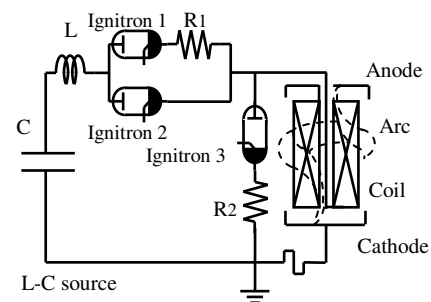


Fig. 3. Experimental test circuit showing the series connection of the B-field coil and arc contacts.

units contained a B-field coil (e.g. Unit E, Air curves, Fig. 4a, b) this current passed through both the arc gap and series connected coil.

The local dielectric strength measurements were made using the technique and circuitry described by Ennis [2] and Mori *et. al.* [1]. A high voltage source of 16kV (separate from the main power source, Fig. 2) charged a small capacitor C through a series resistor R. A pair of electrodes forming a short gap were

connected across the capacitor and were located within each interrupter at the axial position shown on Fig. 2. When the voltage across this gap reached the breakdown voltage of the gas, conduction across the gap caused the capacitor C to be discharged. After recovery from breakdown, the voltage across the capacitor increased again because of a charging current of 1mA flowing from the 16kV source. Each time the voltage on the capacitor reached the breakdown voltage the capacitor repeatedly discharged so providing an indication of the time variation of the breakdown voltage at the locations of the probes.

Examples of the experimental conditions investigated are summarized on Table II. Capacitor source voltages up to 2.3kV were used. Quasi steady D.C. currents in the range of 2 - 9.3kA and 50Hz alternating currents of peak values 1.3 to 18.3kA were used with B-fields of 33.75 - 420.59mT. The duration of the ac-arc discharge was set at 10ms, whilst the dc-arc duration was set at a maximum of 10ms depending upon the electrodes gap required at the end of the half cycle of current. The gap between the contacts at current zero at the end of a half cycle of current was in the range 68 to 122mm. With Unit B, several fixed gap lengths were tested but only one example is given in Table II.

Measurements have been made of the current through the interrupter unit, the voltage across the arc gap and the breakdown voltages of the arc-heated gas at the locations shown on Fig. 2.

V. EXPERIMENTAL RESULTS

A. Arc Voltage Results

Typical time variations of current through and voltages across the interrupter units are given on Fig. 4 a and b. In these particular tests the initial quasi-steady current was 2kA and the peak alternating current approximately 12.5kA.

Fig. 4 a is for Nitrogen in the reference, non-rotary arc interrupter (unit A, Table II) at 3 bar pressure and Air at atmospheric pressure in the prototype interrupter (unit E, Table II). Fig. 4 b is for SF6 at 3 bar pressure in the reference interrupter (unit A) and Air at atmospheric pressure in the prototype interrupter (unit E).

These results show a general trend for the arc voltage to have quasi steady values during the lower current DC phase and higher levels quasi steady values during the main alternating current period, with a peak (voltage extinction peak) developing just prior to the current zero.

B. Local Breakdown Voltage results

Fig. 5 shows a typical time variation at the axial location of the dielectric probes of the breakdown voltage relative to the pre arcing value.

The operating conditions were with air at atmospheric pressure, 5kA peak alternating current and 16.5ms arcing duration. A substantial decrease in breakdown voltage is

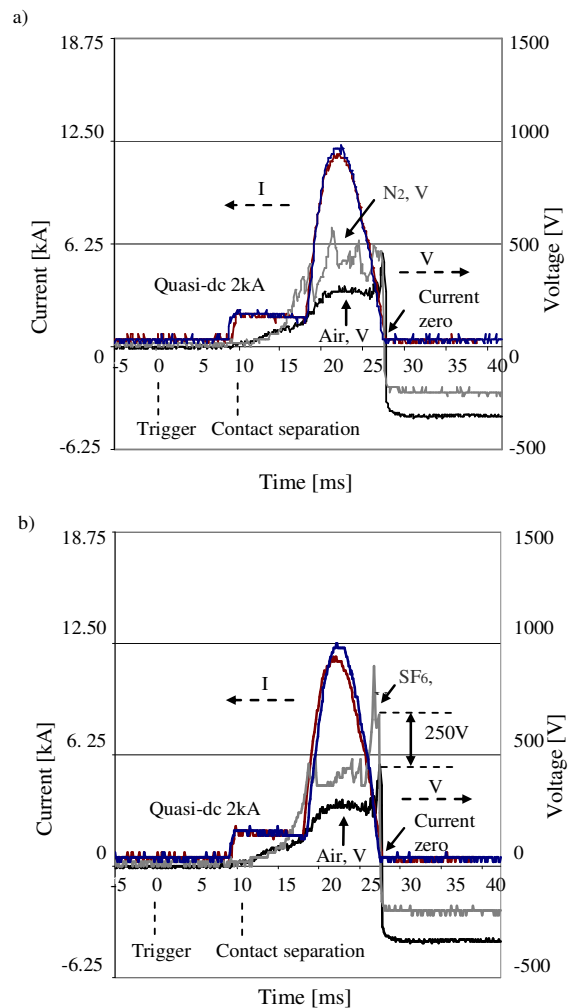


Fig. 4. Comparisons of interrupter current and voltage: time characteristics. a) Reference (Unit A, N2, 3bar pressure) and Prototype (Unit E, Air, atmospheric pressure) interrupters; b) Reference (Unit A, SF6, 3bar pressure) and Prototype (Unit E, Air, atmospheric pressure) interrupters.

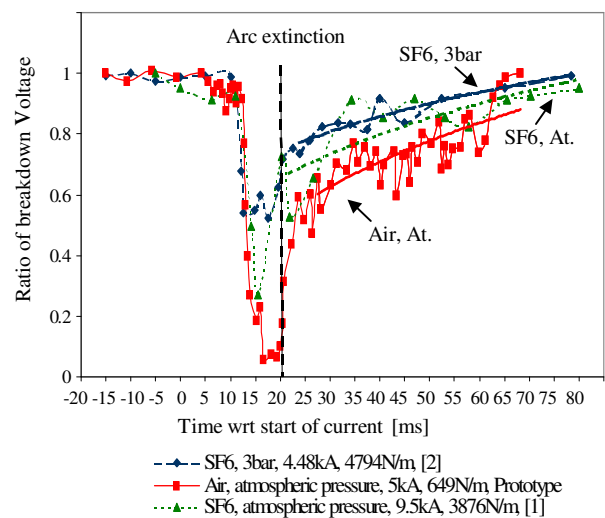


Fig. 5. Response of dielectric probe for arc duration of 16.5ms (Prototype interrupter, Unit E) compared with other interrupters [1], [2].

apparent during the arcing period, followed by a gradual increase post arcing, tending towards the initial pre-arcing value.

## VI. ANALYSIS OF RESULTS

### A. Voltage Extinction Peak

Results of the form shown on Fig. 4 a, b and summarized on Table II enable voltage extinction peaks: peak fault current / B field / contact gap characteristics of the form shown on Fig. 6 to be obtained for the various interrupters (e.g. A, D, E). These results show, for example, that the voltage extinction peaks in both Nitrogen and SF<sub>6</sub> increase with pressure, the SF<sub>6</sub> values being higher than those for Nitrogen and Air. (E.g. for a 12.3kA peak ac, the extinction peak-voltage for SF<sub>6</sub> (Unit A, 3 bar) is higher than with the prototype interrupter operated in Air at atmospheric pressure by about 250 - 400V). Also for the prototype interrupter (atmospheric pressure air, 106 mm contact gap) there is only a small variation of extinction voltage with peak alternating current in the range 8.8 - 15kA.

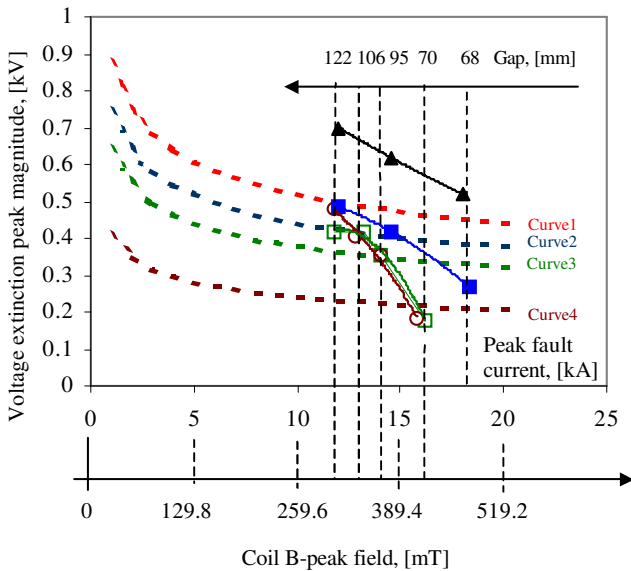


Fig. 6. Voltage extinction peak magnitude: peak fault current. Experimental points: “■” Unit A (reference interrupter), N<sub>2</sub>, 3bar; “▲” Unit A (reference interrupter), SF<sub>6</sub>, 3bar; “□” Unit D (current interrupter), Air, atmospheric pressure; “○” Unit E, (prototype interrupter), Air, atmospheric pressure. (Also shown gap length and B-field corresponding to current). Theoretical curves (equation 1, atmospheric pressure): Curve 1: coil current 11.8kA and B-field 306.35mT, gap 122mm; Curve 2: coil current 13.2kA and B-field 342.7mT, gap 106mm; Curve 3: coil current 14kA and B-field 363.47mT, gap 95mm; Curve 4: coil current 16.2kA and B-field 420.59mT, gap 70mm.

### B. Local Dielectric Strength

The time variation of the relative breakdown voltage at the axial location investigated (Fig. 5) may be used to yield values for the time required for the local dielectric strength to recover following arcing. Fig. 7 shows an example of the time required for the local dielectric strength (mean of three tests) to fully recover as a function of contact gap at current zero for the

prototype interrupter (E) (atmospheric pressure air) with a 5kA peak alternating current.

The result indicates that there is an optimum contact gap, which produces the most rapid overall recovery at the particular axial location shown on Fig. 2.

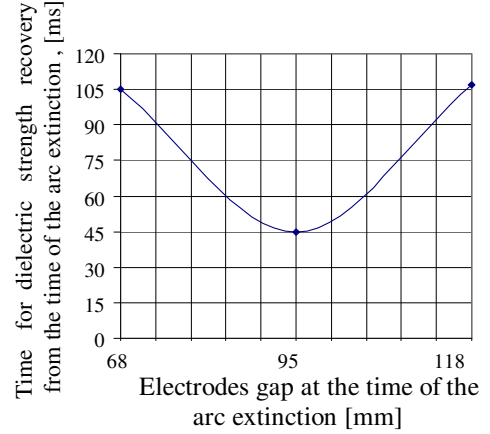


Fig. 7. Dielectric recovery time in the prototype interrupter (Unit E) vs. gap length at arc extinction (ac-arc 5kA, Air, atmospheric pressure).

## VII. QUANTIFICATION OF TRENDS

The voltage extinction peak results (Fig. 4 and 6) and the local breakdown voltage results (Fig. 5 and 7) provide a coarse indication respectively of the probable thermal and local dielectric recoveries of an interrupter.

These two parameters, derived from only voltage measurements, can be considered for giving an indication of interrupter response to different duties as a function of various designated parameters (e.g. contact gap, gas pressure etc.).

### A. Voltage Extinction Peak

Results of the form shown on Fig. 4, 6 and Table II enable an empirical relationship to be obtained between the voltage extinction peak ( $V_{EXT}$ ) and the peak magnetic field [ $B_p$  (T)], peak current [ $i_p$  (A)], contact gap [ $l$  (m)], and pressure [ $P/(P_{REF})$ ] can be derived. This empirical relationship is as follows:

$$V_{EXT} \cong K(1 + \alpha B_p^m) l^g i_p^{-n} \left[ \frac{P}{P_{REF}} \right]^e d^{\left[ \frac{1}{L} \right]}, \text{ [kV]} \quad (1)$$

The coefficients  $\alpha$ ,  $m$ ,  $g$  and  $n$  are constants determined from Fig. 6 having the values 1.8, 1.0, 1.64 and 0.23 respectively, for the present operating conditions. The constant  $K$  has values of 90, 96, and 172 respectively for Air, N<sub>2</sub> and SF<sub>6</sub> determined from Fig. 6. The constant  $e$  was determined with the reference test head (Unit A) for different gases and pressures being, 0.27 (SF<sub>6</sub>) and 0.39 (N<sub>2</sub> and Air).  $d$  represents

the effect of the arc chamber volume being 1.0 with and 0.9 without the outer PTFE cylinder. L, a contact gap constant of 0.106 [m] represents the threshold gap beyond which the effect of the outer cylinder should be observed on the current interruption (Fig. 6).

Examples of extinction voltage: peak current characteristic curves for various interrupters and operating conditions using equation (1) are shown on Fig. 6 (curves 1, 2, 3, 4).

*B. Local Dielectric Strength*

The local breakdown voltage: time results for the air prototype unit (E, atmospheric pressure, 5kA peak current) are compared on Fig. 5 with similar local dielectric probe results for SF6 reported in [2] (3bar, conventional rotary arc interrupter) and in [1] (atmospheric pressure, reference interrupter, no inner PTFE cylinder). The results show that the overall time for full recovery of the relative breakdown voltage is similar for the Air and SF6 based interrupters. However, during the arcing period, the breakdown voltage relative to the ambient value is lower at the probe location for the air prototype than at similar locations with the two SF6 units. During the intermediate period between arc extinction and the approach to full recovery (20-22ms, Fig. 5) the relative voltage recovery rate of the air prototype (E) is ~ 0.55 compared with ~0.1 for the SF6 rotary unit [2]. Thus overall the actual relative voltage recovery values at a given time during this period are lower for the air prototype interrupter compared with the 3 bar SF6 unit but closer to the atmospheric SF6 unit results.

It should be noted that the critical rate of rise of recovery voltage (RRRV) across the entire contact gap during a period of 7.8µs immediately after current zero for interrupter D with atmospheric air (Table I) reported previously [4], [8] was 26V/µs for a peak current of 12.5-13kA (dI/dt=1.75A/µs, e.g. during the final 50µs before current zero) and an electrode gap of 95mm. This result corresponds to the optimum value shown on Fig. 7.

Taken collectively, these results provide a preliminary indication of the dielectric recovery capabilities of such convoluted arc units.

The empirical relationship for the dielectric recovery derived in [1] is also applicable to the prototype interrupter of this investigation.

*C. Chromatic analysis*

The above discussion is based upon separate empirical relationships for the extinction and breakdown voltages. However, it is possible to embody the various interrupter and operational parameters together in a single description based upon an approach known as chromatic analysis [5],[9]. Applying this methodology to the present case involves first ordering and classifying the parameters from Table II, suitably normalized into three groups (I, II, III) as follows:

- I Gas pressure ( $p/p_n=p_c; p_n=1\text{bar}$ ).
- I Contact gap ( $l/l_n=gc; g_n=1\text{m}$ ).
- II, I B-field ( $1 - B/B_n=B_c; B_n=1\text{T}$ ).
- II Fault current ( $I_{pk}/I_{pkn}=I_{pkc}; I_{pkn}=20\text{kA}$ ).
- II, III Arc voltage ( $1-V_{pk}/V_{pkn}=V_{pkc}; V_{pkn}=1\text{kV}$ ).
- III Extinction peak ( $1-V_{ext}/V_{extn}=V_{ec}; V_{extn}=1\text{kV}$ ).
- III Recovery Voltage ( $1-V_{rc}/V_{rcn}=V_{rc}; V_{rcn}=1\text{kV}$ ).

Group I includes a priori determined control parameters, group II the proposed interruption conditions and group III the interrupter responses. The B-field belongs to both groups I and II, whilst the belongs to both groups II and III. The normalisation is arranged so that an increase in a parameter value represents a reduction in interrupter performance. Three overlapping processors (R, G, B), corresponding to each group (I, II, III) are superimposed upon the ordered set of parameters [5] (Fig. 8 a). The outputs from each of the processors (R, G, B) are fed into chromatic algorithms (Appendix I) to yield three chromatic parameters, which represent respectively, the dominating parameter (H), the severity of conditions (L) and

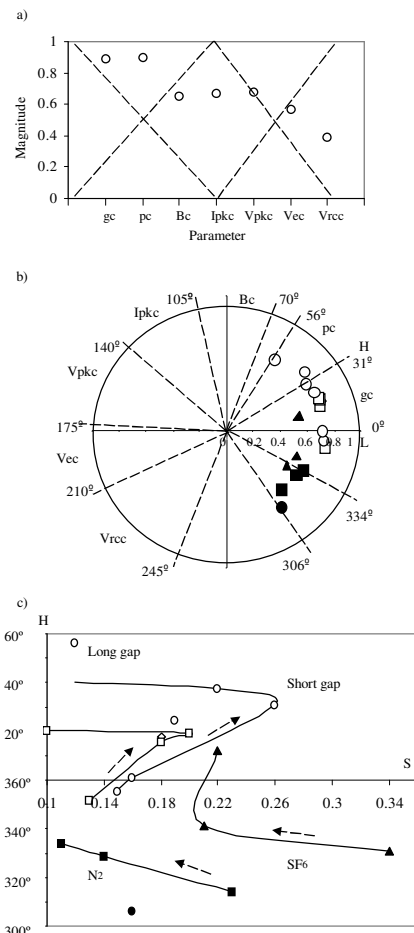


Fig. 8. Chromatic processing of data for current interrupters. a) Data set ordering with non-orthogonal processors superimposed (Example data for interrupter E, Ipeak=13.3kA, Bpeak=345.3mT, Gap=0.106m; Table II); b) Polar H: L diagram; c) Cartesian H: S diagram (Expanded region). Interrupters: “▲” A-SF6; “■” A-N2; “◊” B-Air; “●” C-Air; “□” D-Air; “○” E-Air (Arrow indicate increasing fault current).

the spread of the influence amongst the various parameters (S). Each interrupter and operating condition listed on Table II may be processed in this manner to yield a signature defined by the values of H, L, S. The interrupter signature may then be represented by points on each of two diagrams H: L, H: S. An example of a H: L polar diagram is shown on Fig. 8 b (H=azimuthal angle, L=radius) with the various operational parameters occupying different H locations. The diagram enables the interrupters / operational conditions dominated by gap length, gas pressure to be identified as those in the range  $0 < H < 56$ . It also shows that the prototype (E) and current (D) interrupters ( $0.64 < L < 0.8$ ) are more severely stressed than interrupter (A) ( $0.5 < L < 0.64$ ) and that (A) is more severely stressed when operated with Nitrogen ( $0.58 < L < 0.64$ ) than SF6 ( $0.5 < L < 0.55$ ).

Expanding a chromatic sector of a H-S diagram using Cartesian coordinates (Fig. 8c) shows that for all the interrupters and conditions investigated no single parameter is outstandingly dominant since in all cases  $S < 0.34$  ( $S=0$ -equal influence;  $S=1$ -single totally dominant feature). The variation with peak current is indicated by arrows.

For the prototype interrupter (E), Fig. 8b and c show that increasing the contact length equilibrates further the effects of the various parameters (S reduced from 0.22 to 0.12) by promoting the influence of B, p ( $H \rightarrow 60$ ) whilst reducing the stress level (L reduced from 0.725 to 0.64).

## VIII. CONCLUSIONS

It has been shown that the interruption of an alternating current can be achieved with a convoluted arc formed outside a B-field producing coil along with PTFE ablation. Preliminary assessment of a prototype interrupter (E), design optimized following tests with four subsidiary units (A, B, C, D), has been based upon values of the arc voltage extinction peak prior to current zero and the recovery of dielectric strength at a single axial location close to the arc quenching zone.

The results for the arc voltage extinction peaks are similar for the prototype interrupter (E) with atmospheric pressure air, to those with a reference interrupter (A) with 3bar Nitrogen pressure. This suggests that similar pre current zero power losses and hence arc quenching is achievable with the prototype interrupter with only one third of the gas pressure without a B-field.

The local dielectric recovery results showed that the full relative voltage recovery for the prototype interrupter (E) occurred on time scales similar to those of rotary arc interrupters [1], [2]. The axial location of the prototype interrupter had a lower dielectric strength during arcing than observed at the locations addressed in the rotary arc interrupters.

Performance signatures of the various interrupters and their dependence upon operational conditions (e.g. gas pressure etc.) have been produced using a chromatic analysis technique [5].

Further investigations of the convoluted arc interrupter would be warranted particularly to explore in more detail the initial rate of recovery voltage capability and that of the entire contact gap rather than only at the location of the probe investigated here.

## APPENDIX I

The chromatic parameters H, L, S are given in [5]:

$$L = (R + G + B)/3 \quad (I.1)$$

$$S = [\text{MAX} - \text{MIN}]/[\text{MAX} + \text{MIN}] \quad (I.2)$$

$$60(G - B)/[\text{MAX} + \text{MIN}], R = \text{MAX}$$

$$H = 60[2 + (B - R)]/[\text{MAX} + \text{MIN}], G = \text{MAX} \quad (I.3)$$

$$60[4 + (R - G)]/[\text{MAX} + \text{MIN}], B = \text{MAX}$$

Where: MAX = the highest (R, G or B) output value,  
MIN = the lowest (R, G or B) output value.

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